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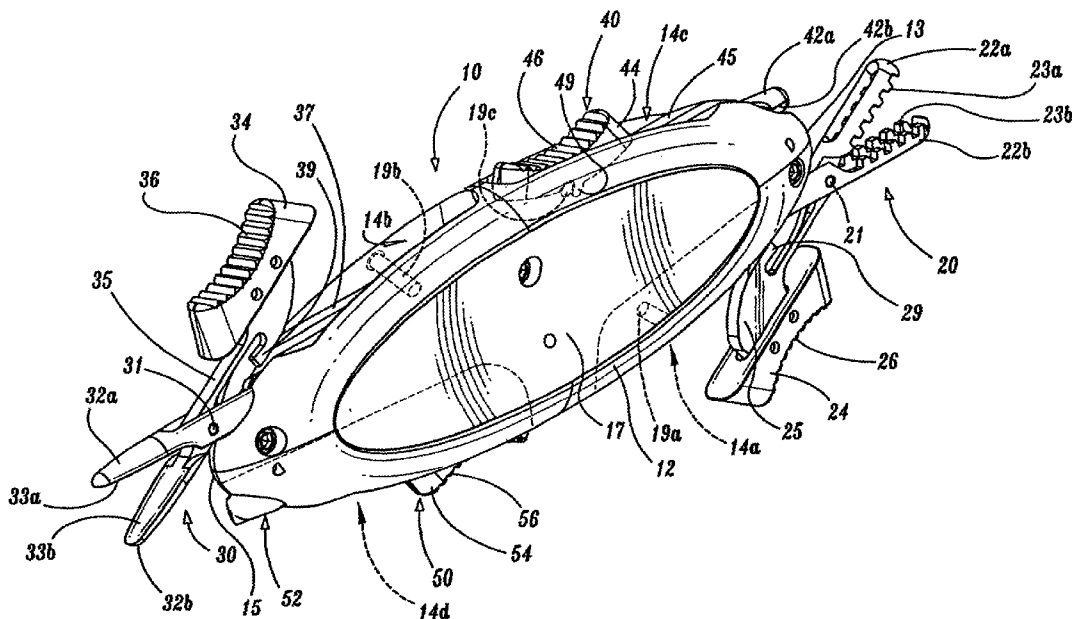
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- (71) Applicant (for all designated States except US): **TYCO HEALTHCARE GROUP LP** [US/US]; 150 Glover Avenue, Norwalk, CT 06850 (US).
- (72) Inventors; and
- (75) Inventors/Applicants (for US only): **BAYER, Hanspeter, Robert** [CA/US]; 38 Lockwood Street, Extension, Meriden, CT 06451-2840 (US). **HEINRICH, Russell** [US/US]; 11 Beaver Pond Road, Madison, CT 06443 (US).
- (74) Agents: **PERRY, Kimberly, V.** et al.; Tyco Healthcare Group LP, 10 Glover Avenue, Norwalk, CT 06850 (US).
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(54) Title: MULTI-PURPOSE SURGICAL INSTRUMENT



(57) Abstract: A multi-instrument surgical tool (10) for use during hand-assisted laparoscopic surgery includes a housing having a plurality of ports (14a-d) disposed therein which are each dimensioned to slidably house one of a plurality of surgical instruments (20, 30, 40, 50) for selective deployment from the case. The housing also includes a corresponding plurality of elongated channels each in communication with a respective one of the plurality of ports. Each of the instruments including an actuator (24, 34) which is movable within a respective channel from a first position wherein the instrument is at least partially housed within the housing to a second position wherein the actuator is disengaged from the respective channel and the actuator is freely operable to actuate the instrument for its intended purpose.

MULTI-PURPOSE SURGICAL INSTRUMENT

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BACKGROUND

Technical Field

The present invention relates to the field of surgical tools and more particularly to a multipurpose surgical tool for use during hand-assisted laparoscopic surgery, minimally invasive surgical procedures and traditional open surgical procedures.

Background of Related Art

Open surgery, in general, has remained the procedure of choice for many surgeons since it enhances a surgeon's view of the operating cavity and allows a surgeon to readily palpate the internal organs as needed during a surgical procedure. However, the relatively large incisions required can often be traumatic for patients and may result in a prolonged healing process. As a result and as an alternative to traditional open surgery, many surgeons utilize minimally invasive surgical techniques to treat tissue remotely through small incisions utilizing specialized endoscopic instruments. More particularly, endoscopic instruments are inserted into the patient through a cannula or port that has been made with a trocar. Typical sizes for cannulas range from three millimeters to twelve millimeters. Smaller cannulas are usually preferred, which, as can be appreciated, ultimately presents a design challenge to instrument manufacturers who must find ways to make surgical instruments that fit through the smaller cannulas.

Certain endoscopic surgical procedures require cutting, cauterizing and/or sealing blood vessels and/or vascular tissue which, typically, requires the surgeon to insert different instruments through the working lumen of the endoscope to treat the tissue. As can be appreciated, this simply adds to the overall complexity of the operation since it requires the repeated exchange of surgical instruments through the working lumen to perform the different tasks associated with the particular surgery involved.

There are also some disadvantages to endoscopic surgery. For example, endoscopic instruments tend to limit a surgeon's ability to freely manipulate organs and often limit the surgeon's view of the operating cavity. Moreover, when using
5 endoscopic instruments, the surgeon loses tactile feedback of the tissue which can play an important role in some surgical procedures. Further, when the particular surgery dictates the removal of a tissue specimen, the tissue must be either be morselized to fit through the trocar lumen or the surgeon must create a larger opening to remove the specimen intact essentially abandoning the benefits associated with
10 endoscopic surgery.

Combining the advantages of the traditional and the laparoscopic techniques for abdominal surgery is commonly referred to as "hand-assisted laparoscopic surgery" (HALS). In this procedure, the normal laparoscopic small puncture openings are made with the exception that one opening is made late in the procedure
15 and large enough to allow a surgeon's hand to pass through the opening to manipulate tissue, deliver new instruments into the operating cavity and/or remove tissue specimens. HALS attempts to restore dexterity and tactile feedback by allowing the surgeon to place one hand within the operating space through a hand access sleeve. Once the hand is in the operating space, it can be used to manipulate and palpate
20 tissues in much the same way as it is used in open surgical procedures.

When performing surgery in the abdominal cavity, air or gas is typically introduced to create a condition known as "pneumoperitoneum". Ideally, HALS procedures are performed while maintaining the pneumoperitoneum which eliminates re-insufflation of the surgical cavity. As can be appreciated, if a surgeon's hand has
25 to be removed to retrieve additional surgical instruments, the cavity will deflate and subsequent re-insufflation of the pneumoperitoneum may be required. This simply prolongs the overall surgical procedure and makes HALS surgery very tedious especially when multiple instruments must be utilized during the surgical procedure. As a result, a need exists to develop an improved surgical tool which reduces the need
30 to remove the instruments useful for performing hand assisted laparoscopic surgical procedures.

SUMMARY

The present disclosure relates to a multipurpose surgical tool for use in minimally invasive surgical procedures such as Hand Assisted Laparoscopic Surgery (HALS). Additionally, the multipurpose surgical tool of the present disclosure may be used in traditional open surgical procedures.

During HALS surgery, for example the multipurpose surgical tool may be inserted, in the hand, through a hand access sleeve which is made during the course of the surgery. The surgeon manipulates the tool as needed and switches among the plurality of specialized surgical instruments encased within the tool. As can be appreciated, this eliminates the need for the surgeon to remove his/her hand from the operating cavity to switch among instruments.

The present disclosure includes a multi-instrument surgical tool which includes a housing or casing having a plurality of ports disposed therein. The housing includes a corresponding plurality of elongated channels each in communication with a respective one of the plurality of ports. A plurality of surgical instruments are mounted in the housing. Each surgical instrument is slidably mounted in one of the ports for selective deployment from the housing. At least one of the instruments has a slide member attached to the instrument and accessible from an exterior of the housing.

In one preferred embodiment, the housing includes a slot in communication with the elongated channel for receiving the slide member therethrough. The slot and the elongated channel may be open on an end of the housing and the slide member and the instrument may be slidable in a distal direction in the channel by manipulation of the slide member so as to deploy the instrument from the channel.

The instruments may comprise any combination of the following: vessel sealing devices; dissectors; resectors; probes; morselators; ultrasonic instruments; video-assisted devices; clip appliers; surgical staplers; coagulators; irrigation instruments; and suction instruments. The foregoing is merely by way of an example and other instruments may be included.

In certain preferred embodiments, the elongated channels are configured for interchanging different surgical instruments. The elongated channels may include a first set of channels dimensioned to accommodate a first category of surgical

instruments and a second set of channels dimensioned to accommodate a second set of instruments.

The multi-instrument surgical tool may include a surgical scalpel. In a preferred embodiment, the surgical scalpel includes a proximal end dimensioned to slideably engage one of the ports of the housing. The surgical scalpel desirably includes a distal end having a cutting edge. The tool includes a safety guard which is movable relative to the scalpel from a first position wherein the guard substantially covers the cutting edge of the scalpel to a second position wherein the cutting edge is exposed.

The guard desirably includes a locking tab for releasably locking the guard in the second position. The guard may be spring-biased to return to the first position.

In one preferred embodiment, the housing includes a slot in communication with the elongated channel for receiving the slide member therethrough. The slot and the elongated channel may be open on an end of the housing and the slide member and the instrument may be slidable in a distal direction in the channel by manipulation of the slide member so as to deploy the instrument from the channel.

The instruments may comprise any combination of the following: vessel sealing devices; dissectors; resectors; probes; morselators; ultrasonic instruments; video-assisted devices; clip applicators; surgical staplers; coagulators; irrigation instruments; and suction instruments. The foregoing is merely by way of an example and other instruments may be included.

In certain preferred embodiments, the elongated channels are configured for interchanging different surgical instruments. The elongated channels may include a first set of channels dimensioned to accommodate a first category of surgical instruments and a second set of channels dimensioned to accommodate a second set of instruments.

In another aspect of the present invention, a multi-instrument surgical tool comprises a housing having a plurality of ports disposed therein. The housing includes a corresponding plurality of elongated channels each in communication with a respective one of the ports. A plurality of surgical instruments are mounted in the housing. Each surgical instrument is mounted in one of the ports for selective deployment from the housing. A first instrument of the plurality of instruments comprises a locking flange and the housing has a locking post disposed in the

channel. The locking flange is arranged to engage the locking post when the first instrument is stored within the housing.

The locking flange and the locking post may be arranged so that upon movement of the first instrument proximally, the locking flange is released from the locking post.

In a further aspect of the present invention, a multi-instrument surgical tool comprises a housing having a plurality of ports disposed therein. The housing includes at least one elongated channel in communication with the plurality of ports. The plurality of ports includes a first port open at a first end of the housing and a second port open on a second end of the housing. The first end is opposite from the second end. A plurality of surgical instruments are mounted in the housing. Each surgical instrument is slidably mounted in the at least one elongated channel for selective deployment from the housing.

In certain embodiments, at least one of the instruments has a slide member attached to the instrument and accessible from an exterior of the housing. The housing desirably includes a slot in communication with the elongated channel for receiving the slide member. The slot and the elongated channel may be open on the first end of the housing and the slide member and the instrument may be slidable in a distal direction in the channel by manipulation of the slide member so as to deploy the instrument from the channel.

The instruments may include, in addition to others, vessel sealing devices; dissectors; resectors; probes; morselators; ultrasonic instruments; video-assisted devices; clip applicators; surgical staplers; coagulators; irrigation instruments; and suction instruments. The elongated channels may be configured for interchanging different surgical instruments.

In a further aspect of the present invention, a multi-instrument surgical tool comprises a housing having a plurality of ports disposed therein. The housing includes at least one elongated channel in communication with the plurality of ports. The plurality of ports includes a first port open at a first end of the housing and a second port open on the first end of the housing. A plurality of surgical instruments are mounted in the housing. Each surgical instrument is slidably mounted in the at least one elongated channel for selective deployment from the housing.

In certain embodiments, at least one of the instruments has a slide member attached to the instrument and accessible from an exterior of the housing. The housing desirably includes a slot in communication with the elongated channel for receiving the slide member. The slot and the elongated channel may be open on the first end of the housing and the slide member and the instrument may be slidable in a distal direction in the channel by manipulation of the slide member so as to deploy the instrument from the channel.

In a further aspect of the present invention, a multi-instrument tool comprises a plurality of housings movably mounted with respect to one another. Each of the housings includes a port in communication with an elongated channel. The tool has a plurality of surgical instruments. Each surgical instrument is slidably mounted in one of the housings for selective deployment from the housing.

In certain embodiments, at least one of the instruments has a slide member attached to the instrument and accessible from an exterior of the housing. The housing desirably includes a slot in communication with the elongated channel for receiving the slide member therethrough. The slot and the elongated channel are desirably open on the first end of the housing and the slide member and the instrument is desirably slidable in a distal direction in the channel by manipulation of the slide member so as to deploy the instrument from the channel.

In a further aspect of the present invention, a multi-instrument tool comprises a plurality of housings movably mounted with respect to one another. Each of the housings includes a port in communication with an elongated channel. The tool has a plurality of surgical instruments. Each surgical instrument is slidably mounted in one of the housings for selective deployment from the housing.

In certain embodiments, at least one of the instruments has a slide member attached to the instrument and accessible from an exterior of the housing. The housing may include a slot in communication with the elongated channel for receiving the slide member. The slot and the elongated channel are desirably open on the first end of the housing and the slide member and the instrument are desirably slidable in a distal direction in the channel by manipulation of the slide member so as to deploy the instrument from the channel.

BRIEF DESCRIPTION OF THE DRAWINGS

Other objects and features of the present invention will become apparent from the following detailed description considered in connection with the accompanied drawings. It should be understood, however, that the drawings are designed for the purpose of illustration only and not as a definition of the limits of the invention.

Illustrative embodiments of the subject surgical tool are described herein with reference to the drawings wherein:

Fig. 1A is a perspective view of multi-instrument surgical tool in accordance with the present disclosure;

Fig. 1B is a perspective view of a multi-instrument surgical tool in accordance with an embodiment of the present invention;

Figs. 1C-1E are schematic representations showing various hand orientations for using an instrument according to the embodiment of Fig. 1B;

Fig. 2A is a side perspective view showing a multi-instrument surgical tool according to a further embodiment of the present invention;

Fig. 2B is a side perspective view showing a multi-instrument surgical tool according to another embodiment of the present invention;

Fig. 2C is a perspective view showing a multi-instrument surgical tool according to another embodiment of the present invention;

Fig. 2D is a perspective view showing a multi-instrument surgical tool according to another embodiment of the present invention;

Fig. 3A is a perspective view of a mounting strap for use with a surgical tool in a further embodiment of the present invention;

Fig. 3B is a schematic view showing the proper orientation of the mounting strap of Fig. 3A;

Fig. 3C is a schematic view showing a surgical tool in the embodiment of Figs. 3A - 3B;

Fig. 3D is a cross section of the mounting strap in accordance with the embodiment of Figs. 3A - 3C;

Fig. 3E is a perspective view of a multi-instrument surgical tool in accordance with a further embodiment of the invention;

Fig. 3F is a cross-sectional view of a multi-instrument surgical tool according to another embodiment of the present invention;

Fig. 4A is a side view of a multi-instrument surgical tool in accordance with another embodiment of the present invention;

Fig. 4B is a schematic illustration of a locking mechanism for the embodiment of Fig. 4A; and

Fig. 4C is a side view of the multi-instrument surgical tool in accordance with the embodiment of Figs. 4A - 4B.

DETAILED DESCRIPTION

Preferred embodiments of the multipurpose surgical tool will be described in terms of a HALS procedure wherein the typical laparoscopic incisions are made with the exception that one, larger opening is made during the course of the procedure which is large enough to allow a surgeon's hand to pass through the opening to manipulate tissue, deliver new instruments into the operating cavity and/or remove tissue specimens. Air or gas is introduced to create the pneumoperitoneum and the HALS procedure is performed while maintaining the pneumoperitoneum.

In the drawings and in the description which follows, the term "proximal", as is traditional, will refer to the end of the instrument which is closer to the user, while the term "distal" will refer to the end which is further from the user. When described in accordance with a particular figure, the proximal and distal ends are designated for the purpose of clarification only since the nature and use of the surgical tool of the present invention enables the surgeon to freely position and rotate the tool within the surgeon's hand.

Referring now in detail to the drawing figures in which like reference numerals identify similar or identical elements, one embodiment of the present disclosure is illustrated generally in Fig. 1A and is designated therein as multipurpose surgical tool 10. Surgical tool 10 includes a case or housing 12 which has a plurality of elongated instrument slots or ports 14a, 14b, 14c and 14d defined therein for removably housing a corresponding plurality of surgical instruments 20, 30, 40 and 50, respectively. More particularly, Fig. 1A shows one embodiment of a multipurpose surgical tool 10 which includes four surgical instruments 20, 30, 40 and 50 mounted for selective deployment within elongated ports 14a, 14b, 14c and 14d. In further embodiments, two or more instruments are provided on the tool.

Turning back to the embodiment shown in Fig. 1A, each of the corresponding plurality of surgical instruments, e.g., 20, is deployably housed within a corresponding elongated port 14a defined within the housing 12. With the four-instrument embodiment, two elongated ports 14a and 14c are located at one end, e.g., proximal end 13, for housing instruments 20 and 40, respectively, and two elongated ports, e.g., 14b and 14d are located at the opposite end, e.g., distal end 15, for housing instruments 30 and 50. As can be appreciated, each elongated port, e.g., 14a, is dimensioned to house the particular port's surgical instrument 20 and, as such, the relative dimensions of each port 14a may vary depending upon the particular instrument 20 being housed. Preferably, the outer surface of the housing 12 includes an ergonomically enhanced scallop to facilitate handling the tool 10 under wet operating conditions.

Alternatively, it is envisioned that all or some of the elongated ports 14a-14d may be dimensioned in a substantially uniform manner to enable an interchange of different surgical instruments 20, 30, 40 and 50. For example, it is envisioned that the surgeon may be able to select a combination of surgical instruments needed for a particular operation and assemble the tool 10 with these selected instruments prior to insertion. Preferably, the surgical instruments are selected from a group consisting of: needle holders; needle drivers; graspers; forceps; vessel sealing devices; dissectors; resectors; probes; morselators; ultrasonic instruments; video-assisted devices; clip applicators; surgical staplers; coagulators; bipolar and mechanical scissors; irrigation instruments; and suction instruments.

Moreover, it is also envisioned that certain elongated ports, e.g., 14a and 14c, may be dimensioned to accommodate one category of surgical instruments, e.g., 20 and 40, and the remaining ports 14b and 14d may be dimensioned to accommodate a second category of surgical instruments, e.g., 30 and 50. The surgeon is then able to interchange among the different categories of surgical instruments and removably engage the selected instruments in the correspondingly dimensioned or appropriate elongated ports as needed.

Fig. 1A shows the multi-purpose surgical instrument 10 having a forceps 30 deployed at the distal end 15 of the housing 12. The forceps includes two opposing jaw members 32a and 32b which are movable relative to one another about pivot 31 by virtue of an actuator 34. The jaw members 32a and 32b have inner facing surfaces 33a and 33b which cooperate to grasp tissue therebetween upon selective movement

of the actuator 34. Preferably, the actuator 34 includes an ergonomically enhanced thumb tab 36 to facilitate deployment of the forceps 30 and subsequent actuation of the jaw members 32a and 32b within the operating cavity under wet conditions. A lever arm 35 is disposed between the actuator 34 and the movable jaw member, e.g., 32b, to increase the grasping pressure by mechanical advantage.

The forceps 30 also includes a locking flange 39 which engages a corresponding locking post 19b to releasably lock the forceps 30 within the corresponding elongated port 14b when retracted within housing 12. Preferably, a spring arm or leaf spring 37 biases the locking flange 39 against the locking post 19b in a pre-loaded configuration. As can be appreciated, when the actuator 34 is retracted proximally, the actuator 34 releases the locking flange 39 from the locking post 19b and allows the forceps 30 to deploy from the housing 12, i.e., the pre-loaded spring arm 37 forces the forceps 30 distally or outwardly from the housing 12 when released. Once deployed from elongated port 14b, the spring arm 37 also biases the jaws 32a and 32b in an open configuration to facilitate approximation of the tissue. Downward movement of the actuator 34 moves the jaw members 32a and 32b relative to one another about pivot 31 to grasp tissue.

A second instrument, namely, a grasping forceps 20, is shown deployed from the proximal end of the housing 12 of tool 10. Grasping forceps 20 includes two opposing jaw members 22a and 22b which are movable relative to one another about pivot 21 in much the same manner as forceps 30, and may also include an actuator 24. Preferably, the inner facing surfaces 23a and 23b of the jaw members 22a and 22b are corrugated to facilitate grasping and manipulation of tissue.

Grasping forceps 20 includes many of the same or similar components as forceps 30. For example, grasping forceps 20 also deploys in much the same fashion as forceps 30. An ergonomically enhanced tab surface 24 may be included for disengaging the locking flange 29 from locking post 19a to release spring arm (not shown). The forceps 20 also releasably locks into housing in a similar manner and a locking flange 29 and a corresponding locking post 19a is desirably provided for locking into the housing. As can be appreciated, both of the forceps 20 or 30 may be deployed at any one time or the locking posts 19a and 19b may be interconnected (either mechanically or electro-mechanically) to allow deployment of only one instrument at a time.

Fig. 1A also shows third and fourth instruments 40 and 50 which are shown in a retracted or "housed" position within housing 12. These instruments 40 and 50 may include any of the instruments identified in the group described above. Preferably, each of these instruments is designed to lock within the housing 12 and deploy from the housing 12 in much the same fashion and described above with respect to forceps 20 and 30. Moreover, each of these instruments desirably includes similar components as described above which have similar functions. For example, instrument 40 includes an actuator 44, ergonomic surface 46, lever arm 45, jaw members 42a and 42b and locking flange 49 (which engages locking post 19c). Instrument 50 includes an actuator 54, ergonomic surface 56 and jaw members 52 which again cooperate in much the same fashion as described above.

Fig. 1B shows another embodiment of the surgical tool 100 of the present disclosure which shows a plurality of surgical instruments (forceps 120, needle driver 130, shears 140 and curved shears 150) for use with a housing 112. The housing may have a rectilinear shape, or any other shape. Each instrument 120, 130, 140 and 150 is housed within a respective port 119a, 119b, 119c and 119d. Each instrument, e.g., forceps 120, is manually deployable. Desirably, each instrument has a corresponding slide-like actuator or slide member, e.g., 124, which is movable distally (or forwardly) within an elongated slot 114a disposed within the corresponding port 119a. One arm 125 of the forceps 120 is attached at one end to the slide member 124 and at the other end to a corresponding jaw member 122b. The other jaw member 122a is attached to a second arm 129 which slidably reciprocates within port 119a. Initial distal movement of the slide member 124 rides arm 125 along slot 114a until the slide member 124 releases from slot 114a. Preferably, a spring 127 biases the slide member 124 against arm 129 which, in turn, biases the jaw members 122a and 122b in an open configuration for approximating tissue.

To retract or store the forceps 120 in the housing 112, the surgeon simply re-engages the slide member 124 within slot 114a and moves the slide member 124 proximally along slot 114a until substantially all of the forceps 120 is seated within port 119a. Preferably, the spring 127 holds the forceps 120 in friction-fit engagement within slot 114a. Alternatively, a locking mechanism (not shown) may be employed to secure the forceps 120 within port 119a.

The other instruments, namely, needle driver 130, shears 140 and curved shears 150, all include similar components and are deployable in a similar fashion.

More particularly, needle driver 130 includes a slide member 134 which slides along slot 114b to selectively deploy a needle tip 132 through port 119b. Shears 140 include a slide member 144 which slides along slot 114c to selectively deploy arm 147 and blade members 142a and 142b through port 119c. Curved shears 150 include a slide member 154 which slides along slot 114d to selectively deploy arm 157 and blade members 152a and 152b through port 119d.

As best illustrated in Figs. 1C - 1E, the surgeon can grasp and hold the surgical tool 10, 100 in a variety of different orientations for utilizing the different instruments contained therein. Moreover, the symmetrical aspects of the surgical tool 10, 100 allow the surgeon to comfortably use the tool 10, 100 in either a right-handed or left-handed orientation.

Fig. 2A shows an alternative embodiment of a two-instrument surgical tool 200 which utilizes ports disposed on opposite sides of an elongated housing 212. In the embodiment shown, two-instruments are provided, each in a corresponding port. The housing may have a tube-like shape, or any other shape. Each of the housed instruments (not shown) desirably includes a slide-like actuator or slide member 224 and 234 which moves along a corresponding slot 214a and 214b disposed within the housing 212 to deploy the particular instrument as needed during a given surgical procedure much in the same (or similar) manner as described above with respect to the embodiment of Figs. 1A-1D.

Fig. 2B shows another version of a surgical tool 300 which utilizes two ports 319a and 319b disposed adjacent one another (i.e., on the same side). Each instrument (not shown) includes an actuator 324a and 324b which moves along a corresponding slot 314a and 314b disposed within the housing 312 to deploy the particular instrument in the same (or similar) manner as described above.

Fig. 2C shows an alternative embodiment of a surgical tool 400 which utilizes three instrument housings 412a, 412b and 412c. Each instrument housing has a respective instrument port 419a, 419b and 419c disposed at a distal end 416a, 416b and 416c of each housing (412a, 412b and 412c). The instrument housings 412a, 412b and 412c are commonly attached to an elongated rod or cylinder 460 which engages each housing 412a, 412b and 412c through an aperture 413a, 413b and 413c located at a proximal end 418a, 418b and 418c of housings 412a, 412b and 412c, respectively. Each instrument (not shown) desirably includes an actuator 424a, 424b and 424c which moves along a corresponding slot 414a, 414b and 414c disposed

within housings 412a, 412b and 412c to deploy the particular instrument in the same (or similar) fashion as described with respect to Figs. 1A-1E.

As can be appreciated, the user simply rotates one of the three housings, e.g., 412a, which contains a particular surgical instrument (not shown) about rod 460 in the direction "A" and slides the actuator 424a distally to deploy the surgical instrument for introduction into the surgical field. To select a different instrument, the user retracts slide 424a, rotates housing 412a back into vertical registration with the other housings 412b and 412c in the direction "B" and rotates a new housing, e.g., 412b, in the direction "A" to selectively deploy another instrument (not shown).

Fig. 2D shows another version of a surgical tool 500. Tool 500 has housings 512a, 512b and 512c commonly mounted to a ring 560 through an aperture 517a, 517b and 517c located at the proximal end 518a, 518b and 518c of housings 512a, 512b and 512c, respectively. Much like the embodiment of Fig. 2C, the user simply rotates one of the three housings, e.g., 512a, about ring 560 in the direction of the arrows "AA", "BB" and "CC" to position the surgical instrument for introduction into the surgical field. The user can also move a particular instrument in the direction "DD" along ring 560 to facilitate selection and handling of the instrument in the surgical field.

Figs. 3A-3D show another embodiment of a surgical tool 600 which utilizes a mounting strap or hand clip 670 to permit selective rotation of the surgical tool within a surgeon's hand. Preferably, hand clip 670 includes at least one mechanical interface which mates with a corresponding mechanical interface disposed on the housing 612 of the surgical tool 600. More particularly and as shown in Figs. 3A and 3B, hand clip 670 includes a press-lock fitting 675 which mechanically engages a corresponding aperture 617a (or 617b) located within the outer periphery of the housing 612. As best shown in Figs. 3A and 3D, the press lock is designed for snap-fit engagement within aperture 617a (or 617b).

The press-lock shown includes a segmented top portion 677 which is supported by a stem section 679. Upon introduction of the top portion 677 into one of the two apertures 617a or 617b (for right-handed or left-handed use of the surgical tool, respectively), the segmented top portion 677 initially compresses inwardly to facilitate engagement within the respective aperture 617a (or 617b). Once the top portion 677 is fully engaged within aperture 617a (or 617b), the top portion 677 expands or "snaps" into engagement with a ring-like flange 619a (or 619b) disposed

within the inner periphery of aperture 617a (or 617B). Preferably, the top portion 677 and the ring-like flange 619a (or 619b) are dimensioned to facilitate rotation of the surgical tool 600 relative to the hand clip 670 to allow a surgeon to select and orient the particular surgical tool 600 as needed during surgery (See Fig. 3C).

5 Fig. 3E shows the surgical tool 600 of Fig. 3B with a surgical grasping instrument 620 shown deployed from port 619a of housing 612 and ready for use. Much in the same (or similar) manner as described above with respect to the embodiment of Figs. 1A-1D, the grasping instrument 620 includes a slide-like actuator 624 which moves along slot 614a to extend the shaft 625 and jaws 622a and
10 622b from the housing 612 to enable use of the grasping instrument 620 as needed during a surgical procedure.

Fig. 3F shows another embodiment of the surgical tool 800 according to the present disclosure wherein a plurality of surgical instruments 820, 830 and 840 are each housed in a corresponding recess 819a, 819b and 819c, respectively, disposed
15 along the outer periphery of the housing 812. More particularly, each instrument, e.g., grasper 820, is rotatably mounted to housing 812 about a pivot 837a and is selectively movable from a first "stored" position to a second "deployed" position. Preferably, each recess, e.g., 819a, is dimensioned to store the respective instrument, e.g., grasper 820, in a generally flush manner with respect to the outer periphery of
20 the housing 812. Moreover, each recess 819A is preferably dimensioned such that the jaw members or end effectors 822a and 822b remain properly seated in a generally closed configuration when stored.

As can be appreciated, the other instruments of surgical tool 800 are deployed in much the same fashion as grasper 820 and include similar elements to those
25 instruments described above. For example, instrument 830 is a curved forceps and includes jaws 832a and 832b which are rotatable about pivot 831 to approximate and grasp tissue. The forceps 830 mounts to housing 812 about pivot 837c and is stored within recess 819c when not in use. Likewise, scissors 840 include jaws 842a and 842b which are rotatable about pivot 841 to sever tissue. The scissors 840 mount to
30 housing 812 about pivot 837b and are stored within recess 819b when not in use.

As shown best in Figs. 4A - 4C, one of the plurality of instruments may be a surgical scalpel 720 having proximal and distal ends 713 and 722, respectively. The proximal end 713 is preferably dimensioned to slideably engage one of the ports (not shown) of the housing (not shown) and the distal end 722 includes a cutting edge 724.

A spring-loaded safety guard 730 is also included which is movable relative to the scalpel 720 from a first position wherein the guard 730 substantially covers the cutting edge 724 of the scalpel 720 (See Fig. 4C) to a second position wherein the cutting edge 724 is exposed.

5 Preferably, the safety guard 730 includes a locking tab 740 for releasably locking the guard 730 in the second position (See Fig. 4B). The guard 730 may also include a spring 725 which automatically extends the guard 730 once the locking tab 740 is released to cover the cutting edge 724 when not in use. More particularly, during use the user retracts the guard 730 proximally against spring 725 in the
10 direction "FF" and simultaneously depresses locking flange 740 inwardly (i.e., in the direction of arrow "HH") such that a distal end 742 of the locking tab 740 abuts against a corresponding flange or notch 716 disposed within the outer periphery of scalpel 730 (See Fig. 4B). The biasing force of the spring 725 retains the locking tab 740 within the notch 716 and locks the guard 730 in a retracted position to expose the
15 cutting edge 724 of the scalpel 720 for use. Once the surgeon has completed the cut using the scalpel 720, the surgeon simply retracts the guard 730 proximally (i.e., in the direction "FF") which releases the locking tab 742 from the notch 716 and allows the guard 730 to extend distally in the direction "GG" over the cutting edge 724 under the force of the spring 725.

20 From the foregoing and with reference to the various figure drawings, those skilled in the art will appreciate that certain modifications can also be made to the present disclosure without departing from the scope of the same. While several embodiments of the disclosure have been shown in the drawings, it is not intended that the disclosure be limited thereto, as it is intended that the disclosure be as broad
25 in scope as the art will allow and that the specification be read likewise. Therefore, the above description should not be construed as limiting, but merely as exemplifications of preferred embodiments. Those skilled in the art will envision other modifications within the scope and spirit of the claims appended hereto.

WHAT IS CLAIMED:

1. A multi-instrument surgical tool, comprising:

a) a housing having a plurality of ports disposed therein, said housing

5 including a corresponding plurality of elongated channels each in communication with a respective one of said plurality of ports; and

b) a plurality of surgical instruments mounted in said housing, at least one of said surgical instruments being slidably mounted in one of said plurality of ports for selective deployment from said housing;

10 c) at least one of said instruments having a slide member attached to said instrument and accessible from an exterior of said housing.

2. The tool of claim 1 wherein one of said instruments includes a surgical scalpel which includes:

15 proximal and distal ends, said proximal end being dimensioned to slideably engage one of said ports of said housing and said distal end having a cutting edge;

a guard which is movable relative to said scalpel from a first position wherein said guard substantially covers the cutting edge of said scalpel to a second position wherein said cutting edge is exposed.

20

3. The tool of claim 2 wherein said guard includes a locking tab for releasably locking said guard in said second position.

4. The tool of claim 2 wherein said guard is spring-biased to return to said first position.

25

5. The tool of claim 1, wherein the housing includes a slot in communication with the elongated channel for receiving the slide member therethrough.

30

6. The tool of claim 5, wherein said elongated channel is open on an end of said housing and said slide member and said instrument is slidable in a distal direction in said channel by manipulation of said slide member so as to deploy said instrument from said channel.

7. The tool of claim 1, wherein said instruments are selected from the group consisting of: vessel sealing devices, dissectors, resectors, probes, morselators, ultrasonic instruments, video-assisted devices, clip appliers, surgical staplers, coagulators, irrigation instruments, and suction instruments.

8. The tool of claim 1, wherein the elongated channels are configured for interchanging different surgical instruments therein.

9. The tool of claim 8, wherein the elongated channels include a first set of channels dimensioned to accommodate a first category of surgical instruments and a second set of channels dimensioned to accommodate a second category of surgical instruments.

10. A multi-instrument surgical tool, comprising:
a) a housing having a plurality of ports disposed therein, said housing including a corresponding plurality of elongated channels each in communication with a respective one of said plurality of ports;
b) a plurality of surgical instruments mounted in said housing, each surgical instrument mounted in one of said plurality of ports for selective deployment from said housing; and
c) a first instrument of said plurality of instruments comprising a locking flange and said housing having a locking post disposed in said channel, said locking flange being arranged to engage the locking post when said first instrument is stored within said housing.

11. The tool of claim 10, wherein said locking flange and said locking post are arranged so that upon movement of said first instrument proximally, said locking flange is released from said locking post.

12. A multi-instrument surgical tool, comprising:
a) a housing having a plurality of ports disposed therein, said housing including at least one elongated channel in communication with said plurality of ports;

b) said plurality of ports including a first port open at a first end of said housing and a second port open on a second end of said housing, said first end being opposite from said second end; and

5 c) a plurality of surgical instruments mounted in said housing, each surgical instrument being slidably mounted in said at least one elongated channel for selective deployment from said housing.

10 13. The tool of claim 12, wherein at least one of said instruments has a slide member attached to said instrument and accessible from an exterior of said housing.

15 14. The tool of claim 13, wherein the housing includes a slot in communication with the elongated channel for receiving the slide member therethrough.

20 15. The tool of claim 14, wherein said slot and said elongated channel are open on said first end of said housing and said slide member and said instrument is slidable in a distal direction in said channel by manipulation of said slide member so as to deploy said instrument from said channel.

25 16. The tool of claim 12, wherein said instruments are selected from the group consisting of: vessel sealing devices, dissectors, resectors, probes, moselators, ultrasonic instruments, video-assisted devices, clip appliers, surgical staplers, coagulators, irrigation instruments, and suction instruments.

17. The tool of claim 12, wherein the elongated channels are configured for interchanging different surgical instruments therein.

18. A multi-instrument surgical tool, comprising:

30 a) a housing having a plurality of ports disposed therein, said housing including at least one elongated channel in communication with said plurality of ports;

b) said plurality of ports including a first port open at a first end of said housing and a second port open on said first end of said housing; and

c) a plurality of surgical instruments mounted in said housing, each surgical instrument being slidably mounted in said at least one elongated channel for selective deployment from said housing.

5 19. The tool of claim 18, wherein at least one of said instruments has a slide member attached to said instrument and accessible from an exterior of said housing.

10 20. The tool of claim 19, wherein the housing includes a slot in communication with the elongated channel for receiving the slide member therethrough.

15 21. The tool of claim 20, wherein said slot and said elongated channel are open on said first end of said housing and said slide member and said instrument are slidable in a distal direction in said channel by manipulation of said slide member so as to deploy said instrument from said channel.

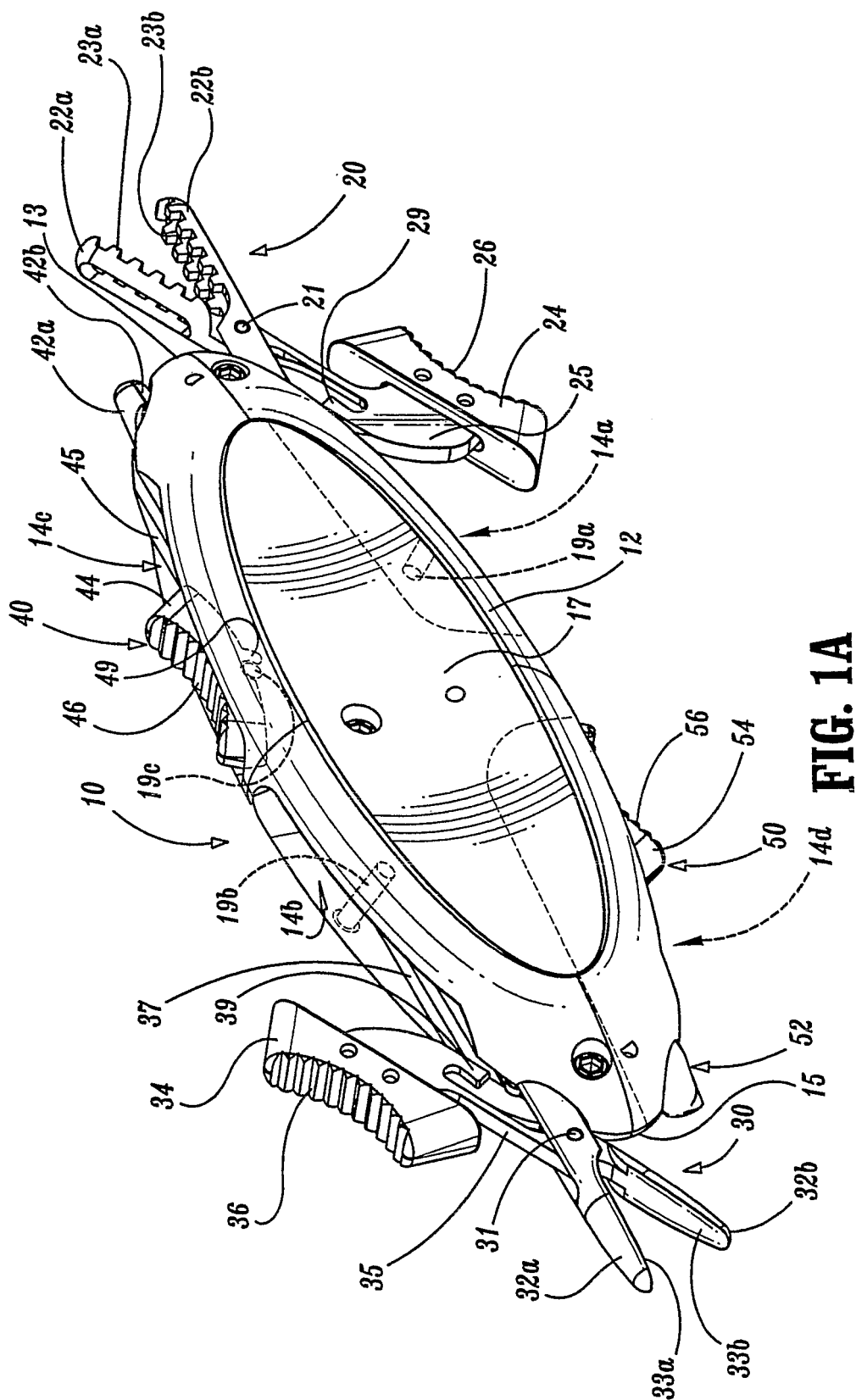
22. A multi-instrument surgical tool, comprising:
a) a plurality of housings movably mounted with respect to one another, each
20 of said housings including a port in communication with an elongated channel; and
b) a plurality of surgical instruments, each surgical instrument being slidably mounted in one of said housings for selective deployment from said housing.

25 23. The tool of claim 22, wherein at least one of said instruments has a slide member attached to said instrument and accessible from an exterior of said housing.

24. The tool of claim 23, wherein the housing includes a slot in communication with the elongated channel for receiving the slide member
30 therethrough.

25. The tool of claim 24, wherein said slot and said elongated channel are open on said first end of said housing and said slide member and said instrument are

slidable in a distal direction in said channel by manipulation of said slide member so as to deploy said instrument from said channel.



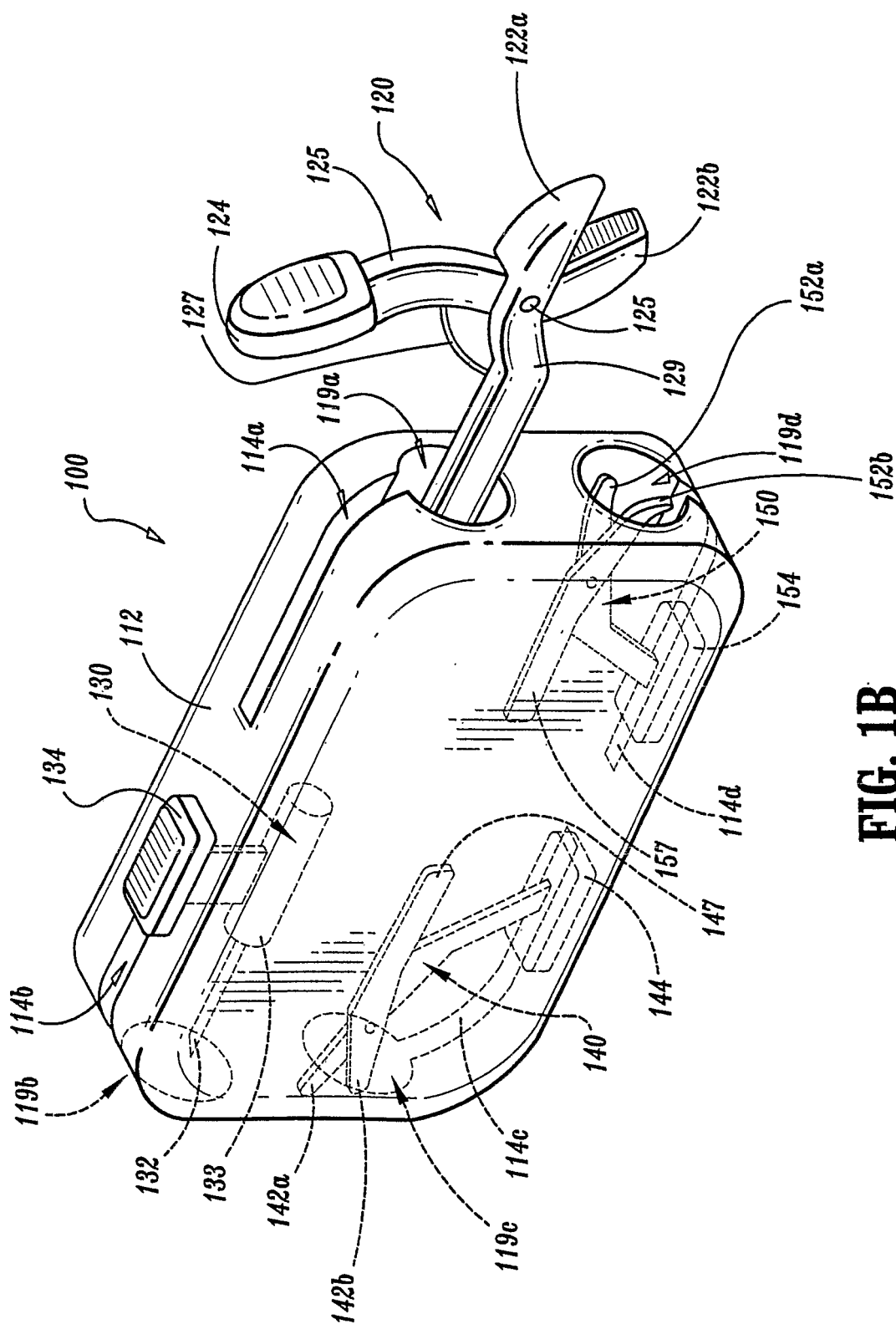


FIG. 1B

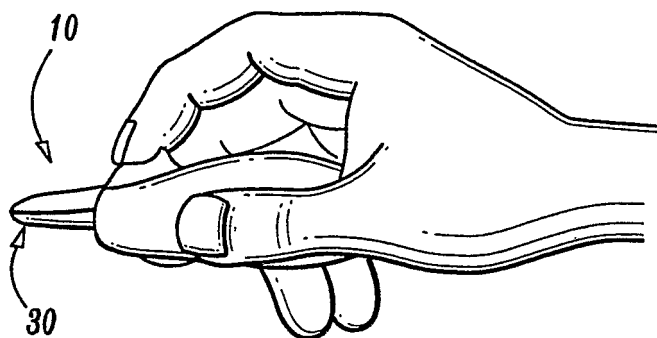


FIG. 1C

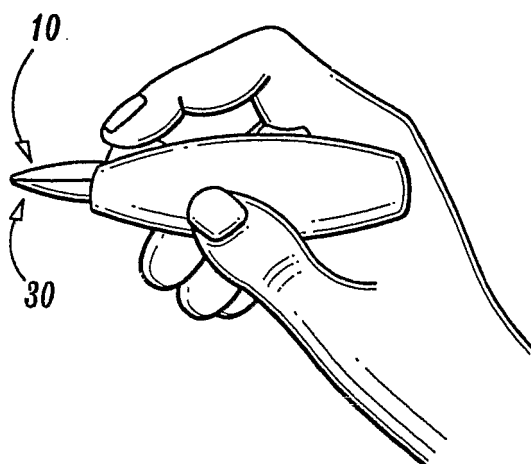


FIG. 1D

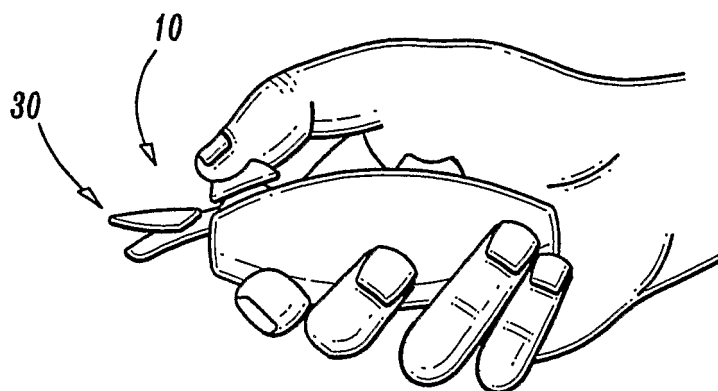


FIG. 1E

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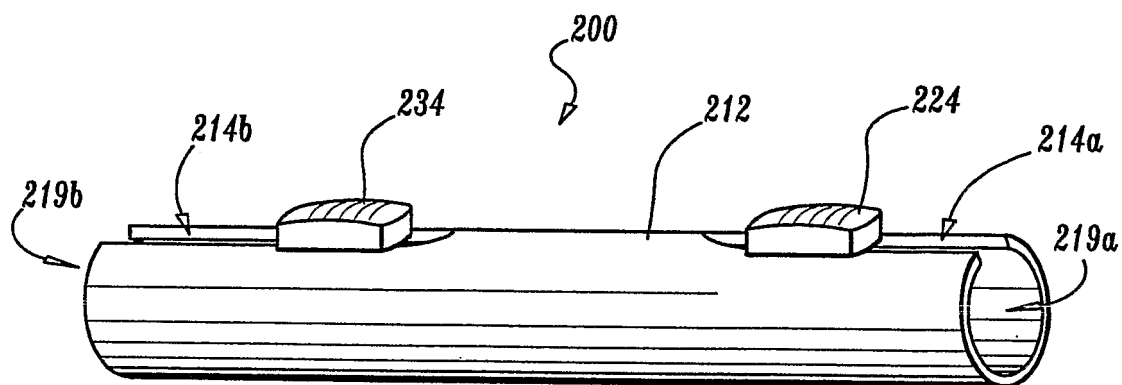


FIG. 2A

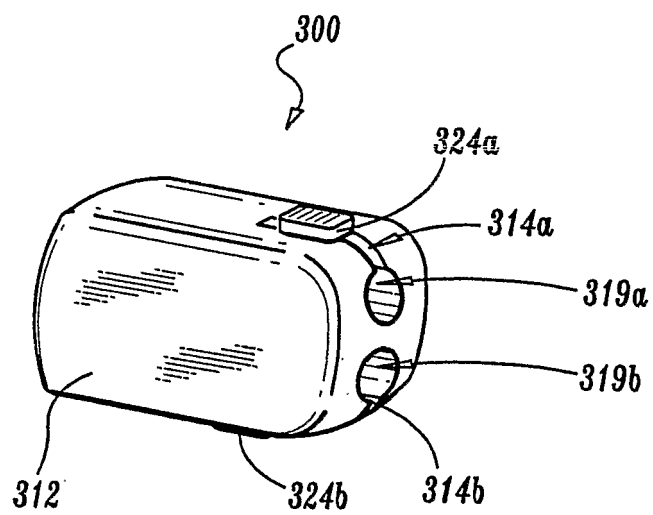
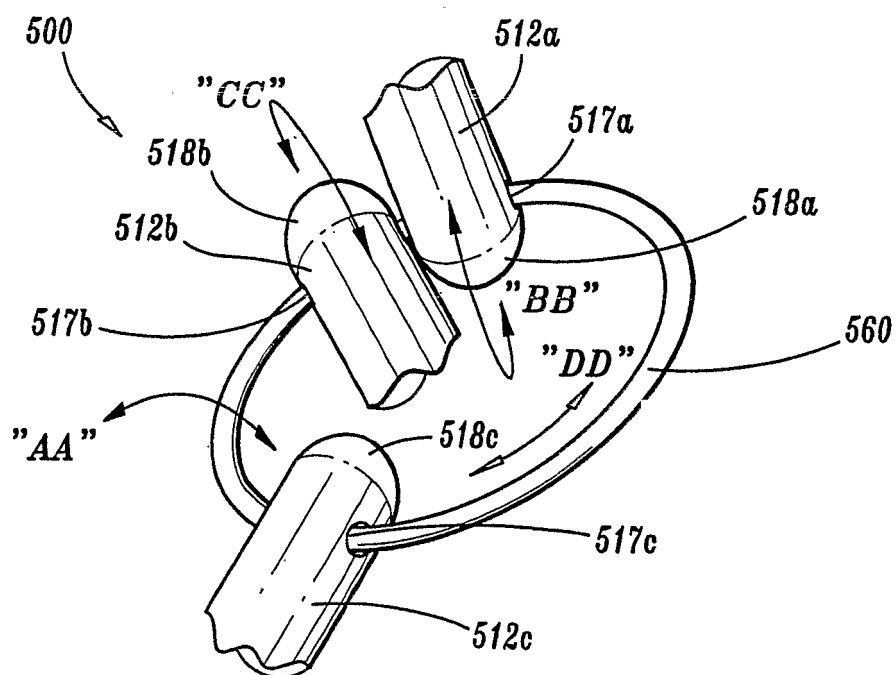
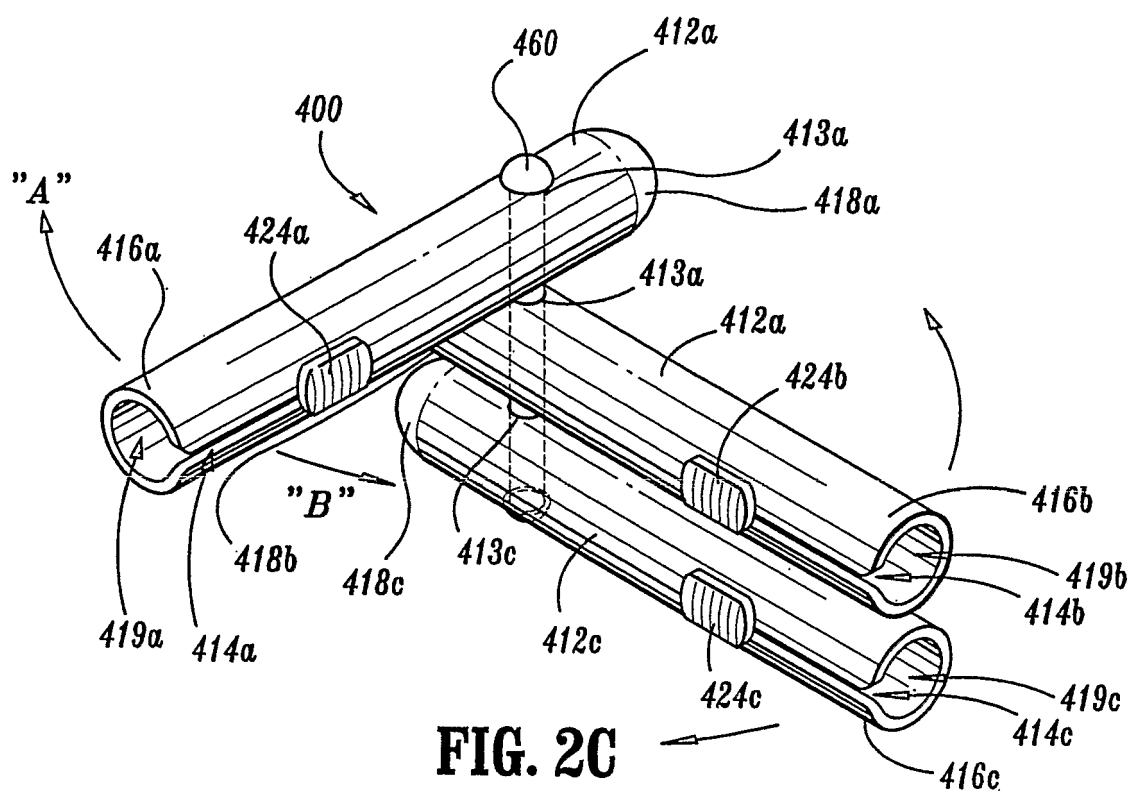
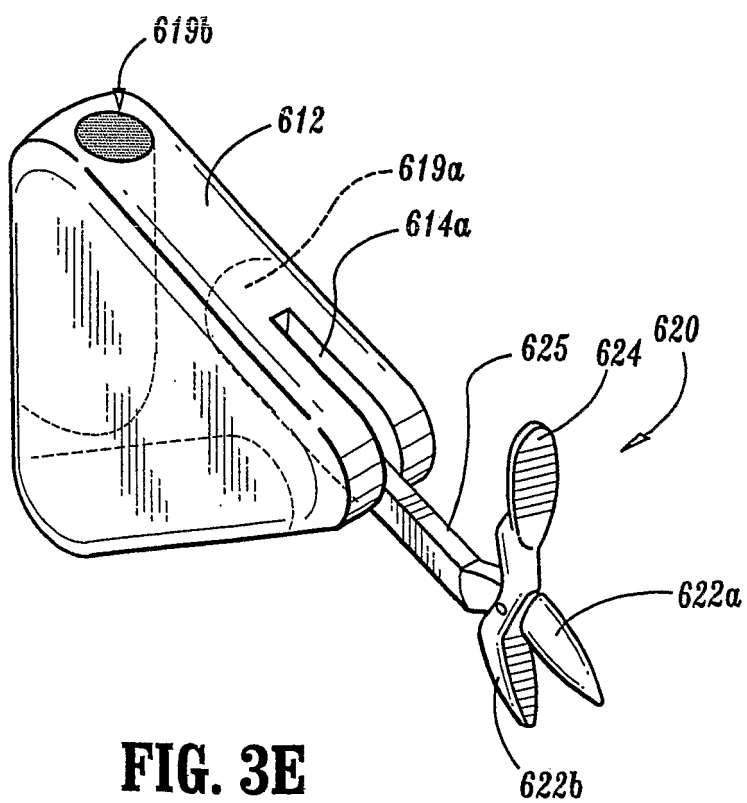
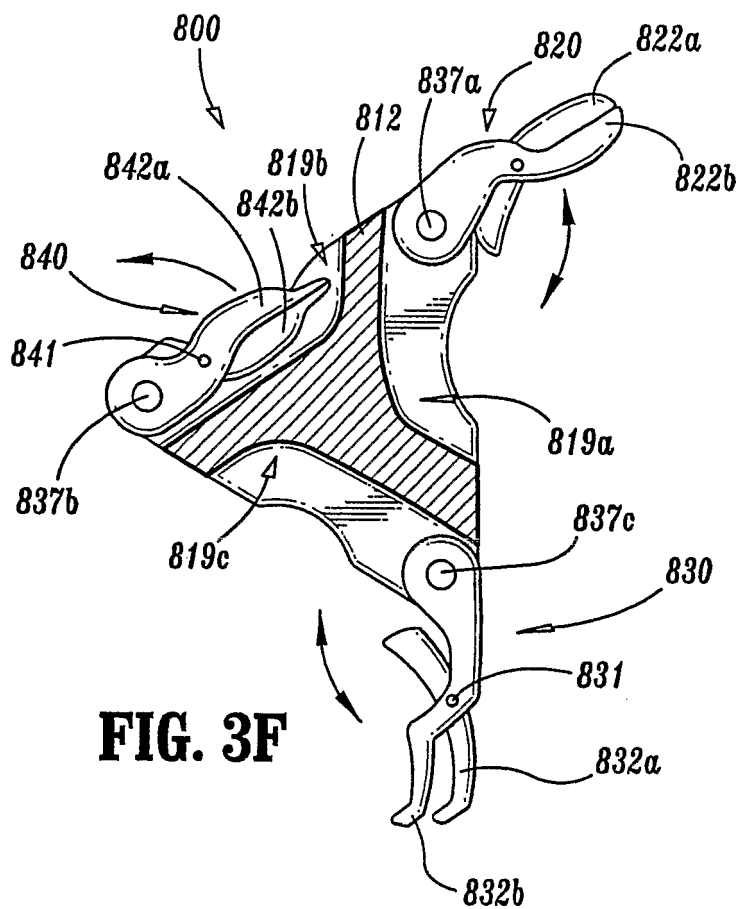


FIG. 2B

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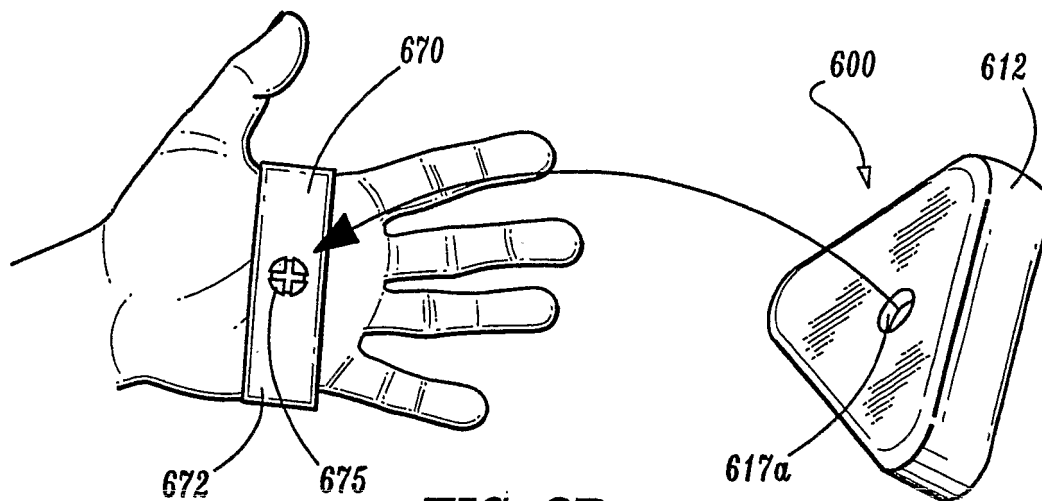


FIG. 3B

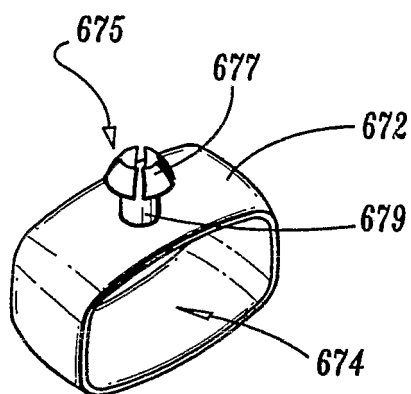


FIG. 3A

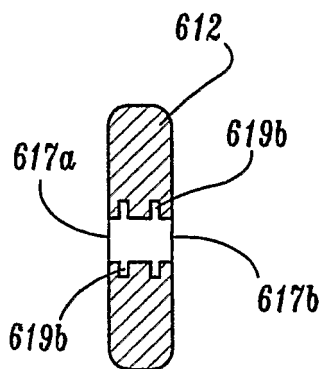


FIG. 3D

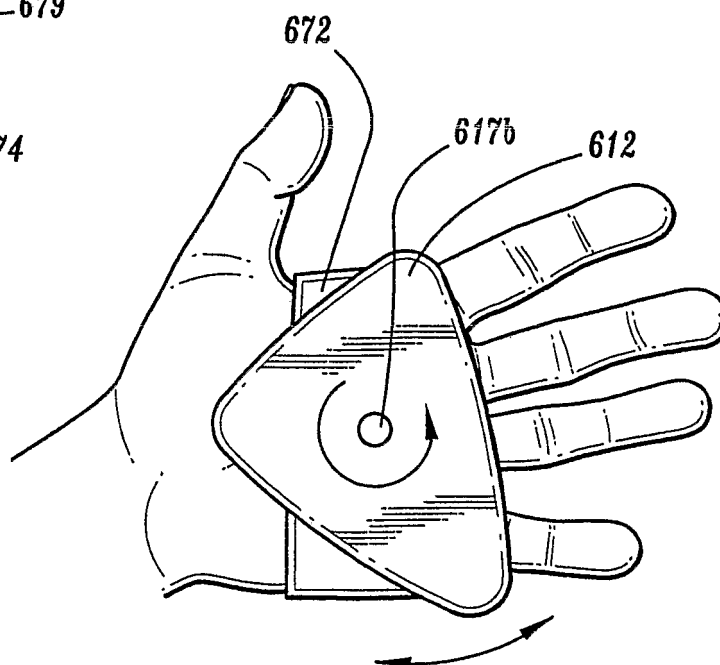
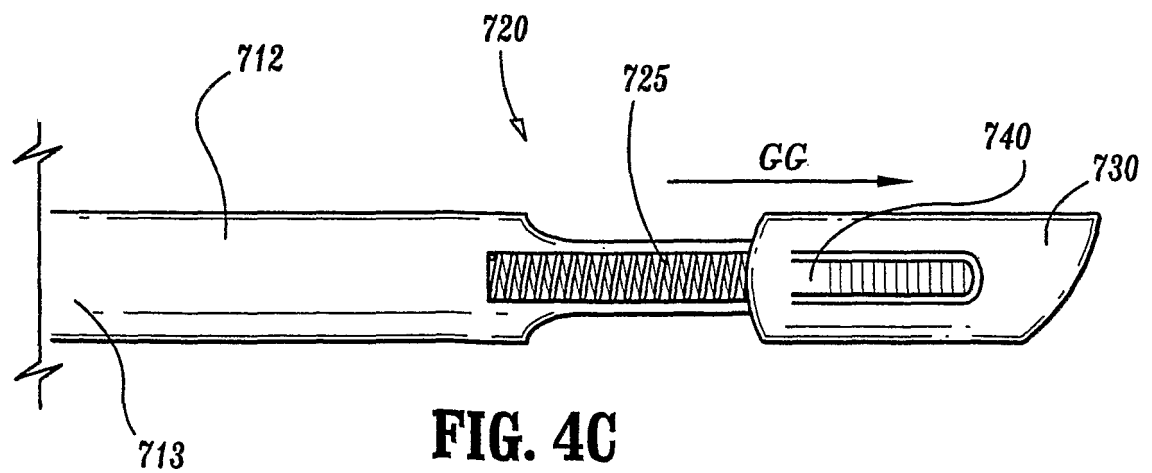
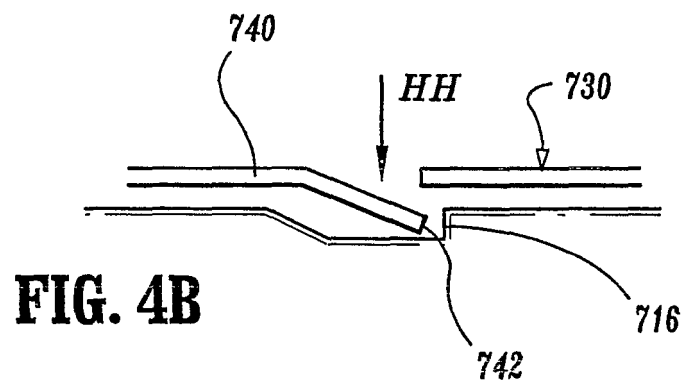
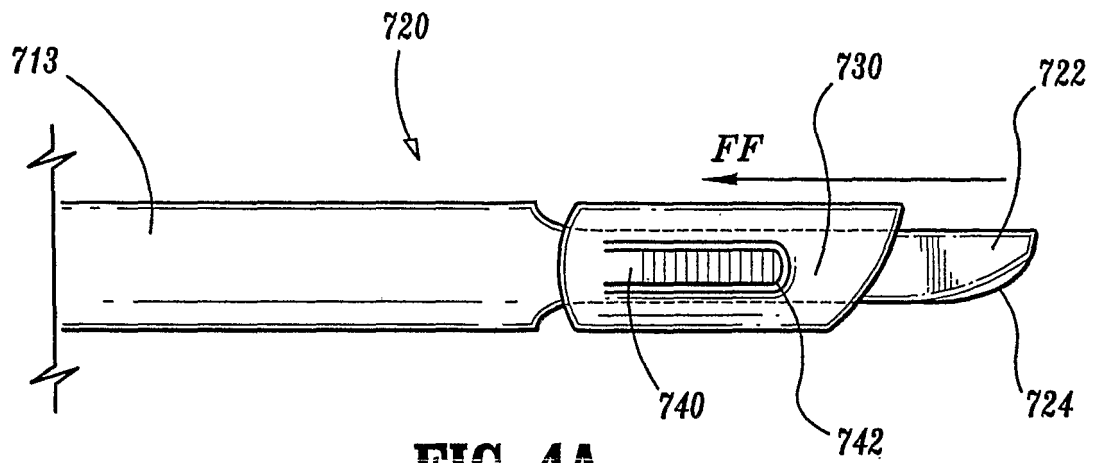


FIG. 3C

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INTERNATIONAL SEARCH REPORT

Internat Application No
PCT/US 03/30396

A. CLASSIFICATION OF SUBJECT MATTER

IPC 7 A61B17/00

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC 7 A61B

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

EPO-Internal, WPI Data

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category °	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	US 2002/098138 A1 (GABELE LORENZ) 25 July 2002 (2002-07-25) paragraph '0039!	1, 10, 12, 18, 22
A	US 5 431 672 A (DOUCETTE THOMAS H ET AL) 11 July 1995 (1995-07-11) the whole document	1, 10, 12, 18, 22

☐ Further documents are listed in the continuation of box C.

☒ Patent family members are listed in annex.

° Special categories of cited documents :

- *A* document defining the general state of the art which is not considered to be of particular relevance
- *E* earlier document but published on or after the international filing date
- *L* document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)
- *O* document referring to an oral disclosure, use, exhibition or other means
- *P* document published prior to the international filing date but later than the priority date claimed

- *T* later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention
- *X* document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone
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- * & * document member of the same patent family

Date of the actual completion of the international search

16 January 2004

Date of mailing of the international search report

27/01/2004

Name and mailing address of the ISA

European Patent Office, P.B. 5818 Patentlaan 2
NL - 2280 HV Rijswijk
Tel. (+31-70) 340-2040, Tx. 31 651 epo nl,
Fax: (+31-70) 340-3016

Authorized officer

Hamann, J

INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No
PCT/US 03/30396

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
US 2002098138 A1	25-07-2002	DE 19935986 C1 WO 0108583 A1 EP 1200004 A1	17-05-2001 08-02-2001 02-05-2002
US 5431672 A	11-07-1995	CA 2147452 A1 DE 69519761 D1 DE 69519761 T2 EP 0681812 A1 JP 2608695 B2 JP 7299076 A	10-11-1995 08-02-2001 07-06-2001 15-11-1995 07-05-1997 14-11-1995

专利名称(译)	多功能手术器械		
公开(公告)号	EP1545320A1	公开(公告)日	2005-06-29
申请号	EP2003752618	申请日	2003-09-25
[标]申请(专利权)人(译)	柯惠有限合伙公司		
申请(专利权)人(译)	泰科医疗集团LP		
当前申请(专利权)人(译)	泰科医疗集团LP		
[标]发明人	BAYER HANSPETER ROBERT HEINRICH RUSSELL		
发明人	BAYER, HANSPETER, ROBERT HEINRICH, RUSSELL		
IPC分类号	A61B17/00 A61B17/04 A61B17/064 A61B17/122 A61B17/128 A61B17/28 A61B17/32		
CPC分类号	A61B17/29 A61B17/062 A61B17/064 A61B17/122 A61B17/128 A61B17/28 A61B17/285 A61B17/3211 A61B2017/00265 A61B2017/00353 A61B2017/0042		
优先权	10/264555 2002-10-04 US 10/428706 2003-05-02 US		
其他公开文献	EP1545320B1		
外部链接	Espacenet		

摘要(译)

在手助腹腔镜手术期间使用的多器械手术工具 (10) 包括壳体，壳体具有设置在其中的多个端口 (14a-d)，每个端口的尺寸设计成可滑动地容纳多个手术器械 (20,30) 中的一个。 ， 40,50) 从案例中选择性部署。壳体还包括相应的多个细长通道，每个细长通道与多个端口中的相应一个连通。每个器械包括致动器 (24,34)，致动器 (24,34) 可在相应的通道内从第一位置移动，其中器械至少部分地容纳在壳体内至第二位置，其中致动器从相应的通道和致动器脱离可自由操作以启动仪器以达到其预期目的。