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Forsell

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(54) **HIP JOINT INSTRUMENT AND METHOD**
(76) Inventor: **Peter Forsell**, Bouveret (CH)
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Jul. 10, 2009 (SE) 0900959
Jul. 10, 2009 (SE) 0900960
Jul. 10, 2009 (SE) 0900962
Jul. 10, 2009 (SE) 0900963
Jul. 10, 2009 (SE) 0900965
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Jul. 10, 2009 (SE) 0900976
Jul. 10, 2009 (SE) 0900978
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Jul. 10, 2009 (SE) 0900972

(51) **Int. Cl.**
A61B 17/16 (2006.01)
A61B 17/88 (2006.01)
(Continued)

(52) **U.S. Cl.**
CPC *A61B 17/1662* (2013.01); *A61B 17/1615* (2013.01); *A61B 17/1631* (2013.01);
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(58) **Field of Classification Search**
USPC 606/79, 80, 81; 623/22.12
See application file for complete search history.

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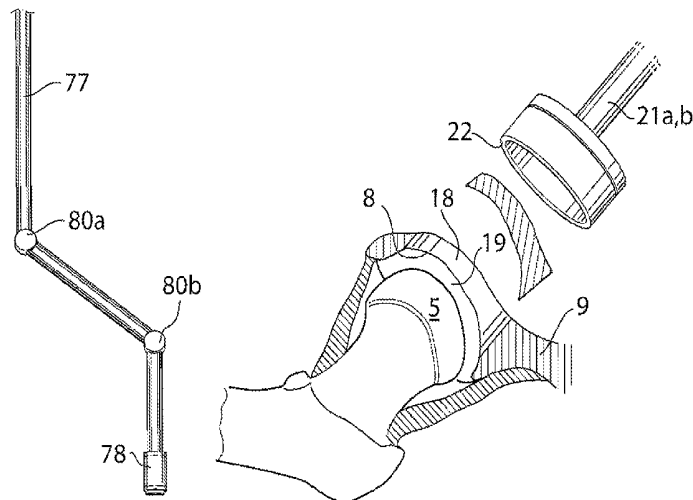
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Primary Examiner — Christian Sevilla

(57) **ABSTRACT**
A surgical instrument for operating hip joint osteoarthritis in a human patient is provided. The hip joint comprises an acetabulum, being a part of the pelvic bone, and a caput femur, being the proximal part of the femoral bone. The surgical instrument is adapted to assist in the operating of the hip joint osteoarthritis from the abdominal side of the pelvic bone of said human patient.

16 Claims, 32 Drawing Sheets



Related U.S. Application Data

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A61F 2/30 (2006.01)
A61F 2/46 (2006.01)
A61B 17/80 (2006.01)
A61B 17/00 (2006.01)

(52) **U.S. Cl.**

CPC *A61B17/1666* (2013.01); *A61B 17/8875* (2013.01); *A61F 2/30721* (2013.01); *A61F 2/4607* (2013.01); *A61F 2/4609* (2013.01); *A61B 17/1637* (2013.01); *A61B 17/1668* (2013.01); *A61B 17/8061* (2013.01); *A61B 2017/0034* (2013.01); *A61F 2002/30494* (2013.01); *A61F 2002/30754* (2013.01); *A61F 2002/4622* (2013.01); *A61F 2002/4628* (2013.01)

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Fig.1

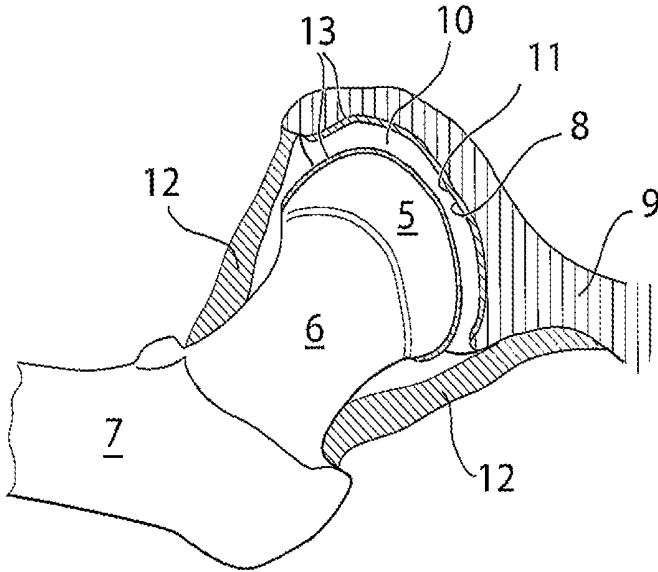


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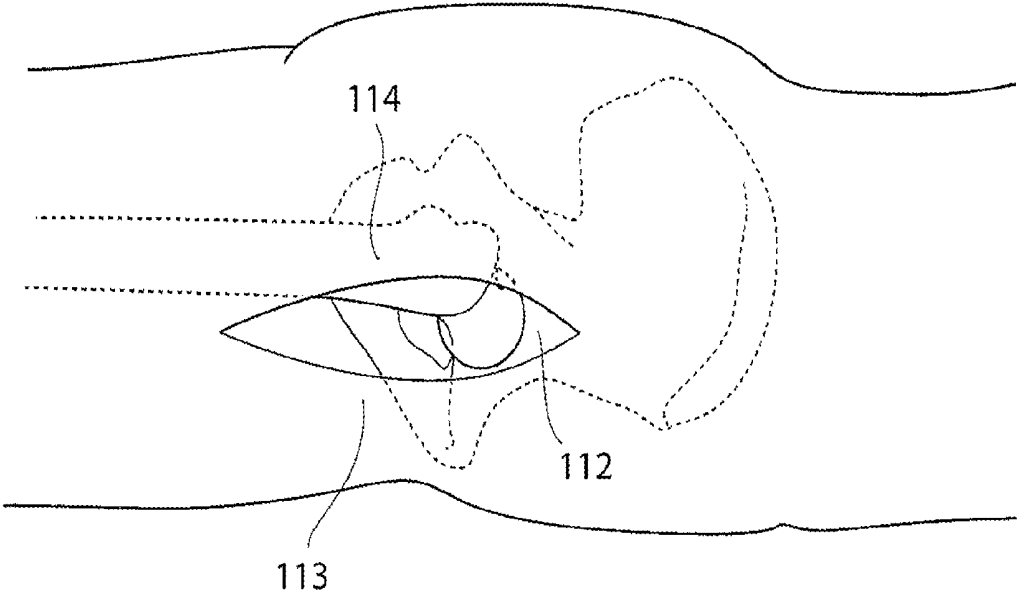


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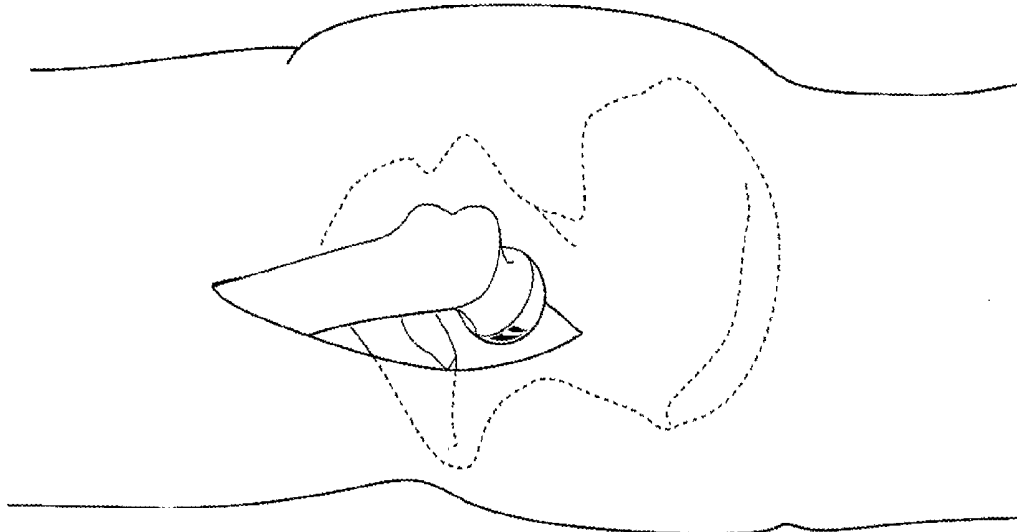


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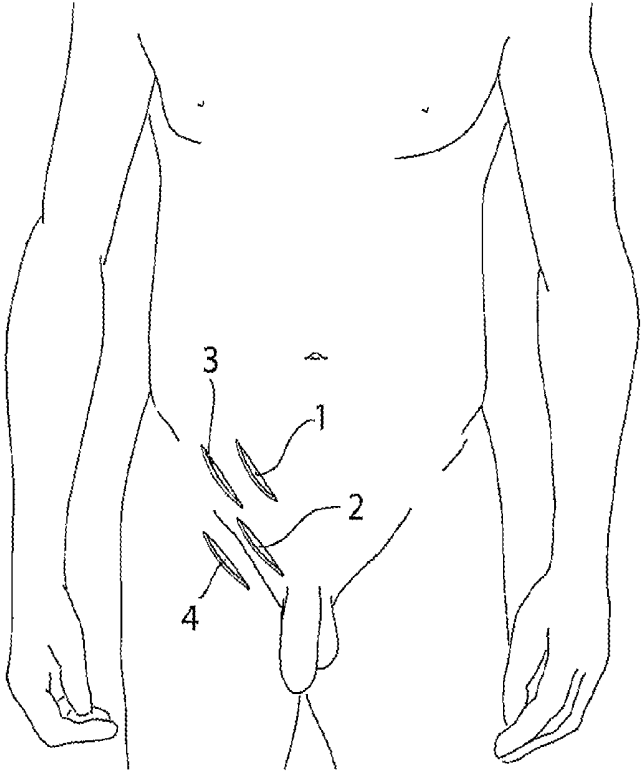
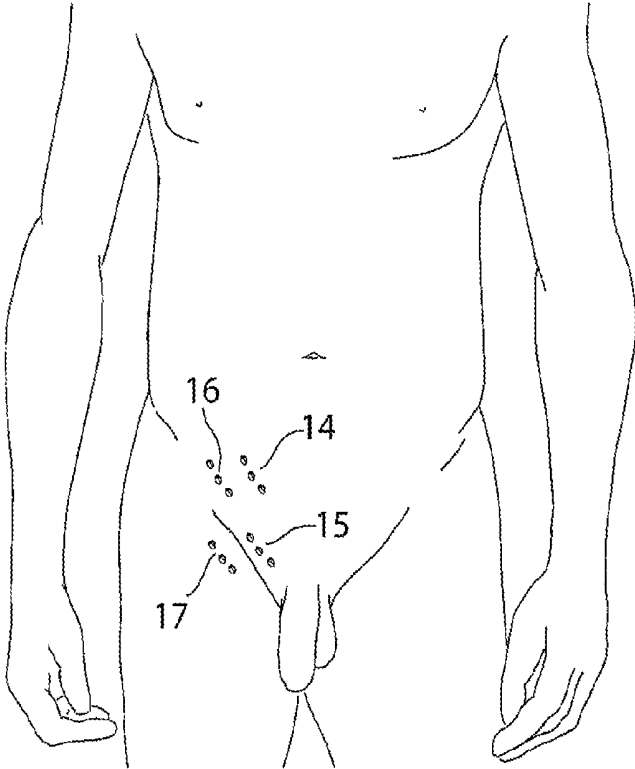
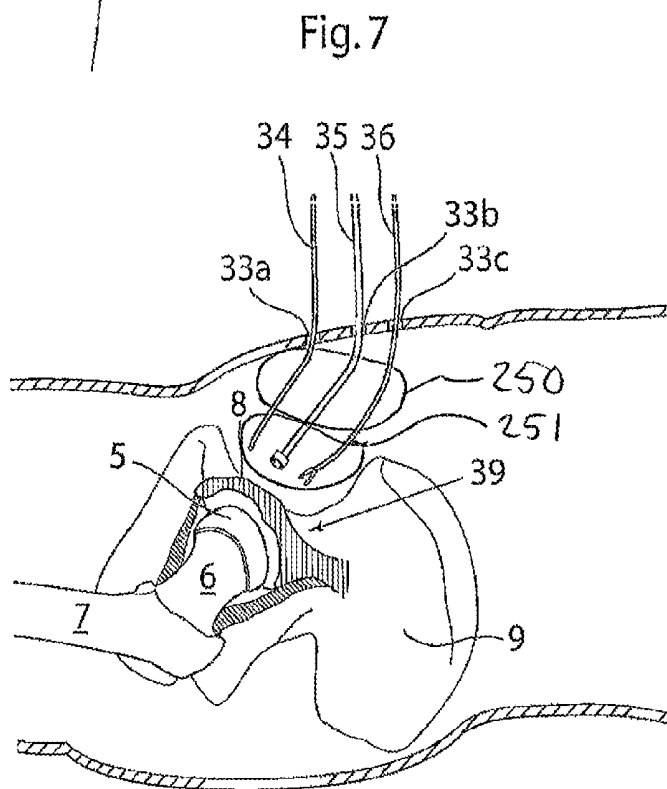
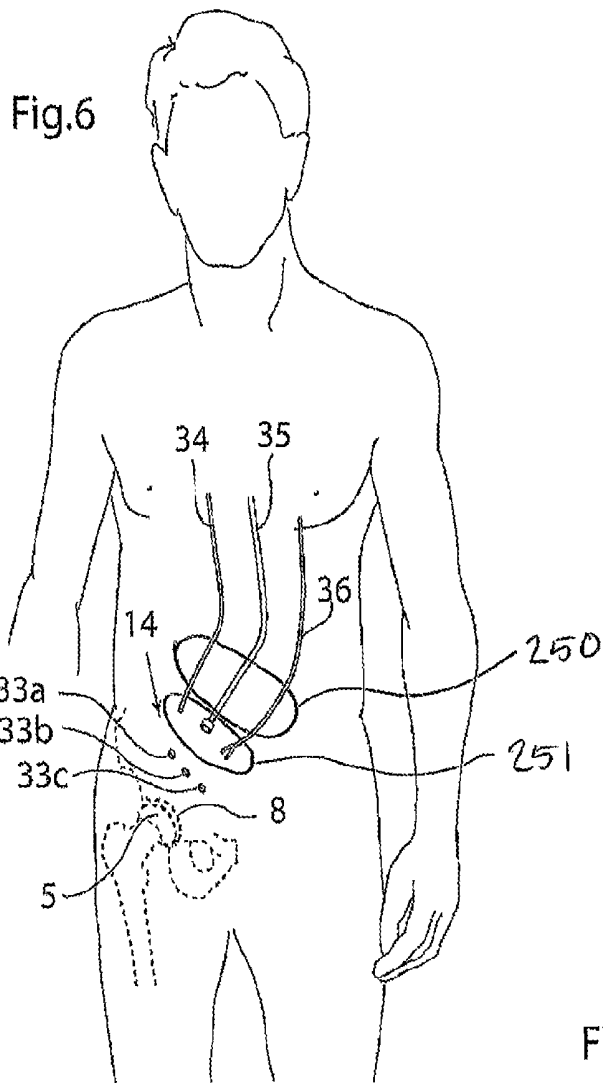


Fig.5





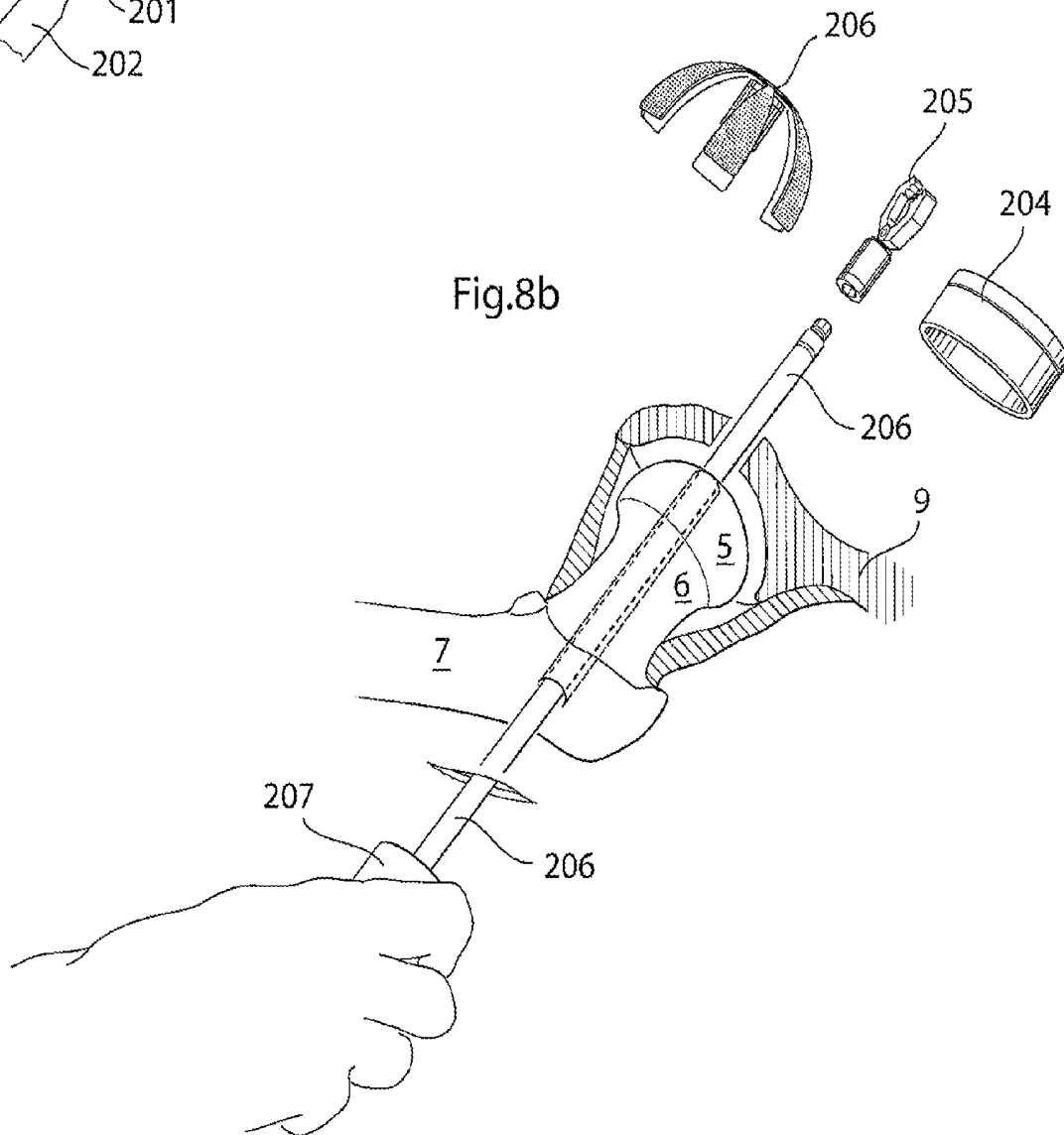
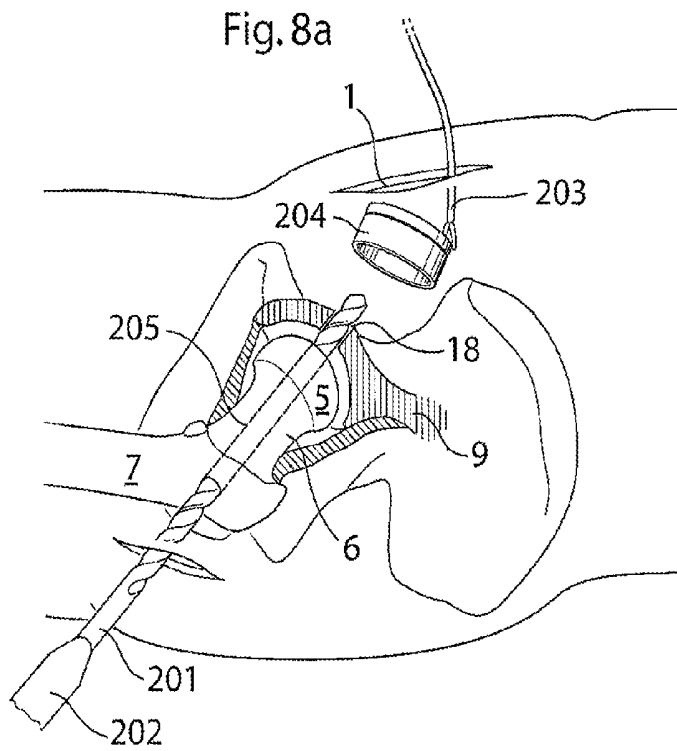


Fig. 9a

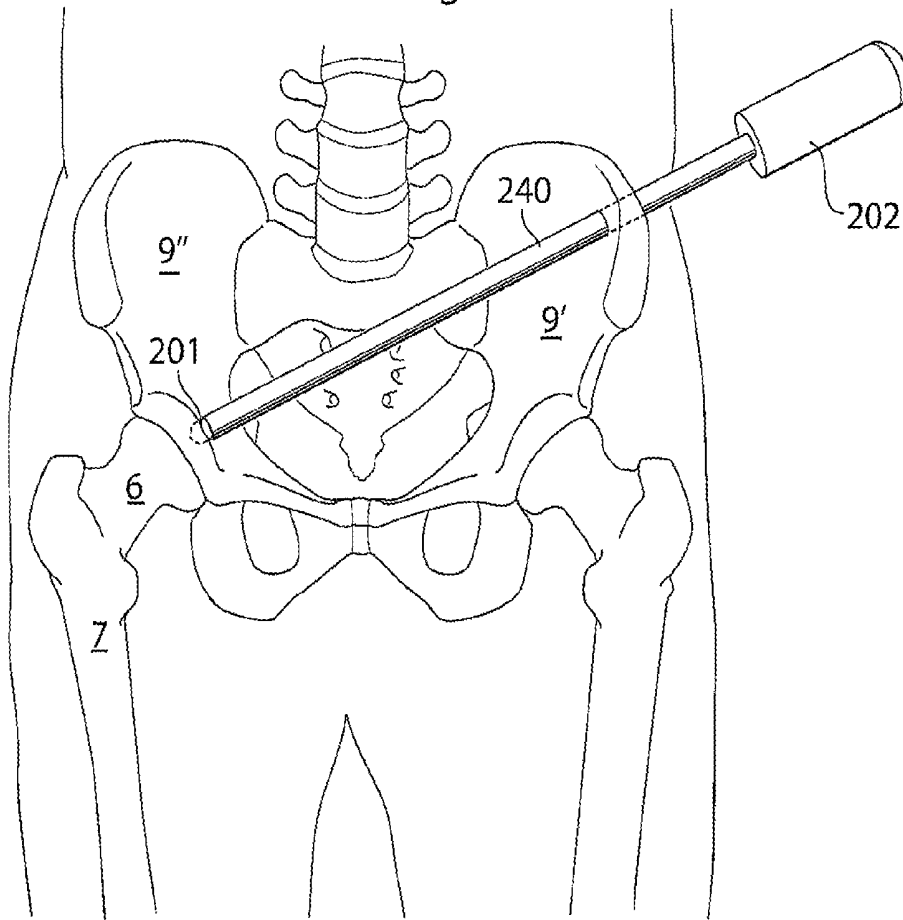


Fig. 9b

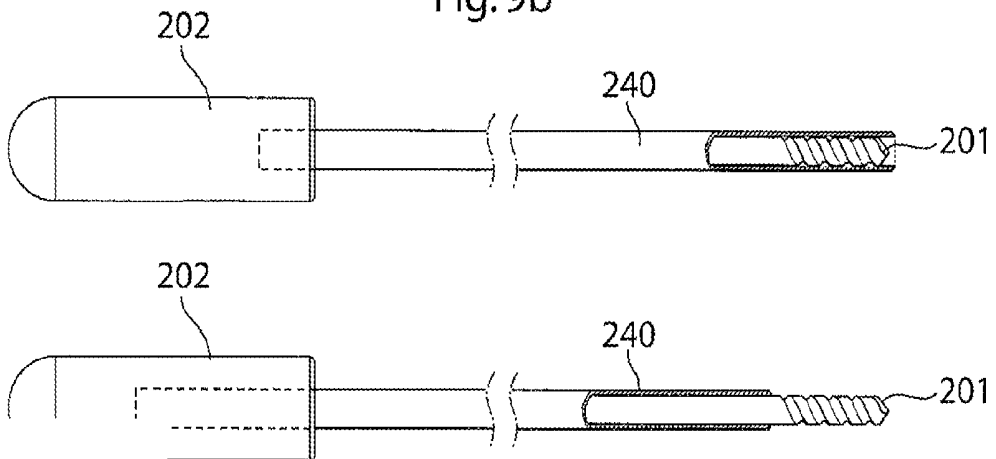


Fig.10a

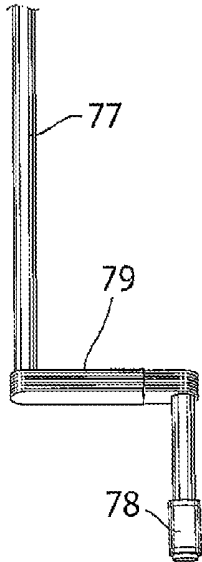


Fig.10c

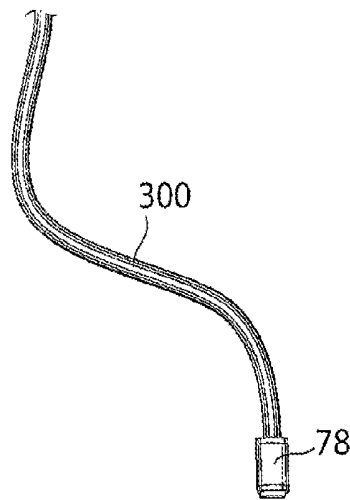


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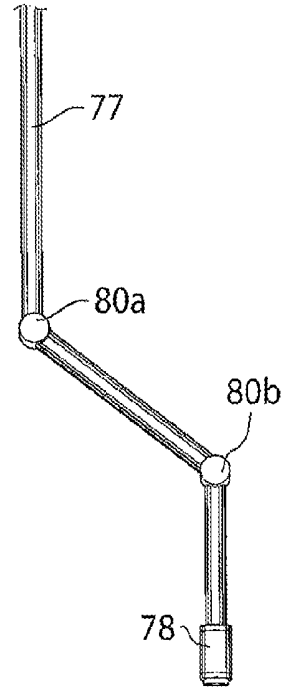


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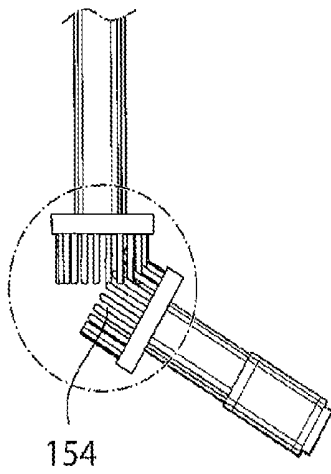


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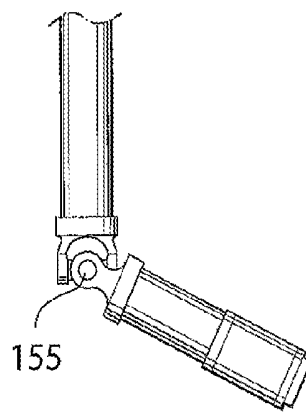
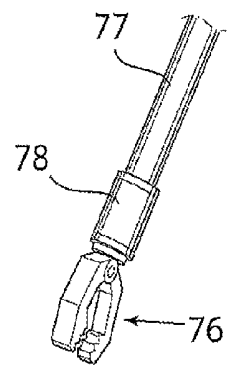


Fig.13



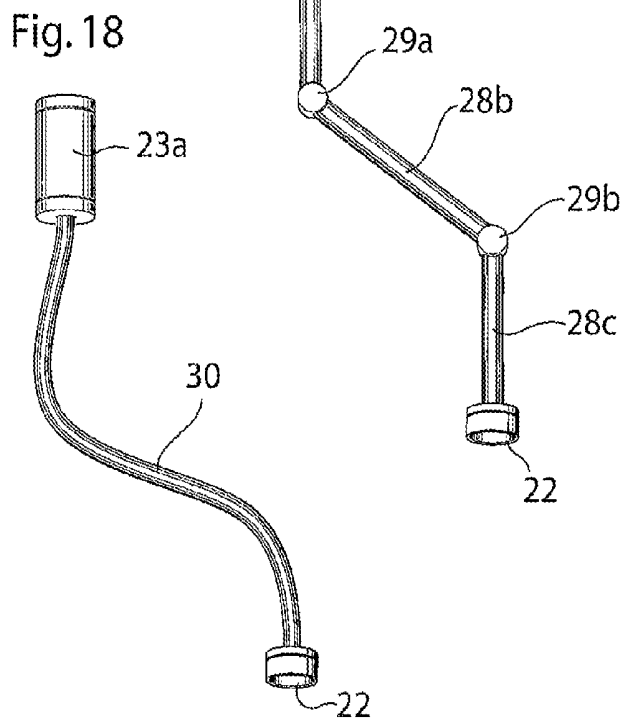
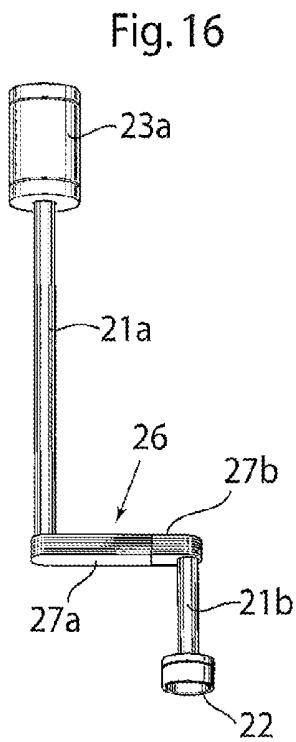
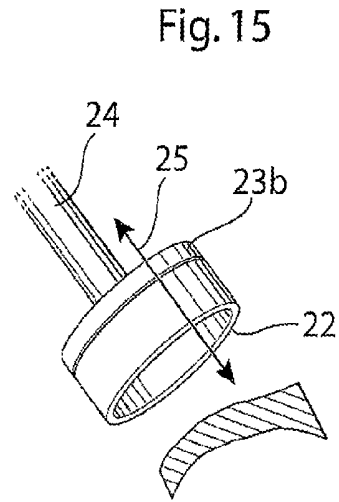
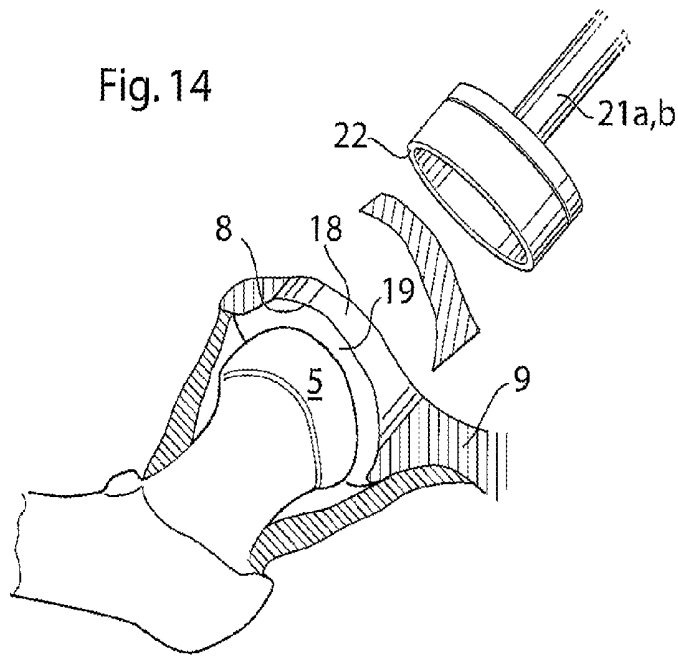


Fig.19a

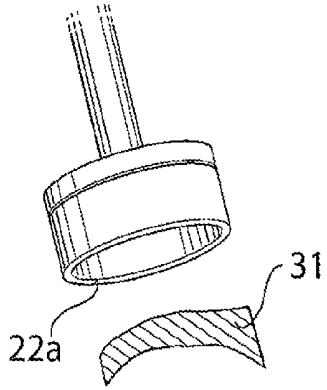


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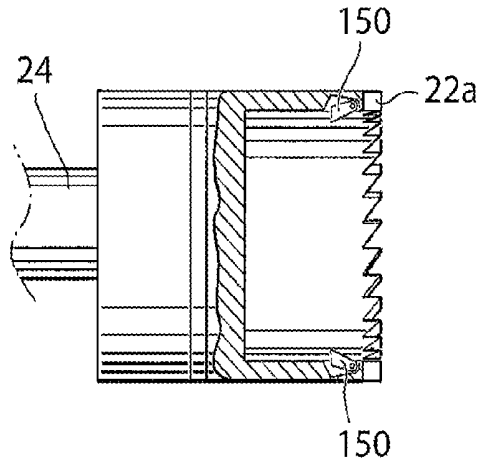


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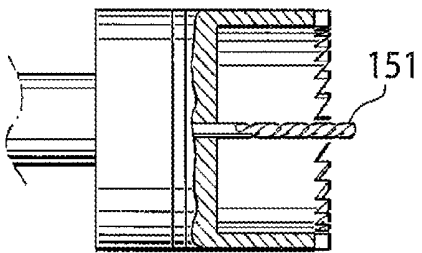


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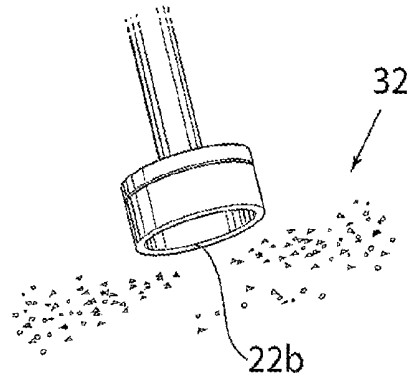


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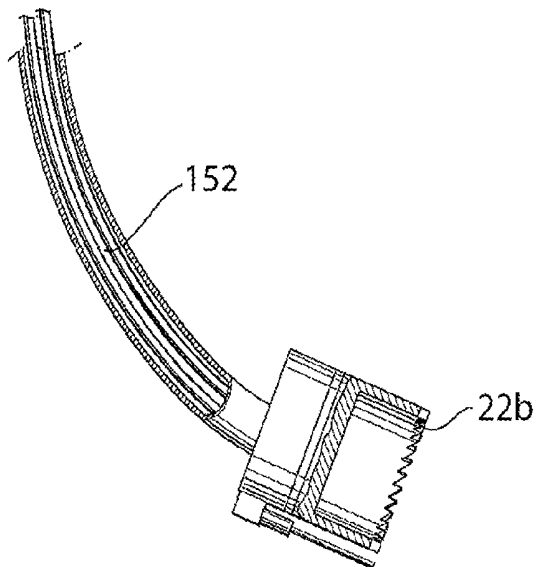


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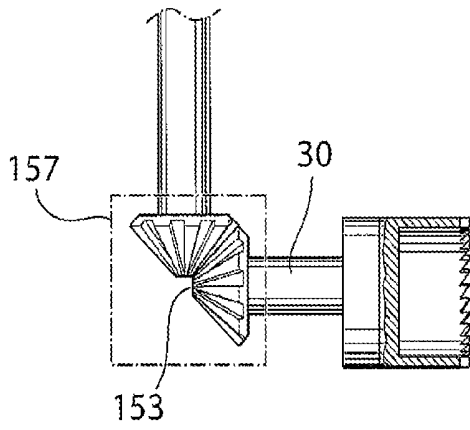


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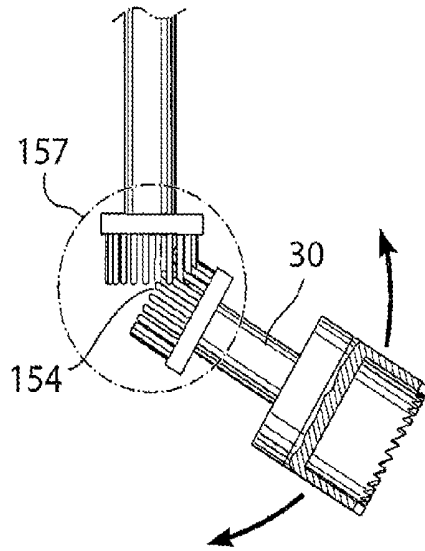


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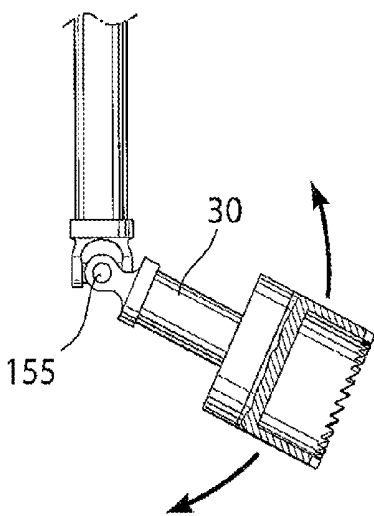
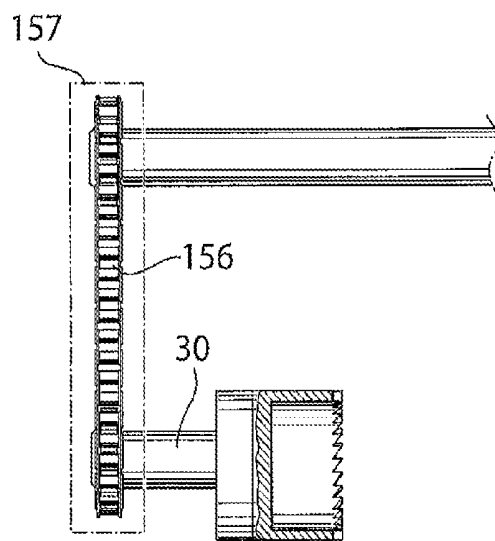


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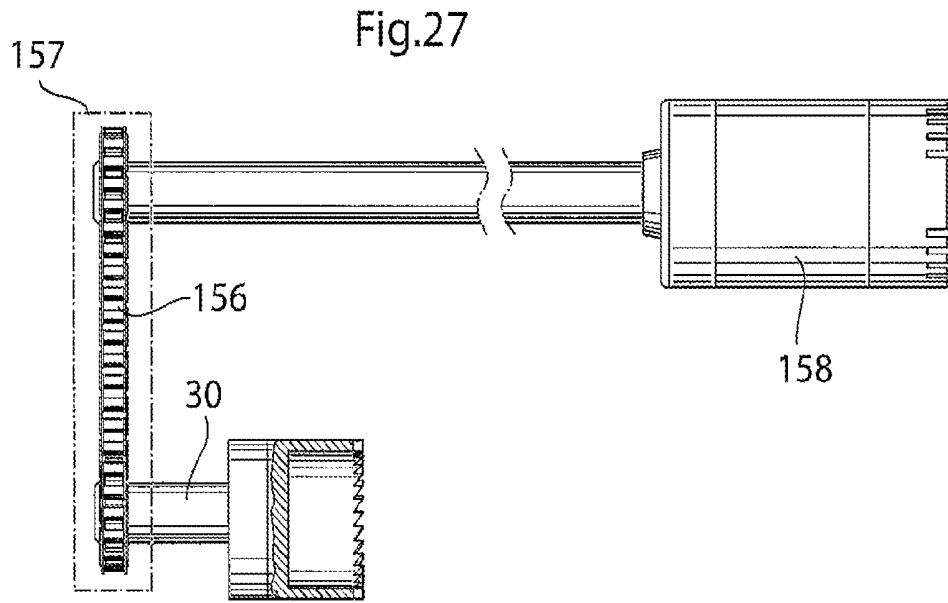


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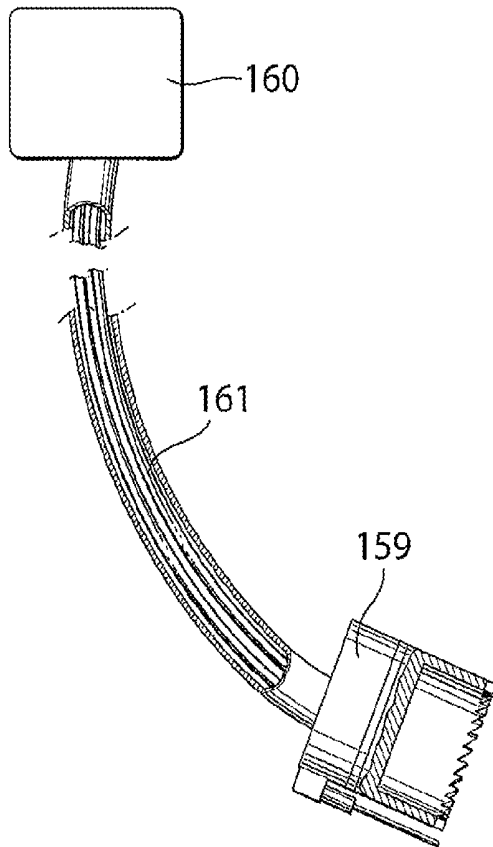


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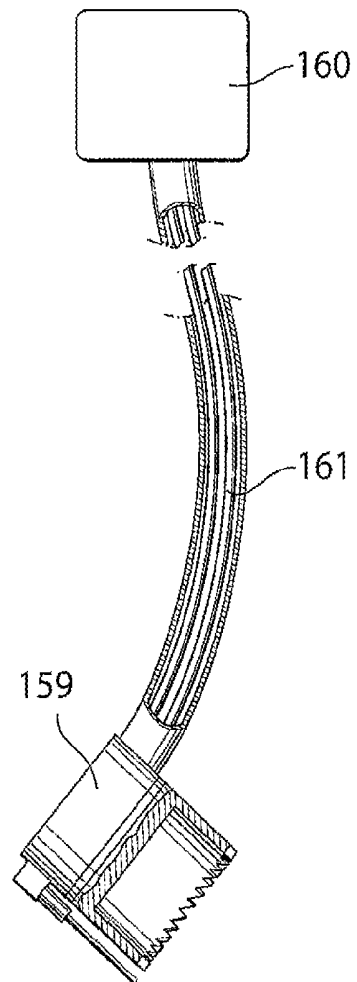


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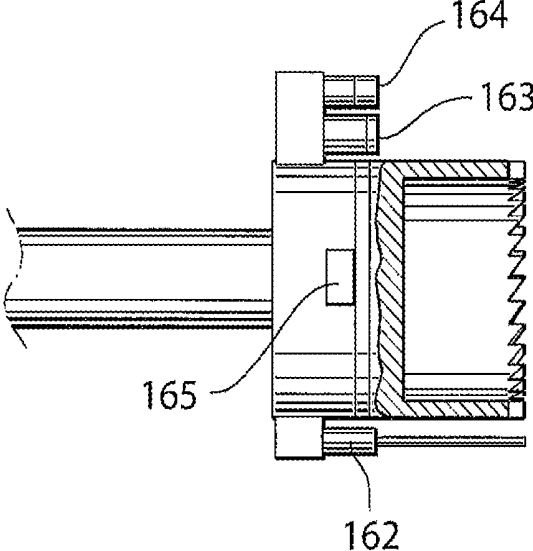


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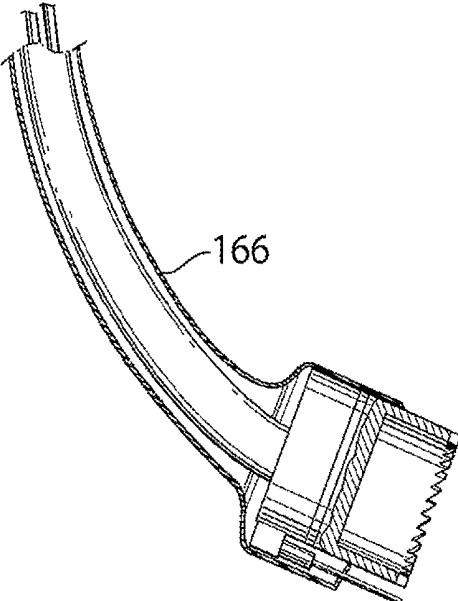


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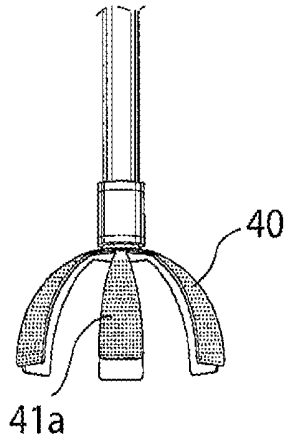


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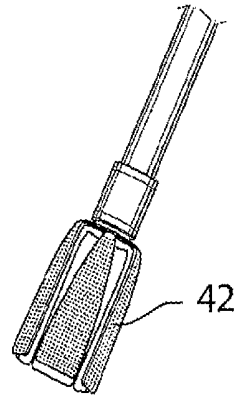


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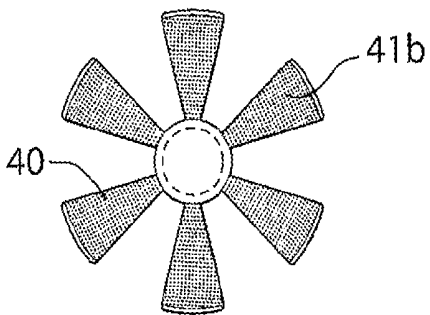


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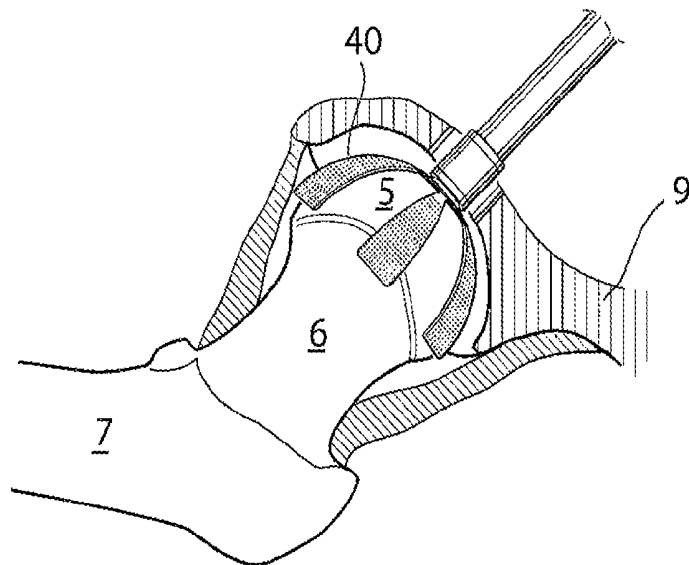


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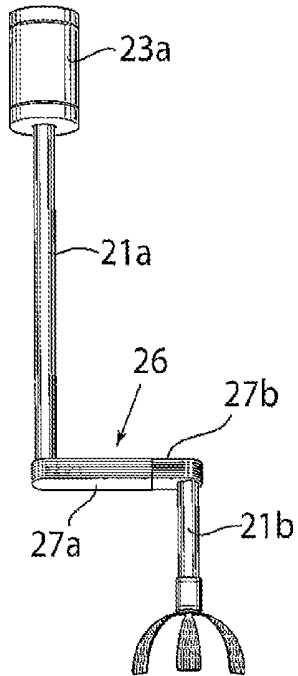


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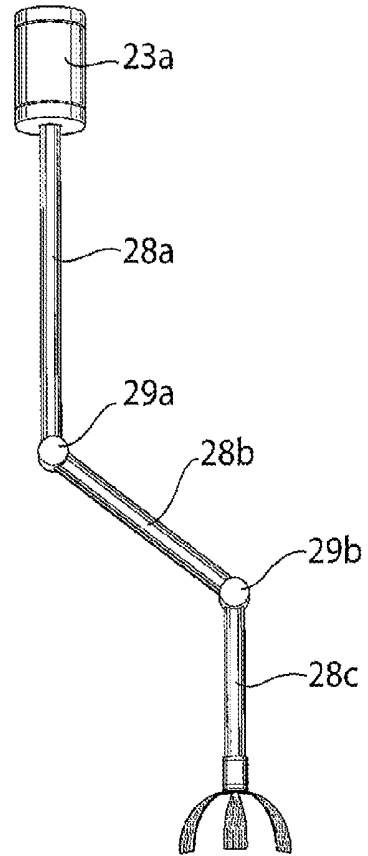


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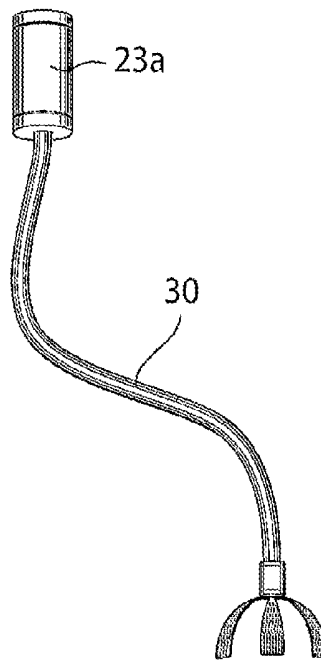


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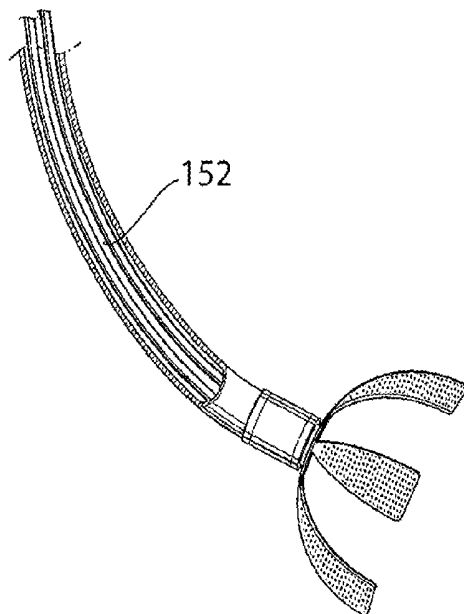


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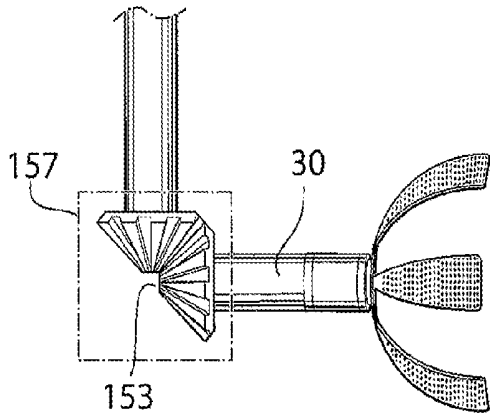


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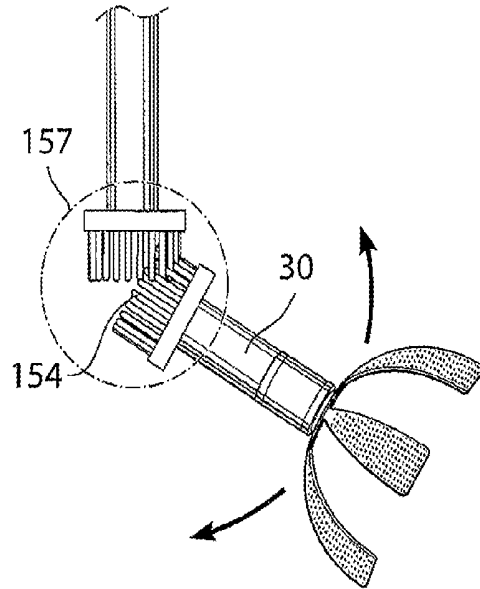


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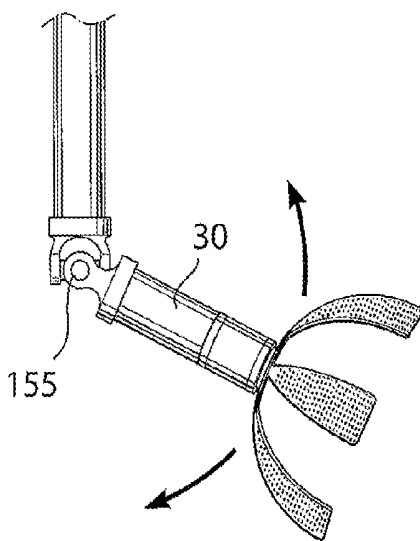


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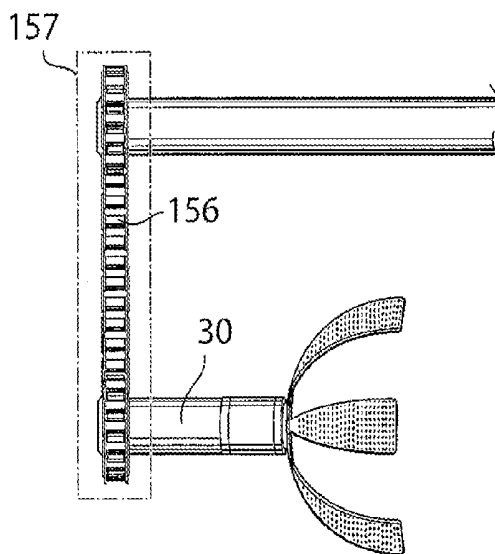


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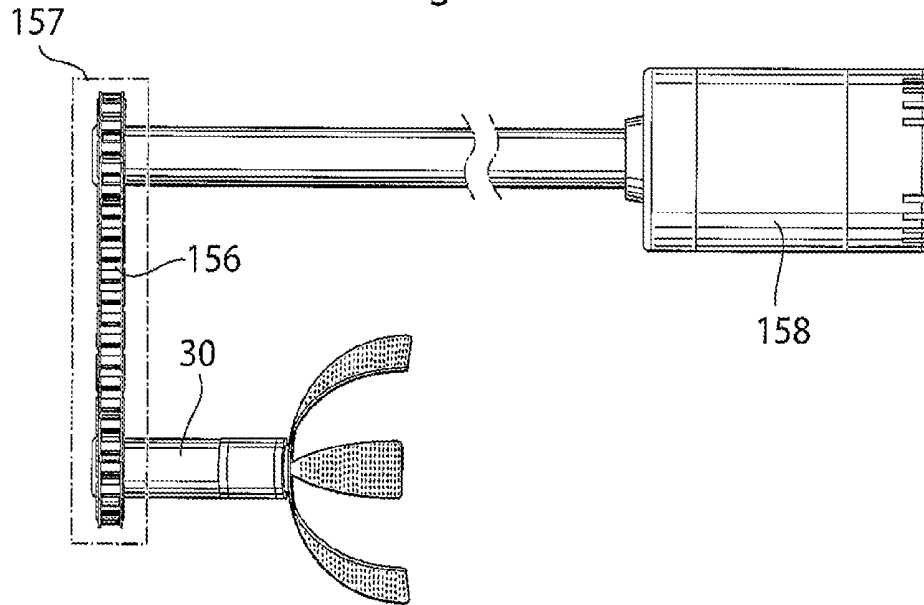


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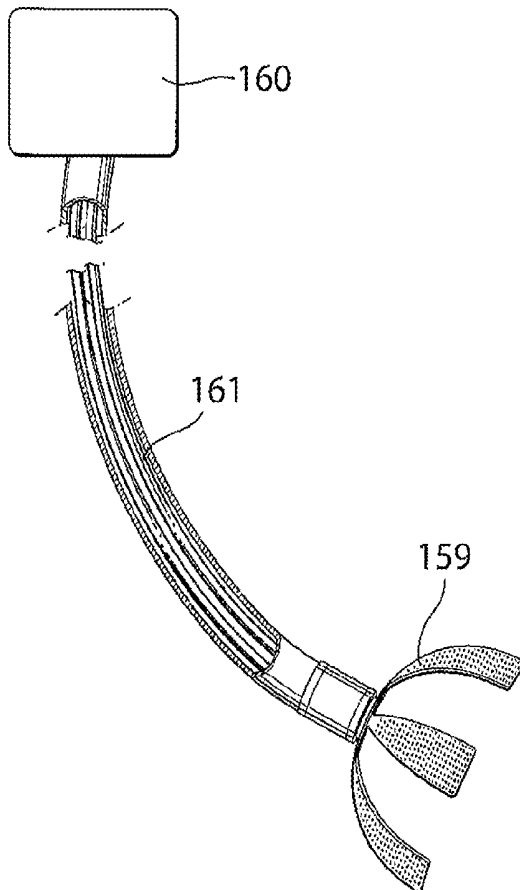


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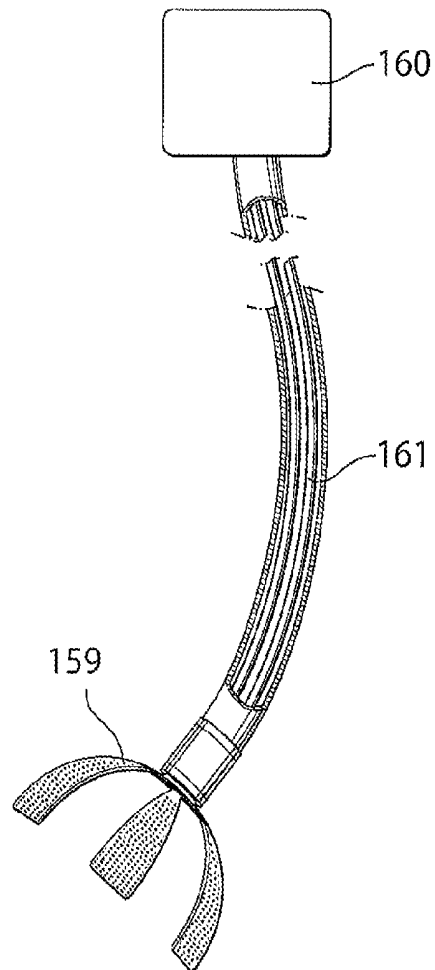


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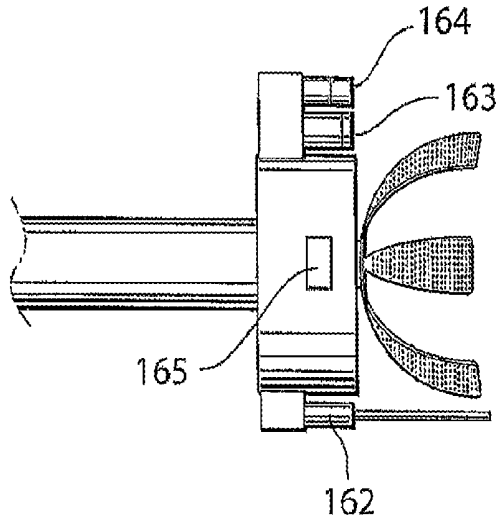


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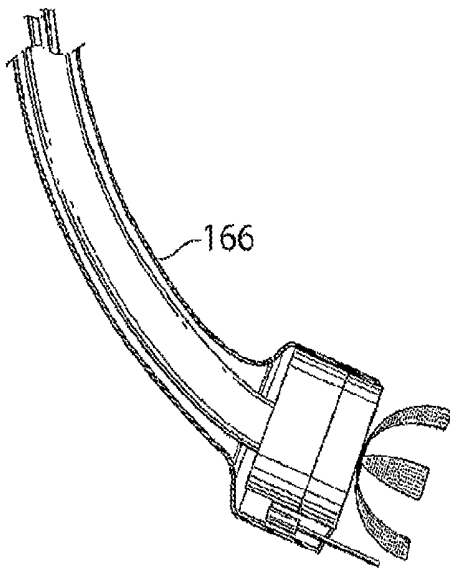


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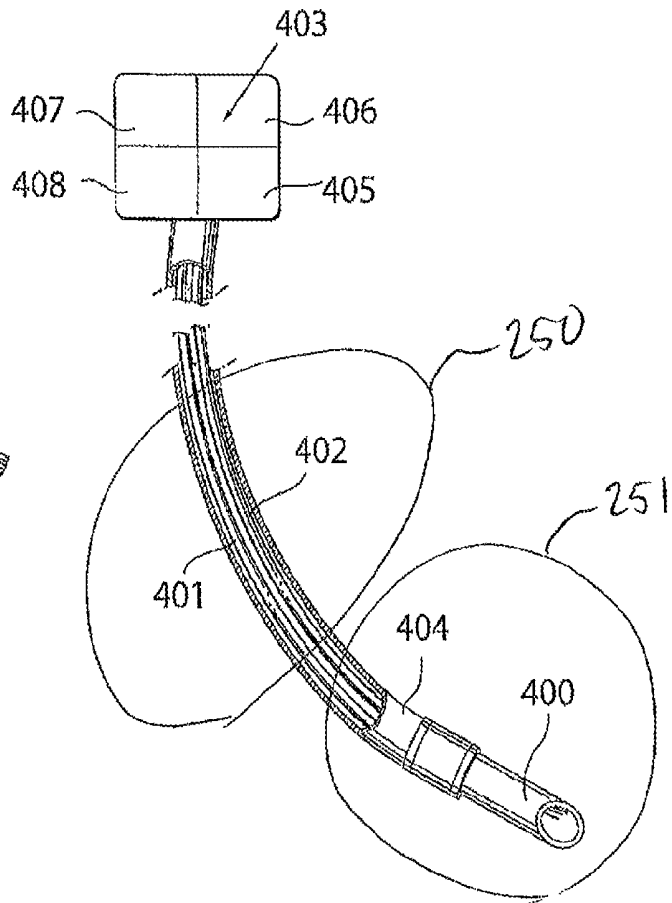


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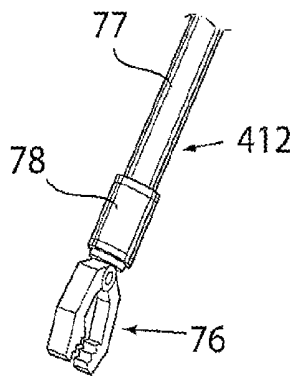


Fig. 50

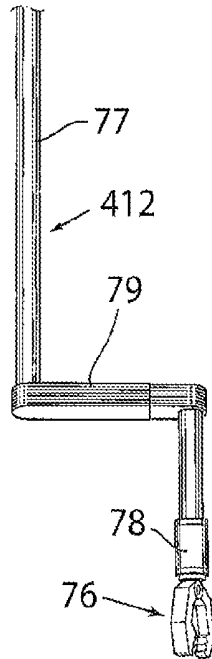


Fig. 51

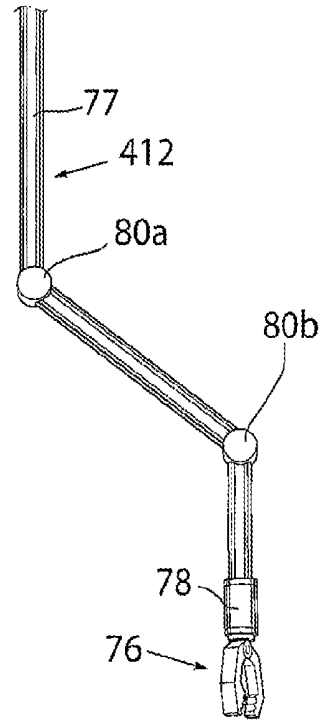


Fig. 52

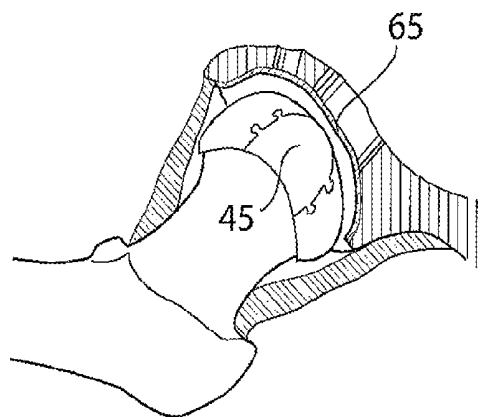


Fig.53

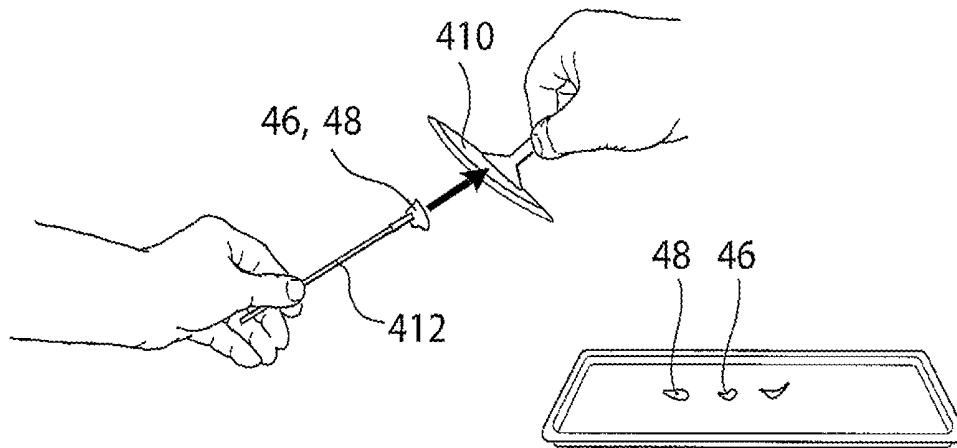
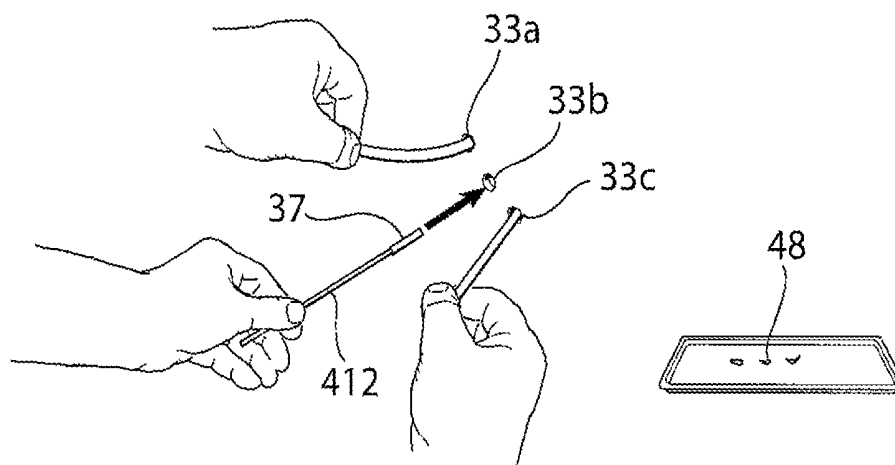
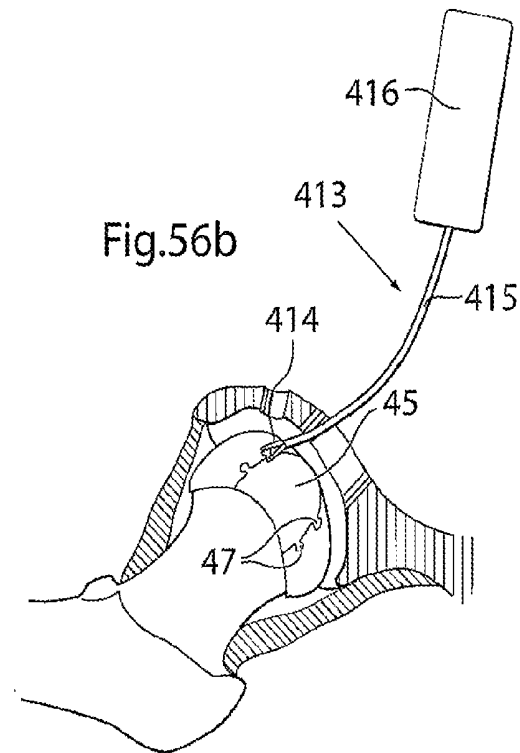
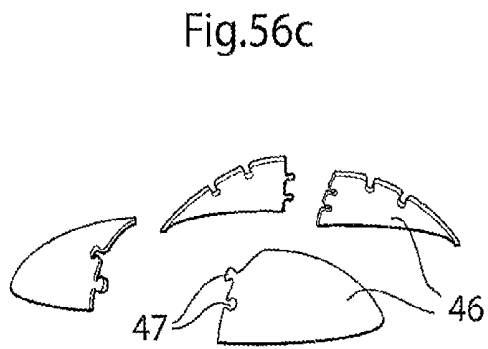
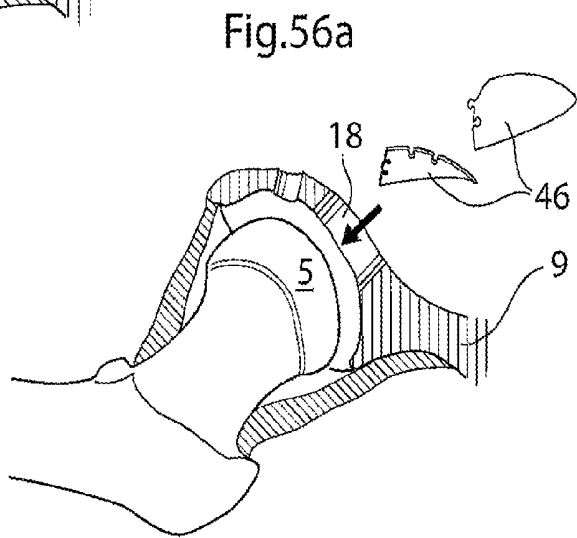
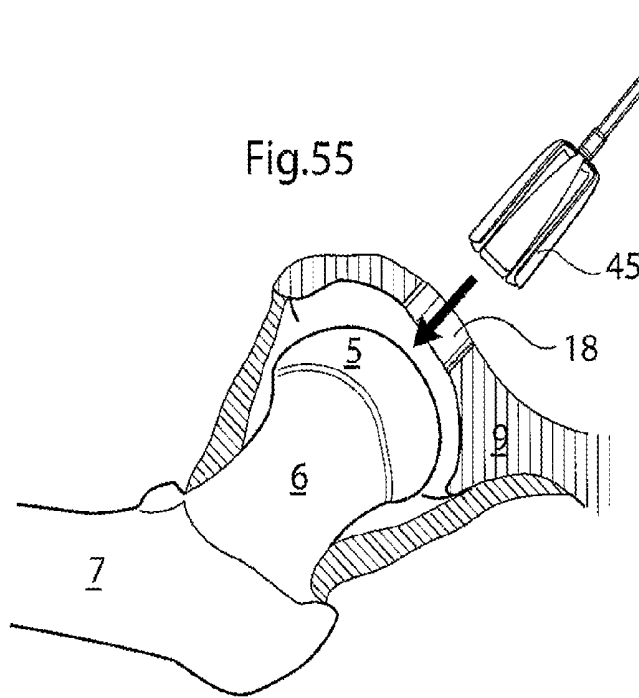


Fig.54





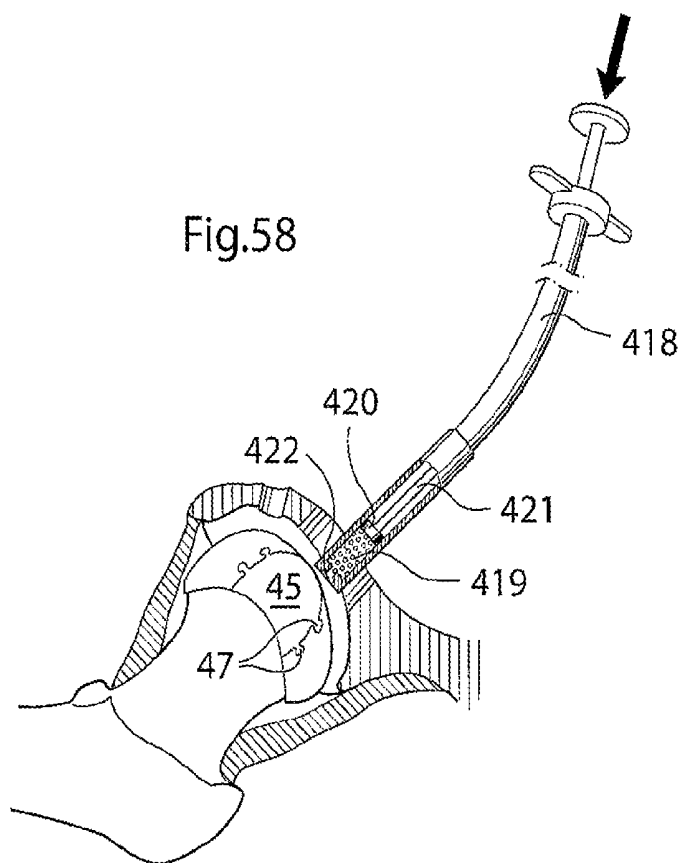
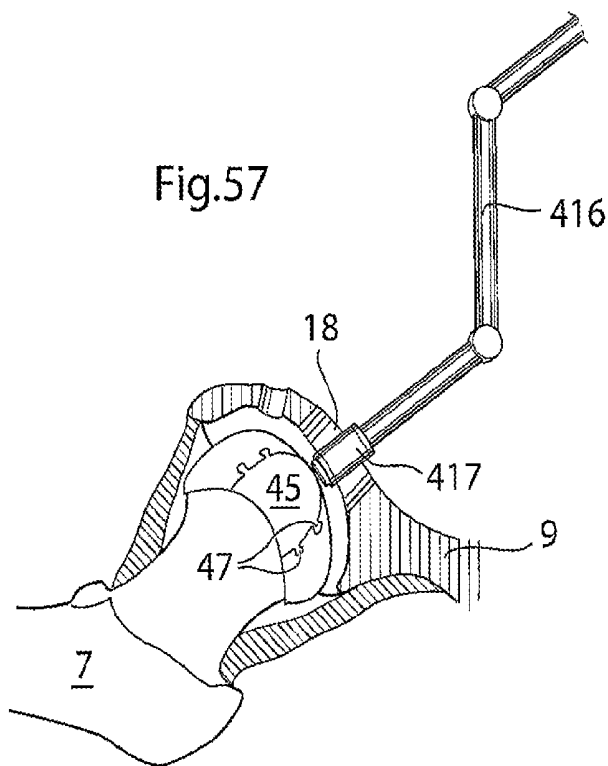


Fig.59a

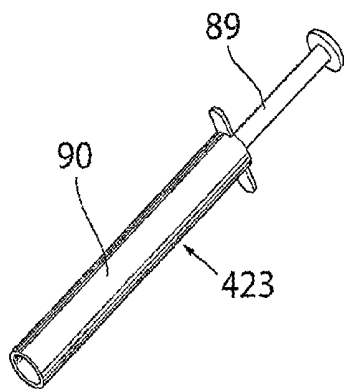


Fig.59b

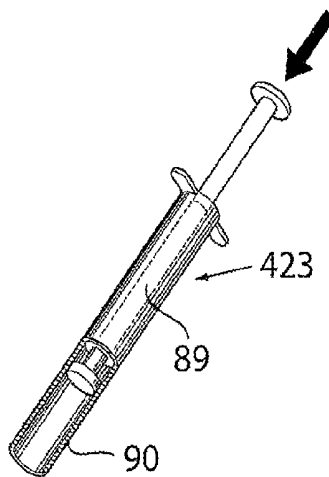


Fig.59c

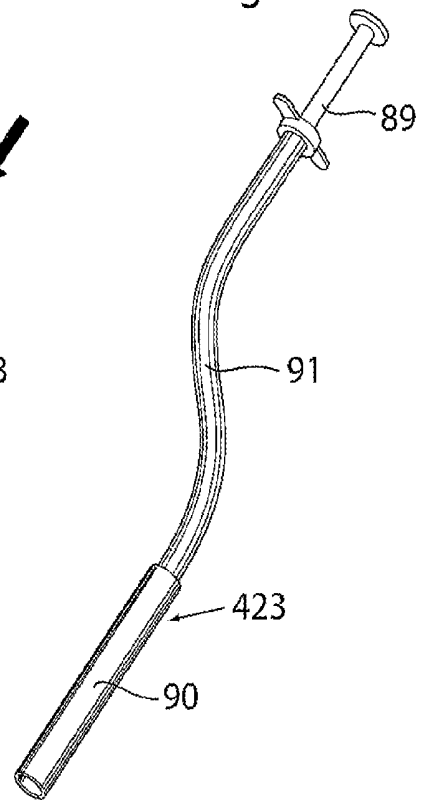


Fig.60a

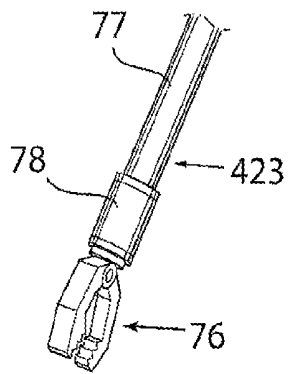


Fig.60b

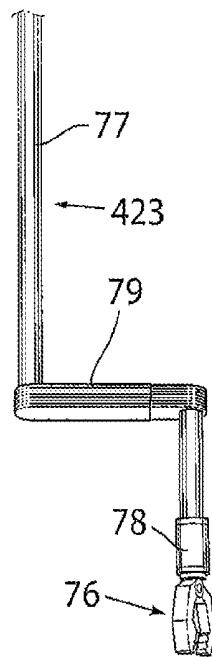
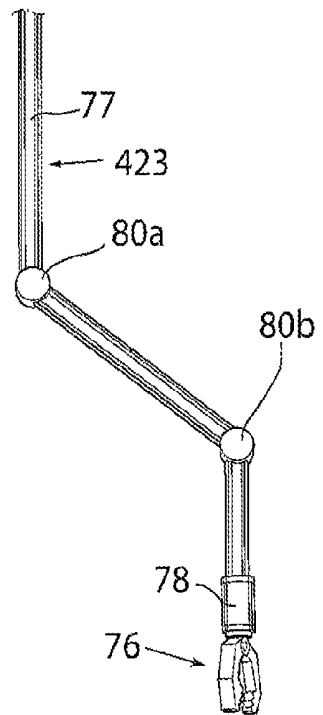


Fig.60c



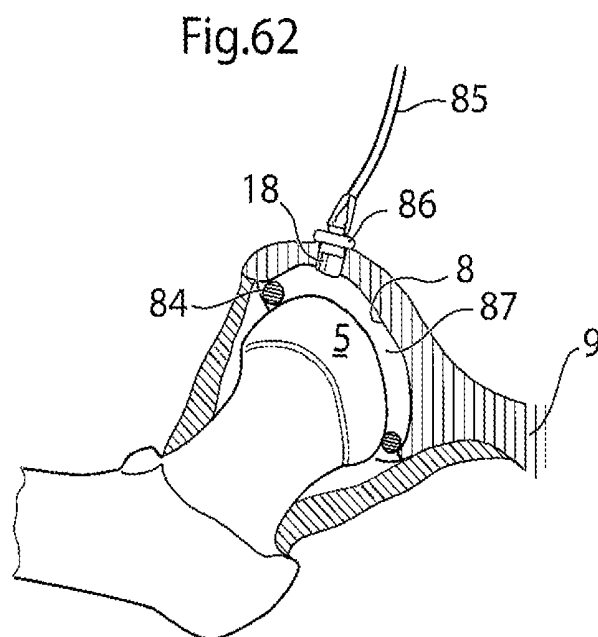
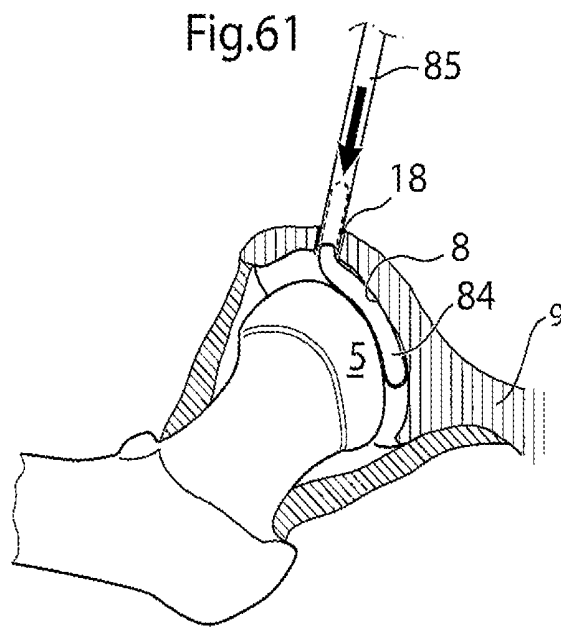


Fig.63a

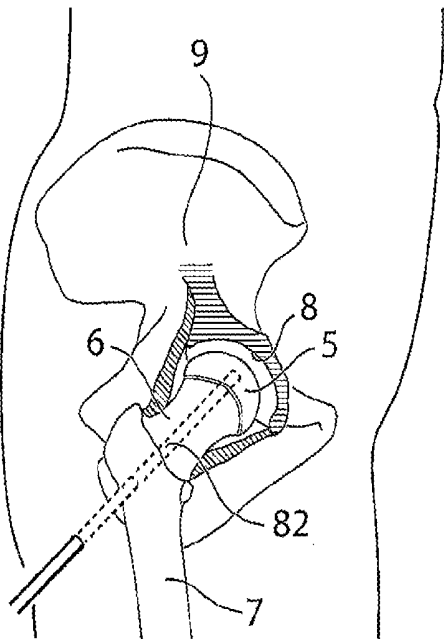


Fig.63b

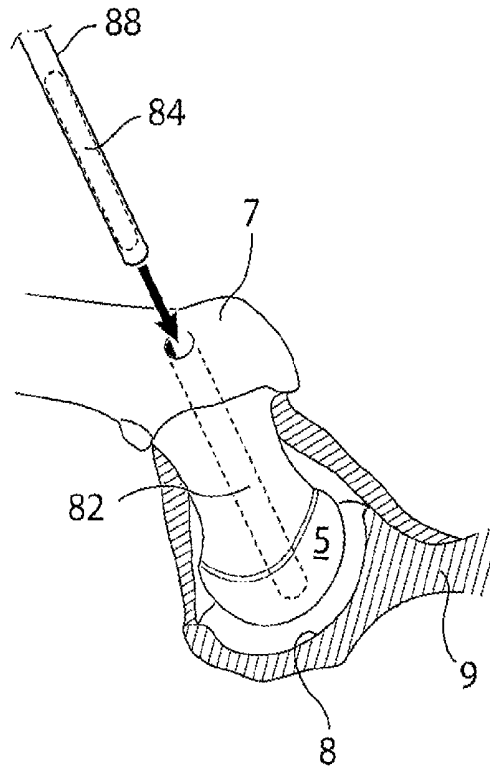


Fig.63c

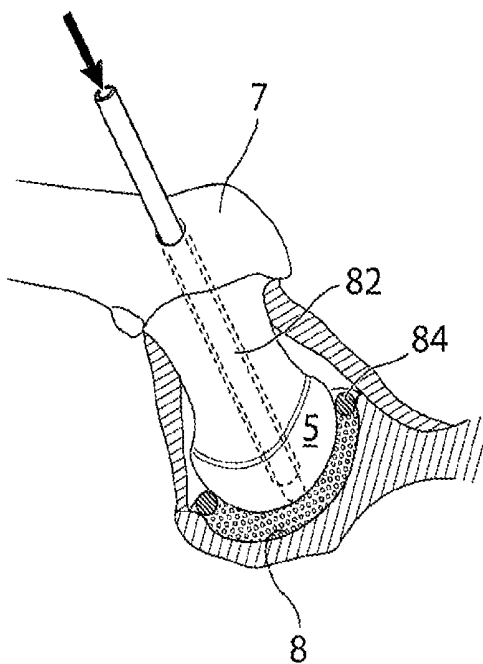


Fig.64

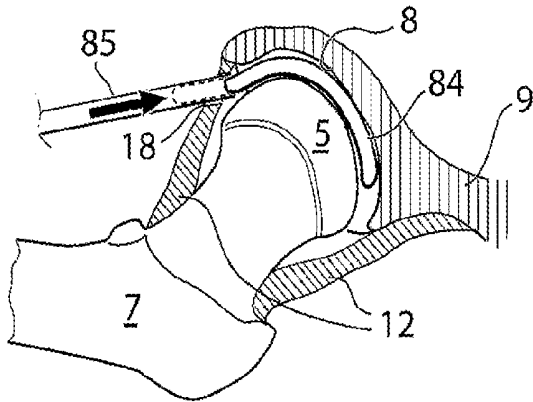


Fig.65

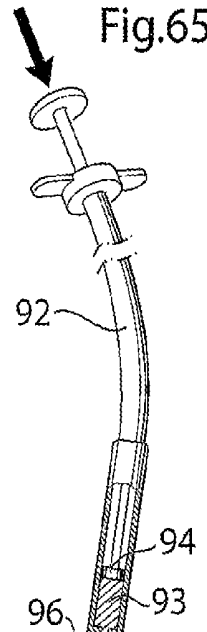
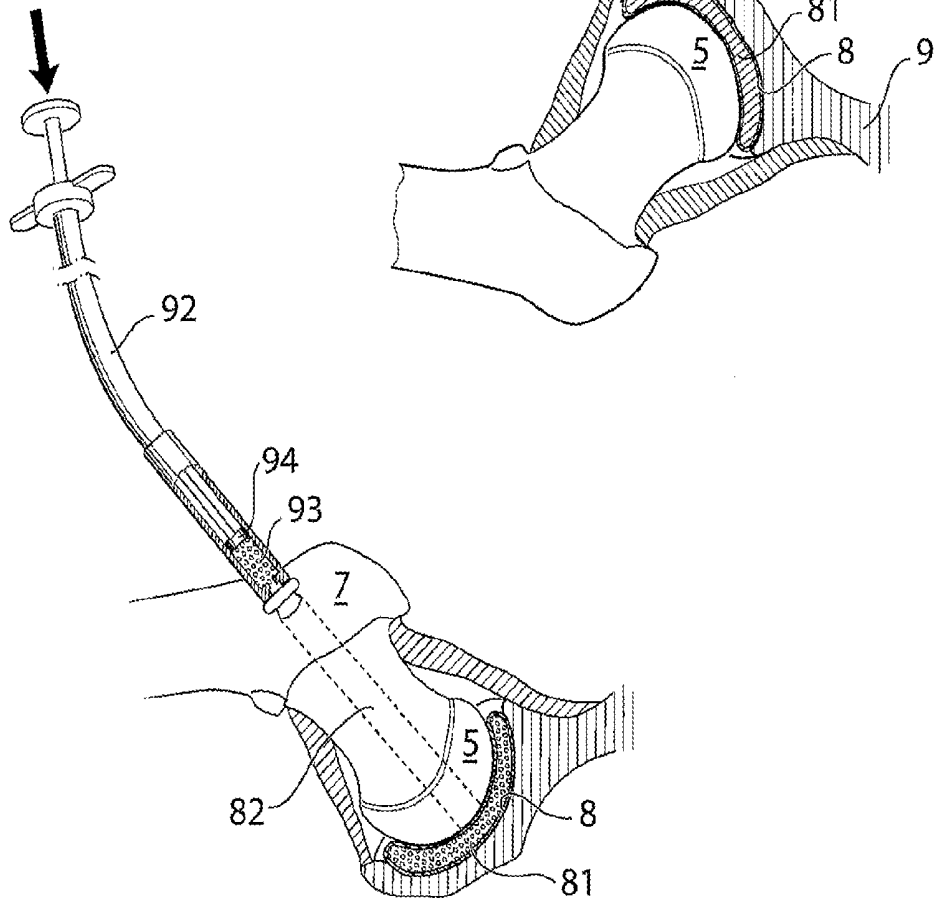


Fig.66



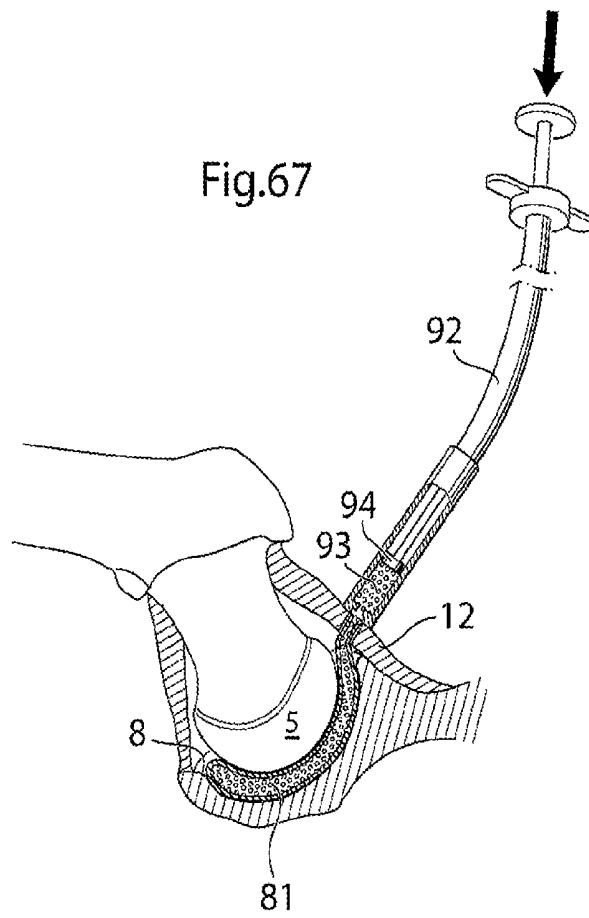


Fig.68

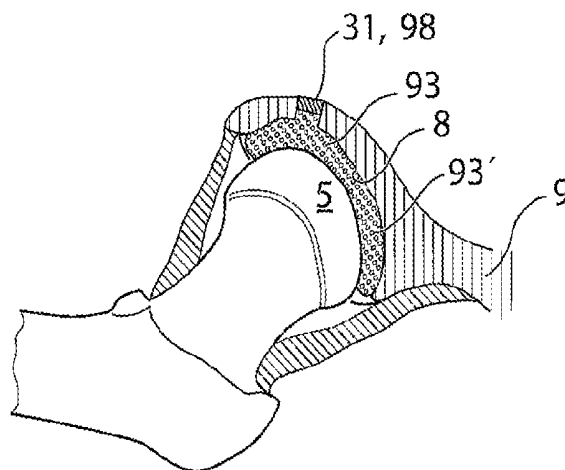


Fig.69

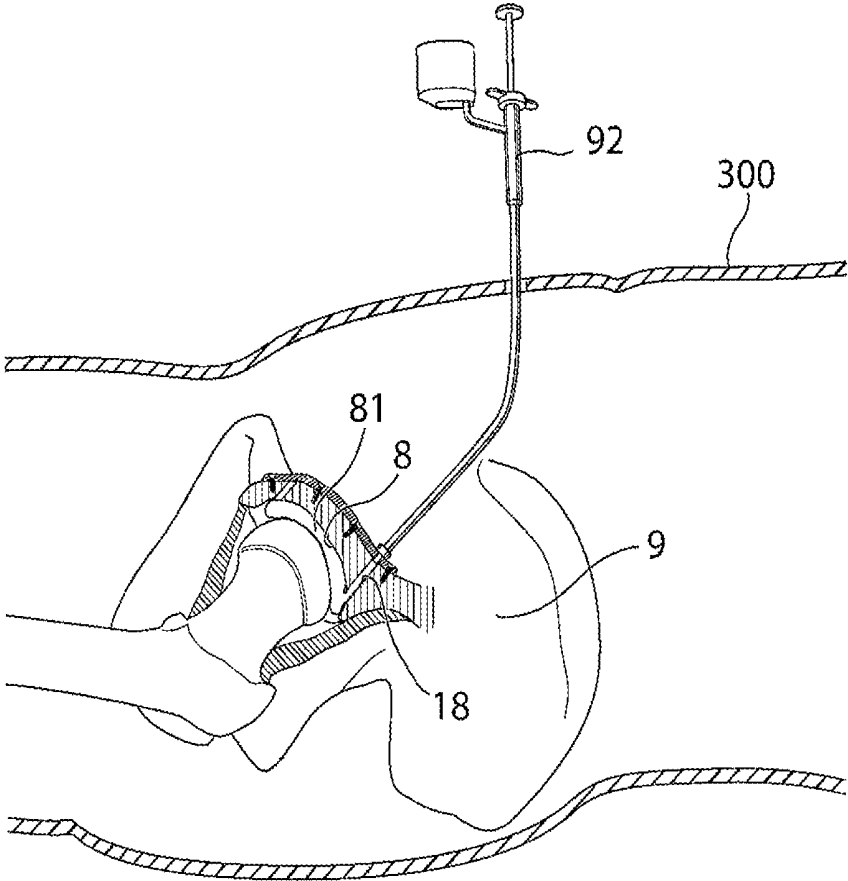


Fig.70

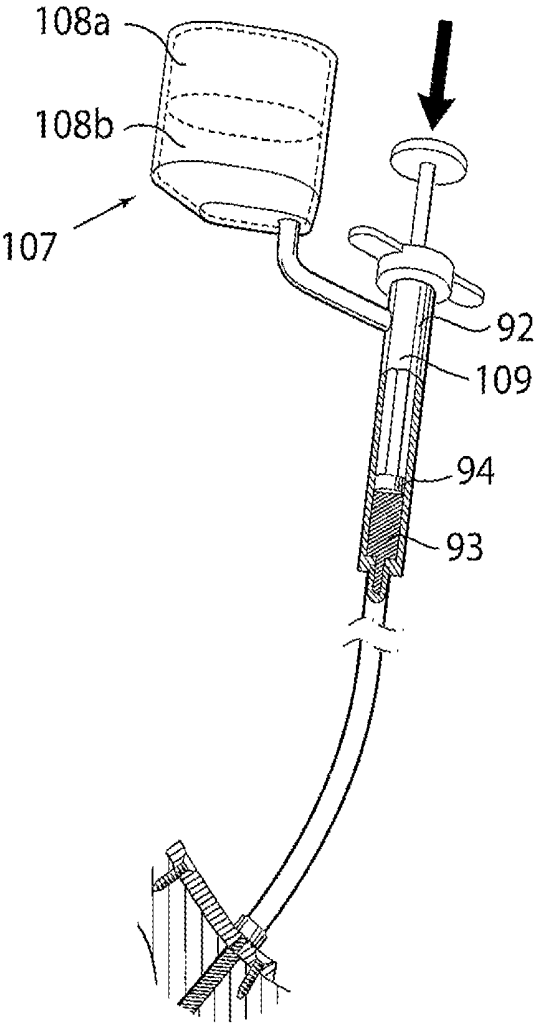


Fig.71a

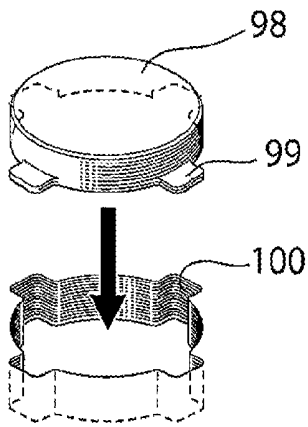


Fig.71b

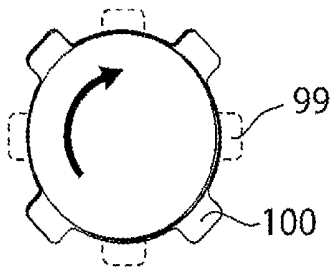


Fig.72

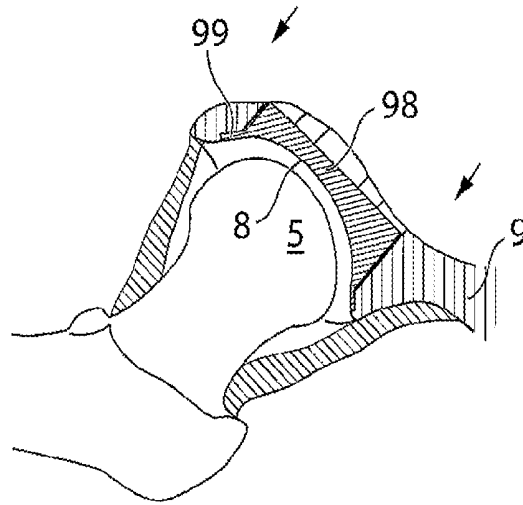
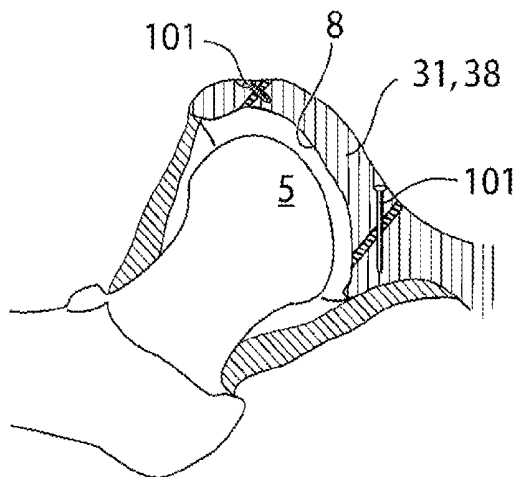


Fig.73



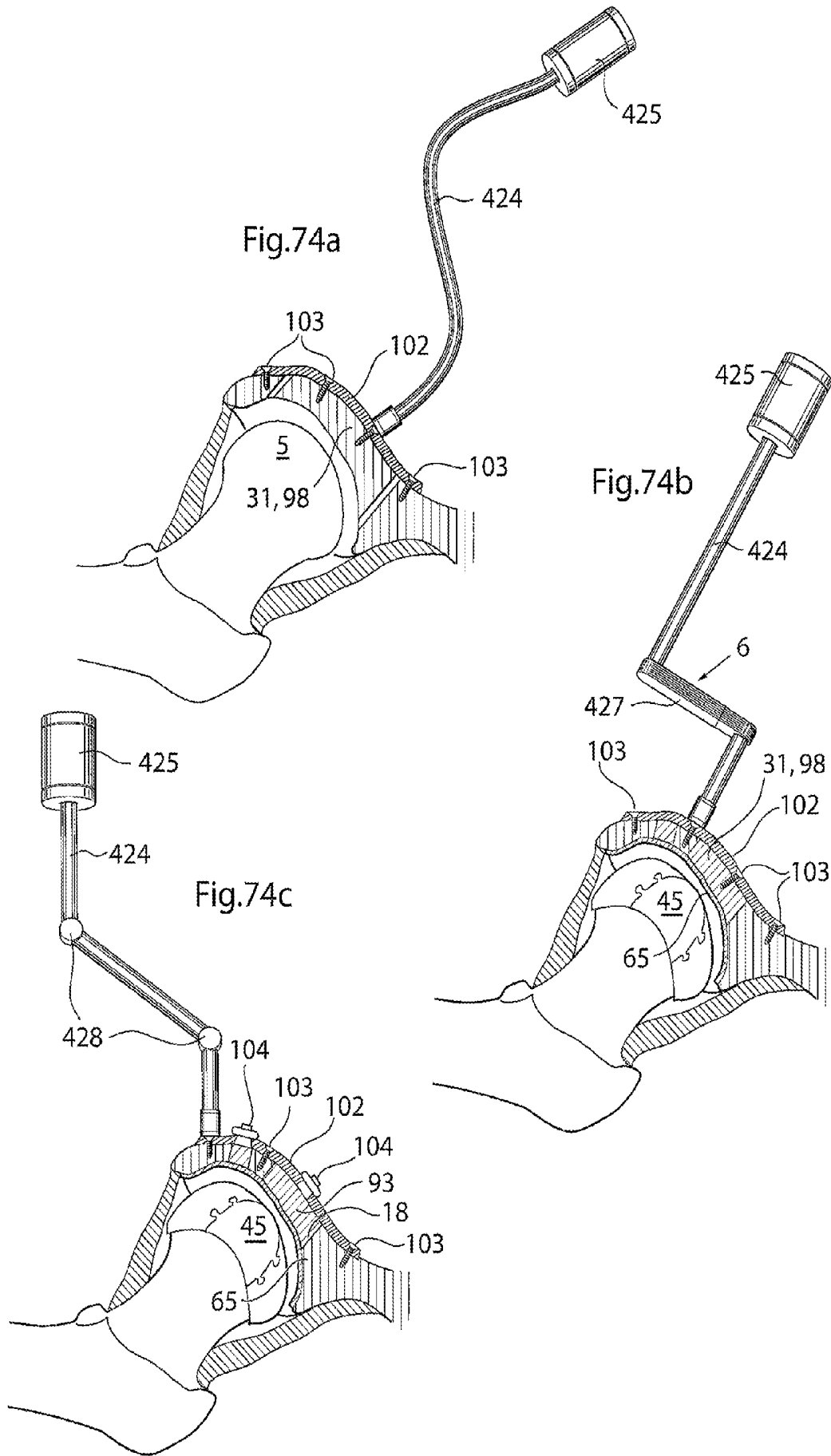


Fig.75

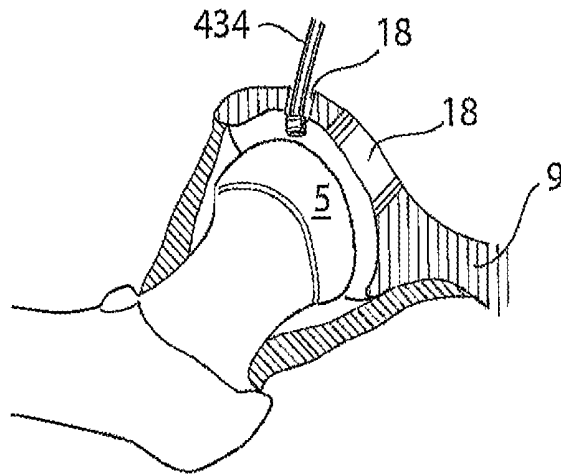
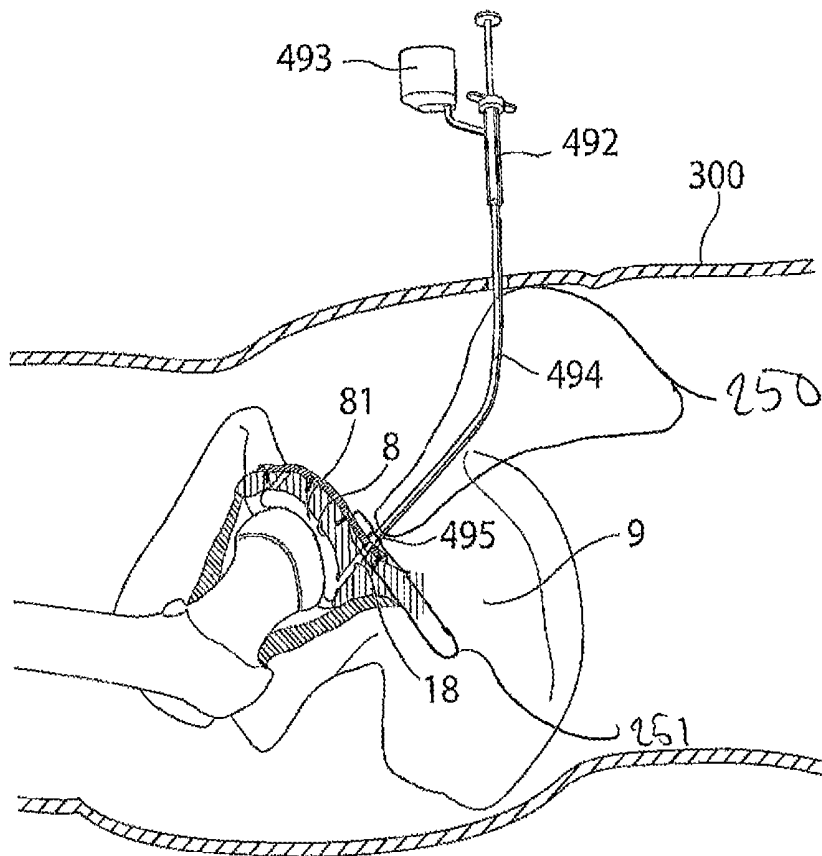


Fig.76



HIP JOINT INSTRUMENT AND METHOD

This application is the U.S. national phase of International Application No. PCT/SE2010/050823, filed 12 Jul. 2010, which designated the U.S. and claims the benefit of U.S. Provisional No. 61/229,755, filed 30 Jul. 2009; 61/229,738 filed 30 Jul. 2009; 61/229,739 filed 30 Jul. 2009; 61/229,743 filed 30 Jul. 2009; 61/229,745 filed 30 Jul. 2009; 61/229,746 filed 30 Jul. 2009; 61/229,747 filed 30 Jul. 2009; 61/229,748 filed 30 Jul. 2009; 61/229,751 filed 30 Jul. 2009; 61/229,752 filed 30 Jul. 2009; 61/229,761 filed 30 Jul. 2009; 61/229,767 filed 30 Jul. 2009; 61/229,778 filed 30 Jul. 2009; 61/229,786 filed 30 Jul. 2009; 61/229,789 filed 30 Jul. 2009; 61/229,796 filed 30 Jul. 2009; 61/229,735 filed 30 Jul. 2009; and which claims priority to Swedish Application Nos.: 0900981-2 filed 10 Jul. 2009; 0900957-2 filed 10 Jul. 2009; 0900958-0 filed 10 Jul. 2009; 0900959-8 filed 10 Jul. 2009; 0900960-6 filed 10 Jul. 2009; 0900962-2 filed 10 Jul. 2009; 0900963-0 filed 10 Jul. 2009; 0900965-5 filed 10 Jul. 2009; 0900966-3 filed 10 Jul. 2009; 0900968-9 filed 10 Jul. 2009; 0900969-7 filed 10 Jul. 2009; 0900970-5 filed 10 Jul. 2009; 0900972-1 filed 10 Jul. 2009; 0900973-9 filed 10 Jul. 2009; 0900974-7 filed 10 Jul. 2009; 0900976-2 filed 10 Jul. 2009 and 0900978-8 filed 10 Jul. 2009, the entire contents of each of which are hereby incorporated by reference.

FIELD OF INVENTION

The present invention relates generally to a surgical instrument for use in treating of hip osteoarthritis in a human patient.

BACKGROUND

Hip Osteoarthritis is a syndrome in which low-grade inflammation results in pain in the hip joints, caused by abnormal wearing of the Cartilage that acts as a cushion inside of the hip joint. This abnormal wearing of the cartilage also results in a decrease of the joints lubricating fluid called Synovial fluid. Hip Osteoarthritis is estimated to affect 80% of all people over 65 years of age, in more or less serious forms.

The present treatments for hip osteoarthritis comprises NSAID drugs, local injections of Hyaluronic acid or Glucocorticoid to help lubricating the hip joint, and replacing parts of the hip joint with a prosthesis through hip joint surgery.

Replacing parts of the hip joint is one of the most common surgeries to date performed at hundreds of thousand of patients in the world every year. The most common method comprises placing a metal prosthesis in Femur and a plastic bowl in Acetabulum. This operation is done through a lateral incision in the hip and upper thigh, through Fascia Lata and the lateral muscles of the thigh. To get access to the joint, the supporting Fibrous Capsule attached to Femur and Ilium needs to be penetrated, making it difficult to get a fully functional joint after the surgery. Femur is then cut at the neck with a bone saw and the prosthesis is placed in femur either with bone cement or without. Acetabulum is slightly enlarged using an Acetabular reamer, and the plastic bowl is positioned using screws or bone cement.

The surgery typically requires one week of hospitalization due to the increased risk of infection. The recovery process is on average about 6 weeks, but even after that the patient should not perform any physical activities that places large strain on the joint.

SUMMARY

A first object is to provide a surgical instrument for operating hip joint osteoarthritis in a human patient. The hip joint

comprises an acetabulum being a part of the pelvic bone, and a caput femur being the proximal part of the femoral bone. The surgical instrument comprises an abdominal portion insertable through an incision in the skin in the abdominal region and adapted to be placed between the incision in the abdominal region and the pelvic bone when the instrument is in use, and a pelvic portion connected to the abdominal portion, being partially insertable through a hole in the pelvic bone from the abdominal side of the pelvic bone, when the instrument is in use, wherein a portion of the pelvic portion is adapted to operate at least partially in a surgically created hole in the pelvic bone.

According to one embodiment the surgical instrument is further adapted to operate through a hole in the pelvic bone of said human patient. For this purpose the instrument could be adapted to be bent, by means of: a fixed angle, an adjustable angle, a parallel displaced part or section, at least one gear wheel or at least one universal joint. It is furthermore conceivable that the surgical instrument is adapted to be curved in such a way that it is adapted to be introduced through the skin and further into the hole in the pelvic bone from the abdominal side thereof and further into the hip joint.

According to one embodiment the length of the surgical instrument is adapted to reach the hip joint from the abdominal side of said pelvic bone. The surgical instrument could further comprise a gripping end and an end reaching the hip joint, in which case the distance between said gripping end and a part of said surgical instrument adapted to be bent could be adapted for operating in a hip joint from the abdominal side of said pelvic bone. It is also conceivable that the length between said gripping end and said end reaching the hip joint is adapted for operating in a hip joint from the abdominal side of said pelvic bone.

According to another embodiment the surgical instrument is a special laparoscopic instrument introduced into the abdomen and further down to the pelvic bone on the opposite side of the acetabulum and introduced into the hip joint. The instrument could further comprise a gripping end, placed outside the abdominal wall when in use, and a hip joint end adapted to be placed in an area of the hip joint. The length of the instrument could be adapted to reach from the gripping end and into the hip joint via a surgically created hole in the pelvic bone and wherein the longitudinal extension of the instrument comprises at least one bend, for the instrument to reach, when used as a special laparoscopic instrument to operate the hip joint, from the gripping end into the abdomen and further down to the pelvic bone on the opposite side of the acetabulum and be introduced into the hip joint through the surgically created hole in the pelvic bone.

According to yet another embodiment the surgical instrument is a special pelvic instrument adapted to be introduced into the pelvic region and further to the pelvic bone on the opposite side of the acetabulum, and introduced into the hip joint via a surgically created hole in the pelvic bone. The instrument could further comprise a gripping end, placed outside the skin above the pelvic region when in use, and a hip joint end adapted to be placed in an area of the hip joint, wherein the length of said instrument is adapted to reach from the gripping end and into the hip joint, and wherein the longitudinal extension of said instrument comprises at least one bend, for the instrument to reach, when used as special pelvic instrument to operate the hip joint, from the gripping end into the pelvic region and further down to the pelvic bone on the opposite side of the acetabulum, and introduced into the hip joint through the surgically created hole in the pelvic bone.

According to yet another embodiment, the surgical instrument could be adapted to be a special retroperitoneal instrument introduced into the body just above the inguinal region following the pelvic bone down to the opposite side of the acetabulum and thereafter introduced into the hip joint via a surgically created hole in the pelvic bone. The instrument could comprise a gripping end, placed outside the skin above the pelvic region when in use, and a hip joint end adapted to be placed in an area of the hip joint. The length of the instrument is adapted to reach from the gripping end and into the hip joint and the longitudinal extension of said instrument comprises at least one bend, for the instrument to reach, when used as special retroperitoneal instrument to operate the hip joint, from the gripping end following the pelvic bone and further down to the pelvic bone on the opposite side of the acetabulum and introduced into the hip joint through the surgically created hole in the pelvic bone.

The surgical instrument according to any of the embodiments could comprise at least one holding part and a mechanical element adapted to be fitted to the at least one holding part of the instrument. The surgical instrument could be adapted to perform a function during an operation of the hip joint. The mechanical element could in turn be adapted to be part of an instrument adapted to be used for at least one of the following functions: drilling, reaming, cooling, heating, flushing, introducing a fluid, sucking, inserting at least one part, connecting at least one part, fixating at least one part, inserting a mould, filling a mould, injecting, lubricating, viewing, optically displaying, placing screws, placing adhesive, placing bone cement.

The surgical instrument could have a distance between the gripping end and the bend that is at least 10 cm, it is furthermore conceivable that the distance between the gripping end and the bend is at least 20 cm. It is furthermore conceivable that the distance between the gripping end and the bend is at least 30 cm. It is furthermore conceivable that the distance between the gripping end and the bend is at least 40 cm. It is furthermore conceivable that the distance between said gripping end and said bend is at least 50 cm.

According to one embodiment the surgical instrument comprises a bend, and wherein the bend is bent with an angle of at least 10 degrees, the bend is bent with an angle of at least 20 degrees or the bend is bent with an angle of at least 30 degrees, or the bend is bent with an angle of at least 40 degrees, or the bend is bent with an angle of at least 50 degrees, or the bend is bent with an angle of at least 60 degrees.

According to one embodiment the of the surgical instrument, the distance between the bend and the hip joint end of the instrument is at least 2 cm, according to another embodiment the distance between the bend and the hip joint end of the instrument is at least 4 cm, according to yet another embodiment the distance between the bend and the hip joint end of the instrument is at least 6 cm, according to yet another embodiment the distance between the bend and the hip joint end of the instrument is at least 8 cm, according to yet another embodiment the distance between the bend and the hip joint end of the instrument is at least 10 cm, according to yet another embodiment the distance between the bend and the hip joint end of the instrument is at least 12 cm, according to yet another embodiment the distance between the bend and the hip joint end of the instrument is at least 14 cm,

APPLICATIONS OF THE INSTRUMENT

The surgical instrument could be adapted for a number of applications. According to a first embodiment the surgical

instrument is adapted to create a through-going hole in the pelvic bone placed in the acetabulum area from the abdominal side of the pelvic bone of said human patient. According to this embodiment the surgical instrument could comprise: a driving member, a bone contacting organ in connection with said driving member, and an operating device adapted to operate said driving member.

According to one embodiment the surgical instrument is adapted to ream the acetabulum and/or the caput femur of said human patient. According to this embodiment the surgical instrument could be adapted to be expandable, thus allowing the surgical instrument to be inserted through a hole in the pelvic bone smaller than the area possible to ream using said surgical instrument. The surgical instrument adapted to ream could comprise: a driving member, a bone contacting organ in connection with said driving member, and an operating device, adapted to operate said driving member. The bone contacting organ could comprise at least one of the materials: titanium, ceramics or stainless steel. The operating device could be: electrically operated hydraulically operated and comprise at least one camera and/or at least one light source.

According to one embodiment the surgical instrument is adapted to cool an area of the hip joint or the pelvic bone. The cooling could be provided using a cooling fluid and could be provided before, during or after the creation of a hole in the pelvic bone. It is also conceivable that the cooling is provided before, during or after a reaming operation.

According to one embodiment the surgical instrument is adapted to provide a fluid to an area of the pelvic bone or the hip joint. The fluid could be adapted to clean or sterilize an area of the pelvic bone or an area of the hip joint.

According to one embodiment the surgical instrument is adapted to provide suction to an area of the pelvic bone or the hip joint. The surgical instrument adapted to provide suction could further be adapted to transport body fluids, parts of bone, cartilage or a fluid provided during the hip joint surgery.

According to one embodiment the surgical instrument is adapted to introduce prosthesis or at least one prosthetic part into the hip joint. The prosthesis or prosthetic part could be acetabulum prosthesis or a part of acetabulum prosthesis or caput femur prosthesis or a part of caput femur prosthesis.

According to one embodiment the surgical instrument is adapted to connect at least two prosthetic parts to each other after insertion into the hip joint. The at least two prosthetic parts could comprises at least two artificial caput femur surface parts or at least two artificial acetabulum surface parts. The fixation could be done using at least one of: screws, form fitting, welding, adhesive, sprint, band, or other mechanical connecting members.

According to one embodiment the surgical instrument is adapted to fixate a hip joint surface, or a part of a hip joint surface, to the pelvic bone or the femur bone. The fixation could be done using at least one of: screws, form fitting, welding, adhesive, sprint, band, or other mechanical connecting members.

According to one embodiment the surgical instrument is adapted to introduce a mould or at least one sealing member into the hip joint. The mould or sealing member could be adapted to be resorbable by the human body or melt after having served its purpose as mould. According to this embodiment the surgical instrument could comprise gripping means for gripping said mould or sealing member.

According to one embodiment the surgical instrument is adapted to inject a fluid, adapted to harden to provide an artificial hip joint surface in the hip joint, into a mould or a sealed area of the hip joint. According to this embodiment the surgical instrument could comprise at least one container, a

fluid injecting member in connection with said mould, and a fluid driving member in fluid connection with said fluid injecting member and said at least one container.

According to one embodiment the surgical instrument comprises at least two containers adapted to hold two different fluids, and a mixing unit adapted to mix said fluids contained in said at least two containers.

According to one embodiment the surgical instrument is adapted to introduce adhesive or bone cement into the hip joint. According to this embodiment the surgical instrument could comprise: at least one container, a fluid injecting member, and a fluid driving member in fluid connection with said fluid injecting member and said at least one container. According to one embodiment the surgical instrument comprises at least two containers adapted to hold two different fluids, and a mixing unit adapted to mix said fluids contained in said at least two containers.

According to one embodiment the surgical instrument is adapted to place or fixate fixating elements to the pelvic bone or a prosthetic part in the pelvic region. The fixating elements could comprise: at least one screw, at least one plate and/or at least one nut.

According to one embodiment the surgical instrument comprises at least one camera, at least one light source or an x-ray tube or x-ray detector.

According to one embodiment the surgical instrument is adapted to inject a lubricating fluid into the hip joint, in which case the surgical instrument could comprise: at least one container, a fluid injecting member, and a fluid driving member in fluid connection with said fluid injecting member and said at least one container. The lubricating fluid is preferably a biocompatible lubricating fluid, such as hyaluronic acid.

Please note that any embodiment or part of embodiment, feature, method, associated system, part of system described herein may be combined in any way.

BRIEF DESCRIPTION OF THE DRAWINGS

The embodiments are now described, by way of example, with reference to the accompanying drawings, in which:

FIG. 1 shows a hip joint in section,

FIG. 2 shows a lateral view of a conventional hip joint surgery,

FIG. 3 shows an artificial caput femur being used in conventional surgery,

FIG. 4 shows a frontal view of the body of a human patient,

FIG. 5 shows a frontal view of the body of a human patient,

FIG. 6 shows a frontal view of the body of a human patient,

FIG. 7 shows a lateral view of the body of a human patient in section,

FIG. 8a shows the creation of a hole through the collum femur, in a length axis thereof,

FIG. 8b shows mechanical instruments adapted to be placed on an elongated member placed in a hole in collum femur,

FIG. 9a shows the placement of an elongated member through the pelvic bone,

FIG. 9b shows the elongated member in further detail,

FIG. 10a shows an instrument with a parallel displaced part or section,

FIG. 10b shows an instrument with two joints,

FIG. 10c shows an instrument with a flexible part or section,

FIG. 11 shows an instrument comprising a worm gear,

FIG. 12 shows an instrument comprising a universal joint,

FIG. 13 shows an instrument comprising a gripping member,

FIG. 14 shows an instrument adapted to create a hole in the pelvic bone,

FIG. 15 shows an instrument adapted to create a hole in the pelvic bone in further detail,

FIG. 16 shows an instrument adapted to create a hole in the pelvic bone comprising a parallel displaced part or section,

FIG. 17 adapted to create a hole in the pelvic bone comprising two joints,

FIG. 18 shows an instrument adapted to create a hole in the pelvic bone comprising a flexible part or section,

FIG. 19a shows an instrument adapted to create a hole in the pelvic bone in further detail,

FIG. 19b shows an instrument adapted to create a hole in the pelvic bone in further detail,

FIG. 20 shows an instrument adapted to create a hole in the pelvic according to another embodiment,

FIG. 21 shows an instrument adapted to create a hole in the pelvic according to another embodiment,

FIG. 22 shows an instrument adapted to create a hole in the pelvic according to another embodiment,

FIG. 23 shows an instrument adapted to create a hole in the pelvic bone comprising two gear wheels,

FIG. 24 shows an instrument adapted to create a hole in the pelvic bone comprising a worm gear,

FIG. 25 shows an instrument adapted to create a hole in the pelvic comprising a universal joint,

FIG. 26 shows an instrument adapted to create a hole in the pelvic bone comprising a chain,

FIG. 27 shows an instrument adapted to create a hole in the pelvic bone comprising a chain according to another embodiment,

FIG. 28a shows an instrument adapted to create a hole in the pelvic according to another embodiment,

FIG. 28b shows an instrument adapted to create a hole in the pelvic according to another embodiment,

FIG. 29 shows an instrument adapted to create a hole in the pelvic bone in further detail,

FIG. 30 shows an instrument adapted to create a hole in the pelvic bone comprising a cover,

FIG. 31 shows an instrument adapted to ream, in a first position,

FIG. 32 shows an instrument adapted to ream, in a second position,

FIG. 33 shows an instrument adapted to ream, from underneath,

FIG. 34 shows an instrument adapted to ream, when reaming,

FIG. 35 shows an instrument adapted to ream, comprising a parallel displaced part or section,

FIG. 36 shows an instrument adapted to ream comprising two joints,

FIG. 37 shows an instrument adapted to ream comprising a flexible part or section,

FIG. 38 shows an instrument adapted to ream, in further detail,

FIG. 39 shows an instrument adapted to ream, comprising two gear wheels,

FIG. 40 shows an instrument adapted to ream, comprising a worm gear,

FIG. 41 shows an instrument adapted to ream, comprising a universal joint,

FIG. 42 shows an instrument adapted to ream, comprising a chain,

FIG. 43 shows an instrument adapted to ream, comprising a chain, according to another embodiment,

FIG. 44 shows an instrument adapted to ream, according to another embodiment,

FIG. 45 shows an instrument adapted to ream, according to another embodiment,

FIG. 46 shows an instrument adapted to ream according to another embodiment,

FIG. 47 shows an instrument adapted to ream, comprising a cover,

FIG. 48 shows an instrument adapted for flushing, cooling and/or sucking,

FIG. 49 shows an instrument for gripping or handling,

FIG. 50 shows an instrument for gripping or handling, comprising a parallel displaced part or section,

FIG. 51 shows an instrument for gripping or handling, comprising two joints,

FIG. 52 shows the hip joint in section,

FIG. 53 shows the insertion of prosthetic parts is a surgical method,

FIG. 54 shows the insertion of prosthetic parts is a laparoscopic method,

FIG. 55 shows the insertion of prosthesis, through a hole in the pelvic bone,

FIG. 56a shows the insertion of prosthetic parts, through a hole in the pelvic bone,

FIG. 56b shows the connecting of prosthetic parts, through a hole in the pelvic bone,

FIG. 56c shows prosthetic parts,

FIG. 57 shows an instrument adapted to fixate a hip joint surface,

FIG. 58 shows an instrument adapted to inject a fluid into a hip joint,

FIG. 59a shows an instrument adapted to insert a mould or a sealing member into a hip joint,

FIG. 59b shows an instrument adapted to insert a mould or a sealing member into a hip joint, in section,

FIG. 59c shows an instrument adapted to insert a mould or a sealing member into a hip joint, comprising a flexible part or section,

FIG. 60a shows an instrument adapted to insert a mould or a sealing member into a hip joint,

FIG. 60b shows an instrument adapted to insert a mould or a sealing member into a hip joint, comprising a parallel displaced part or section,

FIG. 60c shows an instrument adapted to insert a mould or a sealing member, comprising two joints,

FIG. 61 shows the insertion of a mould or a sealing member, through the pelvic bone,

FIG. 62 shows the placing of a second sealing member,

FIG. 63a shows the insertion of a mould or a sealing member, through the femoral bone,

FIG. 63b shows the insertion of a mould or a sealing member, through the femoral bone,

FIG. 63c shows the insertion of a mould or a sealing member, through the femoral bone,

FIG. 64 shows the insertion of a mould or a sealing member, through the hip joint capsule,

FIG. 65 shows the injection of fluid into a mould, through the hip joint,

FIG. 66 shows the injection of fluid into a mould, through the femoral bone,

FIG. 67 shows the injection of fluid into a mould, through the hip joint capsule,

FIG. 68 shows the hip joint in section, after a fluid has been injected,

FIG. 69 shows a lateral view of a human patient in section, with an instrument for injecting a fluid,

FIG. 70 shows an instrument for injecting a fluid in further detail,

FIG. 71a shows a prosthetic part being used to close a hole in a pelvic bone,

FIG. 71b shows how sections of a prosthetic part is used as support against the edges of the hole in a pelvic bone,

FIG. 72 shows the insertion of a prosthetic part in a hole in a pelvic bone,

FIG. 73 shows how screws are being used to fixate a bone plug or a prosthetic part in a hole in a pelvic bone of a human patient,

FIG. 74a shows an instrument for fixating fixation members to an area of the pelvic bone,

FIG. 74b shows an instrument for fixating fixation members to an area of the pelvic bone,

FIG. 74c shows an instrument for fixating fixation members to an area of the pelvic bone,

FIG. 75 shows an instrument comprising an arthroscopic camera,

FIG. 76 shows an instrument for injecting a lubricating fluid.

DETAILED DESCRIPTION

In the following a detailed description of embodiments will be given. In the drawing figures, like reference numerals designate identical or corresponding elements throughout the several figures. It will be appreciated that these figures are for illustration only and are not in any way restricting the scope. Thus, any references to direction, such as “up” or “down”, are only referring to the directions shown in the figures. Also, any dimensions etc. shown in the figures are for illustration purposes.

Please note that any embodiment or part of embodiment as well as any method or part of method could be combined in any way. All examples herein should be seen as part of the general description and therefor possible to combine in any way in general terms.

FIG. 1 shows the hip joint of a human patient in section. The hip joint comprises a caput femur 5 placed at the very top of collum femur 6 which is the top part of the femur bone 7. The caput femur is in connection with the acetabulum 8 which is a bowl shaped part of the pelvic bone 9. Both the caput femur surface 10 and the acetabulum surface 11 is covered with articular cartilage 13 which acts as a cushion in the hip joint. In patients with hip joint osteoarthritis, this articular cartilage 13 is abnormally worn down sometimes due to a low grade inflammation. The hip joint is surrounded by the hip joint capsule 12 which provides support for the joint and hinders luxation. After conventional hip joint surgery, penetrating the hip joint capsule 12, the capsule 12 is dramatically weakened due to the limited healing possibilities of its ligament tissue. By performing hip joint surgery without damaging the hip joint capsule 12 the patient can fully recover and place equal amount of strain on an artificial joint as is possible on a natural one.

FIG. 2 shows a lateral view of a conventional hip joint surgery where an incision 112 is made in the thigh 113 enabling the surgeon to reach the femur bone 7 on which the caput femur 5 is located. In a conventional hip joint surgery the hip joint is accessed through the hip joint capsule.

FIG. 3 shows the placing of an artificial caput femur surface 45 on the caput femur 5 in conventional surgery.

FIG. 4 shows a frontal view of the body of a human patient. A surgical method of operating the hip joint from the opposite side from acetabulum, is according to a first embodiment performed starting with an incision 1 in the abdominal wall of the human patient. The incision 1 passes through the abdominal wall sometimes including the rectus abdominis and

including peritoneum in to the abdomen of the human patient. In a second embodiment the incision 2 is conducted through the skin and into the pelvic area, below peritoneum. According to a third embodiment the incision 3 is performed just between Ilium and the surrounding tissue, an incision 3 which could enable the pelvic bone to be dissected with very little penetration of fascia and muscular tissue. According to a fourth embodiment the incision 4 is made in the inguinal region or slightly above. In all of the four embodiments the tissue surrounding the pelvic bone 9 in the area opposite to acetabulum is removed or penetrated which enables the surgeon to reach the pelvic bone 9.

FIG. 5 shows a frontal view of the body of a human patient. A laparoscopic method of operating the hip joint, from the opposite side from acetabulum, is according to a first embodiment performed starting with making small incisions 14 in the abdominal wall of the human patient. The small incisions enable the surgeon to insert laparoscopic trocars into the abdomen of the human patient. According to the first embodiment the incisions 14 passes through the abdominal wall including the peritoneum in to the abdomen of the human patient. According to a second embodiment the small incisions 15 is conducted through the skin and in to the pelvic area, below peritoneum. According to a third embodiment the small incisions 16 is performed just between Ilium and the surrounding tissue, an incision 16 which could enable the pelvic bone to be dissected with very little penetration of fascia and muscular tissue. According to a fourth embodiment the incision 17 is made in the inguinal channel. In all of the four embodiments the tissue surrounding the pelvic bone 9 in the area opposite to acetabulum 8 is removed or penetrated which enables the surgeon to reach the pelvic bone 9.

After the incision is made the surgical instruments according to any on the embodiments below can enter the human body and be used to assist the surgeon in the operation of the hip joint osteoarthritis.

FIG. 6 shows a frontal view of the body of a human patient, illustrating the instruments 34, 35, 36 assisting in the method of operating the hip joint from the opposite side from acetabulum 8, the hip joint comprising the acetabulum 8 and the caput femur 5. The small incisions 14 in the abdominal wall of the human patient allows the insertion of laparoscopic trocars 33a,b,c into the body of the patients. Whereafter one or more camera 34, a surgical instrument 35 adapted to create a hole in the pelvic bone 9, or instruments 36 for introducing, placing, connecting, attaching, creating or filling prosthesis or prosthetic parts, can be inserted into said body through said laparoscopic trocars 33a,b,c. many different placements of the trocars is possible. The portions of the instruments adapted to be placed in the abdominal area are the abdominal portions 250, and the portions adapted to at least partially be placed inside of the pelvic bone is the pelvic portions 251 throughout this application.

FIG. 7 shows a lateral view of the body of a human patient, with the hip joint shown in section in further detail. The hip joint comprises a caput femur 5 placed at the very top of collum femur 6 which is the top part of the femur bone 7. The caput femur is in connection with the acetabulum 8 which is a bowl shaped part of the pelvic bone 9. Laparoscopic trocars 33a,b,c is being used to reach the hip joint 39 with one or more camera 34, a surgical instrument adapted to create a hole in the pelvic bone 35, or instruments 36 for introducing, placing, connecting, attaching, creating or filling prosthesis or prosthetic parts. The portions of the instruments adapted to be placed in the abdominal area are the abdominal portions 250,

and the portions adapted to at least partially be placed inside of the pelvic bone is the pelvic portions 251 throughout this application.

FIG. 8a shows a human patient in section when an incision 1 is made in the abdominal wall of the human patient, and a second incision 200 in made in the lateral part of the left thigh. A drilling member 201 has been introduced through the incision 200 in the thigh, penetrating the fascia lata, and reaching the femoral bone 7. After the drilling member 201 has made contact with the femoral bone 7, a drilling process is started which creates a hole 205 in the cortical bone of the femoral bone 7 and into the cancellous bone of the femoral bone 7, the hole 205 then propagates along a length axis of the collum femur 6 and eventually reaches the caput femur 5, from the inside thereof. The caput femur 5 is penetrated from the inside and the drilling member 201 continues to the acetabulum 8 which is a bowl shaped part of the pelvic bone 9. The drilling member 201 penetrates the pelvic bone 9 and continues into the abdominal area of the human patient. The drilling member 201 is then retracted from the hole 205 which leaves a hole 201 reaching from the lateral side of the thigh, to the area of the hip joint. The drilling member 201 is powered by an operating device 202 which could be an electrically, hydraulically or pneumatically powered operating device 202.

After the hole 205 has been created along a length axis of the collum femur 6, a force transferring member 206 is inserted through the hole 205. The force transferring member 206 could be a tubular or solid shaft, or a flexible member such as a wire.

FIG. 8b shows the hip joint in section when a force transferring member 206 has been inserted through the hole 205. The force transferring member 206 comprises a tool fixating member 218 positioned on the end of the force transferring member 206. The tool fixating member 218 could comprise a screw-thread or a bayonet joint which could be activated to fixate a tool 224,225,226 to the force transferring member 206, by the turning of said force transferring member by means of manual manipulation or an operating device 207. FIG. 5 further shows a tool for creating a hole 224 in the pelvic bone 9, a tool 225 for manipulating an implantable device such as a prosthesis or a prosthetic part, and a tool 226 for reaming the acetabulum 8 and/or the caput femur 5. The tools comprise a fixating member 219 which acts together with the tool fixating member 218 on the force transferring member 206 to fixate the tool 224,225,226 to the force transferring member 206. The tools 224,225,226 is inserted through the incision in the abdominal region, as shown in FIG. 4. where a tool 224 for creating a hole in the pelvic bone 9 is inserted through an incision 1 in the abdominal region of the human patient using a tool introducing member 203. The force transferring member 206 according to any of the embodiments could be used as a positioning shaft, for positioning, centering and guiding a tool or a medical device, such as a prosthetic part.

FIG. 9a shows an embodiment in which a hole is created in two different parts of the pelvic bone 9. A drilling member 201 is first brought to the left part of the pelvic bone 9' for creating a hole in the left part of the pelvic bone 9. The drilling member thereafter continues through the abdominal and/or pelvic region and reaches the right part of the pelvic bone 9'' where a second hole is created reaching into the hip joint. The drilling member 201 is powered by an operation device 202, which could be a powered operation device, such as an electrical, hydraulic or pneumatic motor. According to another embodiment the drilling member 201 is manually operated. The drilling member further comprises a protective sleeve

240 adapted to protect the organs and tissue of the body from the drilling member **201** when advancing the drilling member through the abdominal and/or the pelvic region. The creation of two holes enables a very stable position of an elongated member which could be placed through the two holes for delivering an action to the hip joint or its surroundings.

FIG. **9b** shows the drilling member in further detail, first in a state in which the protective sleeve **240** is advanced for covering the drilling member **201** and thereby protecting the organs and tissue of the human body from the drilling member. Below, the drilling member is shown in a second state, in which the protective sleeve **240** is refracted and thereby exposing the drilling member **201** and enabling the drilling member **201** to create a hole in bone.

After the hole has been created along a force transferring member or elongated member, according to any of the embodiments herein, could be inserted through the holes for delivering an action to the hip joint or its surroundings. The force transferring member could be a tubular or solid shaft, or a flexible member such as a wire.

To reach the pelvic bone or the hip joint from the abdominal side, it is conceivable that the surgical instrument is adapted to be bent.

FIG. **10a** shows the surgical instrument according to a first embodiment wherein the surgical instrument comprises a handling portion **77** and a parallel displaced part or section **79**, which increases the reach of the instrument and facilitates the reaching of the pelvic bone or the hip joint through from the abdominal side of the pelvic bone, or through a hole in the pelvic bone from the opposite side from acetabulum.

FIG. **10b** shows the surgical instrument according to a second embodiment wherein the surgical instrument comprises two angle adjusting members **80a,b**. The angle adjusting members could be adapted to be flexible for adjusting of the angle during surgery or fixed in a preset position.

FIG. **10c** shows the surgical instrument according to a third embodiment wherein the surgical instrument comprises a flexible part or section **300**, enabling the surgical instrument to be very precisely adjusted to reach the pelvic bone or the hip joint from the abdominal side of the pelvic bone. The stiffness of said flexible part or section **300** could range from completely flexible to completely stiff to fit the surroundings of the particular operation.

FIG. **11** shows the surgical instrument according to a fourth embodiment wherein the surgical instrument is adapted to be bent by means of gearwheels **154**. The gearwheel construction can be such that the angled could be changed during the surgery, or it could be adapted to be fixed in a specific angle.

FIG. **12** shows the surgical instrument according to a fifth embodiment wherein the surgical instrument is adapted to be bent by means of a universal joint **155**. The universal joint construction can be such that the angled could be changed during the surgery, or it could be adapted to be fixed in a specific angle.

FIG. **13** shows the surgical instrument according to a sixth embodiment, wherein the surgical instrument comprises a gripping portion **76** and a handling portion **77**. According to the embodiments shown in FIG. **40a** the instrument further comprises a rotation element **78** that enables the gripping part **76** to rotate in relation to the handling part **77**, however it is equally conceivable that the surgical instrument lacks this rotation element **78**.

The surgical instrument is generally adapted to assist the surgeon in a surgical or laparoscopic method of operating hip joint osteoarthritis. Embodiments of the surgical instrument for performing specific task will now be described with reference to the accompanying drawings.

FIG. **14** shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole **18, 20** in the pelvic bone **9**. According to a first embodiment, the instrument comprises a driving member **21a, b**. The driving member **21a, b** could be a shaft, a rod, a belt, a chain or any other element suitable for transferring force or torque. The instrument also comprises a bone contacting organ **22** which is adapted to create the hole **18, 20** in the pelvic bone **9**. The bone contacting organ **22** could have a sawing, drilling or milling effect using sharp objects; it is furthermore conceivable that said bone contacting organ **22** creates a hole using water, abrasive fluids, laser or radiation. The instrument also comprises an operating device **23a** adapted to operate the driving member **21a, b**. The operating device could comprise an electrical, hydraulic, mechanical, pneumatic or magnetic engine and it could be adapted to create a rotating, oscillating, vibrating or repetitive movement.

FIG. **15** shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole **18, 20** in the pelvic bone **9** according to a second embodiment in which the operating device **23b** is placed in direct connection with the bone contacting organ **22**. In this case the operating device **23b** also serves as driving member. In this construction a handle portion **24** could be attached to the instrument, facilitating the surgeons handling of said surgical instrument. To improve the reach of the surgical instrument the handle portion **24** could be attached perpendicular to the hole-creating direction **25** of the surgical instrument, it is furthermore conceivable that the handle portion **24** is bent by means of a parallel displaced part or section, a fixed angle, an adjustable angle or a flexible part or section.

FIG. **16** shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole **18, 20** in the pelvic bone **9** according to a third embodiment wherein the instrument further comprises a parallel displaced part or section **26**. The parallel displaced part or section **26** improves the reach of the instrument and enables the creation of a hole **18** in the pelvic bone **9** from the opposite side from acetabulum **8**. According to the embodiment shown in FIG. **16** the parallel displaced part or section **26** has a telescopic function by means of the parallel displaced part or section **26** being divided in to a first and second part **27a, b**, wherein the second part **27b** can slide in and out of the first part **27a**.

FIG. **17** shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole **18, 20** in the pelvic bone **9** according to a fourth embodiment wherein said instrument comprises a driving member **28a, b, c** with two angle adjusting members **29a, b**. The angle adjusting members **29a, b** could be adjustable for varying the angle of said driving member **28a, b, c** or fixed in an angle suitable for creating a hole in the pelvic bone **9** from the opposite side from acetabulum **8**. In another embodiment (not shown) the part of the driving member **28c** in connection with the bone contacting organ **22** could be very short enabling the instrument to operate very close to the pelvic bone **9** when creating a hole **18** in said pelvic bone **9**.

FIG. **18** shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole **18, 20** in the pelvic bone **9** according to a fifth embodiment wherein the driving member **30** is flexible, enabling said driving member **30** to be very precisely adjusted to create a hole **18** in the pelvic bone **9** of the patient. The stiffness of said driving member **30** could range from completely flexible to completely stiff to fit the surroundings of the particular operation.

FIG. 19a shows the bone contacting organ according to a first embodiment wherein the bone contacting organ 22a is adapted to create a bone plug 31. The bone plug 31 could be adapted to be replaced into said hole 18 after the surgical or laparoscopic steps performed in the hip joint has been concluded.

FIG. 19b shows the bone contacting organ according to the first embodiment in section wherein the bone contacting organ 22a is adapted to create a bone plug 31. According to this embodiment the instrument further comprises at least one holding member 150 for holding said bone plug in place after it has been removed from the pelvic bone of the human patient.

FIG. 20 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to a sixth embodiment wherein said instrument comprises a stabilizing drill 151 adapted to stabilize the instrument when creating said hole in the pelvic bone from the opposite side from acetabulum.

FIG. 21 shows the bone contacting organ according to a second embodiment wherein the bone contacting organ 22b is adapted to create small pieces of bone 32 when creating said hole 18 in the pelvic bone 9. The small pieces of bone 32 could be transported from the area and out of the body using vacuum power or a hydraulic transport system.

FIG. 22 shows a pneumatic, vacuum powered or a hydraulic transport system 152 for transport of said small pieces of bone. The same system 152 or an additional one could be for rinsing or cooling purposes when creating said hole in the pelvic bone 9.

FIG. 23 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to a seventh embodiment, wherein the driving member 30 comprises at least one worm gear 153 which enables the driving member 30 to be angled. It is also conceivable that said angle could be adjustable in which case said worm gear has a radius (not shown).

FIG. 24 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to an eighth embodiment, wherein the driving member 30 comprises at least one gear wheel 154. In the embodiment shown the two gear wheels 154 is constructed to enable the adjusting of an angle of the driving member 30.

FIG. 25 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to a ninth embodiment, wherein the driving member 30 comprises at least one universal joint 155, said universal joint enabling the adjusting of an angle of said driving member 30.

FIG. 26 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to a tenth embodiment, wherein the driving member 30 comprises at least one chain 156.

According to any of the embodiments above the driving member could comprise a housing 157 shown in FIGS. 23, 24 and 26. Said housing could be adapted to hold a lubricating fluid for lubricating at least a part of said driving member. Said lubricating fluid is preferably a biocompatible lubricating fluid, such as hyaluronic acid.

FIG. 27 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9, according to an

embodiment where said operating device comprises an electrical motor 158. Said electrical motor is connected to the driving member 30.

FIG. 28a shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to an embodiment wherein said operating device comprises a hydraulic motor 159, hydraulically connected to a hydraulic power source 160 by means of a hydraulic power transport system 161.

FIG. 28b shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to an embodiment wherein said operating device comprises a hydraulic motor, but wherein the hydraulic power transport system is located substantially perpendicular to the hole creation direction.

FIG. 29 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to an eleventh embodiment wherein said instrument further comprises at least one of: at least one camera 163, at least one light source 164, at least one measurement device for measuring the depth of said hole in the pelvic bone or at least one torque meter 165 for sensing the torque exerted on the driving member 30 from the connection with the bone contacting organ 22 and the operating device 23.

FIG. 30 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to a twelfth embodiment in which the part of said instrument adapted to be inserted in the human body is covered with a housing 166 for protecting the human body from the parts of the surgical instrument. The housing 166 could be made of a stiff or flexible material and could have an antibacterial surface. Said housing 166 could be adapted to be used to house the surgical instrument according to any of the embodiments.

FIG. 31 shows the surgical instrument adapted for a second application wherein said instrument is an instrument for holding a mechanical element which according to this embodiment is a reamer adapted to ream the acetabulum or and/or the caput femur. According to one embodiment the reamer could be adapted to be expandable. The expandable reamer comprises at least one reaming blade 40 which comprises a reaming surface 41a,b. Said expandable reamer could be adapted to ream the acetabulum 8, the caput femur 5 or both. In the embodiment where said expandable reamer is adapted to ream the acetabulum 8 said reaming surface 41a is located on the exterior part of the at least one reaming blade 40, whereas in the embodiment when said expandable reamer is adapted to ream the caput femur 5, said reaming surface 41b is located on the interior part of the at least one reaming blade 40. According to a second embodiment said expandable reamer is adapted to ream both the acetabulum and the caput femur, in which case the reamer has reaming surfaces 41a,b both on the exterior and the interior part of the at least one reaming blade 40.

FIG. 32 shows the expandable reamer, according to any of the embodiments, wherein the reaming blades 40 can be folded towards a center of the semi-sphere that the expandable reamer produces in its expanded state, shown in FIG. 21. The folding of the reaming blades 40 enables the expandable reamer to be introduced into a hip joint through a hole smaller than the area possible to ream using said expandable reamer.

FIG. 33 shows the interior said of the expandable reamer with the reaming blades 40. In the embodiment when the

expandable reamer is adapted to ream the caput femur said interior side of the at least one reaming blade **40** comprises a reaming surface **41b**.

FIG. **34** shows the expandable reamer according to any of the embodiments when reaming the acetabulum **8** and/or the caput femur **5**. The reamer can be adapted to be operated manually or by means of a rotating, vibrating or oscillating operating device.

FIG. **35** shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to a second embodiment wherein the instrument further comprises a parallel displaced part or section **26**. The parallel displaced part or section **26** improves the reach of the instrument and enables the reaming of the acetabulum and/or the caput femur through a hole **18** in the pelvic bone **9** from the opposite side from acetabulum **8**. According to the embodiment shown in FIG. **16** the parallel displaced part or section **26** has a telescopic function by means of the parallel displaced part or section **26** being divided in to a first and second part **27a, b**, wherein the second part **27b** can slide in and out of the first part **27a**.

FIG. **36** shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to a third embodiment wherein said instrument comprises a driving member **28a,b,c** with two angle adjusting members **29a,b**. The angle adjusting members **29a,b** could be adjustable for varying the angle of said driving member **28a,b,c** or fixed in an angle suitable for reaming the acetabulum and/or the caput femur through a hole in the pelvic bone **9** from the opposite side from acetabulum **8**.

FIG. **37** shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to a fourth embodiment wherein the driving member **30** is flexible, enabling said driving member **30** to be very precisely adjusted to ream the acetabulum and/or the caput femur through a hole **18** in the pelvic bone **9** of the patient. The stiffness of said driving member **30** could range from completely flexible to completely stiff to fit the surroundings of the particular operation.

FIG. **38** shows a pneumatic, vacuum powered or a hydraulic transport system **152** for transport of the small pieces of bone created when reaming the acetabulum and/or the caput femur. The same system **152** or an additional one could be for rinsing or cooling purposes when reaming the acetabulum and/or caput femur. The shown transport system could be added to the reamer according to any of the embodiments.

FIG. **39** shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to a fifth embodiment, wherein the driving member **30** comprises at least one worm gear **153** which enables the driving member **30** to be angled. It is also conceivable that said angle could be adjustable in which case said worm gear has a radius (not shown).

FIG. **40** shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to a sixth embodiment, wherein the driving member **30** comprises at least one gear wheel **154**. In the embodiment shown the two gear wheels **154** is constructed to enable the adjusting of an angle of the driving member **30**.

FIG. **41** shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according

to a seventh embodiment, wherein the driving member **30** comprises at least one universal joint **155**, said universal joint enabling the adjusting of an angle of said driving member **30**.

FIG. **42** shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to an eighth embodiment, wherein the driving member **30** comprises at least one chain **156**.

According to the any of the embodiments above the driving member could comprise a housing **157** shown in FIGS. **23, 24** and **26**. Said housing could be adapted to hold a lubricating fluid for lubricating at least a part of said driving member. Said lubricating fluid is preferably a biocompatible lubricating fluid, such as hyaluronic acid.

FIG. **43** shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum and/or the caput femur, according to an embodiment where said operating device comprises an electrical motor **158**. Said electrical motor is connected to the driving member **30**.

FIG. **44** shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum and/or the caput femur, according to an embodiment wherein said operating device comprises a hydraulic motor **159**, hydraulically connected to a hydraulic power source **160** by means of a hydraulic power transport system **161**.

FIG. **45** shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to an embodiment wherein said operating device comprises a hydraulic motor, but wherein the hydraulic power transport system is located substantially perpendicular to the hole creation direction.

FIG. **46** shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to a ninth embodiment wherein said instrument further comprises at least one of: at least one camera **163**, at least one light source **164**, at least one measurement device for measuring the depth of said hole in the pelvic bone or at least one torque meter **165** for sensing the torque exerted on the driving member **30** from the connection with the reaming organ and the operating device **23**.

FIG. **47** shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to a tenth embodiment in which the part of said instrument adapted to be inserted in the human body is covered with a housing **166** for protecting the human body from the parts of the surgical instrument, and the surgical instrument from the human body. The housing **166** could be made of a stiff or flexible material and could have an antibacterial surface. Said housing **166** could be adapted to be used to house the surgical instrument according to any of the embodiments.

FIG. **48** shows the surgical instrument adapted for a third, a fourth and/or a fifth application wherein said instrument is an instrument for flushing, cooling and/or sucking an affected area during an operation for treating hip joint osteoarthritis in a human patient. A member for flushing, cooling and/or sucking **400** is positioned on the proximal part of a hydraulic or pneumatic transportation system **404** comprising one pressure tube **401** and one suction tube **402**. In the application where the surgical instrument is used for flushing only, it is conceivable that the hydraulic or pneumatic transportation system **404** only comprises a pressure tube. Furthermore the surgical instrument according to the third application com-

prises a unit **403** that could comprise at least one of a pneumatic or hydraulic pumping device **405**, a cooling member **406**, a filter device **407** and an energy accumulating or transforming unit **408**. The portions of the instruments adapted to be placed in the abdominal area are the abdominal portions **250**, and the portions adapted to at least partially be placed inside of the pelvic bone is the pelvic portions **251** throughout this application.

FIG. **49** shows the surgical instrument adapted for a sixth application, wherein said instrument is an instrument comprising a mechanical element adapted to insert a prosthesis, a prosthetic parts or parts needed to create or provide a hip joint surface, according to a first embodiment wherein the surgical instrument comprises a gripping portion **76** and a handling portion **77**. According to the embodiments shown in FIG. **49** the instrument further comprises a rotation element **78** that enables the gripping part **76** to rotate in relation to the handling part **77**, however it is equally conceivable that the surgical instrument lacks this rotation element **78**.

According to other embodiments the mechanical element comprises a prosthesis or prosthetic part for insertion in the human body.

FIG. **50** shows the surgical instrument adapted for a sixth application, wherein said instrument is an instrument adapted to insert a prosthesis, prosthetic parts or parts needed to create or provide a hip joint surface, according to a second embodiment. According to this embodiment the surgical instrument **412** further comprises a parallel displaced section **79**, which increases the reach of the surgical instrument **412** and facilitates the reaching of the hip joint through a hole in the pelvic bone from the opposite side from acetabulum.

FIG. **51** shows the surgical instrument adapted for a sixth application, wherein said instrument is an instrument adapted to insert a prosthesis, prosthetic parts or parts needed to create or provide a hip joint surface, according to a third embodiment. According to this embodiment the surgical instrument **412** further comprises two angle adjusting members **80a,b**. The angle adjusting members could be adjustable for varying the angle of said gripping part **76** in relation to the handling portion **77**, or fixed in an angle suitable for creating operating in a hip joint through a hole in the pelvic bone from the opposite side from acetabulum **8**.

FIG. **52** shows the hip joint in section after the artificial caput femur surface **45**, and the artificial acetabulum surface **65** have been provided.

FIG. **53** shows the surgical instrument adapted for a sixth application, wherein said surgical instrument **412** is a surgical instrument **412** adapted to insert a prosthesis, prosthetic parts **46, 48** or parts needed to create or provide a hip joint surface when being used by a surgeon to insert a prosthesis, prosthetic parts **46, 48** or parts needed to create or provide a hip joint surface through an opening in said human body.

FIG. **54** shows a prosthesis, prosthetic parts **48** or parts needed to create or provide a hip joint surface inserted through laparoscopic trocars **33a,b,c**, through a small incision according to a laparoscopic method. The artificial hip joint surface parts **48** or the artificial caput femur surface parts **46** are adapted to be connected to each other after the insertion to form an artificial hip joint surface.

FIG. **55** shows how an expandable artificial caput femur surface **45** is being inserted through a hole **18** in the pelvic bone **9**, using said surgical instrument **412**.

FIG. **56a** shows the hip joint in section with a hole **18** in the pelvic bone **9**. An artificial caput femur surface **45** is introduced into the hip joint through the hole **18** in the pelvic bone **9** from the opposite side from acetabulum **8**. The artificial

caput femur surface parts **46** are connected to each other after insertion into the hip joint to form the artificial caput femur surface **45**.

FIG. **56b** shows the hip joint in section when the artificial caput femur surface parts **46** are connected to each other using the surgical instrument adapted for the sixth application. According to this embodiment the artificial caput femur surface parts **46** are adapted to supply a form fitting **47** that enables the parts to connect to each other without the use of any adhesive or additional mechanical parts. The surgical instrument adapted for the sixth application is adapted to be inserted through a hole **18** in the pelvic bone **9** and connecting said at least two hip joint surface parts **46** to each other. FIG. **56b** shows the artificial caput femur surface parts, however it is equally conceivable that the artificial hip joint surface parts are artificial acetabulum surface parts. The surgical instrument **413** could comprise at least one gripping member **414**, for gripping in the hip joint. The gripping member **414** could be powered by hydraulic, pneumatic or electrical energy. The gripping member **414** or otherwise part being in connection with said artificial hip joint surface parts is in connection with a handling part **416** through a connecting member **415**, which could be bent or otherwise adapted to improve the reach of the surgeon for operating in a hip joint through a hole **18** in the pelvic bone **9** of a human patient.

FIG. **56c** shows the artificial caput femur surface parts **46** with the parts supplying the form fitting **47**.

FIG. **57** shows the surgical instrument adapted for a seventh application, wherein the surgical instrument **416** is adapted to fixate a hip joint surface **45** to the caput femur **5** through a hole **18** in the pelvic bone **9**. According to the embodiment shown in FIG. **57** the surgical instrument **416** is adapted to fixate an artificial caput femur surface, however it is equally conceivable that the surgical instrument **416** is adapted to fixate an artificial acetabulum surface to the pelvic bone **9**. The fixation could be done by means of screws, form fitting, welding, adhesive, sprint, band, or other mechanical connecting members. The surgical instrument **416** in FIG. **57** further comprises a member for providing rotational force **417** which could be used to fixate an artificial hip joint surface with screws or other rotation fixation members. The proximal part of the surgical instrument **416** could however also be equipped with a welding electrode, or a tool for fixating artificial hip joint surface using sprint or band.

FIG. **58** shows the surgical instrument adapted for a seventh application, wherein the surgical instrument **416** is adapted to fixate a hip joint surface **45** to the caput femur **5** through a hole **18** in the pelvic bone **9**. According to this embodiment the surgical instrument **418** is a surgical instrument **418** adapted to fixate an artificial caput femur surface **45** to the caput femur **5** using bone cement or adhesive. According to this embodiment the surgical instrument **418** comprises a hollow space **419** for housing the fluid **419** such as bone cement or adhesive to be used in the fixation of the artificial hip joint surface. A piston part **420** supplies the pressure to the fluid **419** and pushes it through an injecting tip **422**. The piston part **420** is powered or manually operated via a force rod **421** which could be flexible for improved reach.

FIG. **59a** shows the surgical instrument adapted for an eight application wherein the instrument is adapted for placing a mould or a first and/or second sealing member in the hip joint through a hole in the pelvic bone, the femur bone or the hip joint capsule. The mould or sealing member could be used to create an artificial hip joint surface inside of the hip joint. The surgical instrument **423** comprises a piston **89** for transporting said mould or first and/or second sealing member into

the hip joint and a tube like element **90** for housing of said mould or first and/or second sealing member.

FIG. **59b** shows a section of the surgical instrument **413** comprising the tube like element **90** for housing of said mould or first and/or second sealing member

FIG. **59c** shows the surgical instrument **413** according to another embodiment in which the surgical instrument **413** comprises a flexible or bent part **91** improving the reach of the surgical instrument **413**. The surgical instrument **413** according to any of the embodiments can be used to place said mould or first or second sealing members inside of the hip joint in any of the ways described in the following embodiments.

FIG. **60a** shows the surgical instrument **423** adapted to insert the mould or first and/or second sealing member in the hip joint, according to a second embodiment. According to this embodiment the surgical instrument **423** comprises a gripping portion **76** and a handling portion **77**. According to the embodiments shown in FIG. **60a,b,c** the surgical instrument **423** further comprises a rotation element **78** that enables the gripping part **76** to rotate in relation to the handling part **77**, however it is equally conceivable that the surgical instrument **423** lacks this rotation element **78**.

FIG. **60b** shows the surgical instrument **423** adapted to insert the mould or first and/or second sealing member in the hip joint, according to a third embodiment. According to this embodiment the surgical instrument further comprises a parallel displaced section **79**, which increases the reach of the surgical instrument **423** and facilitates the reaching of the hip joint through a hole **18** in the pelvic bone **9**, the femoral bone or the hip joint capsule.

FIG. **60c** shows the surgical instrument **423** adapted to insert the mould or first and/or second sealing member in the hip joint, according to a third embodiment. According to this embodiment the surgical instrument **423** further comprises two angle adjusting members **80a,b**. The angle adjusting members **80a,b** could be adjustable for varying the angle of said gripping part **76** in relation to the handling portion **77**, or fixed in an angle suitable for operating in a hip joint through a hole **18** in the pelvic bone **9**, the femur bone or the hip joint capsule.

FIG. **61** shows the hip joint in section wherein a mould or a first sealing member **84** is inserted through a hole **18** in the pelvic bone **9** using an instrument adapted therefor **85**. The step of placing said mould or first sealing member **84** can be performed in a surgical, or in a laparoscopic method.

FIG. **62** shows the hip joint in section wherein a second sealing member **86** is inserted through a hole in the pelvic bone **9** in a surgical or a laparoscopic method. The first **84** and second **86** sealing members creates a sealed space **87** between the acetabulum **8** and the caput femur **5** adapted to be used as a mould for providing an artificial acetabulum **65** and/or a caput femur surface **45**.

FIG. **63a,b,c** shows an alternative approach to placing said mould or first sealing member **84** in the hip joint of a human patient. Said alternative approach comprises the steps of creating a hole **82** in the femur bone **7** following a length axis of the collum femur **6**, as shown in FIG. **63a**, said hole starting from the lateral side of the thigh, penetrating the cortex of the femur bone **7** and eventually reaching the cortex of the caput femur **5** from the inside thereof, penetrating said cortex and entering into the hip joint. After the creation of the hole **82** in the femur bone **7** the mould or first sealing member **84** is inserted into the hip joint through the hole **82** using a surgical instrument **88** adapted therefor, as shown in FIG. **63c**. This approach could also be used for placing a second sealing member **86** in pelvic bone **9** or the femur bone **7** through the hole **82** in the femur bone **7**.

FIG. **64** shows a third approach to the placing of a mould or a first sealing member **84** inside of the hip joint. According to this approach the first sealing **84** member is placed in the hip joint through the hip joint capsule **12**.

It is furthermore conceivable that the first sealing member **84** is placed in the hip joint using any of the approaches above, whereas the second sealing member **86** is placed in the hip joint using another of the approaches above.

FIG. **65** shows the surgical instrument adapted for a ninth application, wherein the surgical instrument is an injecting member **92** adapted to inject a fluid **93** into a mould or sealed area **81** in the hip joint through a hole **18** in the pelvic bone **9** from the opposite side from acetabulum **8**. The injecting member **92** comprises a piston **94** that pushes said fluid **93** into the mould **81**.

FIG. **66** shows the hip joint in section wherein an injecting member **92** injects a fluid **93** into a mould **81** or a sealed area in the hip joint through a hole **82** in the femur bone **7**. The injecting member **92** comprises a piston **94** that pushes said fluid **93** into the mould **81**.

FIG. **67** shows the hip joint in section wherein an injecting member injects a fluid **93** into a mould **81** in the hip joint through a hole in the hip joint capsule **12**. The injecting member **92** comprises a piston **94** that pushes said fluid **93** into the mould **81**. Said fluid **93** being adapted to harden to create a medical device adapted to serve as at least one artificial hip joint surface.

FIG. **68** shows the hip joint in section wherein the medical device **93'** is located between the acetabulum **8** and the caput femur **5** which has been created by the hardening of the fluid **93** adapted to harden. Said medical device is adapted to serve as at least one artificial hip joint surface. The hole in the pelvic bone is preferably sealed with a bone plug **31** or a prosthetic part **98**. The mould **81** used to create the medical device **93'** has been resorbed by the human body. According to another embodiment the mould used to create the medical device **93'** has melted.

FIG. **69** shows a lateral section of the human body wherein an injecting member **92** injects a fluid into a mould **81** or a sealed area in the hip joint through a hole **18** in the pelvic bone **9** from the opposite side from acetabulum **8**. The injecting member penetrates the skin **300** of the human patient in a surgical or laparoscopic method.

FIG. **70** shows the injecting member **92** according to any of the embodiments above, adapted to inject fluid **93** into a mould **81** in the hip joint. The injecting member **92** could further be adapted to inject material **93** or a fluid **93** into a connecting area between the pelvic bone **9** and a prosthetic part, the pelvic bone **9** and a bone plug **31** or the caput femur **5** and a prosthetic part. Said injecting member **92** comprises a container **107** adapted to hold a fluid **93** for injection. According to a first embodiment said container **107** comprises two compartments **108a,b** adapted to hold two different fluids, said fluids being adapted to harden when mixed. In the embodiment when the container **107** is adapted to hold two fluids, it is conceivable that the injecting member **105** further comprises a mixing member **109** wherein said two fluids are being mixed before injection. According to a second embodiment (not shown) said container **107** is adapted to keep said fluid sterile. According to a third embodiment (not shown) said container **107** is adapted to keep said fluid cold or hot and according to a fourth embodiment (not shown) said container **107** is adapted to keep said fluid in a dark environment. Furthermore a combination of the above mentioned embodiments is conceivable.

According to another embodiment (not shown) the fluid is adapted to harden through the mixing with a gas. In which

case one of the two compartments is adapted to hold a pressurized gas (such as nitrogen gas) adapted to act as catalyzing agent for the fluid adapted to harden. According to that embodiment the mixing unit **109** is adapted to mix one liquid and one gas fluid. Said first, second or mixed fluid could also be adapted to harden by means of UV-light, thermic change or contact with a body fluid.

According to a tenth application the surgical instrument is adapted to assist in the placing of a bone plug or prosthetic part for sealing the hole in the pelvic bone created to reach the hip joint from the abdominal side of the pelvic bone.

FIG. **71a** shows a prosthetic part **98** being inserted into a hole **18** in the pelvic bone **9** from the opposite side from acetabulum **8**. According to one embodiment the prosthetic part **98** comprises supporting members **99** adapted to correspond with sections **100** of the hole **18** in the pelvic bone **9**. After the prosthetic part **98** has been inserted using said surgical instrument it is rotated so that the supporting members **99** comes in contact with the pelvic bone **9** and can carry the load placed on the acetabulum **8** from weight of the human patient through the contact with the caput femur **5**. Said prosthetic part **98** could also be adapted to serve as artificial acetabulum surface **65** according to any of the above mentioned embodiments.

FIG. **71b** shows the prosthetic part **98** when rotated to carry the load placed on the acetabulum **8** from weight of the human patient through the contact with the caput femur **5**.

FIG. **72** shows the hip joint of a human patient in section wherein the prosthetic part **98** closes the hole **18** in the pelvic bone **9** and carries the load placed on the acetabulum **8** from weight of the human patient through the contact with the caput femur **5** by means of the supporting members **99**. The prosthetic part **98** can further be fixated to the pelvic bone **9** by means of bone cement, adhesive, screws, form fitting, welding, sprints, band or some other mechanical connecting member.

FIG. **73** shows the hip joint of a human patient in section wherein bone plug **31** or prosthetic part **98** is attached to the pelvic bone **9** by means of screws **101** placed from the opposite side from acetabulum **8**. The screws **101** are possible to place in different angles depending on reach or need for support.

According to an eleventh application the surgical instrument is adapted to assist in the fixation of a bone plug or prosthetic part for sealing the hole in the pelvic bone created to reach the hip joint from the abdominal side of the pelvic bone

FIG. **74a** shows the hip joint of a human patient in section wherein the surgical instrument **424** is adapted to place screws **103** bone fixating a plate **102** that at least partly covers said bone plug **31** or prosthetic part **98**. According to a first embodiment the surgical instrument **424** comprises a flexible part or section **426** that improves the reach of said surgical instrument **424**. The surgical instrument **424** further comprises an operating device **425** that supplies rotational force to the surgical instrument for fixating the screws **103**.

FIG. **74b** shows the surgical instrument **424** according to a second embodiment wherein said surgical instrument comprises a parallel displaced part or section **427** that improves the reach of said surgical instrument **424**.

FIG. **74c** shows the surgical instrument **424** according to a third embodiment wherein said surgical instrument comprises two angle adjusting members **428** that improves the reach of said surgical instrument **424**.

In the above mentioned embodiments the plate **102** and/or the bone plug **31** or prosthetic part **98** are fixated by means of screws **103**, however it is equally conceivable that said screws

103 can be replaced or assisted by bone cement, adhesive, form fitting, welding, sprints, band or some other mechanical connecting member.

FIG. **75** shows the surgical instrument adapted for an eleventh application wherein said surgical instrument **434** is an arthroscopic camera adapted to be inserted into the hip joint through a hole **18** in the pelvic bone from the abdominal side thereof. It is also conceivable that said surgical instrument **434** is a light source (not shown) or a device for performing x-ray of the hip joint (not shown).

FIG. **76** shows a twelfth application. The surgical instrument **492** is adapted to inject a lubricating fluid into the hip joint, through a hole **18** in the pelvic bone **9**. Said lubricating fluid is preferably a biocompatible lubricating fluid such as hyaluronic acid. The surgical instrument **492** comprises a container **493** and a fluid transporting member **494** for transporting said fluid from the container **493** to the injecting member **495**, which is the proximal part of said fluid transporting member. The portions of the instruments adapted to be placed in the abdominal area are the abdominal portions **250**, and the portions adapted to at least partially be placed inside of the pelvic bone is the pelvic portions **251** throughout this application.

Please note that any embodiment or part of embodiment, feature, method, associated system, part of system described herein may be combined in any way.

The invention claimed is:

1. A surgical instrument for operating hip joint osteoarthritis in a human patient, a hip joint comprising an acetabulum, the acetabulum being a part of a pelvic bone, and a caput femur, the caput femur being a proximal part of a femoral bone, wherein said surgical instrument is adapted to assist in the operating of the hip joint osteoarthritis from an abdominal side of the pelvic bone of said human patient, said surgical instrument comprising:

an abdominal portion insertable through an incision in a skin in an abdominal region and adapted to be placed between the incision in the abdominal region and the pelvic bone when the instrument is in use, and

a pelvic portion connected to the abdominal portion, being partially insertable through a hole in the pelvic bone from the abdominal side of the pelvic bone, when the instrument is in use, wherein a portion of the pelvic portion is adapted to operate at least partially in a surgically created hole in the pelvic bone, and

a reamer connected to the pelvic portion and being adapted to at least one of ream the acetabulum of said human patient, ream the caput femur of said human patient, and ream both the acetabulum and the caput femur of said human patient, wherein said reamer is expandable, thus allowing said surgical instrument to be inserted through a hole in the pelvic bone smaller than the area possible to ream using said surgical instrument, and

an angle adjusting member for adjusting the angle between the reamer and the abdominal portion, and wherein the abdominal portion is more than 100 mm, such that the abdominal portion can reach from the incision in the abdominal region to an area of the hip joint opposite the acetabulum.

2. The surgical instrument according to claim 1, wherein said surgical instrument comprises a bend between said abdominal portion and said pelvic portion.

3. The surgical instrument according to claim 1, further comprising a gripping end for handling of the instrument, wherein said gripping end is connected to the abdominal portion and adapted to remain outside the skin of the patient when the instrument is in use, wherein a portion between the

gripping end and a bend is at least 100 mm such that the bend can be placed at the pelvic bone on the opposite side from acetabulum.

4. The surgical instrument according to claim 1, further comprising a gripping end for handling of the instrument, wherein said gripping end is connected to the abdominal portion and adapted to remain outside the skin of the patient when the instrument is in use, wherein a portion between the gripping end and a bend is at least 200 mm such that the instrument can operate inside of the hip joint from the abdominal side of the pelvic bone.

5. The surgical instrument according to claim 1, wherein the surgical instrument is a laparoscopic instrument adapted to be inserted through the skin of the abdominal region through a laparoscopic port.

6. The surgical instrument according to claim 1, wherein the surgical instrument is a laparoscopic instrument introduced into the abdomen and further down to the pelvic bone on the opposite side of the acetabulum and introduced into the hip joint, further comprising a gripping end, placed outside the abdominal wall when in use, and a hip joint end adapted to be placed in an area of the hip joint, wherein the length of said instrument is adapted to reach from the gripping end and into the hip joint via a surgically created hole in the pelvic bone and wherein the longitudinal extension of said instrument comprises at least one bend, for the instrument to reach, when used as a laparoscopic instrument to operate the hip joint, from the gripping end into the abdomen and further down to the pelvic bone on the opposite side of the acetabulum and be introduced into the hip joint through the surgically created hole in the pelvic bone.

7. The surgical instrument according to claim 1, wherein the surgical instrument is a pelvic instrument introduced into the pelvic region and further to the pelvic bone on the opposite side of the acetabulum, and introduced into the hip joint via a surgically created hole in the pelvic bone, further comprising a gripping end, placed outside the skin above the pelvic region when in use, and a hip joint end adapted to be placed in an area of the hip joint, wherein a length of said instrument is adapted to reach from the gripping end and into the hip joint, and wherein a longitudinal extension of said instrument comprises at least one bend, for the instrument to reach, when used as a pelvic instrument to operate the hip joint, from the gripping end into the pelvic region and further down to the pelvic bone on the opposite side of the acetabulum, and introduced into the hip joint through the surgically created hole in the pelvic bone.

8. The surgical instrument according to claim 1, wherein the surgical instrument is a retroperitoneal instrument introduced into the body just above the inguinal region following the pelvic bone down to the opposite side of the acetabulum and thereafter introduced into the hip joint via a surgically created hole in the pelvic bone, further comprising a gripping end, placed outside the skin above the pelvic region when in use, and a hip joint end adapted to be placed in an area of the hip joint, wherein a length of said instrument is adapted to reach from the gripping end and into the hip joint and wherein a longitudinal extension of said instrument comprises at least one bend, for the instrument to reach, when used as retroperitoneal instrument to operate the hip joint, from the gripping end following the pelvic bone and further down to the pelvic bone on an opposite side of the acetabulum and introduced into the hip joint through the surgically created hole in the pelvic bone.

9. The surgical instrument according to claim 1, wherein said instrument further comprises at least one holding portion connected to the pelvic portion, and at least one mechanical element adapted to be fitted to said at least one holding portion of said instrument, wherein said mechanical element is adapted to perform a function during an operation of the hip joint, wherein said mechanical element is adapted to be part of an instrument adapted to be used for at least one of the following functions; drilling, reaming, cooling, heating, flushing, introducing a fluid, sucking, inserting at least one part, connecting at least one part, fixating at least one part, inserting a mould, filling a mould, injecting, lubricating, viewing, optically displaying, placing screws, placing adhesive, and placing bone cement.

10. The surgical instrument according to claim 6, wherein the distance between the gripping end and the bend is at least one of; at least 150 mm, at least 200 mm, at least 300 mm, at least 400 mm, and at least 500 mm.

11. The surgical instrument according to claim 2, wherein said bend is bent with an angle of at least one of; at least 10 degrees, at least 20 degrees, at least 30 degrees, at least 40 degrees, at least 50 degrees, and at least 60 degrees.

12. The surgical instrument according to claim 2, wherein the distance between said bend and the pelvic portion of the instrument is at least one of at least 20 mm, at least 40 mm, at least 60 mm, at least 80 mm, at least 100 mm, at least 120 mm, and at least 140 mm.

13. The surgical instrument according to claim 1, wherein said surgical instrument further comprising at least one camera.

14. The surgical instrument according to claim 1, wherein said surgical instrument further comprising at least one light source.

15. The surgical instrument according to claim 1, wherein said surgical instrument is adapted to at least one of:

introduce a prosthesis through the hole in the pelvic bone and into the hip joint,

connect at least two prosthetic parts to each other after insertion into the hip joint,

fixate an artificial hip joint surface, or a part of an artificial hip joint surface, to the pelvic bone or the femoral bone, and

place or fixate fixating elements to the pelvic bone or a prosthetic part in the hip region or the pelvic bone region.

16. The surgical instrument according to any one of claims 1, wherein said surgical instrument is adapted to at least one of;

cool an area of the hip joint or an area of the pelvic bone, provide a fluid to an area of the pelvic bone or the hip joint, and

provide suction to an area of the pelvic bone or an area of the hip joint,

introduce a mould into the hip joint,

inject a fluid into a mould placed in the hip joint,

introduce adhesive into the hip joint,

inject a lubricating fluid into the hip joint, said surgical instrument comprising at least one container, a fluid injecting member, and a fluid driving member in fluid connection with said fluid injecting member and said at least one container.

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摘要(译)

提供了一种用于在人类患者中操作髋关节骨关节炎的手术器械。髋关节包括作为骨盆骨的一部分的髌臼和作为股骨的近端部分的股骨头股骨。手术器械适于帮助从所述人类患者的骨盆骨的腹侧操作髋关节骨关节炎。

