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(54) **SURGICAL STAPLER**

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(*) Notice: Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 0 days.

This patent is subject to a terminal disclaimer.

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Related U.S. Application Data

(63) Continuation of application No. 13/593,628, filed on Aug. 24, 2012, now Pat. No. 8,453,912, which is a continuation of application No. 13/414,185, filed on Mar. 7, 2012, now Pat. No. 8,272,553, which is a continuation of application No. 13/210,470, filed on Aug. 16, 2011, now Pat. No. 8,162,197, which is a continuation of application No. 12/794,925, filed on Jun. 7, 2010, now Pat. No. 8,011,553, which is a continuation of application No. 12/644,450, filed on Dec. 22, 2009, now Pat. No. 7,913,893, which is a continuation of application No. 12/118,924, filed on May 12, 2008, now Pat. No. 7,770,774, which is a continuation of application No. 11/903,586, filed on Sep. 24, 2007, now Pat. No. 7,472,814, which is a continuation of application No. 11/590,441, filed on Oct. 30, 2006, now Pat. No. 7,278,562, which is a continuation of application No. 11/186,743, filed on Jul. 20, 2005, now Pat. No. 7,128,253, which is a continuation of application No. 11/011,355, filed on Dec. 14, 2004, now Pat. No. 7,044,353, which is a continuation of application No. 09/625,886, filed on Jul. 26, 2000, now Pat. No. 6,986,451, which is a continuation of application No. 09/497,647, filed on Feb. 3, 2000, now abandoned, which is a continuation of application No. 09/119,543, filed on Jul. 20, 1998, now Pat. No. 6,032,849, which is a continuation of application No. 08/546,253, filed on Oct. 20, 1995, now Pat. No. 5,782,396, which is a continuation of application No. 08/520,202, filed on Aug. 28, 1995, now Pat. No. 5,762,256.

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A61B 17/068 (2006.01)

(52) **U.S. Cl.**
USPC **227/176.1**; 227/19; 227/180.1; 606/139; 606/219

(58) **Field of Classification Search**
USPC 227/19, 175.1, 176.1, 175.2, 180.1; 606/139, 219
See application file for complete search history.

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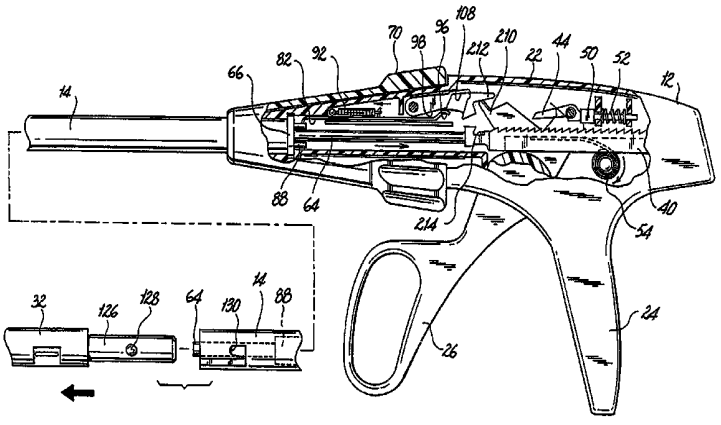
Primary Examiner — Scott A. Smith

(57) **ABSTRACT**

A surgical device is described herein that can be used to fire different types and sizes of disposable loading units. In a preferred embodiment, the device applies parallel rows of surgical fasteners to body tissue and concomitantly forms an incision between the rows of staples during an endoscopic or laparoscopic surgical procedure. The device can be utilized with disposable loading units configured to apply linear rows of staples measuring from about 15 mm in length to about 60 mm in length and can be used to fire disposable loading units containing surgical clips and individual staples.

12 Claims, 38 Drawing Sheets



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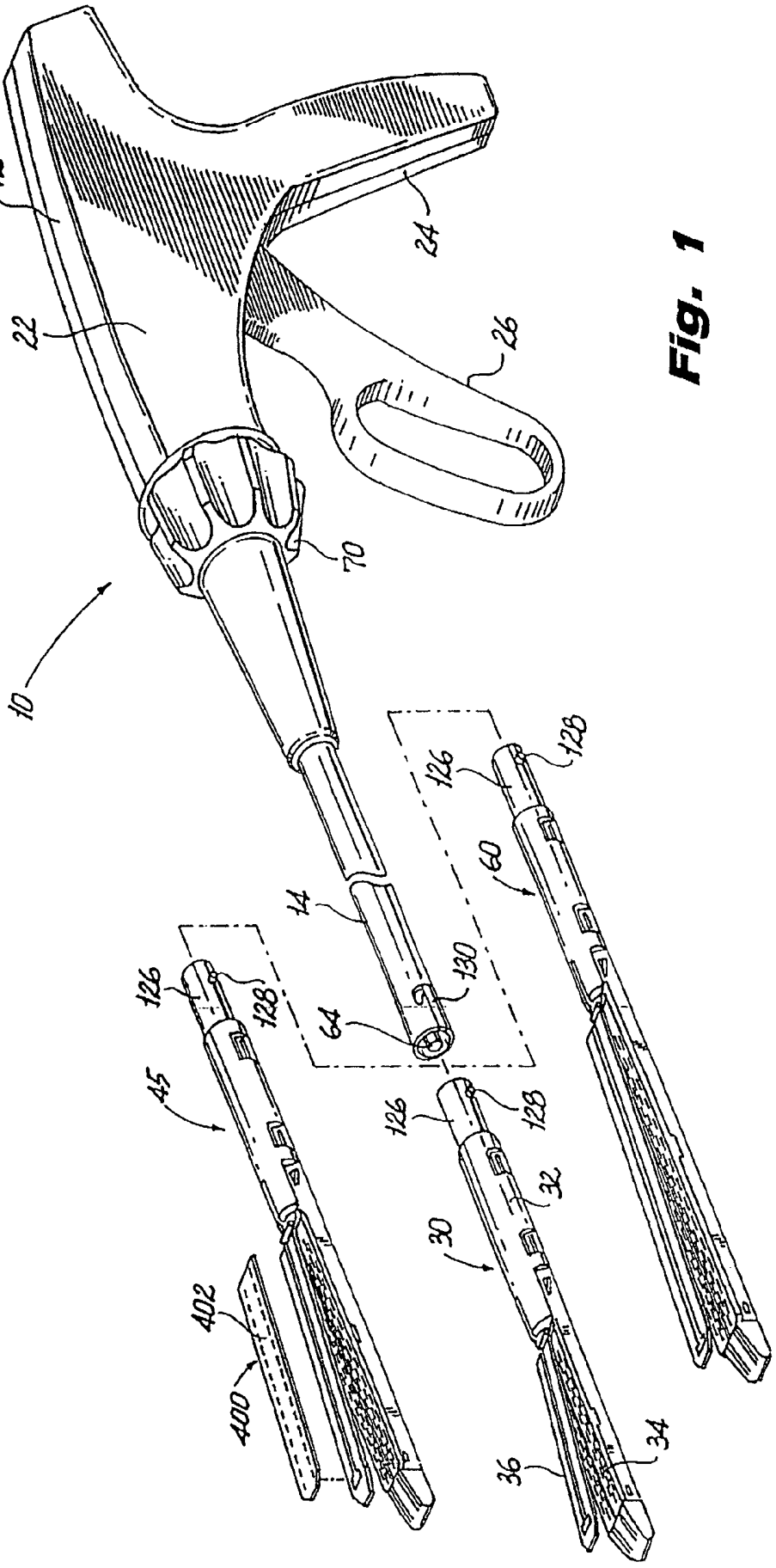
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Fig. 1

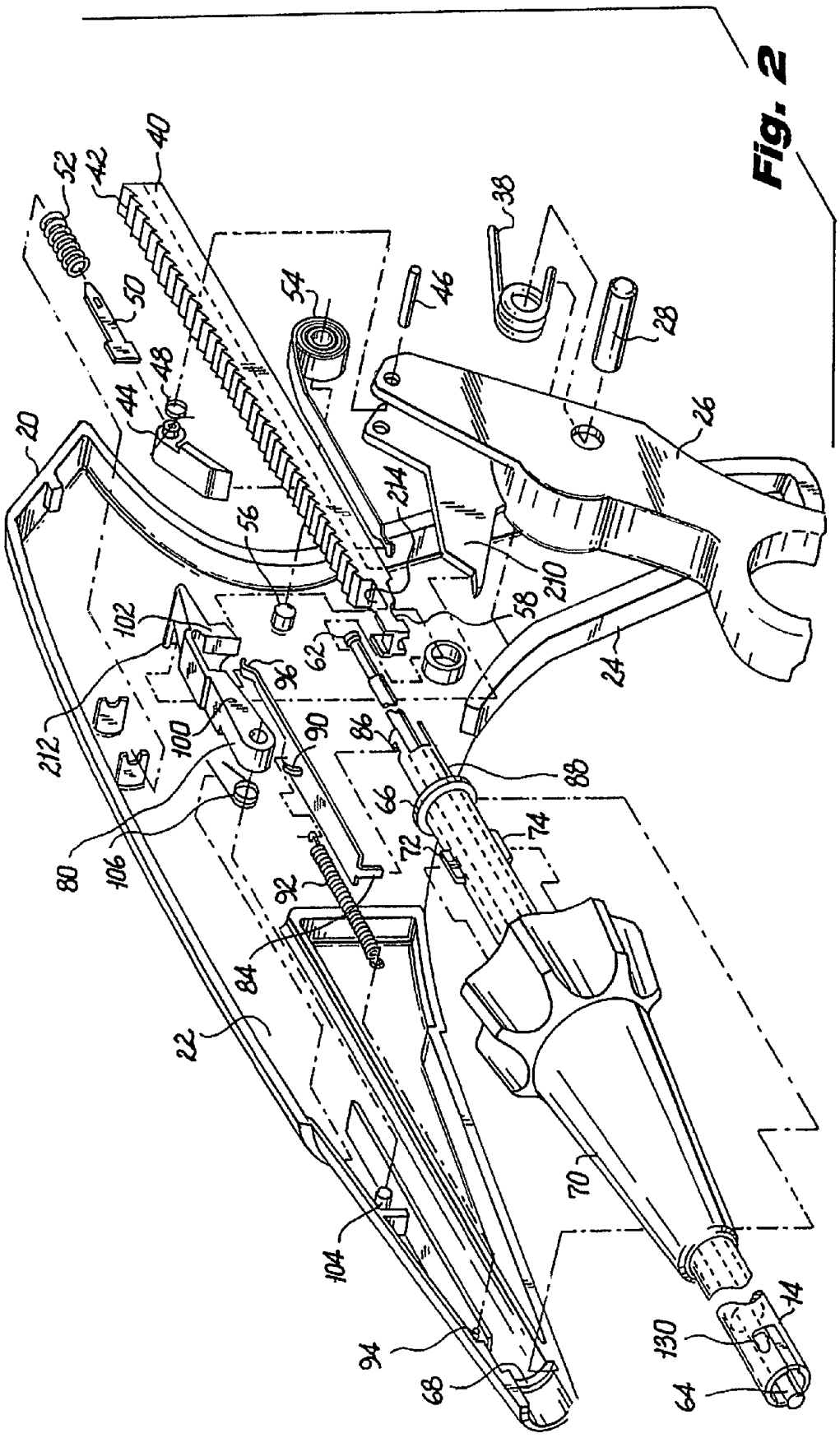
Fig. 2
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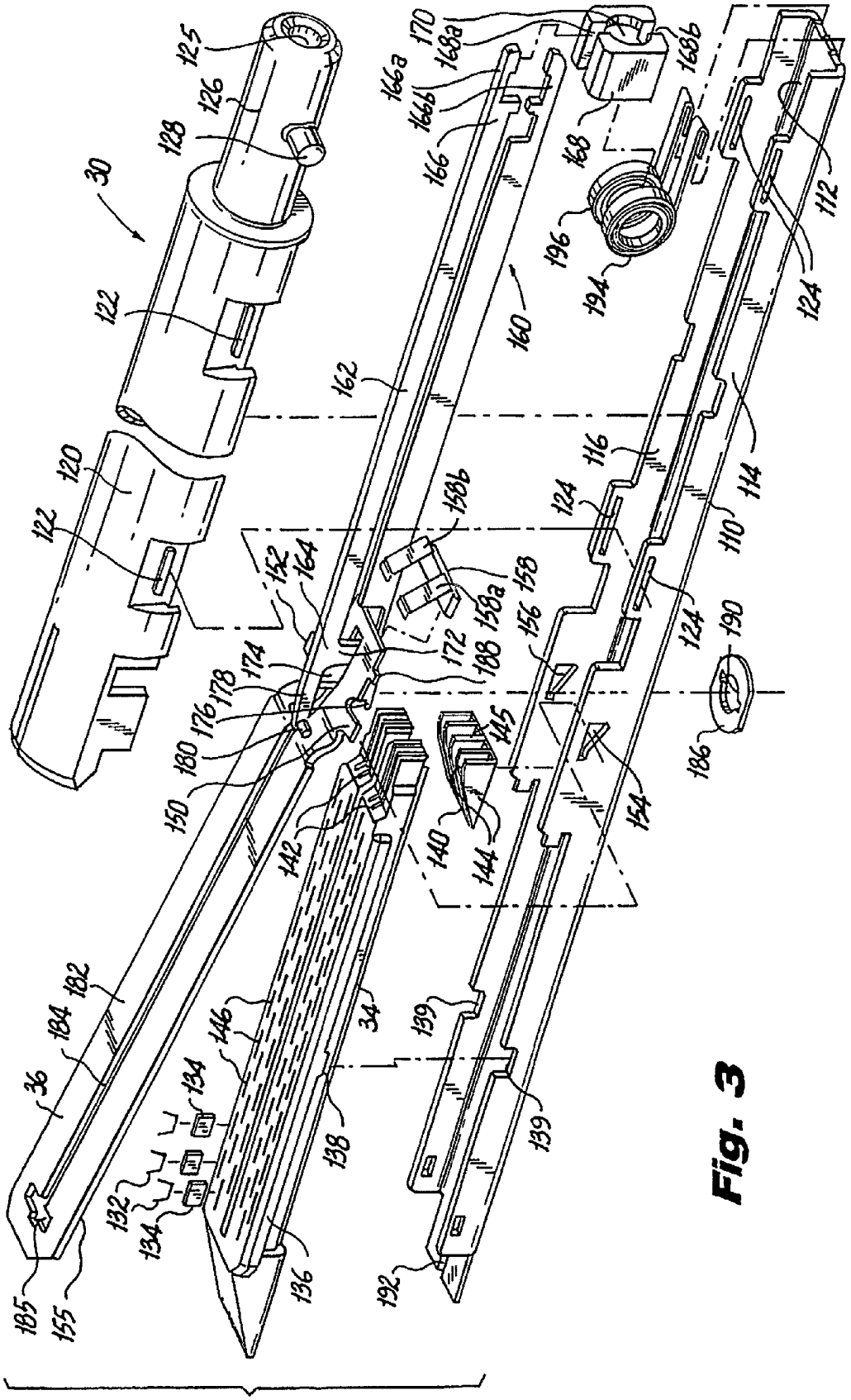
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Fig. 3

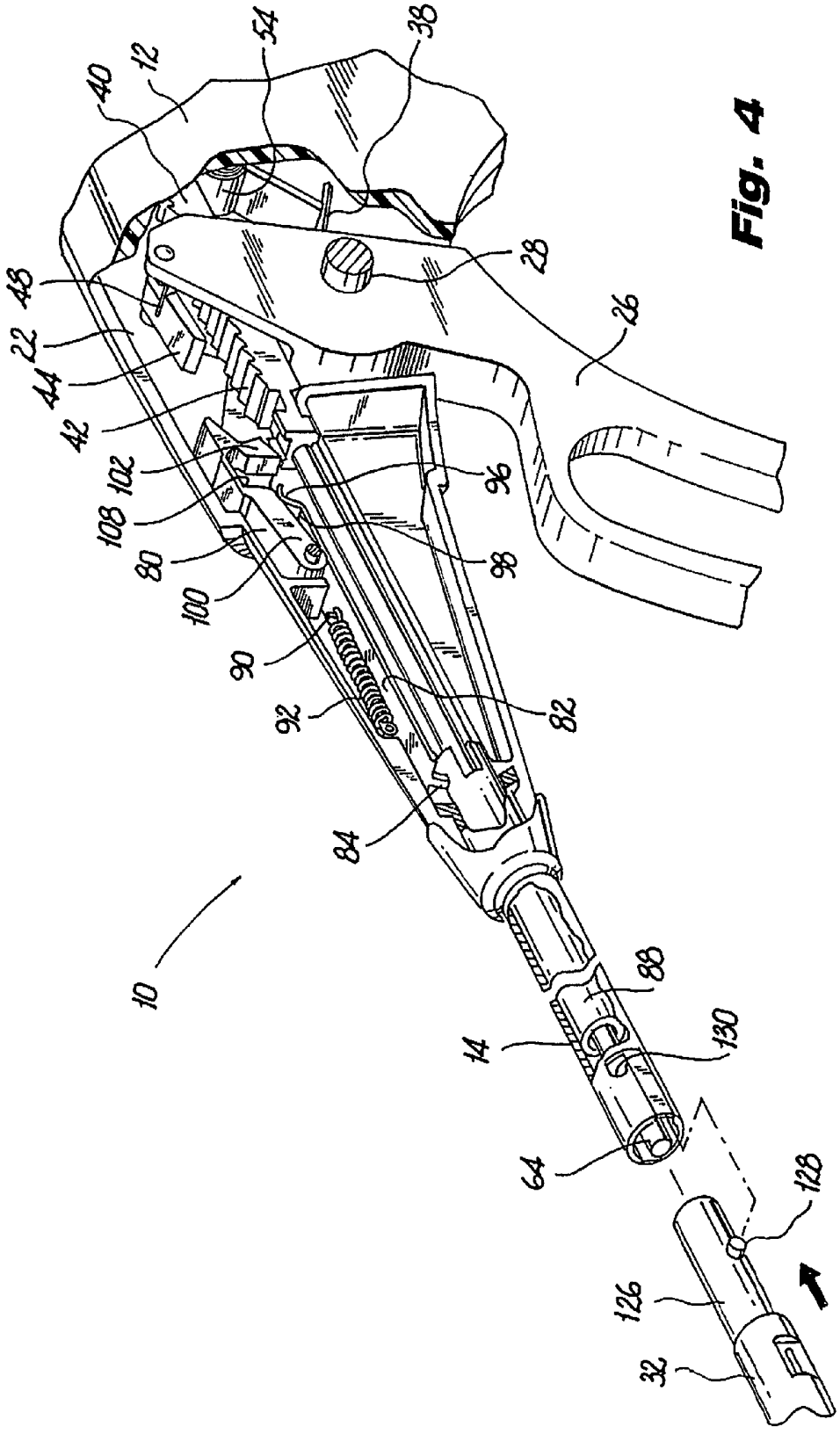
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Fig. 4

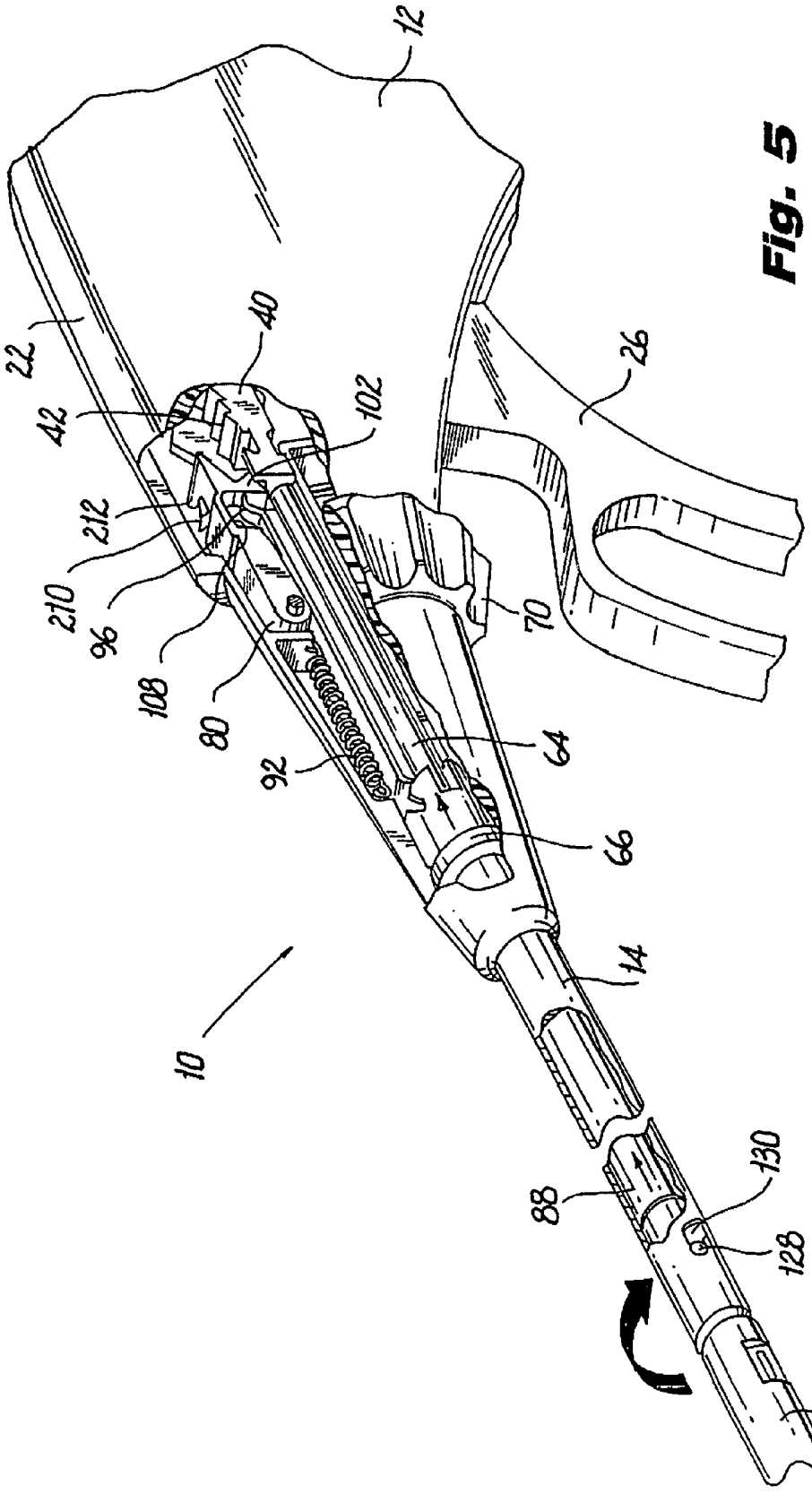

Fig. 5

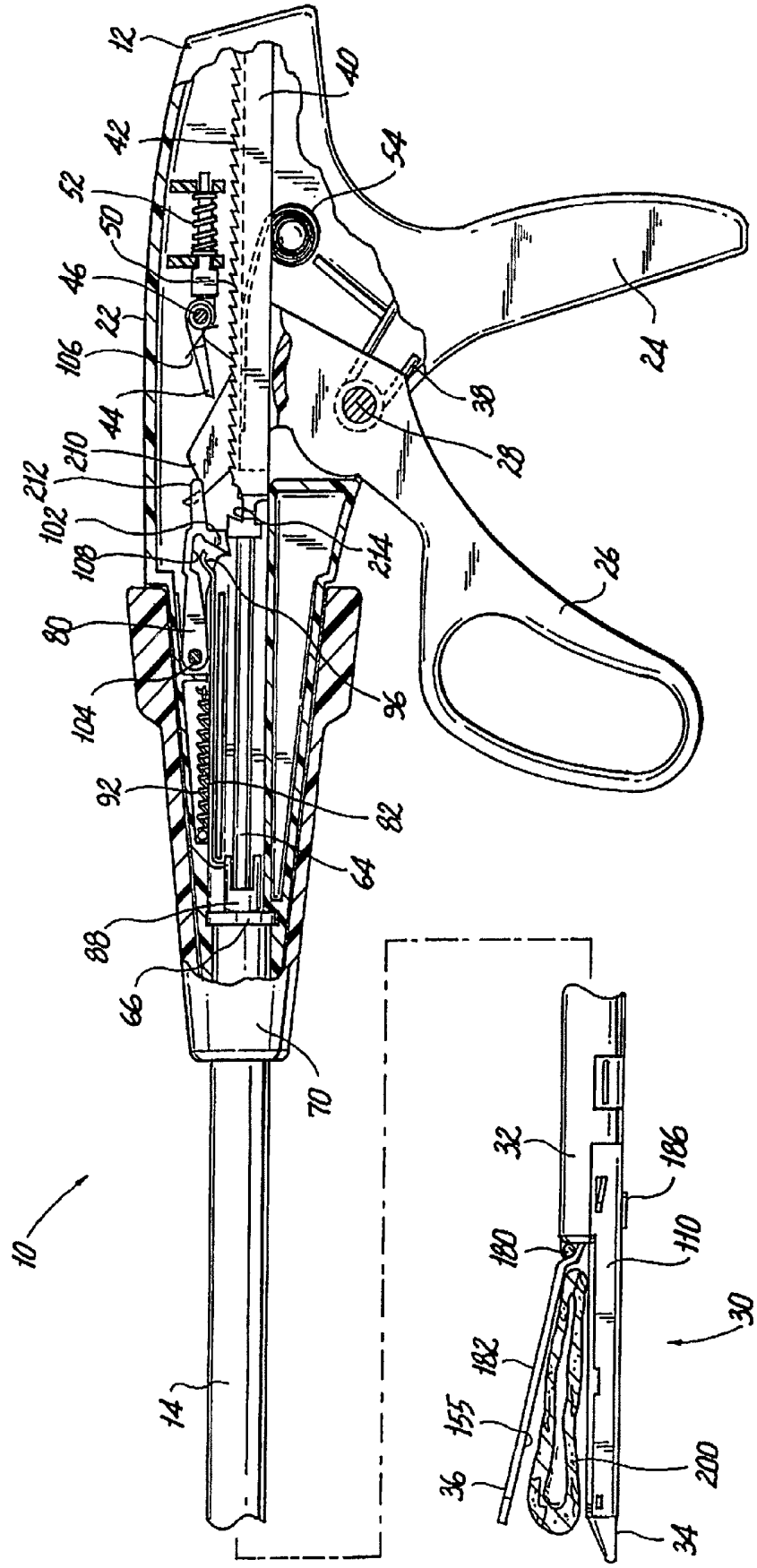
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Fig. 6

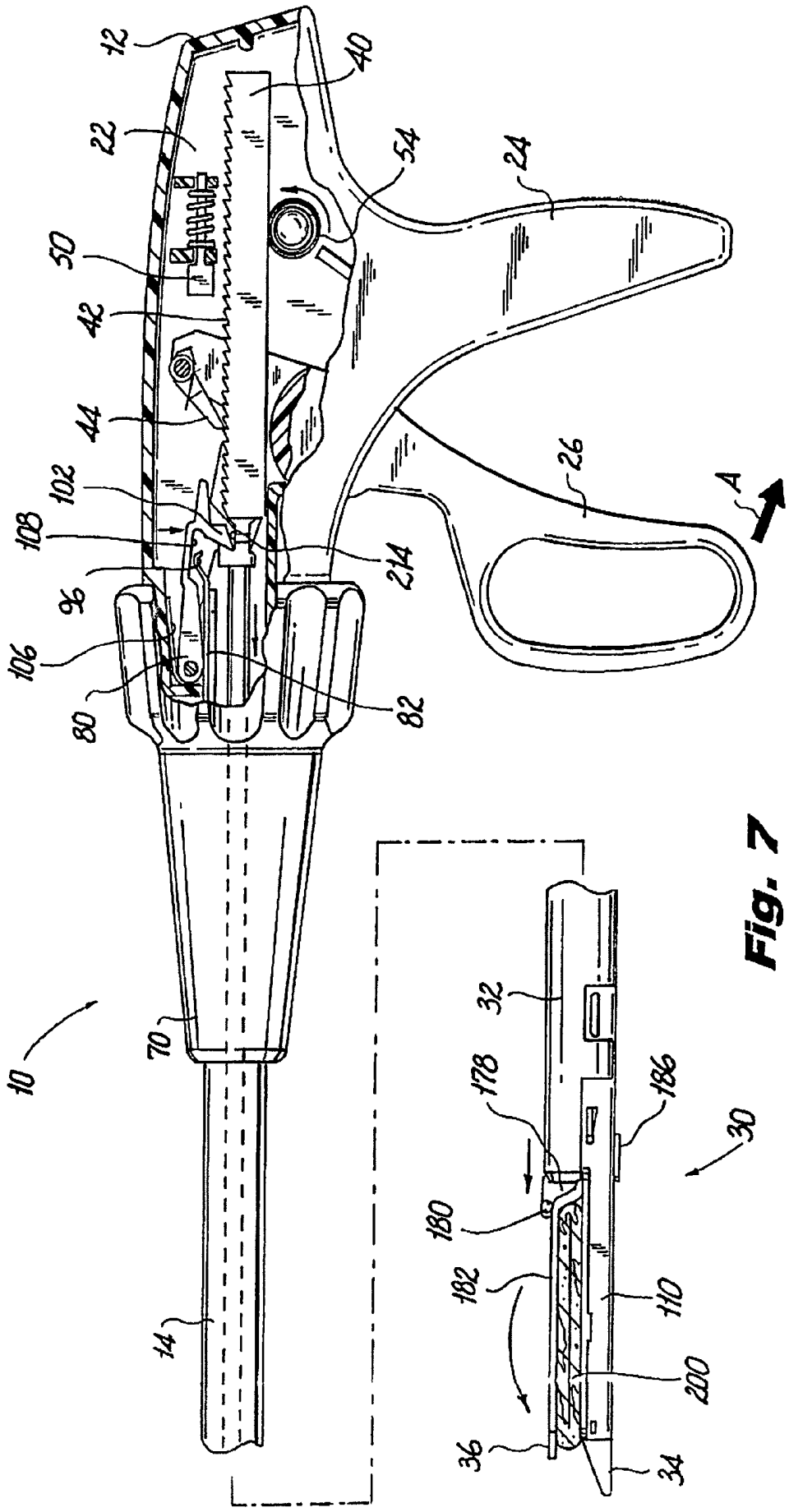
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Fig. 7

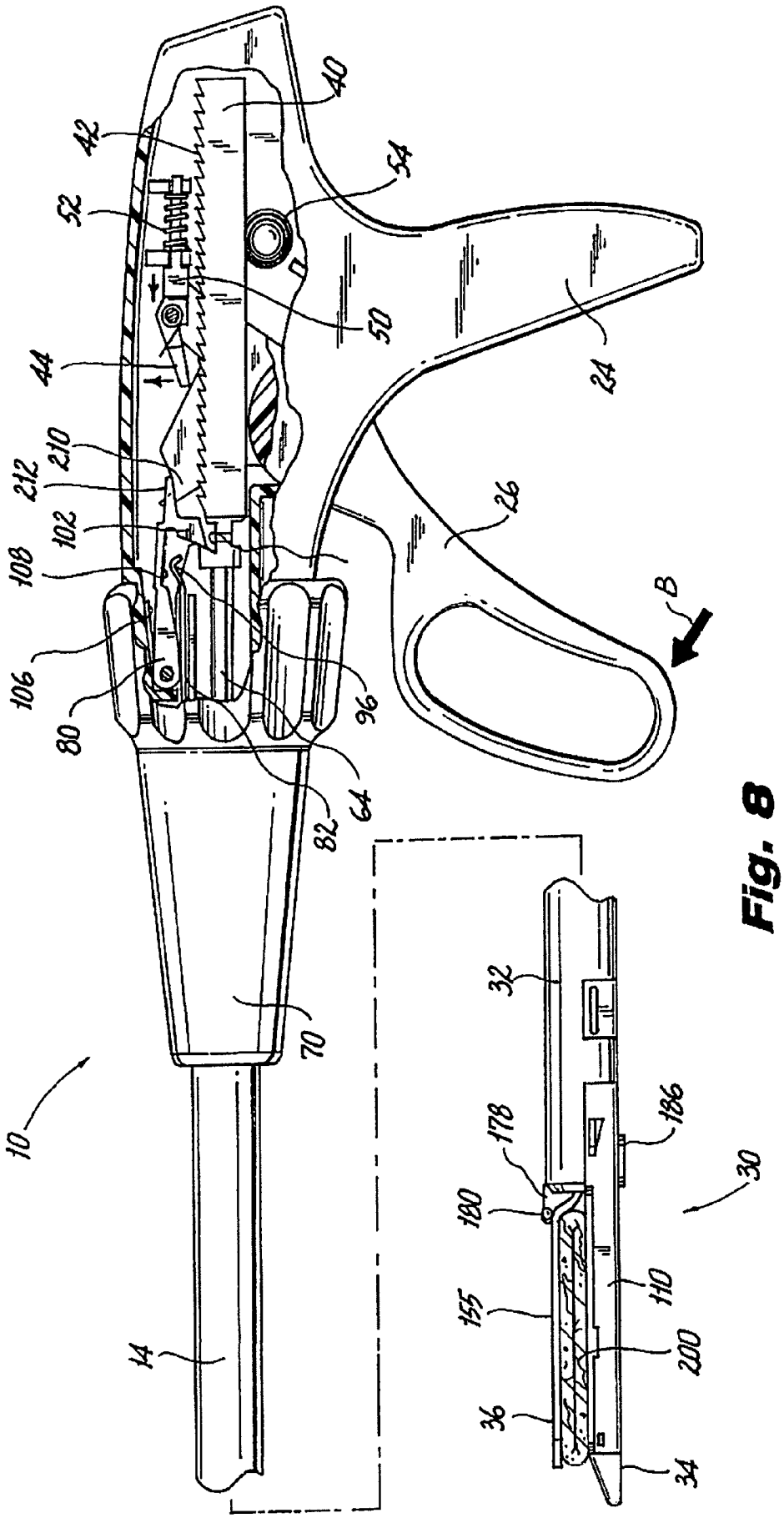
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Fig. 8

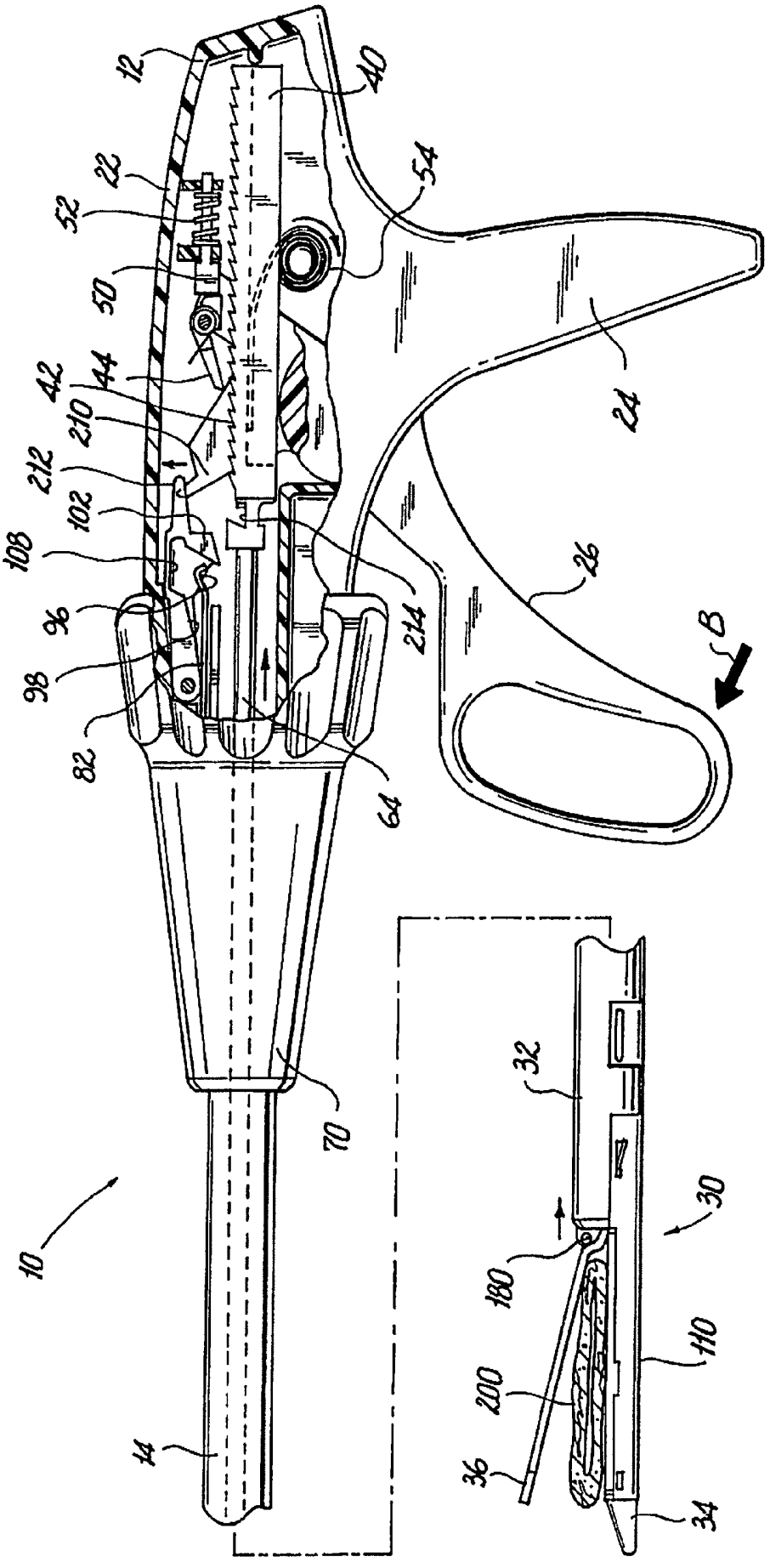
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Fig. 9

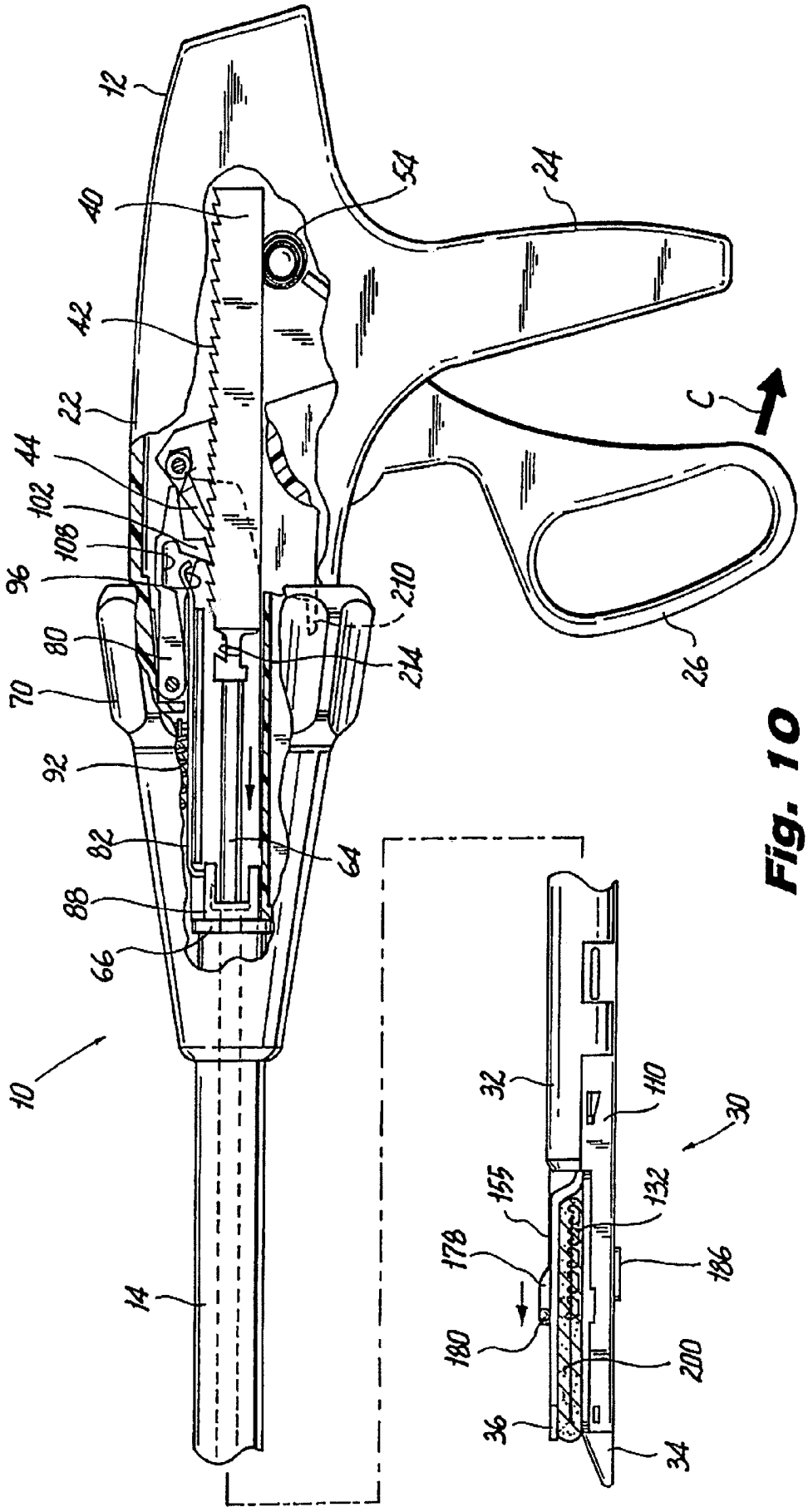
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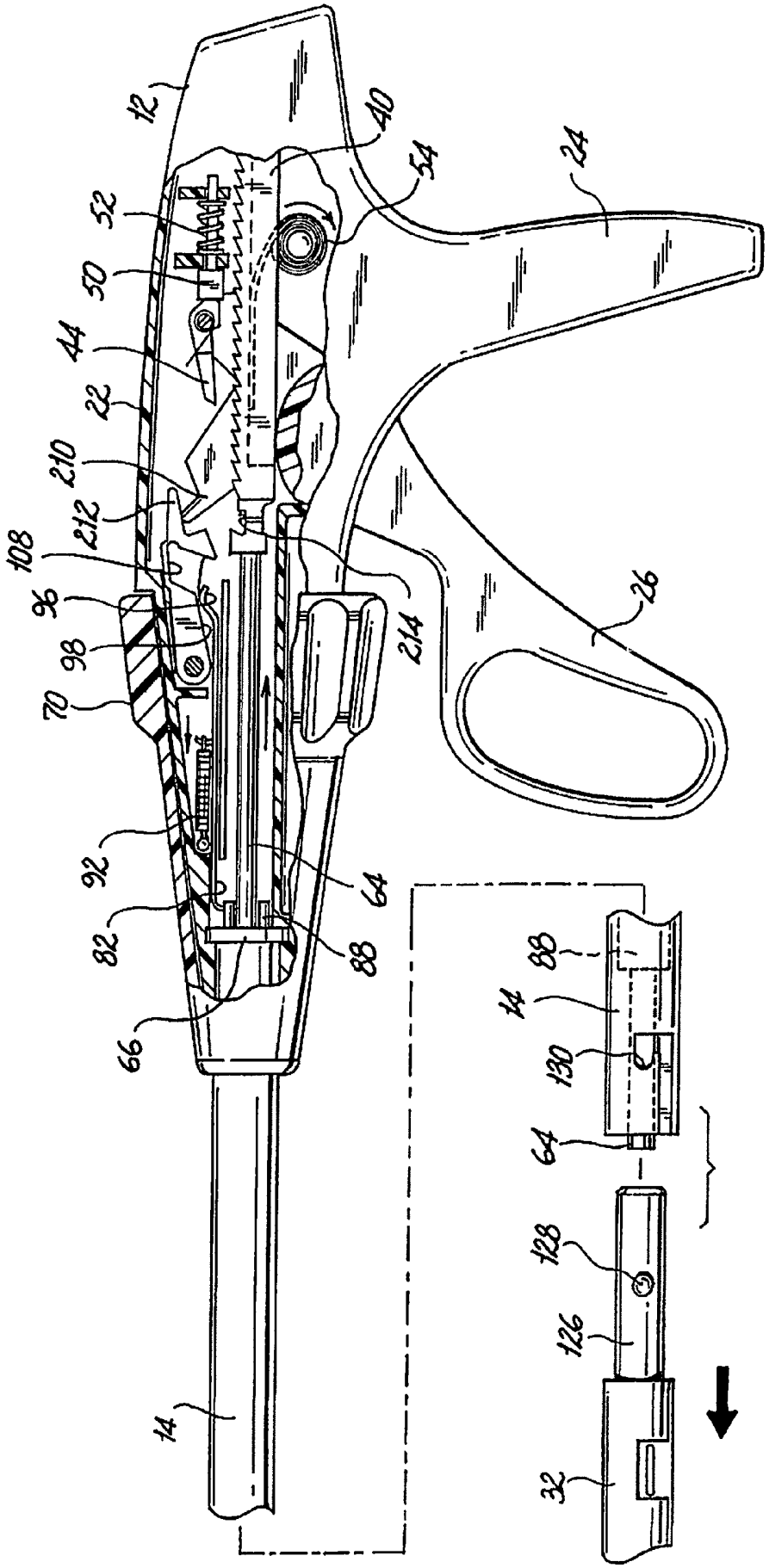
Fig. 10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88
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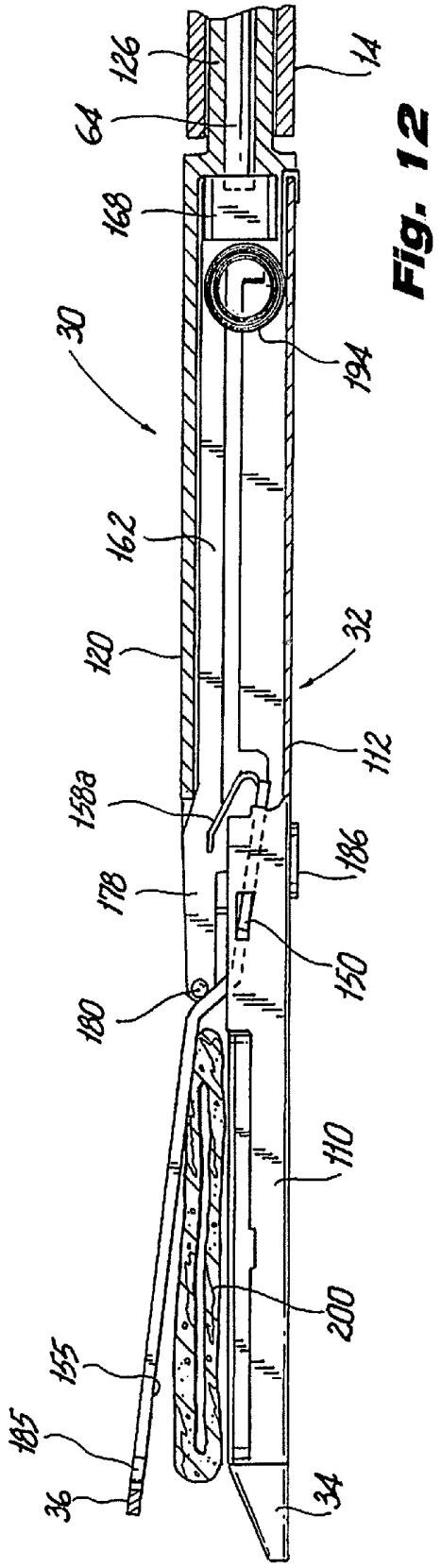
130
64
128
126
32

Fig. 11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64
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110
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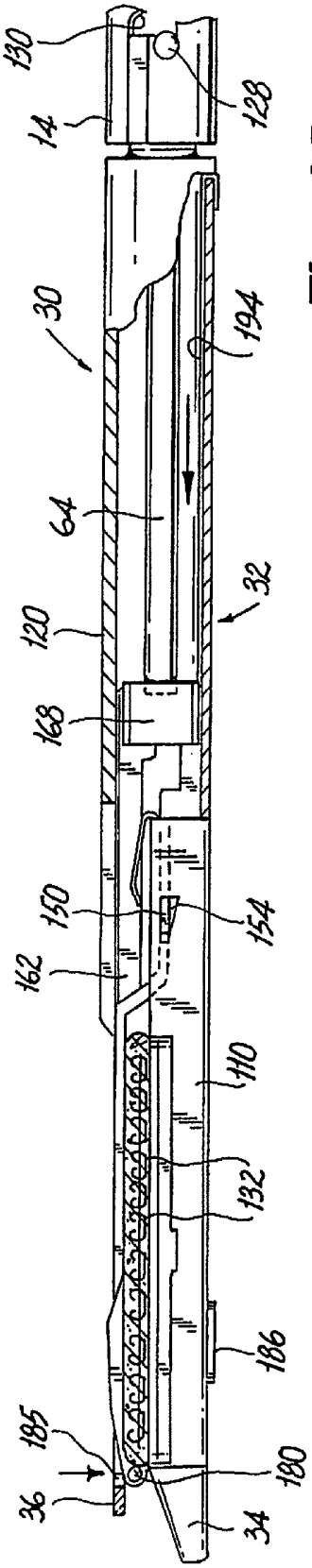
155
185
36
34

Fig. 12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34

Fig. 13

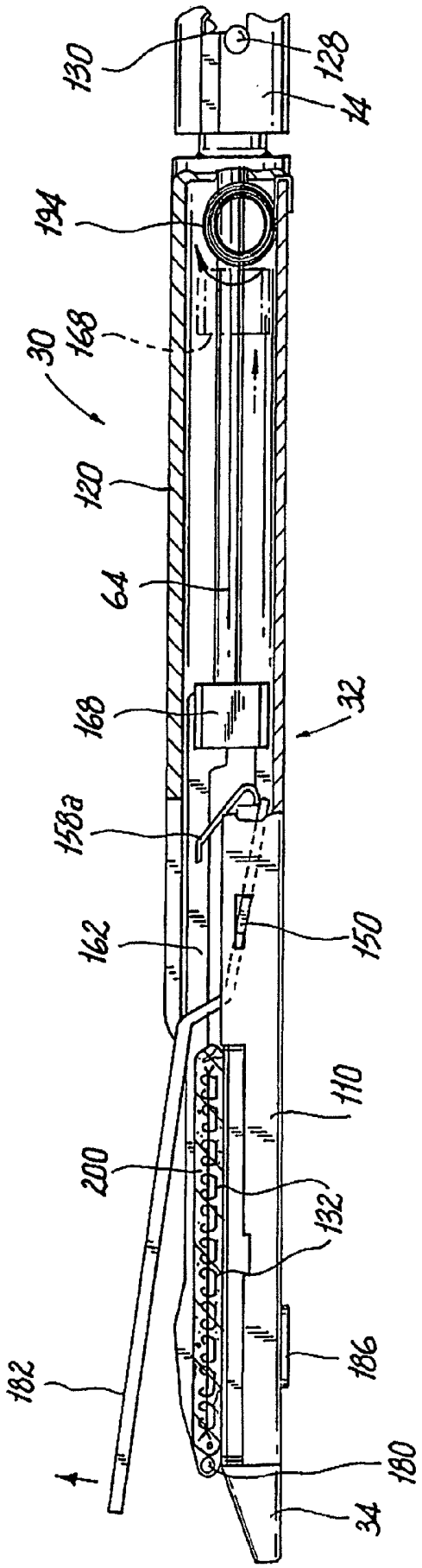
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Fig. 14

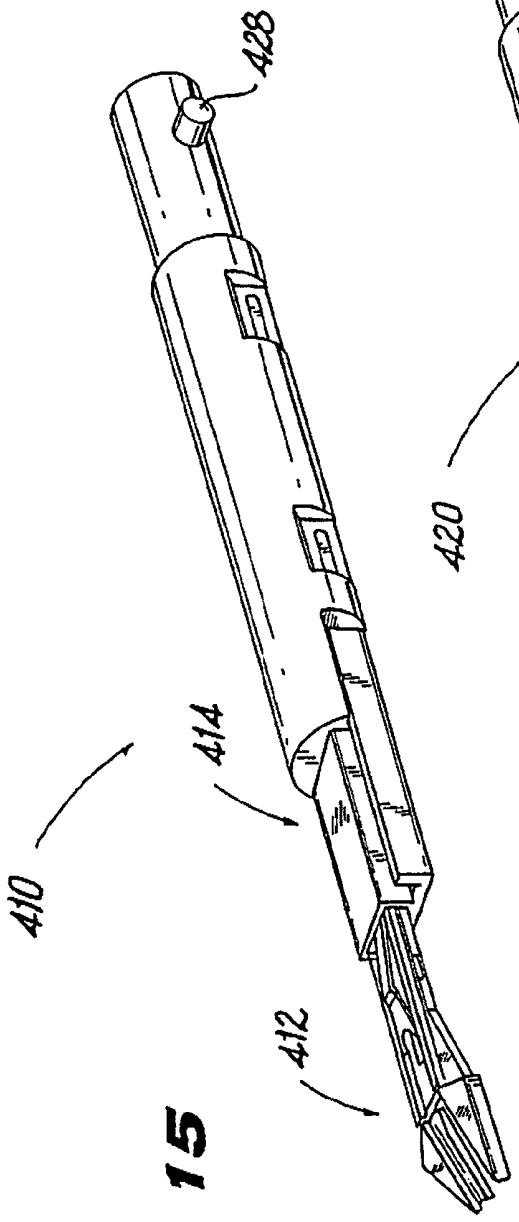


Fig. 15

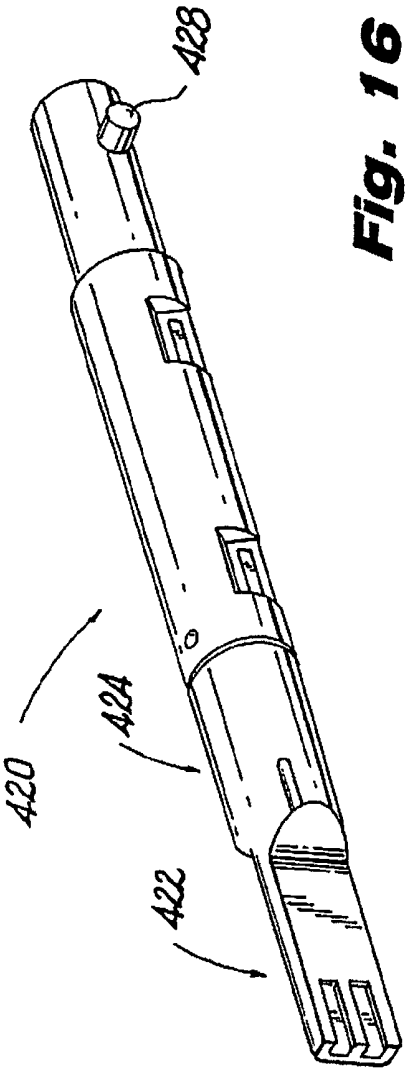
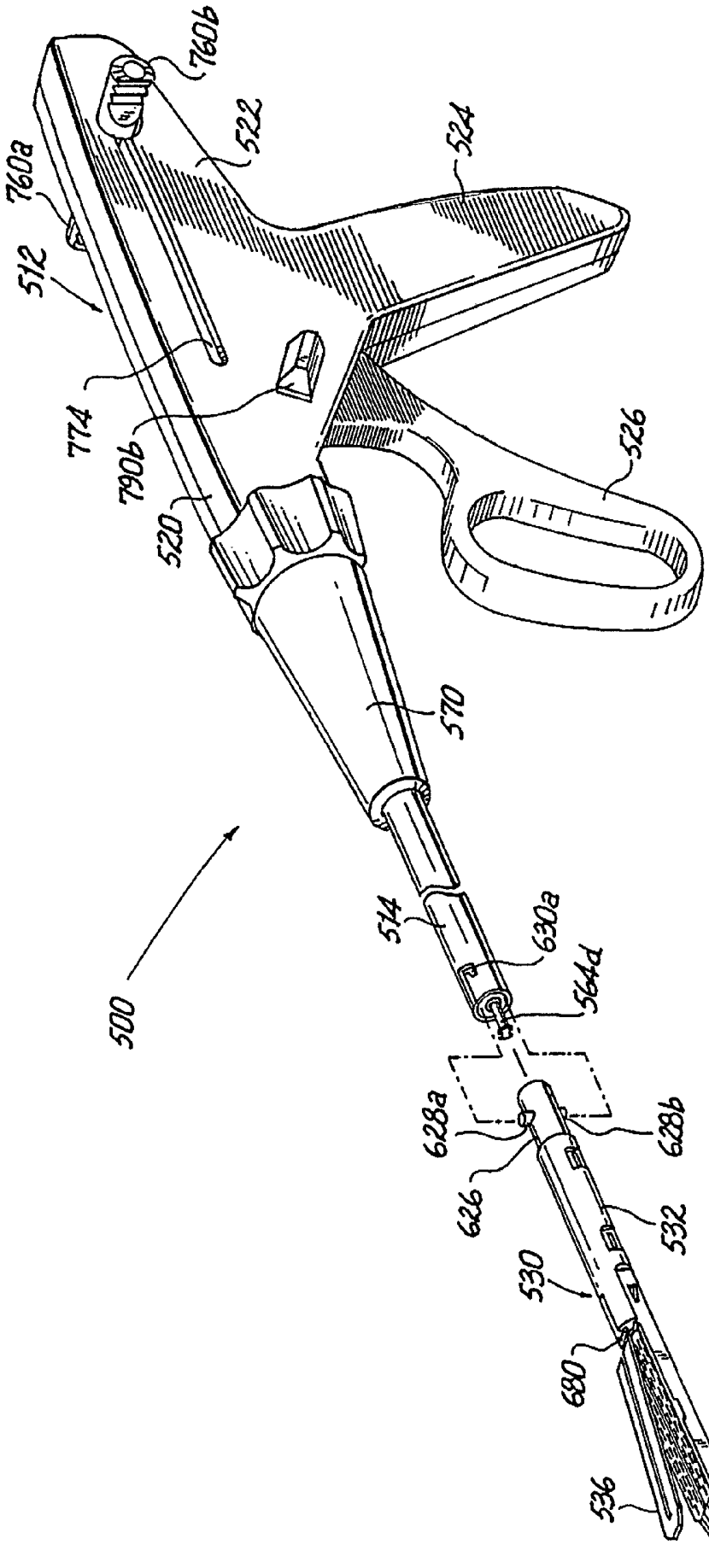


Fig. 16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760a
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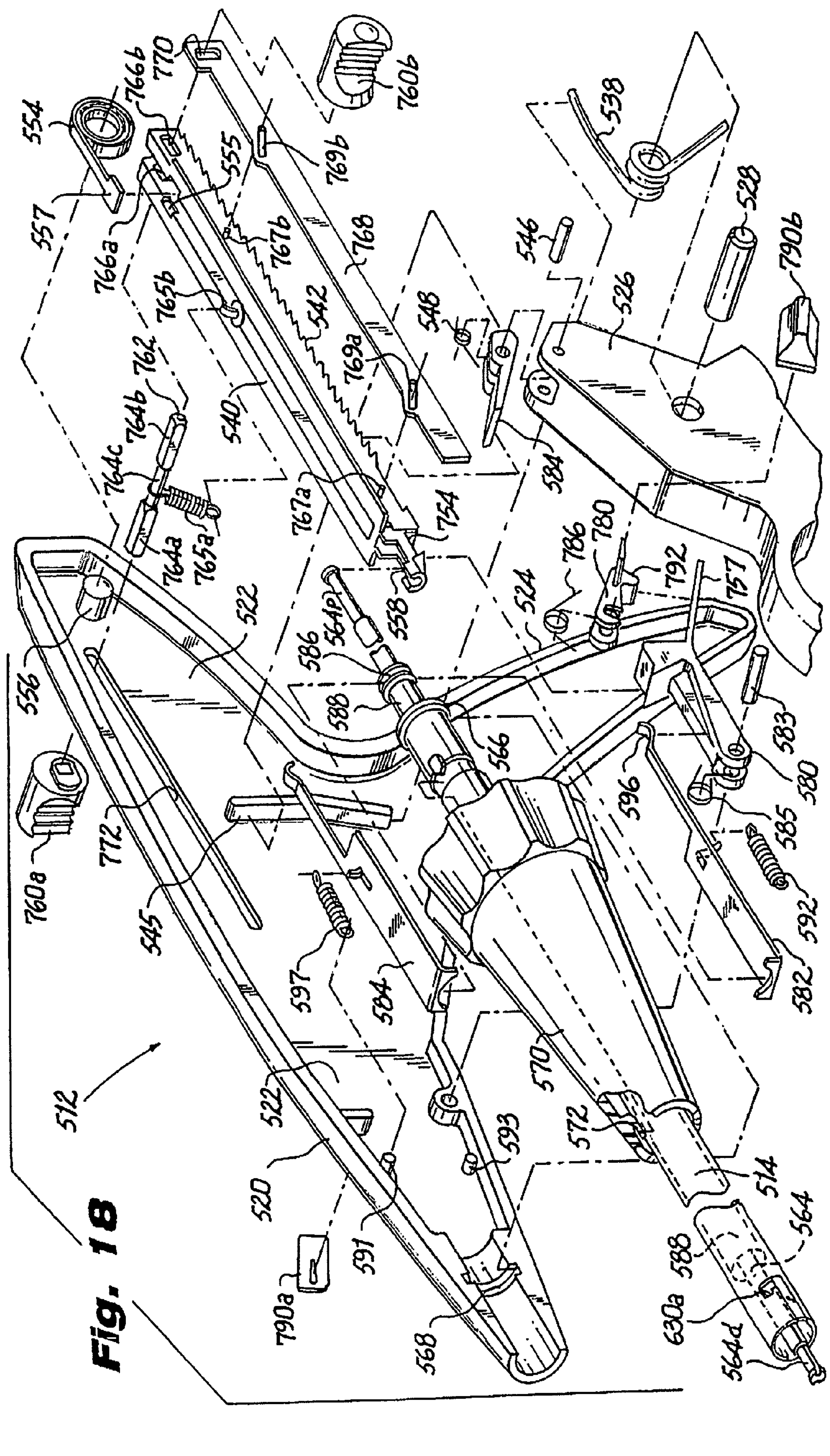
628a
628b
626
532
530
680
536
534

Fig. 17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572
580
582
583
584
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586
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593
596
597
630a
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757
760a
760b
762
764a
764b
764c
765a
765b
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790a
790b
792

Fig. 18

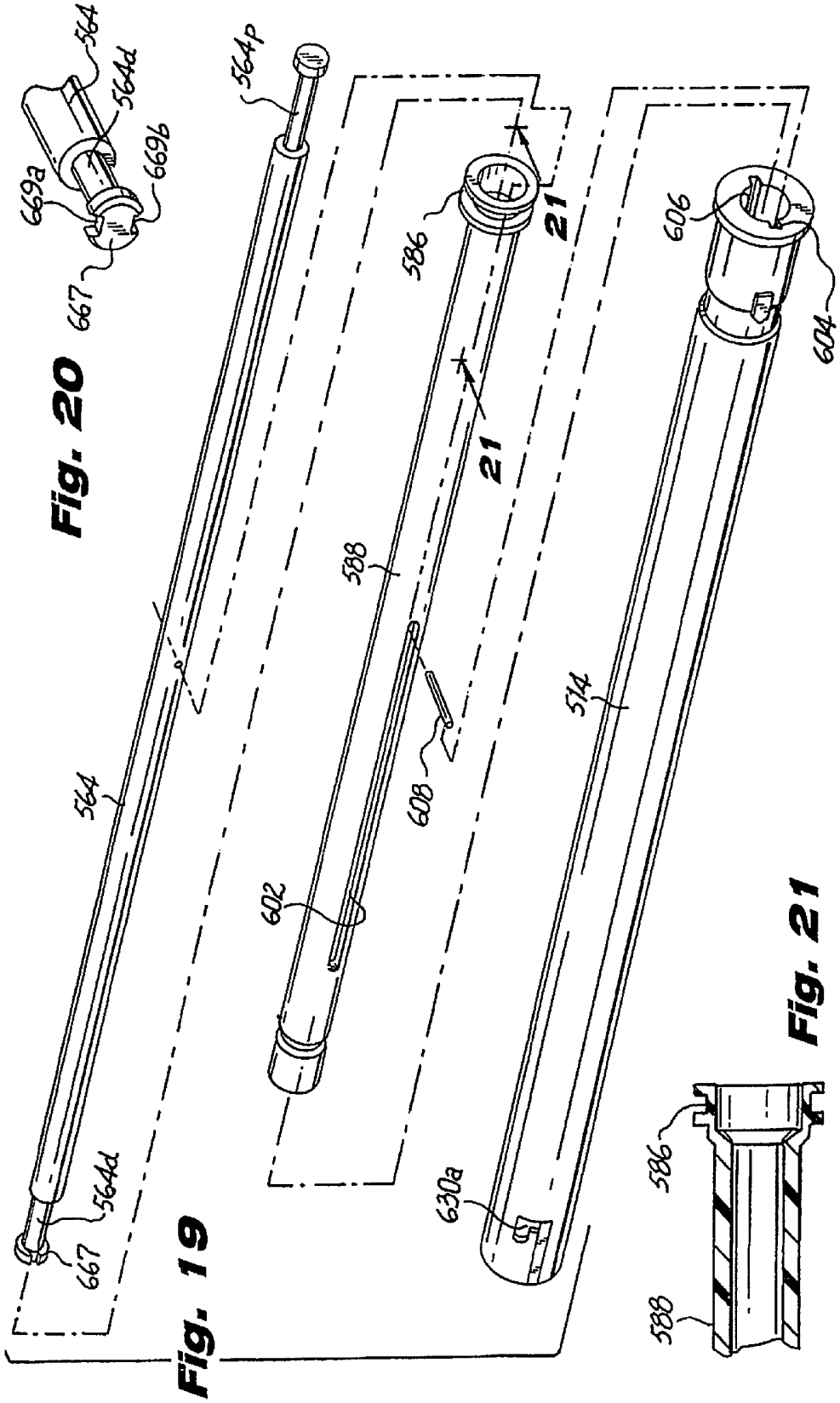
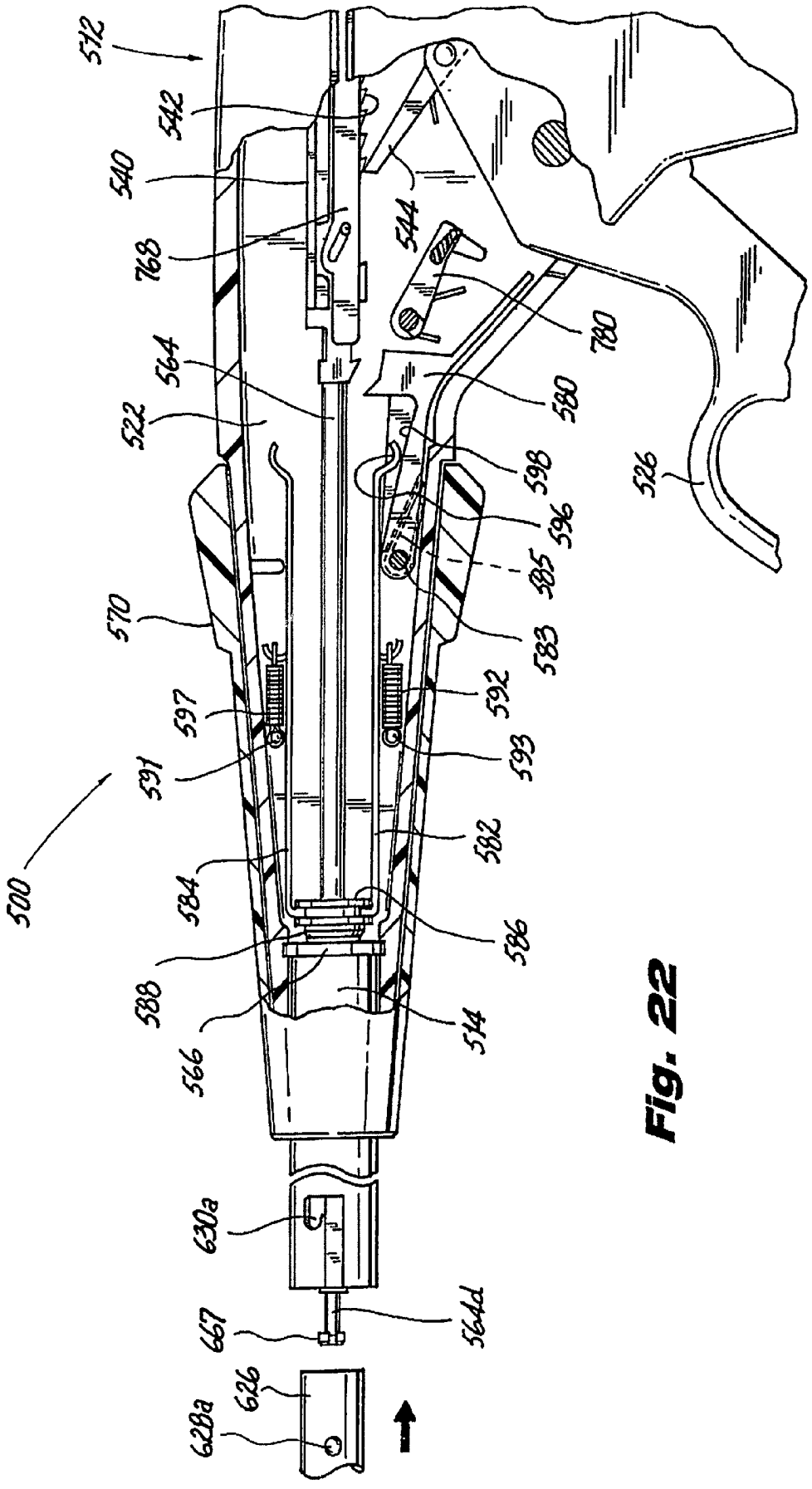


Fig. 20

Fig. 19

Fig. 21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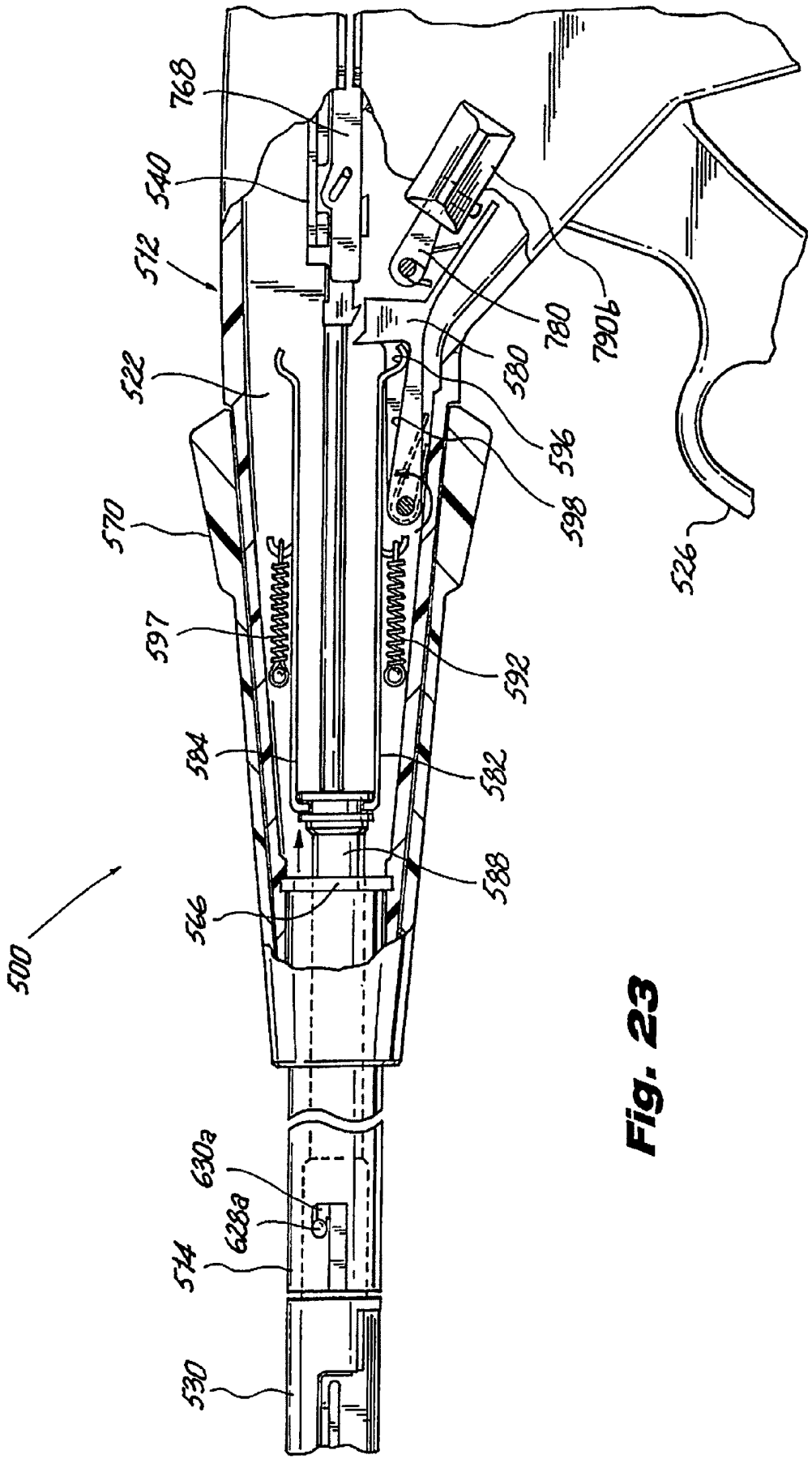
514
566
630a
564d
667
626
628a

Fig. 22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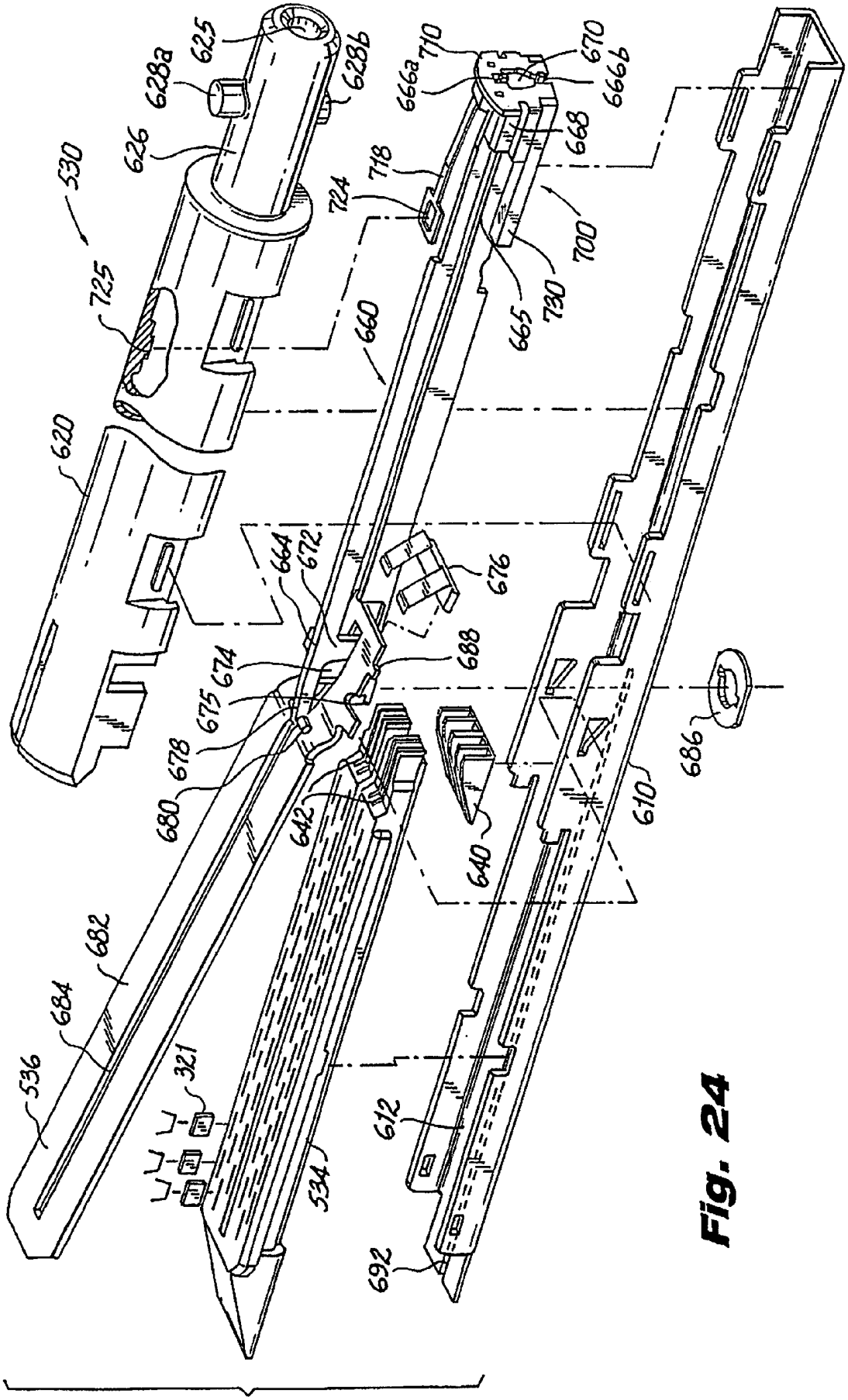
582
588

Fig. 23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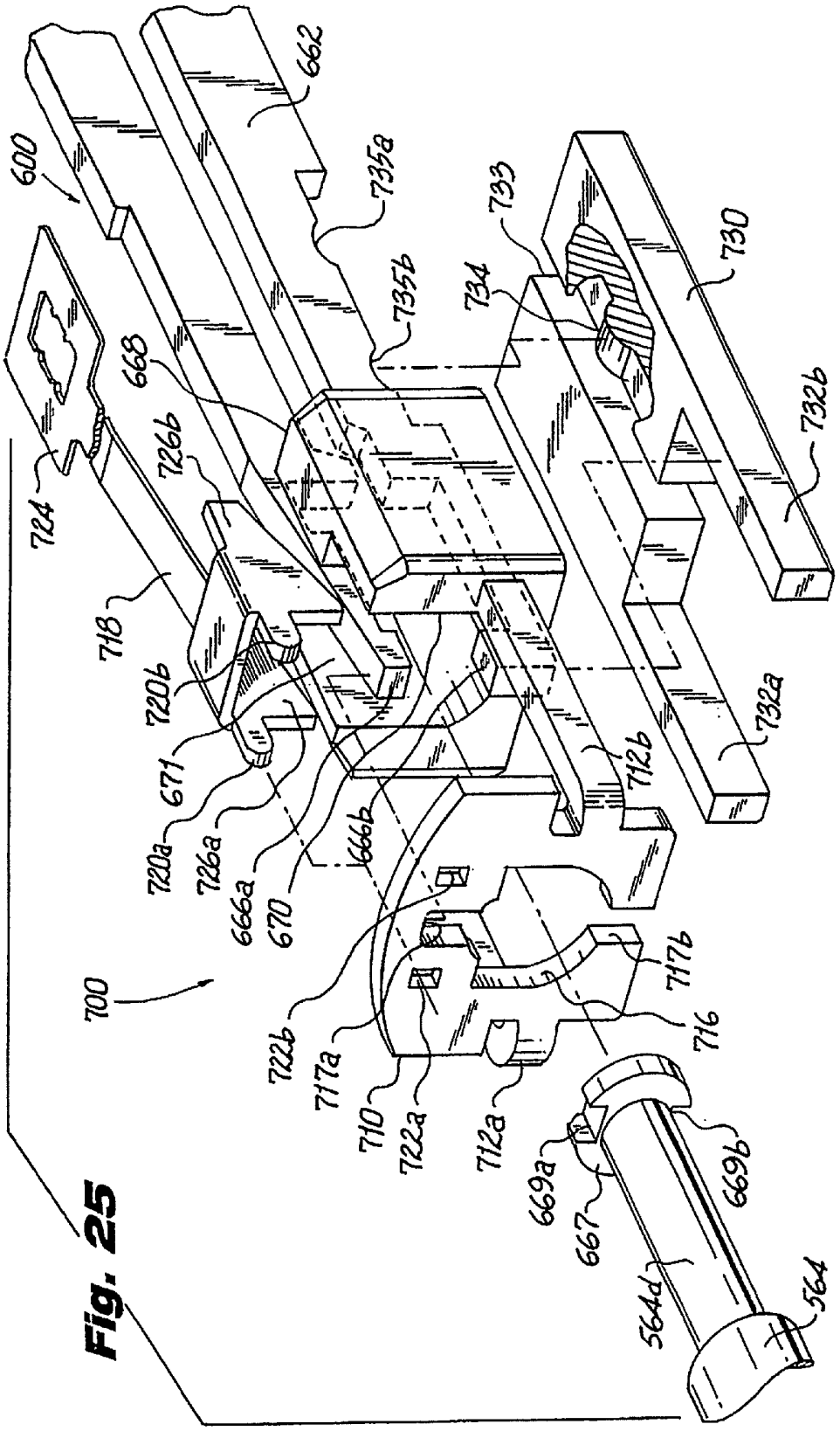
612
534
692

Fig. 24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720a
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666b
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712a
717b
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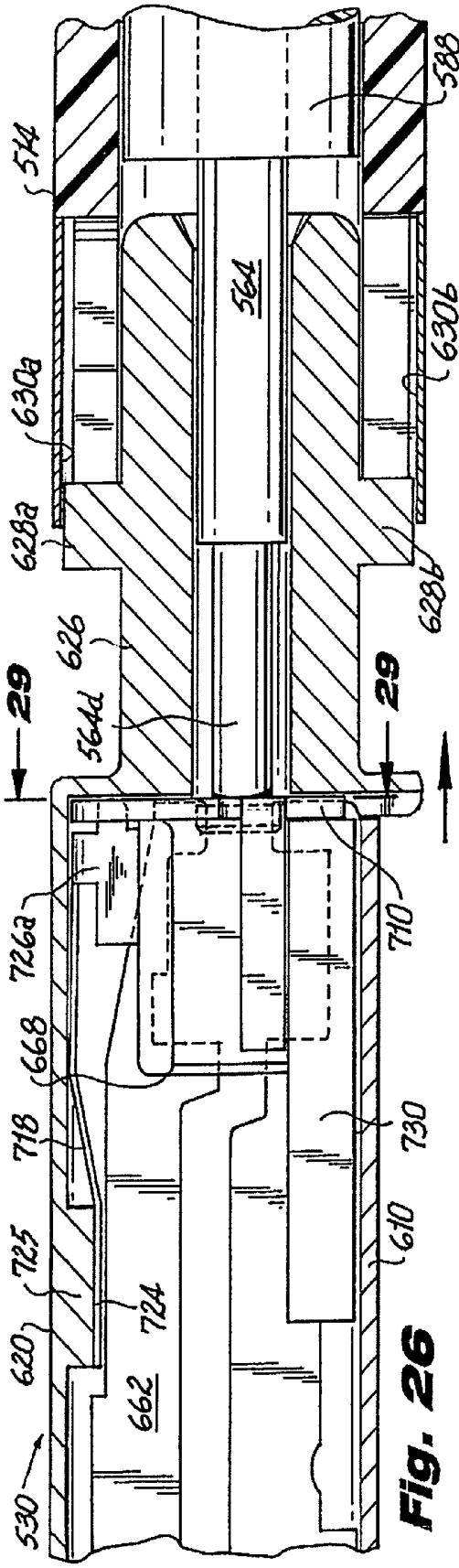
669a
667
669b
564d
564

Fig. 25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718
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725
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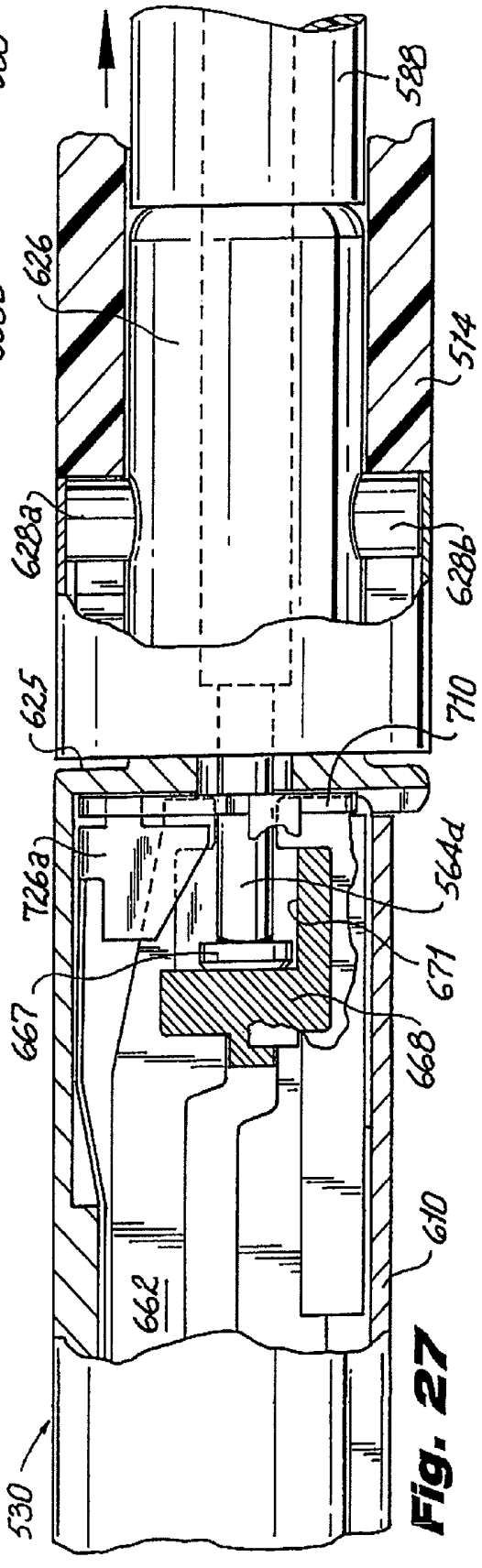
620
724
662
530

Fig. 26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564d
726a
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668
610
662
530

Fig. 27

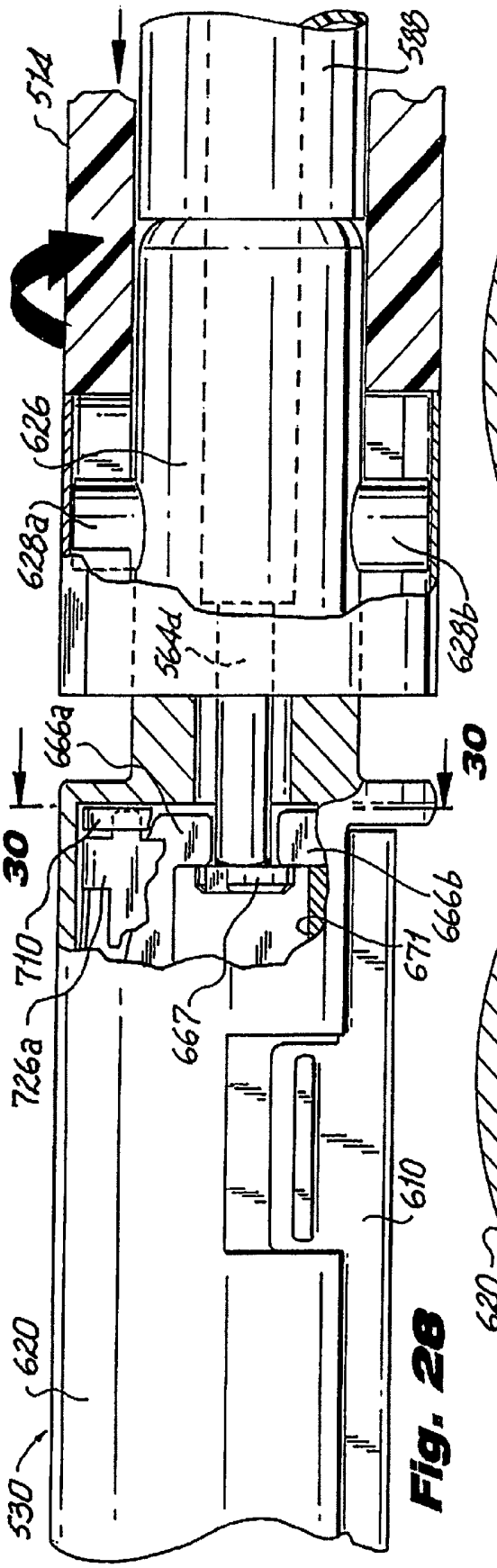


Fig. 28

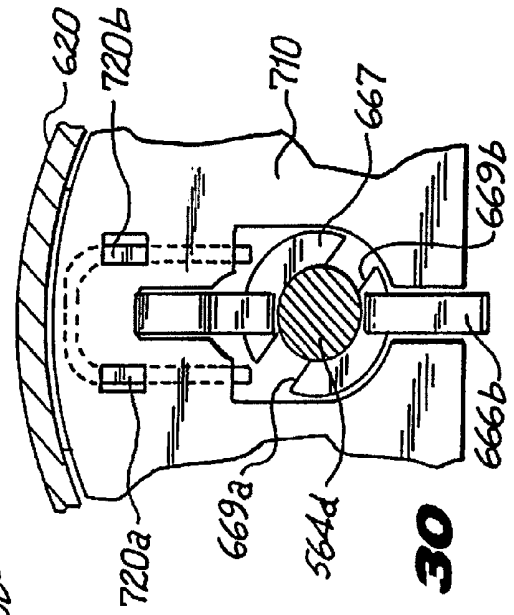


Fig. 30

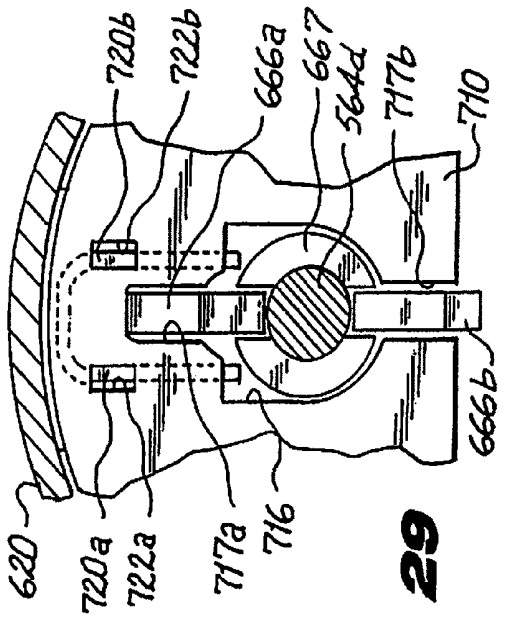
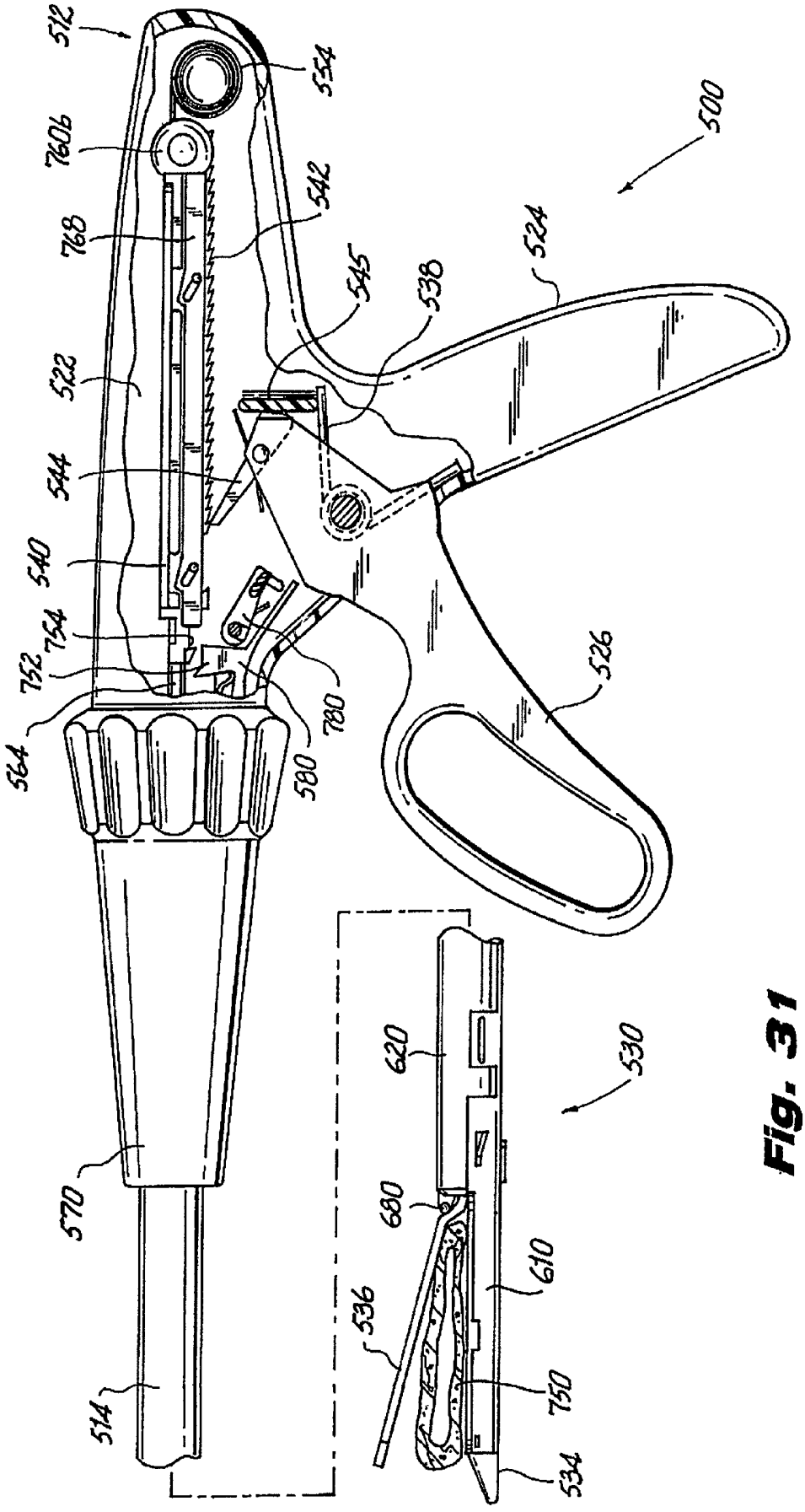


Fig. 29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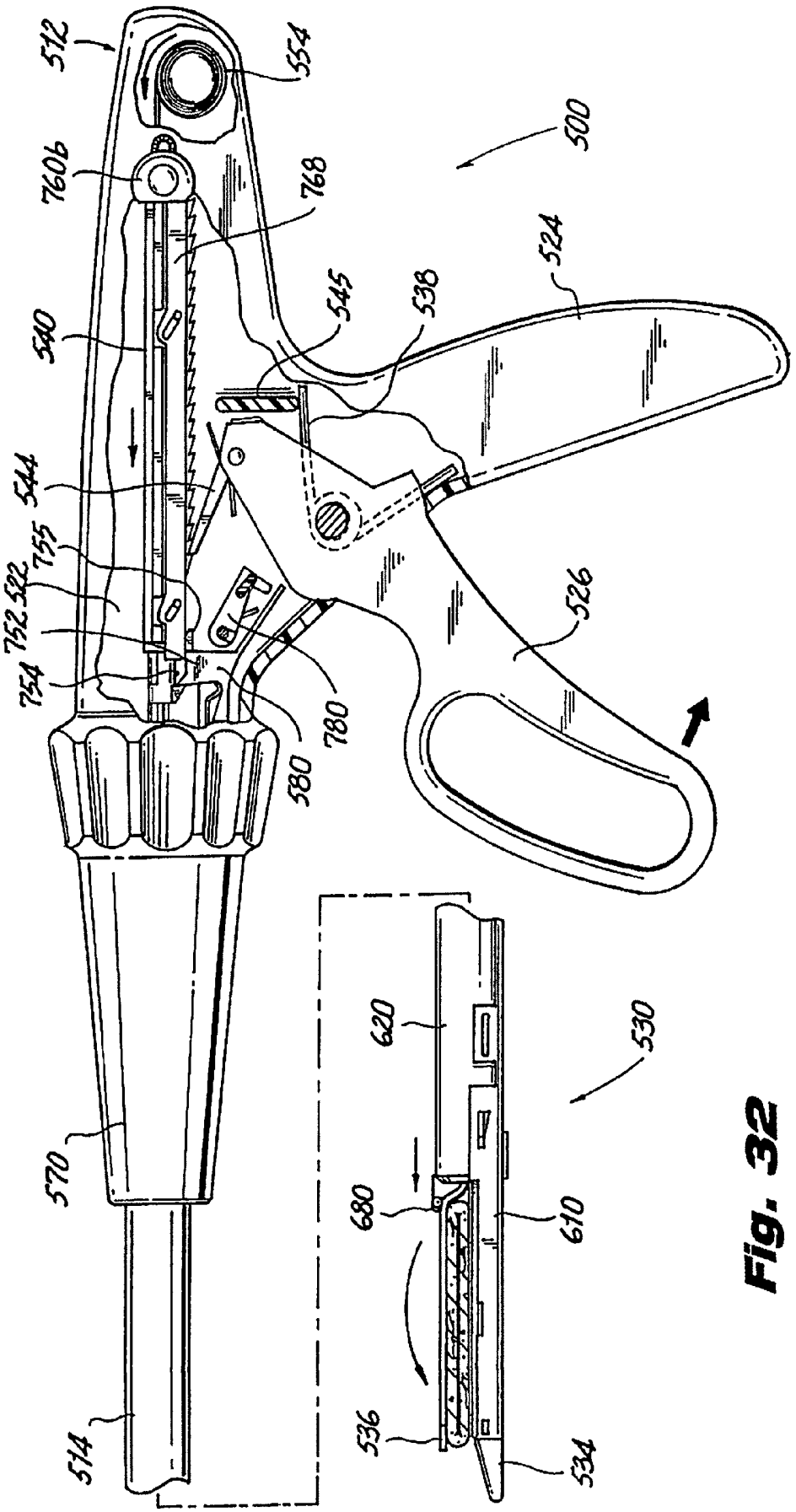
750
514
534

Fig. 31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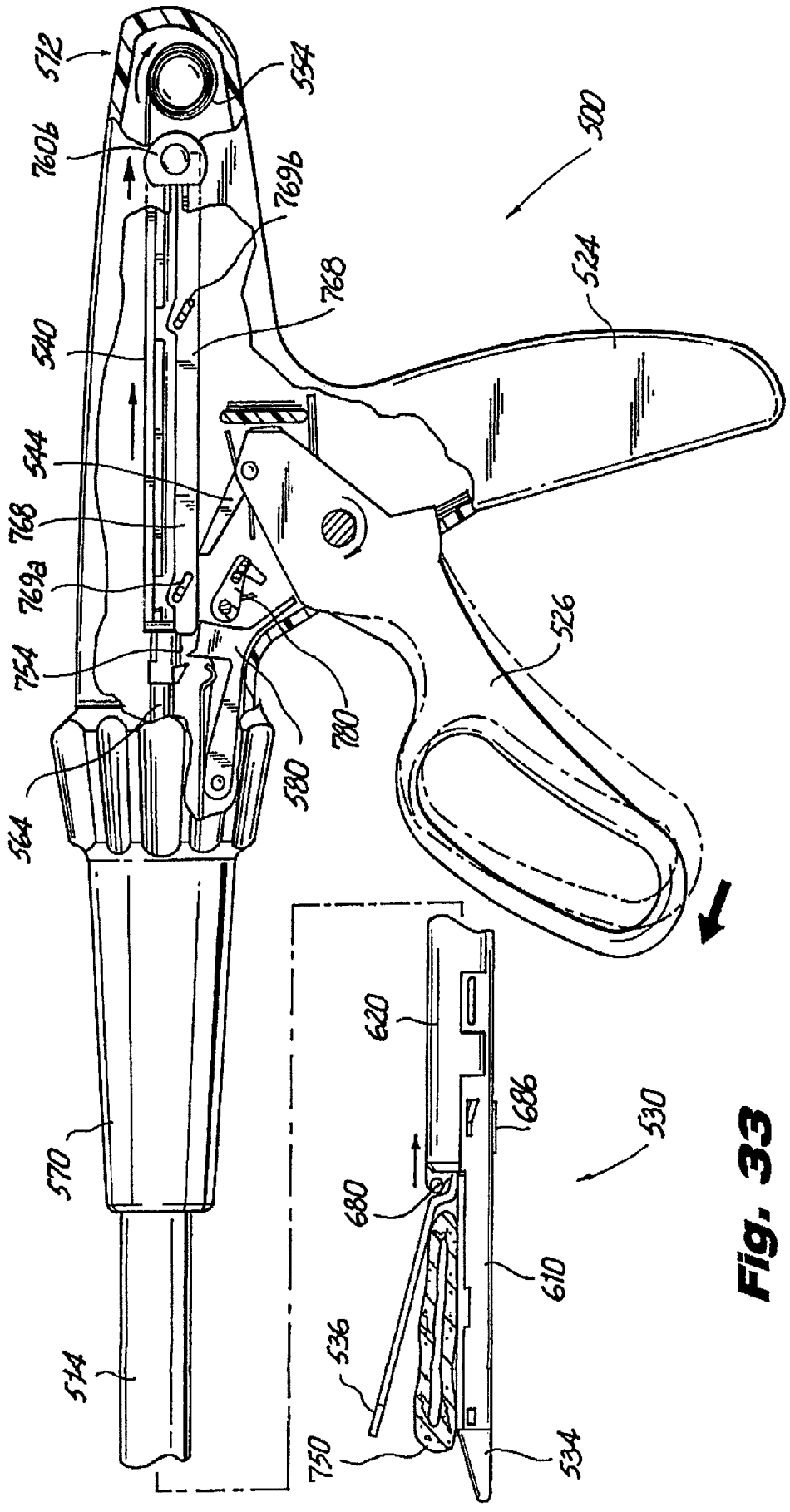
514

Fig. 32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680
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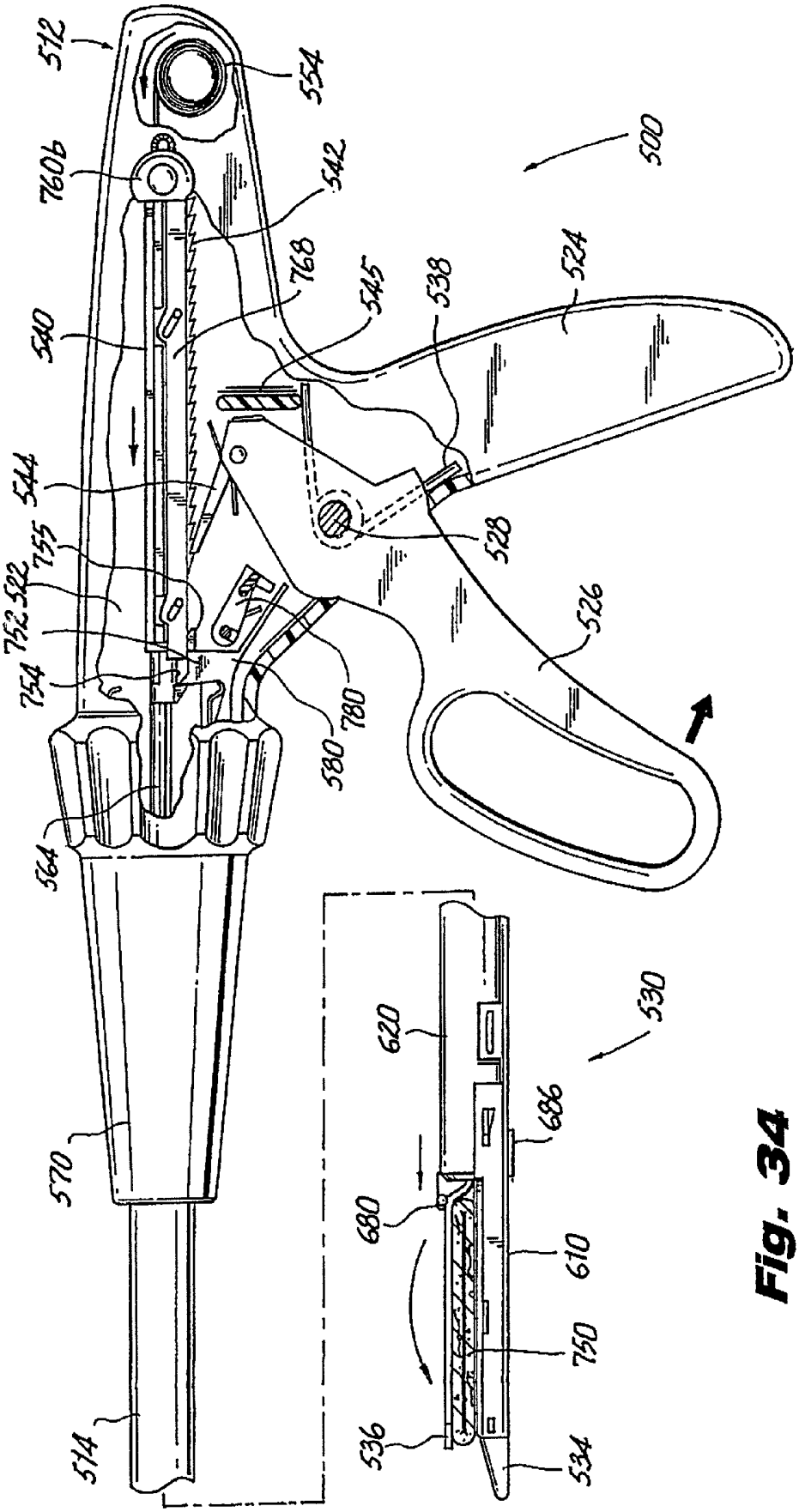
536
514
750
534

Fig. 33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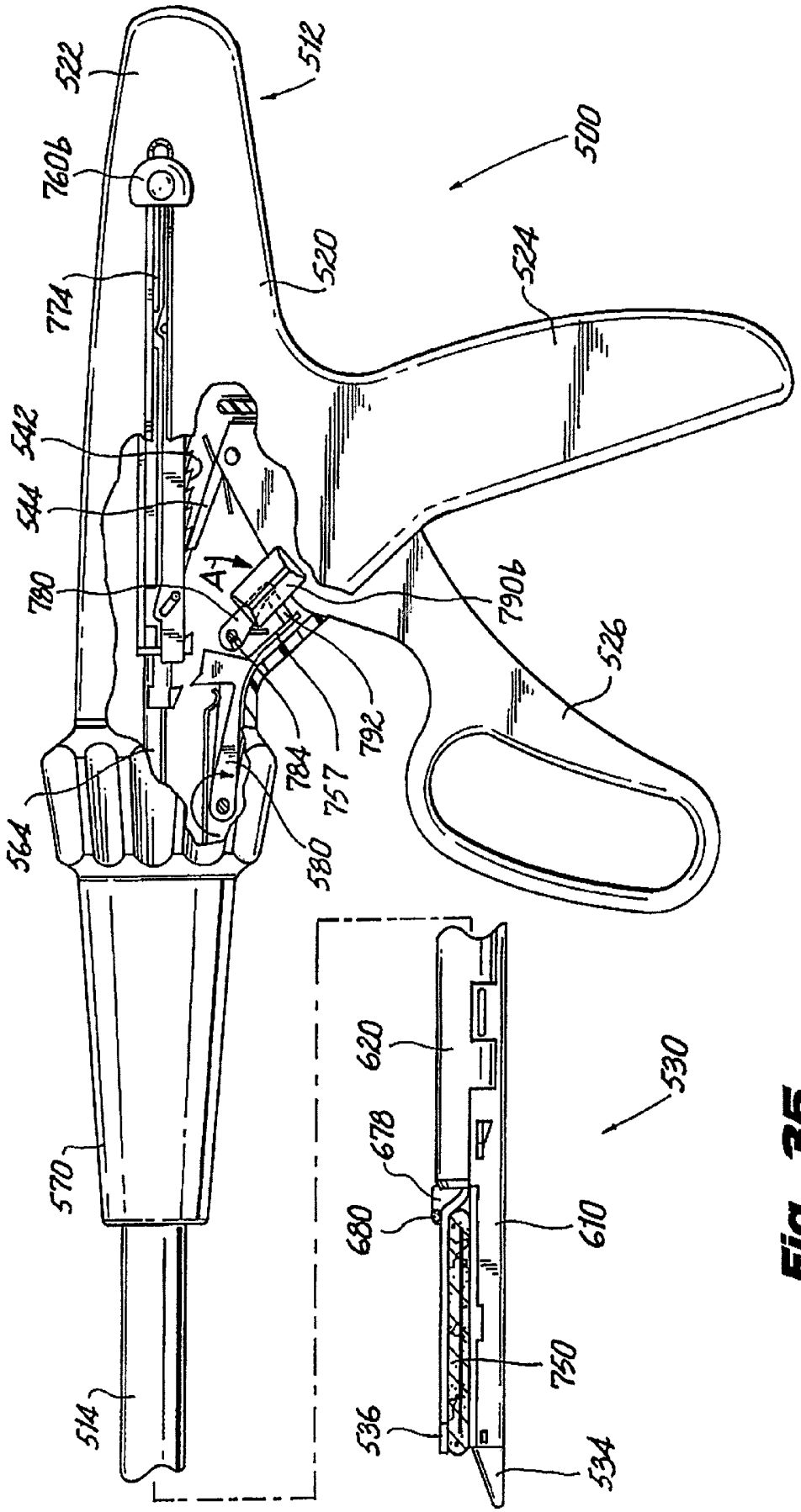
514

Fig. 34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680
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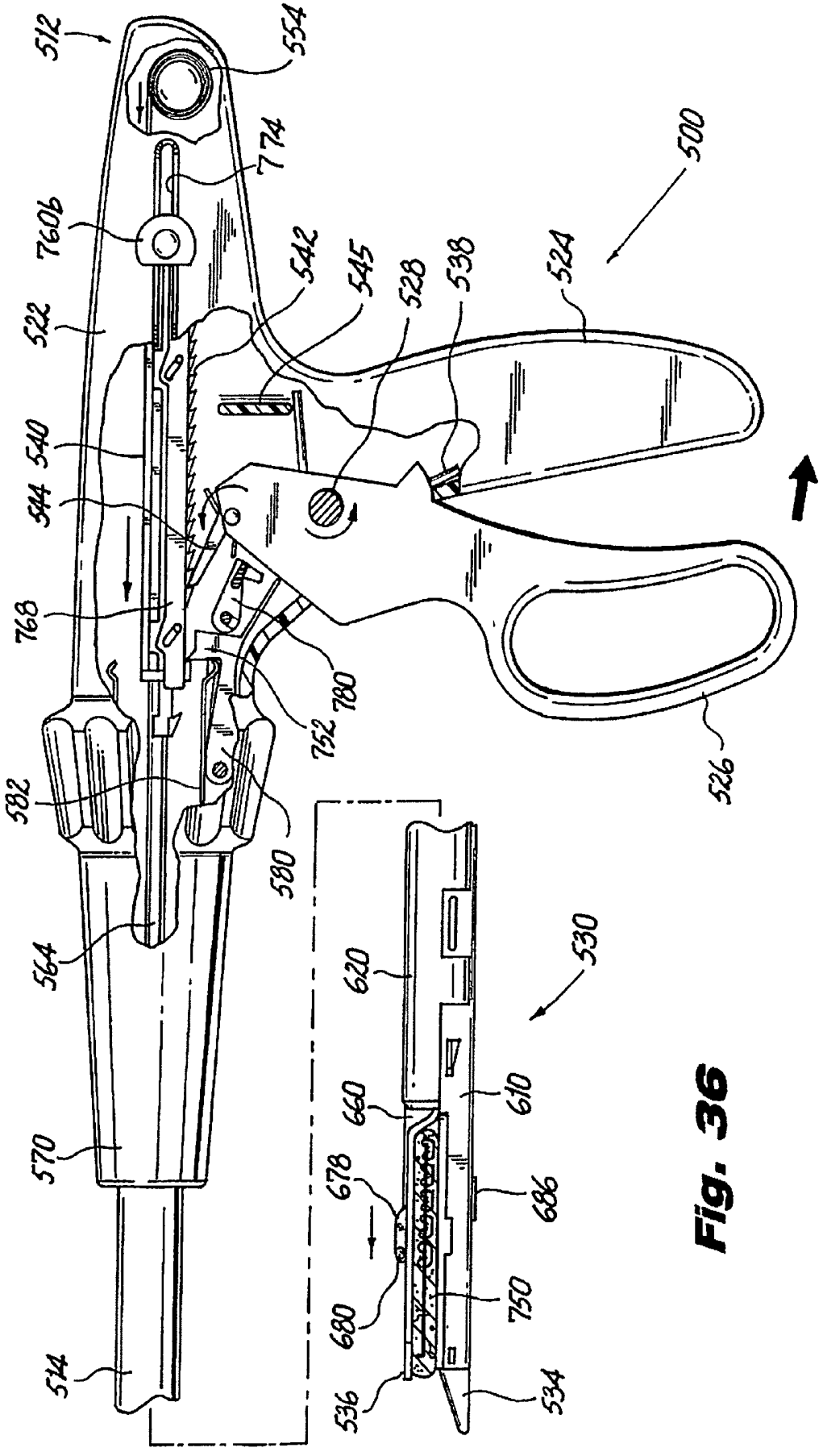
534
514

Fig. 35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530
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678
686
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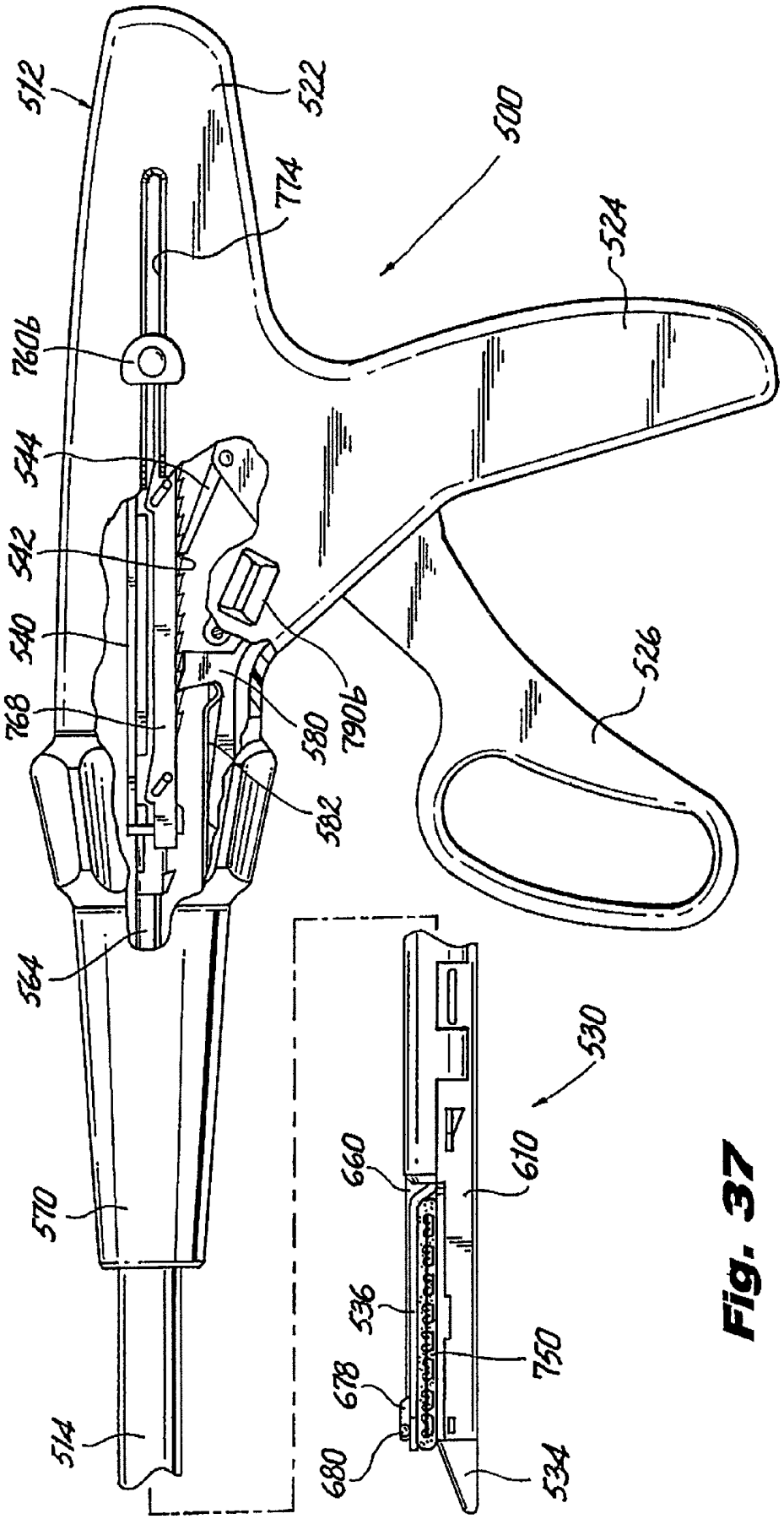
534

Fig. 36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760b
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790b
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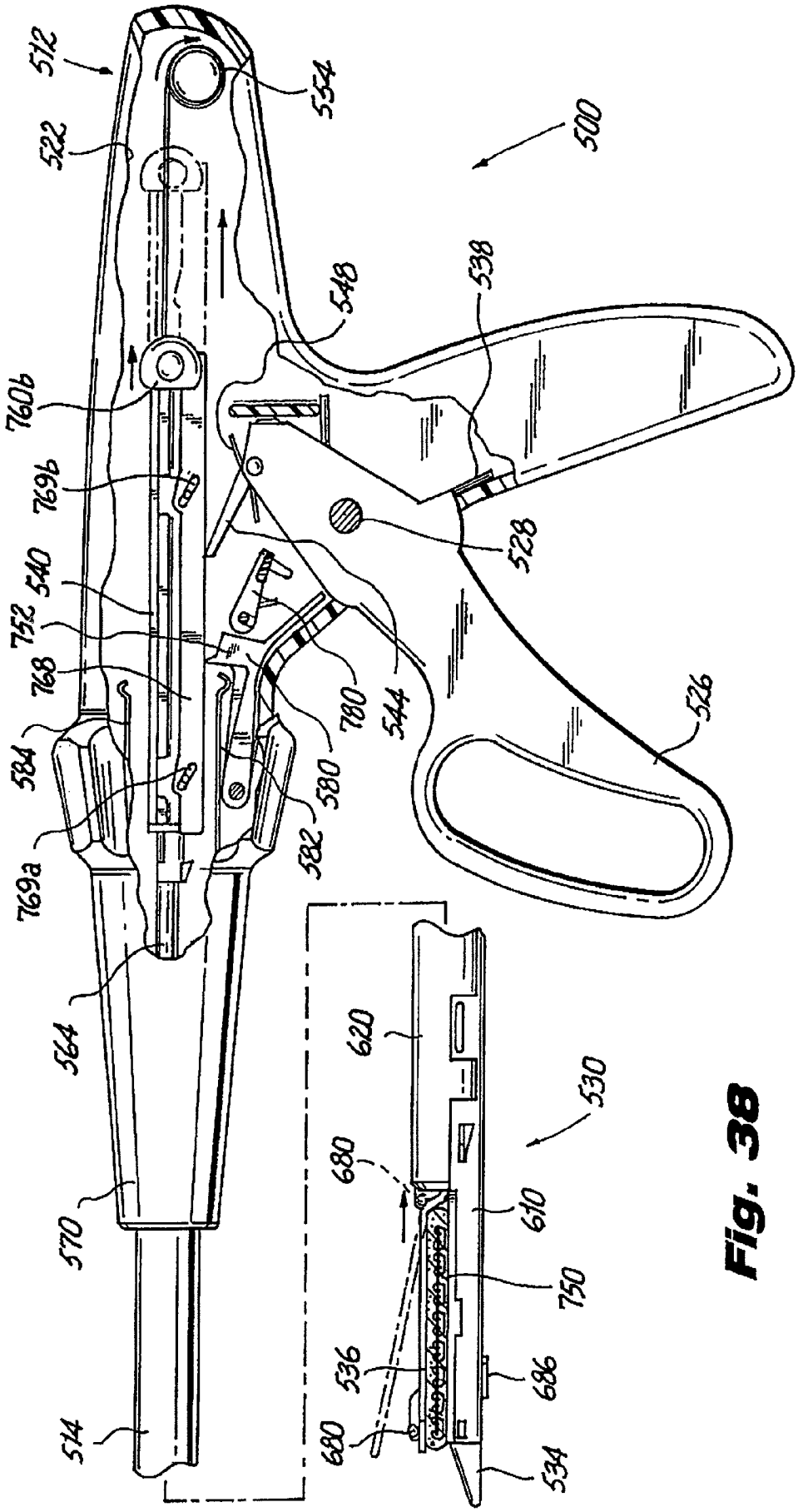
570
536
750
678
680
534
514

Fig. 37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752
768
780
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769a
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620
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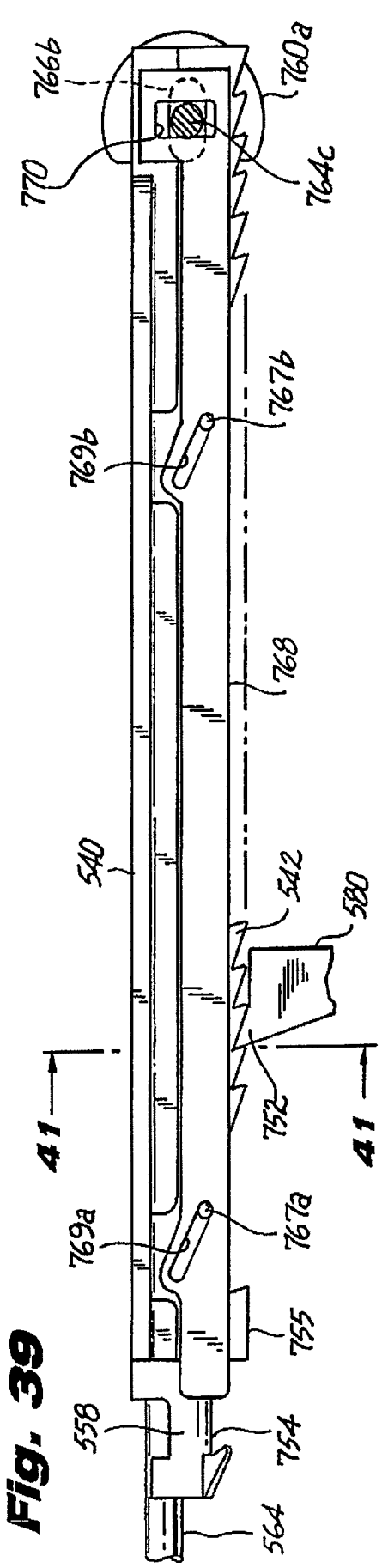
680
610
570
750
536
686
680
534
514

Fig. 38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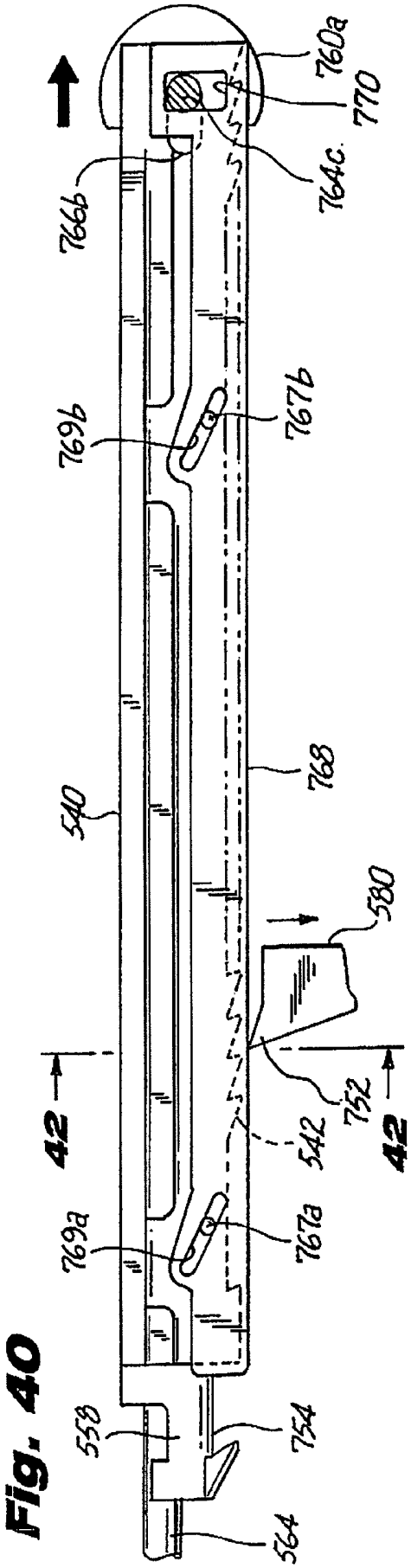
41
769a
767a
755
558
754
564

Fig. 39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768
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42
769a
767a
558
754
564

Fig. 40

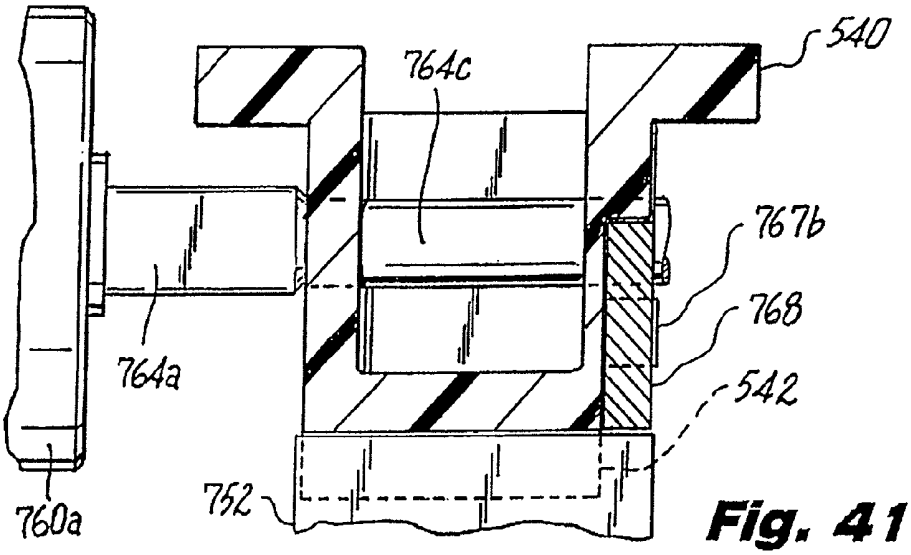


Fig. 41

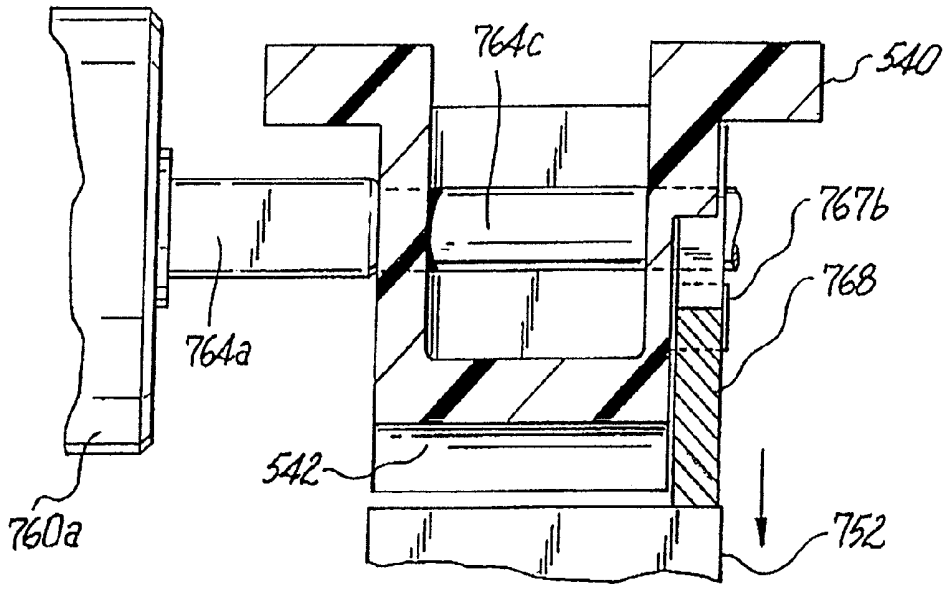


Fig. 42

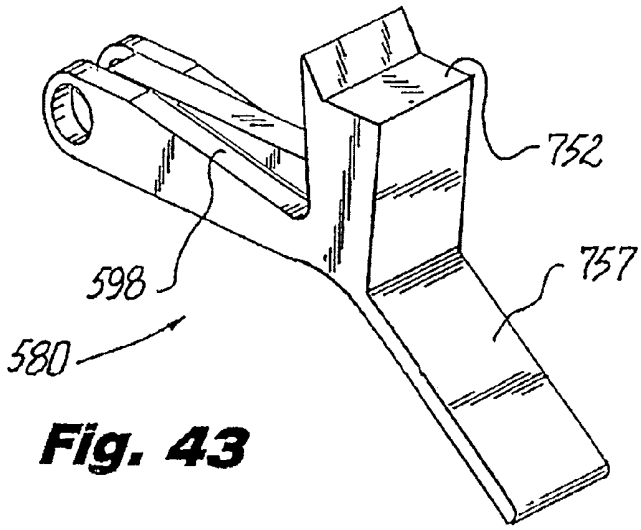
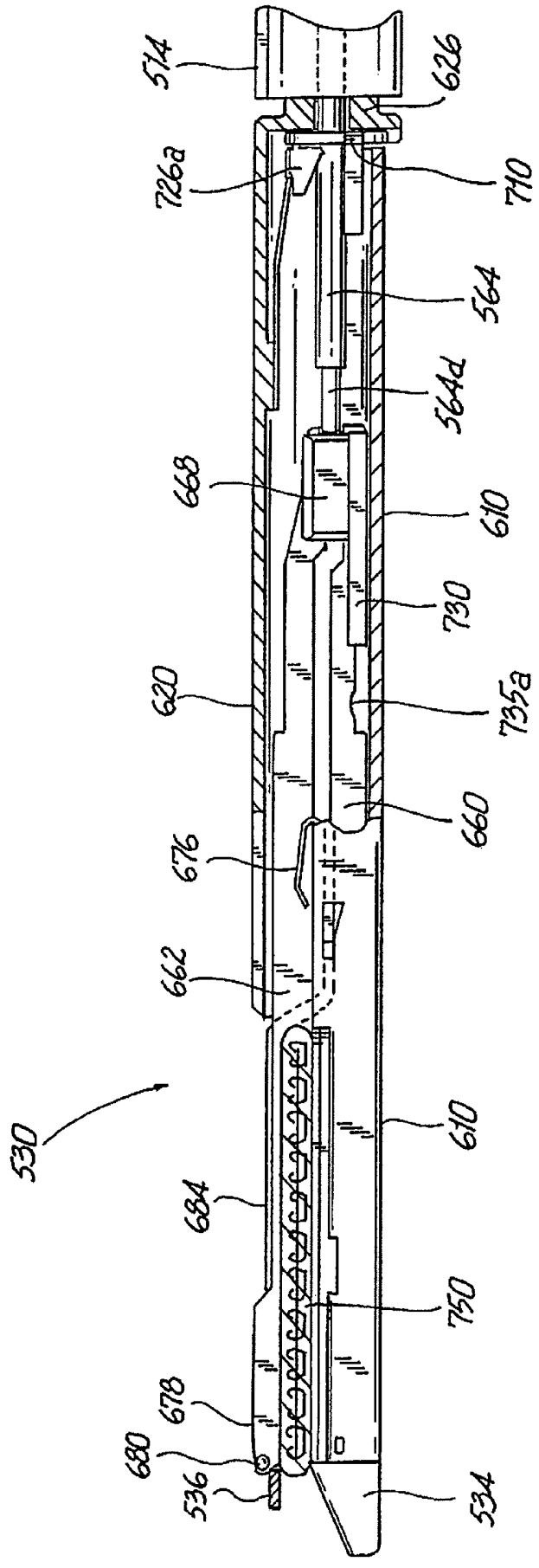


Fig. 43


514
626
726a
710
564
564d
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620
735a
660
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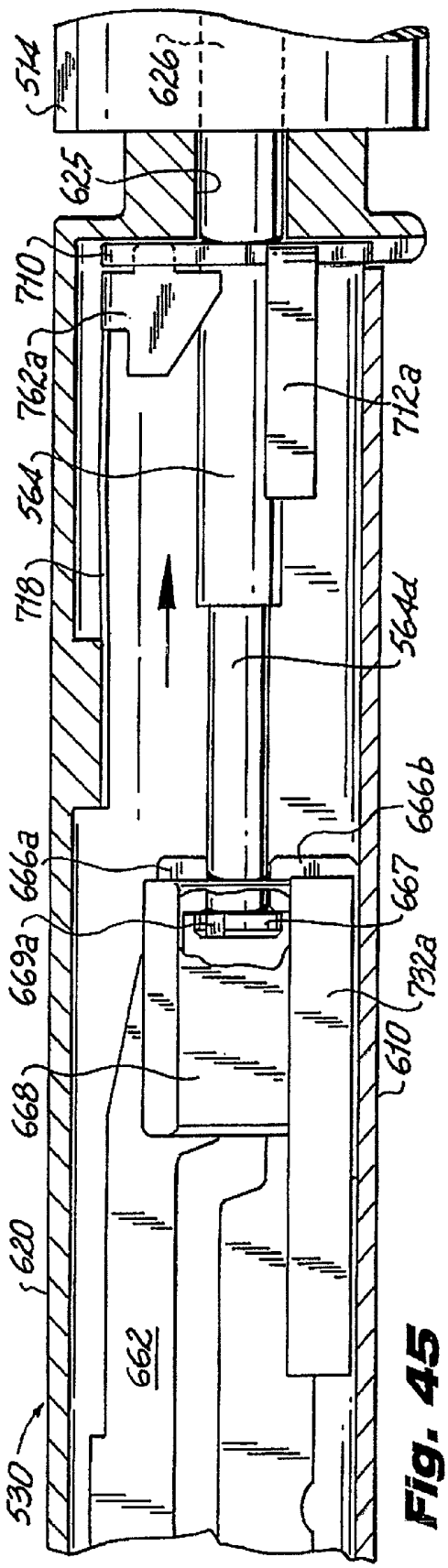
662
530
610
684
750
678
680
536
534

Fig. 44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626
625
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564d
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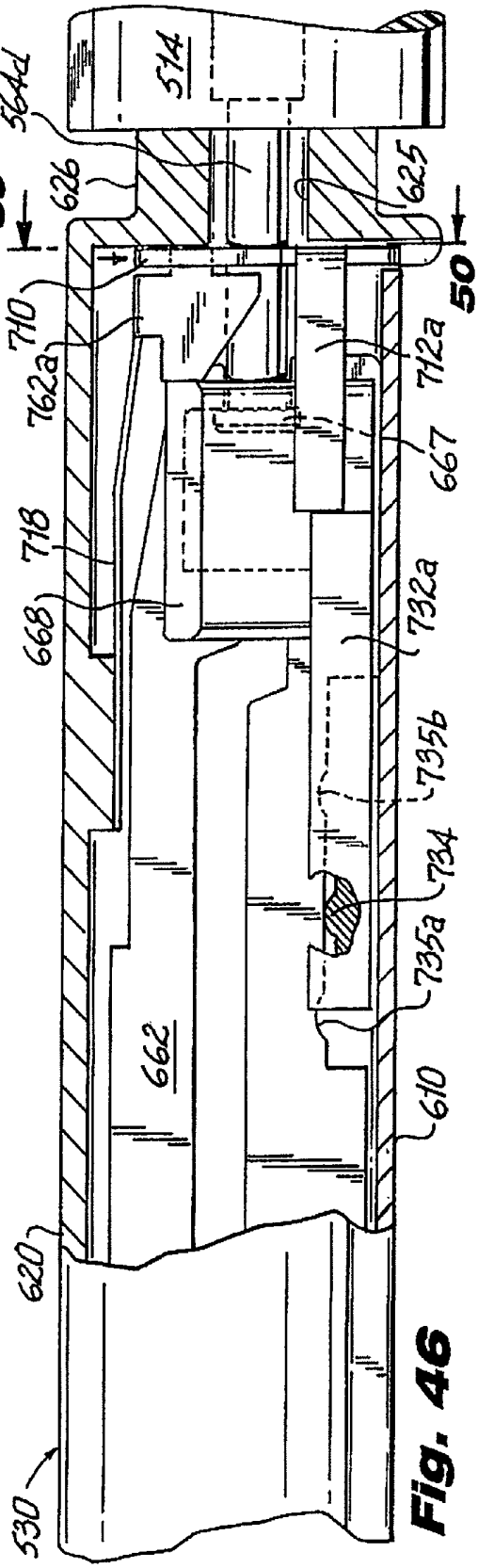
669a
732a
668
610
620
662
530

Fig. 45


564d
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50
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718
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732a
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734
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610
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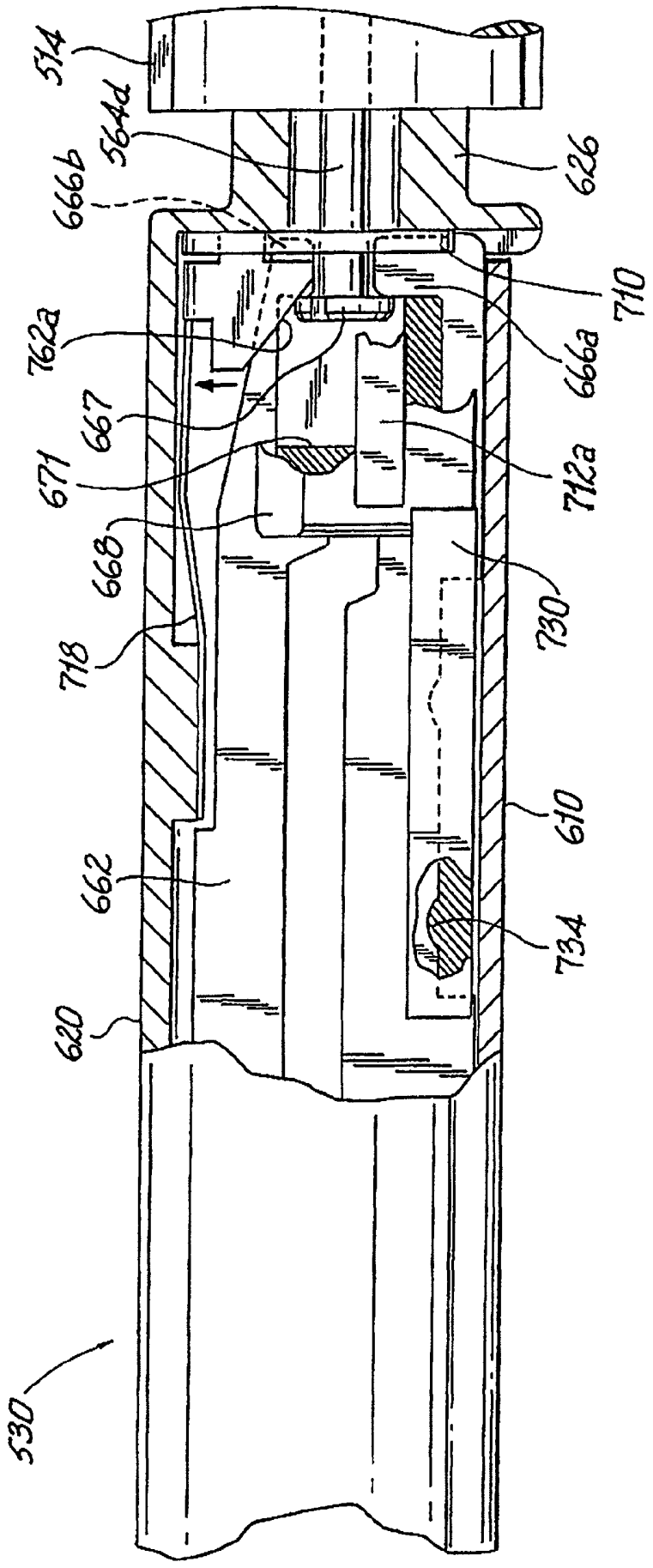
530

Fig. 46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564d
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710
762a
666a
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712a
671
668
730
718
610
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530

Fig. 47

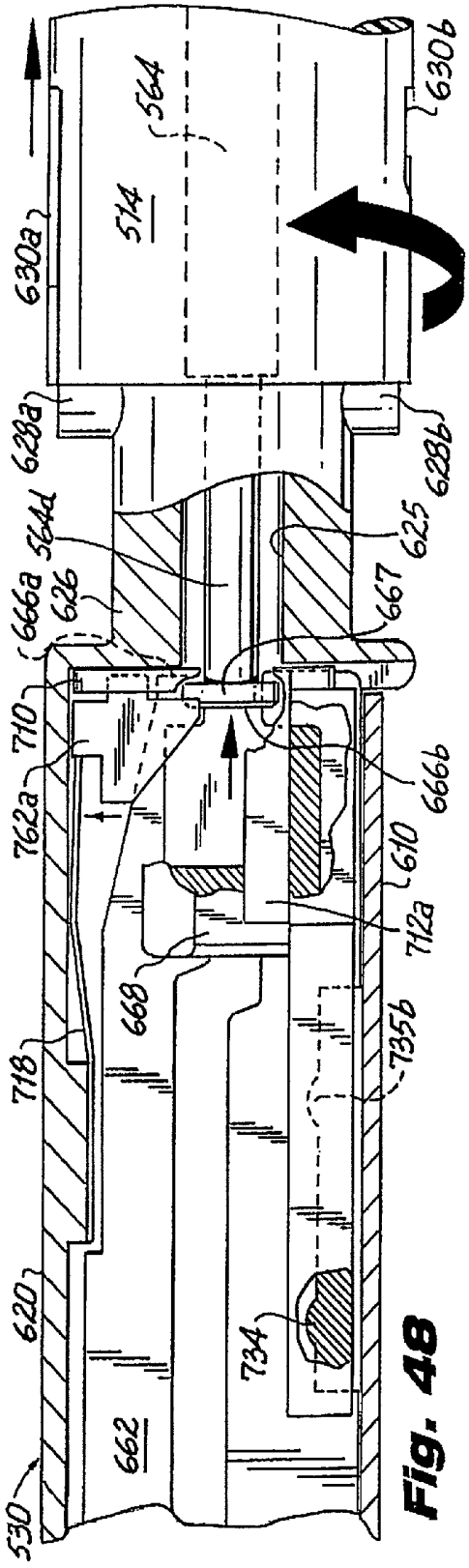
530
662
620
718
762a
710
666a
626
564d
564
514
630a
628a
628b
625
667
666b
610
712a
668
735b
734

Fig. 48

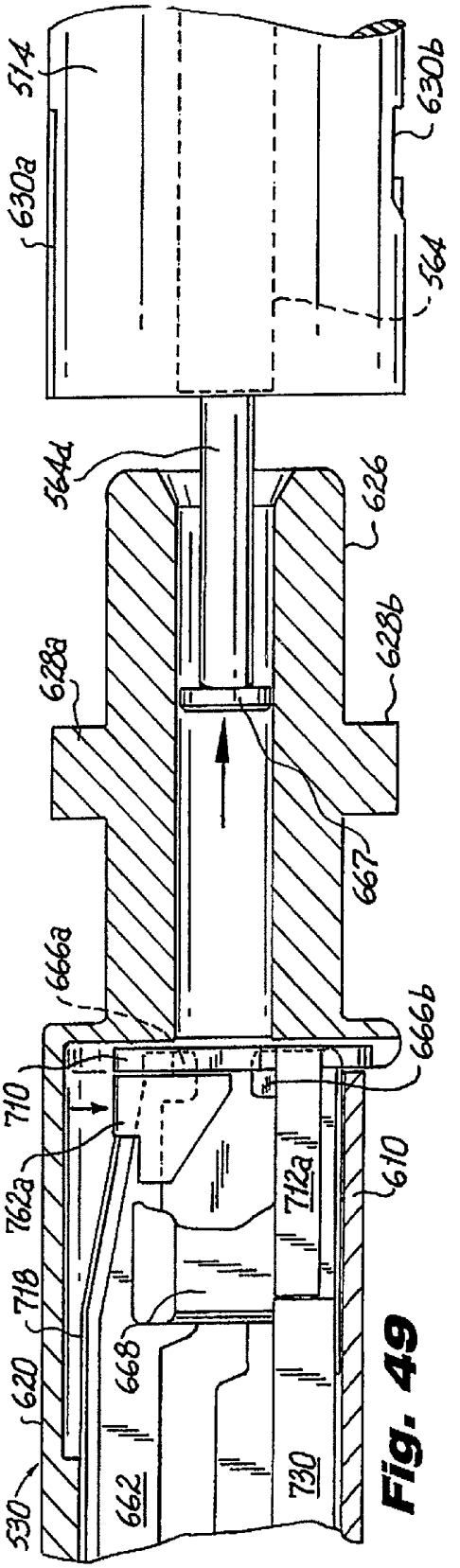
530
662
620
718
762a
710
666a
626
564d
564
514
630a
628a
628b
667
666b
610
712a
668
730

Fig. 49

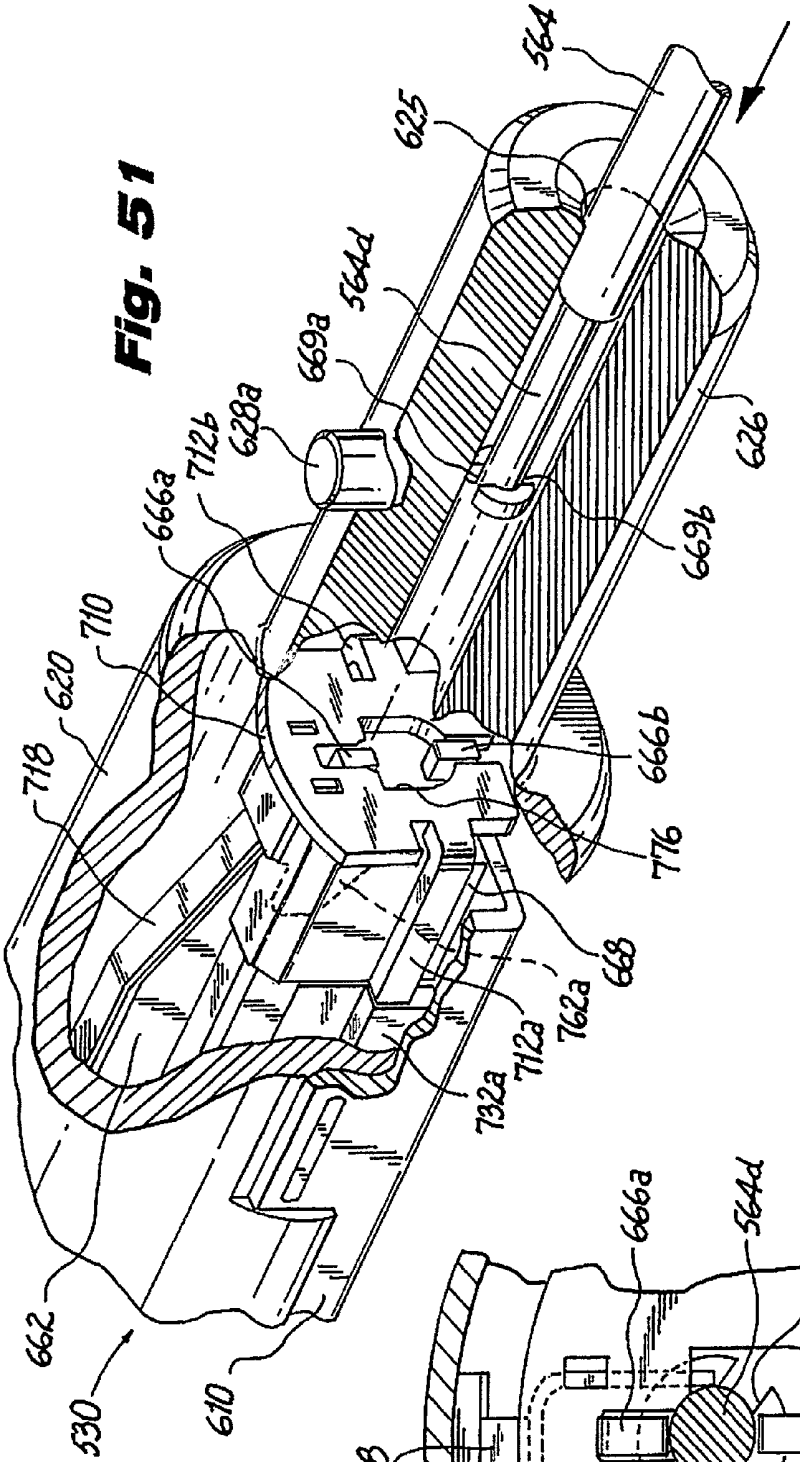
564
625
564d
669a
628a
712b
666a
710
620
718
626
669b
666b
776
668
762a
712a
732a
662
530
610

Fig. 51

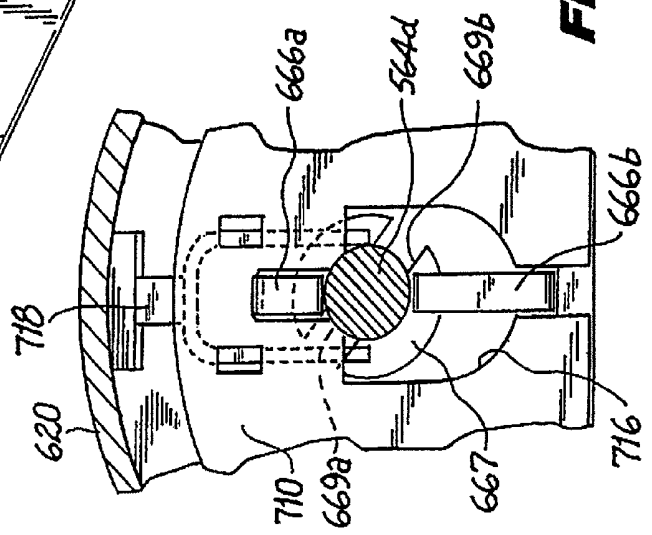
666a
564d
669b
666b
718
620
710
669a
667
716

Fig. 50

SURGICAL STAPLER

CROSS-REFERENCE TO RELATED APPLICATIONS

This application is a continuation of U.S. application Ser. No. 13/593,628 filed Aug. 24, 2012 now U.S. Pat. No. 8,453,912, which is a continuation of U.S. application Ser. No. 13/414,185 filed Mar. 7, 2012, now U.S. Pat. No. 8,272,553 which is a continuation of U.S. application Ser. No. 13/210,470 filed Aug. 16, 2011, now U.S. Pat. No. 8,162,197, which is a continuation of U.S. application Ser. No. 12/794,925 filed Jun. 7, 2010, now U.S. Pat. No. 8,011,553, which is a continuation of U.S. application Ser. No. 12/644,450 filed Dec. 22, 2009, now U.S. Pat. No. 7,913,893, which is a continuation of U.S. application Ser. No. 12/118,924 filed May 12, 2008, now U.S. Pat. No. 7,770,774, which is a continuation of U.S. application Ser. No. 11/903,586 filed Sep. 24, 2007, now U.S. Pat. No. 7,472,814, which is a continuation of U.S. application Ser. No. 11/590,441 filed Oct. 30, 2006, now U.S. Pat. No. 7,278,562, which is a continuation of U.S. application Ser. No. 11/186,743 filed Jul. 20, 2005, now U.S. Pat. No. 7,128,253 which is a continuation of U.S. application Ser. No. 11/011,355 filed Dec. 14, 2004, now U.S. Pat. No. 7,044,353, which is a continuation of U.S. application Ser. No. 09/625,886 filed Jul. 26, 2000, now U.S. Pat. No. 6,986,451, which is a continuation of U.S. application Ser. No. 09/497,647 filed Feb. 3, 2000, now abandoned, which is a continuation of U.S. application Ser. No. 09/119,543 filed Jul. 20, 1998, now U.S. Pat. No. 6,032,849, which is a continuation of U.S. application Ser. No. 08/546,253 filed Oct. 20, 1995, now U.S. Pat. No. 5,782,396, which is a continuation-in-part of U.S. application Ser. No. 08/520,202 filed on Aug. 28, 1995, now U.S. Pat. No. 5,762,256. Each of these applications is incorporated herein by reference in its entirety.

BACKGROUND

1. Technical Field

This application relates to a surgical stapling apparatus, and more particularly, to an apparatus for sequentially applying a plurality of surgical fasteners to body tissue and optionally incising the fastened tissue.

2. Background of Related Art

Surgical devices wherein tissue is first grasped or clamped between opposing jaw structure and then joined by surgical fasteners are well known in the art. In some instruments a knife is provided to cut the tissue which has been joined by the fasteners. The fasteners are typically in the form of surgical staples but two part polymeric fasteners can also be utilized.

Instruments for this purpose can include two elongated members which are respectively used to capture or clamp tissue. Typically, one of the members carries a staple cartridge which houses a plurality of staples arranged in at least two lateral rows while the other member has an anvil that defines a surface for forming the staple legs as the staples are driven from the staple cartridge. Generally, the stapling operation is effected by cam bars that travel longitudinally through the staple cartridge, with the cam bars acting upon staple pushers to sequentially eject the staples from the staple cartridge. A knife can travel between the staple rows to longitudinally cut and/or open the stapled tissue between the rows of staples. Such instruments are disclosed, for example, in U.S. Pat. No. 3,079,606 and U.S. Pat. No. 3,490,675.

A later stapler disclosed in U.S. Pat. No. 3,499,591 applies a double row of staples on each side of the incision. This is accomplished by providing a disposable loading unit in which a cam member moves through an elongate guide path between two sets of staggered staple carrying grooves. Staple drive members are located within the grooves and are positioned in such a manner so as to be contacted by the longitudinally moving cam to effect ejection of the staples from the staple cartridge of the disposable loading unit. Other examples of such staplers are disclosed in U.S. Pat. Nos. 4,429,695 and 5,065,929.

Each of the instruments described above were designed for use in conventional surgical procedures wherein surgeons have direct manual access to the operative site. However, in endoscopic or laparoscopic procedures, surgery is performed through a small incision or through a narrow cannula inserted through small entrance wounds in the skin. In order to address the specific needs of endoscopic and/or laparoscopic surgical procedures, endoscopic surgical stapling devices have been developed and are disclosed in, for example, U.S. Pat. No. 5,040,715 (Green, et al.); U.S. Pat. No. 5,307,976 (Olson, et al.); U.S. Pat. No. 5,312,023 (Green, et al.); U.S. Pat. No. 5,318,221 (Green, et al.); U.S. Pat. No. 5,326,013 (Green, et al.); and U.S. Pat. No. 5,332,142 (Robinson, et al.).

U.S. Surgical, the assignee of the present application, has manufactured and marketed endoscopic stapling instruments, such as the Multifire ENDO GIA* 30 and Multifire ENDO GIA* 60 instruments, for several years. These instruments have provided significant clinical benefits. Nonetheless, improvements are possible, for example, by reducing the cost and complexity of manufacture.

Current laparoscopic linear stapling devices are configured to operate with disposable loading units (U.S. Surgical) and staple cartridges (Ethicon) of only one size. For example, individual linear staplers are presently available for applying parallel rows of staples measuring 30 mm, 45 mm and 60 mm in length. Thus, during a normal operation, a surgeon may be required to utilize several different stapling instruments to perform a single laparoscopic surgical procedure. Such practices increase the time, complexity and overall costs associated with laparoscopic surgical procedures. In addition, costs are greater in designing and manufacturing multiple stapler sizes, as opposed to creating a single, multipurpose stapler.

It would be extremely beneficial to provide a surgical device for use during laparoscopic and/or endoscopic surgical procedures that can be employed with several different sized disposable loading units to reduce the overall costs associated with such procedures. It would also be particularly beneficial if the device could perform multiple tasks, using disposable loading units of varying size and of varying purpose, such as, for example, to staple, clip and/or cut.

In making improvements or modifications to the current instruments, it would be highly desirable not to sacrifice any of the important benefits of the MULTIFIRE ENDO GIA* 30 and 60 instruments as compared to other commercially available products, e.g., the endoscopic stapling instruments manufactured and marketed by Ethicon, Inc. For example, any improvement should advantageously provide a fresh knife blade for each firing of the instrument and ensure that the disposable loading unit is securely retained in the stapling instrument unless and until the operating team chooses to remove it. These advantages have historically been found in the U.S. Surgical instruments, but not in the Ethicon instruments.

Therefore, a need exists for a reliable surgical stapler and disposable loading units for use therewith that exhibit all of the benefits of the present assignee's commercially available instruments while also reducing the cost and complexity of manufacture.

SUMMARY

The subject application is primarily directed to a stapling device for applying parallel rows of surgical fasteners to body tissue and, preferably, one that concomitantly forms an incision between the rows of staples during an endoscopic or laparoscopic surgical procedure. A particularly unique feature of the stapling device described herein is that it can be employed with a number of different disposable loading units. Moreover, the stapling device of the subject application can be utilized with disposable loading units configured to apply linear rows of staples measuring from about 15 mm in length to about 60 mm in length.

In a preferred embodiment of the subject surgical stapler, the device includes a handle assembly including an elongated barrel portion and an actuation handle movable through an actuating stroke, and an elongated body extending distally from the barrel portion of the handle assembly and defining a longitudinal axis. An elongated actuation shaft is supported at least in part within the barrel portion of the handle assembly and it has a particular linear dimension. The actuation handle interacts with the actuation shaft such that manipulation of the actuation handle through a complete actuating stroke causes the actuation shaft to translate through a predetermined linear distance.

A disposable loading unit is operatively engaged in a distal portion of the elongated body. The disposable loading unit preferably includes a carrier, a staple cartridge containing a plurality of staples, an actuator (movable through the housing and staple cartridge) and an anvil. The instrument actuation shaft drives the actuator through the staple cartridge to eject the staples against the anvil to form a staple line having a particular linear dimension. Preferably, the linear dimension of the staple line corresponds to the distance through which the actuation shaft translates in response to manipulation of the actuation handle through a particular number of complete or partial actuation strokes numbering more than one complete stroke.

The actuation shaft is preferably defined at least in part by a toothed rack having a particular rack length, and the actuation handle has a pawl member for selectively engaging the toothed rack and advancing the actuation shaft in response to manipulation of the actuation handle. When a disposable loading unit having linear rows of staples is used, the linear dimension of the staple line applied by the stapling unit is preferably proportional to the longitudinal travel of the actuation shaft. In a most preferred embodiment, the minimum linear dimension of the staple line will always be greater than the maximum linear distance through which the actuation shaft translates in response to a complete actuation stroke.

When a disposable loading unit having an anvil is used, the actuation handle is preferably movable through a clamping stroke in which the actuation shaft translates through a predetermined clamping distance to move the anvil from an open position to a closed position. The clamping stroke precedes the first of any number of complete or partial actuation strokes. In a preferred embodiment, an engagement hook is mounted within the barrel portion of the handle assembly to selectively maintain the actuation shaft in a particular position after traveling through the clamping distance and a notch is defined in a distal end portion of the actuation shaft, distal of the toothed rack, for receiving and releasably retaining the engagement hook.

In use of a preferred embodiment, movement of the actuation handle in a direction opposite the clamping stroke causes the engagement hook to release the actuation shaft, permitting the anvil to move to an open position. A lift finger is provided on a flange extending from the actuation handle and is positioned to move the engagement hook out of engagement with the notch when the actuation handle is moved in a direction opposite the clamping stroke. Preferably, a first biasing spring is provided within the handle assembly for biasing the actuation handle in a clockwise direction and a second biasing spring is provided within the handle assembly for biasing the actuation handle in a counter-clockwise direction, about a handle pivot point. The counter-clockwise direction corresponds to the direction of the clamping and actuating strokes.

The engagement hook is preferably configured to interact with the toothed rack to maintain the actuation shaft in a particular linear position during an actuation stroke, and it is normally biased into engagement with the actuation shaft. An abutment strut or beam is operatively associated with a proximal end portion of the stapler body for maintaining the engagement hook in a position out of engagement with the actuation shaft until a disposable loading unit is operatively engaged in a distal end portion of the elongated body. The abutment strut permits the engagement hook to engage the actuation shaft after a disposable loading unit has been operatively engaged in a distal end portion of the elongated instrument body.

In another preferred embodiment of the surgical stapling apparatus disclosed herein, a release mechanism is operatively associated with the handle assembly for effectuating the manual disengagement of the engagement hook from the actuation shaft to permit subsequent distal advancement of the actuation shaft in response to manipulation of the actuation handle through any number of subsequent stapling strokes. In addition, a retracting mechanism is operatively associated with the handle assembly for effectuating the manual retraction of the actuation shaft at any point in the actuating stroke so that the actuator can be withdrawn to permit the anvil to move from a closed position to an open position.

In a preferred embodiment of the device described herein, the disposable loading unit is a adapted to apply linear rows of staples and includes: a carrier having a proximal end portion including a coupling for releasable engagement in a distal end portion of the elongated instrument body; an elongate staple cartridge supported in the carrier and containing a plurality of surgical fasteners and a plurality of fastener pushers for ejecting the fasteners from the staple cartridge; an actuator for contacting the fastener pushers; and an anvil supported on the carrier and mounted for movement with respect to the staple cartridge between an open position and a closed position. The anvil preferably has a fastener forming surface against which the surgical fasteners are driven when ejected from the staple cartridge by the fastener pushers, and a camming surface opposite the fastener forming surface. The actuator is preferably wedged actuator that translates through the staple cartridge to sequentially interact with the fastener pushers to eject the fasteners from the staple cartridge.

The disposable loading unit further preferably includes an elongated drive beam having a proximal engagement portion, a distal working end portion having an abutment surface and a camming member. The proximal engagement portion is configured to mate with a distal end portion of the actuation assembly of the stapler while the abutment surface engages the actuator to eject staples from the staple cartridge during firing. The camming member contacts the camming surface of the anvil during firing. In use, the stapler actuation assembly moves the drive beam through the carrier causing the camming member to close the anvil or maintain the anvil closed as it substantially simultaneously causes the actuator

to translate through the staple cartridge, thereby sequentially interacting with the plurality of fastener pushers to fire the staples.

Preferably, the camming member is defined by a cylindrical cam roller mounted on a flange extending from the distal working end portion of the drive beam. A longitudinal slot is defined in the anvil to accommodate the linear translation of the working end portion of the drive beam, and a transverse support flange is operatively mounted on the working end portion opposite the cam roller to engage an undersurface of the carrier as the cam roller engages the camming surface of the anvil. A longitudinal slot is also defined in the undersurface of the carrier to accommodate the linear translation of the working end portion of the drive beam. An optional anvil cover can be provided to ensure tissue is not inadvertently contacted by the drive beam or cam roller during firing.

Preferably, a knife blade is operatively supported adjacent a leading edge of the working end portion of the drive beam for forming an incision in stapled body tissue. Also, the actuator is preferably a sled including a planar base portion and a plurality of spaced apart upstanding cam wedges each having an inclined leading edge for interacting with the fastener pushers within the staple cartridge.

In a preferred embodiment of the stapling device described herein, the distal end portion of the elongated body and the proximal portion of the carrier includes cooperating portions of a bayonet-type coupling. The coupling facilitates the convenient removal and engagement of a variety of different sized disposable loading units including those which are configured to apply staple rows that are approximately 30 mm in length, 45 mm in length, and 60 mm in length. Accordingly, it is envisioned that the device can be sold and marketed as a kit which would include at least one surgical instrument designed to actuate compatible disposable loading units and a plurality of disposable loading units that can vary in size and type. The disposable loading units can be adapted to apply linear rows of staples, clips or other forms of fasteners. A common feature of these disposable loading units is that they utilize the longitudinal motion of the instrument actuation control rod to apply the fasteners.

These and other features of the surgical stapling device of the subject application will become more readily apparent to those skilled in the art from the following detailed description of the preferred embodiments of the device taken in conjunction with the drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

Various embodiments of the surgical stapling apparatus of the subject application will be described hereinbelow with reference to the drawings wherein:

FIG. **1** is a perspective view of a surgical stapling apparatus constructed in accordance with a preferred embodiment of the subject application in conjunction with three different sized disposable loading units each configured for utilization with the stapling apparatus;

FIG. **2** is an exploded perspective view of the handle assembly of the surgical stapling apparatus illustrated in FIG. **1**;

FIG. **3** is an exploded perspective view of a disposable loading unit constructed in accordance with a preferred embodiment of the subject application;

FIG. **4** is a perspective view in partial cross-section of the handle assembly and body portion of the stapling apparatus illustrated in FIG. **1** as the disposable loading unit of FIG. **3** is inserted into the distal end of the body;

FIG. **5** is a perspective view which corresponds to the illustration in FIG. **4** with the disposable loading unit mounted in the body of the stapling apparatus and the actuation mechanism within the handle portion enabled as a result of the insertion of the disposable loading unit;

FIG. **6** is a side elevational view of the surgical stapling apparatus of the subject application with the handle portion sectioned to illustrate the relative positions of the components of the actuation assembly housed therein prior to actuation;

FIG. **7** is a side elevational view of the surgical stapling apparatus of the subject application with the handle portion sectioned to illustrate the relative positions of the components of the actuation assembly when the actuation handle is partially compressed to move the anvil of the disposable loading unit to a closed position;

FIG. **8** is a side elevational view of the surgical stapling apparatus of the subject application with the handle portion sectioned to illustrate the relative positions of the components of the actuation assembly when the actuation handle is released to permit the anvil of the disposable loading unit to move to an open position;

FIG. **9** is a side elevational view of the surgical stapling apparatus of the subject application with the handle portion sectioned to illustrate the relative positions of the components of the actuation assembly when the actuation handle is moved to a position wherein the anvil of the disposable loading unit is maintained in an open position;

FIG. **10** is a side elevational view of the surgical stapling apparatus of the subject application with the handle portion sectioned to illustrate the relative positions of the components of the actuation assembly when the actuation handle is manipulated through one complete actuation stroke to apply a portion of the staples from the staple cartridge of the disposable loading unit to body tissue;

FIG. **11** is a side elevational view of the surgical stapling apparatus of the subject application with the handle portion sectioned to illustrate the relative positions of the components of the actuation assembly when the disposable loading unit is removed from the distal end of the stapler body;

FIG. **12** is a side elevational view of the disposable loading unit of the subject application with the body thereof sectioned to illustrate the relative positions of the components prior to closing the anvil to clamp a tubular vessel;

FIG. **13** is a side elevational view of the disposable loading unit of the subject application with the body thereof sectioned to illustrate the relative positions of the components after the apparatus has been completely fired;

FIG. **14** is a side elevational view of the disposable loading unit as illustrated in FIG. **13** with the anvil moved to an open position under the bias of a release spring;

FIG. **15** illustrates an alternate embodiment of a disposable loading unit adapted to apply surgical clips;

FIG. **16** illustrates an alternate embodiment of a disposable loading unit adapted to apply single surgical staples;

FIG. **17** is a perspective view of another surgical stapling apparatus constructed in accordance with a preferred embodiment of the subject invention illustrated in conjunction with one of several different sized disposable loading units employed with the apparatus;

FIG. **18** is an exploded perspective view of the handle assembly of the surgical stapling apparatus of FIG. **17** with the components associated therewith separated for ease of illustration;

FIG. **19** is an exploded perspective view of the body portion of the surgical stapling apparatus of FIG. **17** in conjunction with the elongated control rod which extends therethrough;

FIG. **20** is a perspective view of a distal portion of the control rod illustrated in FIG. **19**;

FIG. **21** is a cross-sectional view taken along line **21-21** of FIG. **19** illustrating the proximal portion of the inner support tube housed within the body portion of the surgical stapling apparatus of FIG. **17**;

FIG. **22** is a side elevational view in partial cross-section of the surgical stapling apparatus of FIG. **17** illustrating the orientation of the rack lock prior to mounting the disposable loading unit in the distal end of the body portion;

FIG. **23** is a side elevational view in partial cross-section of the surgical stapling apparatus of FIG. **17** illustrating the orientation of the rack lock after the disposable loading unit has been mounted in the distal end of the body portion;

FIG. **24** is an exploded perspective view of a disposable loading unit constructed in accordance with a preferred embodiment of the subject invention which includes a lockout assembly that functions to limit the longitudinal translation of the control shaft illustrated in FIGS. **19** and **20**;

FIG. **25** is an enlarged exploded perspective view of the lockout assembly illustrated in FIG. **24** with a distal portion of the control rod;

FIG. **26** is a side elevational view in partial cross-section of a proximal portion of the disposable loading unit of FIG. **24** as it is inserted into the distal end of the body portion with the lockout assembly disposed in a pre-actuated condition;

FIG. **27** is a side elevation view in partial cross-section of the proximal portion of the disposable loading unit of FIG. **24** when the mounting portion thereof is fully inserted into the distal end of the body portion;

FIG. **28** is a side elevational view in partial cross-section of the proximal portion of the disposable loading unit of FIG. **24** as it is rotated into an operational position;

FIG. **29** is a cross-sectional view taken along line **29-29** of FIG. **26** illustrating the alignment of the notches in the head of the control rod and the engagement fingers at the proximal end of the axial drive assembly;

FIG. **30** is a cross-sectional view taken along line **30-30** of FIG. **28** illustrating the position of the head of the control rod in relation to the engagement fingers after the disposable loading unit has been rotated into an operational position;

FIG. **31** is a side elevational view in partial cross-section of the surgical stapling apparatus of FIG. **17** prior to a stapling procedure with the anvil in an open position and the actuation shaft and toothed rack disposed in a proximal-most position within the handle assembly;

FIG. **32** is a side elevational view in partial cross-section of the surgical stapling apparatus of FIG. **17** illustrating the actuation shaft and toothed rack advanced distally through a clamping stroke to effectuate the movement of the anvil from the open position shown in FIG. **31** to a closed position;

FIG. **33** is a side elevational view in partial cross-section of the surgical stapling apparatus of FIG. **17** illustrating the disengagement of the rack lock and pawl from the actuation shaft and toothed rack by the retraction mechanism to effectuate the movement of the anvil from the closed position shown in FIG. **32** to an open position;

FIG. **34** corresponds to FIG. **32** and illustrates the surgical stapling apparatus with the anvil in a closed position after the actuation handle has been manipulated through a clamping stroke;

FIG. **35** is a side elevational view in partial cross-section of the surgical stapling apparatus of FIG. **17** illustrating the manual release of the rack lock to permit distal translation of the actuation shaft during subsequent stapling strokes;

FIG. **36** is a side elevational view in partial cross-section of the surgical stapling apparatus of FIG. **17** illustrating the actuation shaft and toothed rack advanced distally in response to a complete stapling stroke of the actuation handle to effectuate partial sequential ejection of staples from the cartridge;

FIG. **37** is a side elevational view in partial cross-section of the surgical stapling apparatus of FIG. **17** illustrating the actuation shaft and toothed rack advanced distally in response to a second complete stapling stroke of the actuation handle to complete the sequential ejection of the staples from the cartridge;

FIG. **38** is a side elevational view in partial cross-section of the surgical stapling apparatus of FIG. **17** illustrating the disengagement of the rack lock and pawl from the toothed rack by the release plate as the retraction knobs are pulled proximally to withdraw the actuation shaft and permit the anvil to move from the closed position shown in FIG. **37** to an open position;

FIG. **39** is an enlarged side elevational view of the toothed rack and the release plate associated therewith illustrating the rack lock engaged in the toothed rack;

FIG. **40** is an enlarged side elevational view of the toothed rack and the release plate associated therewith illustrating the release plate moved to disengage the rack lock from the toothed rack;

FIG. **41** is a cross-sectional view taken along line **41-41** of FIG. **39**;

FIG. **42** is a cross-sectional view taken along line **42-42** of FIG. **40**;

FIG. **43** is an enlarged perspective view of the rack lock for engagement member) illustrating the structural geometry thereof;

FIG. **44** is a side elevational view in partial cross-section of the disposable loading unit illustrating the position of the axial drive assembly and control rod at the conclusion of a stapling procedure;

FIG. **45** is a side elevational view in partial cross-section of the disposable loading unit of FIG. **24** with the components of the lockout assembly illustrated in a position corresponding to the control rod being withdrawn toward a post-fired proximal position;

FIG. **46** is a side elevational view in partial cross-section of the disposable loading unit of FIG. **24** illustrating the orientation of the lockout assembly components as the control rod approaches its proximal-most position;

FIG. **47** is a side elevational view in partial cross-section of the disposable loading unit of FIG. **24** illustrating the orientation of the lockout assembly components when the control rod has been withdrawn to its proximal-most position;

FIG. **48** is a side elevational view in partial cross-section of the disposable loading unit of FIG. **24** illustrating the orientation of the lockout assembly components when the loading unit has been moved distally with respect to the body portion to disengage the bayonet connection;

FIG. **49** is a side elevational view in partial cross-section of the disposable loading unit of FIG. **24** disengaged from the distal end of the body portion at the conclusion of a stapling procedure with the components of the lockout assembly illustrated in a blocking position to prevent subsequent utilization of the loading unit;

FIG. **50** is a cross-sectional view taken along line **50-50** of FIG. **46** illustrating the relative positions of the blocking plate and control rod prior to the removal of the disposable loading unit from the distal end of the body portion; and

FIG. **51** is an enlarged perspective view in partial cross-section of the disposable loading unit after it has been removed from the distal end of the body portion illustrating

the lockout assembly in a blocking position to prevent entry of the distal end of the control rod into the drive block of the axial drive assembly.

DETAILED DESCRIPTION OF PREFERRED EMBODIMENTS

In the drawings and in the description which follows, the term "proximal", as is traditional, will refer to the end of the stapling apparatus which is closest to the operator, while the term "distal" will refer to the end of the apparatus which is furthest from the operator.

Referring now to the drawings wherein like reference numerals identify similar structural elements of the subject invention, there is illustrated in FIG. **1** a surgical apparatus constructed in accordance with a preferred embodiment of the subject application and designated generally by reference numeral **10**. In brief, surgical apparatus **10** is a surgical stapling apparatus configured to engage body tissue, apply a plurality of surgical fasteners thereto, and form an incision in the fastened body tissue during a laparoscopic surgical procedure. Apparatus **10** can also be used to apply surgical clips and other fasteners (discussed in greater detail below) but will be primarily discussed in the context of applying parallel rows of staples from a staple cartridge disposed in a disposable loading unit.

Surgical apparatus **10** is unique among laparoscopic devices known in the art because it can employ a plurality of different sized disposable loading units. Moreover, apparatus **10** is preferably configured to operate with individual disposable loading units that apply linear rows of staples measuring 30 mm, 45 mm, or 60 mm in length (FIG. **1**) or apply other types of fasteners (FIGS. **15** and **16**). Thus, during a laparoscopic surgical procedure, a single instrument can be utilized with a plurality of interchangeable disposable loading units to perform several tasks. The preferred embodiments discussed in detail primarily relate to disposable loading units adapted to apply linear rows of staples.

As illustrated in FIG. **1**, surgical apparatus **10**, has a handle assembly **12** and an elongated body **14**. Apparatus **10** is adapted for use with disposable loading units **30**, **45** and **60** each of which has a carrier **32**, a staple cartridge **34**, and an anvil **36** against which staples are driven when ejected from their housing. The following specification will provide a detailed description of the construction and operation of the apparatus and disposable loading units for use therewith.

Referring to FIG. **2**, handle assembly **12** includes a housing **20** defined by an elongated barrel portion **22**, a stationary handle **24** depending from the barrel portion, and an actuation handle **26** which is pivotably mounted to the barrel portion and movable with respect to the stationary handle. Actuation handle **26** is supported within housing **20** by a pivot pin **28** and is biased against counter-clockwise movement by a coiled torsion spring **38**.

Actuation handle **26** controls the linear movement of actuation shaft **40** which is mounted within barrel portion **22**. More particularly, actuation shaft **40** has a toothed rack **42** defined thereon, and actuation handle **26** has a ratcheting pawl **44** mounted thereto for incrementally engaging and advancing actuation shaft **40**. Pawl **44** is mounted on a pivot pin **46** and a coiled torsion spring **48** biases the pawl into engagement with toothed rack **42**. A linear biasing strut **50** is supported within barrel portion **22** and is biased distally by a coiled compression spring **52** to bias the pawl, and hence the actuation handle, against clockwise rotation about pivot pin **28**. Biasing strut **50** also serves to act on an angled rear cam surface on pawl **44** wherein contact of the cam surface with strut **50** causes pawl **44** to rotate clockwise (away from rack **42**). When the instrument is at rest, pawl **44** is biased away from toothed rack **42**. When actuation handle **26** is pulled proximally, pawl **44** moves away from strut **50** and rotates counterclockwise and engages the teeth of actuation shaft **40**, thereby allowing actuation handle **26** to drive the shaft distally.

Actuation shaft **40** is normally biased in a proximal direction within barrel portion **22** by a constant force spring **54** which is mounted to the actuation shaft adjacent the distal end thereof by conventional fastening means known in the art. Constant force spring **54** is supported on a boss **56** provided within the housing **22** of handle assembly **12**. The distal end portion of actuation shaft **40** has a cavity **58** defined in an undersurface thereof for engaging and retaining the flanged proximal end **62** of control rod **64**. Control rod **64** extends coaxially through the elongated body **14** of surgical stapler **10** to interact with a disposable loading unit at a distal end thereof. Thus, linear advancement of actuation shaft **40** in response to manipulation of actuation handle **26** causes corresponding longitudinal movement of control rod **64**, and, as will be discussed in detail hereinbelow, actuation of an associated disposable loading unit.

With continuing reference to FIG. **2**, the proximal end portion of the elongated body **14** of surgical stapler **10** has an annular flange **66** formed thereon which engages a corresponding annular recess **68** formed within the barrel portion **22** adjacent the distal end thereof to fixedly attach the two structural members. The engagement of flange **66** within recess **68** facilitates rotational movement of body portion **14** with respect to the barrel portion **22** about a longitudinal axis which extends therethrough. A collar **70** is fixedly mounted to the proximal portion of stapler body **14** by a pair of opposed protuberances **72** and **74**. Thus, rotation of collar **70** will cause corresponding rotation of body portion **14** to increase the range of operability of surgical stapler **10**.

Within handle assembly **12**, there is also contained a mechanism for initiating the engagement between a rack lock **80** and the toothed rack **42** of actuation shaft **40**. Rack lock **80** maintains the longitudinal position of actuation shaft **40** under the bias of constant force spring **54**. Rack lock **80** will not engage the rack unless and until a disposable loading unit is operatively engaged in the distal end portion of portion body **14**. This mechanism is illustrated in FIG. **2** and its interaction with rack lock **80** is best understood by also referring to FIGS. **4** and **5**. The mechanism includes an elongate beam or strut **82** having a distal tang **84** that engages a keeper notch **86** formed adjacent the proximal end of a support tube **88** that is slidably mounted within stapler body **14**. Beam **82** has a medial hook **90** for engaging the proximal end of a coiled biasing spring **92**, the distal end of which is mounted on a boss **94** provided within barrel portion **22**. Biasing spring **92** biases beam **82**, and hence support tube **88**, against proximal movement. An arcuate cam finger **96** projects proximally from beam **82** for interacting with an angled cam surface **98** defined on the undersurface of the body **100** of rack lock **80**. Rack lock **80** further includes a wedged clasp portion **102** which is dimensioned and configured to engage the teeth of the toothed rack **42** to maintain the longitudinal position of actuation shaft **40** during the operation of instrument **10**. The body **100** of rack lock **80** is mounted on a boss **104** provided within the barrel portion **22** of housing **20**. A coiled torsion spring **106** is also mounted on boss **104** and is connected to body **100** to bias the rack lock into engagement with toothed rack **42**.

As best seen in FIGS. **4** and **5**, when the proximal end portion of the carrier **32** of disposable loading unit **30** is

inserted into the distal end of elongated body **14**, support tube **88** is urged in a proximal direction against the bias of spring **92**. Thereupon, beam **82** translates proximally and the arcuate cam finger **96** contacts angled cam surface **98**, lifting rack lock **80** and causing it to rotate in a counter-clockwise direction against the bias of torsion spring **106**. At such a time, the cam finger **96** of beam **82** is accommodated within a recess **108** formed in the body **100** of rack lock **80**. With the rack lock in this position, it will engage actuation shaft **40** when it is advanced distally upon manipulation of actuation handle **26**. The interaction of rack lock **80** and actuation shaft **40** will be discussed in greater detail hereinbelow with respect to the manner in which instrument **10** is operated to clamp body tissue and apply fasteners thereto.

Referring now to FIG. **3**, an exemplary disposable loading unit is illustrated and is designated generally by reference numeral **30**. As noted hereinabove, disposable loading unit **30**, which is particularly adapted to apply a plurality of linear rows of staples measuring about 30 mm in length, is one of several different size or type of disposable loading units that can be utilized with instrument **10** during a surgical procedure. The carrier **32** of stapling unit **30** includes an elongate channel **110** having a base **112** and two parallel upstanding walls **114** and **116** which include several mounting structures for supporting staple cartridge **34** and anvil **36**. Carrier **32** also includes mounting portion **120** which is mounted to the proximal portion of channel **110** through the engagement of a plurality of spaced apart rectangular tangs **122** and a plurality of corresponding slots **124** formed in the opposed walls **114** and **116** of channel **110**. The proximal end section **126** of mounting portion **120** is dimensioned and configured for insertion into the distal end portion of elongated body **14**, and it is provided with an axial bore **125** for accommodating the distal end of control rod **64**.

A coupling stem **128** projects radially outwardly from end section **126** for interacting with the J-shaped coupling slot **130** defined in the wall of the distal end portion of elongated body **14** (see FIGS. **4** and **5**). Stem **128** and slot **130** together define a conventional bayonet-type coupling which facilitates quick and easy engagement and removal of the stapling unit from the stapler during a surgical procedure. Once engaged in the distal end portion of stapler elongated **14**, the distal end of support tube **88** urges proximal end section **126** distally under the bias of coiled spring **92**, thereby maintaining the coupling stem **128** within coupling slot **130**.

With continuing reference to FIG. **3**, the distal portion of channel **110** supports staple cartridge **34** which contains a plurality of surgical fasteners **132** and a plurality of corresponding ejectors or pushers **134** that drive the fasteners from cartridge **34** under the influence of a fastener driving force exerted by actuation sled **140**. Staple cartridge **34** is maintained within channel **110** by lateral struts **136** which frictionally engage the upper surfaces of channel walls **114** and **116**, and the frictional engagement of housing tabs, such as tab **138**, within notches **139**. These structures serve to restrict lateral, longitudinal, and elevational movement of the staple cartridge **34** within channel **110**.

A plurality of spaced apart longitudinal slots **142** extend through staple cartridge **34** to accommodate the upstanding cam wedges **144** of actuation sled **140**. Slots **142** communicate with a plurality of transverse retention slots **146** within which the plurality of fasteners **132** and pushers **134** are respectively supported. During operation, as actuation sled **140** translates through staple cartridge **34**, the angled leading edges of cam wedges **144** sequentially contact pushers **136**, causing the pushers to translate vertically within slots **146**, urging the fasteners **134** therefrom. The result of the interaction between actuation sled **140** and pushers **136** is illustrated in FIGS. **12-14**, and will be described hereinbelow with reference thereto. See also, commonly assigned U.S. Pat. No. 4,978,049 to Green, the disclosure of which is herein incorporated by reference in its entirety.

With continuing reference to FIG. **3**, the anvil **36** of disposable loading unit **30** is provided with opposed mounting wings **150** and **152** which are dimensioned and configured to engage pivot apertures **154** and **156** in channel walls **114** and **116**, respectively. A biasing member **158** having spring arms **158***a* and **158***b* is secured to the proximal end of anvil **36**. The spring arms bear against internal-bearing surfaces defined within mounting portion **120** to bias anvil **36** into a normally open position wherein the interior fastener forming surface **155** thereof is spaced from staple cartridge **34**.

Disposable loading unit **30** further includes an axial drive assembly **160** for transmitting the longitudinal drive forces exerted by control rod **64** to actuation sled **140** during a stapling procedure. Drive assembly **160** includes an elongated drive beam **162** including a distal working head **164** and a proximal engagement section **166**. Engagement section **166** includes a pair of engagement fingers **166***a* and **166***b* which are dimensioned and configured to mountingly engage a pair of corresponding retention slots **168***a* and **168***b* formed in a drive block **168**. Drive block **168** has a proximal porthole **170** for receiving the distal end of control rod **64** when the proximal end of stapling unit **30** is inserted into the distal end of stapler body **14**. Drive block **168** can be provided with an internal slot to receive a stem (not shown) from a distal end of control rod **64** to form a bayonet type connection, similar to that shown in connecting elongated body **14** to coupling stem **128**. Such a connection would enable the user to manipulate drive beam **162** upon movement of control rod **64**. The working end **164** of drive beam **162** is defined by a vertical support strut **172** which supports a knife blade **174**, and an abutment surface **176** which engages the central support wedge **145** of actuation sled **140**. Knife blade **174** travels slightly behind actuation sled **140** during a stapling procedure to form an incision between the rows of staple body tissue. A retention flange **178** projects distally from vertical strut **172** to retain a cylindrical cam roller **180**. Cam roller **180** is dimensioned and configured to engage and translate with respect to the exterior camming surface **182** of anvil **36** to progressively clamp the anvil against body tissue during firing.

A longitudinal slot **184** extends through anvil **36** to accommodate the translation of retention flange **178** and vertical strut **172**. A balancing flange **186** is secured to the working end of drive beam **162** through the engagement of retention foot **188** within a complementary retention port **190** formed in flange **186**. Flange **186** serves to balance the clamping forces generated by cam roller **180** as anvil **36** is progressively clamped. A longitudinal slot **192** is formed in the base **112** of channel **110** to accommodate the longitudinal translation of retention foot **188** during firing.

With reference to disposable loading unit **45** in FIG. **1**, an anvil cover is provided to protect tissue from moving parts along the exterior of anvil **36**. In particular, anvil cover **400** has channel **402** formed on an underside thereof and is secured to an upper surface of anvil **36** to form a channel therebetween. Cam roller **180** travels in channel **402** between cover **400** and anvil **36** during firing. Anvil cover **400** is preferably plastic, but can be fabricated from any suitable biocompatible material.

Returning to FIG. **3**, dual constant force spring members **194** and **196** are connected to the proximal end of channel base **112** and are disposed distal of drive block **168** to bias the block against distal movement. As best seen in FIGS. **12-14**,

when drive block **168** translates distally, spring members **194** and **196** unwind until they are passed over by the block at the end of its travel. At such a time, the spring members return to their normally wound position providing a buffer for the mounting block. Thus, an attempt to return the block to the proximal most position after firing the disposable loading unit will be inhibited.

Referring now in sequential order to FIGS. **4-11**, to initiate the operation of instrument **10**, a desired disposable loading unit is selected. Such disposable loading unit can be one of the different sized disposable loading units illustrated in FIG. **1** or one of the disposable loading units adapted to apply surgical clips (FIG. **15**) or other types of surgical staples (FIG. **16**). Use of the instrument will be discussed herein using a disposable loading unit adapted to apply linear rows of staples. Disposable loading unit **30**, is mounted to the stapler by inserting the proximal mounting section thereof into the distal end of the elongated body **14**, as shown in FIG. **4**. Prior to insertion, support tube **88** is in its distal-most position within elongated body **14** and it is maintained in that position by spring **92**. Accordingly, the cam finger **96** of beam **82** maintains rack lock **80** in a disengaged uplifted position, spaced from the toothed rack **42** of actuation shaft **40**.

Once the proximal end of the disposable loading unit is inserted into the distal end of elongated body **14**, it is rotated approximately 10' to 15' to position coupling stem **128** in the base of coupling slot **130**. Thereupon, the bias of spring **92** urges support tube **88** distally to lock stem **128** within the base of slot **130**. If a coupling system is provided between control rod **64** and drive block **168** (discussed above) such rotation would couple these member as well. In addition, as illustrated in FIG. **5**, when support tube **88** is shifted proximally by the insertion of the proximal section **126** of mounting portion **120** into elongated body **14**, arcuate cam finger **96** of beam **82** translates proximally against cam surface **98** until it reaches recess **108**. Thereupon rack lock **80** moves into an engagement position under the bias of torsion spring **106**, and instrument **10** is ready for use.

Turning to FIG. **6**, prior to utilization, actuation handle **26** is in the illustrated neutral position. In this position, pawl **44** is spaced from the toothed rack **42** of actuation shaft **40**. In addition, lift arm **210** which projects distally from actuation handle **26** is engaged beneath a transverse finger **212** formed at the proximal end of rack lock **80** adjacent the wedged clasp portion **102**. Lift arm **210** serves to disengage clasp portion **102** from actuation shaft **40** under certain operating conditions which will be discussed hereinbelow with respect to FIGS. **8** and **9**.

Prior to manipulating actuation handle **26**, actuation shaft **40** is in its proximal-most position, as is control rod **64**, biased against distal movement by constant force spring **54**. Accordingly, anvil **36** is in an open position biased against closure by spring arms **158***a* and **158***b*. Thus, at such a time, body tissue such as tubular vessel **200** may be captured between the fastener forming surface of anvil **36** and the tissue contacting surface of staple cartridge **34**.

Turning now to FIG. **7**, manipulation of actuation handle **26** in the direction indicated by reference arrow "A" causes pawl **44** move distally and rotate counterclockwise to engage toothed rack **42** and drive actuation shaft **40** distally against the bias of spring **54**. As a result, control rod **64** is driven distally, forcing drive block **168** forward within disposable loading unit **30**. Accordingly, a working end **164** of drive beam **162** translates distally and cam roller **180** engages the proximal end portion of the cam surface of anvil **36**, causing the anvil to move into a closed position, clamping tubular vessel **200** against the tissue contacting surface of staple cartridge **34**. In addition, when actuation shaft **40** advances distally, the clasp portion **102** of rack lock **80** engages a notched area **214** formed in the distal end portion of actuation shaft **40** distal of toothed rack **42** under the bias of torsion spring **106**. Thereupon, the longitudinal position of actuation shaft **40** within barrel portion **22** is maintained, and anvil **36** is locked in a closed position.

Under certain circumstances it may be necessary to open the anvil and unclamp the captured vessel or body tissue, i.e., to recapture the vessel at a different location. As illustrated in FIG. **8**, to release the anvil, actuation handle **26** is manipulated in the direction indicated by reference arrow "B" against the bias of linear compression spring **52**. As a result, arm **210** lifts finger **212**, rotating rack lock **80** in a counter-clockwise direction against the bias of torsion spring **106**, as shown in FIG. **9**. The clasp portion **102** of rack lock **80** is thereby disengaged from notched area **214**, permitting actuation shaft **40** and control rod **64** to return to their proximal-most positions. At such a time, drive block **168** moves proximally under the bias of spring members **194** and **196**. Accordingly, cam roller **180** is drawn off of the exterior camming surface **182** of anvil **36**, and the anvil moves to an open position under the bias of spring member **158**. Subsequent anvil closure is achieved in the manner described hereinabove with reference to FIG. **7**.

Referring to FIG. **10**, to fire instrument **10** and apply a plurality of surgical fasteners **132** to the tissue clamped between anvil **36** and staple cartridge **34**, actuation handle **26** is manipulated toward stationary handle **24** in the direction indicated by reference arrow "C" against the bias of torsion spring **38**. Thereupon, pawl **44** engages toothed rack **42** and drives actuation shaft **40** distally against the bias of constant force spring **54**. In a preferred embodiment of firing a disposable loading unit having linear rows of staples, one complete stroke of actuation handle **26** causes actuation shaft **40** to advance approximately 15 mm within barrel portion **22**, urging drive beam **162** an equivalent distance within disposable loading unit **30** as control shaft **64** transmits longitudinal motion thereto. As a result, half of the surgical fasteners **132** within 30 mm staple cartridge **34** are ejected therefrom upon moving actuation handle **26** one complete stroke. Actuation shaft **40** is maintained in this longitudinally advanced position through the engagement of the clasp portion **102** of rack lock **80** and the toothed rack **42**. Subsequent release and movement of actuation handle **26** to a relaxed position will therefore have no bearing on the longitudinal position of actuation shaft **40**.

To complete the staple firing operation, actuation handle **26** is once again approximated toward stationary handle **24**, causing pawl **44** to engage toothed rack **42** and advance actuation shaft **40** in a distal direction another 15 mm. Thus, two complete strokes of actuation handle **26** causes actuation shaft **40** to advance 30 mm within barrel portion **22**, urging the working end **164** of drive beam **162** through staple cartridge **34** to sequentially eject all of the surgical fasteners therefrom. If desired, the operator can incrementally advance control shaft **64** by multiple short strokes, wherein the minimum advancement is dictated by the linear distance between the teeth on rack **42**. Therefore, while two complete strokes of the preferred stroke distance of 15 mm can be used (to fire a 30 mm disposable loading unit), complete strokes are not necessary or required.

As best seen in FIGS. **12-14**, two complete strokes of actuation handle **26** causes actuation shaft **40** and the associated control rod **64** to translate from the proximal-most position illustrated in FIG. **12**, wherein drive block **168** is disposed adjacent the proximal end of channel **110**, to the distal-

most position illustrated in FIG. **13**, wherein drive block **168** travels to the distal end of staple cartridge **34**. During its travel, drive block **168** urges drive beam **166** distally, effectuating progressive closure of anvil **36** against tubular vessel **200**, and sequential ejection of surgical fasteners **132** into the body tissue as actuation sled **140** travels through staple cartridge **34**. As shown in FIG. **13**, when cam roller **180** reaches the distal end of its travel, it drops into the transverse slot **185** formed at the distal end of anvil slot **184**. As a result, anvil **36** returns to an open position under the bias of spring member **158**, releasing the stapled body tissue as illustrated in FIG. **14**. Furthermore, spring members **194** and **196** rewind and return to a coiled condition at the proximal end of channel **110**.

At the conclusion of the above-described firing operation, disposable loading unit **30** is removed from the distal end of elongated body **14**, as illustrated in FIG. **11**. At such a time, support tube **88** is permitted to return to its distal-most position under the bias of spring **92**. Accordingly, beam **82** translates distally causing arcuate cam finger **96** to lift rack lock **80** out of engagement with the toothed rack **42** of actuation shaft **40**. As a result, actuation shaft **40** returns to its proximal-most position within barrel portion **22** under the bias of constant force spring **54**. Thereupon, a new disposable loading unit can be joined with the instrument and another surgical task performed.

If the surgeon desires to apply parallel rows of staples each measuring about 45 mm in length, disposable loading unit **45** (FIG. **1**) is mounted to the distal end portion of elongated body **14**. After mounting, actuation handle **26** is manipulated through a number of strokes equaling three complete actuation strokes to incrementally advance actuation shaft **40** and control rod **64** a distance of 45 mm. Alternatively, if disposable loading unit **60** is selected for utilization to apply staple rows measuring about 60 mm in length, actuation handle **26** must be manipulated through a number of strokes equaling four complete actuation strokes to incrementally advance actuation shaft **40** and control rod **64** a distance of 60 mm.

Turning to FIGS. **15** and **16**, two alternate embodiments of disposable loading units are shown. Disposable loading unit **410** in FIG. **15** is designed to apply surgical clips. Disposable loading unit **410** has jaw structure **412** and a plurality of clips disposed in housing **414**. Commonly assigned U.S. Pat. No. 5,100,420, the disclosure of which is herein incorporated by reference in its entirety, discloses a manner in which clips can be fed to jaw structure **412** and formed. Disposable loading unit **420** in FIG. **16** is designed to apply individual surgical staples, such as those useful during hernia repair. Disposable loading unit **420** has jaw structure **422** and a plurality of staples disposed in housing **424**. Commonly assigned U.S. Pat. No. 5,289,963, the disclosure of which is herein incorporated by reference in its entirety, discloses a manner in which staples can be fed to jaw structure **422** and formed. Both disposable loading units **410** and **420** are secured to the surgical instrument in a manner similar to the disposable loading units previously described and are actuated by the longitudinal motion of actuation shaft **40** and control rod **64**.

It is readily apparent and may be appreciated by those having ordinary skill in the art that the stroke distance traveled by the actuation shaft may be adjusted in accordance with desired surgical practices. For example, it may be desirable to employ disposable loading units which apply parallel staple rows measuring 40 mm, 60 mm, or 80 mm. Thus, the incremental stroke distance traveled by the actuation shaft could be adjusted to approximately 20 mm intervals. In addition, one skilled in the art could provide alternate structure or orientation of structures to control the advancement of control rod **64**. For example, toothed rack **42** could be rotated so the teeth face downward towards the handles and the locks and pawls moved to engage the rack from the underside. Also, various safety mechanisms can be added, such as a lockout in the handle that needs to be released prior to actually firing a disposable loading unit. These and other features are described in greater detail, below.

Referring now to FIG. **17**, there is illustrated another surgical stapling apparatus constructed in accordance with a preferred embodiment of the subject application and designated generally by reference numeral **500**. As in the previously described embodiment, surgical stapling apparatus **500** is configured to engage body tissue, apply a plurality of surgical fasteners thereto, and form an incision in the fastened body tissue during a laparoscopic surgical procedure. The apparatus is preferably configured to operate with individual disposable loading units that apply linear rows of staples measuring 30 mm, 45 mm, or 60 mm in length (see generally FIG. **1**), or other types of disposable loading units (see, generally FIGS. **15** and **16**).

As illustrated in FIG. **17**, surgical stapler **500** has a handle assembly **512** and an elongated body **514**, and is adapted for use with a disposable loading unit **530**, among other units not shown, which has a carrier **532**, a staple cartridge **534**, and an anvil **536** against which staples are driven when ejected from the cartridge.

Referring to FIG. **18**, as in the previous embodiment, handle assembly **512** includes a housing **520** defined by a barrel portion **522**, a stationary handle **524**, and a pivoting actuation handle **526**. Actuation handle **526** is supported in housing **520** by pivot pin **528** and is biased away from stationary handle **524** by a torsion spring **538**. Actuation handle **526** controls the linear movement of actuation shaft **540** which is supported within the barrel portion **522** of housing **520**. More particularly, actuation shaft **540** has a toothed rack **542** defined on an undersurface thereof and actuation handle **526** is provided with a pawl **544** which is mounted to selectively engage toothed rack **542** and advance the actuation shaft **540** in a distal direction in response to manipulation of actuation handle **526** through an actuating stroke. Pawl **544** is mounted to actuation handle **526** by a pivot pin **546** and is biased toward toothed rack **542** by a coiled torsion spring **548**. The mounting portion of pawl **544** is curved to interact with an abutment wall **545** defined within the housing **520** of handle assembly **512**. More particularly, when the curved mounting portion of pawl **544** contacts abutment wall **545**, the pawl is rotated out of engagement with the toothed rack **542** of actuation shaft **540**.

Actuation shaft **540** is normally biased in a proximal direction within barrel portion **522** by a constant force spring **554** which is supported on a boss **556** provided within housing **520**. A notched area **555** is formed in the upper surface of actuation shaft **540** adjacent the proximal end thereof for receiving and retaining an engagement tab **557** provided at the free end of constant force spring **554**. The distal end of actuation shaft **540** is provided with a catchment fitting **558** for engaging the flanged proximal end **564***p* of control rod **564**. Control rod **564** extends from the handle assembly **512** through the elongated body portion **514** to interact with the disposable loading unit **530** supported at the distal end of the body portion. Accordingly, manipulation of actuation handle **526** causes corresponding longitudinal translation of the actuation shaft **540** and control rod **564** to actuate the disposable loading unit in a manner which will be discussed in detail hereinbelow.

With continuing reference to FIG. **18**, the proximal end of the elongated body portion **514** of surgical stapler **500** has an annular flange **566** formed thereon which is received in a

corresponding annular recess **568** formed within the barrel portion **522** adjacent the distal end thereof. This connection facilitates rotational movement of body **514** relative to handle assembly **512** about a longitudinal axis extending therethrough. A collar **570** is fixedly mounted to body portion **514** by at least one protuberance **572** to effectuate the axial rotation of body portion **514** and thereby increase the operational range of surgical stapler **500**.

As in the previously described embodiment, surgical stapler **500** includes a rack lock (or engagement member) **580** which interacts with the toothed rack **542** of actuation shaft **540** to selectively maintain the longitudinal position thereof within barrel portion **522** against the bias of constant force spring **554**. Rack lock **580** is mounted in such a manner so as to move into a position to interact with toothed rack **542** only when a disposable loading unit has been inserted into the distal end of body portion **514**. More particularly, rack lock **580**, which is mounted on a pivot pin **583** and biased toward the toothed rack **542** by a coiled torsion spring **585**, is maintained in a non-interactive position by an abutment strut **582** until a disposable loading unit is loaded into the device. Abutment strut **582** is mounted on a securement flange **586** formed at the proximal end of a support tube **588** which is mounted for axial translation within body portion **514** (see FIG. **21**). A coiled biasing spring **592** connects abutment strut **582** to a boss **593** in the housing **520** of handle assembly **512**, and, in effect, biases the support tube **588** in a distal direction so that upon insertion of a disposable loading unit, support tube **588** and abutment strut **582** are shifted in a proximal direction.

More specifically, as illustrated in FIG. **22**, prior to insertion of loading unit **530**, an arcuate camming finger **596** which projects proximally from abutment strut **582** is in contact with a distal portion of an angled camming surface **598** defined on rack lock **580**. At such a time, rack lock **580** is maintained in a non-interactive position against the bias of coiled torsion spring **585**. Thereafter, as shown in FIG. **23**, when loading unit **530** is inserted into the distal end of body portion **514** and rotated to engage the bayonet connection associated therewith (stems **628***a* and **628***b*, slots **630***a* and **630***b*), support tube **588** and abutment strut **582** are urged proximally against the bias of coiled spring **592** (and coiled spring **597**). As a result, the proximal camming finger **596** translates in a proximal direction along camming surface **598**, permitting rack lock **580** to rotate about pin **583** under the bias of torsion spring **585** into an interactive position in which the toothed rack **542** of actuation shaft **540** may be engaged upon the distal translation thereof.

As illustrated in FIGS. **22** and **23**, a second abutment strut **584** is disposed opposite abutment strut **582** and is connected to the proximal end of support tube **588** in the same manner as abutment strut **582**. Abutment strut **584**, and the spring **597** which is associated therewith and connected to housing **520** by boss **591**, provide additional biasing force to securely maintain the bayonet connection between the disposable loading unit **530** and the body portion **514**.

Referring to FIG. **19**, an elongated slot **602** extends along a portion of support tube **588** and a transverse groove **604** extends along the axial bore **606** of body portion **514** to accommodate a support pin **608** which extends radially outwardly from the central portion of control rod **564**. This connection permits longitudinal movement of support tube **588** with respect to body portion **514** and control rod **564** while maintaining the respective angular orientation of the three coaxial structures to facilitate their axial rotation by collar **570**.

Turning now to FIG. **24**, there is illustrated disposable loading unit **530** which is constructed in a manner that is substantially similar to the loading unit illustrated in FIG. **3**. It includes a carrier **532** having an elongated support channel **610** for supporting staple cartridge **534** and anvil **536** and a mounting portion **620** which is configured for releasable engagement in the distal end of body portion **514**. More particularly, the proximal end portion **626** of mounting portion **620** is provided with a pair of coupling stems **628***a* and **628***b* which interact with the J-shaped coupling slots **630***a* and **630***b* formed at the distal end of body portion **514** (see, for example, FIG. **26**). The coupling stems and J-shaped slots together define the conventional bayonet-type coupling which facilitates the engagement and removal of the loading unit from the stapler. As in the previous embodiment, an axial bore **625** extends through the proximal end **626** of mounting portion **620** to receive the distal end portion **564***d* of control rod **564**.

As in the previous embodiment, disposable loading unit **530** includes an axial drive assembly **660** which, among other things, transmits the longitudinal drive forces exerted by control rod **564** to the actuation sled **640** disposed within the spaced apart longitudinal slots **642** that extend through staple cartridge **534**. A plurality of staple pushers **643** are operatively associated with slots **642** and are sequentially contacted by actuation sled **640** as it is driven through staple cartridge **534** by drive assembly **660**. The staple pushers interact with the plurality of staples housed within staple cartridge **534** to sequentially eject the staples therefrom.

Drive assembly **660** includes a bifurcated drive beam **662** having a distal working head **664** and a proximal engagement section **665** that includes a pair of engagement fingers **666***a* and **666***b* (see FIG. **25**) configured to mountingly engage a drive block **668**. Drive block **668** has a proximal porthole **670** for receiving the distal end **564***d* of control rod **564** when the proximal mounting portion **626** of loading unit **530** is inserted into the distal end of elongated body portion **514**, as illustrated, for example, in FIG. **27**.

Referring to FIG. **20**, the distal end portion **564***d* of control rod **564** is formed with a flange **667** having a pair of diametrically opposed notches **669***a* and **669***b* dimensioned to accommodate the two opposed engagement fingers **666***a* and **666***b* when the control rod is received in the proximal portal **670** of drive block **668**, as best seen in FIGS. **26** and **29**. Thereafter, as illustrated in FIGS. **28** and **30**, when loading unit **530** is rotated through approximately a **20**' axial turn to engage coupling stems **628***a* and **628***b* within J-shaped coupling slots **630***a* and **630***b*, engagement fingers **666***a* and **666***b* are moved out of alignment with engagement notches **669***a* and **669***b*, and flange **667** is secured from exiting disposable loading unit **530** until its removal from surgical stapler **500**. As seen when comparing FIG. **27** to FIG. **28**, the interior cavity **671** of drive block **668** is dimensioned to accommodate the extension of the distal portion **564***a* of control rod **564** into portal **670** during the insertion of the loading unit **530** into the distal end of body portion **514**.

Referring again to FIG. **24**, the working head **664** of drive assembly **660** is defined in part by vertical support strut **672** which supports a knife blade **674**, and defines an abutment surface **675** for engaging actuation sled **640**. A retention flange **678** projects distally from support strut **672** to retain a cam roller **680** which is configured to translate along the exterior camming surface **682** of anvil **536** during a stapling procedure to effect closure of the anvil against the bias of anvil spring **676**. A longitudinal slot **684** extends through anvil **536** to accommodate the translation of retention flange **678**, and a similar slot **692** is formed in the base **612** of

channel **610** to accommodate the translation of retention foot **688** which supports balancing flange **686**. Flange **686** serves to balance the clamping forces exerted by cam roller **680** on anvil **536**. As in the previous embodiment, an anvil cover (not shown) can be provided to protect tissue from contacting components traveling along the exterior surface **682** of anvil **536** during a stapling procedure.

Referring to FIGS. **24** and **25**, disposable loading unit **530** is provided with a lockout assembly **700** configured to operate in two distinct stages. In brief, during the first stage of operation, the lockout assembly functions to limit the longitudinal movement of control rod **564** with respect to the axial drive assembly **660** (see FIG. **46**). In the second stage of operation, i.e., after the disposable loading unit has been removed from the apparatus following a stapling procedure, the lockout assembly serves to prevent subsequent utilization of the loading unit by blocking the entry of control rod **564** into the proximal portal **670** of drive block **668** (see FIG. **51**).

As best seen in FIG. **25**, preferred lockout assembly **700** includes a blocking plate **710** having a pair of parallel support arms **712***a* and **712***b* which depend distally therefrom. A central aperture **716** is formed in blocking plate **710** which is dimensioned and configured to accommodate the longitudinal translation of control rod **564**. Aperture **716** includes diametrically opposed slots **717***a* and **717***b* to accommodate the engagement fingers **666***a* and **666***b* of the proximal portion **665** of actuation beam **662**. A retention spring **718** is connected to blocking plate **710** through the engagement of a pair of spaced apart tabs **720***a* and **720***b* with a pair of corresponding ports **722***a* and **722***b*. Retention spring **718** includes a mounting flange **724** for securing the spring to a mounting area **725** on the interior surface of the mounting portion **620** of disposable loading unit **530** (see FIG. **26**). The proximal end portion of retention spring **718** is defined by a pair of spaced apart camming ramps **726***a* and **726***b* which are angled proximally to interact with the distal flange **667** of control rod **564** when disposable loading unit **530** is removed from the apparatus (see generally FIG. **47**).

Lockout assembly **700** further includes a support plate **730** having a pair of depending arms **732***a* and **732***b* which interact with the support arms **712***a* and **712***b* of blocking plate **710** to maintain the blocking plate in a non-blocking position against the bias of retention spring **718** (see FIG. **26**). Support plate **730** is formed with a central slotted region **733** which accommodates the lower portion of drive beam **662**. A detent **734** is formed within slotted region **733** for interacting with distal and proximal complementary recesses **735***a* and **735***b* formed in the lower portion of drive beam **662**.

In use, when drive beam **662** is driven distally, as shown for example in FIG. **44**, support plate **730** is drawn therewith through the engagement of detent **734** with proximal recess **735***b*. As a result, blocking plate **710** is released and translates in a direction transverse to the longitudinal axis of control rod **564** under the bias of retention spring **718**. As shown for example in FIG. **45**, while control rod **564** is extending through aperture **716**, blocking plate **710** remains in a non-blocking position. However, when control rod **564** is fully retracted to open anvil **536** after a stapling procedure, blocking plate **710** moves into a limiting position, engaging the distal portion **564***d* of control shaft **564**, as illustrated in FIG. **46**. In this position, blocking plate **710** effectively limits the range of longitudinal motion of control rod **564**, the range being defined by the reduced diameter portion at the distal end of control rod **564**.

Upon full withdrawal of flange **667** from drive block **668**, blocking plate **710** is free to translate into a full blocking position under the bias of retention spring **718** to block the proximal portal **670** of drive block **668**, as illustrated in FIG. **49**. The function of lockout assembly **700** and its interaction with control rod **564** and axial drive assembly **660** will be discussed in further detail hereinbelow.

Referring now in sequential order to FIGS. **31-38**, to initiate operation of surgical stapler **500**, a desired disposable loading unit of a particular size and kind is selected from a group of different units and loaded into the distal end of body portion **514**, The loading unit, i.e., loading unit **530**, is mounted to stapler **500** by inserting the proximal mounting portion **626** into the distal end of body portion **514** and rotating the unit to securely engage the bayonet connection (see FIGS. **22** and **23**). A preferred degree of rotation is between about 5' and about 40', while about 20' is most preferred. At such a time, support tube **588** is urged proximally from the position shown in FIG. **22** to that which is illustrated in FIG. **23**. As a result, rack lock **580** is moved into an interactive position shown in FIG. **31**, wherein the toothed rack **542** of actuation shaft **540** may be engaged upon the distal advancement thereof. As illustrated in FIG. **31**, when actuation shaft **540** is in its proximal-most position biased by constant force spring **554**, anvil **536** is in an open position to receive body tissue such as tubular vessel **750**. At such a time, pawl **544** is engaged in the distal-most tooth on toothed rack **542** and actuation handle **526** may be manipulated against the bias of spring **538** to advance the toothed rack.

As best seen in FIG. **32**, upon initial manipulation of actuation handle **526** through a first segment of the actuation stroke (i.e., the clamping stroke segment), actuation shaft **540** is driven in a distal direction by the interaction of pawl **544** and toothed rack **542**. Thereupon, the engagement hook **752** of rack lock **580** engages a keeper notch **754** formed adjacent the distal fastening portion **558** of actuation shaft **540**. At such a time, anvil **536** is moved to a closed position by the advancement of cam roller **680** along the proximal camming portion of anvil surface **682**, and the proximal end of engagement hook **752** is in abutment with a buttress **755** formed on the under surface of actuation shaft **540**. As a result, further distal translation of actuation shaft **540** is prohibited and anvil **536** is maintained in a clamped position.

If, at a such a time, the user of the apparatus desires to unclamp tubular vessel **750** by opening anvil **536**, this can be accomplished through the manipulation of a retraction mechanism (described below) associated with handle assembly **512** which serves to disengage rack lock **580** and pawl **544** from actuation shaft **540** to permit the user to draw the actuation shaft in a proximal direction, as illustrated in FIG. **33**.

Referring back to FIG. **18**, the retraction mechanism preferably includes a pair of retractor knobs **760***a* and **760***b* which are connected to the proximal end of actuation shaft **540** by a coupling rod **762**. Coupling rod **762** includes right and left engagement portions **764***a* and **764***b* for receiving retractor knobs **760***a* and **760***b* and a central portion **764***c* which is dimensioned and configured to translate within a pair of longitudinal slots **766***a* and **766***b* formed in actuation shaft **540** adjacent the proximal end thereof. A release plate **768** is operatively associated with actuation shaft **540** and is mounted for movement with respect thereto in response to manipulation of retractor knobs **760***a* and **760***b*. More particularly, a pair of spaced apart pins **767***a* and **767***b* extend outwardly from a lateral face of actuation shaft **540** to engage a pair of corresponding angled cam slots **769***a* and **769***b* formed in release plate **768**. The cam slots define the path through which the release plate moves with respect to the actuation shaft **540**, and more specifically, with respect to the toothed rack **542**. A transverse slot **770** is formed at the proximal end of release plate **768** to accommodate the central

portion **760***c* of coupling rod **762**, and elongated slots **772** and **774** are defined in the barrel section **522** of handle assembly **520** to accommodate the longitudinal translation of coupling rod **762** as retraction knobs **760***a* and **760***b* move in conjunction with actuation shaft **540**. Coupling rod **762** is biased distally by spring **765***a* which is secured at one end to coupling rod portion **764***c* and at the other end to post **765***b* on actuation shaft **540**.

Referring again to FIG. **33**, when it is desirable to open anvil **536** to release the clamped body tissue **750**, the user of apparatus **500** pulls retraction knobs **760***a* and **760***b* proximally, whereupon release plate **768** translates in a generally proximal direction along the path of angled cam slots **769***a* and **769***b* (see generally FIGS. **39** and **40**). Consequently, the release plate urges the engagement hook **752** of rack lock **580** out of keeper notch **754** and forces pawl **544** out of engagement with toothed rack **542**. At such a time, the user can draw actuation shaft **540** in a proximal direction, causing cam roller **680** to be drawn proximally with actuation beam **662**. As a result, anvil **536** moves to an open position under the bias of anvil spring **676** and actuation handle **526** returns to a neutral position under the bias of torsion spring **538**. Once actuation shaft **540** has been returned to its proximal-most position, stapling apparatus **500** is in a reset condition.

Referring now to FIG. **34**, to clamp body tissue **750** once again, actuation handle **526** is manipulated through the clamping segment of an actuation stroke to drive actuation shaft **540** distally until the engagement hook **752** of rack lock **580** is once again engaged in keeper notch **754** and in abutment with buttress **755**. If, at such a time, the user of apparatus **500** is confident that the stapling procedure can commence, rack lock **580** must be manually released from keeper notch **754** to permit subsequent distal movement of actuation shaft **540**. This is accomplished by way of a manual release mechanism operatively associated with handle assembly **512** which interacts with the proximal release tail **757** of rack lock **580**, as shown in FIG. **35**. The details of a preferred construction of rack lock (or engagement member) **580** are illustrated in FIG. **43**.

Referring back once again to FIG. **18**, the manual release mechanism preferably includes a pivoting release member **780** mounted on a boss **784** and biased away from the release tail **757** of rack lock **580** by a coiled torsion spring **786**. A pair of opposed winglets, i.e., winglet **788**, project laterally from release member **780** to support release knobs **790***a* and **790***b*, respectively. Release member **780** has a downturned nose **792** which is dimensioned to contact the release tail **757** of rack lock **580** when release knobs **790***a* and **790***b* are manipulated by the user in the direction indicated by arrow "A" in FIG. **35**.

Referring once again to FIG. **35**, upon manipulation of release knobs **790***a* and **790***b* and the consequential liberation of rack lock **580**, actuation shaft **540** is free to translate in a distal direction in response to manipulation of actuation handle **526**. At such a time, the linear position of actuation shaft **540** is maintained through the engagement of pawl **544** and toothed rack **542**.

Turning to FIG. **36**, manipulation of actuation handle **526** toward stationary handle **524** through a stapling stroke segment causes pawl **544** to advance toothed rack **542**, and hence actuation shaft **540** and control rod **564**, in a distal direction. As a result, the axial drive assembly **660** supported within loading unit **530** is driven distally to cause actuation sled **640** to intersect with pushers **643** to sequentially eject staples from cartridge **534**. At the same time, knife blade **674** travels behind actuation sled **640**, forming an incision in the stapled body tissue. As shown in FIG. **36**, one complete stapling stroke effects firing of only a portion of the staples within cartridge **534**. As previously described, multiple partial strokes can also be used to incrementally advance drive rod **564**, i.e. pawl **544** can advance rack **542** one tooth at a time.

Referring to FIG. **37**, all of the staples within cartridge **534** are ejected and applied to tubular vessel **750**. If a loading unit having a greater length had been employed with stapling apparatus **500**, additional stapling strokes would have been required to advance actuation shaft **540** further. In total, the toothed rack **542** of actuation shaft **540** is preferably dimensioned to accommodate at least four complete stapling strokes of 15 mm each. Thus, if each complete stapling stroke of actuation handle **526** advances the actuation shaft 15 mm, stapling apparatus **500** can be used to fire disposable loading units that are configured to apply staple lines of 15 mm, 30 mm, 45 mm, and 60 mm using a whole number of complete strokes.

Referring now to FIG. **38**, at the conclusion of the stapling procedure, to move anvil **536** to an open position and release stapled body tissue **750** from surgical apparatus **500**, the user once again employs the retraction knobs **760***a* and **760***b* associated with the barrel portion **522** of handle assembly **520**. More particularly, as best seen in FIGS. **39-42** proximal retraction of knobs **760***a* and **760***b* causes coupling rod **762** (FIG. **18**) to translate proximally within the longitudinal slots **766***a* and **766***b* formed at the proximal end of actuation shaft **540**. As a result, release plate **768** translates along an angled path defined by cam slots **769***a* and **769***b*, urging the engagement hook **752** of rack lock **580** and the pawl **544** (not shown) out of engagement with toothed rack **542**. Thereupon, as illustrated in FIG. **38**, actuation shaft **540** is free to translate in a proximal direction under the bias of the user and constant force spring **554**. Consequently, the axial drive assembly **660** within disposable loading unit **530** is drawn proximally by the head of control rod **564**, and anvil **536** moves to an open position as cam roller **680** is retracted.

Referring now to FIG. **45**, as control rod **564** is withdrawn in a proximal direction from its distal-most position illustrated in FIG. **44**, blocking plate **710** rides along control rod **564** and is maintained in an upright position against the bias of retention spring **718**. However, as illustrated in FIG. **46**, as reduced diameter distal end portion **564***d* of control rod **564** approaches its proximal-most position, blocking plate **710** is urged toward the control rod such that the peripheral edge of aperture **716** engages distal end portion **564***d* of control rod **564** (see also FIG. **50**). Further proximal movement of control rod **564** draws drive block **668** to its proximal-most position illustrated in FIG. **47**, wherein flange **667** interacts with camming ramps **762***a* and **762***b* of retention spring **718** and at least partially lifts blocking plate **710**. At such a time, distal movement of control rod **564** is limited due to interaction between blocking plate **710** and the larger diametered ledge where the proximal end of **564***d* meets the larger diameter of rod **564**. However, control rod **564** is still afforded a limited range of longitudinal motion along reduced diameter portion **564***d* of control rod **564** so that anvil **536** can be moved between open and closed positions. Accordingly, anvil **536** may be easily closed to facilitate removal of surgical apparatus **500** through a trocar or cannula device.

As best seen in FIG. **47**, when axial drive assembly **660** and the drive block **668** associated therewith assume their proximal-most position, the detent **734** on support plate **730** engages distal recess **735***a*. At such a time, support plate **730** is securely retained in its final rest position to prevent the plate from floating within disposable loading unit **530** after it has been removed from surgical apparatus **500**.

Referring to FIG. **48**, to remove disposable loading unit **530** from the distal end of body portion **514**, the loading unit

is shifted proximally and rotated to disengage the bayonet coupling. Simultaneously, the engagement fingers **666***a* and **666***b* are re-aligned with the notches **669***a* and **669***b* in flange **667**. The flange can now further bias locking plate **710** upward, allowing for the removal of disposable loading unit **530** from the distal end of body portion **514**. As soon as flange **667** moves past caroming ramps **762***a* and **762***b* and blocking plate **710**, the blocking plate is free to translate into a full blocking position under the bias of retention spring **718**. In this position, which is best seen in FIG. **51**, entry of the distal end of control rod **564** into the proximal portal **670** of drive block **668** is advantageously prohibited. Accordingly, a fired or partially fired disposable loading unit cannot be subsequently utilized after it has been removed from surgical apparatus **500**.

Although the subject invention has been described with respect to preferred embodiments, it will be readily apparent to those having ordinary skill in the art to which it appertains that changes and modifications may be made thereto without departing from the spirit or scope of the subject invention as defined by the appended claims.

What is claimed is:

1. A surgical tool for applying staples, comprising:

a body having a connection portion at one end and first and second jaws supported at an opposite other end, the first jaw having a plurality of staples arranged in rows, and the second jaw having an anvil, the first and second jaws having an open position and a closed position;

a drive member supporting a cam member at a distal end, wherein the cam member is positioned to engage the second jaw, the drive member including an elongated drive beam, wherein the drive member includes a balancing flange positioned to engage the first jaw to balance clamping forces generated by the cam member as tissue is progressively clamped between the first and second jaws; and

a handle assembly connectable to the connection portion, the handle assembly having a toothed actuation shaft and a pawl for engaging the actuation shaft and incrementally advancing the actuation shaft, the drive member being connected to the actuation shaft when the handle assembly is connected to the connection portion of the body.

2. The surgical tool according to claim **1**, wherein the first jaw includes a longitudinal slot for accommodating the drive member.

3. The surgical device according to claim **1**, wherein the handle assembly includes a pivotable handle.

4. The surgical device according to claim **1**, wherein the first jaw includes a surgical stapling cartridge.

5. The surgical device according to claim **1**, wherein the drive member includes a knife.

6. The surgical device according to claim **1**, wherein the drive member has a distal working head.

7. The surgical device according to claim **1**, wherein the drive member includes a vertical strut and a retention flange projecting distally from the vertical strut, the cam member being disposed on the retention flange.

8. The surgical device according to claim **1**, wherein the second jaw is pivotable with respect to the first jaw.

9. The surgical device according to claim **1**, wherein the anvil defines a plurality of staple forming recesses.

10. The surgical device according to claim **1**, wherein the cam member is a cam roller.

11. The surgical device according to claim **1**, wherein the handle assembly includes a release mechanism.

12. The surgical device according to claim **11**, wherein the actuation shaft is biased in a proximal direction.

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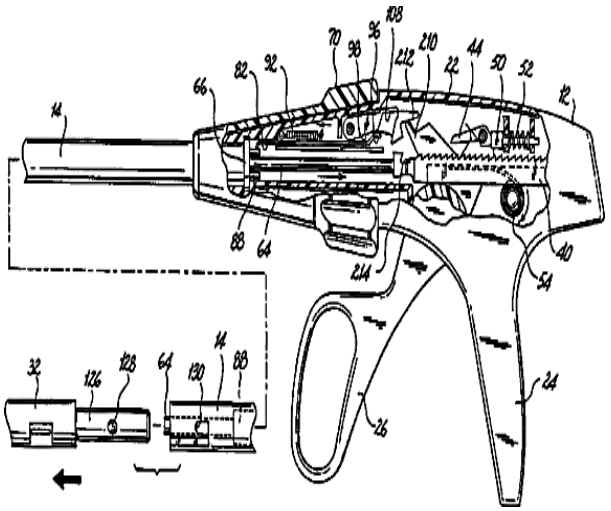
专利名称(译)	外科缝合器		
公开(公告)号	US8740035	公开(公告)日	2014-06-03
申请号	US13/905471	申请日	2013-05-30
[标]申请(专利权)人(译)	柯惠有限合伙公司		
申请(专利权)人(译)	COVIDIEN LP		
当前申请(专利权)人(译)	COVIDIEN LP		
[标]发明人	MASTRI DOMINICK L VIOLA FRANK J ALESI JR THOMAS W GEISTE ROBERT J WILSON JON		
发明人	MASTRI, DOMINICK L. VIOLA, FRANK J. ALESI, JR., THOMAS W. GEISTE, ROBERT J. WILSON, JON		
IPC分类号	A61B17/072 A61B17/068 A61B17/68		
CPC分类号	A61B17/072 A61B17/07207 A61B2017/2923 A61B2017/07271 A61B2017/0688 A61B2017/0046 A61B2017/07214 A61B2017/07285		
审查员(译)	SMITH，SCOTT A.		
优先权	13/414185 2012-09-25 US 13/210470 2012-04-24 US 12/794925 2011-09-06 US 12/644450 2011-03-29 US 12/118924 2010-08-10 US 11/903586 2009-01-06 US 11/590441 2007-10-09 US 11/186743 2006-10-31 US 11/011355 2006-05-16 US 09/625886 2006-01-17 US 09/119543 2000-03-07 US 08/546253 1998-07-21 US 08/520202 1998-06-09 US		
其他公开文献	US20130256384A1		
外部链接	Espacenet USPTO		

摘要(译)

本文描述了一种手术装置，其可用于发射不同类型和尺寸的一次性装载单元。在优选实施例中，该装置将平行排的外科紧固件施加到身体组织上，并在内窥镜或腹腔镜外科手术过程中伴随地在各排钉之间形成切口。该装置可以与一次性装载单元一起使用，该一次性装载单元构造成应用线性行的钉，其长度从大约15mm到大约60mm，并且可以用于发射包含手术夹和单个钉的一次性装载单元。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