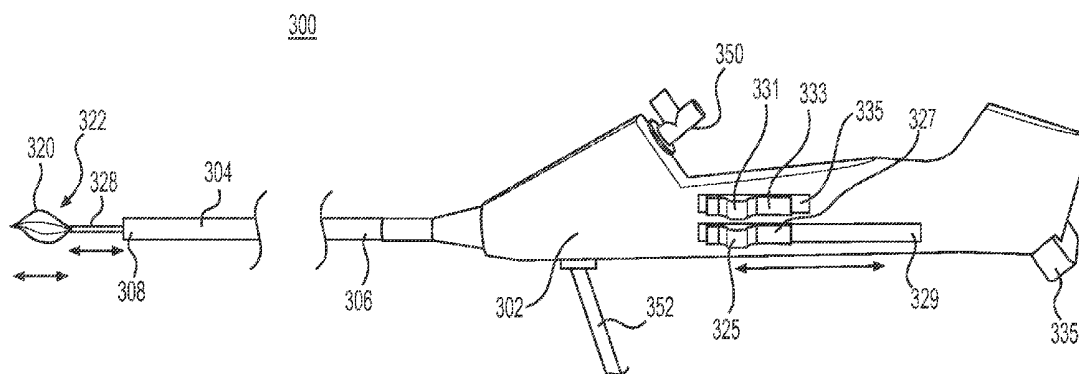


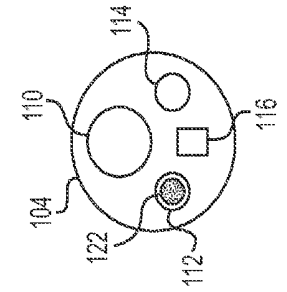
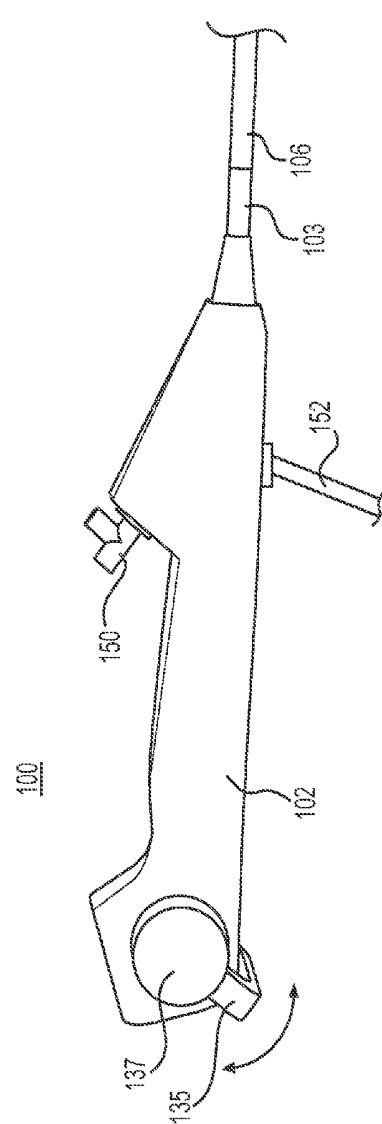
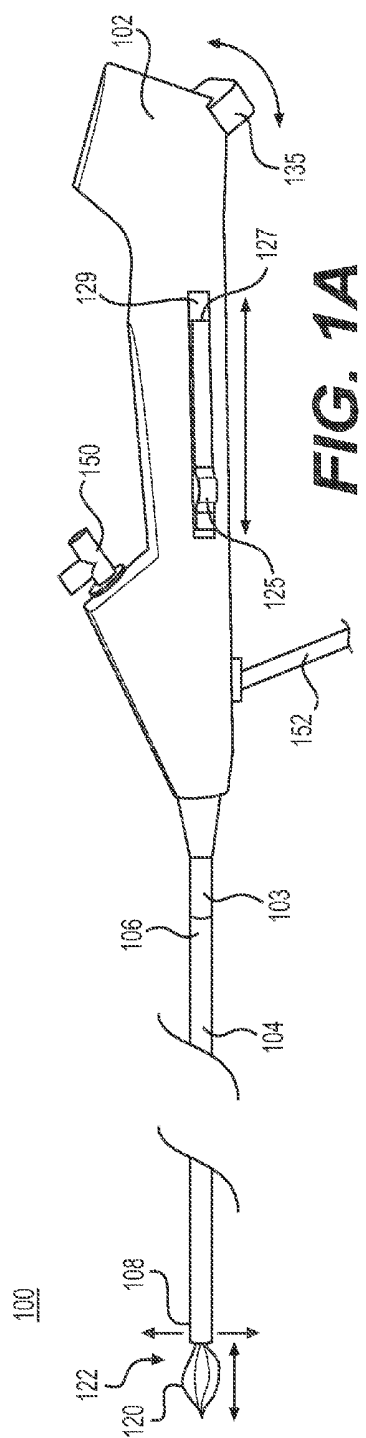


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PROCEDURES AND METHODS OF USE
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Grove, MN (US)(21) Appl. No.: **14/989,283**(22) Filed: **Jan. 6, 2016****Related U.S. Application Data**(60) Provisional application No. 62/106,543, filed on Jan.
22, 2015.(57) **ABSTRACT**

Medical devices performing diagnostic and/or treatment procedures, such as retrieving autogenous materials and/or foreign materials from a patient are disclosed. The medical device may comprise a handle, a shaft coupled to the handle, and a retrieval device movably disposed within a working channel of the shaft. The handle may include a steering mechanism for deflecting a distal end of the shaft and a control mechanism for translating the retrieval device within the working channel. The retrieval device may be integrated into the medical device.





200

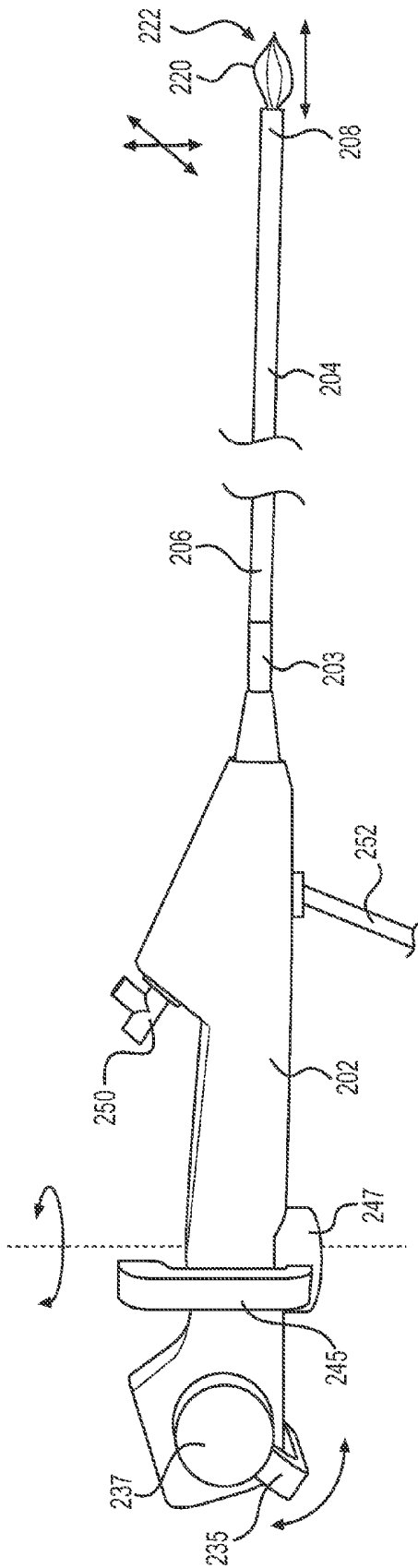


FIG. 2

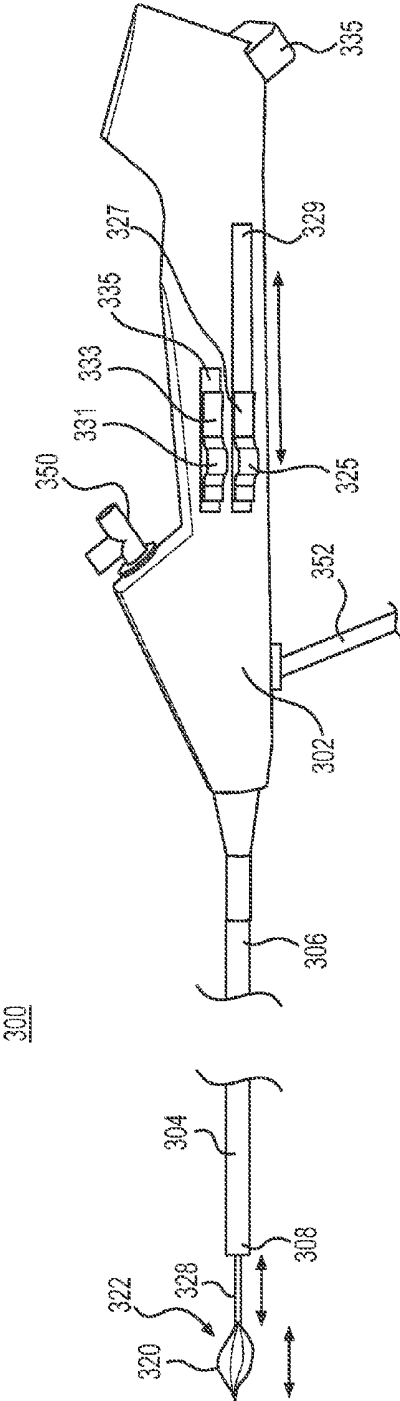


FIG. 3A

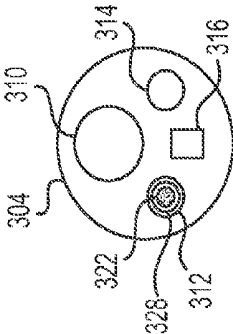
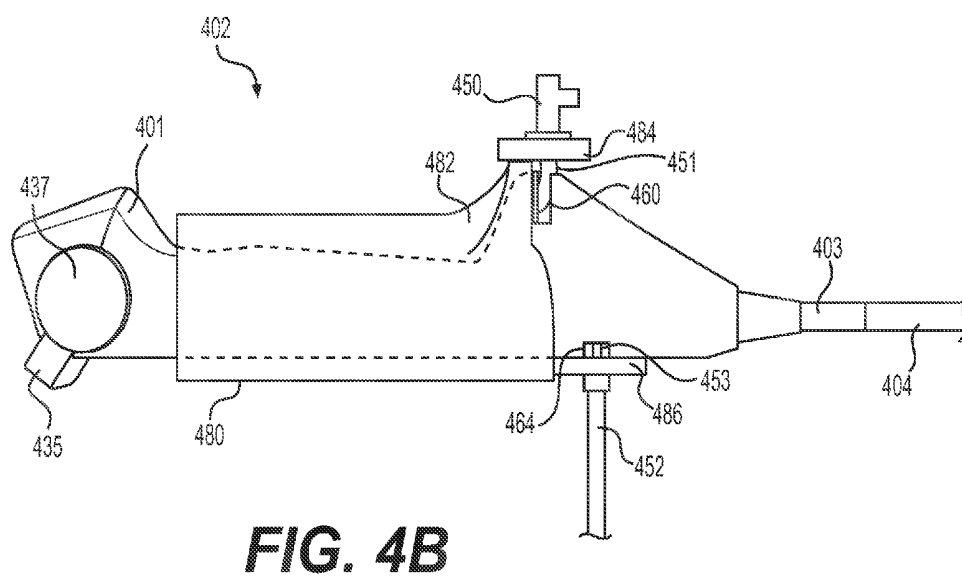
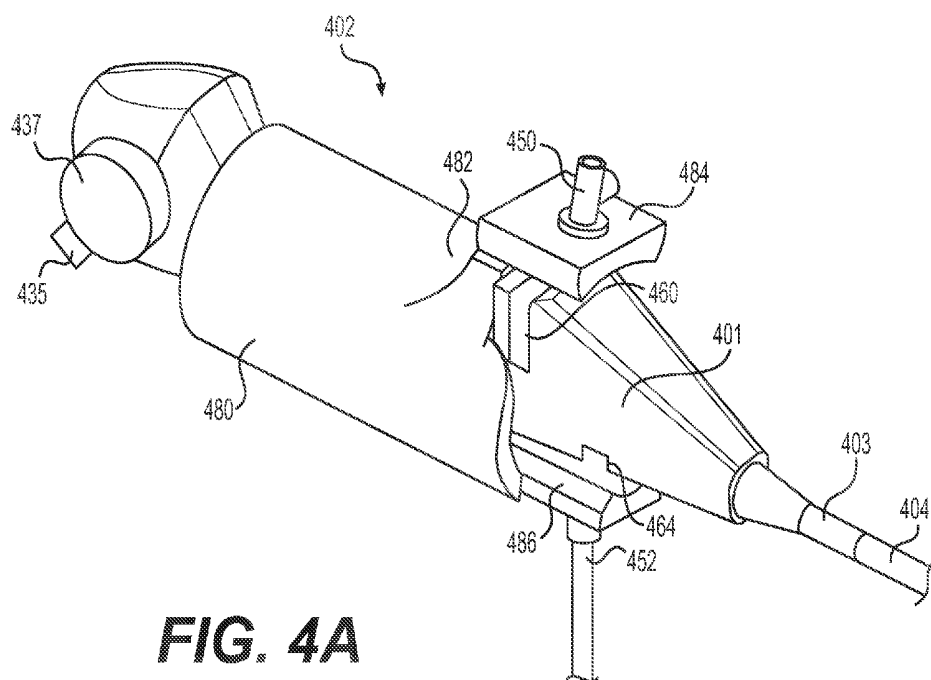


FIG. 3B



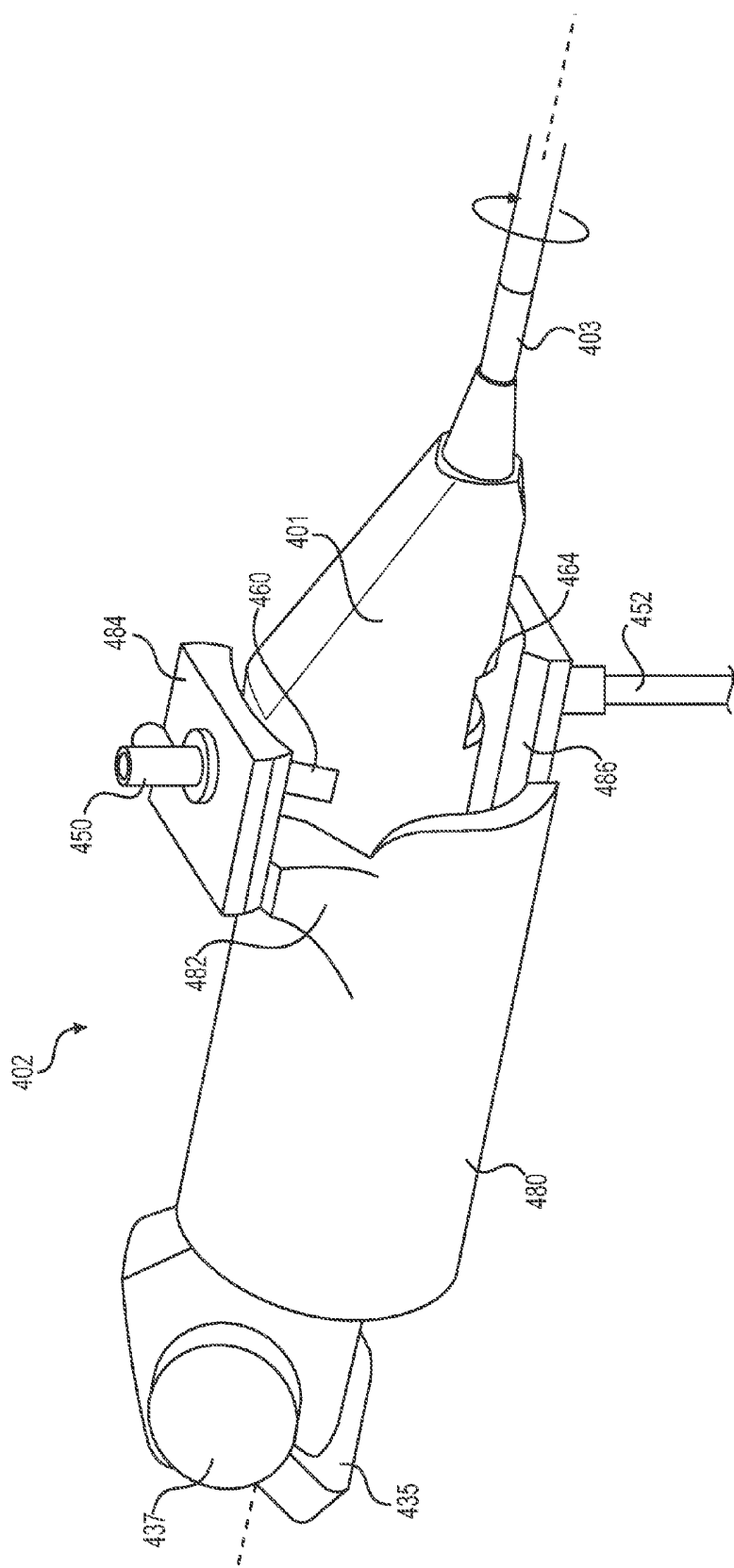


FIG. 4C

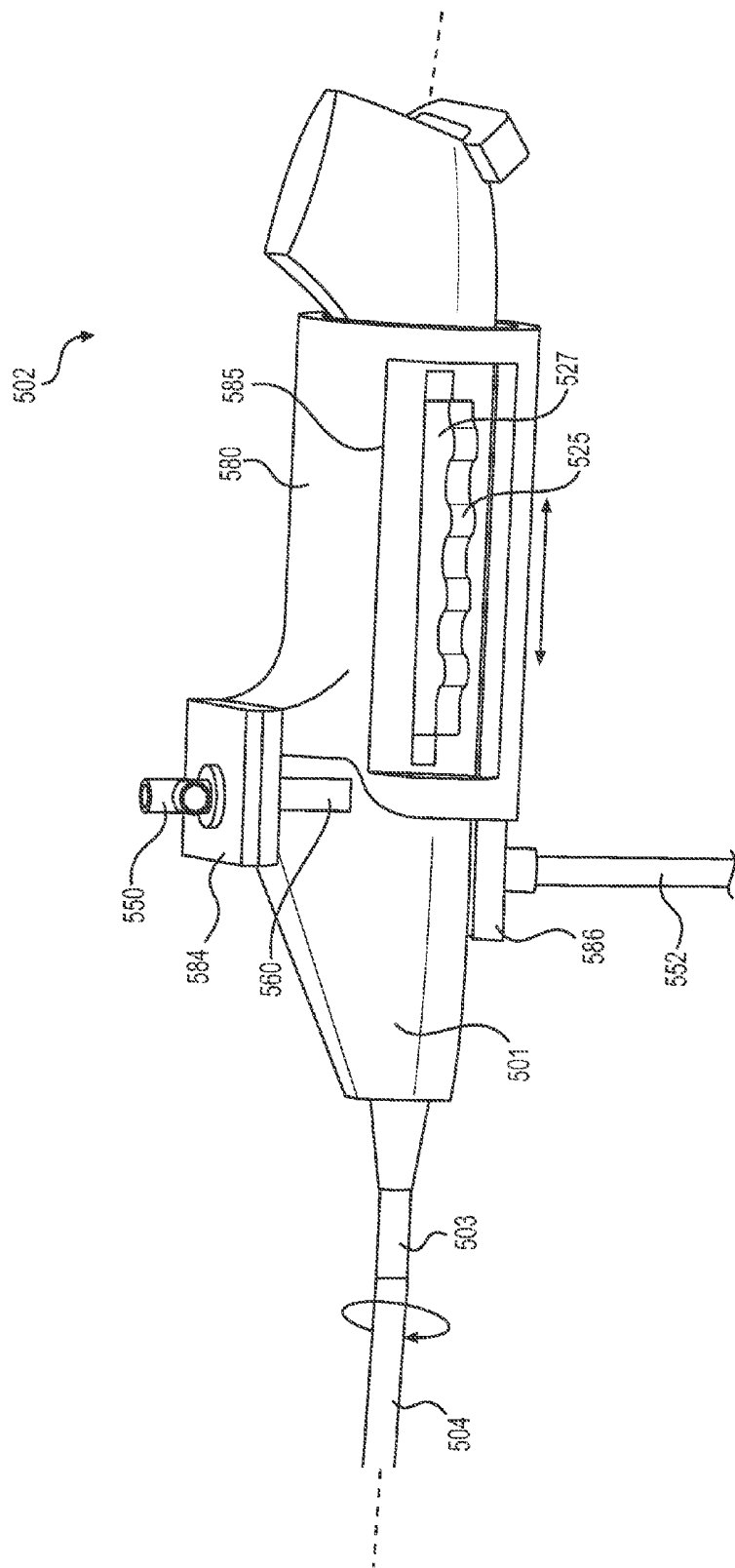


FIG. 5

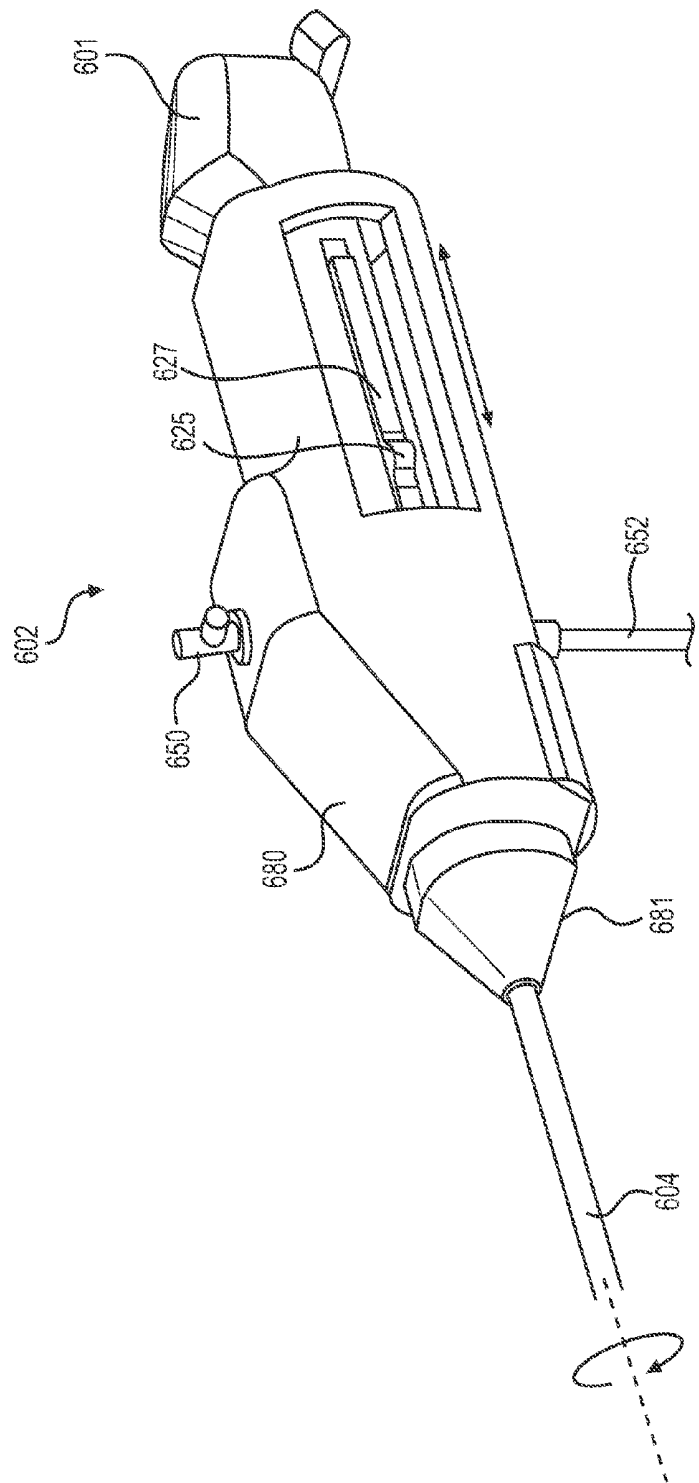


FIG. 6

DEVICES FOR MEDICAL RETRIEVAL PROCEDURES AND METHODS OF USE THEREOF

CROSS-REFERENCE TO RELATED APPLICATIONS

[0001] This patent application claims the benefit of priority under 35 U.S.C. §119 to U.S. Provisional Patent Application No. 62/106,543, filed Jan. 22, 2015, which is herein incorporated by reference in its entirety.

TECHNICAL FIELD

[0002] Various aspects of the present disclosure relate generally to medical devices useful in retrieving and removing tissue or other materials from within a patient. More specifically, the present disclosure includes medical devices with integrated tool manipulation and/or relative rotation capability, and methods of use thereof.

BACKGROUND

[0003] Retrieval devices and systems allow physicians and other medical professionals to remove various materials from a patient, including organic material (e.g., blood clots, tissue, and biological concretions such as urinary, biliary, and pancreatic stones) and inorganic material (e.g., components of a medical device or other foreign matter). For example, concretions can develop in the kidneys, pancreas, ureter, or gallbladder, and cause blockages or other complications within the body. Minimally-invasive medical procedures may be used to remove these materials through a natural orifice, such as lithotripsy and ureteroscopy, or through an incision, such as percutaneous nephrolithotomy.

[0004] Current endoscopic systems have disadvantages, however. For example, ureteroscopic procedures typically require two or more people, wherein a physician controls the ureteroscope with both hands (one hand to grasp the handle and the other to hold the distal portion of the ureteroscope as it enters the urinary tract via the urethral meatus), and an assistant inserts a tool such as a basket, forceps, or a laser through a working channel of the ureteroscope and manipulates the tool. To remove a kidney stone, for example, a ureteroscope is used to gain access to the kidney, and a separate basket device is inserted into the working channel of the ureteroscope to remove or reposition the stone. In order to fragment larger stones into smaller pieces for removal, the basket device can be withdrawn from the working channel and substituted for a laser. After fragmenting the stone, the laser can be removed from the working channel and the basket device reinserted to capture the fragments.

[0005] This technique requires careful coordination. If communication between the physician and assistant is unclear, the assistant may require multiple attempts to successfully fragment and retrieve a stone or other material from the patient. Multiple attempts can increase risk to the patient, increase procedure time, and lead to tool damage for repeated unsuccessful attempts. Further, coordination between multiple people to control separate instruments simultaneously in a limited space can be logistically difficult and inconvenient, requiring awkward gripping and imprecise manipulation of the instruments.

SUMMARY

[0006] The present disclosure includes a medical device comprising a handle; a shaft coupled to the handle, the shaft including a plurality of working channels; and a retrieval device movably disposed within one of the working channels, wherein the handle includes a steering mechanism configured to deflect a distal end of the shaft and a control mechanism configured to translate the retrieval device within the at least one working channel.

[0007] According to some aspects, the retrieval device may include an expandable basket. The control mechanism may include a sliding actuator coupled to the handle for controlling translation of the retrieval device. Additionally or alternatively, the control mechanism may include a locking device for locking a position of the retrieval device.

[0008] The handle may include an outer body coupled to an inner body, wherein the inner body is rotatable relative to the outer body, the inner body being coupled to the shaft. In some aspects, for example, the inner body may be rotatable through an arc of up to about 180 degrees, up to about 120 degrees, up to about 90 degrees, up to about 45 degrees, or up to about 30 degrees. Additionally or alternatively, the handle may include at least one port connector in communication with at least one working channel of the plurality of working channels. For example, the handle may include at least one port connector coupled to the outer body and in communication with at least one working channel of the plurality of working channels, wherein rotating the inner body relative to the outer body does not rotate the at least one port connector. The at least one port connector may include a port connector in communication with the at least one working channel, for example. According to some aspects, the medical device may further include a connector configured for at least one of light or data transmission.

[0009] According to some aspects of the present disclosure, the steering mechanism of the handle may be configured to deflect a distal end of the shaft along a plurality of planes. For example, the handle may include a first actuator for controlling deflection of the distal end of the shaft along a first plane and a second actuator for controlling deflection of the distal end of the shaft along a second plane transverse to the first plane.

[0010] The medical device may further comprise a sheath surrounding at least a portion of the retrieval device, the sheath being disposed within the working channel that includes the retrieval device. The control mechanism of the handle may be configured to translate the retrieval device independently of the sheath. Additionally or alternatively, the control mechanism may be configured to translate the retrieval device and the sheath simultaneously. According to some aspects of the present disclosure, the shaft of the medical device may include at least three working channels. Further, for example, the medical device may be a ureteroscope, wherein the retrieval device is integrated into the ureteroscope.

[0011] According to some aspects, the shaft of the medical device may include a first working channel and a second working channel, wherein the first working channel includes the retrieval device and the second working channel is in communication with one or more port connector of the handle. The handle may include an outer body coupled to an inner body, wherein the inner body is rotatable relative to the outer body and coupled to the shaft. The handle may include at least one port connector coupled to the outer body, for

example, wherein the port may be in communication with the at least one working channel, and wherein rotating the inner body relative to the outer body does not rotate the at least one port connector.

[0012] The present disclosure further includes a medical device comprising a handle including an inner body and an outer body, wherein the outer body at least partially surrounds the inner body; a shaft coupled to the inner body, the shaft including at least one working channel; and a port connector coupled to the outer body, the port connector being in communication with the at least one working channel, wherein the inner body and the shaft are rotatable relative to the outer body and relative to the port connector.

[0013] According to some aspects, the medical device may further comprise a retrieval device disposed within the at least one working channel, wherein the inner body includes a control mechanism for translating the retrieval device within the at least one working channel. The shaft of the medical device may include a first working channel and a second working channel, wherein the first working channel includes the retrieval device and at least one of the first working channel or the second working channel is in communication with the port connector. According to some aspects, for example, the medical device may be a ureteroscope, and the retrieval device may include an expandable basket.

[0014] The present disclosure further includes a medical device comprising a handle; a shaft coupled to the handle, the shaft including at least two working channels; a retrieval device movably disposed within the at least one working channel, the retrieval device including an expandable basket; and a sheath surrounding at least a portion of the retrieval device and disposed within the at least one working channel, wherein the handle includes a steering mechanism configured to deflect a distal end of the shaft and a control mechanism configured to translate each of the retrieval device and the sheath within the at least one working channel, and wherein the medical device is a ureteroscope. According to some aspects, the retrieval device may be integrated into the medical device, such that the retrieval device is not removable from the shaft.

BRIEF DESCRIPTION OF THE FIGURES

[0015] The accompanying drawings, which are incorporated in and constitute a part of this specification, illustrate various exemplary embodiments and together with the description, serve to explain the principles of the disclosed embodiments.

[0016] FIGS. 1A-1C show an exemplary medical device, in accordance with aspects of the present disclosure.

[0017] FIG. 2 shows an exemplary medical device, in accordance with aspects of the present disclosure.

[0018] FIGS. 3A and 3B show an exemplary medical device, in accordance with aspects of the present disclosure.

[0019] FIGS. 4A-4C show an exemplary medical device, in accordance with aspects of the present disclosure.

[0020] FIG. 5 shows an exemplary medical device, in accordance with aspects of the present disclosure.

[0021] FIG. 6 shows an exemplary medical device, in accordance with aspects of the present disclosure.

DETAILED DESCRIPTION

[0022] Embodiments of the present disclosure include medical devices useful in diagnostic and/or treatment proce-

dures, such as retrieving autogenous materials and/or foreign materials from a patient. Medical devices according to the present disclosure may provide for integrated tool manipulation, for example, and/or rotational control without disturbing attachments coupled to the device via an adapter, such as irrigation or suction channels.

[0023] An exemplary medical device **100** according to some aspects of the present disclosure is shown in FIGS. 1A-1C, comprising a handle **102** coupled to a shaft **104**. The medical device **100** may be suitable for use in ureteroscopy, for example, but may be configured for use in other procedures and for diagnosis/treatment of other areas of a patient's body. The handle **102** may have any shape suitable for gripping and controlling the medical device **100**. For example, the handle **102** may have an ergonomic shape designed to be held comfortably in the hand, e.g., the palm of the hand. The shaft **104** extends from a proximal end **106** to a distal end **108**, such that the proximal end **106** of the shaft may be coupled to (e.g., detachably or permanently connected to) the distal end **103** of the handle **102**. The handle **102** and/or the shaft **104** may be disposable.

[0024] The medical device **100** may include a steering mechanism for deflecting the shaft **104** along one or more planes. For example, the handle **102** may include an actuator **135** coupled to one or more portions of the shaft **104** at or near the distal end **108** of the shaft **104** via one or more control members, such as steering wires (not shown). Any suitable steering mechanism and/or actuators may be used, including those disclosed in U.S. Patent Application Publication No. 2013/0190561, incorporated by reference herein. The actuator **135** may be pivotably coupled to the handle **102** via a post **137**, as shown in FIG. 1B, such that pivoting the actuator **135** about the post **137** moves the distal end **108** of the shaft **104** along a plane (e.g., left/right or up/down). According to some aspects, the actuator **135** may include a locking device, such that the actuator **135** may be locked in place when the distal end **108** of the shaft **104** is in a desired position.

[0025] The shaft **104** may include at least one working channel, for example three working channels **110**, **112**, **114** as shown in cross-section in FIG. 1C. According to some aspects, the medical device **100** may include two working channels (e.g., only working channels **110** and **112**, or **110** and **114**), or may include more than three working channels. Further, the working channels may have different shapes and/or sizes. For example, working channel **110** of FIG. 1C as shown is relatively larger than the other two working channels **112**, **114**, e.g., such that working channel **110** may serve as a main working channel **110**. In some embodiments, the shaft **104** may include one or more electronic components **116**, such as a camera or other imaging device, a light source, and/or other sensor. For example, the shaft **104** may include a camera lens ranging from about 0.5 mm² to about 2 mm² in size, or from about 0.75 mm² to about 1.5 mm² in size, or approximately 1 mm² in size. Additionally or alternatively, one of the working channels **110**, **112**, **114**, may provide a lumen for light delivery. For embodiments comprising a steering mechanism, the shaft **104** may include control channels (not shown) to house the steering control members.

[0026] In some aspects of the present disclosure, the handle **102** may include at least one port **150** in communication with one or more of the working channels **110**, **112**, **114**, e.g., to allow for the insertion of tools (e.g., forceps, scissors, a grasper, a snare, a probe, a guidewire, a laser, an optical device, an imaging device), for irrigation, and/or for suction.

For example, an irrigation fluid may be pumped through one or more of the working channels, such as working channel 110 and/or working channel 112, via the port 150 to provide lubrication and/or aid in visualization. The handle 102 may include an electronics hub or connector 152 for electrical connections, such as transferring data and/or powering a light source.

[0027] Further referring to FIG. 1C, at least one of the working channels (or according to some aspects of the present disclosure, the only working channel), e.g., channel 112, may house a tool 122 configured to translate proximally and distally, such that the tool 122 may exit the distal end 108 of the shaft 104 for performing a procedure. The tool 122 may be integrated into the medical device 100, such that movement of the tool 122 (e.g., translation) is controlled via a control mechanism of the handle 102. For example, the handle 102 may include a sliding actuator, slide 127, coupled to the tool 122, such that moving the slide 127 with respect to the handle 102 moves the tool 122 with respect to the working channel 112. Moving the slide 127 proximally and distally along the handle 102 may control proximal and distal movement of the tool 122.

[0028] The slide 127 may be directly or indirectly coupled to the proximal end of the tool 122 and configured such that moving the slide 127 a certain distance moves the tool 122 the same distance, or a multiple of that distance (e.g., half the distance, two times the distance, three times the distance, etc.). The slide 127 may be configured to slide within a recessed window 129 of the handle 102 as shown in FIG. 1A. Additionally or alternatively, the inner surface of the slide 127 may include an extension that fits into a corresponding groove of the handle, such that the slide 127 moves proximally and distally within the groove to translate the tool 122.

[0029] The slide 127 may be located approximately where the user's thumb would be upon gripping the handle 102, such that the thumb may engage the slide 127 to extend and withdraw the tool 122 from the working channel 112. In some embodiments, the slide 127 may include one or more protrusions 125 to facilitate gripping, or to move the slide 127. While only one protrusion 125 is shown in FIG. 1A, according to some aspects of the present disclosure the slide 127 may include a plurality of protrusions 125 (see, e.g., slide 527 of FIG. 5). According to some aspects, the slide 127 may include a locking device, such that the slide 127 may be locked in place, relative to the handle 102, when the tool 122 is in a desired position.

[0030] While FIG. 1A illustrates a sliding actuator for controlling translation of the tool 122, other mechanisms may be used. For example, the handle 120 may include a tool actuator configured as a rotatable wheel or a spindle and crank type of mechanism, such that rotating the tool actuator clockwise and counterclockwise with respect to the handle 102 controls proximal and distal translation of the tool 122.

[0031] In some aspects of the present disclosure, the tool 122 may comprise an end effector 120, such as a basket as shown in FIG. 1A. For example, the tool 122 may be a basket device configured to capture stones and other materials. Any other suitable tools may be used according to the present disclosure, including, but not limited to, forceps, scissors, a grasper, a snare, a probe, and/or other tools. Tools may comprise materials such as metals, metal alloys, shape memory materials, polymers (including plastics and thermopolymers), or any combinations thereof.

[0032] The basket 120 (or other expandable end effector) may be configured to self-expand, wherein basket 120 has a compressed configuration within the working channel 112 and an expanded configuration outside the working channel 112. When in the expanded configuration, outside the distal end 108 of the shaft 104, the basket 120 may be used to retrieve materials and objects captured within the basket 120. For example, the walls of the working channel 112 may serve to compress the basket 120, without the need for a separate sheath or cover. In some aspects this configuration may help to minimize the size of the medical device 100. For example, according to some aspects, the basket device 122 may have a cross-sectional diameter ranging from about 0.5 Fr (0.17 mm) to about 1.5 Fr (0.5 mm), or approximately 1 Fr (0.33 mm); and the working channel 112 may have a cross-sectional diameter ranging from about 1 Fr (0.33 mm) to about 2 Fr (0.67), or approximately 1.5 Fr (0.5 mm).

[0033] In some aspects, the basket device 122 may comprise wire, e.g., a wire filament that splits into three, four, or more wires in a generally bulbous shape (basket 120) that converge at the tip. Additionally or alternatively, the basket device 122 may comprise a mesh or net-like portion towards the proximal end of the basket 120, e.g., to capture relatively smaller pieces of materials, such as pulverized stone. Further, for example, the basket 120 may be configured as a net and/or mesh that facilitates the retrieval of small fragments of material. A guidewire and/or laser may be inserted into one of the working channels, such as working channel 110 or 114, during a procedure. For example, a laser may be used to break apart relatively larger pieces of materials within the body to facilitate removal of the material with the basket device 122.

[0034] The basket device 122 may comprise Nitinol or other suitable flexible materials. For example, the basket device 122 may comprise Nitinol such that the basket 120 is self-expandable. Alternatively, the basket 120 may be configured to expand manually once extended beyond the distal end 108 of the shaft 104, e.g., via a suitable control mechanism in the handle 102.

[0035] Medical devices according to the present disclosure may include a steering mechanism to deflect the shaft along one plane as mentioned above (e.g., via a single actuator, such as actuator 135 of medical device 100 in FIGS. 1A and 1B), or along a plurality of planes, as illustrated by medical device 200 in FIG. 2. Medical device 200 may include any of the features of medical device 100 discussed above. Thus, the medical device 200 may comprise a handle 202 including one or more ports 250 and an electronics connector 252, and a shaft 204 coupled to the distal end 203 of the handle 202, the shaft 204 extending from proximal end 206 to distal end 208. Further, a tool 222 may be disposed within the shaft 204 and include an expandable end effector 220, which may be controlled by a sliding actuator on the handle 202.

[0036] The handle 202 may include two actuators for controlling the shaft 204: a first actuator 235 for deflecting the shaft 204 along a first plane (e.g., xy plane), and a second actuator 245 for deflecting the shaft 204 along a second plane (e.g., yz plane). First and second actuators 235, 245 may include any of the features of actuator 135 of medical device 100 discussed above. For example, each actuator 235, 245 may be coupled to the shaft 204 via one or more control members, and may be pivotably coupled to the handle 202 via posts 237, 247, respectively. Thus, rotating the actuators 235, 245 about their respective posts 237, 247 (see arrows in FIG. 2) may move the distal end 208 of the shaft 204 along differ-

ent planes. The actuators **235**, **245** may be controlled independently of each other, or may be used in concert to provide for 360 degree deflection of the shaft **204**. In some aspects, the actuators **235**, **245** may be oriented such that they rotate about axes that are transverse to each other, e.g., axes that are orthogonal to each other. According to some aspects, one or both of the actuators **235**, **245** may include a locking device, such that either or both of actuators **235**, **245** may be locked in place when the distal end **208** of the shaft **204** is in a desired position. Any suitable steering mechanism and/or actuators for controlling deflection along a plurality of planes may be used, including those disclosed in U.S. Patent Application Publication No. 2013/0190561, incorporated by reference herein.

[0037] In some aspects of the present disclosure, the medical devices may provide for extension of a basket device beyond the distal end of the shaft, e.g., before, during, or after expansion of the basket end effector. FIGS. 3A and 3B illustrate an exemplary medical device **300**, which may include any of the features of medical device **100** and/or medical device **200** discussed above. Thus, the medical device **300** may comprise a handle **302** including one or more ports **350** and an electronics connector **352**, and a shaft **304** extending from a proximal end **306** to a distal end **308**. Further, a basket device **322** may be disposed within a working channel **312** of the shaft **304** and include an expandable basket end effector **320**. As shown in cross-section in FIG. 3B, the shaft **304** may include additional working channels, such as working channels **310** and **314**, and may include one or more electronic components **316**, such as any combination of electronic components **116** discussed in connection to medical device **100** above.

[0038] The basket device **322** may include any of the features of tool **122** discussed in connection to medical device **100** above. For example, the basket device **322** may be integrated into the medical device **300**, such that movement of the basket device **322** (e.g., translation and/or rotation) is controlled via a control mechanism of the handle **302**. In some aspects, at least a portion of the basket device **322** may be covered by a sheath **328**. For example, when the basket device **322** is in a retracted position, the entire length of the basket device **322** may be covered by the sheath **328**, and when the basket device **322** is in an extended position, only a proximal portion of the basket device **322** may be covered by the sheath **328**, the basket end effector **320** being uncovered in the extended position. Exemplary materials suitable for the sheath **328** include stretchable and/or flexible materials, including, but not limited to, polymers.

[0039] Each of the sheath **328** and the basket device **322** may be translated relative to the working channel **312** and relative to each other. For example, the handle **302** may include a control mechanism comprising a first slide **327** configured to slide within a recessed window **329** of the handle **302**, and a second slide **333** configured to slide within a recessed window **335**. The recessed windows **329**, **335** for the first and second slides **327**, **333** may be different sizes as shown in FIG. 3A, e.g., to allow the slides **327**, **333** to slide different lengths along the handle **302**. According to some aspects, however, the recessed windows **329**, **335** may be approximately the same size. Although shown as being parallel, either of windows **329**, **335** and slides **327**, **333** may also be oriented transversely to favor certain ergonomic configurations.

[0040] Each of the first slide **327** and the second slide **333** may include one or more protrusions, e.g., first protrusion **325** and second protrusion **331**, respectively, to facilitate gripping by a user, e.g., with the thumb. The first and second protrusions **325**, **331** may be located approximately where the user's thumb would be (or accessible by the thumb) upon gripping the handle **302**. The first and second protrusions **325**, **331** may have generally the same shape and size, or may have different shapes and/or sizes to allow the user to distinguish between them for controlling the sheath **328** and the basket device **322**.

[0041] According to some aspects, the first slide **327** may be configured to control (e.g., translate) the basket device **322**, and the second slide **333** may be configured to control (e.g., translate) the sheath **328**. For example, first slide **327** may be coupled to the proximal end of the basket device **322**, and the second slide **333** may be coupled to the proximal end of the sheath **328**.

[0042] Moving the second slide **333** (e.g., by applying force to the second protrusion **331**) proximally and distally with respect to the handle **302** may translate the sheath **328** relative to the basket device **322** and relative to the working channel **312**. Thus, for example, the user first may move the second slide **333** to extend the sheath **328** distally beyond the distal end **308** of the shaft **304**. While covered by the sheath **328**, the basket **320** may be in a retracted and compressed configuration suitable for translation within the working channel **312**, and/or within a body passageway prior to expansion.

[0043] The user then may move the first slide **327** (e.g., by applying force to the first protrusion **325**) proximally and distally to translate the basket device **322** distally through the sheath **328** until the entire basket **320** is uncovered. Once uncovered, the basket **320** may expand into a deployed, expanded configuration as shown in FIG. 3A. The length of the windows **329**, **335** for the first and second slides **327**, **333** may allow for sufficient freedom of movement of the basket device **322** and the sheath **328** relative to the working channel **312** and relative to each other.

[0044] The basket **320** may be self-expandable or manually expandable, as discussed in connection to basket **120** above. Upon capturing material within the basket **320**, the basket device **322** may be withdrawn proximally, e.g., by moving the first slide **327** proximally. The shaft **304** then may be withdrawn and removed from the patient. In some aspects, the sheath **328** may be sufficiently flexible to allow the basket **320** and trapped material to be at least partially or completely withdrawn within and surrounded by the sheath **328**, wherein the sheath **328** may apply a force radially inward to help to compress the trapped material for removal.

[0045] While FIG. 3A illustrates the first and second slides **327**, **333** on the same side of the handle **302**, e.g., for control by the user's thumb, according to some aspects the first and second slides **327**, **333** may be on opposite sides of the handle **302**, e.g., for control by the user's thumb and index (or other) finger. For example, the first slide **327** may be located on one side of the handle **302** approximately where of the user's thumb would be (e.g., as shown in FIG. 3A), and the second slide **333** may be located on the opposite side (not visible in FIG. 3A) approximately where the user's index finger would be. Thus, the handle **302** may have a generally ergonomic design to allow the user to control both slides **327**, **333** without repositioning his/her hand.

[0046] While FIG. 3B illustrates the basket device **322** and the sheath **328** being disposed within working channel **312**,

e.g., without sufficient room for the passage of an additional tool (e.g., a guidewire, a laser, etc.) through the working channel **312** at the same time. According to some aspects, the basket device **322** and the sheath **328** may be disposed within a relatively larger working channel, such as working channel **310**, so that the basket device **322** and the sheath **328** may occupy only a portion of the working channel **310**. This configuration allows the remainder of the working channel **310** to be used for insertion of other tools, such as those for irrigation, or for suction.

[0047] As an alternative or in addition to the features described above, medical devices according to the present disclosure may provide for rotational control without rotating and disturbing external connections, such as connections for irrigation, suction, tools, or electronic components such as power supply or data transfer.

[0048] FIGS. 4A-4C illustrate an exemplary handle **402** of a medical device, e.g., configured for detachable or permanent connection to a suitable shaft having one or more working channels. According to some aspects of the present disclosure, for example, the distal end **403** of an inner body **401** of the handle **402** may be configured for attachment to a shaft **404** of similar or otherwise compatible external dimensions, such as any of shafts **104**, **204**, or **304** discussed above. In particular, shaft **404** may include some or all of the features of shaft **104** shown in FIGS. 1A-1C; these features will be referenced below regarding shaft **404**.

[0049] The handle **402** may include the inner body **401** and an outer body **480** disposed at least partially around the inner body **401**. The inner and outer bodies **401**, **480** may be coupled together and rotatable relative to each other, as discussed further below. FIGS. 4A and 4B show perspective and side views, respectively, of the handle in a first position. FIG. 4C shows the handle **402** in a second position where the inner body **401** has been rotated relative to the outer body **440**, e.g., about a longitudinal axis of the inner body **401**. The handle **402** may have any suitable shape for gripping and controlling the distal portion of the medical device. For example, the inner body **401** and outer body **480** may have a generally ergonomic shape such that the outer body **480** may be held comfortably in the palm of a user's hand.

[0050] The handle **402** may include any features of handles **102**, **202**, or **302** above. According to some aspects of the present disclosure, the handle **402** may include a steering mechanism for controlling the distal end of the medical device (e.g., distal end of shaft **404**). For example, the handle **402** may include at least one actuator **435** pivotably coupled to the inner body **401** via a post **437**. The actuator **435** and/or post **437** may be coupled to the distal portion of the medical device (e.g., at or near the distal end of the shaft **404**) via control members to provide for movement along a plane (e.g., left/right or up/down) as discussed above. In some aspects, the handle **402** may include two or more actuators, e.g., such as first and second actuators **235**, **245** of handle **202**, to provide for 360 degree deflection (see FIG. 2, discussed above above).

[0051] The handle **402** may include at least one port **450** (which may include any of the features of ports **150**, **250**, and/or **350** discussed above) and an electronic connector **452** (which may include any of the features of connectors **152**, **252**, and/or **352** discussed above). The locations of the port **450** and electronic connector **452** illustrated in FIGS. 4A-4C are exemplary, such that other configurations are possible and encompassed by the present disclosure. For example, the port

450 and the electronics connector **452** both may be disposed on an upper portion of the handle **402**, a lower portion of the handle **402**, or on one side of the handle **402**, or the port **450** and the electronics connector **452** may be disposed on opposite sides of the handle **402**.

[0052] According to some aspects, the port **450** may provide for access to one or more working channels of the medical device (e.g., working channels **110**, **112**, **114** of shaft **104**), e.g., such that various tools may be inserted into the working channel(s) and exchanged for different tools (e.g., forceps, scissors, a grasper, a snare, a probe, a guidewire, a laser fiber, an optical device, an imaging device), the introduction of fluids (e.g., water or saline for irrigation, contrast dye, etc.) into the working channel(s), and/or for suction via one or more of the working channels. For example, an irrigation fluid may be pumped into the handle **402** via the port **450** to flush out one or more of the working channels, or aid in visualization during a procedure by delivering fluid. For examples in which the handle **402** includes two or more ports **450**, each port **450** may be in communication with different working channels of the shaft **404**. The electronics connector **452** may be configured for providing light and/or data transmission to a camera or other imaging device. The electronic components may be integrated into the medical device (such as, e.g., electronic component(s) **116** of medical device **100** discussed above).

[0053] Both the port **450** and the electronics connector **452** may be coupled to the outer body **480**. As shown in FIGS. 4A-4C, for example, the port **450** may be coupled (e.g., fixedly attached) to a mantle **484** of the outer body **480**, and the electronics connector **452** may be coupled (e.g., fixedly attached) to a ledge **486** of the outer body **480**, opposite the mantle **484**. The outer body **480** may include an inclined portion **482** supporting the mantle **484**.

[0054] The port **450** may lead into the inner body **401** through the mantle **484** and via flexible tubing **451** connecting the mantle **484** to the inner body **401**. The tubing **451** may provide a water-tight and/or air-tight connection from the port **450** to the working channel(s) of the medical device. For example, the tubing **451** may extend into an upper slot **460** of the inner body **401** (see, e.g., FIG. 4A) with sufficient slack between the inner and outer bodies **401**, **480** to allow the inner body **401** to rotate relative to the outer body **480** without pulling, twisting, crimping, or otherwise compromising the integrity of the water-tight and/or air-tight connection.

[0055] Similarly, the electronics connector **452** may lead into the inner body **401** through the ledge **486** and via one or more flexible electronic cables **453**, or via flexible tubing housing one or more flexible electronic cables **453**. The inner body **401** may include a lower slot **464** (see FIG. 4B) through which the cable **453** may enter into the inner body **401**, e.g., with sufficient slack to allow the inner body **401** to rotate relative to the outer body without pulling, twisting, crimping, or otherwise compromising the integrity of the electrical connection. The inner surfaces of the mantle **484** and the ledge **486** may be curved to provide sufficient clearance for the inner body **401** to rotate relative to the outer body **480**.

[0056] As mentioned above, FIGS. 4A and 4B show the handle **402** in a first, neutral position, before rotation. FIG. 4C shows the handle **402** in a second, rotated position, after the inner body **401** has rotated counterclockwise (from the perspective of the user) about its longitudinal axis and relative to the outer body **480**. That is, the outer body **480** and the port **450** and electronic connector **452** attached to the outer body

480 maintain the same position, while the inner body **401** and the shaft **404** coupled to the inner body **401** rotate. Thus, the user may reposition tools at the distal end of the medical device by rotating the inner body **401** about its longitudinal axis without disturbing connections at port **450** or the electronics connector **452**. The inner body **401** may be rotatable through an arc of up to about 180 degrees, up to about 120 degrees, up to about 90 degrees, up to about 45 degrees, or up to about 30 degrees. For example, the inner body **401** may be rotatable through an arc ranging from about 0 degrees to about 90 degrees, from about 5 degrees to about 90 degrees, from about 5 degrees to about 45 degrees, or from about 5 degrees to about 30 degrees. The slots **460**, **464** may have dimensions suitable for accommodating the desired arc of rotation, e.g., the inner body **401** having relatively longer slots **460**, **464** to allow the inner body **401** to rotate relative to the outer body **480** without straining or compromising connections to the port **450** and the electronics connector **452**.

[0057] In some aspects, the handle **402** may be coupled to a stand (not shown) to support the handle **402** and facilitate manipulation of the handle **402**. The stand may extend to the floor, a table, or other substantially flat surface. For example, the stand may comprise a tripod or other suitable design, and may be adjustable for height and/or incline, and may provide for rotational adjustments to position the handle **402** of the medical device with the proposer orientation relative to a patient. Adjustments may be made manually, such as with a hand crank, or via electronic control. According to some aspects, the stand may be configured to clamp onto a support surface near the patient, such as a table, a bed, or other support. Once the stand properly positioned, the outer body **480** of the handle **402** may be secured to the stand via any suitable mechanism (e.g., a tripod head mount or other detachable connection), such that the outer body **480** does not move relative to the stand. With the outer body **480** secured to the stand, the inner body **401** may be free to rotate relative to the outer body **480** and relative to the stand as discussed above.

[0058] Medical devices according to the present disclosure may combine features of the integrated tools discussed in connection to medical device **100** and medical device **300** with the rotational capability discussed in connection to handle **402** above. FIG. 5 illustrates an exemplary handle **502**, for example, which may include any of the features of handle **402**. Thus, for example, the handle **502** may include an inner body **501** and an outer body **580** at least partially surrounding the inner body **501**. The distal end **503** of the inner body **501** may be configured for attachment to a shaft **504** of similar or otherwise compatible external dimensions, such as any of shafts **104**, **204**, **304**, or **404** discussed above. The outer body **580** may be coupled to at least one port **550** (which may include any of the features of ports **150**, **250**, **350**, and/or **450** discussed above) via a mantle **584** and an electronics connector **552** (which may include any of the features of electronics connectors **152**, **252**, **352**, and/or **452** discussed above) via a ledge **586**. The inner body **501** may include slots similar to slots **460**, **464** of inner body **401** of FIGS. 4A-4C. For example, FIG. 5 shows a slot **560** to accommodate connections via the port **550** (slot corresponding to the electronics connector **552** not shown in FIG. 5).

[0059] The handle **502** may include a control mechanism for controlling an integrated tool, such as the mechanisms discussed above for controlling the tool **122** of medical device **100**, or the basket device **322** of medical device **300**. As

shown in FIG. 5, for example, the handle **502** may include a slide **527** coupled to the inner body **501** and movable along the inner body **501**, e.g., to control translation of a tool. The slide **527** may include one or more protrusions **525**, such as a plurality of protrusions **525** with grooves therebetween to facilitate gripping of the slide **527**, accommodate different hand sizes or thumb positions, and/or gripping by multiple fingers. The outer body **580** may include an opening **585** generally aligned with the slide **527** to allow the user to move the slide **527** while gripping the outer body **580**. The dimensions of the opening **585** may allow the slide **527** to move freely in proximal and distal directions, and allow for rotation of the inner body **501** relative to the outer body **580** such that the slide **527** may rotate freely clockwise or counterclockwise without contacting the walls of the opening **585**. Other control mechanisms may be used as discussed above, such as a rotatable wheel, wherein rotating the wheel corresponds to translation of the tool. Further, while FIG. 5 illustrates a single slide **527**, according to some aspects the handle **502** may include two slides, such as first and second slides **327**, **333** of handle **302**, for controlling a basket device (or other tool) and sheath independently or in combination.

[0060] FIG. 6 illustrates yet another exemplary handle **602** according to some aspects of the present disclosure. The handle **602** may include any of the features of handles **402** and **502** discussed above. Thus, for example, the handle **602** may include an inner body **601** and an outer body **680** at least partially surrounding the inner body **601**. The distal end of the inner body **601** may be coupled to a shaft **604** (which may include any of the features of shafts **104**, **204**, **304**, **404**, and/or **504** discussed above), wherein the distal end of the inner body **601** may be entirely covered by the distal end **681** of the outer body **680**. As shown in FIG. 6, the shaft **604** may extend through an opening of the distal end **681** of the outer body **680**.

[0061] The outer body **680** may be coupled to at least one port **650**, which may include any of the features of ports **150**, **250**, **350**, **450**, and/or **550** discussed above; and an electronics connector **652**, which may include any of the features of electronics connectors **152**, **252**, **352**, **452**, and/or **552** discussed above. The inner body **601** may include slots (not shown) similar to slots **460**, **464** of inner body **401** of FIGS. 4A-4C. Thus, a user may rotate the inner body **601** about its longitudinal axis and relative to the outer body **680**, without disturbing connections at the port **650** (e.g., in communication with working channels of the shaft **604**) or the electronics connector **652**.

[0062] The handle **602** may include a control mechanism for controlling an integrated tool, such as the mechanisms discussed above. As shown in FIG. 6, for example, the handle **602** may include a slide **627** (including a protrusion **625**) coupled to the inner body **601** and movable along the inner body **601**, e.g., to control translation of a tool within a working channel of the shaft **604**. The outer body **680** may include an opening generally aligned with the slide **627** to allow the user to move the slide **627** proximally and distally along the inner body **601**, and to allow the user to rotate the inner body **601** such that the outer body **680** does not obstruct access to the slide **627**.

[0063] Further, the inner body **601** and outer body **680** may be coupled together with sufficient clearance, e.g., between the distal end of the inner body **601** and the distal end **681** of the outer body **680**, to allow the inner body **601** to rotate freely

relative to the outer body **680**. Rotating the inner body **601** may rotate the shaft **604** relative to the outer body **680**.

[0064] Other embodiments of the present disclosure will be apparent to those skilled in the art from consideration of the specification and practice of the embodiments disclosed herein. While certain features of the present disclosure are discussed within the context of exemplary procedures, the devices, instruments, and methods are not so limited and may be used in other areas of the body, and for other medical procedures according to the general principles disclosed. It is intended that the specification and examples be considered as exemplary only, with a true scope and spirit of the present disclosure being indicated by the following claims.

We claim:

1. A medical device comprising:
a handle;
a shaft coupled to the handle, the shaft including a plurality of working channels; and
a retrieval device movably disposed within one of the working channels,
wherein the handle includes a steering mechanism configured to deflect a distal end of the shaft and a control mechanism configured to translate the retrieval device within the at least one working channel.
2. The medical device of claim 1, wherein the retrieval device includes an expandable basket.
3. The medical device of claim 1, wherein the control mechanism includes a sliding actuator coupled to the handle for controlling translation of the retrieval device.
4. The medical device of claim 1, wherein the handle includes at least one port connector.
5. The medical device of claim 4, wherein the at least one port connector includes a port in communication with the at least one working channel, the medical device further including a connector configured for at least one of light or data transmission.
6. The medical device of claim 4, wherein the shaft includes a first working channel and a second working channel, wherein the first working channel includes the retrieval device and the second working channel is in communication with the at least one port connector.
7. The medical device of claim 1, wherein the handle includes an outer body coupled to an inner body, wherein the inner body is rotatable relative to the outer body, the inner body being coupled to the shaft.
8. The medical device of claim 7, wherein the handle includes at least one port connector coupled to the outer body and in communication with the at least one working channel, wherein rotating the inner body relative to the outer body does not rotate the at least one port connector.
9. The medical device of claim 2, further comprising a sheath surrounding at least a portion of the retrieval device, the sheath being disposed within the at least one working channel.
10. The medical device of claim 9, wherein the control mechanism is configured to translate the retrieval device independently of the sheath.

11. The medical device of claim 9, wherein the control mechanism is configured to translate the retrieval device and the sheath simultaneously.

12. The medical device of claim 1, wherein the medical device is a ureteroscope, and the retrieval device is integrated into the ureteroscope.

13. The medical device of claim 1, wherein the steering mechanism is configured to deflect a distal end of the shaft along a plurality of planes.

14. A medical device comprising:

a handle including an inner body and an outer body, wherein the outer body at least partially surrounds the inner body;

a shaft coupled to the inner body, the shaft including at least one working channel; and

a port connector coupled to the outer body, the port connector being in communication with the at least one working channel,

wherein the inner body and the shaft are rotatable relative to the outer body and relative to the port connector.

15. The medical device of claim 14, further comprising a retrieval device disposed within the at least one working channel, wherein the inner body includes a control mechanism for translating the retrieval device within the at least one working channel.

16. The medical device of claim 15, wherein the medical device is a ureteroscope, and the retrieval device includes an expandable basket.

17. The medical device of claim 15, wherein the shaft includes a first working channel and a second working channel, wherein the first working channel includes the retrieval device and at least one of the first working channel or the second working channel is in communication with the port connector.

18. A medical device comprising:

a handle;

a shaft coupled to the handle, the shaft including at least two working channels;

a retrieval device movably disposed within the at least one working channel, the retrieval device including an expandable basket; and

a sheath surrounding at least a portion of the retrieval device and disposed within the at least one working channel,

wherein the handle includes a steering mechanism configured to deflect a distal end of the shaft and a control mechanism configured to translate each of the retrieval device and the sheath within the at least one working channel.

19. The medical device of claim 18, wherein the medical device is a ureteroscope.

20. The medical device of claim 19, wherein the retrieval device is integrated into the ureteroscope and not removable from the shaft.

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摘要(译)

公开了执行诊断和/或治疗程序的医疗装置，例如从患者取回自体材料和/或外来材料。医疗装置可包括手柄，连接到手柄的轴，以及可移动地设置在工作通道内的取回装置。手柄可包括用于使轴的远端偏转偏转的转向机构和用于将取回装置平移在工作通道内的控制机构。检索设备可以集成到医疗设备中。

