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Leonard et al.

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(54) **SURGICAL DEVICE**

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(52) **U.S. Cl.**
USPC **606/1; 606/41**

(58) **Field of Classification Search**
USPC 606/1, 41-52; 607/88-102
See application file for complete search history.

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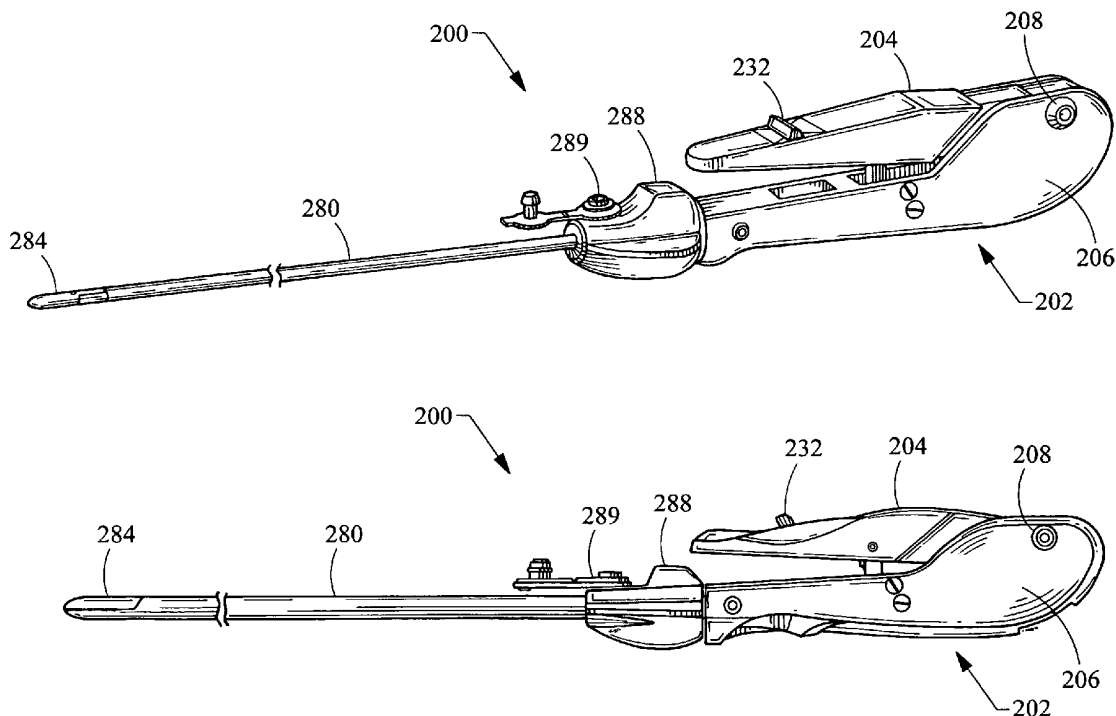
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(57) **ABSTRACT**

An in-line laparoscopic surgical instrument is provided, including a ratchet mechanism. The ratchet mechanism includes a single actuating means that may be used to engage, release, or defeat a ratchet engagement between portions of the handle.

2 Claims, 16 Drawing Sheets



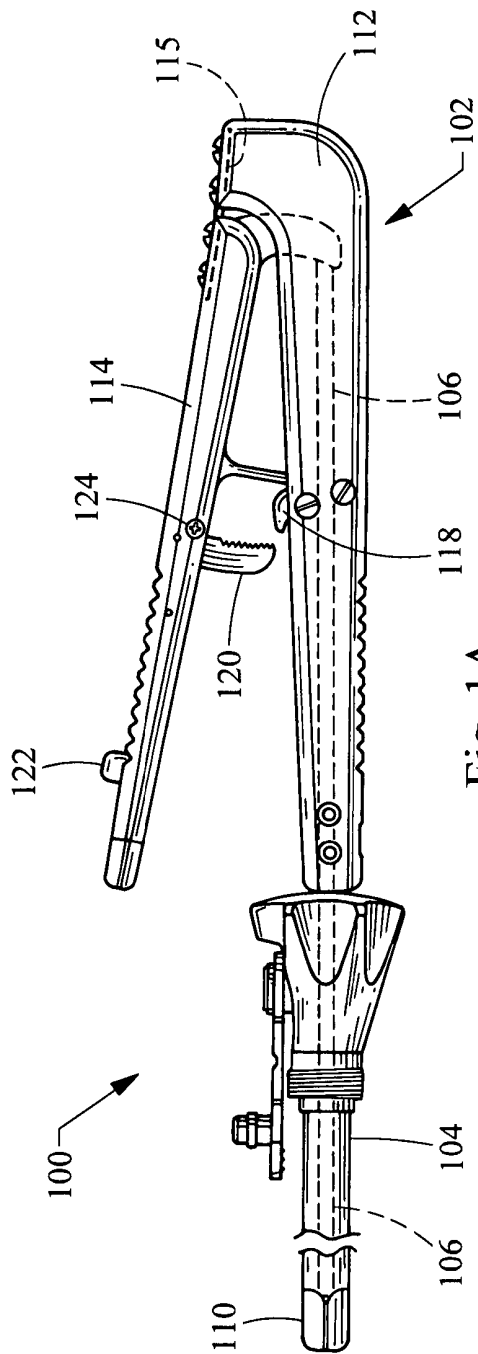


Fig. 1A
(Prior Art)

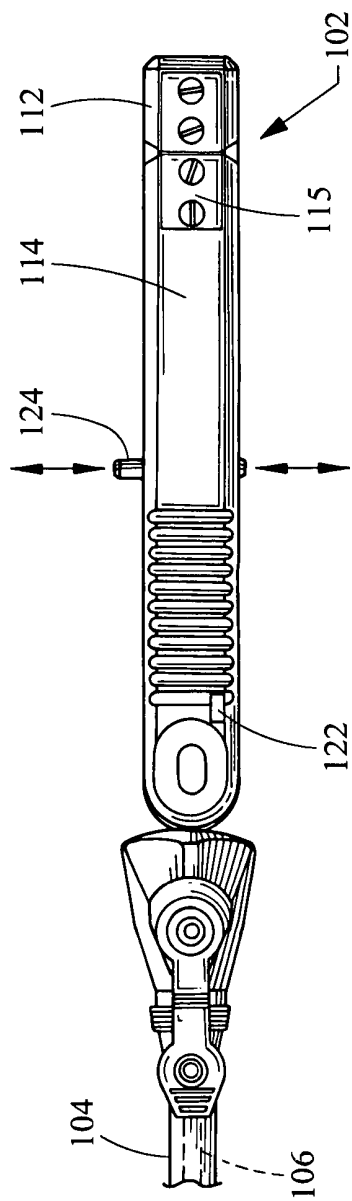


Fig. 1B
(Prior Art)

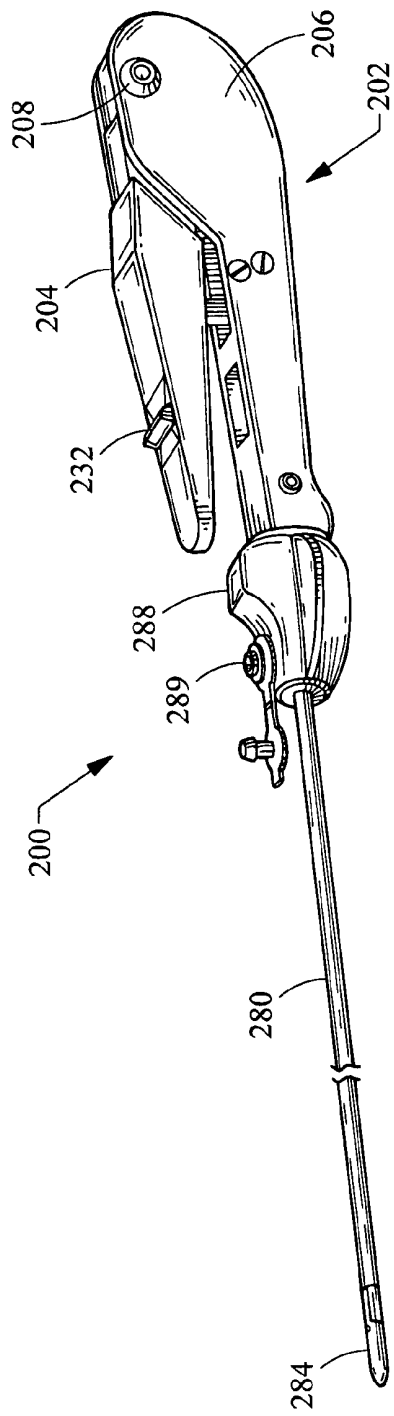


Fig. 2A

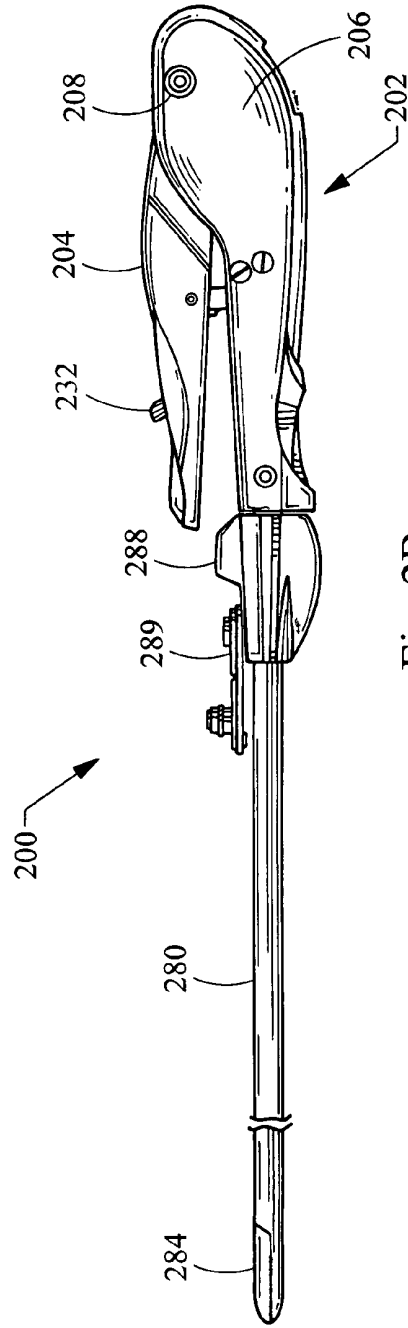


Fig. 2B

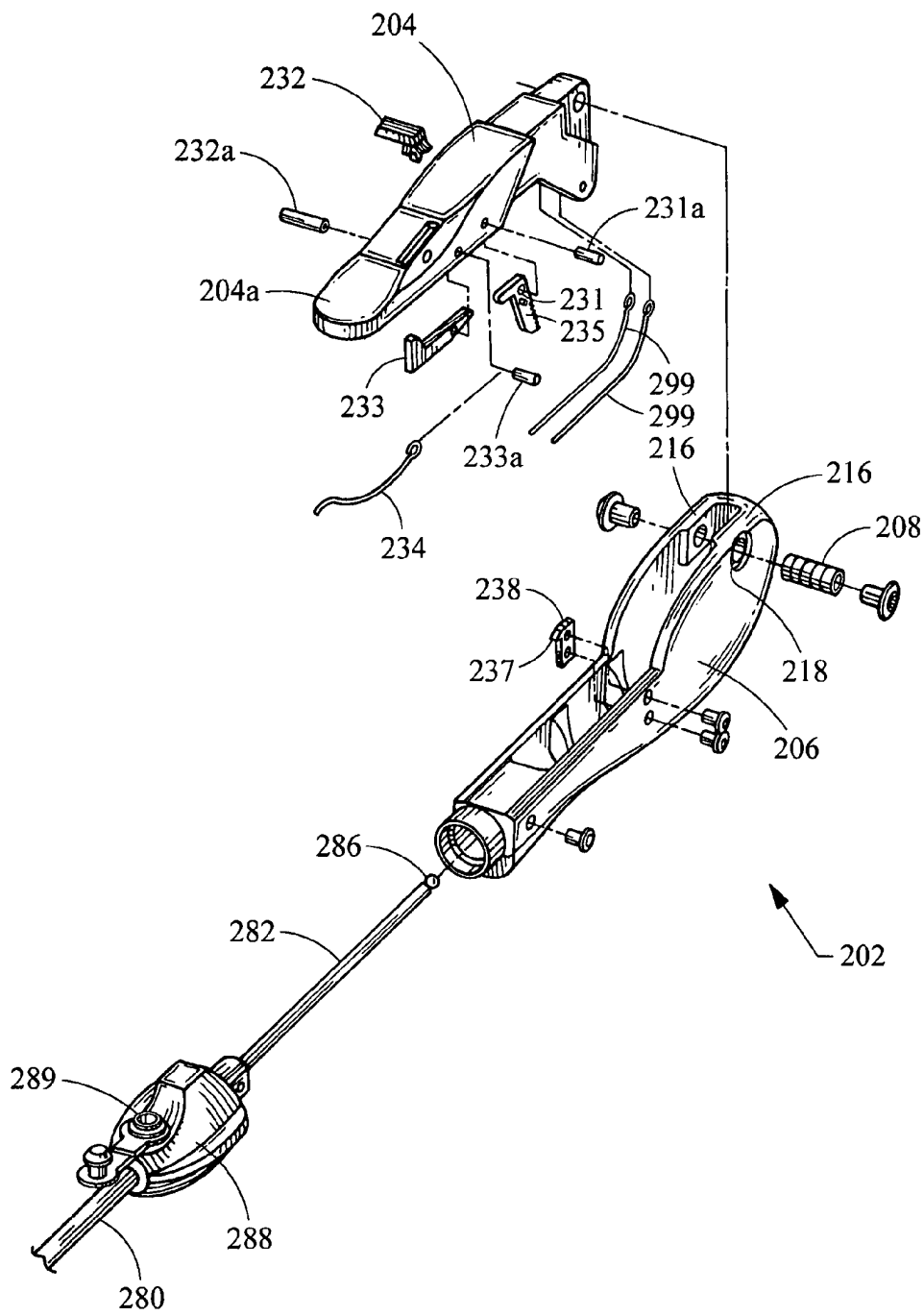


Fig. 3

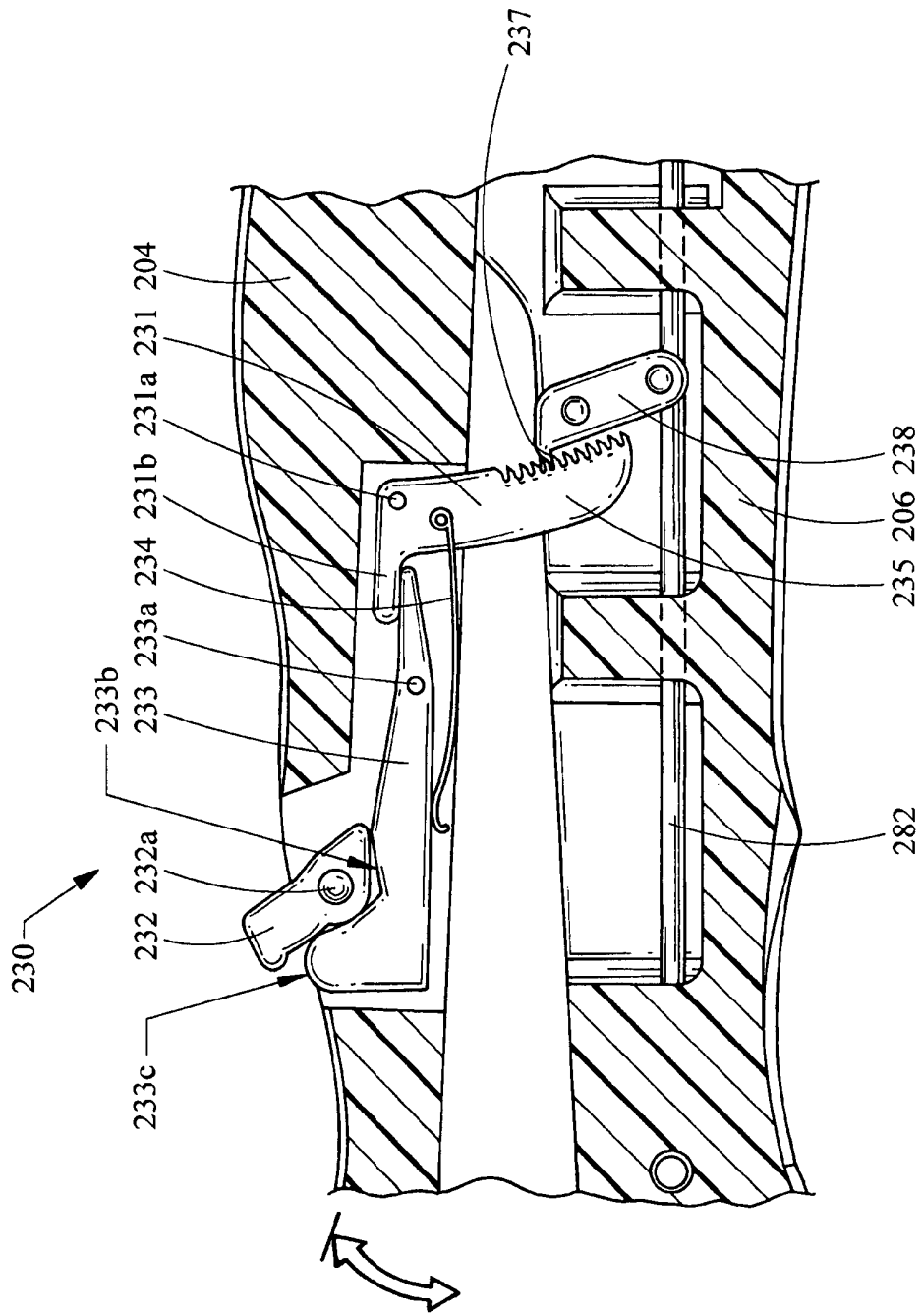


Fig. 3A

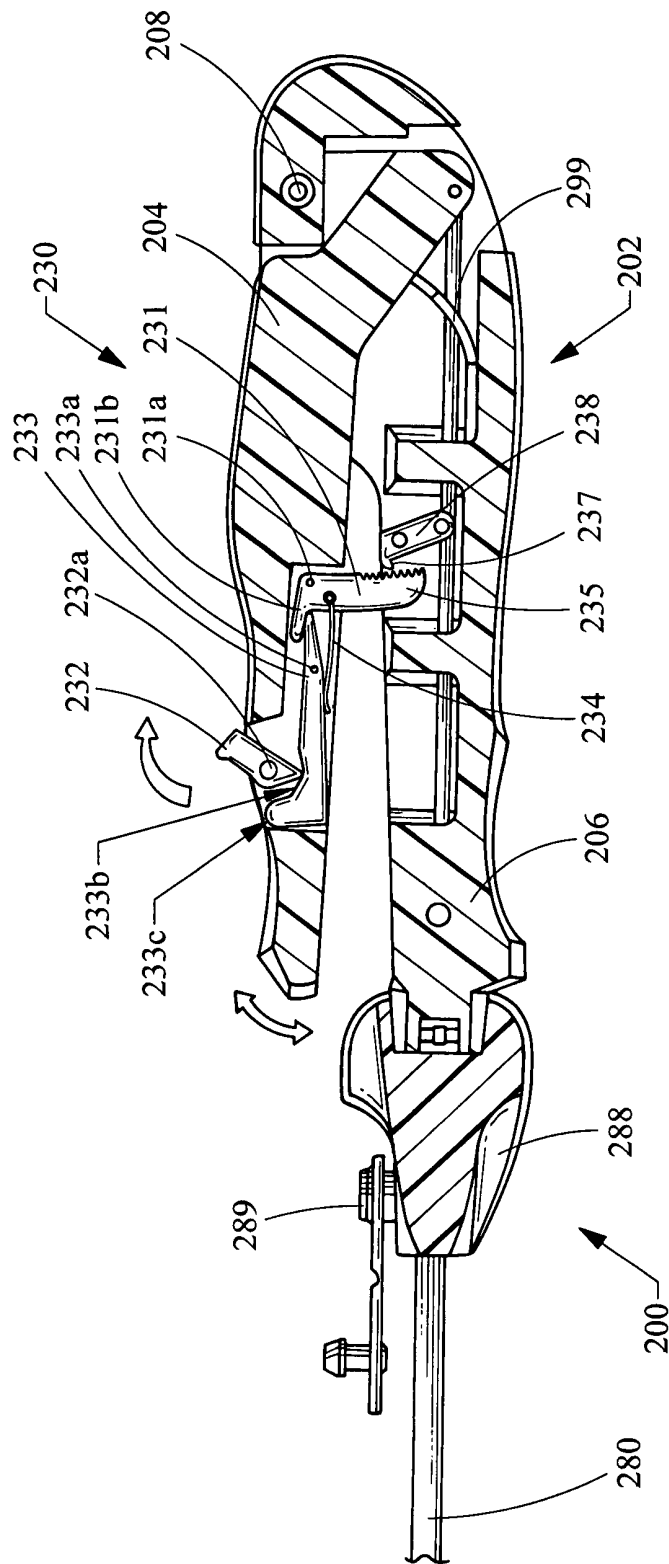


Fig. 3C

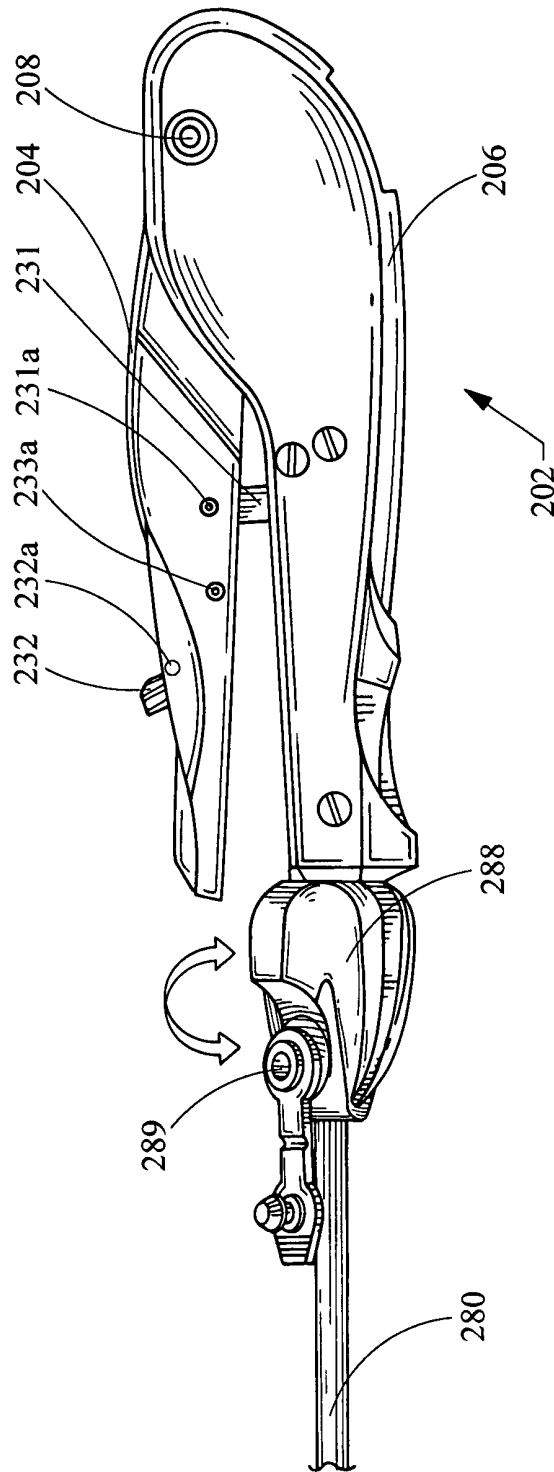


Fig. 3D

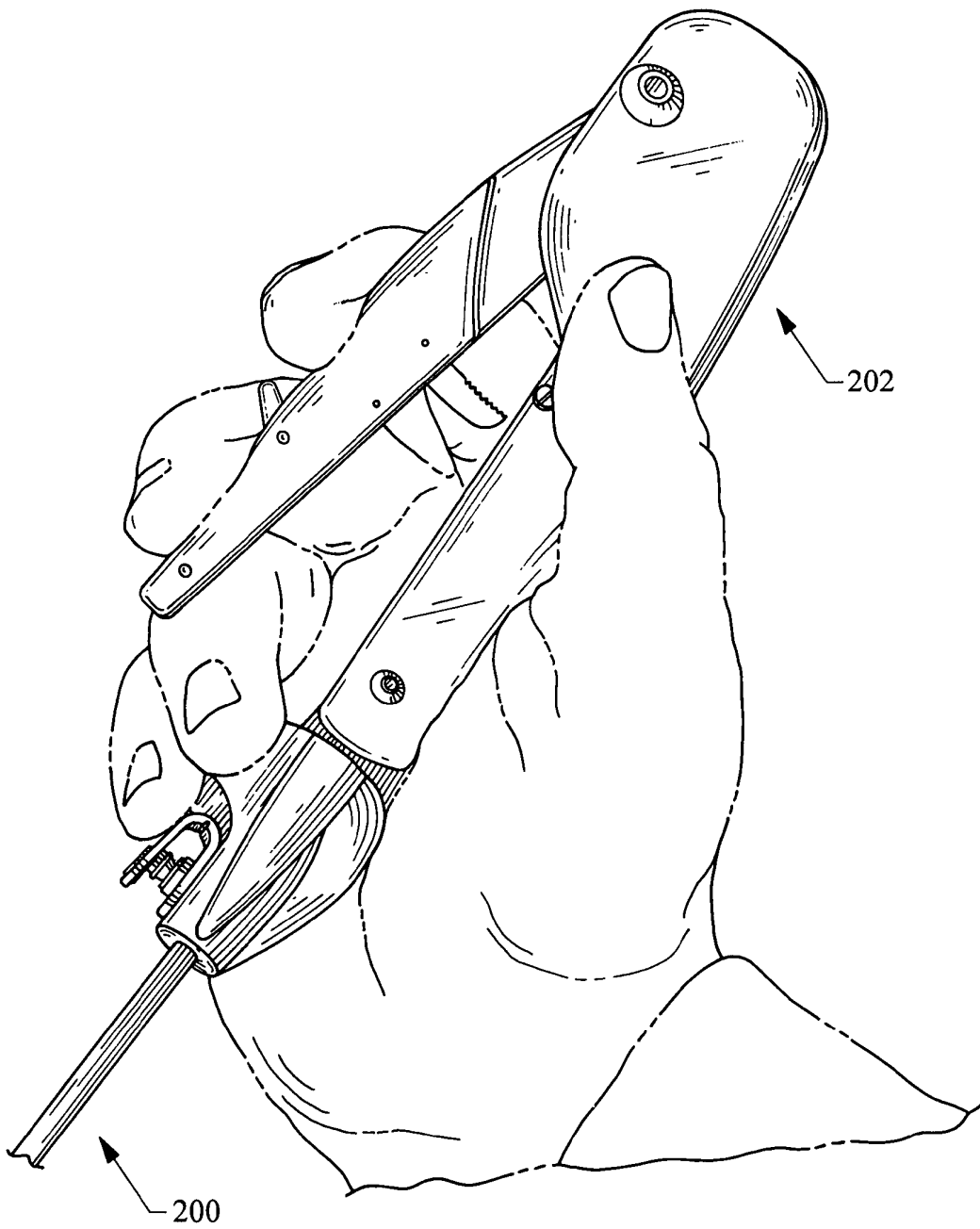


Fig. 4A

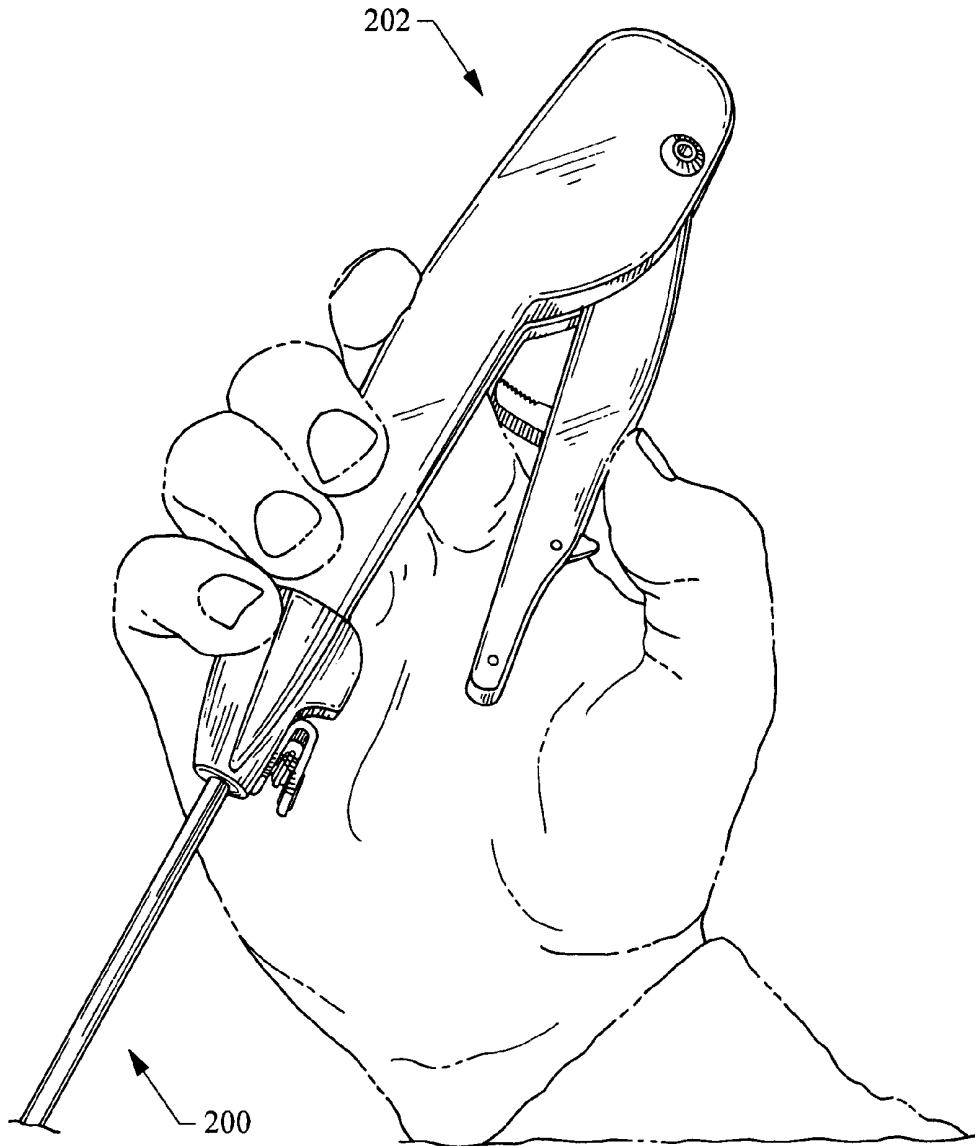


Fig. 4B

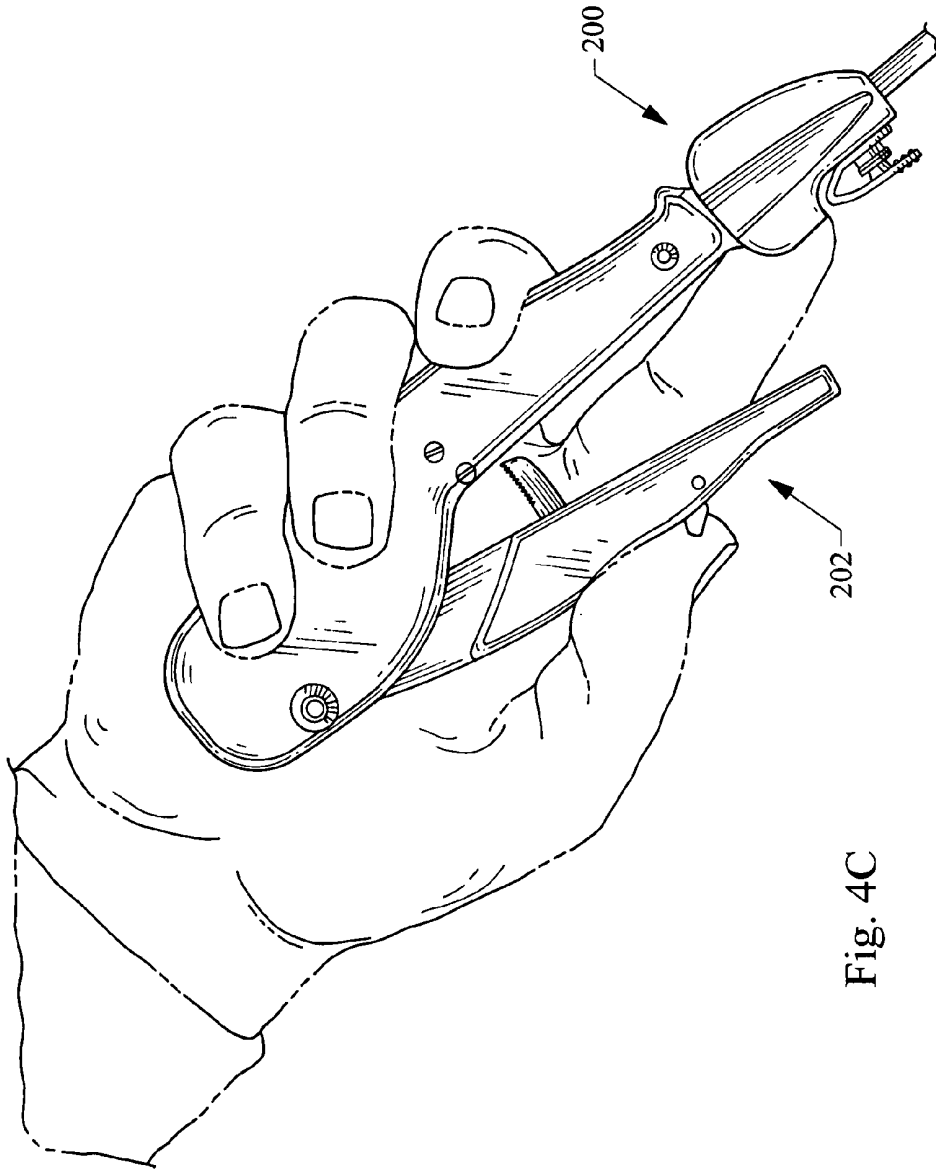


Fig. 4C

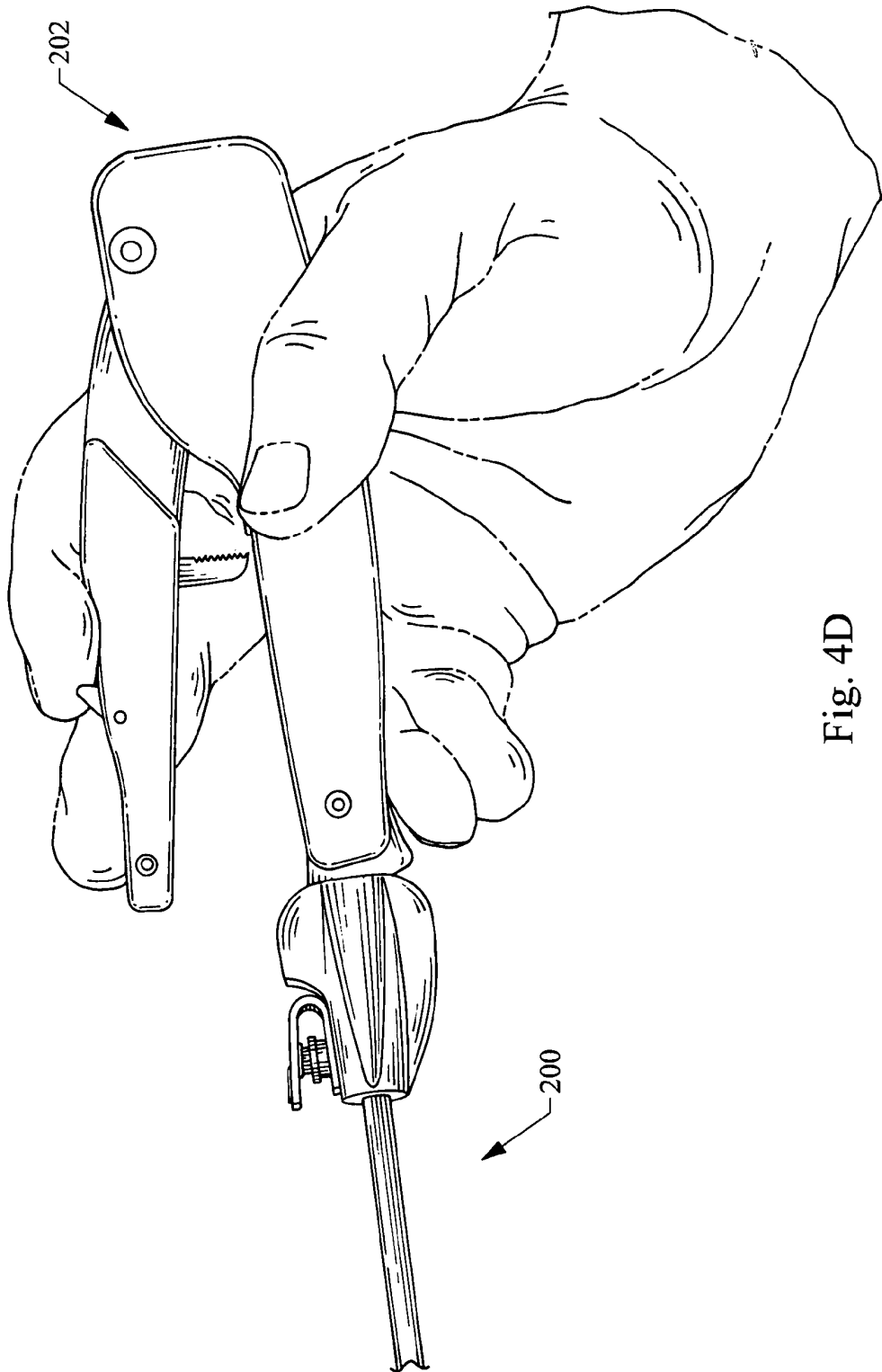


Fig. 4D

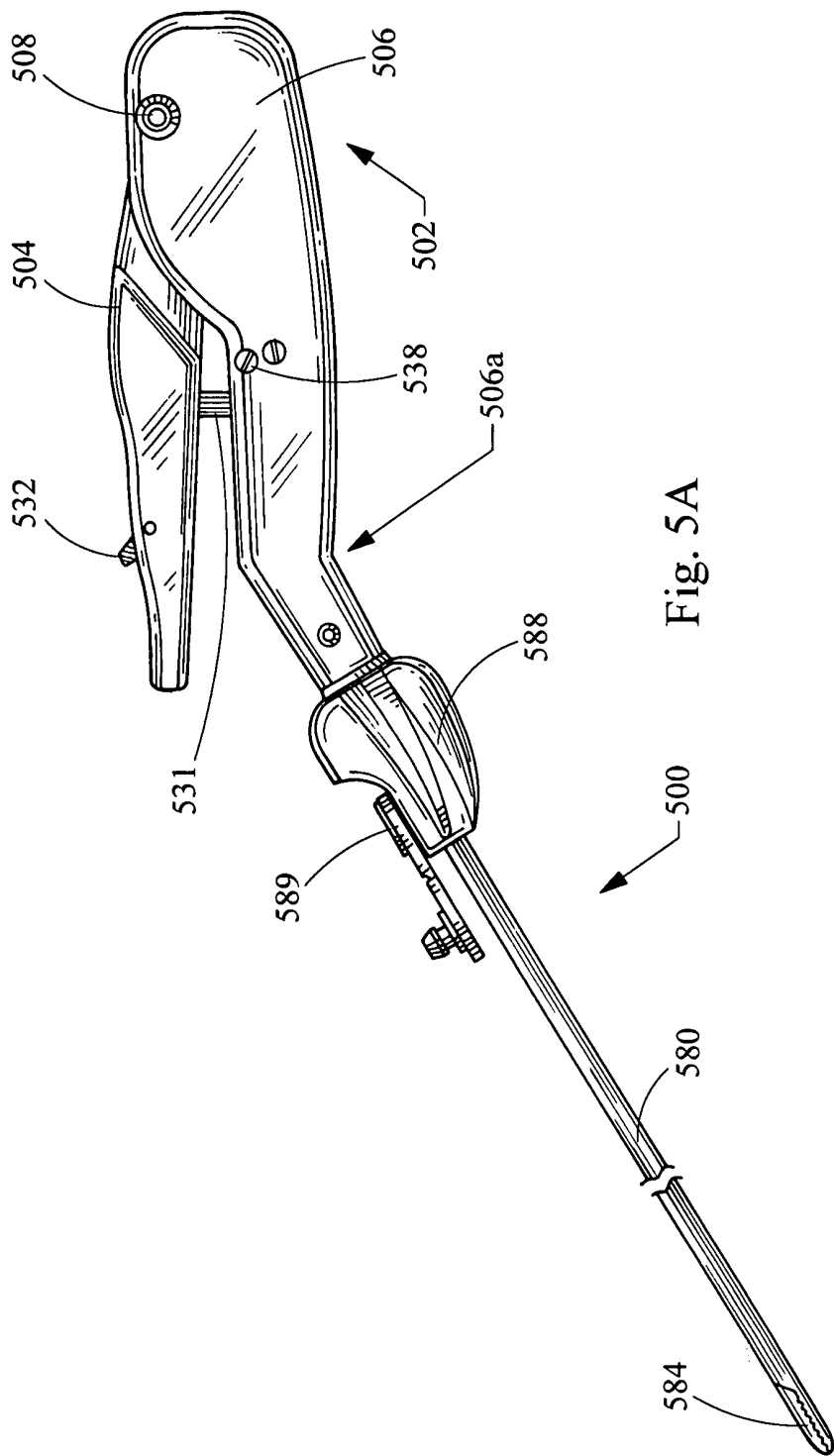


Fig. 5A

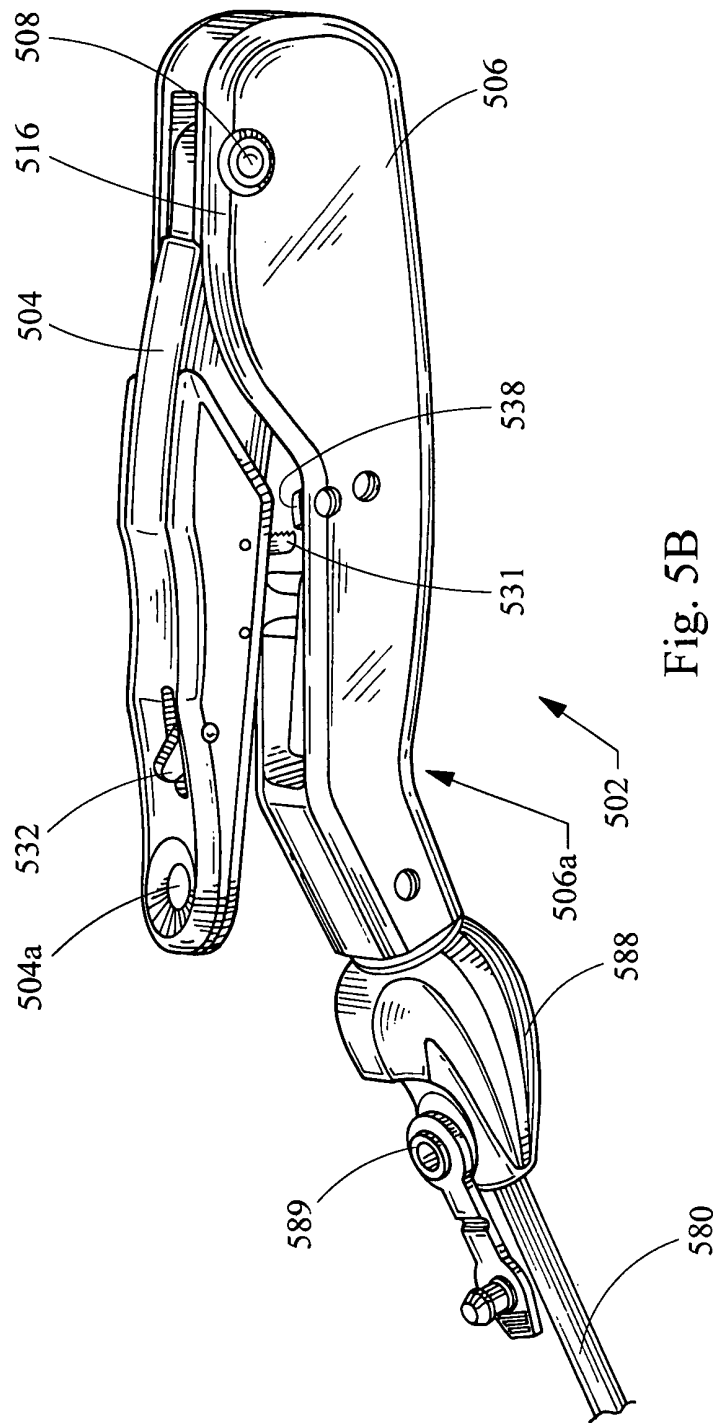


Fig. 5B

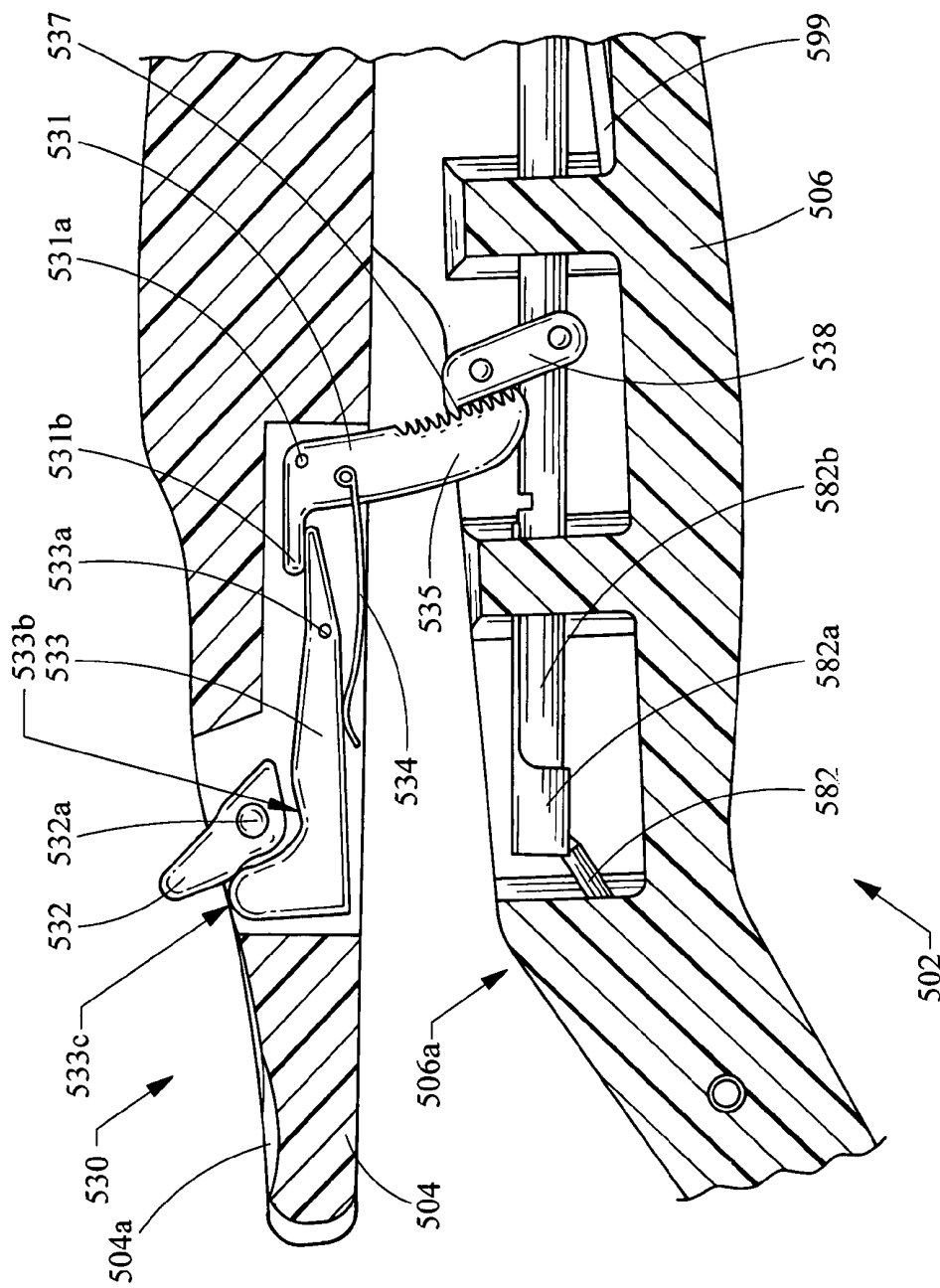


Fig. 6A

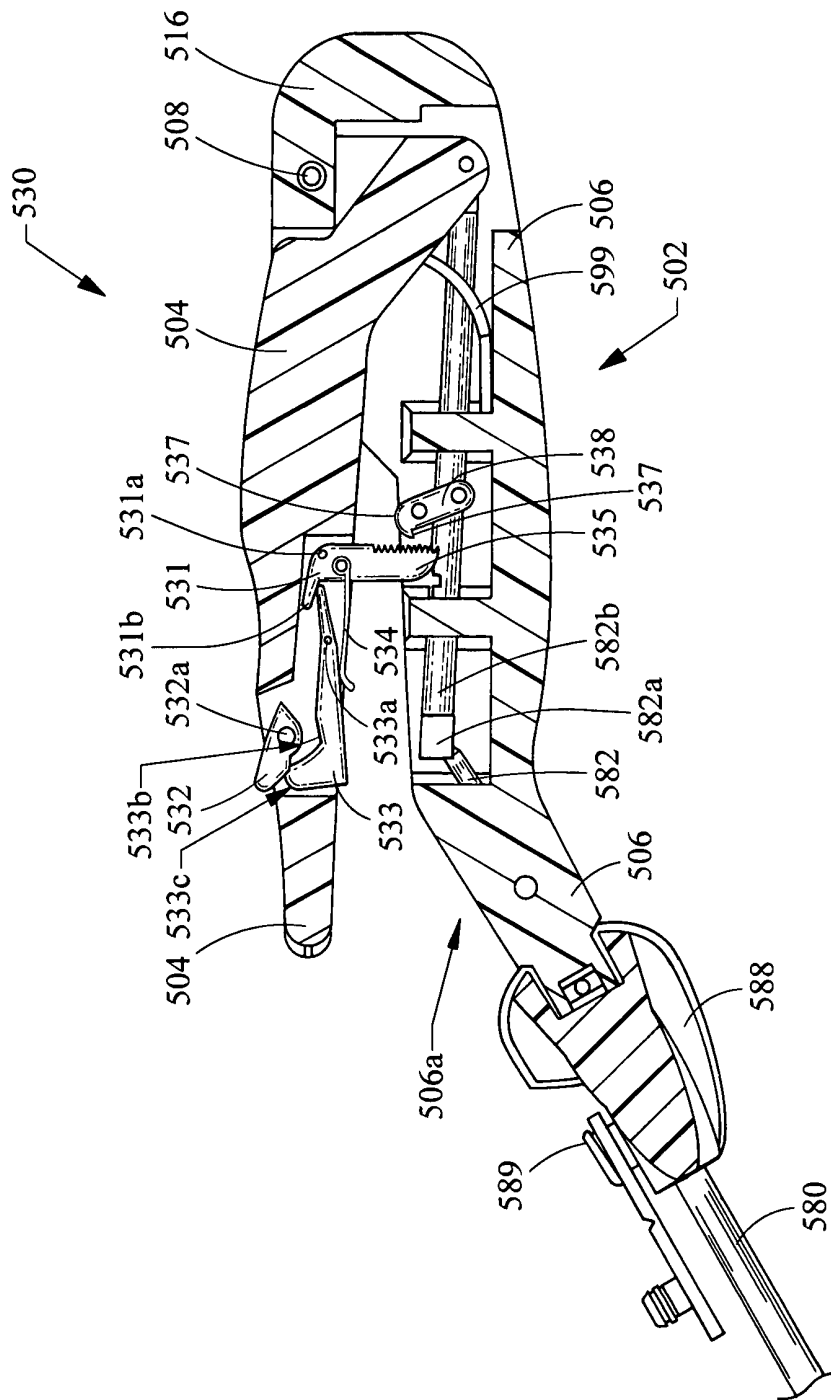


Fig. 6B

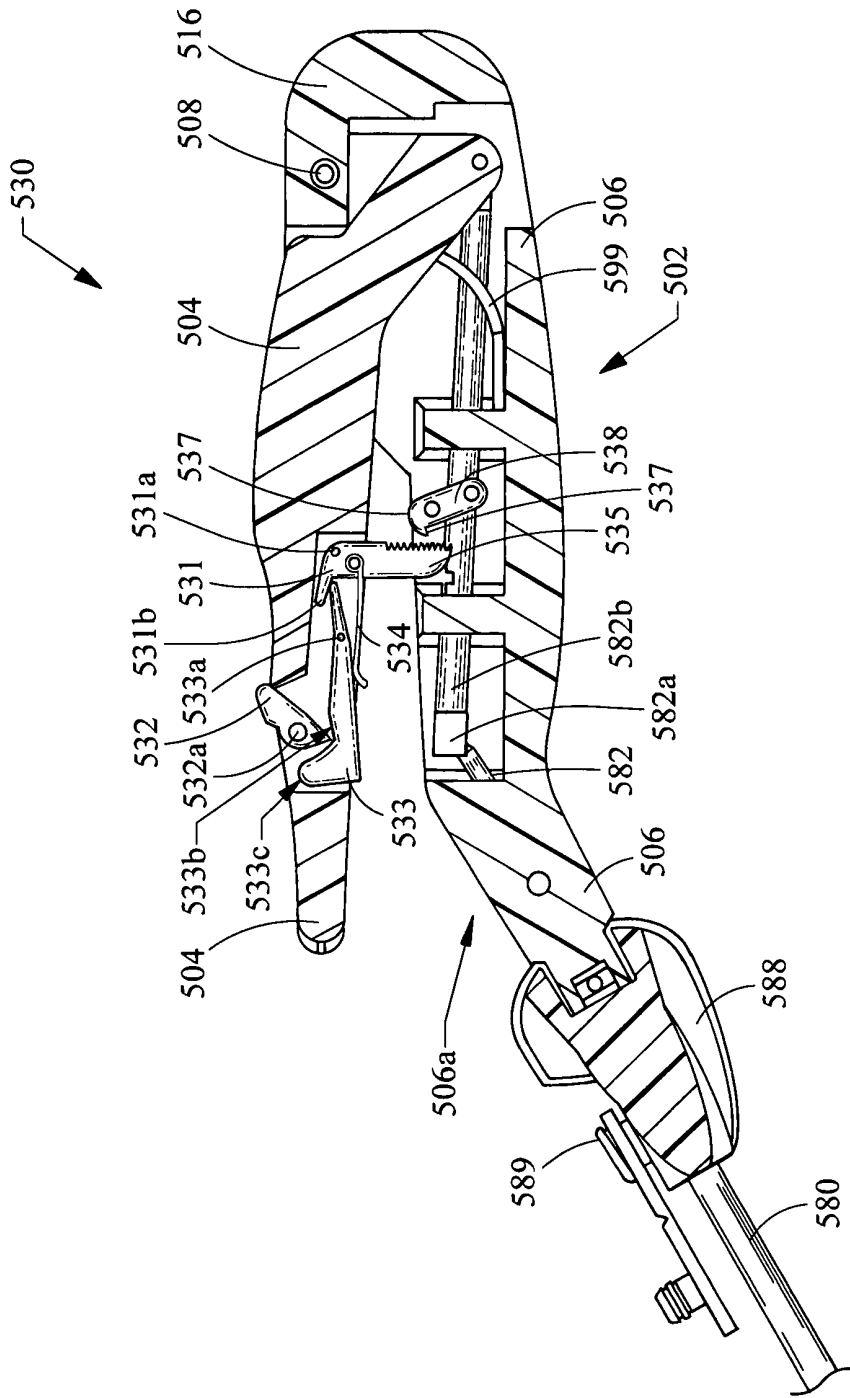


Fig. 6C

SURGICAL DEVICE

This application claims the benefit of U.S. patent application Ser. No. 11/186,627, filed Jul. 21, 2005, now abandoned, which claims priority to U.S. Provisional Patent Application No. 60/590,095, filed Jul. 21, 2004, each of which is hereby incorporated by reference in its entirety.

FIELD OF THE INVENTION

The present invention relates generally to medical devices, and more particularly to a handle configured to manipulate a distal tool end of a generally axial laparoscopic device.

BACKGROUND

As depicted in FIGS. 1A-1B, a typical axial/in-line laparoscopic tool device **100** generally has five main components: a handle **102**, an outer shaft **104** extending longitudinally from the handle, an actuation rod **106** extending through the outer shaft, and an actuatable end effector **110**, disposed at the distal end of the device. The handle **102** illustrated is an "in-line handle", which has a stationary handle portion **112** attached to the outer shaft **104** and an actuatable handle portion **114** attached to the actuation rod **106**. Actuation of the actuatable handle portion **114** by pivoting relative to the stationary handle portion **112** moves the actuation rod **106** axially within the outer shaft **104** to operate the end effector **110**. The actuatable handle portion **114** typically is biased into an open position by a spring such as a hinge spring **115**. Some existing devices include a ratchet mechanism to hold the handle portions **112**, **114** in a selected position relative to each other. As shown in FIGS. 1A-1B, a known ratchet has a pawl arm **118** that engages a ratchet-toothed arm **120**. The ratchet is biased into a disengaged position, but it can be selectably engaged/disengaged by actuating and holding in place a ratchet lever **122** or it can be lockedly disengaged by actuating a separate, transversely mounted, ratchet-locking button **124** that holds the ratchet-toothed element **120** at an angle configured to remain disengaged from the pawl element **118**. With this configuration, a user may be required to use his/her opposite hand and/or to change grip position on the handle **102** to reach and actuate the ratchet-locking button **124**.

Although different variations of each of the above components have been introduced into the art, there exists a need for designs that provide efficiency in manufacturing, and that provide surgeons and other users with ergonomic features to enhance safety and ease of use. In particular, there is a need for a handle design that includes an easy-to-use locking feature having a minimal number of components to provide for ease of assembly and durability. In particular, there is a need for a durable handle design including a ratchet mechanism that can easily be operated by the user's gripping hand from a variety of grip positions, without requiring a user to significantly alter his/her grip, or to use his/her other hand to engage, disengage, and lock the mechanism.

BRIEF SUMMARY

Embodiments of the present invention may be configured to address the needs in the art for ergonomic designs that present advantages in use and manufacture. Preferred embodiments of the present invention will be configured such that they may be sterilized and reused. In one aspect, embodiments of the present invention may include a ratchet mechanism that is biased such that it engages the handle members with each other when the ratchet mechanism is in a default/

rest position. A preferred ratchet mechanism may be configured such that it can be actuated (i.e., engaged, released, or defeated) using a single button, lever, slide, switch, or other actuation means that is positioned conveniently for a user such that the user's grip not be changed significantly for ratchet actuation. This provides an advantage over the prior art ratchet mechanisms that require actuation of two or more separate components and/or that require a user to significantly alter his/her grip—or even require use of another hand (of the user or an assistant)—to actuate a ratchet mechanism between engaged, released, and defeated states. Although embodiments of the present invention are directed to aspects of the handle for a laparoscopic surgical device, those of skill in the art will appreciate that handle embodiments of the present invention may be used with different shaft configurations and end effectors (e.g., needle holders, clamps, scissors, dissectors, graspers), and that such uses are within the scope of the present invention.

In one aspect, the present invention includes an in-line surgical instrument having a handle operatively connected to an elongate shaft, the handle comprising: a first handle member pivotably connected to a second handle member, said pivotable connection being located near a proximal end of both handle members; a first engagement member fixed in and projecting from the first handle member toward the second handle member, a first end portion of the first engagement member being biased into engagement with the second engagement member; and a camming switch pivotably connected to the first handle member and in mechanical communication by an operative contact with the first engagement member; wherein, when the camming switch is disposed at a first angle relative to the first engagement member, the operative contact provided is sufficient to pivot the first engagement member so as to disengagingly overcome the biased engagement of the first engagement member with the second engagement member; and wherein, when the camming switch is at a second angle relative to the first engagement member, the operative contact is sufficient to pivot the first engagement member so as to overcome the biased engagement of the first engagement member with the second engagement member and is sufficient to bias the first engagement member out of engagement with the second engagement member.

In another aspect, the present invention includes an in-line surgical instrument having a handle operatively connected to an elongate shaft, the handle comprising: a first handle member; a second handle member pivotably connected to the first handle member near a proximal end of both handle members; and a ratchet mechanism disposed distal relative to the pivotable connection and configured for removably engaging the first and second handle members, the ratchet mechanism comprising first and second ratchet mechanism portions; wherein the first ratchet mechanism portion comprises: an L-shaped ratchet-toothed engagement member; a cammed lever member; and a camming switch; wherein the L-shaped ratchet-toothed engagement member is mounted pivotably to and projects from the first handle member toward the second handle member, the L-shaped ratchet-toothed engagement member comprising a toothed portion generally perpendicular to a lever-arm projection portion; wherein the camming switch is mounted pivotably to and projects from the first handle member away from the second handle member; wherein the cammed lever member comprises a camming end, a levering end, a pivot axis therebetween connecting the cammed lever member pivotably to the first handle member; and wherein the camming switch contacts the camming end of the cammed lever member and the levering end of the cammed lever member contacts the lever-arm projection of

the L-shaped ratchet-toothed engagement member; the camming end comprising a protruding camming surface and a depressed camming surface; and wherein the second ratchet mechanism portion comprises: a pawl member mounted to the second handle member, the pawl member including a pawl tooth portion and a pawl leg portion, wherein the pawl tooth portion projects toward, and is configured to engage with, the toothed portion of the ratchet-toothed engagement member; and wherein, a biasing spring contacting the L-shaped ratchet-toothed engagement member biases said L-shaped ratchet-toothed engagement member into engagement with the pawl tooth portion; and wherein, the camming switch and the camming end of the cammed lever member are configured such that when the camming switch is disposed at a first angle relative to the cammed lever member, a first operative contact between the camming switch and the protruding camming surface of the cammed lever member levers the L-shaped ratchet-toothed engagement member out of its biased engagement with the pawl tooth portion of the pawl member; and wherein, the camming switch and the camming end of the cammed lever member are also configured such that when the camming switch is disposed at a second angle relative to the cammed lever member, a second operative contact between the camming switch and the depressed camming surface of the cammed lever member levers the L-shaped ratchet-toothed engagement member out of its biased engagement with the pawl tooth portion of the pawl member.

In yet another aspect, the present invention includes a single-switch release/defeat ratchet mechanism for an in-line surgical instrument handle, the ratchet mechanism comprising: a cam switch member, a pivotable ratchet member in operative contact with the cam switch member, a biasing member, and a pawl member; wherein, when the mechanism is in a ratchet-engaged state, the cam switch member occupies a neutral first position such that the operative contact is minimal and the biasing member biases the ratchet member into engagement with the pawl member; wherein, when the mechanism is in a ratchet-released state, the cam switch member occupies a second position such that the operative contact opposes the bias of the biasing member and releases the ratchet member from engagement with the pawl member; and wherein, when the mechanism is in a ratchet-defeated state, the cam switch member occupies a third position such that the operative contact biases the ratchet member out of engagement with the pawl member.

In still another aspect, the present invention includes an in-line surgical instrument having a handle ratchet mechanism with a single-switch release/defeat feature, the handle ratchet mechanism comprising: a first engagement member; a second engagement member pivotably mounted to a handle portion and projecting toward the first engagement member, a first end portion of the second engagement member being spring-biased into engagement with the first engagement member; and a cam switch movably connected to the handle portion and comprising an operative contact with a second end portion of the second engagement member; wherein, when the cam switch is oriented at a first position relative to the second engagement member, the operative contact is sufficient to pivot the second engagement member so as to overcome the spring-biased engagement of the second engagement member with the first engagement member; and wherein, when the cam switch is oriented at a second position relative to the second engagement member, the operative contact is sufficient to pivot the second engagement member so as to overcome the biased engagement of the second engagement member with the first engagement member and

is also sufficient to bias the second engagement member out of engagement with the first engagement member.

In still yet another aspect, the present invention includes an in-line surgical instrument having a handle operatively connected to an elongate shaft, the handle comprising: a first handle member pivotably connected near a proximal end thereof to a second handle member near a proximal end thereof; a ratchet-toothed engagement member comprised by the first handle member; a pawl engagement member pivotably mounted in the second handle member, a portion of the toothed engagement member being biased into engagement with the pawl engagement member; and an elongate camming switch pivotably connected to the first handle member and comprising an operative contact with a surface of the toothed engagement member; wherein, when the elongate camming switch is oriented in a first position relative to the toothed engagement member, the operative contact provides a force sufficient to overcome the biased engagement of the toothed engagement member with the pawl engagement member; and wherein, when the elongate camming switch is oriented in a second position relative to the toothed engagement member, the operative contact is sufficient to pivot the toothed engagement member so as to overcome the biased engagement of the toothed engagement member with the pawl engagement member and is sufficient to bias the toothed engagement member out of engagement with the pawl engagement member.

In still another aspect, the present invention includes an in-line surgical instrument having a handle operatively connected to an elongate shaft, the handle comprising: a ratchet mechanism configured to be engaged, released, and defeated by actuation of a single actuation means.

BRIEF DESCRIPTION OF THE DRAWINGS

FIGS. 1A-1B show a prior art laparoscopic tool device;

FIGS. 2A-2B illustrate, respectively, perspective and side elevation views of a laparoscopic device incorporating a first handle embodiment of the present invention;

FIG. 3 depicts a perspective view of a partially exploded handle embodiment of the present invention;

FIGS. 3A-3C show, respectively, engaged, released, and defeated states of a ratchet mechanism of the present invention in a first handle embodiment;

FIG. 3D shows a side view of a handle embodiment of the present invention with an indexed rotation knob being rotated;

FIGS. 4A-4D depict four of the grips that a user may utilize with the first handle embodiment;

FIGS. 5A-5B illustrate, respectively, side elevation and perspective views of a laparoscopic device incorporating a second handle embodiment of the present invention; and

FIGS. 6A-6C show, respectively, engaged, released, and defeated states of a ratchet mechanism of the present invention in a second handle embodiment.

DETAILED DESCRIPTION

A first embodiment of a handle **202** for a laparoscopy device **200** is illustrated with reference to FIGS. 2A-2B and FIGS. 3-3D. The handle **202** includes a first handle member **204** pivotably attached at a pivot pin **208** to a second handle member **206**. The first and second handle members **204**, **206** preferably may be constructed of a resin material but may also be constructed of plastic, metal, or other materials known in the art to be suitable for multiple sterilizations in an autoclave. A single-use embodiment may also be constructed of mate-

rials known in the art. An elongate tubular shaft **280** extends distally from the second handle member **206**, and preferably will be configured to be axially rotatable. An actuation rod **282** extends distally from the first handle member **204** through the shaft **280**. At the distal end of the device **200**, an end effector **284** (e.g., grasper, scissors, forceps, dissector, needle holder, clamp) is operably connected both to the shaft **280** and the actuation rod **282**. Those of skill in the art will appreciate that this configuration provides for actuation of the end effector **284** by pivoting the first handle member **204** relative to the second handle member **206** (see, e.g., U.S. Pat. Nos. 5,498,256 and 5,827,263).

In the embodiment illustrated in FIGS. 2A-3D, a ratchet mechanism **230**, embodied as a single-switch release/defeat ratchet mechanism, is mounted in the handle **202** and configured to selectively secure the first handle member **204** at a user-selected angle to the second handle member **206**.

FIG. 3 shows a partially exploded view of the handle **202**. FIG. 3A shows a longitudinal section view of a portion of the handle **202**, and is magnified to show greater detail of the ratchet mechanism than is depicted in FIGS. 3B-3D, which show the entire handle in longitudinal section. The upper proximal region of the second handle member **206** is constructed to engage the first handle member **204**. Specifically, the upper proximal region includes an upwardly-extending pair of arms **216** with a pivot aperture **218** that extends through the arms **216** and that is configured for engaging the pivot pin **208** (depicted as a dual sexbolt) on either side of an upper proximal region of the first handle member **204**. The proximal lower region of the first handle member **204** is configured to receive a ball **286** (or other actuation-rod-retaining structure) on the proximal end of the actuation rod **282**. The distal upper surface of the first handle member **204** may include a depressed surface **204a** configured to aid a user's grip and/or tactile sensory location of the handle end. In the illustrated embodiment, a pair of wire springs **299** (preferably formed of a nickel-titanium shape-memory alloy such as nitinol or another suitable material) may be mounted to the proximal portion of the first handle portion **204** and configured to contact an inner surface of the second handle portion **206** in a manner that biases the first handle portion **204** to pivot away from the second handle portion **206**. As a result of this bias, the default position of the handle **202** will be for the handle members **204**, **206** to be spread apart. Additionally, this bias may help to maintain engaging tension within a ratchet mechanism **230** (described below) when it is engaged. Those of skill in the art will appreciate that other embodiments configured to bias apart the handles may be practiced within the scope of the present invention such as, for example, one or more compression springs, hinge springs, an elastomeric structure or other biasing means known or developed in the art.

In the embodiment illustrated, an indexed rotation knob **288** rotatably overlaps the distal exterior of the upper region of the second handle member **206** and is attached to the shaft **280**. The rotation knob **288** preferably includes a flush port **289** open to the interior of the shaft **280** and configured to provide fluid communication thereto. (See, e.g., U.S. Pat. No. 5,489,290, which is incorporated herein by reference, for illustration of a representative flush port/rotation knob mechanism). The rotation knob **288** provides means for rotating the shaft **280** about its longitudinal axis, relative to the handle **202**. The knob **288** preferably is disposed in an ergonomically-oriented position such that a user may rotate it without removing or significantly altering his/her grip on the handle **202**, and its outer surface preferably includes a plurality of broad grooves to provide purchase for the user's

finger. Rotation of the shaft by rotating the knob **288** preferably will be indexed (for example, by use of a ball detent) to allow precise, controlled rotation of the shaft **280** that may be in a smooth or an incremental manner. By way of illustration, FIG. 3D shows an external side view of the handle **202** with the knob **288** rotated at an angle. Those of skill in the art will appreciate that other embodiments may be configured for use as a monopolar or bipolar electrosurgical instruments (e.g., by providing an electrode and appropriately insulated surfaces as is known in the art) within the scope of the present invention.

The handle **202** includes a ratchet mechanism **230**, described with reference to FIGS. 3A-3C, the design of which provides advantages for assembly of the device **200** and ease of use. An inverted-L-shaped ratchet-toothed member **231** is pivotably mounted (on a transverse pivot pin **231a**) in the first handle member **204**, together with a release/defeat camming lever or camming switch (which are used as equivalents herein)—shown here as a camming switch **232**—a cammed lever **233** that provides mechanical communication between the camming switch **232** and the ratchet-toothed member **231**. A leaf spring **234** may be mounted at one end to the ratchet-toothed member **231** to bias it (**231**) against the cammed lever **233**, and to bias the cammed lever **233** into contact with the camming switch **232**. A pawl member **238** is disposed in the second handle member **206** opposite the ratchet-toothed member **231**. The ratchet-toothed member **231** includes a slightly curved toothed projection **235** that extends out of the first handle member **204** toward the second handle member **206**. The pawl member **238** extends toward the first handle member **204** and includes a pawl tooth **237** that is configured to engage teeth on the toothed projection **235** of the ratchet-toothed member **231**. The cammed lever **233** also includes a depressed first camming surface **233b** on its upper side and a protruding second camming surface **233c** extending above and distally from the first camming surface **233b**. Those of skill in the art will appreciate that the biasing means embodied as leaf spring **234** may take other forms in other embodiments within the scope of the present invention, such as, for example, a compression or coil spring oriented adjacent any of the above-described components to provide the desired bias, or an elastomeric member configured to provide the desired bias.

The proximal end of the leaf spring **234** is secured to the ratchet-toothed member **231** below that member's pivot pin **231a** and oriented such that its distal contact surface contacts the lower side of the cammed lever **233** distal of its (**233**) fulcrum/pivot axis at mounting/pivot pin **233a**, thereby simultaneously biasing the distal portion of the cammed lever **233** generally upward and biasing the lower portion (below the pivot pin **231a**) of the ratchet-toothed member **231** generally proximally. The camming switch **232** is pivotably attached to the first handle member **206** by a cam switch pivot pin **232a**. In an alternative embodiment, the relative positions of the ratchet-toothed member **231** and the pawl member **238** may be reversed (for example, such that the pawl member is pivotably disposed in the first handle member and the ratchet-toothed member is disposed in the second handle member). Those of skill in the art will appreciate that this reversibility of the complementary/engaging surfaces is applicable to other embodiments of the present invention and that other variations of the illustrated embodiments may be practiced within the scope of the present invention. Those of skill in the art will also appreciate that, within the scope of the present invention, the entire mechanism may also be reversed in orientation—

such as, for example, with the camming switch 232 and either a pawl or ratchet-toothed member being disposed in the non-pivoting handle member.

The ratchet mechanism 230 can be actuated to one of three user-selected states (engaged, released, and defeated), which are described, respectively, with reference to FIGS. 3A, 3B, and 3C.

As shown in FIG. 3A, when the ratchet mechanism 230 is in an engaged state, the teeth of the ratchet-toothed projection 235 engage the pawl tooth 237 of the pawl member 238. This engagement prevents the first handle 204 from being moved away from the second handle 206 (e.g., by the handle-separating bias of the wire springs 299), but allows it to be moved closer to the second handle 206 with auditory and tactile feedback as the ratchet teeth move incrementally across the pawl tooth 237. In the engaged state, pawl tooth contact with the ratchet-toothed projection 235 of the ratchet-toothed member 231 is maintained by the bias of the leaf spring 234 against the underside of the cammed lever 233. This leaf spring bias exerts a proximal force against the portion of the ratchet-toothed member 231 (below its pivot axis 231a), thereby pivoting the ratchet-toothed member 231 about its pivot axis 231a such that the curved, toothed projection 235 is directed proximally into engagement with the pawl tooth 237 of the pawl member 238 in the second handle member 206. When the handle 202 is in the engaged position, the camming switch 232 is at rest (in a neutral central position in the illustrated embodiment) and does not have significant operative contact with the cammed lever 233. In the illustrated embodiment the bias-apart effect of the wire springs 299 on the handle members 204, 206 provides a tension that may help to maintain a contact tension between the ratchet-toothed member 231 and the pawl member 238.

As shown in FIG. 3B, when the ratchet mechanism 230 is in a released state, the teeth of the ratchet-toothed projection 235 are disengaged from the pawl tooth 237 of the pawl member 238. This disengagement allows the first handle 204 freely to be moved toward or away from the second handle 206. The released state is effected by pivoting the upper end of the camming switch 232 in a distal direction. When pivoted thus, the camming switch 232 is dynamically held in operative contact against the protruding second camming surface 233c of the cammed lever 233. This contact levers downward the distal portion of the cammed lever 233 (distal of the cammed lever pivot pin 233a) against the bias of the leaf spring 234. Consequently, a proximal portion of the cammed lever 233 is levered upward against an upper distal projection 231b of the ratchet toothed member 231, thereby levering it (231) to rotate about its pivot pin 231a such that its lower portion (the ratchet-toothed projection 235) pivots distally and out of engagement with the pawl tooth 237 of the pawl member 238 in the second handle member 206. In order to maintain the released state, the camming switch 232 must be held in the rotated-distal/forward position (to resist the bias of the leaf spring 234). Releasing the camming switch 232 allows the bias of the leaf spring 234 to return the ratchet mechanism 230 to its engaged state.

The ratchet mechanism 230 is in a defeated state in FIG. 3C, wherein the ratchet-toothed projection 235 is disengaged from the pawl tooth 237 of the pawl member 238, allowing the handle portions 204, 206 to travel through a full range of motion without engagement of the ratchet mechanism 230, and without a user exerting dynamic pressure on the camming switch 232 (as is required in the released state). The defeated state is effected by pivoting the upper end of the camming switch 232 into a proximal position. In this defeated state, the lower portion of the camming switch 232 is locked in opera-

tive contact against the depressed first camming surface 233b of the cammed lever 233. This contact levers downward the distal portion of the cammed lever 233 (distal of the cammed lever pivot pin 233a) against the bias of the leaf spring 234. Consequently, a proximal portion of the cammed lever 233 is levered upward against the distal projection 231b of the ratchet toothed member 231, thereby levering it to rotate about its pivot pin 231a such that its lower portion (the ratchet-toothed projection 235) will pivot distally and out of engagement with the pawl tooth 237 of the pawl member 238 in the second handle member 206. The "locked" status of the camming switch 232 in the defeated state is effected by the upward bias of the leaf spring 234 on the cammed lever 233 against the camming switch 232. Specifically the camming switch is locked into a proximally rotated position as its lower portion (below the pivot pin 232a) is pivoted past a point of inflection such that the depressed first cam-engaging surface 233b contacts the camming switch 232 and the upward bias of the leaf spring 234 on the cammed lever 233 against the camming switch 232 effectively enables the depressed first cam-engaging surface 233b to capture the lower portion of the camming switch 232.

Those of skill in the art will appreciate that the handle 202 may be allowed to be sufficiently open such that the ratchet-toothed member 231 is longitudinally separated from the pawl member 238 and positioning the camming switch 232 at an angle associated with the engaged, released, or defeated states will prepare the handle for a desired state when the handle members 204, 206 are pivoted toward each other. Those of skill in the art will also appreciate that, in other embodiments within the scope of the present invention, a camming switch may be configured to roll or slide relative to the cammed lever 233 rather than pivoting, and/or a camming switch (such as, for example, the camming switch 232) may be configured to have a direct operative contact with a ratchet-toothed member or a pawl member together with, or in the absence of a cammed lever.

FIGS. 4A-4D show four examples of grip positions that a user may utilize with the device 200 having a handle 202. These grips may be selected based upon one or more of a user's style, personal preference; comfort, necessity of orientation angle (such as, for example, due to port placement and/or trocar angle during a laparoscopic procedure), or any other reason a user may wish to utilize or alter his/her grip. Those of skill in the art will appreciate that the handle shape and the position and function of the ratchet mechanism 231 described above present advantages for a user to operate the device from a variety of angles and positions during a procedure such as, for example, a laparoscopic bariatric surgical procedure. Specifically, those of skill in the art will appreciate that users may choose variants of the grips shown, or may use other grips, but that virtually all practical grip positions will provide for easy actuation of the ratchet mechanism 230 without the user significantly altering his/her grip and without requiring another hand to actuate the ratchet mechanism 230 using the camming switch 232.

A second embodiment of a handle 502 for a laparoscopy device 500 is illustrated with reference to FIGS. 5A-5B and FIGS. 6A-6C. FIG. 5A shows a side view of the device 500, and FIG. 5B shows a top perspective view of the device handle 502. The handle 502 includes a first handle member 504 pivotably attached at a pivot pin 508 to a second handle member 506. The first and second handle members 504, 506 preferably may be constructed of a resin material but may also be constructed of plastic, metal, or other materials known in the art to be suitable for multiple sterilizations in an autoclave. A single-use embodiment may also be constructed of mate-

rials known in the art. An elongate tubular shaft **580** extends distally from the second handle member **506**, and preferably will be configured to be axially rotatable. An actuation rod **582** extends distally from the first handle member **504** through the shaft **580**. At the distal end of the device **500**, an end effector **584** (e.g., a tool tip such as, for example, grasper, scissors, forceps, dissector, clamp, needle holder) is operably connected both to the shaft **580** and the actuation rod **582**. Those of skill in the art will appreciate that this configuration provides for actuation of the end effector **584** by pivoting the first handle member **504** relative to the second handle member **506** (see, e.g., U.S. Pat. Nos. 5,498,256 and 5,827,263).

The handle embodiment **502** may be substantially similar to the handle embodiment **202** described above, except that the second handle member **506** includes a distal bend **506a** configured to allow a user the ability to exert a desired rotational torque for rotating the distal tool tip **584**. Accordingly, a transition member **582a** and rod anchor member **582b** are included between the proximal end of the actuation rod **582** and the first handle member **504**, and are configured for transmitting longitudinal motion from the handle **502** through the actuation rod **582** to the tool tip **584**. Those of skill in the art will appreciate that this handle configuration may be particularly well adapted for use with, for example, a laparoscopic needle grasper used for suturing with a curved needle wherein a user desires to rotate the shaft and tip about a longitudinal axis. It should also be appreciated that, for the purpose of this application, the term “in-line surgical instrument” includes the embodiments of all of FIGS. 2A-6C, whether the handle portion is strictly axial or includes the angled offset of FIGS. 5A-6C.

In the embodiment illustrated in FIGS. 6A-6D, a ratchet mechanism **530**, embodied as a single-switch release/defeat ratchet mechanism, is mounted in the handle **502** and configured to selectably secure the first handle member **504** at a user-selected angle to the second handle member **506**.

FIG. 6 shows a partially exploded view of the handle **502**. FIG. 6A shows a longitudinal section view of a portion of the handle **502**, and is magnified to show greater detail of the ratchet mechanism than is depicted in FIGS. 6B-6C, which show the entire handle in longitudinal section. The upper proximal region of the second handle member **506** is constructed to engage the first handle member **504**. Specifically, the upper proximal region includes an upwardly-extending pair of arms **516** with a pivot aperture **518** that extends through the arms **516** and that is configured for engaging the pivot pin **508** (depicted as a dual sexbolt) on either side of an upper proximal region of the first handle member **504**. The proximal lower region of the first handle member **504** is configured to receive a ball **586** (or other actuation-rod-retaining structure) on the proximal end of the actuation rod **582**. The distal upper surface of the first handle member **504** may include a depressed surface **504a** configured to aid a user's grip and/or tactile sensory location of the handle end. In the illustrated embodiment, a pair of wire springs **599** (preferably formed of a nickel-titanium shape-memory alloy or another suitable material) may be mounted to the proximal portion of the first handle portion **504** and configured to contact an inner surface of the second handle portion **506** in a manner that biases the first handle portion **504** to pivot away from the second handle portion **506**. As a result of this bias, the default position of the handle **502** will be for the handle members **504**, **506** to be spread apart. Additionally, this bias may help to maintain engaging tension within a ratchet mechanism **530** (described below) when it is engaged.

In the embodiment illustrated, an indexed rotation knob **588** rotatably overlaps the distal exterior of the upper region

of the second handle member **506** and is attached to the shaft **580**. The rotation knob **588** preferably includes a flush port **589** open to the interior of the shaft **580**. (See, e.g., U.S. Pat. No. 5,489,290, which is incorporated herein by reference, for illustration of a representative flush port/rotation knob mechanism). The rotation knob **588** provides means for rotating the shaft **580** about its longitudinal axis, relative to the handle **502**. The knob **588** preferably is disposed in an ergonomically-oriented position such that a user may rotate it without removing or significantly altering his/her grip on the handle **502**, and its outer surface preferably includes a plurality of broad grooves to provide purchase for the user's finger. Rotation of the shaft by rotating the knob **588** preferably will be indexed (for example, by use of a ball detent) to allow precise, controlled rotation of the shaft **580** that may be in a smooth or an incremental manner.

The handle **502** includes a ratchet mechanism **530**, described with reference to FIGS. 6A-6C, the design of which provides advantages for assembly of the device **500** and ease of use. An inverted-L-shaped ratchet-toothed member **531** is pivotably mounted (on a transverse pivot pin **531a**) in the first handle member **504**, together with a release/defeat switch—shown here as a camming switch **532**, a cammed lever **533** that provides mechanical communication between the camming switch **532** and the ratchet-toothed member **531**. A leaf spring **534** mounted at one end to the ratchet-toothed member **531** biases it (**531**) against the cammed lever **533**, and biases the cammed lever **533** into contact with the camming switch **532**. A pawl member **538** is disposed in the second handle member **506** opposite the ratchet-toothed member **531**. The ratchet-toothed member **531** includes a slightly curved toothed projection **535** that extends out of the first handle member **504** toward the second handle member **506**. The pawl member **538** extends toward the first handle member **504** and includes a pawl tooth **537** that is configured to engage with teeth of the toothed projection portion **535** of the ratchet-toothed member **531**. The cammed lever **533** also includes a depressed first camming surface **533b** on its upper side and a protruding second camming surface **533c** extending above and distally from the first camming surface **533b**.

The proximal end of the leaf spring **534** is secured to the ratchet-toothed member **531** below that member's pivot pin **531a** and oriented such that its distal contact surface contacts the lower side of the cammed lever **533** distal of its (**533**) pivot axis at mounting/pivot pin **533a**, thereby simultaneously biasing the distal portion of the cammed lever **533** generally upward and biasing the lower portion (below the pivot pin **531a**) of the ratchet-toothed member **531** generally proximally. The camming switch **532** is pivotably attached to the first handle member **506** by a cam switch pivot pin **532a**. In an alternative embodiment, the relative positions of the ratchet-toothed member **531** and the pawl member **538** may be reversed (such that the pawl member is pivotably disposed in the first handle member and the ratchet toothed member is disposed in the second handle member). Those of skill in the art will appreciate that this reversibility of the complementary/engaging surfaces is applicable to other embodiments of the present invention and that other variations of the illustrated embodiments may be practiced within the scope of the present invention.

The ratchet mechanism **530** can be actuated to one of three user-selected states (engaged, released, and defeated), which are described, respectively, with reference to FIGS. 6A, 6B, and 6C.

As shown in FIG. 6A, when the ratchet mechanism **530** is in an engaged state, the teeth of the ratchet-toothed projection **535** engage the pawl tooth **537** of the pawl member **538**. This

engagement prevents the first handle **504** from being moved away from the second handle **506** (e.g., by the handle-separating bias of the wire springs **599**), but allows it to be moved closer to the second handle **506** with auditory and tactile feedback as the ratchet teeth move incrementally across the pawl tooth **537**. In the engaged state, pawl tooth contact with the ratchet-toothed projection **535** of the ratchet-toothed member **531** is maintained by the bias of the leaf spring **534** against the underside of the cammed lever **533**. This leaf spring bias exerts a proximal force against the portion of the ratchet-toothed member **531** (below its pivot axis **531a**), thereby pivoting the ratchet-toothed member **531** about its pivot axis **531a** such that the curved, toothed projection **535** is directed proximally into engagement with the pawl tooth **537** of the pawl member **538** in the second handle member **506**. When the handle **502** is in the engaged position, the camming switch **532** is at rest (in a neutral central position in the illustrated embodiment) and does not have significant operative contact with the cammed lever **533**. In the illustrated embodiment the bias-apart effect of the wire springs **599** on the handle members **504**, **506** provides a tension that may help to maintain a contact tension between the ratchet-toothed member **531** and the pawl member **538**.

As shown in FIG. **6B**, when the ratchet mechanism **530** is in a released state, the teeth of the ratchet-toothed projection **535** are disengaged from the pawl tooth **537** of the pawl member **538**. This disengagement allows the first handle **504** freely to be moved toward or away from the second handle **506**. The released state is effected by pivoting the upper end of the camming switch **532** in a distal direction. When pivoted thus, the camming switch **532** is dynamically held in operative contact against the protruding second camming surface **533c** of the cammed lever **533**. This contact levers downward the distal portion of the cammed lever **533** (distal of the cammed lever pivot pin **533a**) against the bias of the leaf spring **534**. Consequently, a proximal portion of the cammed lever **533** is levered upward against an upper distal projection **531b** of the ratchet toothed member **531**, thereby levering it (**531**) to rotate about its pivot pin **531a** such that its lower portion (the ratchet-toothed projection **535**) pivots distally and out of engagement with the pawl tooth **537** of the pawl member **538** in the second handle member **506**. In order to maintain the released state, the camming switch **532** must be held in the rotated-distal/forward position (to resist the bias of the leaf spring **534**). Releasing the camming lever **532** allows the bias of the leaf spring **534** to return the ratchet mechanism **530** to its engaged state.

The ratchet mechanism **530** is in a defeated state in FIG. **6C**, wherein the ratchet-toothed projection **535** is disengaged from the pawl tooth **537** of the pawl member **538**, allowing the handle portions **504**, **506** to travel through a full range of motion without engagement of the ratchet mechanism **530**, and without a user exerting dynamic pressure on the camming switch **532** (as is required in the released state). The defeated state is effected by pivoting the upper end of the camming switch **532** into a proximal position. In this defeated state, the lower portion of the camming switch **532** is locked in operative contact against the depressed first camming surface **533b** of the cammed lever **533**. This contact levers downward the distal portion of the cammed lever **533** (distal of the cammed lever pivot pin **533a**) against the bias of the leaf spring **534**. Consequently, a proximal portion of the cammed lever **533** is levered upward against the distal projection **531b** of the ratchet toothed member **531**, thereby levering it to rotate about its pivot pin **531a** such that its lower portion (the ratchet-toothed projection **535**) will pivot distally and out of engagement with the pawl tooth **537** of the pawl member **538**

in the second handle member **506**. The “locked” status of the camming switch **532** in the defeated state is effected by the upward bias of the leaf spring **534** on the cammed lever **533** against the camming switch **532**. Specifically the camming switch is locked into a proximally rotated position as its lower portion (below the pivot pin **532a**) is pivoted past a point of inflection such that the depressed first cam-engaging surface **533b** contacts the camming switch **532** and the upward bias of the leaf spring **534** on the cammed lever **533** against the camming switch **532** effectively enables the depressed first cam-engaging surface **533b** to capture the lower portion of the camming switch **532**.

Those of skill in the art will appreciate that the handle **502** may be allowed to be sufficiently open such that the ratchet-toothed member **531** is longitudinally separated from the pawl member **538** and positioning the camming switch **532** at an angle associated with the engaged, released, or defeated states will prepare the handle for a desired state when the handle members **504**, **506** are pivoted toward each other.

Those of skill in the art will appreciate that curved exterior surfaces of the handle embodiments of the present invention may provide a distinctive ornamental appearance of the device. The curved surfaces may also provide ergonomic advantages for a user, which could also be provided by curved surfaces having a different ornamental appearance. It is intended that the foregoing detailed description be regarded as illustrative rather than limiting. It should be understood that the following claims, including all equivalents, are intended to define the spirit and scope of this invention.

We claim:

1. An in-line surgical instrument having a handle operatively connected to an elongate shaft, the handle comprising:
 - a first handle member;
 - a second handle member pivotably connected to the first handle member near a proximal end of both handle members; and
 - a ratchet mechanism disposed distal relative to the pivotable connection and configured for removably engaging the first and second handle members, the ratchet mechanism comprising first and second ratchet mechanism portions,
 - wherein the first ratchet mechanism portion comprises:
 - an L-shaped ratchet-toothed engagement member;
 - a cammed lever member; and
 - a camming switch;
 - wherein the L-shaped ratchet-toothed engagement member is mounted pivotably to and projects from the first handle member toward the second handle member, the L-shaped ratchet-toothed engagement member comprising a toothed portion generally perpendicular to a lever-arm projection portion;
 - wherein the camming switch is mounted pivotably to and projects from the first handle member away from the second handle member;
 - wherein the cammed lever member comprises a camming end, a levering end, a pivot axis therebetween connecting the cammed lever member pivotably to the first handle member; and
 - wherein the camming switch contacts the camming end of the cammed lever member and the levering end of the cammed lever member contacts the lever-arm projection of the L-shaped ratchet-toothed engagement member;
 - the camming end comprising a protruding camming surface and a depressed camming surface; and
 - wherein the second ratchet mechanism portion comprises:

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a pawl member mounted to the second handle member, the pawl member including a pawl tooth portion and a pawl leg portion, wherein the pawl tooth portion projects toward, and is configured to engage with, the toothed portion of the ratchet-toothed engagement member; and
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wherein, a biasing spring contacting the L-shaped ratchet-toothed engagement member biases said L-shaped ratchet-toothed engagement member into engagement with the pawl tooth portion when the camming switch is oriented at a neutral position
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between a first angle and a second angle; and
wherein, the camming switch and the camming end of the cammed lever member are configured such that when the camming switch is disposed at the first angle
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relative to the cammed lever member, a first operative contact between the camming switch and the protruding camming surface of the cammed lever member levers the L-shaped ratchet-toothed engagement

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member out of its biased engagement with the pawl tooth portion of the pawl member; and
wherein, the camming switch and the camming end of the cammed lever member are also configured such that when the camming switch is disposed at the second angle relative to the cammed lever member, a second operative contact between the camming switch and the depressed camming surface of the cammed lever member levers the L-shaped ratchet-toothed engagement member out of its biased engagement with the pawl tooth portion of the pawl member.
2. The in-line surgical instrument of claim 1, wherein the second operative contact comprises a frictional engagement simultaneously locking the camming switch at the second angle and the L-shaped ratchet-toothed engagement member out of its biased engagement with the pawl tooth portion of the pawl member.

* * * * *

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摘要(译)

提供一种在线腹腔镜手术器械，包括棘轮机构。棘轮机构包括单个致动装置，该致动装置可用于接合，释放或击败手柄的部分之间的棘轮接合。

