

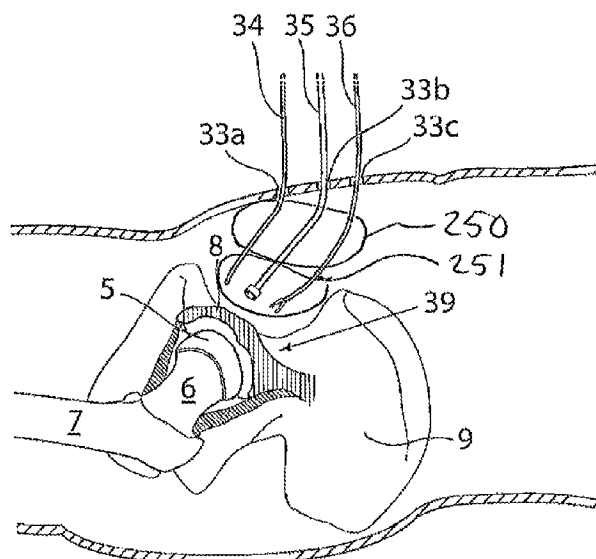


(51) International Patent Classification:		0900973-9	10 July 2009 (10.07.2009)	SE
<i>A61F 2/46</i> (2006.01) <i>A61B 17/16</i> (2006.01)		0900974-7	10 July 2009 (10.07.2009)	SE
(21) International Application Number:		0900976-2	10 July 2009 (10.07.2009)	SE
PCT/SE2010/050823		0900978-8	10 July 2009 (10.07.2009)	SE
(22) International Filing Date:		0900958-0	10 July 2009 (10.07.2009)	SE
12 July 2010 (12.07.2010)		61/229,738	30 July 2009 (30.07.2009)	US
(25) Filing Language:		61/229,739	30 July 2009 (30.07.2009)	US
(26) Publication Language:		61/229,743	30 July 2009 (30.07.2009)	US
English		61/229,745	30 July 2009 (30.07.2009)	US
English		61/229,746	30 July 2009 (30.07.2009)	US
(30) Priority Data:		61/229,747	30 July 2009 (30.07.2009)	US
0900981-2	10 July 2009 (10.07.2009)	61/229,748	30 July 2009 (30.07.2009)	US
0900957-2	10 July 2009 (10.07.2009)	61/229,751	30 July 2009 (30.07.2009)	US
0900959-8	10 July 2009 (10.07.2009)	61/229,752	30 July 2009 (30.07.2009)	US
0900960-6	10 July 2009 (10.07.2009)	61/229,755	30 July 2009 (30.07.2009)	US
0900962-2	10 July 2009 (10.07.2009)	61/229,761	30 July 2009 (30.07.2009)	US
0900963-0	10 July 2009 (10.07.2009)	61/229,767	30 July 2009 (30.07.2009)	US
0900965-5	10 July 2009 (10.07.2009)	61/229,778	30 July 2009 (30.07.2009)	US
0900966-3	10 July 2009 (10.07.2009)	61/229,786	30 July 2009 (30.07.2009)	US
0900968-9	10 July 2009 (10.07.2009)	61/229,789	30 July 2009 (30.07.2009)	US
0900969-7	10 July 2009 (10.07.2009)	61/229,796	30 July 2009 (30.07.2009)	US
0900970-5	10 July 2009 (10.07.2009)	61/229,735	30 July 2009 (30.07.2009)	US
0900972-1	10 July 2009 (10.07.2009)	SE		

[Continued on next page]

(54) Title: HIP JOINT INSTRUMENT AND METHOD

Fig. 7



(57) **Abstract:** A surgical instrument for operating hip joint osteoarthritis in a human patient is provided. The hip joint comprises an acetabulum, being a part of the pelvic bone, and a caput femur, being the proximal part of the femoral bone. The surgical instrument is adapted to assist in the operating of the hip joint osteoarthritis from the abdominal side of the pelvic bone of said human patient.



(71) **Applicant** (for all designated States except US): **MILUX HOLDING S.A.** [LU/LU]; 12, Rue Guillaume Schneider, L-2522 Luxemburg (LU).

(72) **Inventor; and**

(75) **Inventor/Applicant** (for US only): **FORSELL, Peter** [SE/CH]; Aegestrasse 66, CH-6300 Zug (CH).

(74) **Agent:** **BERGENSTRÄHLE & LINDVALL AB**; Box 17704, S-118 93 Stockholm (SE).

(81) **Designated States** (unless otherwise indicated, for every kind of national protection available): AE, AG, AL, AM, AO, AT, AU, AZ, BA, BB, BG, BH, BR, BW, BY, BZ, CA, CH, CL, CN, CO, CR, CU, CZ, DE, DK, DM, DO, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, GT, HN, HR, HU, ID, IL, IN, IS, JP, KE, KG, KM, KN, KP, KR, KZ, LA, LC, LK, LR, LS, LT, LU, LY, MA, MD, ME, MG, MK, MN, MW, MX, MY, MZ, NA, NG, NI, NO, NZ, OM, PE, PG, PH, PL, PT, RO, RS, RU, SC, SD,

SE, SG, SK, SL, SM, ST, SV, SY, TH, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, ZA, ZM, ZW.

(84) **Designated States** (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, GH, GM, KE, LR, LS, MW, MZ, NA, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European (AL, AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU, LV, MC, MK, MT, NL, NO, PL, PT, RO, SE, SI, SK, SM, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, ML, MR, NE, SN, TD, TG).

Published:

- with international search report (Art. 21(3))
- before the expiration of the time limit for amending the claims and to be republished in the event of receipt of amendments (Rule 48.2(h))

HIP JOINT INSTRUMENT AND METHOD

FIELD OF INVENTION

5 The present invention relates generally to a surgical instrument for use in treating of hip osteoarthritis in a human patient.

BACKGROUND

10 Hip Osteoarthritis is a syndrome in which low-grade inflammation results in pain in the hip joints, caused by abnormal wearing of the Cartilage that acts as a cushion inside of the hip joint. This abnormal wearing of the cartilage also results in a decrease of the joints lubricating fluid called Synovial fluid. Hip Osteoarthritis is estimated to affect 80% of all people over 65 years of age, in more or less serious forms.

The present treatments for hip osteoarthritis comprises NSAID drugs, local injections of Hyaluronic acid or Glucocorticoid to help lubricating the hip joint, and replacing parts of the hip joint with a prosthesis through hip joint surgery.

15 Replacing parts of the hip joint is one of the most common surgeries to date performed at hundreds of thousand of patients in the world every year. The most common method comprises placing a metal prosthesis in Femur and a plastic bowl in Acetabulum. This operation is done through a lateral incision in the hip and upper thigh, through Fascia Lata and the lateral muscles of the thigh. To get access to the joint, the supporting Fibrous Capsule
20 attached to Femur and Ilium needs to be penetrated, making it difficult to get a fully functional joint after the surgery. Femur is then cut at the neck with a bone saw and the prosthesis is placed in femur either with bone cement or without. Acetabulum is slightly enlarged using an Acetabular reamer, and the plastic bowl is positioned using screws or bone cement.

25 The surgery typically requires one week of hospitalization due to the increased risk of infection. The recovery process is on average about 6 weeks, but even after that the patient should not perform any physical activities that places large strain on the joint.

SUMMARY

A first object is to provide a surgical instrument for operating hip joint osteoarthritis in a human patient. The hip joint comprises an acetabulum being a part of the pelvic bone, and a caput femur being the proximal part of the femoral bone. The surgical instrument comprises an abdominal portion insertable through an incision in the skin in the abdominal region and adapted to be placed between the incision in the abdominal region and the pelvic bone when the instrument is in use, and a pelvic portion connected to the abdominal portion, being partially insertable through a hole in the pelvic bone from the abdominal side of the pelvic bone, when the instrument is in use, wherein a portion of the pelvic portion is adapted to operate at least partially in a surgically created hole in the pelvic bone.

According to one embodiment the surgical instrument is further adapted to operate through a hole in the pelvic bone of said human patient. For this purpose the instrument could be adapted to be bent, by means of: a fixed angle, an adjustable angle, a parallel displaced part or section, at least one gear wheel or at least one universal joint. It is furthermore conceivable that the surgical instrument is adapted to be curved in such a way that it is adapted to be introduced through the skin and further into the hole in the pelvic bone from the abdominal side thereof and further into the hip joint.

According to one embodiment the length of the surgical instrument is adapted to reach the hip joint from the abdominal side of said pelvic bone. The surgical instrument could further comprise a gripping end and an end reaching the hip joint, in which case the distance between said gripping end and a part of said surgical instrument adapted to be bent could be adapted for operating in a hip joint from the abdominal side of said pelvic bone. It is also conceivable that the length between said gripping end and said end reaching the hip joint is adapted for operating in a hip joint from the abdominal side of said pelvic bone.

According to another embodiment the surgical instrument is a special laparoscopic instrument introduced into the abdomen and further down to the pelvic bone on the opposite side of the acetabulum and introduced into the hip joint. The instrument could further comprise a gripping end, placed outside the abdominal wall when in use, and a hip joint end adapted to be placed in an area of the hip joint. The length of the instrument could be adapted to reach from the gripping end and into the hip joint via a surgically created hole in the pelvic bone

and wherein the longitudinal extension of the instrument comprises at least one bend, for the instrument to reach, when used as a special laparoscopic instrument to operate the hip joint, from the gripping end into the abdomen and further down to the pelvic bone on the opposite side of the acetabulum and be introduced into the hip joint through the surgically created hole
5 in the pelvic bone.

According to yet another embodiment the surgical instrument is a special pelvic instrument adapted to be introduced into the pelvic region and further to the pelvic bone on the opposite side of the acetabulum, and introduced into the hip joint via a surgically created hole in the
10 pelvic bone. The instrument could further comprise a gripping end, placed outside the skin above the pelvic region when in use, and a hip joint end adapted to be placed in an area of the hip joint, wherein the length of said instrument is adapted to reach from the gripping end and into the hip joint, and wherein the longitudinal extension of said instrument comprises at least one bend, for the instrument to reach, when used as special pelvic instrument to operate the
15 hip joint, from the gripping end into the pelvic region and further down to the pelvic bone on the opposite side of the acetabulum, and introduced into the hip joint through the surgically created hole in the pelvic bone.

According to yet another embodiment, the surgical instrument could be adapted to be a
20 special retroperitoneal instrument introduced into the body just above the inguinal region following the pelvic bone down to the opposite side of the acetabulum and thereafter introduced into the hip joint via a surgically created hole in the pelvic bone. The instrument could comprise a gripping end, placed outside the skin above the pelvic region when in use, and a hip joint end adapted to be placed in an area of the hip joint. The length of the
25 instrument is adapted to reach from the gripping end and into the hip joint and the longitudinal extension of said instrument comprises at least one bend, for the instrument to reach, when used as special retroperitoneal instrument to operate the hip joint, from the gripping end following the pelvic bone and further down to the pelvic bone on the opposite side of the acetabulum and introduced into the hip joint through the surgically created hole in
30 the pelvic bone.

The surgical instrument according to any of the embodiments could comprise at least one holding part and a mechanical element adapted to be fitted to the at least one holding part of

the instrument. The surgical instrument could be adapted to perform a function during an operation of the hip joint. The mechanical element could in turn be adapted to be part of an instrument adapted to be used for at least one of the following functions; drilling, reaming, cooling, heating, flushing, introducing a fluid, sucking, inserting at least one part, connecting
5 at least one part, fixating at least one part, inserting a mould, filling a mould, injecting, lubricating, viewing, optically displaying, placing screws, placing adhesive, placing bone cement.

The surgical instrument could have a distance between the gripping end and the bend that is at
10 least 10 cm, it is furthermore conceivable that the distance between the gripping end and the bend is at least 20 cm. It is furthermore conceivable that the distance between the gripping end and the bend is at least 30 cm. It is furthermore conceivable that the distance between the gripping end and the bend is at least 40 cm. It is furthermore conceivable that the distance between said gripping end and said bend is at least 50 cm.

15 According to one embodiment the surgical instrument comprises a bend, and wherein the bend is bent with an angle of at least 10 degrees, the bend is bent with an angle of at least 20 degrees or the bend is bent with an angle of at least 30 degrees, or the bend is bent with an angle of at least 40 degrees, or the bend is bent with an angle of at least 50 degrees, or the
20 bend is bent with an angle of at least 60 degrees.

According to one embodiment the of the surgical instrument, the distance between the bend and the hip joint end of the instrument is at least 2 cm, according to another embodiment the distance between the bend and the hip joint end of the instrument is at least 4 cm, according to
25 yet another embodiment the distance between the bend and the hip joint end of the instrument is at least 6 cm, according to yet another embodiment the distance between the bend and the hip joint end of the instrument is at least 8 cm, according to yet another embodiment the distance between the bend and the hip joint end of the instrument is at least 10 cm, according to yet another embodiment the distance between the bend and the hip joint end of the
30 instrument is at least 12 cm, according to yet another embodiment the distance between the bend and the hip joint end of the instrument is at least 14 cm,

APPLICATIONS OF THE INSTRUMENT

The surgical instrument could be adapted for a number of applications. According to a first embodiment the surgical instrument is adapted to create a through-going hole in the pelvic bone placed in the acetabulum area from the abdominal side of the pelvic bone of said human patient. According to this embodiment the surgical instrument could comprise: a driving member, a bone contacting organ in connection with said driving member, and an operating device adapted to operate said driving member.

According to one embodiment the surgical instrument is adapted to ream the acetabulum and or the caput femur of said human patient. According to this embodiment the surgical instrument could be adapted to be expandable, thus allowing the surgical instrument to be inserted through a hole in the pelvic bone smaller than the area possible to ream using said surgical instrument. The surgical instrument adapted to ream could comprise: a driving member, a bone contacting organ in connection with said driving member, and an operating device, adapted to operate said driving member. The bone contacting organ could comprise at least one of the materials: titanium, ceramics or stainless steel. The operating device could be: electrically operated hydraulically operated and comprise at least one camera and/or at least one light source.

According to one embodiment the surgical instrument is adapted to cool an area of the hip joint or the pelvic bone. The cooling could be provided using a cooling fluid and could be provided before, during or after the creation of a hole in the pelvic bone. It is also conceivable that the cooling is provided before, during or after a reaming operation.

According to one embodiment the surgical instrument is adapted to provide a fluid to an area of the pelvic bone or the hip joint. The fluid could be adapted to clean or sterilize an area of the pelvic bone or an area of the hip joint.

According to one embodiment the surgical instrument is adapted to provide suction to an area of the pelvic bone or the hip joint. The surgical instrument adapted to provide suction could further be adapted to transport body fluids, parts of bone, cartilage or a fluid provided during the hip joint surgery.

According to one embodiment the surgical instrument is adapted to introduce prosthesis or at least one prosthetic part into the hip joint. The prosthesis or prosthetic part could be acetabulum prosthesis or a part of acetabulum prosthesis or caput femur prosthesis or a part of caput femur prosthesis.

5

According to one embodiment the surgical instrument is adapted to connect at least two prosthetic parts to each other after insertion into the hip joint. The at least two prosthetic parts could comprises at least two artificial caput femur surface parts or at least two artificial acetabulum surface parts. The fixation could be done using at least one of: screws, form fitting, welding, adhesive, sprint, band, or other mechanical connecting members.

10

According to one embodiment the surgical instrument is adapted to fixate a hip joint surface, or a part of a hip joint surface, to the pelvic bone or the femur bone. The fixation could be done using at least one of: screws, form fitting, welding, adhesive, sprint, band, or other mechanical connecting members.

15

According to one embodiment the surgical instrument is adapted to introduce a mould or at least one sealing member into the hip joint. The mould or sealing member could be adapted to be resorbable by the human body or melt after having served its purpose as mould. According to this embodiment the surgical instrument could comprise gripping means for gripping said mould or sealing member.

20

According to one embodiment the surgical instrument is adapted to inject a fluid, adapted to harden to provide an artificial hip joint surface in the hip joint, into a mould or a sealed area of the hip joint. According to this embodiment the surgical instrument could comprise at least one container, a fluid injecting member in connection with said mould, and a fluid driving member in fluid connection with said fluid injecting member and said at least one container.

25

According to one embodiment the surgical instrument comprises at least two containers adapted to hold two different fluids, and a mixing unit adapted to mix said fluids contained in said at least two containers.

30

According to one embodiment the surgical instrument is adapted to introduce adhesive or bone cement into the hip joint. According to this embodiment the surgical instrument could comprise: at least one container, a fluid injecting member, and a fluid driving member in fluid connection with said fluid injecting member and said at least one container. According to one
5 embodiment the surgical instrument comprises at least two containers adapted to hold two different fluids, and a mixing unit adapted to mix said fluids contained in said at least two containers.

According to one embodiment the surgical instrument is adapted to place or fixate fixating
10 elements to the pelvic bone or a prosthetic part in the pelvic region. The fixating elements could comprise: at least one screw, at least one plate and/or at least one nut.

According to one embodiment the surgical instrument comprises at least one camera, at least one light source or an x-ray tube or x-ray detector.

According to one embodiment the surgical instrument is adapted to inject a lubricating fluid into the hip joint, in which case the surgical instrument could comprise: at least one container, a fluid injecting member, and a fluid driving member in fluid connection with said fluid
15 injecting member and said at least one container. The lubricating fluid is preferably a
20 biocompatible lubricating fluid, such as hyaluronic acid.

Please note that any embodiment or part of embodiment, feature, method, associated system, part of system described herein may be combined in any way.

BRIEF DESCRIPTION OF THE DRAWINGS

The embodiments are now described, by way of example, with reference to the accompanying drawings, in which:

Fig. 1 shows a hip joint in section,

5

Fig. 2 shows a lateral view of a conventional hip joint surgery,

Fig. 3 shows an artificial caput femur being used in conventional surgery,

10 Fig. 4 shows a frontal view of the body of a human patient,

Fig. 5 shows a frontal view of the body of a human patient,

Fig. 6 shows a frontal view of the body of a human patient,

15

Fig. 7 shows a lateral view of the body of a human patient in section,

Fig. 8a shows the creation of a hole through the collum femur, in a length axis thereof,

20 Fig. 8b shows mechanical instruments adapted to be placed on an elongated member placed in a hole in collum femur,

Fig. 9a shows the placement of an elongated member through the pelvic bone,

25 Fig. 9b shows the elongated member in further detail,

Fig. 10a shows an instrument with a parallel displaced part or section,

Fig. 10b shows an instrument with two joints,

5 Fig. 10c shows an instrument with a flexible part or section,

Fig. 11 shows an instrument comprising a worm gear,

Fig. 12 shows an instrument comprising a universal joint,

10

Fig. 13 shows an instrument comprising a gripping member,

Fig. 14 shows an instrument adapted to create a hole in the pelvic bone,

15 Fig. 15 shows an instrument adapted to create a hole in the pelvic bone in further detail,

Fig. 16 shows an instrument adapted to create a hole in the pelvic bone comprising a parallel displaced part or section,

20 Fig. 17 adapted to create a hole in the pelvic bone comprising two joints,

Fig. 18 shows an instrument adapted to create a hole in the pelvic bone comprising a flexible part or section,

25 Fig. 19a shows an instrument adapted to create a hole in the pelvic bone in further detail,

Fig. 19b shows an instrument adapted to create a hole in the pelvic bone in further detail,

Fig. 20 shows an instrument adapted to create a hole in the pelvic according to another embodiment,

5

Fig. 21 shows an instrument adapted to create a hole in the pelvic according to another embodiment,

Fig. 22 shows an instrument adapted to create a hole in the pelvic according to another
10 embodiment,

Fig. 23 shows an instrument adapted to create a hole in the pelvic bone comprising two gear wheels,

15 Fig. 24 shows an instrument adapted to create a hole in the pelvic bone comprising a worm gear,

Fig. 25 shows an instrument adapted to create a hole in the pelvic comprising a universal joint,

20

Fig. 26 shows an instrument adapted to create a hole in the pelvic bone comprising a chain,

Fig. 27 shows an instrument adapted to create a hole in the pelvic bone comprising a chain according to another embodiment,

25

Fig. 28a shows an instrument adapted to create a hole in the pelvic according to another embodiment,

Fig. 28b shows an instrument adapted to create a hole in the pelvic according to another embodiment,

5 Fig. 29 shows an instrument adapted to create a hole in the pelvic bone in further detail,

Fig. 30 shows an instrument adapted to create a hole in the pelvic bone comprising a cover,

Fig. 31 shows an instrument adapted to ream, in a first position,

10

Fig. 32 shows an instrument adapted to ream, in a second position,

Fig. 33 shows an instrument adapted to ream, from underneath,

15 Fig. 34 shows an instrument adapted to ream, when reaming,

Fig. 35 shows an instrument adapted to ream, comprising a parallel displaced part or section,

Fig. 36 shows an instrument adapted to ream comprising two joints,

20

Fig. 37 shows an instrument adapted to ream comprising a flexible part or section,

Fig. 38 shows an instrument adapted to ream, in further detail,

25 Fig. 39 shows an instrument adapted to ream, comprising two gear wheels,

Fig. 40 shows an instrument adapted to ream, comprising a worm gear,

Fig. 41 shows an instrument adapted to ream, comprising a universal joint,

5 Fig. 42 shows an instrument adapted to ream, comprising a chain,

Fig. 43 shows an instrument adapted to ream, comprising a chain, according to another embodiment,

10 Fig. 44 shows an instrument adapted to ream, according to another embodiment,

Fig. 45 shows an instrument adapted to ream, according to another embodiment,

Fig. 46 shows an instrument adapted to ream according to another embodiment,

15

Fig. 47 shows an instrument adapted to ream, comprising a cover,

Fig. 48 shows an instrument adapted for flushing, cooling and/or sucking,

20 Fig. 49 shows an instrument for gripping or handling,

Fig. 50 shows an instrument for gripping or handling, comprising a parallel displaced part or section,

25 Fig. 51 shows an instrument for gripping or handling, comprising two joints,

Fig. 52 shows the hip joint in section,

Fig. 53 shows the insertion of prosthetic parts is a surgical method,

5 Fig. 54 shows the insertion of prosthetic parts is a laparoscopic method,

Fig. 55 shows the insertion of prosthesis, through a hole in the pelvic bone,

Fig. 56a shows the insertion of prosthetic parts, through a hole in the pelvic bone,

10

Fig. 56b shows the connecting of prosthetic parts, through a hole in the pelvic bone,

Fig. 56c shows prosthetic parts,

15 Fig. 57 shows an instrument adapted to fixate a hip joint surface,

Fig. 58 shows an instrument adapted to inject a fluid into a hip joint,

Fig. 59a shows an instrument adapted to insert a mould or a sealing member into a hip joint,

20

Fig. 59b shows an instrument adapted to insert a mould or a sealing member into a hip joint,
in section,

Fig. 59c shows an instrument adapted to insert a mould or a sealing member into a hip joint,

25 comprising a flexible part or section,

Fig. 60a shows an instrument adapted to insert a mould or a sealing member into a hip joint,

Fig. 60b shows an instrument adapted to insert a mould or a sealing member into a hip joint, comprising a parallel displaced part or section,

5

Fig. 60c shows an instrument adapted to insert a mould or a sealing, comprising two joints,

Fig. 61 shows the insertion of a mould or a sealing member, through the pelvic bone,

10 Fig. 62 shows the placing of a second sealing member,

Fig. 63a shows the insertion of a mould or a sealing member, through the femoral bone,

Fig. 63b shows the insertion of a mould or a sealing member, through the femoral bone,

15

Fig. 63c shows the insertion of a mould or a sealing member, through the femoral bone,

Fig. 64 shows the insertion of a mould or a sealing member, through the hip joint capsule,

20 Fig. 65 shows the injection of fluid into a mould, through the hip joint,

Fig. 66 shows the injection of fluid into a mould, through the femoral bone,

Fig. 67 shows the injection of fluid into a mould, through the hip joint capsule,

25

Fig. 68 shows the hip joint in section, after a fluid has been injected,

Fig. 69 shows a lateral view of a human patient in section, with an instrument for injecting a fluid,

5 Fig. 70 shows an instrument for injecting a fluid in further detail,

Fig. 71a shows a prosthetic part being used to close a hole in a pelvic bone,

10 Fig. 71b shows how sections of a prosthetic part is used as support against the edges of the hole in a pelvic bone,

Fig. 72 shows the insertion of a prosthetic part in a hole in a pelvic bone,

15 Fig. 73 shows how screws are being used to fixate a bone plug or a prosthetic part in a hole in a pelvic bone of a human patient,

Fig. 74a shows an instrument for fixating fixation members to an area of the pelvic bone,

20 Fig. 74b shows an instrument for fixating fixation members to an area of the pelvic bone,

Fig. 74c shows an instrument for fixating fixation members to an area of the pelvic bone,

Fig. 75 shows an instrument comprising an arthroscopic camera,

25 Fig. 76 shows an instrument for injecting a lubricating fluid.

DETAILED DESCRIPTION

In the following a detailed description of embodiments will be given. In the drawing figures, like reference numerals designate identical or corresponding elements throughout the several figures. It will be appreciated that these figures are for illustration only and are not in any way restricting the scope. Thus, any references to direction, such as “up” or “down”, are only referring to the directions shown in the figures. Also, any dimensions etc. shown in the figures are for illustration purposes.

Please note that any embodiment or part of embodiment as well as any method or part of method could be combined in any way. All examples herein should be seen as part of the general description and therefor possible to combine in any way in general terms.

Fig. 1 shows the hip joint of a human patient in section. The hip joint comprises a caput femur 5 placed at the very top of collum femur 6 which is the top part of the femur bone 7. The caput femur is in connection with the acetabulum 8 which is a bowl shaped part of the pelvic bone 9. Both the caput femur surface 10 and the acetabulum surface 11 is covered with articular cartilage 13 which acts as a cushion in the hip joint. In patients with hip joint osteoarthritis, this articular cartilage 13 is abnormally worn down sometimes due to a low grade inflammation. The hip joint is surrounded by the hip joint capsule 12 which provides support for the joint and hinders luxation. After conventional hip joint surgery, penetrating the hip joint capsule 12, the capsule 12 is dramatically weakened due to the limited healing possibilities of its ligament tissue. By performing hip joint surgery without damaging the hip joint capsule 12 the patient can fully recover and place equal amount of strain on an artificial joint as is possible on a natural one.

Fig. 2 shows a lateral view of a conventional hip joint surgery where an incision 112 is made in the thigh 113 enabling the surgeon to reach the femur bone 7 on which the caput femur 5 is located. In a conventional hip joint surgery the hip joint is accessed through the hip joint capsule.

Fig. 3 shows the placing of an artificial caput femur surface 45 on the caput femur 5 in conventional surgery.

Fig. 4 shows a frontal view of the body of a human patient. A surgical method of operating the hip joint from the opposite side from acetabulum, is according to a first embodiment

performed starting with an incision 1 in the abdominal wall of the human patient. The incision 1 passes through the abdominal wall sometimes including the rectus abdominis and including peritoneum in to the abdomen of the human patient. In a second embodiment the incision 2 is conducted through the skin and into the pelvic area, below peritoneum. According to a third
5 embodiment the incision 3 is performed just between Ilium and the surrounding tissue, an incision 3 which could enable the pelvic bone to be dissected with very little penetration of fascia and muscular tissue. According to a fourth embodiment the incision 4 is made in the inguinal region or slightly above. In all of the four embodiments the tissue surrounding the pelvic bone 9 in the area opposite to acetabulum is removed or penetrated which enables the
10 surgeon to reach the pelvic bone 9.

Fig. 5 shows a frontal view of the body of a human patient. A laparoscopic method of operating the hip joint, from the opposite side from acetabulum, is according to a first embodiment performed starting with making small incisions 14 in the abdominal wall of the human patient. The small incisions enable the surgeon to insert laparoscopic trocars into the
15 abdomen of the human patient. According to the first embodiment the incisions 14 passes through the abdominal wall including the peritoneum in to the abdomen of the human patient. According to a second embodiment the small incisions 15 is conducted through the skin and in to the pelvic area, below peritoneum. According to a third embodiment the small incisions 16 is performed just between Ilium and the surrounding tissue, an incision 16 which could
20 enable the pelvic bone to be dissected with very little penetration of fascia and muscular tissue. According to a fourth embodiment the incision 17 is made in the inguinal channel. In all of the four embodiments the tissue surrounding the pelvic bone 9 in the area opposite to acetabulum 8 is removed or penetrated which enables the surgeon to reach the pelvic bone 9.

After the incision is made the surgical instruments according to any on the embodiments
25 below can enter the human body and be used to assist the surgeon in the operation of the hip joint osteoarthritis.

Fig. 6 shows a frontal view of the body of a human patient, illustrating the instruments 34, 35, 36 assisting in the method of operating the hip joint from the opposite side from acetabulum
30 8, the hip joint comprising the acetabulum 8 and the caput femur 5. The small incisions 14 in the abdominal wall of the human patient allows the insertion of laparoscopic trocars 33a,b,c into the body of the patients. Whereafter one or more camera 34, a surgical instrument 35

adapted to create a hole in the pelvic bone 9, or instruments 36 for introducing, placing, connecting, attaching, creating or filling prosthesis or prosthetic parts, can be inserted into said body through said laparoscopic trocars 33a,b,c. many different placements of the trocars is possible. The portions of the instruments adapted to be placed in the abdominal area are the abdominal portions 250, and the portions adapted to at least partially be placed inside of the pelvic bone is the pelvic portions 251 throughout this application.

Fig. 7 shows a lateral view of the body of a human patient, with the hip joint shown in section in further detail. The hip joint comprises a caput femur 5 placed at the very top of collum femur 6 which is the top part of the femur bone 7. The caput femur is in connection with the acetabulum 8 which is a bowl shaped part of the pelvic bone 9. Laparoscopic trocars 33a,b,c is being used to reach the hip joint 39 with one or more camera 34, a surgical instrument adapted to create a hole in the pelvic bone 35, or instruments 36 for introducing, placing, connecting, attaching, creating or filling prosthesis or prosthetic parts. The portions of the instruments adapted to be placed in the abdominal area are the abdominal portions 250, and the portions adapted to at least partially be placed inside of the pelvic bone is the pelvic portions 251 throughout this application.

Fig. 8a shows a human patient in section when an incision 1 is made in the abdominal wall of the human patient, and a second incision 200 is made in the lateral part of the left thigh. A drilling member 201 has been introduced through the incision 200 in the thigh, penetrating the fascia lata, and reaching the femoral bone 7. After the drilling member 201 has made contact with the femoral bone 7, a drilling process is started which creates a hole 205 in the cortical bone of the femoral bone 7 and into the cancellous bone of the femoral bone 7, the hole 205 then propagates along a length axis of the collum femur 6 and eventually reaches the caput femur 5, from the inside thereof. The caput femur 5 is penetrated from the inside and the drilling member 201 continues to the acetabulum 8 which is a bowled shaped part of the pelvic bone 9. The drilling member 201 penetrates the pelvic bone 9 and continues into the abdominal area of the human patient. The drilling member 201 is then retracted from the hole 205 which leaves a hole 201 reaching from the lateral side of the thigh, to the area of the hip joint. The drilling member 201 is powered by an operating device 202 which could be an electrically, hydraulically or pneumatically powered operating device 202.

After the hole 205 has been created along a length axis of the collum femur 6, a force transferring member 206 is inserted through the hole 205. The force transferring member 206 could be a tubular or solid shaft, or a flexible member such as a wire.

Fig. 8b shows the hip joint in section when a force transferring member 206 has been inserted through the hole 205. The force transferring member 206 comprises a tool fixating member 218 positioned on the end of the force transferring member 206. The tool fixating member 218 could comprise a screw-thread or a bayonet joint which could be activated to fixate a tool 224,225,226 to the force transferring member 206, by the turning of said force transferring member by means of manual manipulation or an operating device 207. Fig. 5 further shows a tool for creating a hole 224 in the pelvic bone 9, a tool 225 for manipulating an implantable device such as a prosthesis or a prosthetic part, and a tool 226 for reaming the acetabulum 8 and/or the caput femur 5. The tools comprise a fixating member 219 which acts together with the tool fixating member 218 on the force transferring member 206 to fixate the tool 224,225,226 to the force transferring member 206. The tools 224,225,226 is inserted through the incision in the abdominal region, as shown in fig. 4. where a tool 224 for creating a hole in the pelvic bone 9 is inserted through an incision 1 in the abdominal region of the human patient using a tool introducing member 203. The force transferring member 206 according to any of the embodiments could be used as a positioning shaft, for positioning, centering and guiding a tool or a medical device, such as a prosthetic part.

Fig. 9a shows an embodiment in which a hole is created in two different parts of the pelvic bone 9. A drilling member 201 is first brought to the left part of the pelvic bone 9' for creating a hole in the left part of the pelvic bone 9. The drilling member thereafter continues through the abdominal and/or pelvic region and reaches the right part of the pelvic bone 9'' where a second hole is created reaching into the hip joint. The drilling member 201 is powered by an operation device 202, which could be a powered operation device, such as an electrical, hydraulic or pneumatic motor. According to another embodiment the drilling member 201 is manually operated. The drilling member further comprises a protective sleeve 240 adapted to protect the organs and tissue of the body from the drilling member 201 when advancing the drilling member through the abdominal and/or the pelvic region. The creation of two holes enables a very stable position of an elongated member which could be placed through the two holes for delivering an action to the hip joint or its surroundings.

Fig. 9b shows the drilling member in further detail, first in a state in which the protective sleeve 240 is advanced for covering the drilling member 201 and thereby protecting the organs and tissue of the human body from the drilling member. Below, the drilling member is shown in a second state, in which the protective sleeve 240 is retracted and thereby exposing the drilling member 201 and enabling the drilling member 201 to create a hole in bone.

After the hole has been created along a force transferring member or elongated member, according to any of the embodiments herein, could be inserted through the holes for delivering an action to the hip joint or its surroundings. The force transferring member could be a tubular or solid shaft, or a flexible member such as a wire.

To reach the pelvic bone or the hip joint from the abdominal side, it is conceivable that the surgical instrument is adapted to be bent.

Fig. 10a shows the surgical instrument according to a first embodiment wherein the surgical instrument comprises a handling portion 77 and a parallel displaced part or section 79, which increases the reach of the instrument and facilitates the reaching of the pelvic bone or the hip joint through from the abdominal side of the pelvic bone, or through a hole in the pelvic bone from the opposite side from acetabulum.

Fig. 10b shows the surgical instrument according to a second embodiment wherein the surgical instrument comprises two angle adjusting members 80a,b. The angle adjusting members could be adapted to be flexible for adjusting of the angle during surgery or fixed in a preset position.

Fig 10c shows the surgical instrument according to a third embodiment wherein the surgical instrument comprises a flexible part or section 300, enabling the surgical instrument to be very precisely adjusted to reach the pelvic bone or the hip joint from the abdominal side of the pelvic bone. The stiffness of said flexible part or section 300 could range from completely flexible to completely stiff to fit the surroundings of the particular operation.

Fig. 11 shows the surgical instrument according to a fourth embodiment wherein the surgical instrument is adapted to be bent by means of gearwheels 154. The gearwheel construction can be such that the angled could be changed during the surgery, or it could be adapted to be fixed in a specific angle.

Fig. 12 shows the surgical instrument according to a fifth embodiment wherein the surgical instrument is adapted to be bent by means of a universal joint 155. The universal joint construction can be such that the angled could be changed during the surgery, or it could be adapted to be fixed in a specific angle.

5 Fig. 13 shows the surgical instrument according to a sixth embodiment, wherein the surgical instrument comprises a gripping portion 76 and a handling portion 77. According to the embodiments shown in fig. 40a the instrument further comprises a rotation element 78 that enables the gripping part 76 to rotate in relation to the handling part 77, however it is equally conceivable that the surgical instrument lacks this rotation element 78.

10 The surgical instrument is generally adapted to assist the surgeon in a surgical or laparoscopic method of operating hip joint osteoarthritis. Embodiments of the surgical instrument for performing specific task will now be described with reference to the accompanying drawings.

Fig. 14 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9. According to a first
15 embodiment, the instrument comprises a driving member 21a, b. The driving member 21a, b could be a shaft, a rod, a belt, a chain or any other element suitable for transferring force or torque. The instrument also comprises a bone contacting organ 22 which is adapted to create the hole 18, 20 in the pelvic bone 9. The bone contacting organ 22 could have a sawing, drilling or milling effect using sharp objects; it is furthermore conceivable that said bone
20 contacting organ 22 creates a hole using water, abrasive fluids, laser or radiation. The instrument also comprises an operating device 23a adapted to operate the driving member 21a, b. The operating device could comprise an electrical, hydraulic, mechanical, pneumatic or magnetic engine and it could be adapted to create a rotating, oscillating, vibrating or repetitive movement.

25 Fig. 15 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to a second embodiment in which the operating device 23b is placed in direct connection with the bone contacting organ 22. In this case the operating device 23b also serves as driving member. In this construction a handle portion 24 could be attached to the instrument, facilitating the
30 surgeons handling of said surgical instrument. To improve the reach of the surgical instrument the handle portion 24 could be attached perpendicular to the hole-creating direction 25 of the

surgical instrument, it is furthermore conceivable that the handle portion 24 is bent by means of a parallel displaced part or section, a fixed angle, an adjustable angle or a flexible part or section.

Fig. 16 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to a third embodiment wherein the instrument further comprises a parallel displaced part or section 26. The parallel displaced part or section 26 improves the reach of the instrument and enables the creation of a hole 18 in the pelvic bone 9 from the opposite side from acetabulum 8.

According to the embodiment shown in fig. 16 the parallel displaced part or section 26 has a telescopic function by means of the parallel displaced part or section 26 being divided in to a first and second part 27a, b, wherein the second part 27b can slide in and out of the first part 27a.

Fig. 17 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to a fourth embodiment wherein said instrument comprises a driving member 28a,b,c with two angle adjusting members 29a,b. The angle adjusting members 29a,b could be adjustable for varying the angle of said driving member 28a,b,c or fixed in an angle suitable for creating a hole in the pelvic bone 9 from the opposite side from acetabulum 8. In another embodiment (not shown) the part of the driving member 28c in connection with the bone contacting organ 22 could be very short enabling the instrument to operate very close to the pelvic bone 9 when creating a hole 18 in said pelvic bone 9.

Fig. 18 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to a fifth embodiment wherein the driving member 30 is flexible, enabling said driving member 30 to be very precisely adjusted to create a hole 18 in the pelvic bone 9 of the patient. The stiffness of said driving member 30 could range from completely flexible to completely stiff to fit the surroundings of the particular operation.

Fig 19a shows the bone contacting organ according to a first embodiment wherein the bone contacting organ 22a is adapted to create a bone plug 31. The bone plug 31 could be adapted to be replaced into said hole 18 after the surgical or laparoscopic steps performed in the hip joint has been concluded.

Fig. 19b shows the bone contacting organ according to the first embodiment in section wherein the bone contacting organ 22a is adapted to create a bone plug 31. According to this embodiment the instrument further comprises at least one holding member 150 for holding said bone plug in place after it has been removed from the pelvic bone of the human patient.

5 Fig. 20 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to a sixth embodiment wherein said instrument comprises a stabilizing drill 151 adapted to stabilize the instrument when creating said hole in the pelvic bone from the opposite side from acetabulum.

10 Fig. 21 shows the bone contacting organ according to a second embodiment wherein the bone contacting organ 22b is adapted to create small pieces of bone 32 when creating said hole 18 in the pelvic bone 9. The small pieces of bone 32 could be transported from the area and out of the body using vacuum power or a hydraulic transport system.

Fig. 22 shows a pneumatic, vacuum powered or a hydraulic transport system 152 for transport
15 of said small pieces of bone. The same system 152 or an additional one could be for rinsing or cooling purposes when creating said hole in the pelvic bone 9.

Fig. 23 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to a seventh
20 embodiment, wherein the driving member 30 comprises at least one worm gear 153 which enables the driving member 30 to be angled. It is also conceivable that said angle could be adjustable in which case said worm gear has a radius (not shown).

Fig. 24 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to an eighth
25 embodiment, wherein the driving member 30 comprises at least one gear wheel 154. In the embodiment shown the two gear wheels 154 is constructed to enable the adjusting of an angle of the driving member 30.

Fig. 25 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to a ninth
30 embodiment, wherein the driving member 30 comprises at least one universal joint 155, said universal joint enabling the adjusting of an angle of said driving member 30.

Fig. 26 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to a tenth embodiment, wherein the driving member 30 comprises at least one chain 156.

According to any of the embodiments above the driving member could comprise a housing 157 shown in fig 23, 24 and 26. Said housing could be adapted to hold a lubricating fluid for lubricating at least a part of said driving member. Said lubricating fluid is preferably a biocompatible lubricating fluid, such as hyaluronic acid.

Fig. 27 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9, according to an embodiment where said operating device comprises an electrical motor 158. Said electrical motor is connected to the driving member 30.

Fig. 28a shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to an embodiment wherein said operating device comprises a hydraulic motor 159, hydraulically connected to a hydraulic power source 160 by means of a hydraulic power transport system 161.

Fig. 28b shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to an embodiment wherein said operating device comprises a hydraulic motor, but wherein the hydraulic power transport system is located substantially perpendicular to the hole creation direction.

Fig. 29 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to an eleventh embodiment wherein said instrument further comprises at least one of: at least one camera 163, at least one light source 164, at least one measurement device for measuring the depth of said hole in the pelvic bone or at least one torque meter 165 for sensing the torque exerted on the driving member 30 from the connection with the bone contacting organ 22 and the operating device 23.

Fig. 30 shows the surgical instrument adapted for a first application wherein said instrument is an instrument for creating a hole 18, 20 in the pelvic bone 9 according to a twelfth embodiment in which the part of said instrument adapted to be inserted in the human body is covered with a housing 166 for protecting the human body from the parts of the surgical instrument. The housing 166 could be made of a stiff or flexible material and could have an

antibacterial surface. Said hosing 166 could be adapted to be used to house the surgical instrument according to any of the embodiments.

Fig. 31 shows the surgical instrument adapted for a second application wherein said instrument is an instrument for holding a mechanical element which according to this
5 embodiment is a reamer adapted to ream the acetabulum or and/or the caput femur. According to one embodiment the reamer could be adapted to be expandable. The expandable reamer comprises at least one reaming blade 40 which comprises a reaming surface 41a,b. Said expandable reamer could be adapted to ream the acetabulum 8, the caput femur 5 or both. In the embodiment where said expandable reamer is adapted to ream the acetabulum 8 said
10 reaming surface 41a is located on the exterior part of the at least one reaming blade 40, whereas in the embodiment when said expandable reamer is adapted to ream the caput femur 5, said reaming surface 41b is located on the interior part of the at least one reaming blade 40. According to a second embodiment said expandable reamer is adapted to ream both the acetabulum and the caput femur, in which case the reamer has reaming surfaces 41a,b both on
15 the exterior and the interior part of the at least one reaming blade 40.

Fig. 32 shows the expandable reamer, according to any of the embodiments, wherein the reaming blades 40 can be folded towards a center of the semi-sphere that the expandable reamer produces in its expanded state, shown in fig. 21. The folding of the reaming blades 40 enables the expandable reamer to be introduced into a hip joint through a hole smaller than
20 the area possible to ream using said expandable reamer.

Fig. 33 shows the interior said of the expandable reamer with the reaming blades 40. In the embodiment when the expandable reamer is adapted to ream the caput femur said interior side of the at least one reaming blade 40 comprises a reaming surface 41b.

Fig. 34 shows the expandable reamer according to any of the embodiments when reaming the
25 acetabulum 8 and/or the caput femur 5. The reamer can be adapted to be operated manually or by means of a rotating, vibrating or oscillating operating device.

Fig. 35 shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to a second embodiment wherein the instrument further comprises a parallel displaced part or
30 section 26. The parallel displaced part or section 26 improves the reach of the instrument and enables the reaming of the acetabulum and/or the caput femur through a hole 18 in the pelvic bone 9. From the opposite side from acetabulum 8. According to the embodiment shown in fig.

16 the parallel displaced part or section 26 has a telescopic function by means of the parallel displaced part or section 26 being divided in to a first and second part 27a, b, wherein the second part 27b can slide in and out of the first part 27a.

Fig. 36 shows the surgical instrument adapted for a second application wherein said
5 instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to a third embodiment wherein said instrument comprises a driving member 28a,b,c with two angle adjusting members 29a,b. The angle adjusting members 29a,b could be adjustable for varying the angle of said driving member 28a,b,c or fixed in an angle suitable for reaming the acetabulum and/or the caput femur through a hole in the pelvic bone 9 from the opposite side
10 from acetabulum 8.

Fig. 37 shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to a fourth embodiment wherein the driving member 30 is flexible, enabling said driving member 30 to be very precisely adjusted to ream the acetabulum and/or the caput femur
15 through a hole 18 in the pelvic bone 9 of the patient. The stiffness of said driving member 30 could range from completely flexible to completely stiff to fit the surroundings of the particular operation.

Fig. 38 shows a pneumatic, vacuum powered or a hydraulic transport system 152 for transport of the small pieces of bone created when reaming the acetabulum and/or the caput femur. The
20 same system 152 or an additional one could be for rinsing or cooling purposes when reaming the acetabulum and/or caput femur. The shown transport system could be added to the reamer according to any of the embodiments.

Fig. 39 shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according
25 to a fifth embodiment, wherein the driving member 30 comprises at least one worm gear 153 which enables the driving member 30 to be angled. It is also conceivable that said angle could be adjustable in which case said worm gear has a radius (not shown).

Fig. 40 shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according
30 to a sixth embodiment, wherein the driving member 30 comprises at least one gear wheel

154. In the embodiment shown the two gear wheels 154 is constructed to enable the adjusting of an angle of the driving member 30.

Fig. 41 shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to a seventh embodiment, wherein the driving member 30 comprises at least one universal joint 155, said universal joint enabling the adjusting of an angle of said driving member 30.

Fig. 42 shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to an eight embodiment, wherein the driving member 30 comprises at least one chain 156.

According to any of the embodiments above the driving member could comprise a housing 157 shown in fig 23, 24 and 26. Said housing could be adapted to hold a lubricating fluid for lubricating at least a part of said driving member. Said lubricating fluid is preferably a biocompatible lubricating fluid, such as hyaluronic acid.

Fig. 43 shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum and/or the caput femur, according to an embodiment where said operating device comprises an electrical motor 158. Said electrical motor is connected to the driving member 30.

Fig. 44 shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum and/or the caput femur, according to an embodiment wherein said operating device comprises a hydraulic motor 159, hydraulically connected to a hydraulic power source 160 by means of a hydraulic power transport system 161.

Fig. 45 shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to an embodiment wherein said operating device comprises a hydraulic motor, but wherein the hydraulic power transport system is located substantially perpendicular to the hole creation direction.

Fig. 46 shows the surgical instrument adapted for a second application wherein said instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to a ninth embodiment wherein said instrument further comprises at least one of: at least one camera 163, at least one light source 164, at least one measurement device for measuring the

depth of said hole in the pelvic bone or at least one torque meter 165 for sensing the torque exerted on the driving member 30 from the connection with the reaming organ and the operating device 23.

Fig. 47 shows the surgical instrument adapted for a second application wherein said
5 instrument is an instrument for reaming the acetabulum or and/or the caput femur, according to a tenth embodiment in which the part of said instrument adapted to be inserted in the human body is covered with a housing 166 for protecting the human body from the parts of the surgical instrument, and the surgical instrument from the human body. The housing 166 could be made of a stiff or flexible material and could have an antibacterial surface. Said
10 housing 166 could be adapted to be used to house the surgical instrument according to any of the embodiments.

Fig. 48 shows the surgical instrument adapted for a third, a fourth and/or a fifth application wherein said instrument is an instrument for flushing, cooling and/or sucking an affected area during an operation for treating hip joint osteoarthritis in a human patient. A member for
15 flushing, cooling and/or sucking 400 is positioned on the proximal part of a hydraulic or pneumatic transportation system 404 comprising one pressure tube 401 and one suction tube 402. In the application where the surgical instrument is used for flushing only, it is conceivable that the hydraulic or pneumatic transportation system 404 only comprises a pressure tube. Furthermore the surgical instrument according to the third application
20 comprises a unit 403 that could comprise at least one of a pneumatic or hydraulic pumping device 405, a cooling member 406, a filter device 407 and an energy accumulating or transforming unit 408. The portions of the instruments adapted to be placed in the abdominal area are the abdominal portions 250, and the portions adapted to at least partially be placed inside of the pelvic bone is the pelvic portions 251 throughout this application.

25 Fig. 49 shows the surgical instrument adapted for a sixth application, wherein said instrument is an instrument comprising a mechanical element adapted to insert a prosthesis, a prosthetic parts or parts needed to create or provide a hip joint surface, according to a first embodiment wherein the surgical instrument comprises a gripping portion 76 and a handling portion 77. According to the embodiments shown in fig. 49 the instrument further comprises a rotation
30 element 78 that enables the gripping part 76 to rotate in relation to the handling part 77, however it is equally conceivable that the surgical instrument lacks this rotation element 78.

According to other embodiments the mechanical element comprises a prosthesis or prosthetic part for insertion in the human body.

Fig. 50 shows the surgical instrument adapted for a sixth application, wherein said instrument is an instrument adapted to insert a prosthesis, prosthetic parts or parts needed to create or provide a hip joint surface, according to a second embodiment. According to this embodiment the surgical instrument 412 further comprises a parallel displaced section 79, which increases the reach of the surgical instrument 412 and facilitates the reaching of the hip joint through a hole in the pelvic bone from the opposite side from acetabulum.

Fig. 51 shows the surgical instrument adapted for a sixth application, wherein said instrument is an instrument adapted to insert a prosthesis, prosthetic parts or parts needed to create or provide a hip joint surface, according to a third embodiment. According to this embodiment the surgical instrument 412 further comprises two angle adjusting members 80a,b. The angle adjusting members could be adjustable for varying the angle of said gripping part 76 in relation to the handling portion 77, or fixed in an angle suitable for creating operating in a hip joint through a hole in the pelvic bone from the opposite side from acetabulum 8.

Fig. 52 shows the hip joint in section after the artificial caput femur surface 45, and the artificial acetabulum surface 65 have been provided.

Fig. 53 shows the surgical instrument adapted for a sixth application, wherein said surgical instrument 412 is a surgical instrument 412 adapted to insert a prosthesis, prosthetic parts 46, 48 or parts needed to create or provide a hip joint surface when being used by a surgeon to insert a prosthesis, prosthetic parts 46, 48 or parts needed to create or provide a hip joint surface through an opening in said human body.

Fig. 54 shows a prosthesis, prosthetic parts 48 or parts needed to create or provide a hip joint surface inserted through laparoscopic trocars 33a,b,c, through a small incision according to a laparoscopic method. The artificial hip joint surface parts 48 or the artificial caput femur surface parts 46 are adapted to be connected to each other after the insertion to form an artificial hip joint surface.

Fig. 55 shows how an expandable artificial caput femur surface 45 is being inserted through a hole 18 in the pelvic bone 9, using said surgical instrument 412.

Fig. 56a shows the hip joint in section with a hole 18 in the pelvic bone 9. An artificial caput femur surface 45 is introduced into the hip joint through the hole 18 in the pelvic bone 9 form

the opposite side from acetabulum 8. The artificial caput femur surface parts 46 are connected to each other after insertion into the hip joint to form the artificial caput femur surface 45.

Fig. 56b shows the hip joint in section when the artificial caput femur surface parts 46 are connected to each other using the surgical instrument adapted for the sixth application.

- 5 According to this embodiment the artificial caput femur surface parts 46 are adapted to supply a form fitting 47 that enables the parts to connect to each other without the use of any adhesive or additional mechanical parts. The surgical instrument adapted for the sixth application is adapted to be inserted through a hole 18 in the pelvic bone 9 and connecting said at least two hip joint surface parts 46 to each other. Fig. 56b shows the artificial caput femur surface parts, however it is equally conceivable that the artificial hip joint surface parts are artificial acetabulum surface parts. The surgical instrument 413 could comprise at least one gripping member 414, for gripping in the hip joint. The gripping member 414 could be powered by hydraulic, pneumatic or electrical energy. The gripping member 414 or otherwise part being in connection with said artificial hip joint surface parts is in connection with a handling part 416 through a connecting member 415, which could be bent or otherwise adapted to improve the reach of the surgeon for operating in a hip joint through a hole 18 in the pelvic bone 9 of a human patient.

Fig. 56c shows the artificial caput femur surface parts 46 with the parts supplying the form fitting 47.

- 20 Fig. 57 shows the surgical instrument adapted for a seventh application, wherein the surgical instrument 416 is adapted to fixate a hip joint surface 45 to the caput femur 5 through a hole 18 in the pelvic bone 9. According to the embodiment shown in fig. 57 the surgical instrument 416 is adapted to fixate an artificial caput femur surface, however it is equally conceivable that the surgical instrument 416 is adapted to fixate an artificial acetabulum surface to the pelvic bone 9. The fixation could be done by means of screws, form fitting, welding, adhesive, sprint, band, or other mechanical connecting members. The surgical instrument 416 in fig. 57 further comprises a member for providing rotational force 417 which could be used to fixate an artificial hip joint surface with screws or other rotation fixation members. The proximal part of the surgical instrument 416 could however also be equipped with a welding electrode, or a tool for fixating artificial hip joint surface using sprint or band.

Fig. 58 shows the surgical instrument adapted for a seventh application, wherein the surgical instrument 416 is adapted to fixate a hip joint surface 45 to the caput femur 5 through a hole

18 in the pelvic bone 9. According to this embodiment the surgical instrument 418 is a surgical instrument 418 adapted to fixate an artificial caput femur surface 45 to the caput femur 5 using bone cement or adhesive. According to this embodiment the surgical instrument 418 comprises a hollow space 419 for housing the fluid 419 such as bone cement or adhesive to be used in the fixation of the artificial hip joint surface. A piston part 420 supplies the pressure to the fluid 419 and pushes it through an injecting tip 422. The piston part 420 is powered or manually operated via a force rod 421 which could be flexible for improved reach.

Fig. 59a shows the surgical instrument adapted for an eight application wherein the instrument is adapted for placing a mould or a first and/or second sealing member in the hip joint through a hole in the pelvic bone, the femur bone or the hip joint capsule. The mould or sealing member could be used to create an artificial hip joint surface inside of the hip joint. The surgical instrument 423 comprises a piston 89 for transporting said mould or first and/or second sealing member into the hip joint and a tube like element 90 for housing of said mould or first and/or second sealing member.

Fig. 59b shows a section of the surgical instrument 413 comprising the tube like element 90 for housing of said mould or first and/or second sealing member

Fig 59c shows the surgical instrument 413 according to another embodiment in which the surgical instrument 413 comprises a flexible or bent part 91 improving the reach of the surgical instrument 413. The surgical instrument 413 according to any of the embodiments can be used to place said mould or first or second sealing members inside of the hip joint in any of the ways described in the following embodiments.

Fig. 60a shows the surgical instrument 423 adapted to insert the mould or first and/or second sealing member in the hip joint, according to a second embodiment. According to this embodiment the surgical instrument 423 comprises a gripping portion 76 and a handling portion 77. According to the embodiments shown in fig. 60a,b,c the surgical instrument 423 further comprises a rotation element 78 that enables the gripping part 76 to rotate in relation to the handling part 77, however it is equally conceivable that the surgical instrument 423 lacks this rotation element 78.

Fig. 60b shows the surgical instrument 423 adapted to insert the mould or first and/or second sealing member in the hip joint, according to a third embodiment. According to this embodiment the surgical instrument further comprises a parallel displaced section 79, which increases the reach of the surgical instrument 423 and facilitates the reaching of the hip joint through a hole 18 in the pelvic bone 9, the femoral bone or the hip joint capsule.

Fig. 60c shows the surgical instrument 423 adapted to insert the mould or first and/or second sealing member in the hip joint, according to a third embodiment. According to this embodiment the surgical instrument 423 further comprises two angle adjusting members 80a,b. The angle adjusting members 80a,b could be adjustable for varying the angle of said gripping part 76 in relation to the handling portion 77, or fixed in an angle suitable for operating in a hip joint through a hole 18 in the pelvic bone 9, the femur bone or the hip joint capsule.

Fig. 61 shows the hip joint in section wherein a mould or a first sealing member 84 is inserted through a hole 18 in the pelvic bone 9 using an instrument adapted therefor 85. The step of placing said mould or first sealing member 84 can be performed in a surgical, or in a laparoscopic method.

Fig. 62 shows the hip joint in section wherein a second sealing member 86 is inserted through a hole in the pelvic bone 9 in a surgical or a laparoscopic method. The first 84 and second 86 sealing members creates a sealed space 87 between the acetabulum 8 and the caput femur 5 adapted to be used as a mould for providing an artificial acetabulum 65 and/or a caput femur surface 45.

Fig. 63a,b,c shows an alternative approach to placing said mould or first sealing member 84 in the hip joint of a human patient. Said alternative approach comprises the steps of creating a hole 82 in the femur bone 7 following a length axis of the collum femur 6, as shown in fig. 63a, said hole starting from the lateral side of the thigh, penetrating the cortex of the femur bone 7 and eventually reaching the cortex of the caput femur 5 from the inside thereof, penetrating said cortex and entering into the hip joint. After the creation of the hole 82 in the femur bone 7 the mould or first sealing member 84 is inserted into the hip joint through the hole 82 using a surgical instrument 88 adapted therefor, as shown in fig. 63c. This approach could also be used for placing a second sealing member 86 in pelvic bone 9 or the femur bone 7 through the hole 82 in the femur bone 7.

Fig. 64 shows a third approach to the placing of a mould or a first sealing member 84 inside of the hip joint. According to this approach the first sealing 84 member is placed in the hip joint through the hip joint capsule 12.

It is furthermore conceivable that the first sealing member 84 is placed in the hip joint using
5 any of the approaches above, whereas the second sealing member 86 is placed in the hip joint using another of the approaches above.

Fig. 65 shows the surgical instrument adapted for a ninth application, wherein the surgical instrument is an injecting member 92 adapted to inject a fluid 93 into a mould or sealed area 81 in the hip joint through a hole 18 in the pelvic bone 9 from the opposite side from
10 acetabulum 8. The injecting member 92 comprises a piston 94 that pushes said fluid 93 into the mould 81.

Fig. 66 shows the hip joint in section wherein an injecting member 92 injects a fluid 93 into a mould 81 or a sealed area in the hip joint through a hole 82 in the femur bone 7. The injecting member 92 comprises a piston 94 that pushes said fluid 93 into the mould 81.

15 Fig. 67 shows the hip joint in section wherein an injecting member injects a fluid 93 into a mould 81 in the hip joint through a hole in the hip joint capsule 12. The injecting member 92 comprises a piston 94 that pushes said fluid 93 into the mould 81. Said fluid 93 being adapted to harden to create a medical device adapted to serve as at least one artificial hip joint surface.

Fig. 68 shows the hip joint in section wherein the medical device 93' is located between the
20 acetabulum 8 and the caput femur 5 which has been created by the hardening of the fluid 93 adapted to harden. Said medical device is adapted to serve as at least one artificial hip joint surface. The hole in the pelvic bone is preferably sealed with a bone plug 31 or a prosthetic part 98. The mould 81 used to create the medical device 93' has been resorbed by the human body. According to another embodiment the mould used to create the medical device 93' has
25 melted.

Fig. 69 shows a lateral section of the human body wherein an injecting member 92 injects a fluid into a mould 81 or a sealed area in the hip joint through a hole 18 in the pelvic bone 9 from the opposite side from acetabulum 8. The injecting member penetrates the skin 300 of the human patient in a surgical or laparoscopic method.

Fig. 70 shows the injecting member 92 according to any of the embodiments above, adapted to inject fluid 93 into a mould 81 in the hip joint. The injecting member 92 could further be adapted to inject material 93 or a fluid 93 into a connecting area between the pelvic bone 9 and a prosthetic part, the pelvic bone 9 and a bone plug 31 or the caput femur 5 and a prosthetic part. Said injecting member 92 comprises a container 107 adapted to hold a fluid 93 for injection. According to a first embodiment said container 107 comprises two compartments 108a,b adapted to hold two different fluids, said fluids being adapted to harden when mixed. In the embodiment when the container 107 is adapted to hold two fluids, it is conceivable that the injecting member 105 further comprises a mixing member 109 wherein said two fluids are being mixed before injection. According to a second embodiment (not shown) said container 107 is adapted to keep said fluid sterile. According to a third embodiment (not shown) said container 107 is adapted to keep said fluid cold or hot and according to a fourth embodiment (not shown) said container 107 is adapted to keep said fluid in a dark environment. Furthermore a combination of the above mentioned embodiments is conceivable.

According to another embodiment (not shown) the fluid is adapted to harden through the mixing with a gas. In which case one of the two compartments is adapted to hold a pressurized gas (such as nitrogen gas) adapted to act as catalyzing agent for the fluid adapted to harden. According to that embodiment the mixing unit 109 is adapted to mix one liquid and one gas fluid. Said first, second or mixed fluid could also be adapted to harden by means of UV-light, thermic change or contact with a body fluid.

According to a tenth application the surgical instrument is adapted to assist in the placing of a bone plug or prosthetic part for sealing the hole in the pelvic bone created to reach the hip joint from the abdominal side of the pelvic bone.

Fig. 71a shows a prosthetic part 98 being inserted into a hole 18 in the pelvic bone 9 from the opposite side from acetabulum 8. According to one embodiment the prosthetic part 98 comprises supporting members 99 adapted to correspond with sections 100 of the hole 18 in the pelvic bone 9. After the prosthetic part 98 has been inserted using said surgical instrument it is rotated so that the supporting members 99 comes in contact with the pelvic bone 9 and can carry the load placed on the acetabulum 8 from weight of the human patient through the

contact with the caput femur 5. Said prosthetic part 98 could also be adapted to serve as artificial acetabulum surface 65 according to any of the above mentioned embodiments.

Fig. 71b shows the prosthetic part 98 when rotated to carry the load placed on the acetabulum 8 from weight of the human patient through the contact with the caput femur 5.

- 5 Fig. 72 shows the hip joint of a human patient in section wherein the prosthetic part 98 closes the hole 18 in the pelvic bone 9 and carries the load placed on the acetabulum 8 from weight of the human patient through the contact with the caput femur 5 by means of the supporting members 99. The prosthetic part 98 can further be fixated to the pelvic bone 9 by means of bone cement, adhesive, screws, form fitting, welding, sprints, band or some other mechanical
10 connecting member.

Fig. 73 shows the hip joint of a human patient in section wherein bone plug 31 or prosthetic part 98 is attached to the pelvic bone 9 by means of screws 101 placed from the opposite side from acetabulum 8. The screws 101 are possible to place in different angles depending on reach or need for support.

- 15 According to an eleventh application the surgical instrument is adapted to assist in the fixation of a bone plug or prosthetic part for sealing the hole in the pelvic bone created to reach the hip joint from the abdominal side of the pelvic bone

- Fig. 74a shows the hip joint of a human patient in section wherein the surgical instrument 424 is adapted to place screws 103 bone fixating a plate 102 that at least partly covers said bone
20 plug 31 or prosthetic part 98. According to a first embodiment the surgical instrument 424 comprises a flexible part or section 426 that improves the reach of said surgical instrument 424. The surgical instrument 424 further comprises an operating device 425 that supplies rotational force to the surgical instrument for fixating the screws 103.

- Fig. 74b shows the surgical instrument 424 according to a second embodiment wherein said
25 surgical instrument comprises a parallel displaced part or section 427 the improves the reach of said surgical instrument 424.

Fig. 74c shows the surgical instrument 424 according to a third embodiment wherein said surgical instrument comprises two angle adjusting members 428 that improves the reach of said surgical instrument 424.

In the above mentioned embodiments the plate 102 and/or the bone plug 31 or prosthetic part 98 are fixated by means of screws 103, however it is equally conceivable that said screws 103 can be replaced or assisted by bone cement, adhesive, form fitting, welding, springs, band or some other mechanical connecting member.

- 5 Fig. 75 shows the surgical instrument adapted for an eleventh application wherein said surgical instrument 434 is an arthroscopic camera adapted to be inserted into the hip joint through a hole 18 in the pelvic bone from the abdominal side thereof. It is also conceivable that said surgical instrument 434 is a light source (not shown) or an device for performing x-ray of the hip joint (not shown).
- 10 Fig. 76 shows a twelfth application. The surgical instrument 492 is adapted to inject a lubricating fluid into the hip joint, through a hole 18 in the pelvic bone 9. Said lubricating fluid is preferably a biocompatible lubricating fluid such as hyaluronic acid. The surgical instrument 492 comprises a container 493 and a fluid transporting member 494 for transporting said fluid from the container 493 to the injecting member 495, which is the
- 15 proximal part of said fluid transporting member. The portions of the instruments adapted to be placed in the abdominal area are the abdominal portions 250, and the portions adapted to at least partially be placed inside of the pelvic bone is the pelvic portions 251 throughout this application.
- 20 Please note that any embodiment or part of embodiment, feature, method, associated system, part of system described herein may be combined in any way.

CLAIMS

1. A surgical instrument for operating hip joint osteoarthritis in a human patient, the hip joint comprising an acetabulum, the acetabulum being a part of the pelvic bone, and a
5 caput femur, the caput femur being the proximal part of the femoral bone, wherein said surgical instrument is adapted to assist in the operating of the hip joint osteoarthritis from the abdominal side of the pelvic bone of said human patient, said surgical instrument comprising an abdominal portion insertable through an incision in the skin in the abdominal region and adapted to be placed between the incision in the
10 abdominal region and the pelvic bone when the instrument is in use, and a pelvic portion connected to the abdominal portion, being partially insertable through a hole in the pelvic bone from the abdominal side of the pelvic bone, when the instrument is in use, wherein a portion of the pelvic portion is adapted to operate at least partially in a surgically created hole in the pelvic bone.

COMPRISING AN ANGLE

2. The surgical instrument according to claim 1, wherein said surgical instrument comprises a bend between said abdominal portion and said pelvic portion.
- 20 3. The surgical instrument according to claim 2, wherein said bend comprises a bend with a fixed angle.
4. The surgical instrument according to claim 2, wherein said bend comprises a bend
25 with an adjustable angle.
5. The surgical instrument according to any one of claims 2 – 4, wherein said bend comprises at least one gear wheel.
- 30 6. The surgical instrument according to any one of claims 2 – 4, wherein said bend comprises at least one universal joint.

7. The surgical instrument according to claim 1, wherein said surgical instrument comprises a parallel displaced part or section placed between the abdominal portion and the pelvic portion.

5 FURTHER ADAPTATIONS

8. The surgical instrument according to any one of claim 1-7, wherein the abdominal portion is more than 100mm such that the abdominal portion can reach from the incision in the abdominal region to an area of the hip joint opposite the acetabulum.

10

9. The surgical instrument according to any one of claim 1-8, further comprising a gripping end for handling of the instrument, wherein said gripping end is connected to the abdominal portion and adapted to remain outside the skin of the patient when the instrument is in use.

15

10. The surgical instrument according to claim 9, wherein a portion between the gripping end and the bend is at least 100mm such that the bend can be placed at the pelvic bone on the opposite side from acetabulum.

20

11. The surgical instrument according to claim 9, wherein a portion between the gripping end and the most distal end of the instrument is more than 200mm such that the instrument can operate inside of the hip joint from the abdominal side of the pelvic bone.

25

12. The surgical instrument according to any one of claims 1 – 11, wherein the surgical instrument is a laparoscopic instrument adapted to be inserted through the skin of the abdominal region through a laparoscopic port.

30

13. The surgical instrument according to claim 1, adapted to be a special laparoscopic instrument introduced into the abdomen and further down to the pelvic bone on the opposite side of the acetabulum and introduced into the hip joint, further comprising a gripping end, placed outside the abdominal wall when in use, and a hip joint end adapted to be placed in an area of the hip joint, wherein the length of said instrument

is adapted to reach from the gripping end and into the hip joint via a surgically created hole in the pelvic bone and wherein the longitudinal extension of said instrument comprises at least one bend, for the instrument to reach, when used as a special laparoscopic instrument to operate the hip joint, from the gripping end into the abdomen and further down to the pelvic bone on the opposite side of the acetabulum and be introduced into the hip joint through the surgically created hole in the pelvic bone.

14. The surgical instrument according to claim 1, adapted to be a special pelvic instrument introduced into the pelvic region and further to the pelvic bone on the opposite side of the acetabulum, and introduced into the hip joint via a surgically created hole in the pelvic bone, further comprising a gripping end, placed outside the skin above the pelvic region when in use, and a hip joint end adapted to be placed in an area of the hip joint, wherein the length of said instrument is adapted to reach from the gripping end and into the hip joint, and wherein the longitudinal extension of said instrument comprises at least one bend, for the instrument to reach, when used as special pelvic instrument to operate the hip joint, from the gripping end into the pelvic region and further down to the pelvic bone on the opposite side of the acetabulum, and introduced into the hip joint through the surgically created hole in the pelvic bone.

15. The surgical instrument according to claim 1, adapted to be a special retroperitoneal instrument introduced into the body just above the inguinal region following the pelvic bone down to the opposite side of the acetabulum and thereafter introduced into the hip joint via a surgically created hole in the pelvic bone, further comprising a gripping end, placed outside the skin above the pelvic region when in use, and a hip joint end adapted to be placed in an area of the hip joint, wherein the length of said instrument is adapted to reach from the gripping end and into the hip joint and wherein the longitudinal extension of said instrument comprises at least one bend, for the instrument to reach, when used as special retroperitoneal instrument to operate the hip joint, from the gripping end following the pelvic bone and further down to the pelvic bone on the opposite side of the acetabulum and introduced into the hip joint through the surgically created hole in the pelvic bone.

16. The surgical instrument according to any one of claim 1 – 15, wherein said instrument further comprises at least one holding portion connected to the pelvic portion, and at least one mechanical element adapted to be fitted to said at least one holding part of said instrument.

5

17. The surgical instrument according to claim 16, wherein said mechanical element is adapted to perform a function during an operation of the hip joint.

10

18. The surgical instrument according to any one of claim 16 – 17, wherein said mechanical element is adapted to be part of an instrument adapted to be used for at least one of the following functions; drilling, reaming, cooling, heating, flushing, introducing a fluid, sucking, inserting at least one part, connecting at least one part, fixating at least one part, inserting a mould, filling a mould, injecting, lubricating, viewing, optically displaying, placing screws, placing adhesive, placing bone cement.

15

19. The surgical instrument according to any one of claim 9 – 18, wherein the distance between the gripping end and the bend is at least 150 mm.

20

20. The surgical instrument according to any one of claim 9 – 18, wherein the distance between said gripping end and said bend is at least 200 mm.

21. The surgical instrument according to any one of claim 9 – 18, wherein the distance between said gripping end and said bend is at least 300 mm.

25

22. The surgical instrument according to any one of claim 9 – 18, wherein the distance between said gripping end and said bend is at least 400 mm.

23. The surgical instrument according to any one of claim 9 – 18, wherein the distance between said gripping end and said bend is at least 500 mm.

30

24. The surgical instrument according to any one of claim 2 – 23, wherein said bend is bent with an angle of at least 10 degrees.

25. The surgical instrument according to any one of claim 2 – 23, wherein said bend is bent with an angle of at least 20 degrees.

5 26. The surgical instrument according to any one of claim 2 – 23, wherein said bend is bent with an angle of at least 30 degrees.

27. The surgical instrument according to any one of claim 2 – 23, wherein said bend is bent with an angle of at least 40 degrees.

10 28. The surgical instrument according to any one of claim 2 – 23, wherein said bend is bent with an angle of at least 50 degrees.

29. The surgical instrument according to any one of claim 2 – 23, wherein said bend is bent with an angle of at least 60 degrees.

15 30. The surgical instrument according to any one of claim 2 – 29, wherein the distance between said bend and the pelvic portion of the instrument is at least 20 mm.

20 31. The surgical instrument according to any one of claim 2 – 29, wherein the distance between said bend and the pelvic portion of the instrument is at least 40 mm.

32. The surgical instrument according to any one of claim 2 – 29, wherein the distance between said bend and the pelvic portion of the instrument is at least 60 mm.

25 33. The surgical instrument according to any one of claim 2 – 29, wherein the distance between said bend and the pelvic portion of the instrument is at least 80 mm.

34. The surgical instrument according to any one of claim 2 – 29, wherein the distance between said bend and the pelvic portion of the instrument is at least 100 mm.

30 35. The surgical instrument according to any one of claim 2 – 29, wherein the distance between said bend and the pelvic portion of the instrument is at least 120 mm.

36. The surgical instrument according to any one of claim 2 – 29, wherein the distance between said bend and the pelvic portion of the instrument is at least 140 mm.

APPLICATIONS OF SAID INSTRUMENT

5

REAM

10

37. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to ream the acetabulum of said human patient.

38. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to ream the caput femur of said human patient.

15

39. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to ream both the acetabulum and the caput femur of said human patient.

20

40. The surgical instrument according to any one of claim 37 - 39, wherein said surgical instrument is expandable, thus allowing said surgical instrument to be inserted through a hole in the pelvic bone smaller than the area possible to ream using said surgical instrument.

25

41. The surgical instrument according to claim 40, wherein said surgical instrument comprises:

- a. a base part, adapted to be fixated to a driving member,
- b. a reaming blade, pivotally mounted to said base part.

30

42. The surgical instrument according to claim 41, wherein said surgical instrument further comprises a spring member adapted to affect said pivotally mounted reaming blade.

43. The surgical instrument according to any one of claims 37 - 39, wherein said surgical instrument comprises:

- a driving member,
- a bone contacting organ in connection with said driving member, and
- an operating device, adapted to operate said driving member.

5

10

44. The surgical instrument according to claim 43, wherein said bone contacting organ comprises at least one of the materials: titanium, ceramics or stainless steel.

45. The surgical instrument according to claim 43, wherein said operating device is electrically operated.

15

46. The surgical instrument according to claim 43, wherein said operating device is hydraulically or pneumatically operated.

20

47. The surgical instrument according to claim 17, wherein said mechanical element is adapted to ream at least one of the acetabulum and the caput femur of said human patient.

CAMERA

25

48. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument further comprises at least one camera.

49. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument further comprises at least one light source.

30

COOL

50. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to cool an area of the hip joint or an area of the pelvic bone.

5 51. The surgical instrument according to claim 50, wherein said surgical instrument adapted cool is further adapted to cool using a cooling fluid.

52. The surgical instrument according to claim 50, wherein said surgical instrument adapted cool is further adapted to cool an area before, during or after the creation of a hole in the pelvic bone.

10 53. The surgical instrument according to claim 50, wherein said surgical instrument adapted cool is further adapted to cool an area before, during or after a reaming operation.

15 54. The surgical instrument according to claim 17, wherein said mechanical element is adapted to cool the acetabulum and/or the caput femur during reaming of at least one of the acetabulum and the caput femur of said human patient.

FLUSH

20 55. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to provide a fluid to an area of the pelvic bone or the hip joint.

25 56. The surgical instrument according to claim 55, wherein said surgical instrument is adapted to provide a fluid to an area of the pelvic bone or an area of the hip joint, said fluid being adapted to clean or sterilize said area of the pelvic bone or said area of the hip joint.

30 57. The surgical instrument according to claim 17, wherein said mechanical element is adapted to provide a fluid to an area of the pelvic bone or an area of the hip joint.

SUCTION

58. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to provide suction to an area of the pelvic bone or an area of the hip joint.

5 59. The surgical instrument according to claim 58, wherein said surgical instrument is further adapted to transport body fluids or a fluid provided during the hip joint surgery.

10 60. The surgical instrument according to claim 58, wherein said surgical instrument is further adapted to transport parts of bone and cartilage.

61. The surgical instrument according to claim 17, wherein said mechanical element is adapted to provide suction to an area of the pelvic bone or an area of the hip joint.

15 INSERT PARTS

20 62. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to introduce a prosthesis through the hole in the pelvic bone and into the hip joint.

63. The surgical instrument according to claim 1, wherein said surgical instrument is adapted to introduce at least one prosthetic part into the hip joint.

25 64. The surgical instrument according to any one of claim 62 and 63, wherein said surgical instrument is further adapted to introduce an acetabulum prosthesis or a part of an acetabulum prosthesis into the hip joint.

30 65. The surgical instrument according to any one of claim 62 and 63, wherein said surgical instrument is further adapted to introduce a caput femur prosthesis or a part of a caput femur prosthesis into the hip joint.

66. The surgical instrument according to claim 17, wherein said mechanical element is adapted to introduce a prosthesis through the hole in the pelvic bone and into the hip joint.

5

CONNECT PROSTHETIC PARTS

67. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to connect at least two prosthetic parts to each other after
10 insertion into the hip joint.

68. The surgical instrument according to claim 67, wherein said at least two prosthetic parts comprises at least two artificial caput femur surface parts.

15 69. The surgical instrument according to claim 67, wherein said at least two prosthetic parts comprises at least two artificial acetabulum surface parts.

70. The surgical instrument according to claim 67, wherein said surgical instrument is further adapted to connect said at least two prosthetic parts using at least one of:
20

20

- at least one screw,

- at least one pin,

25

- at least one portion of at least one of the parts adapted to be introduced into the other part,

- the parts being adapted to be sliding into the other part,

30

- form fitting,

- welding,

- adhesive,
- pin,
- 5 - wire,
- a ball mounted into a bowl being portions of said parts,
- a male portion of one part mounted into a female portion of the other part,
- 10 - a key introduced into a lock being portions of said parts,
- band, and
- 15 - other mechanical connecting members.

71. The surgical instrument according to claim 70, wherein said surgical instrument is further adapted to connect said at least two prosthetic parts using an adhesive.

20 72. The surgical instrument according to claim 17, wherein said mechanical element is adapted to connect at least two prosthesis parts to each other after passing through the hole in the pelvic bone and into the hip joint.

FIXATE PROSTHESIS OR PROSTHETIC PARTS

25 73. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to fixate an artificial hip joint surface, or a part of an artificial hip joint surface, to the pelvic bone or the femoral bone.

30 74. The surgical instrument according to claim 73, wherein said surgical instrument is adapted to fixate an artificial hip joint surface, or a part of an artificial hip joint surface, to the pelvic bone or the femoral bone using at least one of:

- at least one screw,
- at least one pin,
- 5 - at least one portion of at least one of the parts adapted to be introduced into the other part,
- the parts being adapted to be sliding into the other part,
- 10 - form fitting,
- welding,
- adhesive,
- 15 - pin,
- wire,
- 20 - a ball mounted into a bowl being portions of said parts,
- a male portion of one part mounted into a female portion of the other part,
- a key introduced into a lock being portions of said parts,
- 25 - band, and
- other mechanical connecting members.
- 30 75. The surgical instrument according to claim 17, wherein said mechanical element is adapted to fixate an artificial hip joint surface, or a part of an artificial hip joint surface, to the pelvic bone or the femoral bone after said artificial hip joint surface, or

a part of an artificial hip joint surface, after passing through the hole in the pelvic bone and into the hip joint.

INSERT MOULD/SEALING

5

76. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to introduce a mould into the hip joint.

10

77. The surgical instrument according to claim 76, wherein said mould is adapted to be resorbable by said human body.

78. The surgical instrument according to claim 76, wherein said surgical instrument comprises gripping means for gripping said mould.

15

79. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to insert at least one sealing member into the hip joint.

80. The surgical instrument according to claim 79, wherein said at least one sealing member is adapted to be resorbed by the human body.

20

81. The surgical instrument according to claim 79, wherein said surgical instrument comprises gripping means for gripping said at least one sealing member.

25

82. The surgical instrument according to claim 17, wherein said mechanical element is adapted to introduce a mould or to insert at least one sealing member into the hip joint, passing through the hole in the pelvic bone and into the hip joint.

FILL MOULD

30

83. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to inject a fluid into a mould placed in the hip joint.

84. The surgical instrument according to claim 83, wherein said surgical instrument comprises:

- at least one container, and
- a fluid injecting member in connection with said mould.

85. The surgical instrument according to claim 84, wherein said surgical instrument comprises at least two containers adapted to hold two different fluids, and a mixing unit adapted to mix said fluids contained in said at least two containers.

86. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to inject a fluid into a sealed area in the hip joint.

87. The surgical instrument according to claim 84, wherein said surgical instrument adapted to inject a mixed fluid into a sealed area in the hip joint comprises:

- at least two containers,
- a fluid injecting member in connection with said mould, and
- a mixing unit to mix fluids from said at least two containers.

88. The surgical instrument according to claim 87, wherein said at least two containers is adapted to hold two different fluids, and said mixing unit is adapted to mix said fluids contained in said at least two containers.

89. The surgical instrument according to claim 17, wherein said mechanical element is adapted to inject a fluid into a mould placed in the hip joint.

90. The surgical instrument according to claim 17, wherein said mechanical element is adapted to inject a fluid into a sealed area in the hip joint.

BONE CEMENT / ADHESIVE

91. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to introduce adhesive into the hip joint.

5

92. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to introduce bone cement into the hip joint.

93. The surgical instrument according to any one of claim 91 and 92, wherein said surgical instrument comprises:

10

- at least one container, and
- a fluid injecting member.

15

94. The surgical instrument according to claim 93, wherein said surgical instrument further comprises at least two containers adapted to hold two different fluids, and a mixing unit adapted to mix said fluids contained in said at least two containers.

20

95. The surgical instrument according to claim 17, wherein said mechanical element is adapted to introduce adhesive into the hip joint.

96. The surgical instrument according to claim 17, wherein said mechanical element is adapted to introduce bone cement into the hip joint.

25

PLACES FIXATING ELEMENTS

97. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to place or fixate fixating elements to the pelvic bone or a prosthetic part in the hip region or the pelvic bone region.

30

98. The surgical instrument according to claim 97, wherein said fixating elements comprises at least one screw.

99. The surgical instrument according to claim 97, wherein said fixating elements comprises at least one plate.

5 100. The surgical instrument according to claim 97, wherein said fixating elements comprises at least one nut.

OPTICAL INSTRUMENT

10 101. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument comprises at least one camera.

102. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument comprises at least one light source.

15

103. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument comprises at least one laser source.

20 104. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument comprises at least one ultra sound source.

105. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument comprises an x-ray tube or an x-ray detector.

25 106. The surgical instrument according to claim 105, wherein said surgical instrument, when used during hip joint surgery, is further adapted to enable the surgeon to perform x-ray during said hip joint surgery.

INJECT LUBRICATION

30

107. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to inject a lubricating fluid into the hip joint, said surgical instrument comprising:

- at least one container,
- a fluid injecting member, and
- a fluid driving member in fluid connection with said fluid injecting member and said at least one container.

108. The surgical instrument according to claim 107, wherein said surgical instrument is adapted to inject a biocompatible lubricating fluid.

109. The surgical instrument according to claim 107, wherein said surgical instrument is adapted to inject hyaluronic acid.

110. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to inject a fluid into a mould placed in the hip joint.

111. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to introduce a mould into the hip joint.

112. The surgical instrument according to any one of claims 1 – 36, wherein said surgical instrument is adapted to introduce a sealing member into the hip joint.

METHOD

113. A method of treating a hip joint of a human patient, said method comprising the steps of:

- cutting the skin of the human patient,
- dissecting an area of the pelvic bone on the opposite side from the acetabulum,

- creating a hole in said dissected area, said hole passing through the pelvic bone and into the hip joint of the human patient, and
- performing an action in the hip joint, through said hole in the pelvic bone.

5

114. The method according to claim 113, wherein the step of performing an action in the hip joint comprises the step of injecting a fluid into the hip joint.

10

115. The method according to claim 114, wherein the step of injecting a fluid into the hip joint comprises the step of injecting a fluid using the instrument according to any one of claim 55, 83, 91 and 107.

15

116. The method according to claim 113, wherein the step of performing an action in the hip joint comprises the step of placing or fixating fixation elements to the pelvic bone or a prosthetic part in the hip region or the pelvic bone region.

20

117. The method according to claim 116, wherein the step of placing or fixating fixation elements to the pelvic bone or a prosthetic part in the hip region or the pelvic bone region comprises the step of placing or fixating fixation elements to the pelvic bone or a prosthetic part in the hip region or the pelvic bone region using the instrument according to claim 97.

25

118. The method according to claim 113, wherein the step of performing an action in the hip joint comprises the step of fixating an artificial hip joint surface, or a part of an artificial hip joint surface, to the pelvic bone or the femoral bone.

30

119. The method according to claim 118, wherein the step of fixating an artificial hip joint surface, or a part of an artificial hip joint surface, to the pelvic bone or the femoral bone comprises the step of fixating an artificial hip joint surface, or a part of an artificial hip joint surface, to the pelvic bone or the femoral bone using the instrument according to claim 73.

120. The method according to claim 113, wherein the step of performing an action in the hip joint comprises the step of connecting at least two prosthetic parts to each other after insertion into the hip joint.

5 121. The method according to claim 120, wherein the step of connecting at least two prosthetic parts to each other after insertion into the hip joint comprises the step of connecting at least two prosthetic parts to each other after insertion into the hip joint using the instrument according to claim 67.

10 122. The method according to claim 113, wherein the step of performing an action in the hip joint comprises the step of introducing a prosthesis through the hole in the pelvic bone and into the hip joint.

15 123. The method according to claim 122, wherein the step of introducing a prosthesis through the hole in the pelvic bone and into the hip joint comprises the step of introducing a prosthesis through the hole in the pelvic bone and into the hip joint using the instrument according to claim 62.

20 124. The method according to claim 113, wherein the step of performing an action in the hip joint comprises the step of providing suction to an area of the pelvic bone or an area of the hip joint.

25 125. The method according to claim 124, wherein the step of providing suction to an area of the pelvic bone or an area of the hip joint comprises the step of providing suction to an area of the pelvic bone or an area of the hip joint using the instrument according to claim 58.

30 126. The method according to claim 113, wherein the step of performing an action in the hip joint comprises the step of cooling an area of the hip joint or an area of the pelvic bone.

127. The method according to claim 126, wherein the step of cooling an area of the hip joint or an area of the pelvic bone comprises the step of cooling an area of the hip joint or an area of the pelvic bone using the instrument according to claim 50.

5 128. The method according to claim 113, wherein the step of performing an action in the hip joint comprises the step of reaming the acetabulum of the human patient.

129. The method according to claim 128, wherein the step of reaming the acetabulum of the human patient comprises the step of reaming the acetabulum of the human
10 patient using the instrument according to claim 37.

130. The method according to claim 113, wherein the step of performing an action in the hip joint comprises the step of reaming the caput femur of the human patient.

15 131. The method according to claim 130, wherein the step of reaming the caput femur of the human patient comprises the step of reaming the caput femur of the human patient using the instrument according to claim 38.

132. A method of treating a hip joint of a human patient, said method comprising the
20 steps of:

- inserting a needle or a tube like instrument into the patient's body,
- using the needle or tube like instrument to fill a part of the patient's body
25 with gas and thereby expanding a cavity within the body,
- placing at least two laparoscopic/arthroscopic trocars in said cavity,
- inserting a camera through one of the laparoscopic/arthroscopic trocars into
30 said cavity,
- inserting at least one dissecting tool through one of said at least two laparoscopic/arthroscopic trocars,

- dissecting an area of the pelvic bone on the opposite side from the acetabulum,
- 5 - creating a hole in said dissected area, said hole passing through the pelvic bone and into the hip joint of the human patient, and
- performing an action in the hip joint, through said hole in the pelvic bone.

10 133. The method according to claim 132, wherein the step of performing an action in the hip joint comprises the step of injecting a fluid into the hip joint.

134. The method according to claim 133, wherein the step of injecting a fluid into the hip joint comprises the step of injecting a fluid using the instrument according to any
15 one of claim 55, 83, 91 and 107.

135. The method according to claim 132, wherein the step of performing an action in the hip joint comprises the step of placing or fixating fixation elements to the pelvic bone or a prosthetic part in the hip region or the pelvic bone region.

20

136. The method according to claim 135, wherein the step of placing or fixating fixation elements to the pelvic bone or a prosthetic part in the hip region or the pelvic bone region comprises the step of placing or fixating fixation elements to the pelvic bone or a prosthetic part in the hip region or the pelvic bone region using the
25 instrument according to claim 97.

137. The method according to claim 132, wherein the step of performing an action in the hip joint comprises the step of fixating an artificial hip joint surface, or a part of an artificial hip joint surface, to the pelvic bone or the femoral bone.

30

138. The method according to claim 137, wherein the step of fixating an artificial hip joint surface, or a part of an artificial hip joint surface, to the pelvic bone or the femoral bone comprises the step of fixating an artificial hip joint surface, or a part of

an artificial hip joint surface, to the pelvic bone or the femoral bone using the instrument according to claim 73.

5 139. The method according to claim 132, wherein the step of performing an action in the hip joint comprises the step of connecting at least two prosthetic parts to each other after insertion into the hip joint.

10 140. The method according to claim 139, wherein the step of connecting at least two prosthetic parts to each other after insertion into the hip joint comprises the step of connecting at least two prosthetic parts to each other after insertion into the hip joint using the instrument according to claim 67.

15 141. The method according to claim 132, wherein the step of performing an action in the hip joint comprises the step of introducing a prosthesis through the hole in the pelvic bone and into the hip joint.

20 142. The method according to claim 141, wherein the step of introducing a prosthesis through the hole in the pelvic bone and into the hip joint comprises the step of introducing a prosthesis through the hole in the pelvic bone and into the hip joint using the instrument according to claim 62.

25 143. The method according to claim 132, wherein the step of performing an action in the hip joint comprises the step of providing suction to an area of the pelvic bone or an area of the hip joint.

30 144. The method according to claim 143, wherein the step of providing suction to an area of the pelvic bone or an area of the hip joint comprises the step of providing suction to an area of the pelvic bone or an area of the hip joint using the instrument according to claim 58.

145. The method according to claim 132, wherein the step of performing an action in the hip joint comprises the step of cooling an area of the hip joint or an area of the pelvic bone.

146. The method according to claim 145, wherein the step of cooling an area of the hip joint or an area of the pelvic bone comprises the step of cooling an area of the hip joint or an area of the pelvic bone using the instrument according to claim 50.

5

147. The method according to claim 132, wherein the step of performing an action in the hip joint comprises the step of reaming the acetabulum of the human patient.

10

148. The method according to claim 147, wherein the step of reaming the acetabulum of the human patient comprises the step of reaming the acetabulum of the human patient using the instrument according to claim 37.

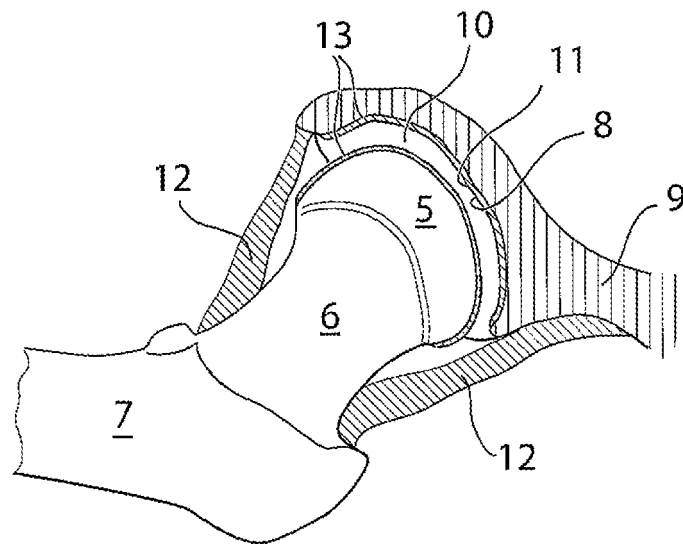
15

149. The method according to claim 132, wherein the step of performing an action in the hip joint comprises the step of reaming the caput femur of the human patient.

150. The method according to claim 149, wherein the step of reaming the caput femur of the human patient comprises the step of reaming the caput femur of the human patient using the instrument according to claim 38.

20

Fig.1



2/32

Fig.2

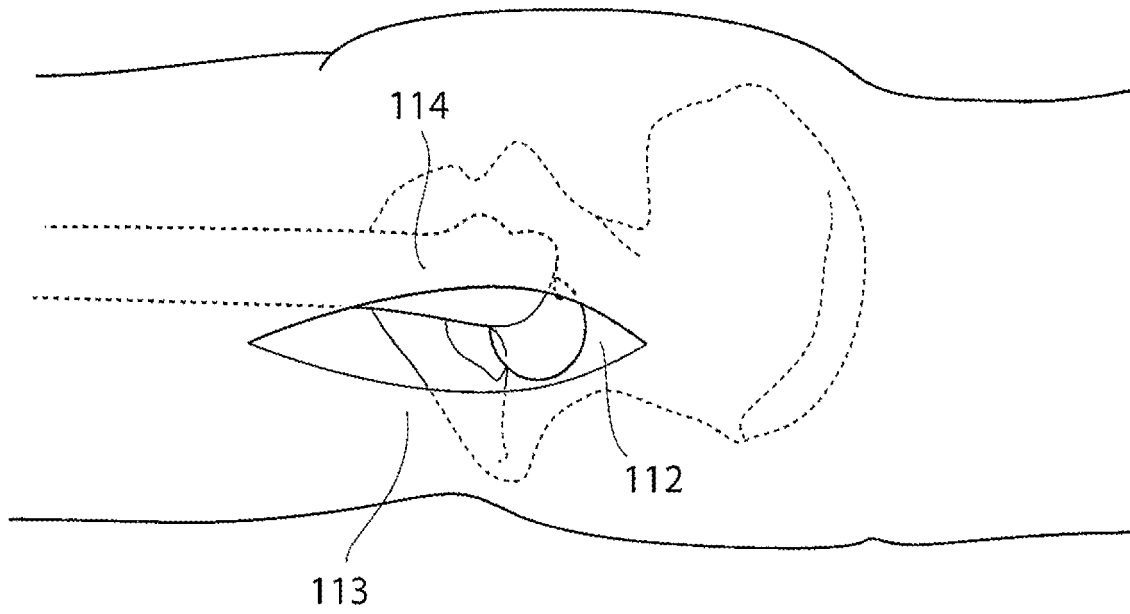
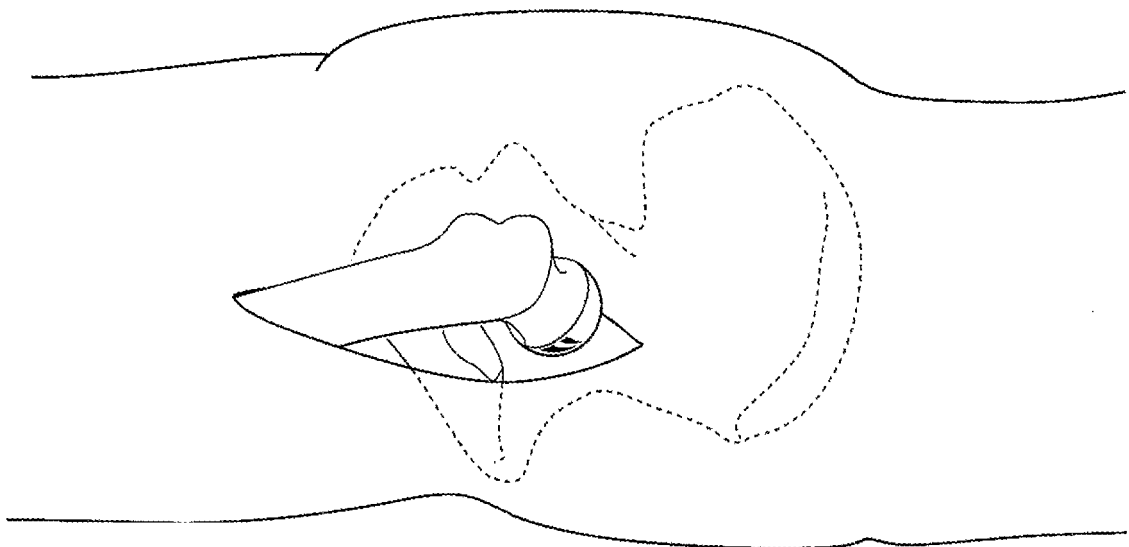


Fig.3



3/32

Fig.4

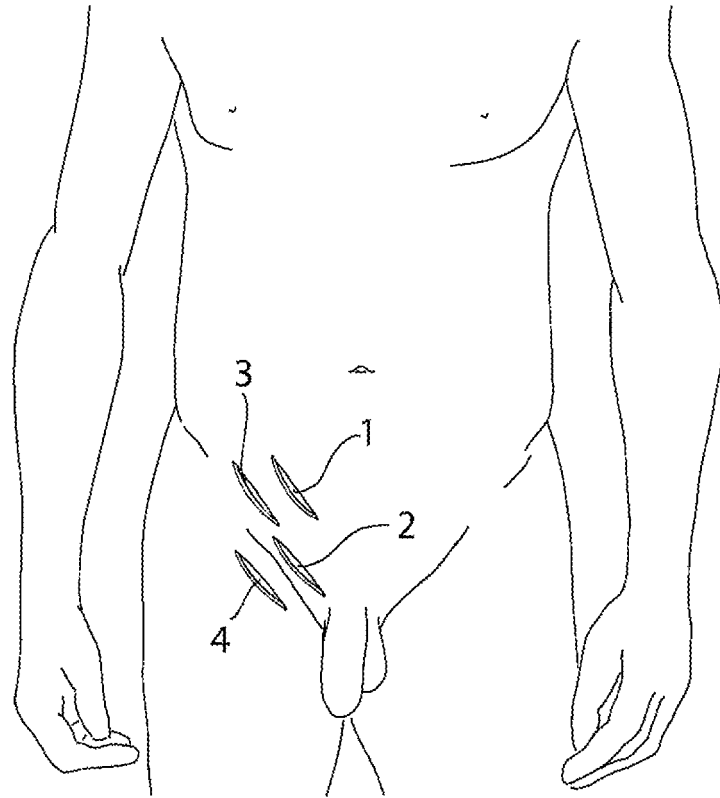
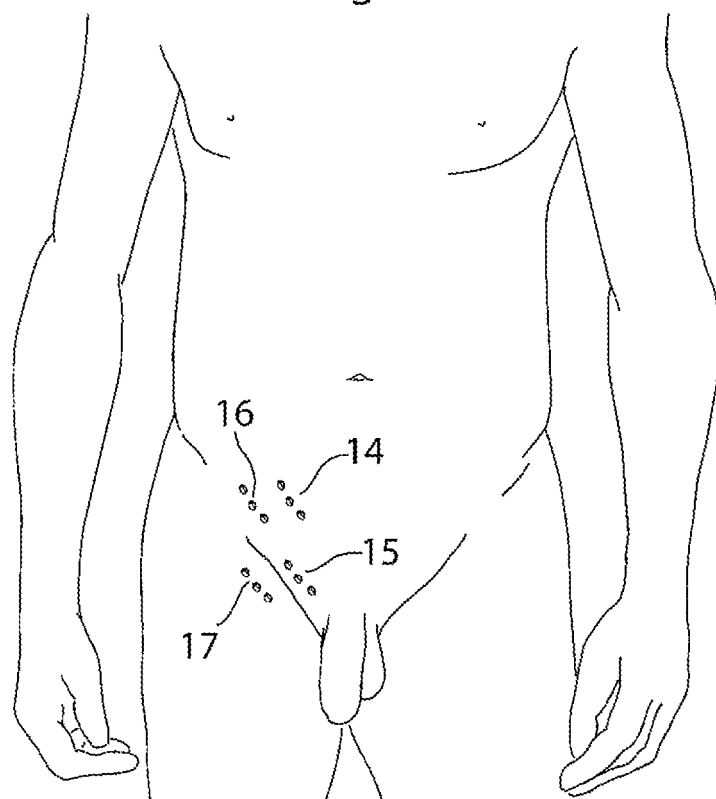


Fig.5



4/32

Fig.6

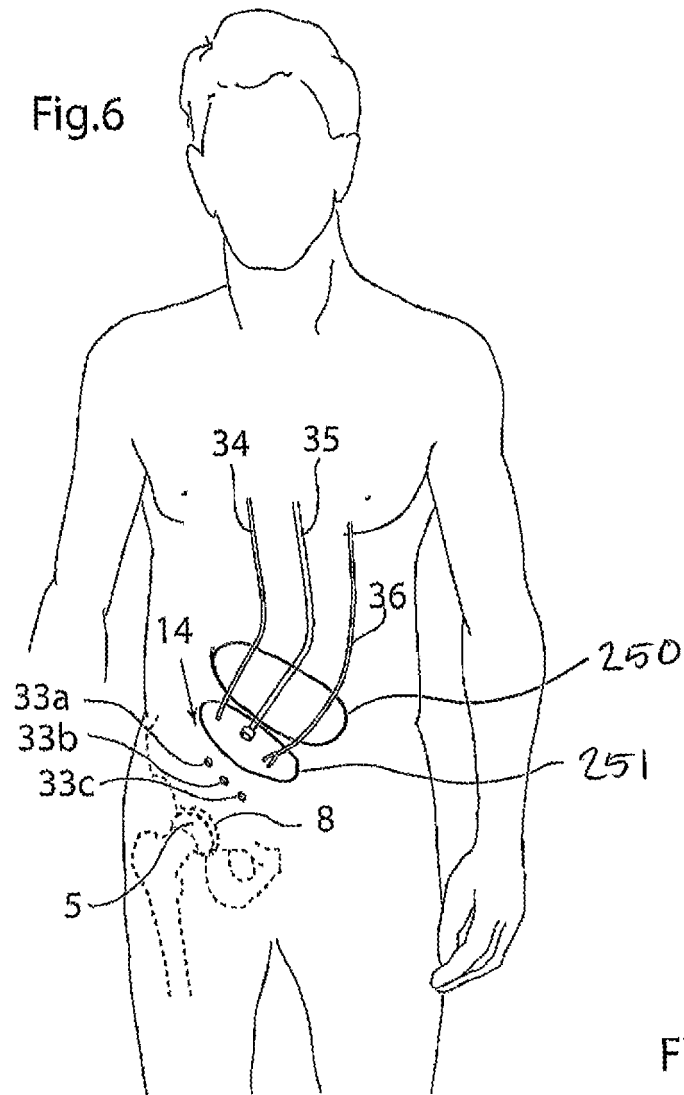
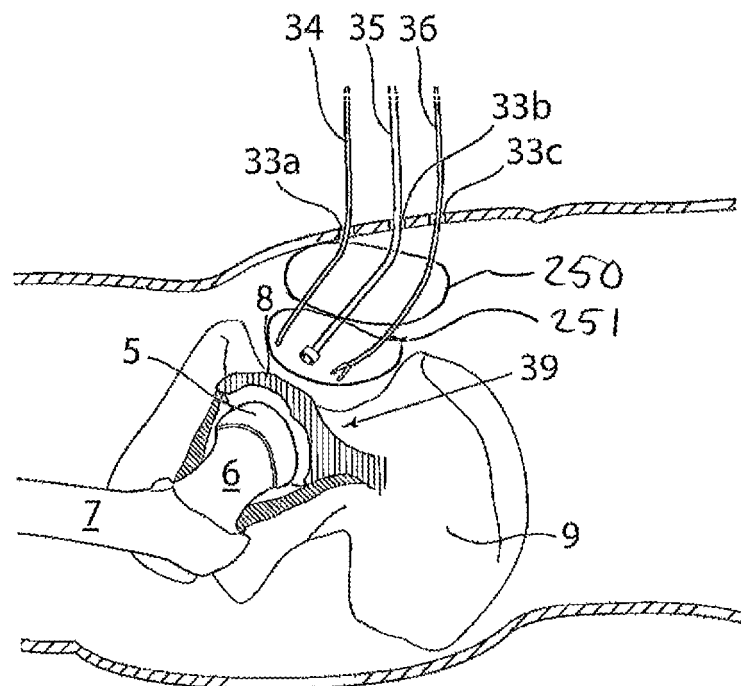


Fig.7



5/32

Fig.8a

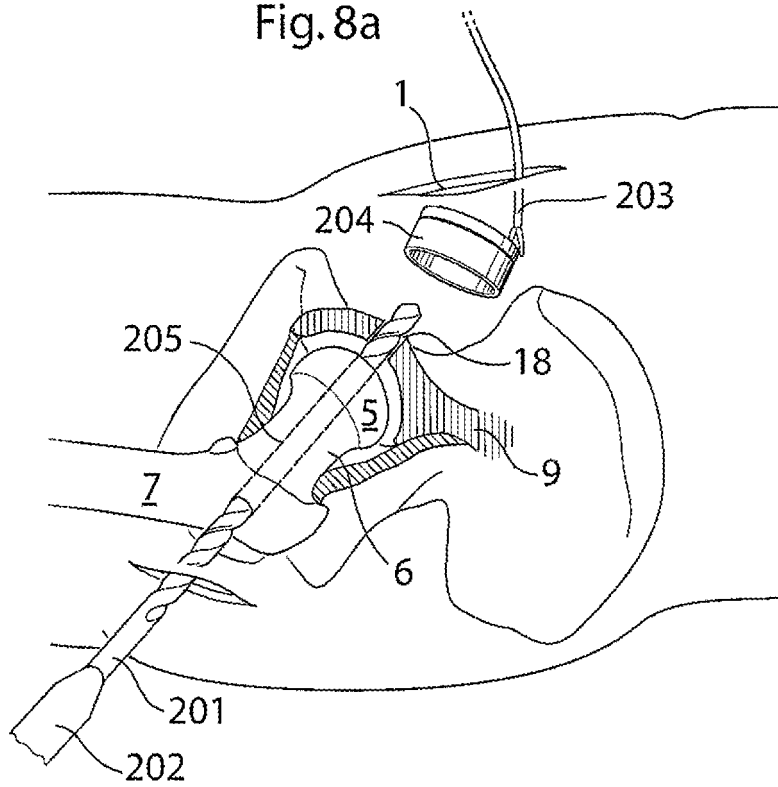
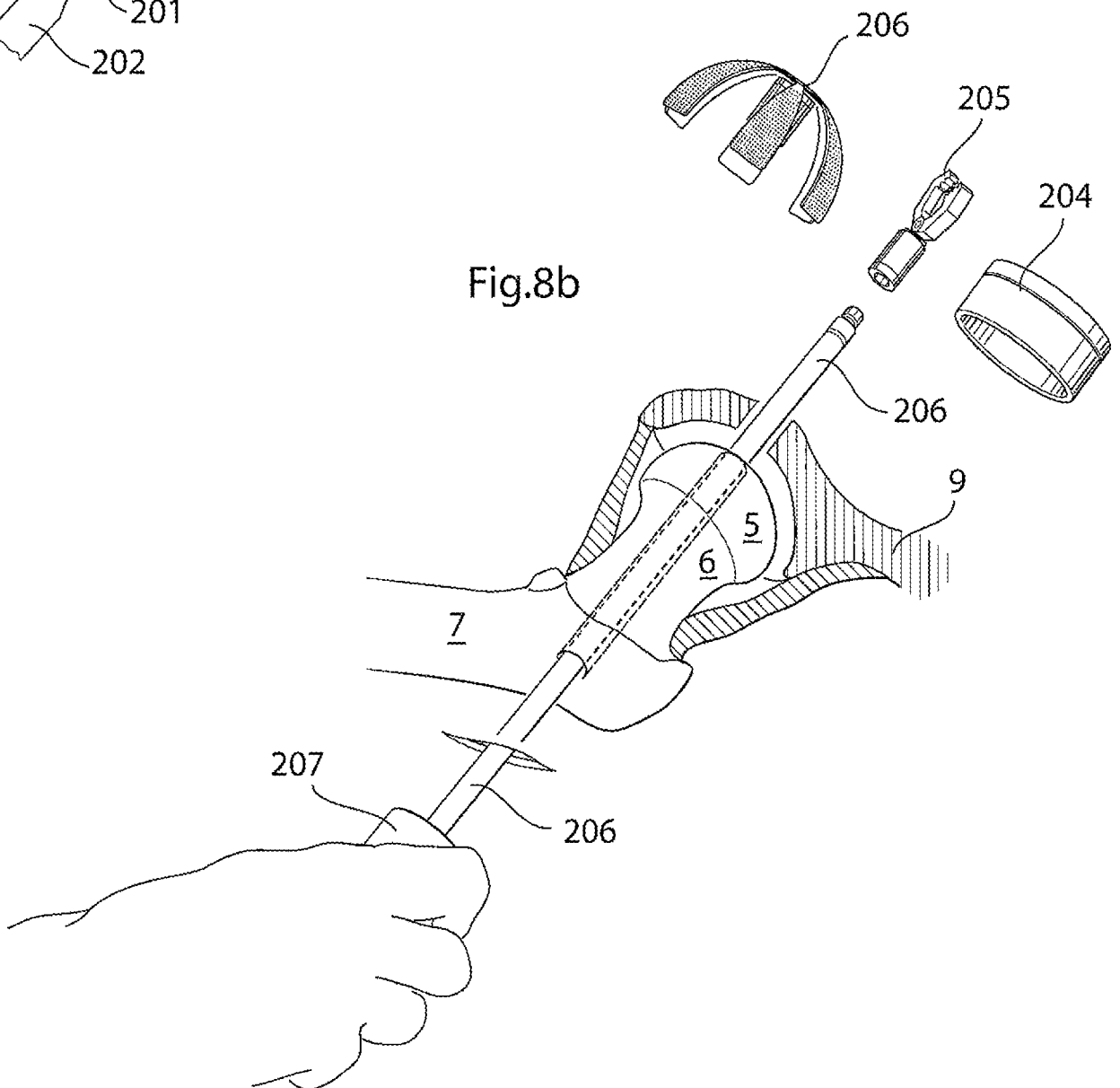


Fig.8b



6/32

Fig. 9a

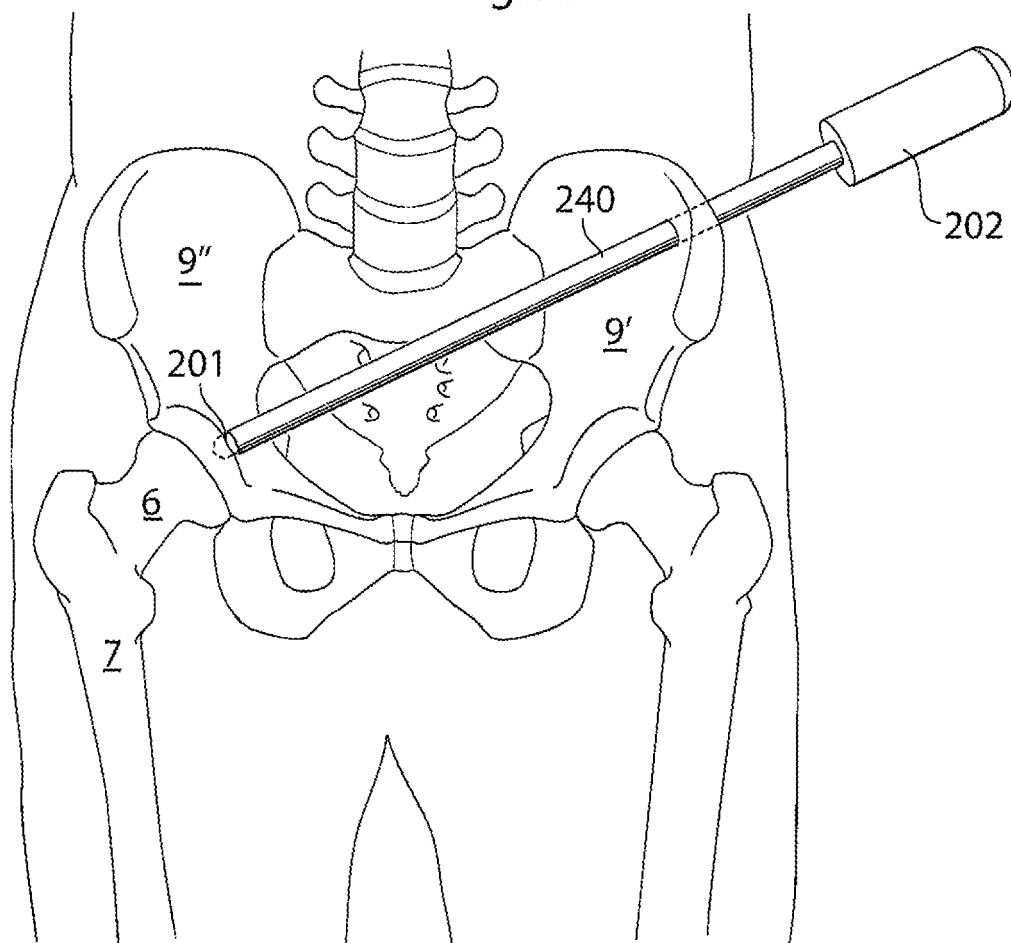
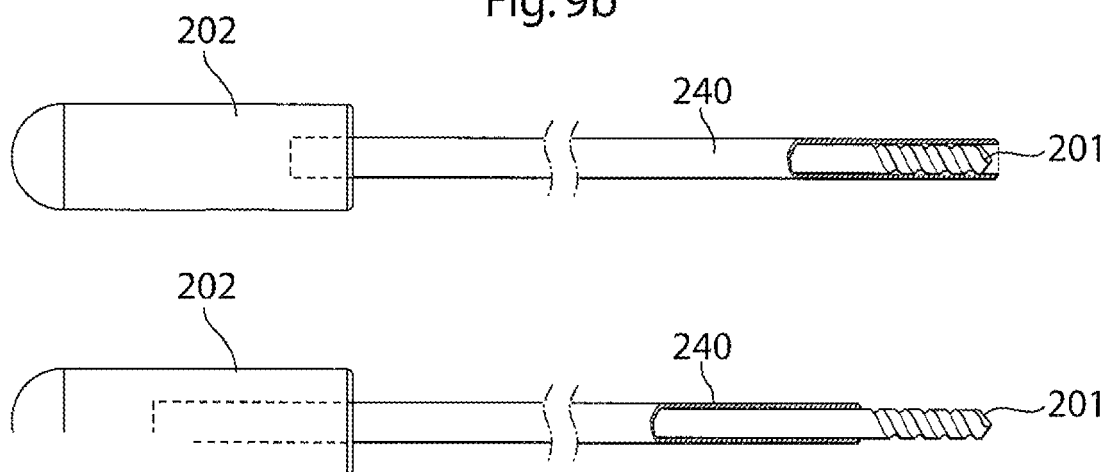


Fig. 9b



7/32

Fig.10a

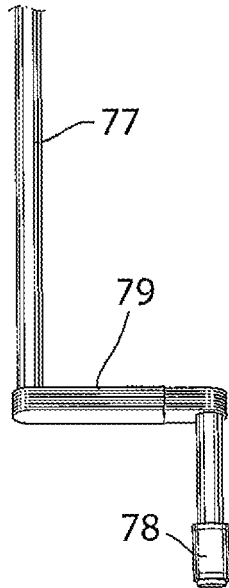


Fig.10c

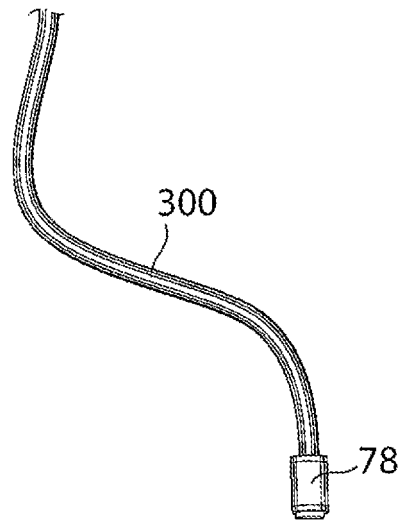


Fig.10b

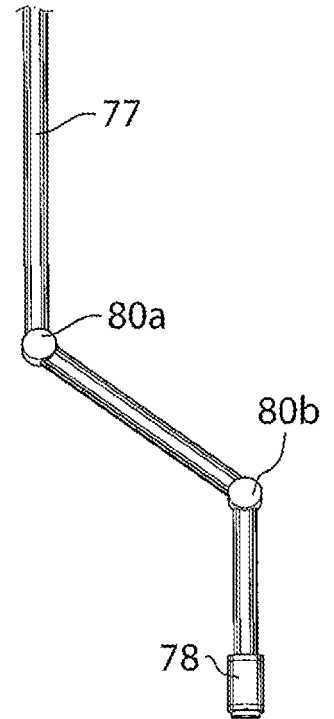


Fig.11

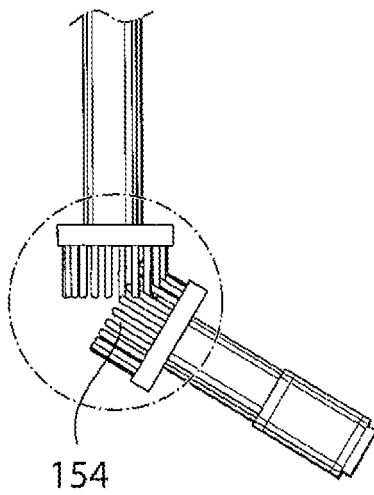


Fig.12

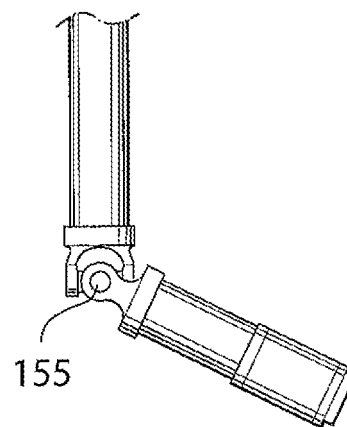
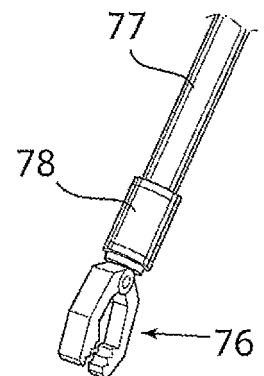


Fig.13



8/32

Fig. 14

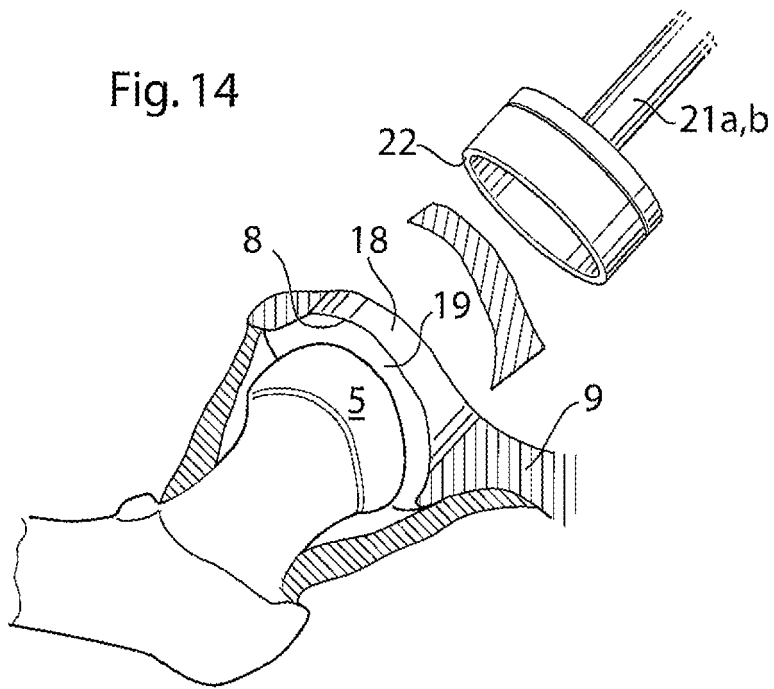


Fig. 15

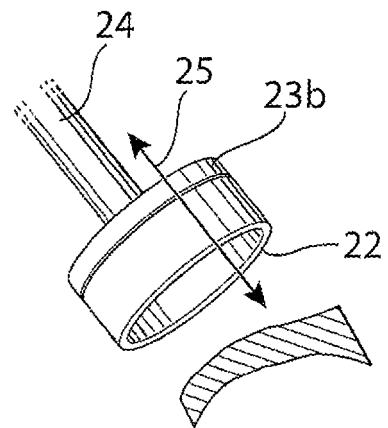


Fig. 17

Fig. 16

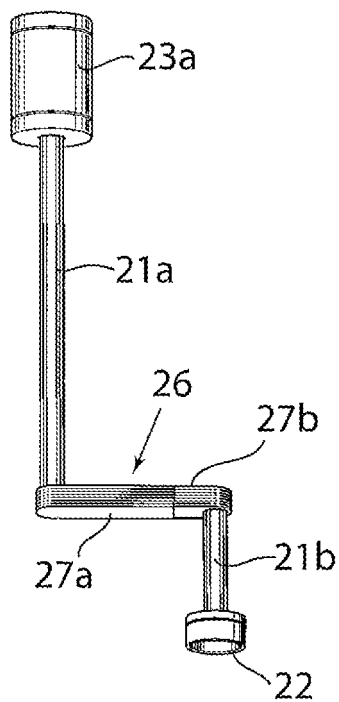


Fig. 18

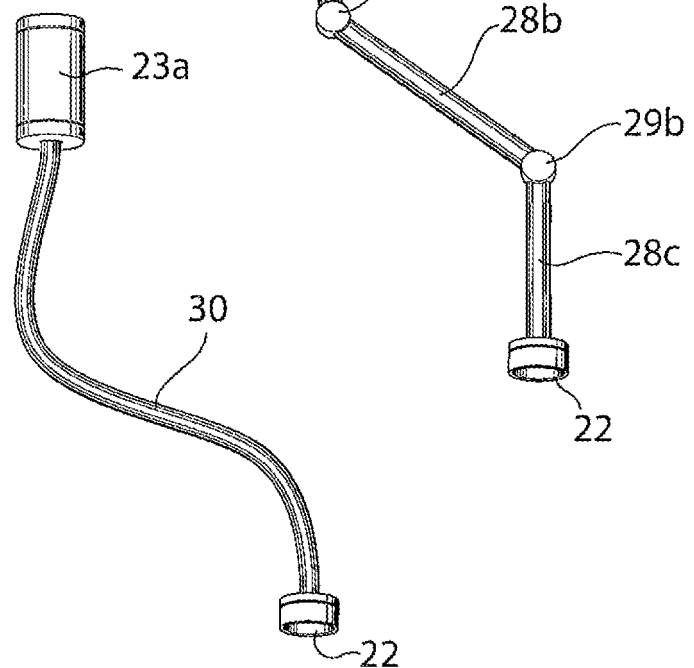


Fig.19a

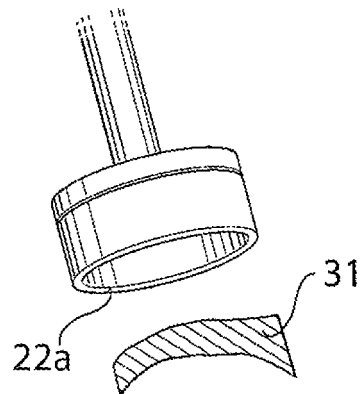


Fig.19b

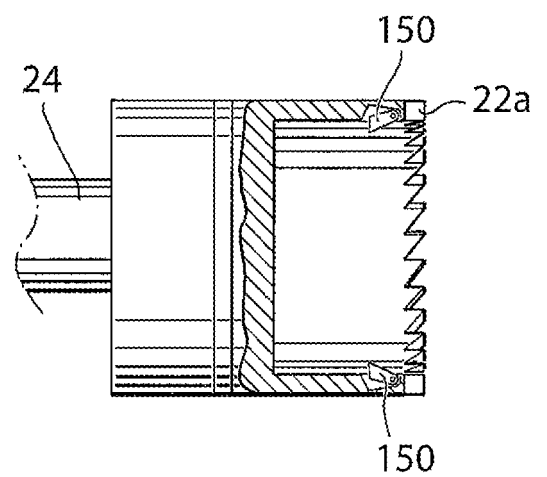


Fig.20

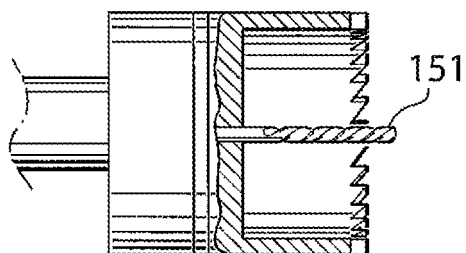


Fig.21

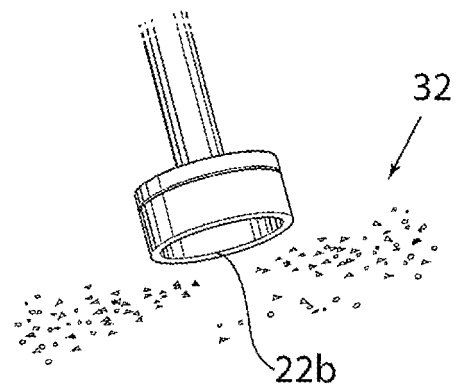
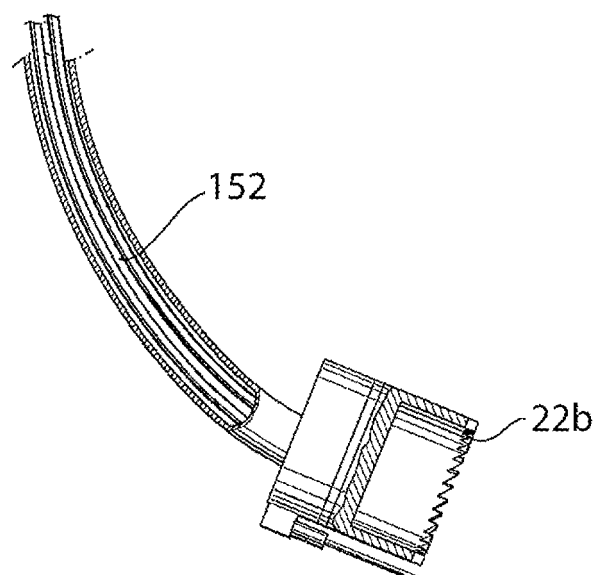


Fig.22



10/32

Fig.23

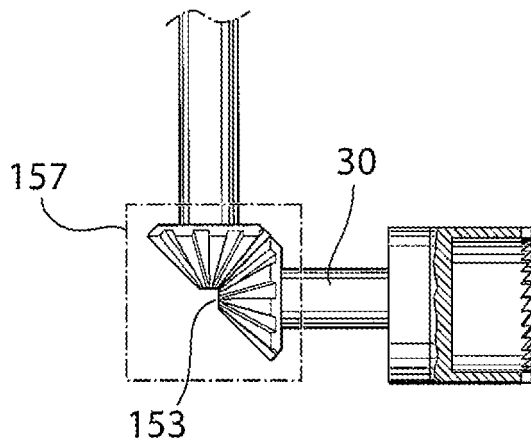


Fig.24

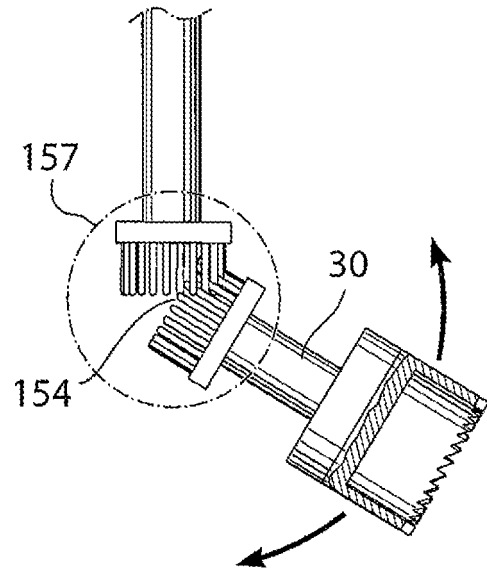


Fig.25

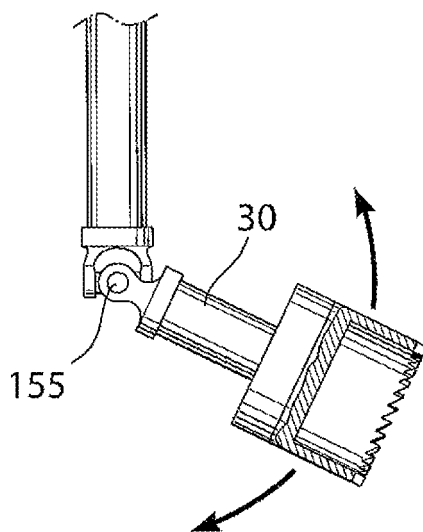
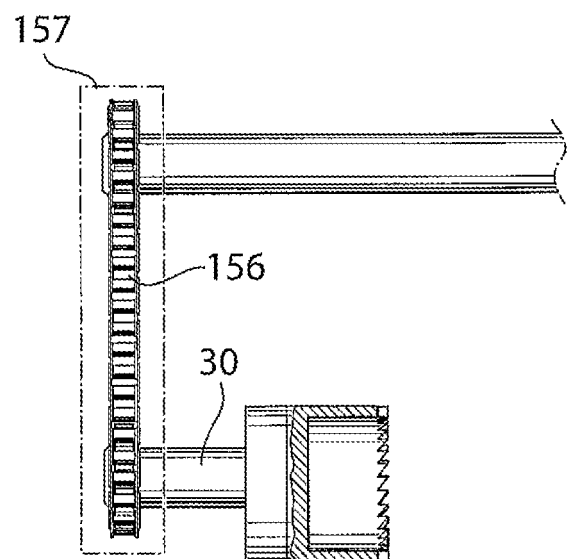


Fig.26



11/32

Fig.27

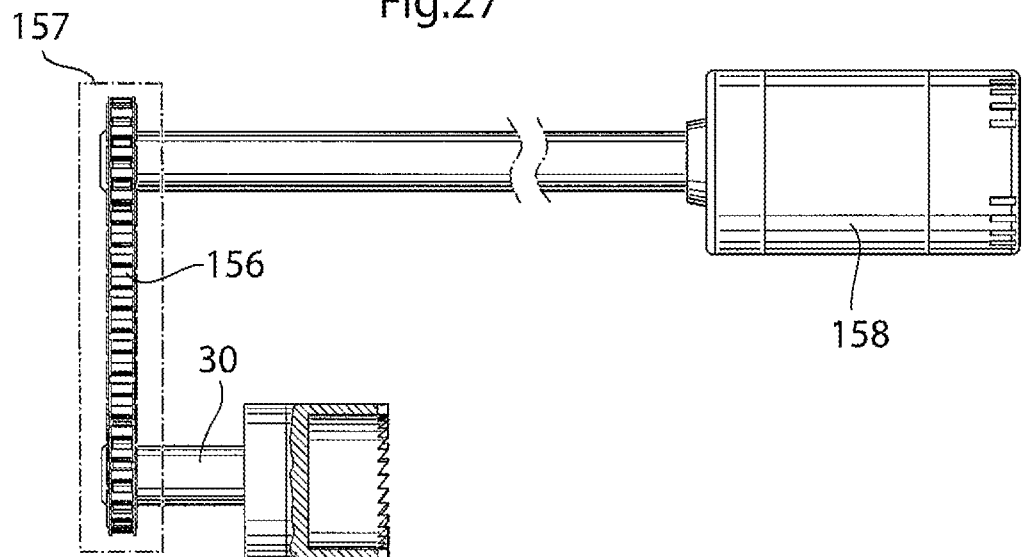


Fig.28a

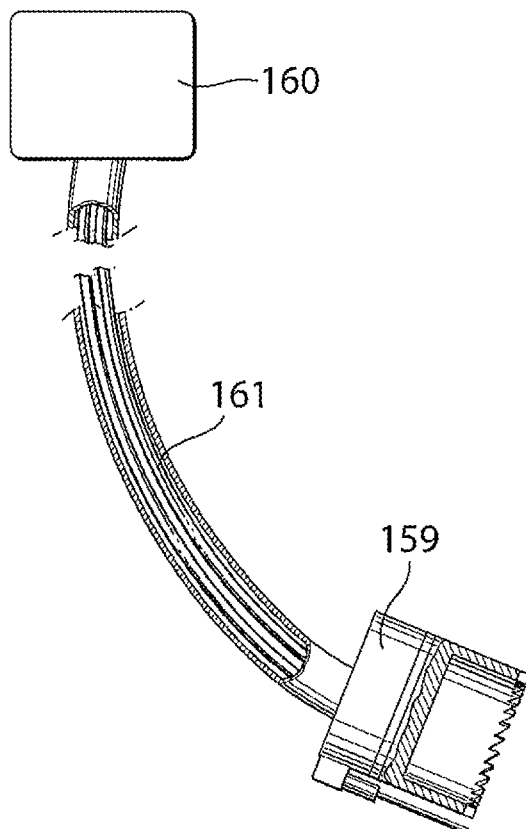
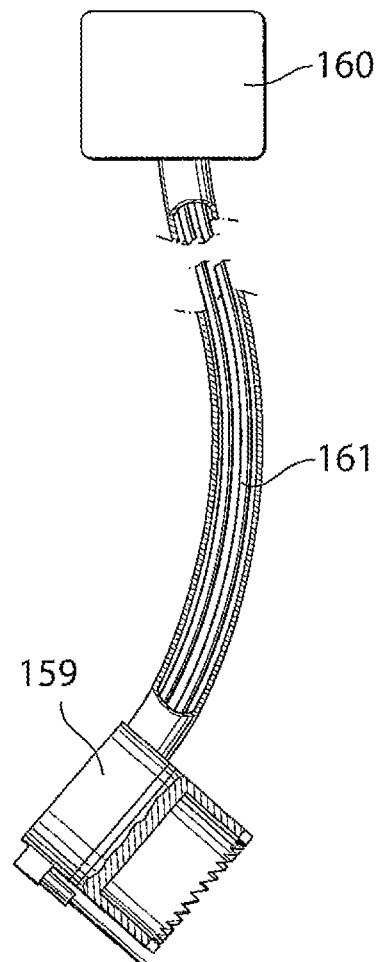


Fig.28b



12/32

Fig.29

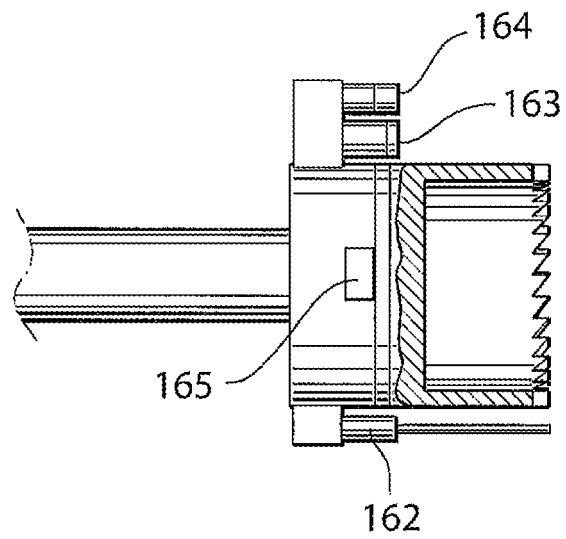


Fig.30

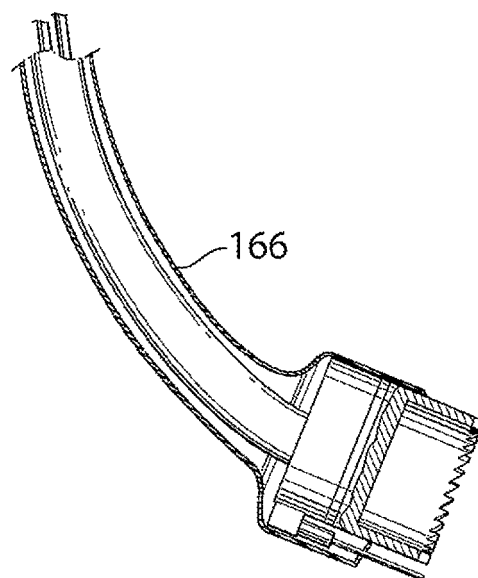


Fig. 31

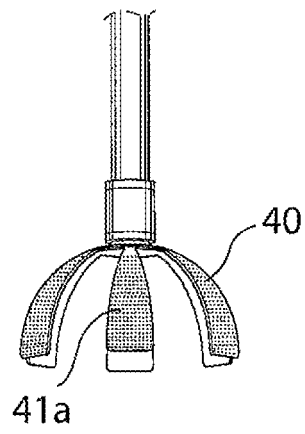


Fig. 32

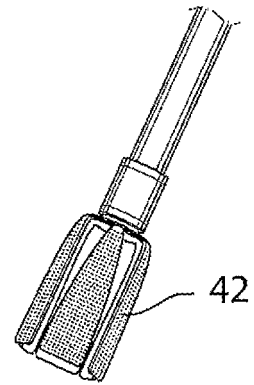


Fig. 33

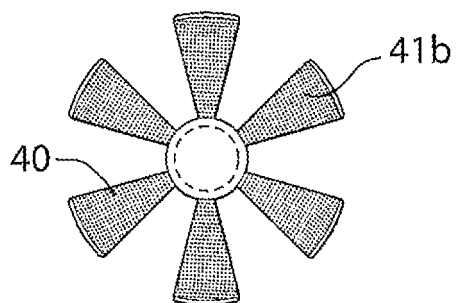


Fig. 34

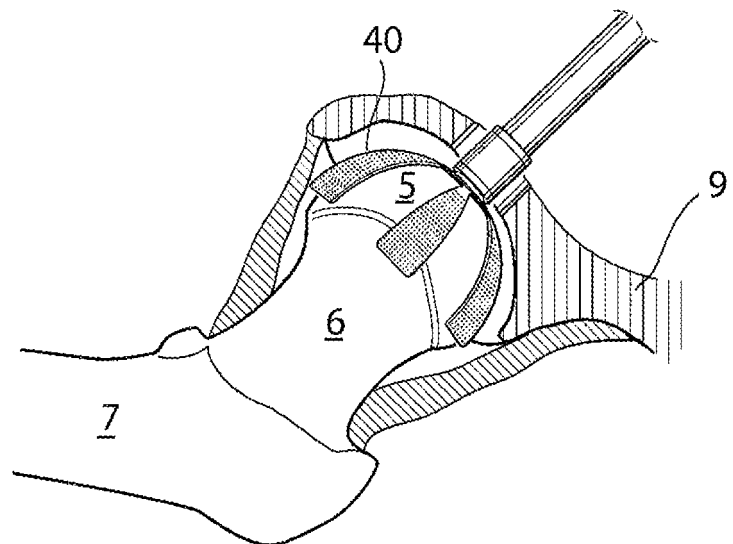


Fig.35

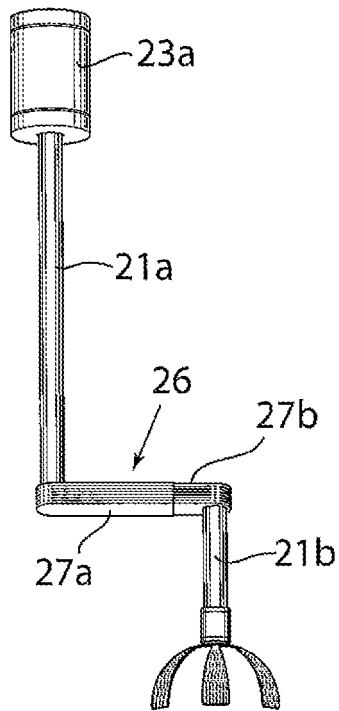


Fig.36

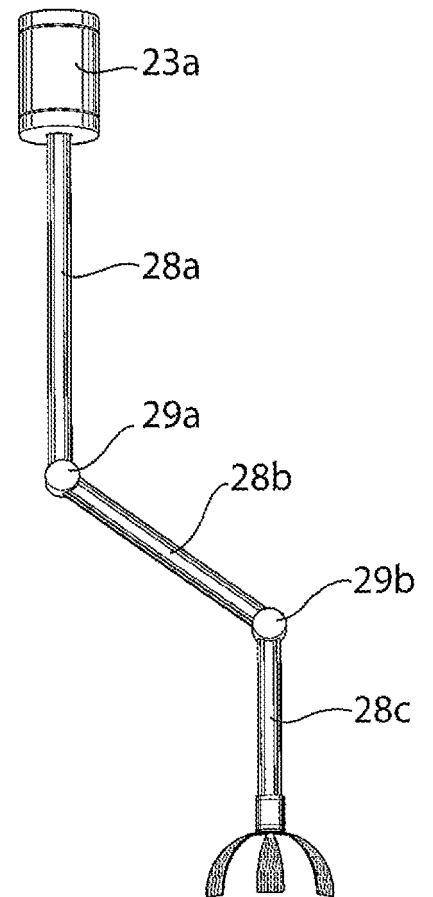


Fig.37

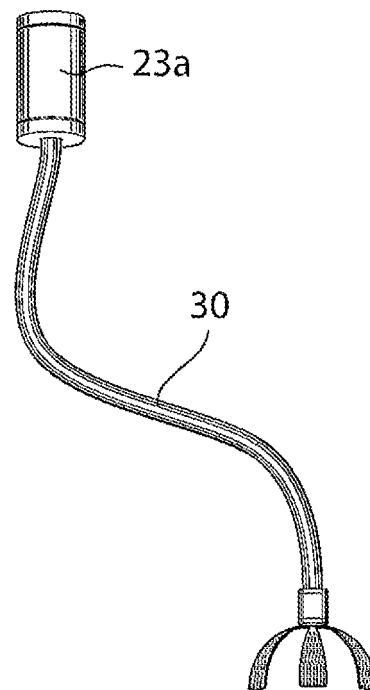


Fig.38

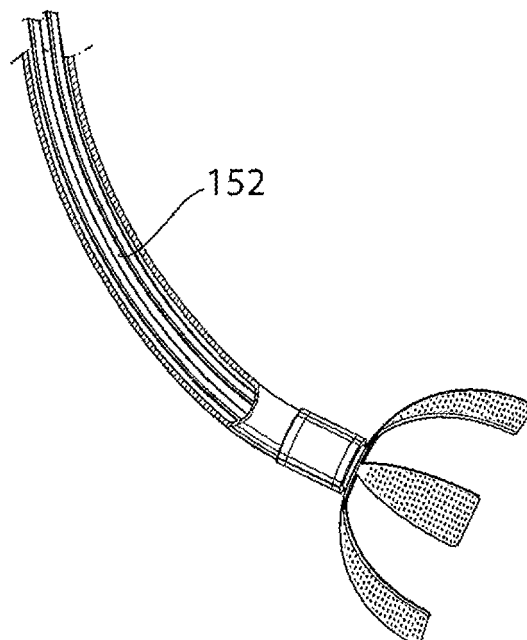


Fig.39

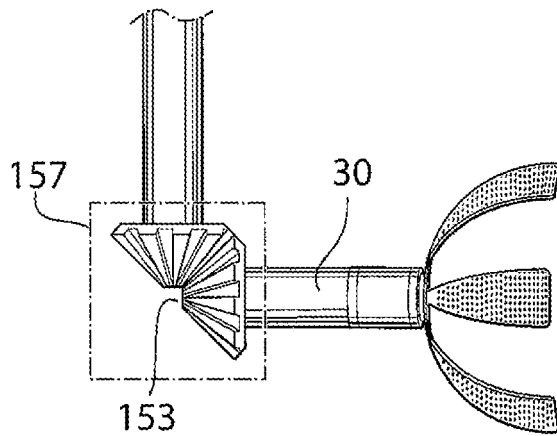


Fig.40

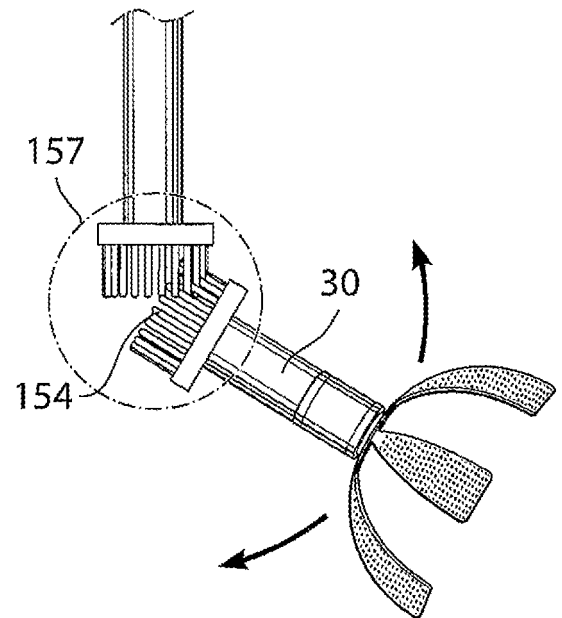


Fig.41

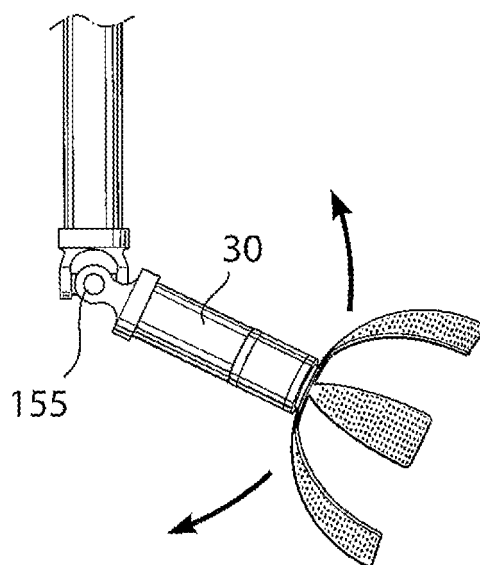
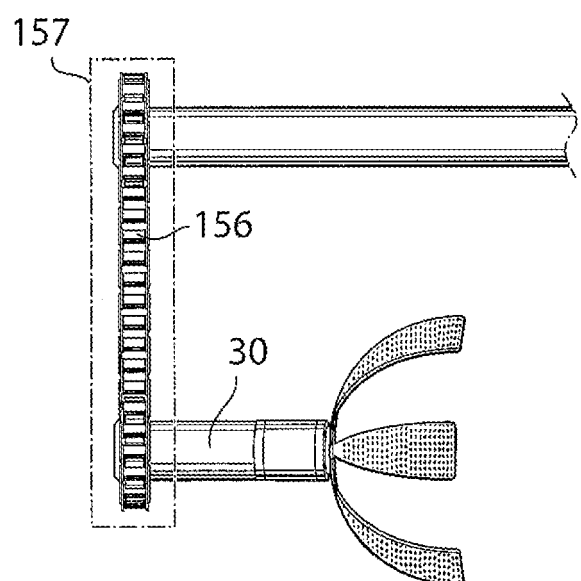


Fig.42



16/32

Fig.43

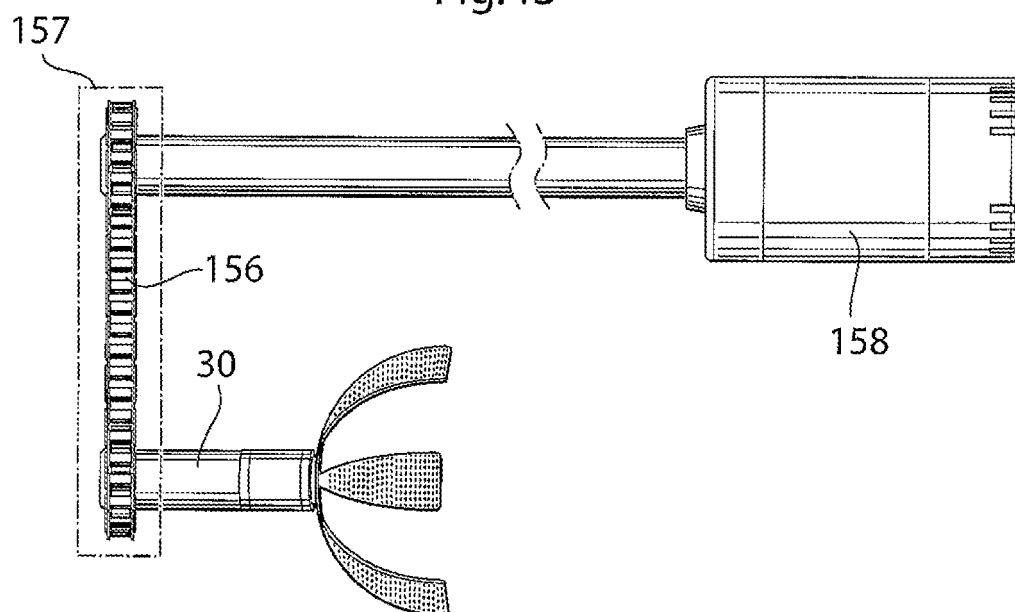


Fig.44

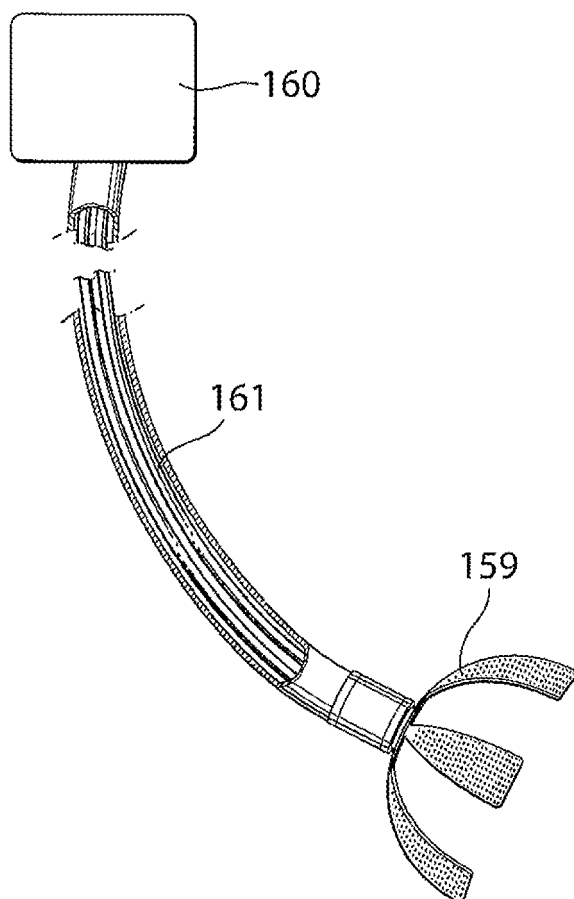
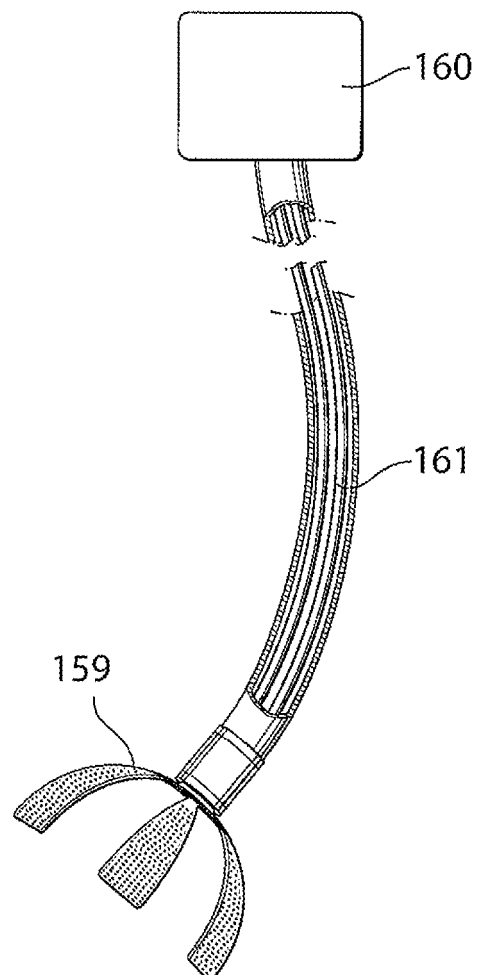


Fig.45



17/32

Fig.46

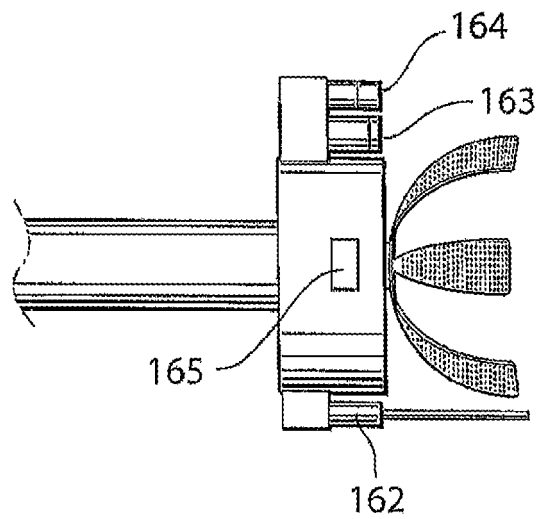


Fig.47

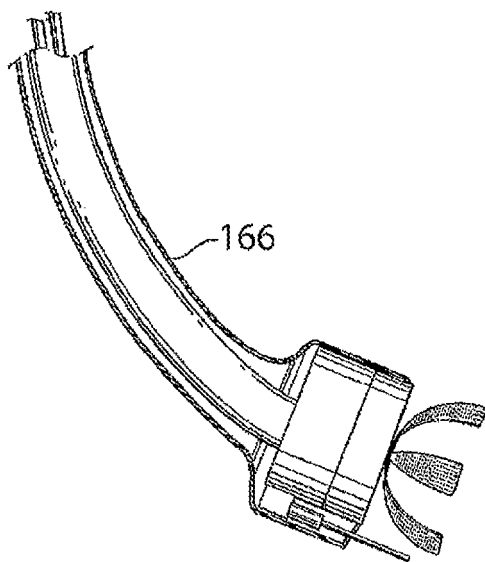


Fig.48

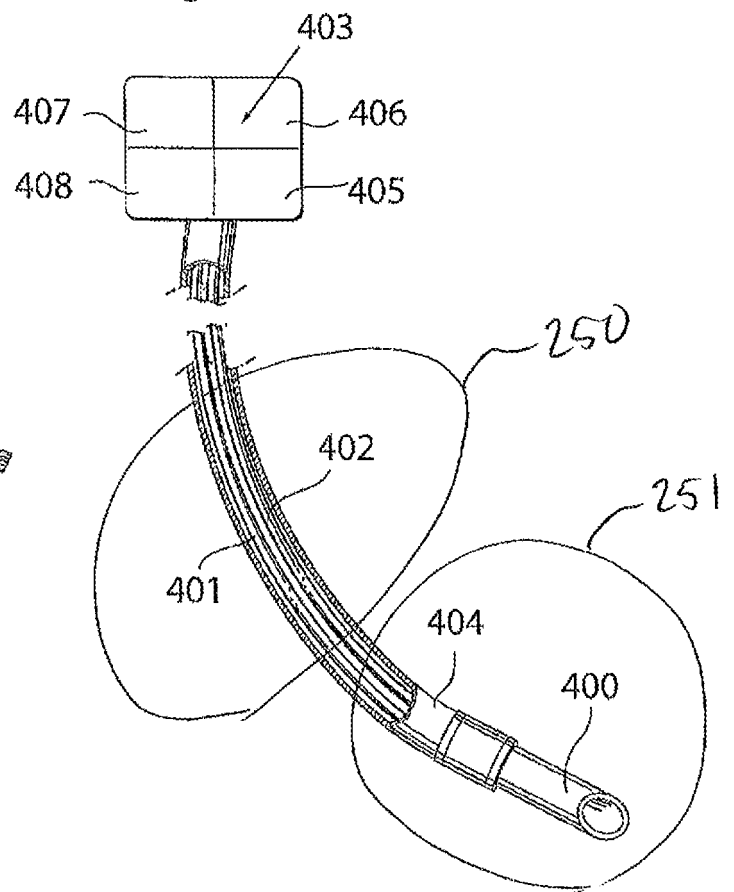


Fig. 49

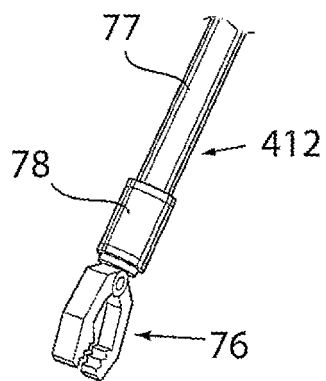


Fig. 50

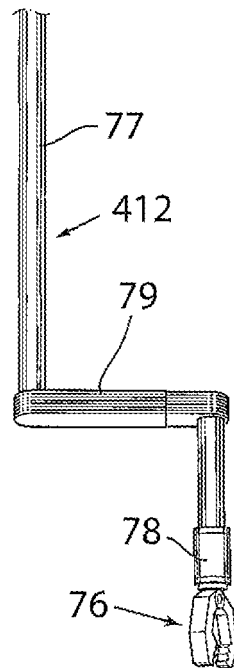


Fig. 51

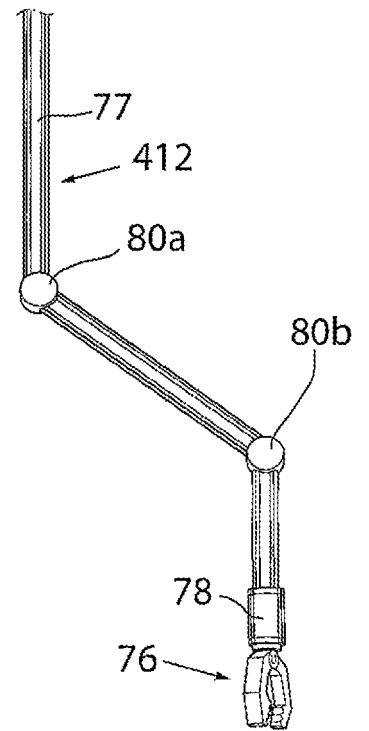


Fig. 52

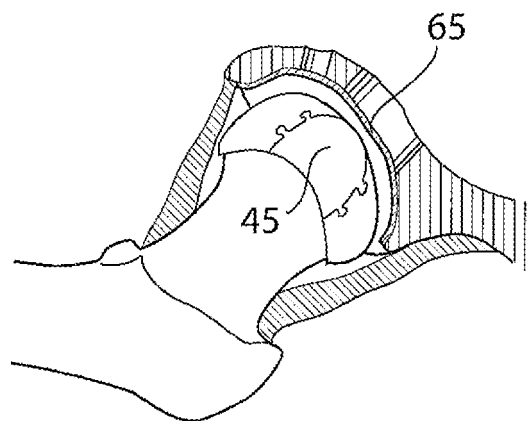


Fig.53

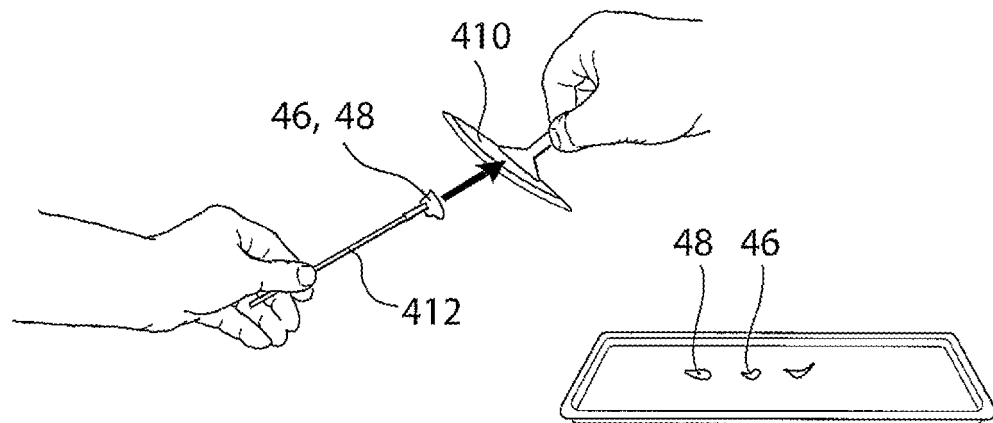
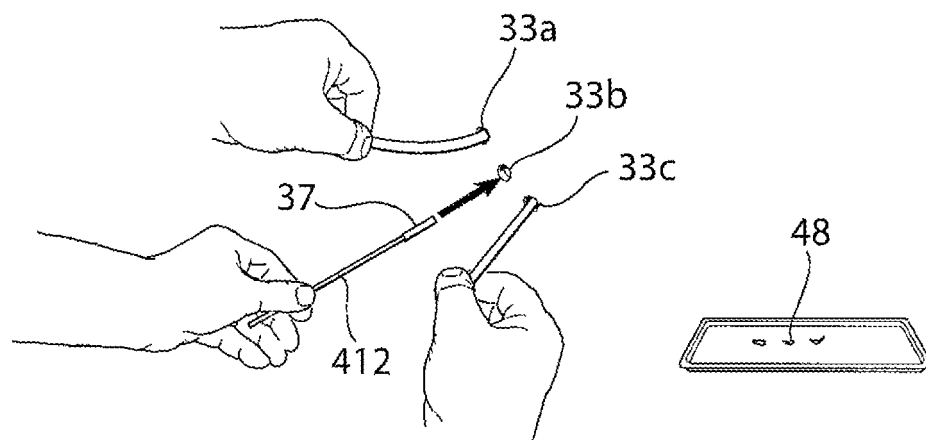
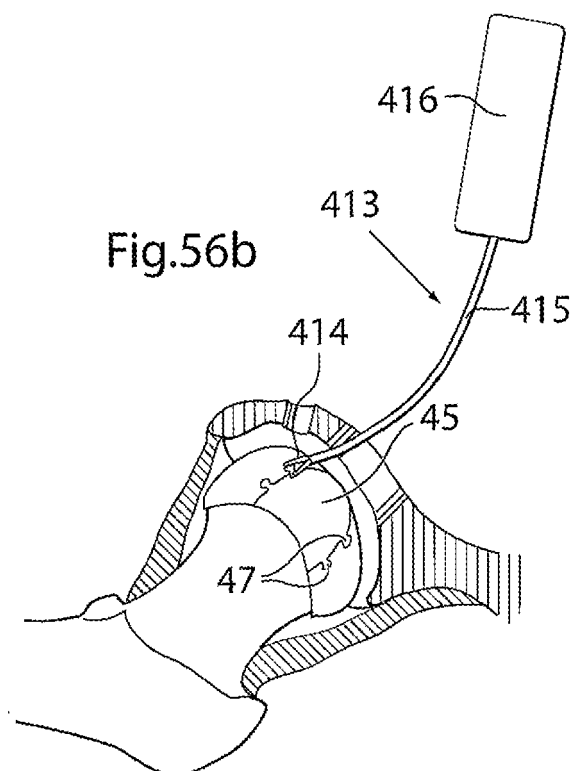
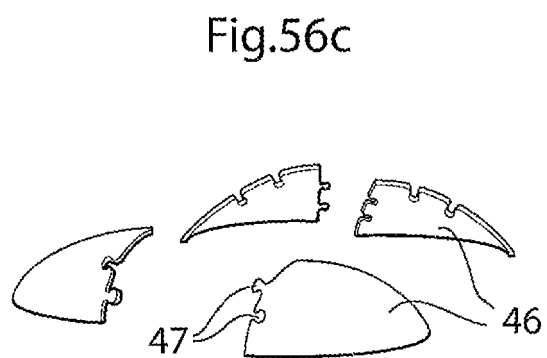
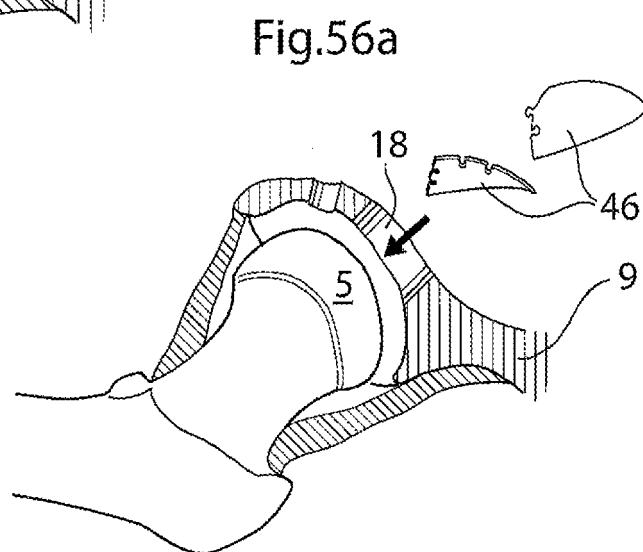
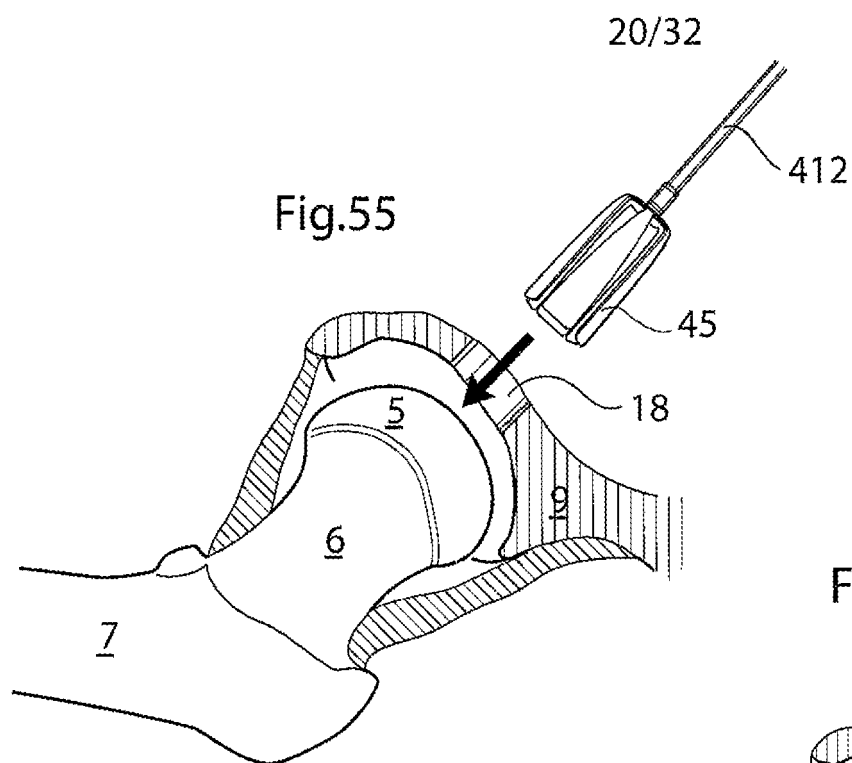


Fig.54





21/32

Fig.57

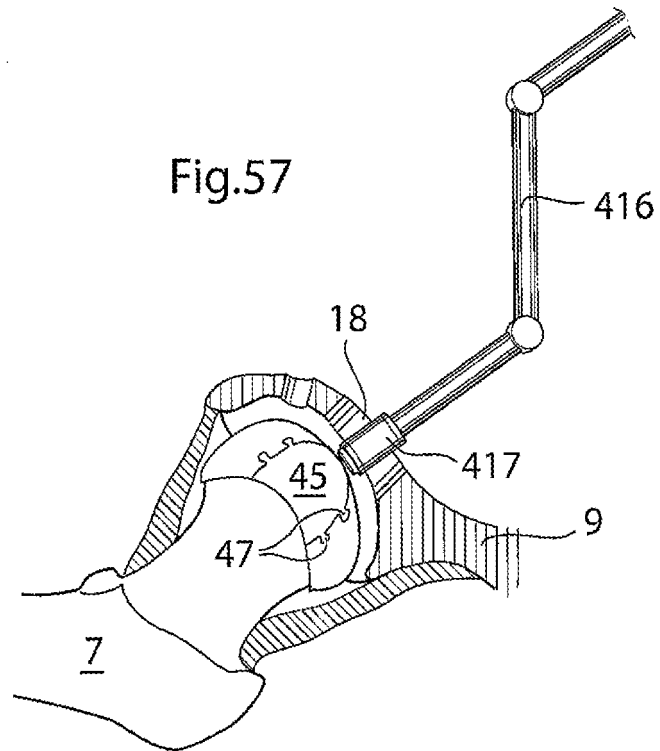


Fig.58

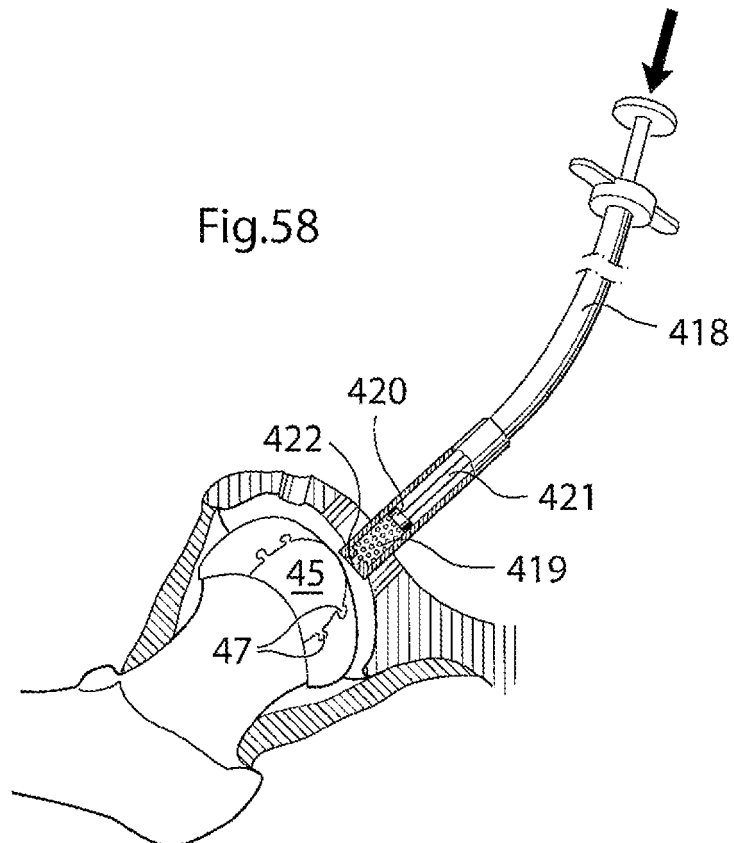


Fig.59a

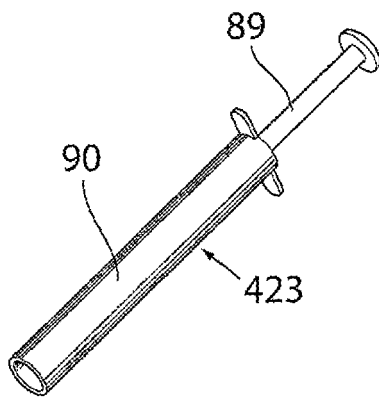


Fig.59b

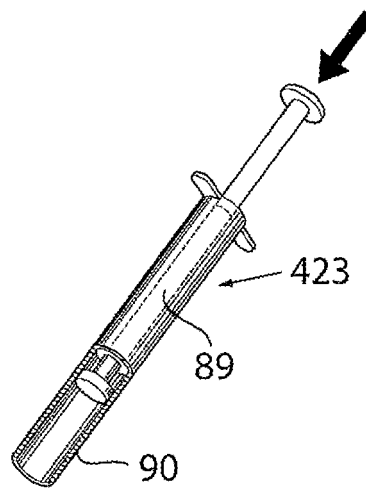


Fig.59c

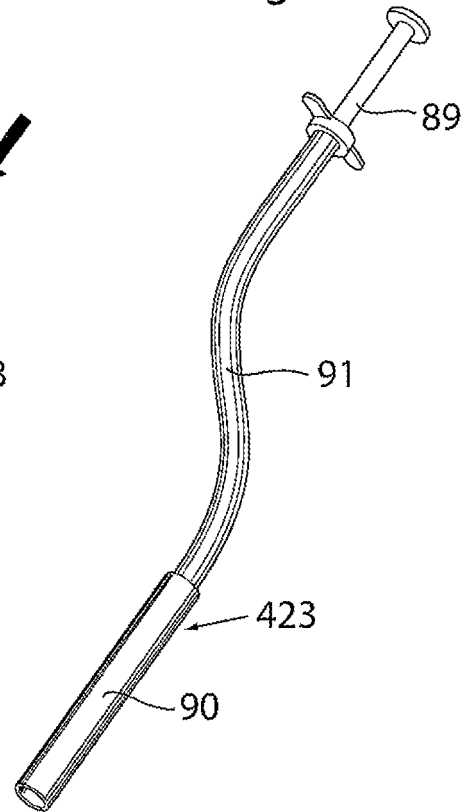


Fig.60a

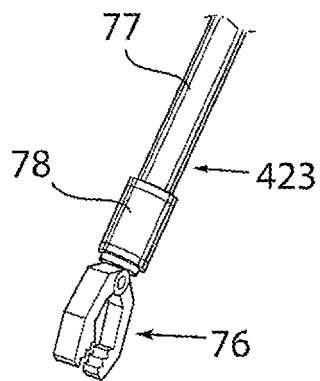


Fig.60b

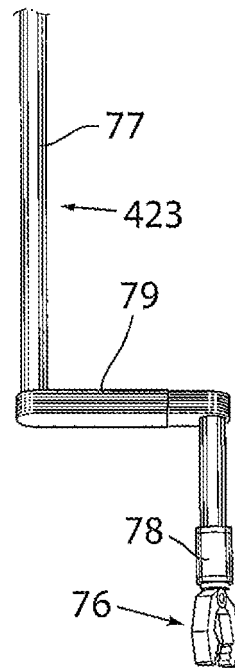
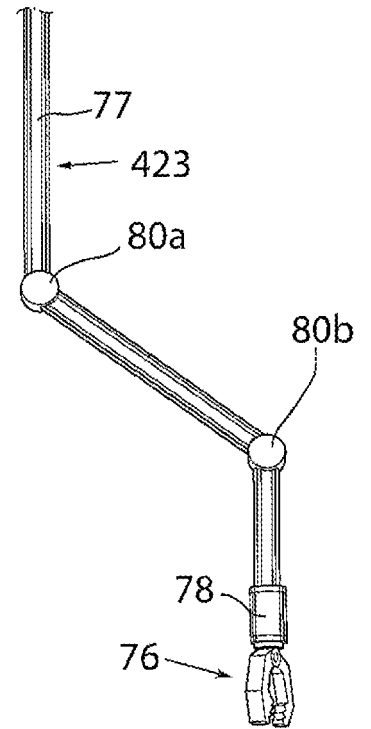


Fig.60c



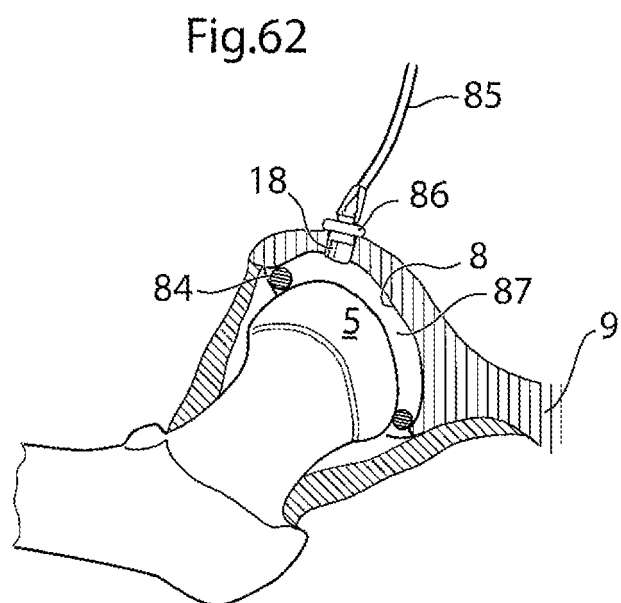
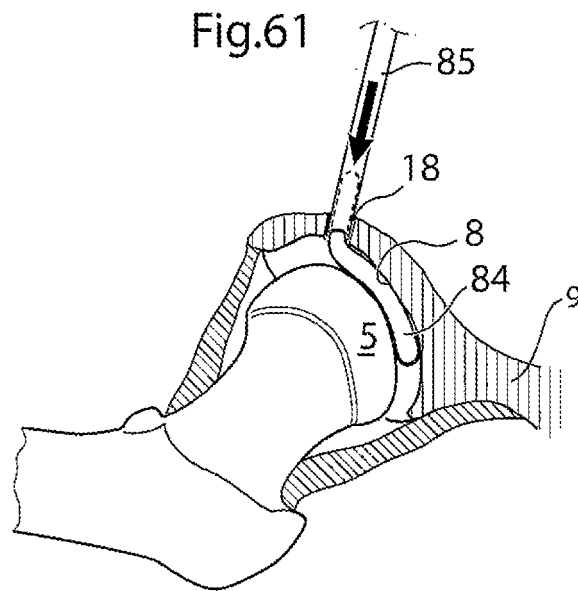


Fig.63a

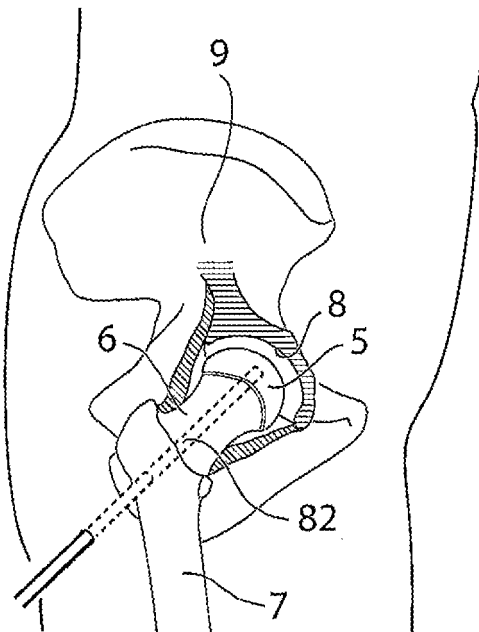


Fig.63b

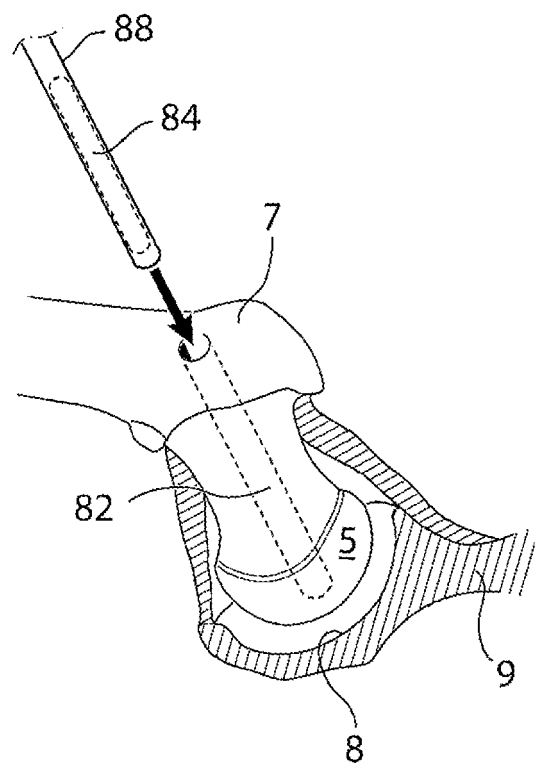


Fig.63c

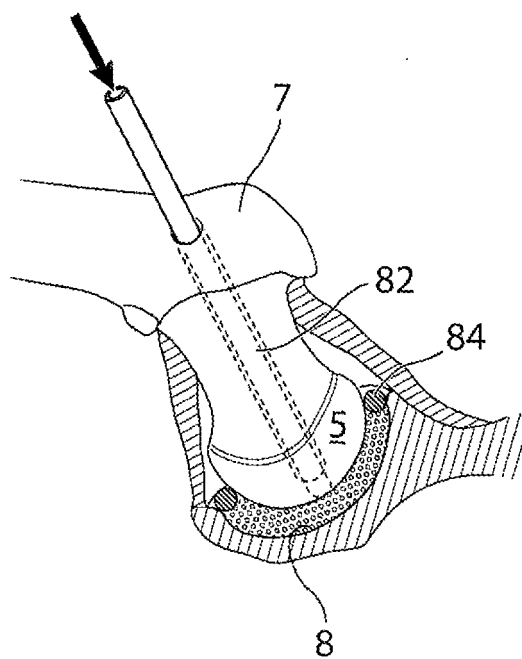


Fig.64

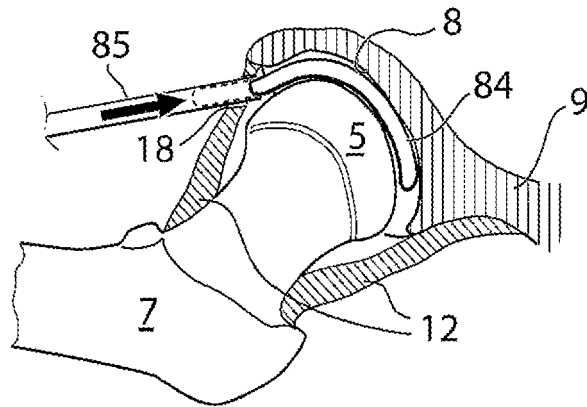


Fig.65

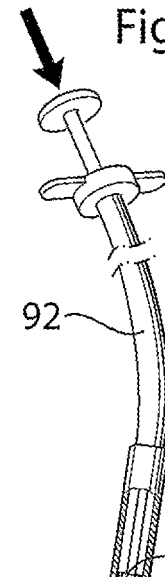
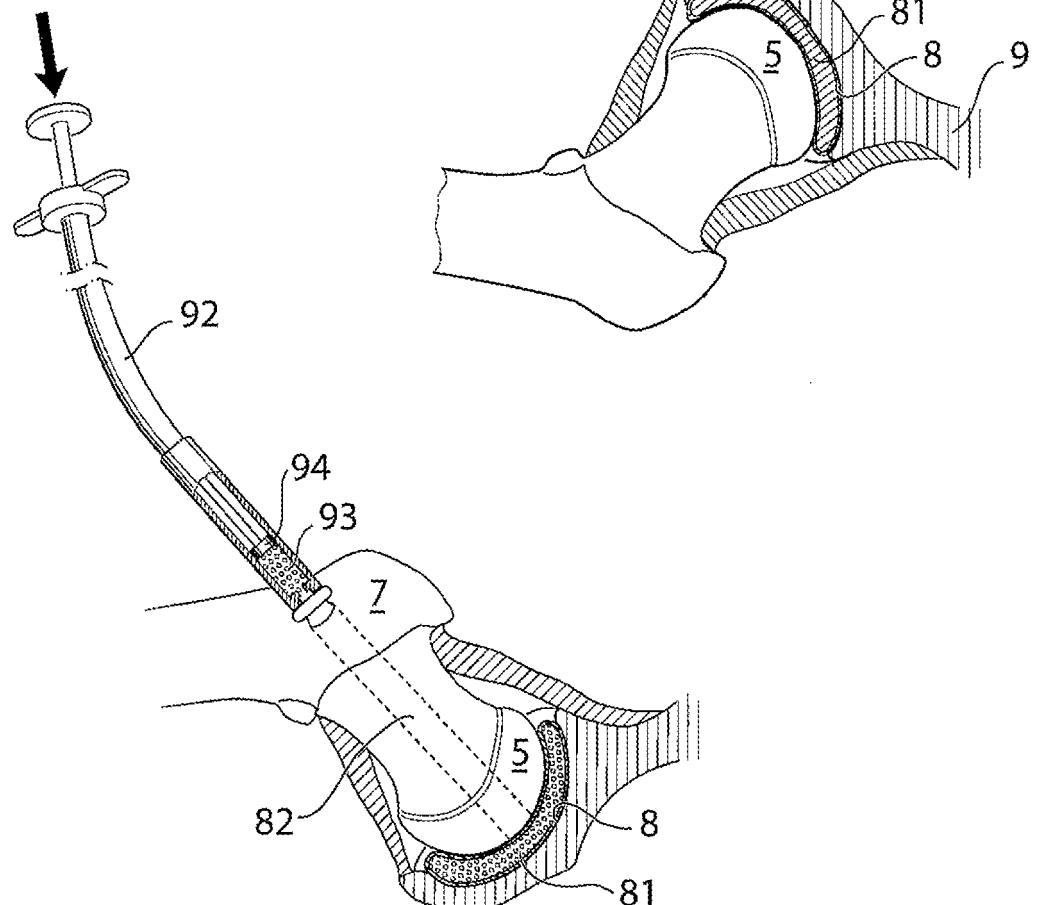


Fig.66



27/32

Fig.67

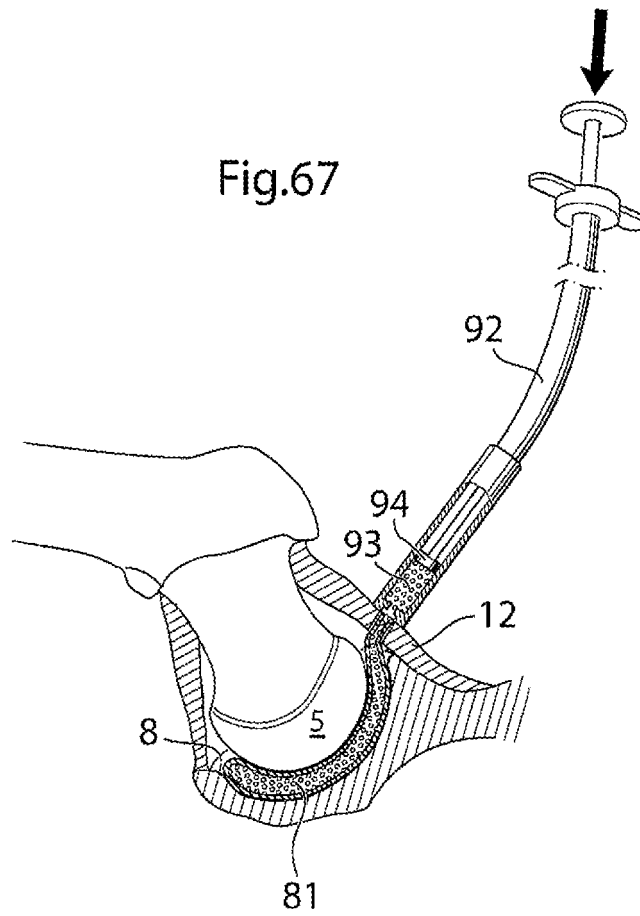


Fig.68

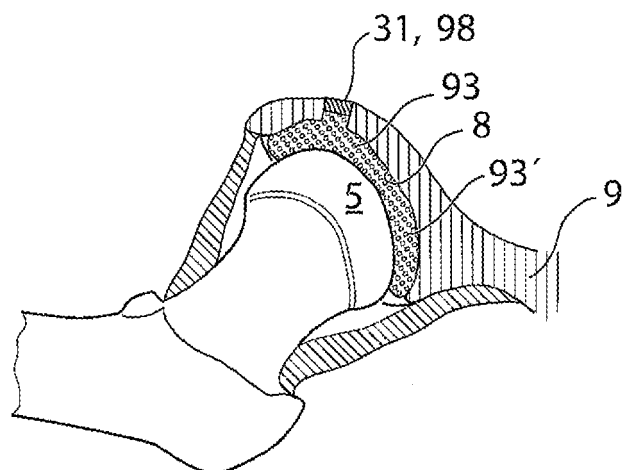


Fig.69

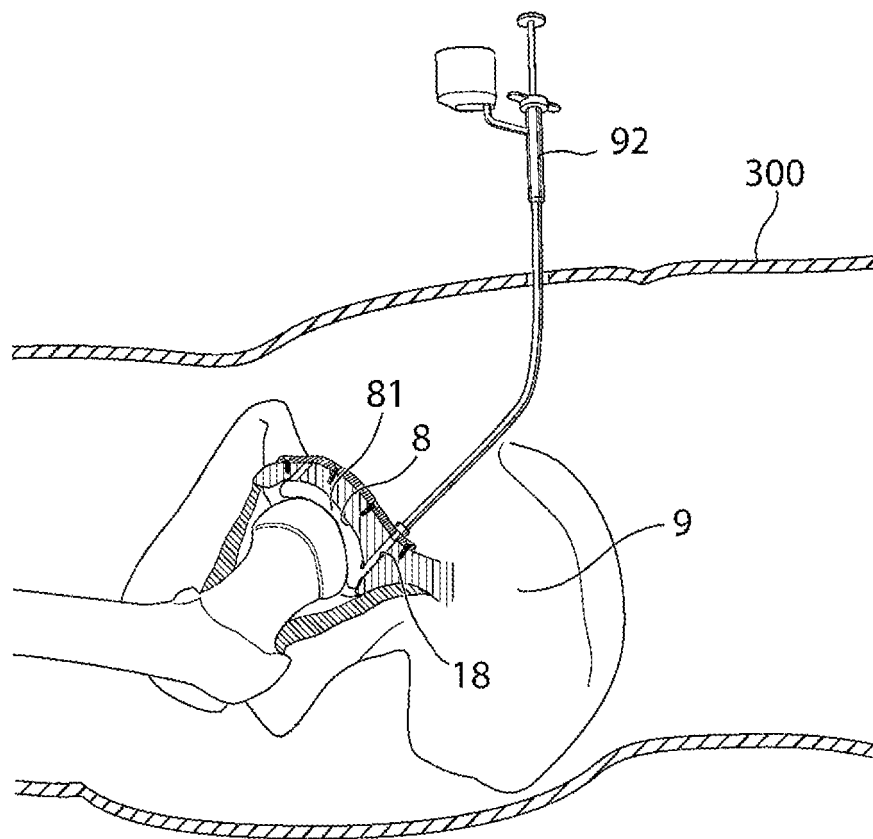


Fig.70

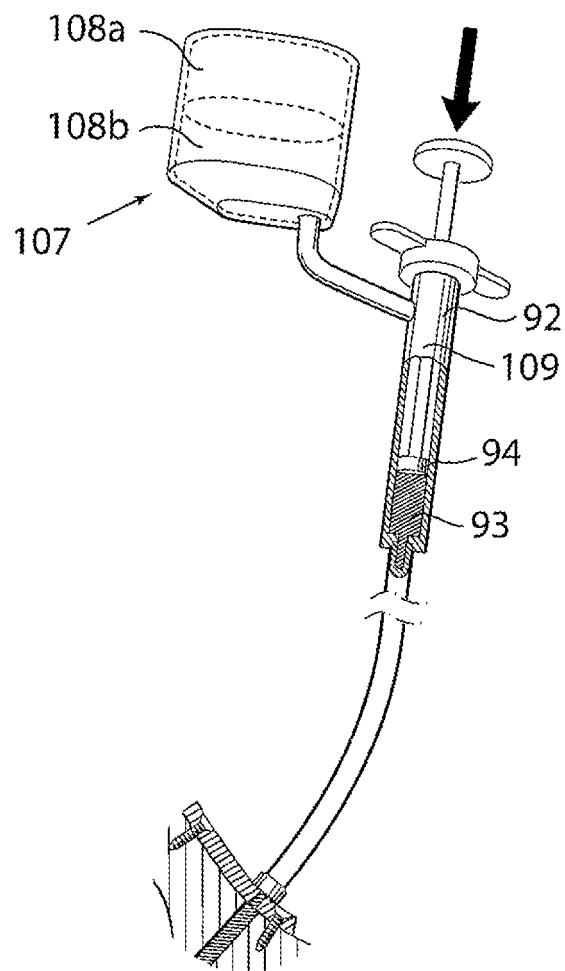


Fig.71a

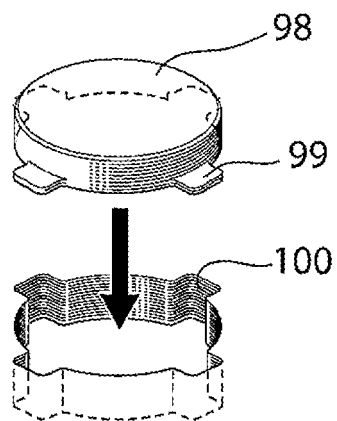


Fig.71b

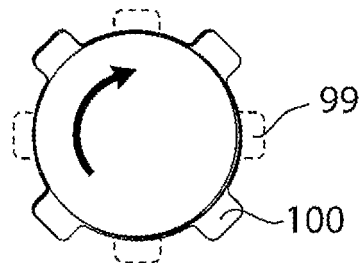


Fig.72

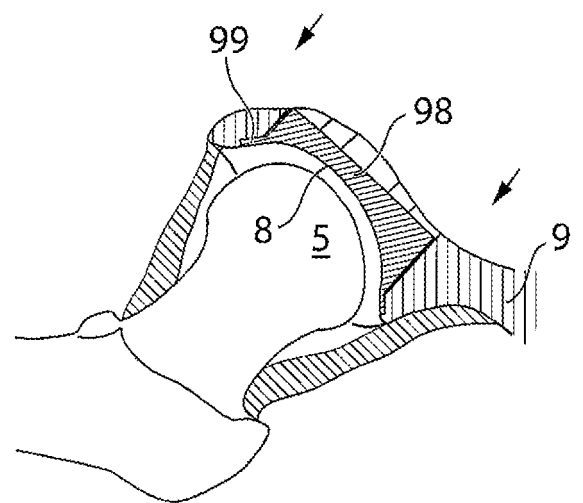
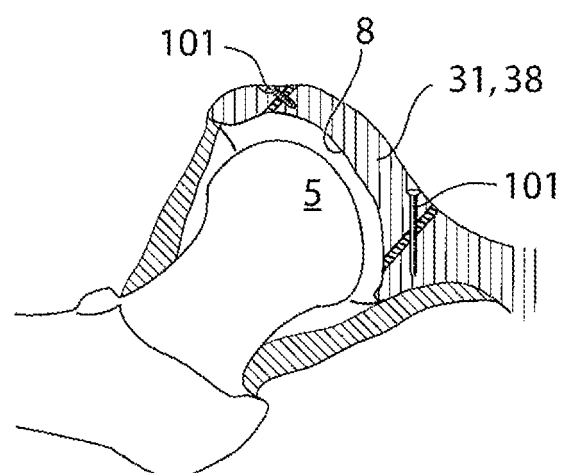
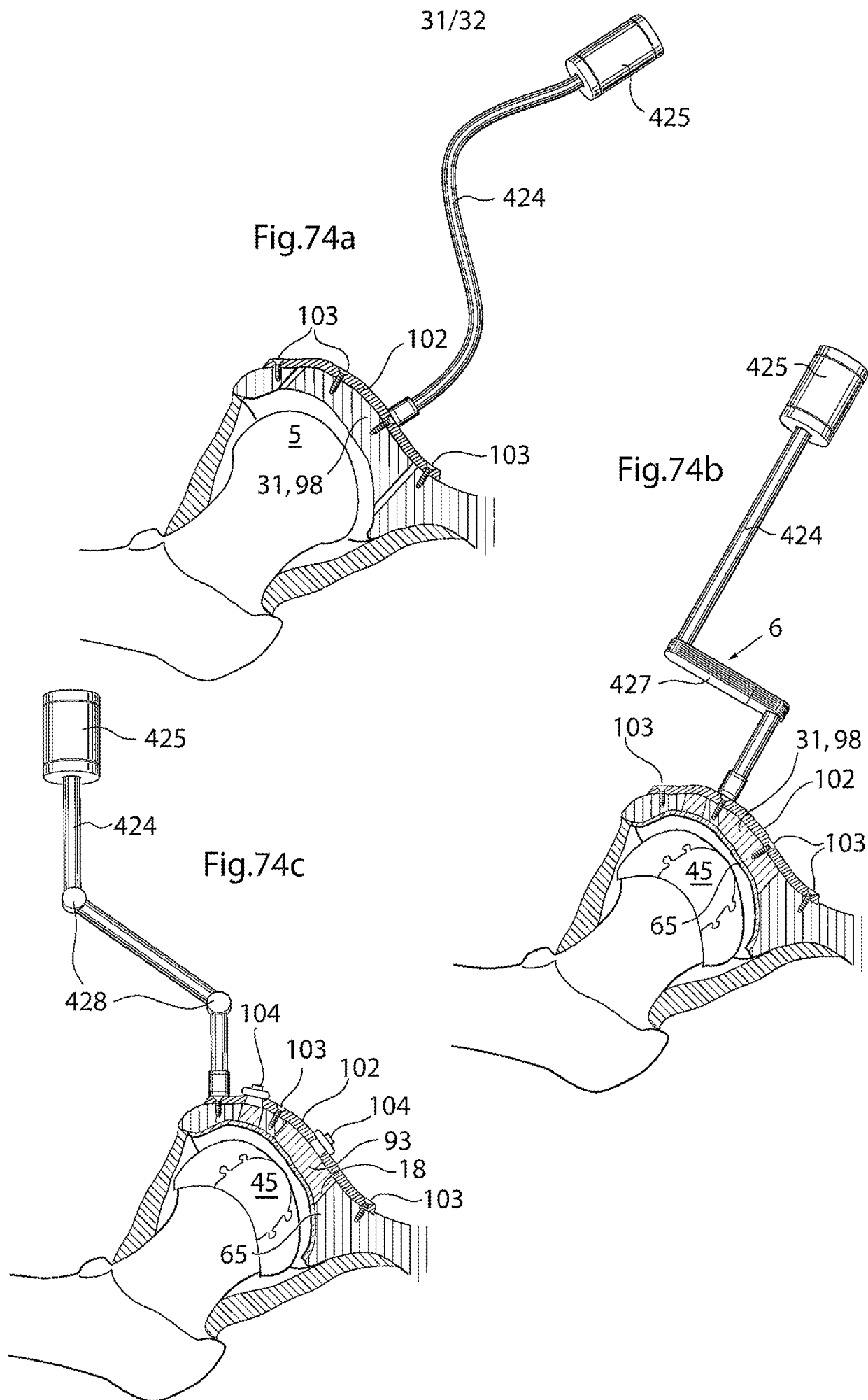


Fig.73





32/32

Fig.75

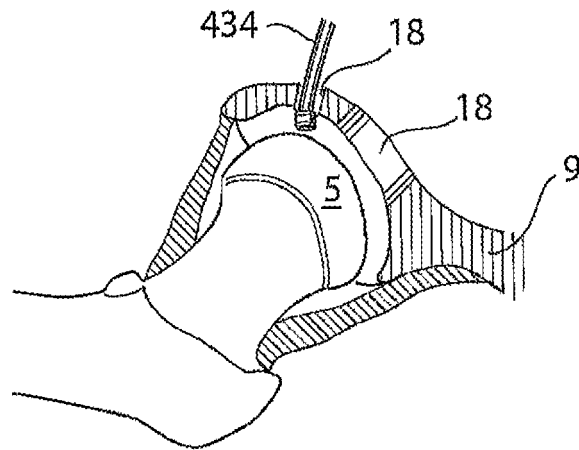
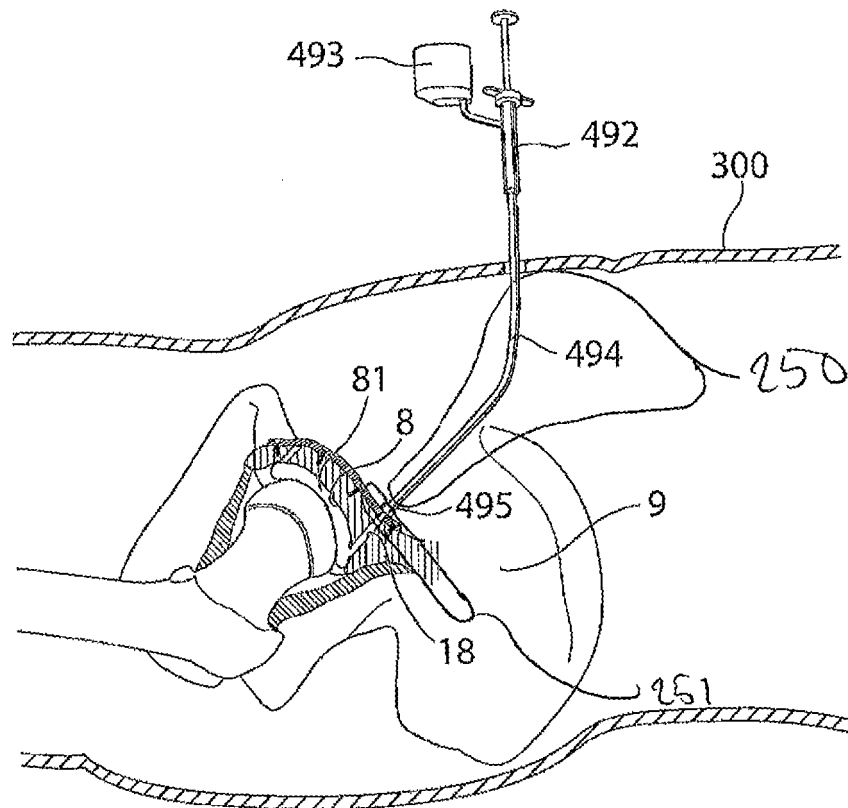


Fig.76



INTERNATIONAL SEARCH REPORT

International application No.

PCT/SE2010/050823

A. CLASSIFICATION OF SUBJECT MATTER

IPC: see extra sheet

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC: A61F, A61B

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

SE,DK,FI,NO classes as above

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

EPO-INTERNAL, WPI DATA, PAJ

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 20030130741 A1 (D.J.W. MCMINN), 10 July 2003 (10.07.2003), figures 12,13, paragraphs (0005), (0007), (0025)-(0027), (0031), (0033), (0042), (0044), (0046)	1-112
A	--	113-150
X	US 20080221392 A1 (G. JORGENSEN), 11 Sept 2008 (11.09.2008), figures 5a,6a, paragraphs (0008)-(0009), (0115), (0126)	1-112
A	--	113-150



Further documents are listed in the continuation of Box C.



See patent family annex.

* Special categories of cited documents:

- "A" document defining the general state of the art which is not considered to be of particular relevance
- "E" earlier application or patent but published on or after the international filing date
- "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)
- "O" document referring to an oral disclosure, use, exhibition or other means
- "P" document published prior to the international filing date but later than the priority date claimed

"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

"X" document of particular relevance: the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

"Y" document of particular relevance: the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art

"&" document member of the same patent family

Date of the actual completion of the international search

27 October 2010

Date of mailing of the international search report

29 -10- 2010

Name and mailing address of the ISA/

Swedish Patent Office
Box 5055, S-102 42 STOCKHOLM
Facsimile No. +46 8 666 02 86

Authorized officer

Gordana Ninkovic / MRo
Telephone No. +46 8 782 25 00

INTERNATIONAL SEARCH REPORT

International application No.

PCT/SE2010/050823

C (Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 5269785 A (P.M. BONUTTI), 14 December 1993 (14.12.1993), figures 3-16, claim 1, abstract	1-112
A	--	113-150
X	WO 2008031245 A2 (UNIVERSITÄT BERN), 20 March 2008 (20.03.2008), page 12, line 10 - page 15, line 5, figures 1-4	1-112
A	--	113-150
A	US 20040236424 A1 (A. BEREZ ET AL), 25 November 2004 (25.11.2004), paragraphs (0002), (0028), (0033)-(0034), (0055)-(0059), (0148), (0152), (0165)-(0169)	1-150
A	--	
A	US 20060190078 A1 (B.M. FELL), 24 August 2006 (24.08.2006), paragraphs (0029), (0038), (0052), (0059)	1-150
A	--	
A	US 5120312 A (B.D. WIGNESS ET AL), 9 June 1992 (09.06.1992), column 3, line 10 - column 4, line 63	1-150
A	--	
A	DE 3343863 A1 (FRÖLICH, J.), 13 June 1985 (13.06.1985), figure 1, abstract	1-150
A	--	
A	WO 9501139 A1 (AOFORSCHUNGSINSTITUT DAVOS), 12 January 1995 (12.01.1995), abstract	1-150
A	--	
A	US 6375684 B1 (H.R. KRICK), 23 April 2002 (23.04.2002), abstract	1-150
	--	

INTERNATIONAL SEARCH REPORT

International application No.

PCT/SE2010/050823

C (Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	US 20040247641 A1 (J.C. FELT ET AL), 9 December 2004 (09.12.2004), abstract --	1-150
A	US 20090043344 A1 (R.D. SCHLOTTERBACK), 12 February 2009 (12.02.2009), abstract -- -----	1-150

INTERNATIONAL SEARCH REPORT

International application No.
PCT/SE2010/050823**Box No. II Observations where certain claims were found unsearchable (Continuation of item 2 of first sheet)**

This international search report has not been established in respect of certain claims under Article 17(2)(a) for the following reasons:

1. ☒ Claims Nos.: 113-150
because they relate to subject matter not required to be searched by this Authority, namely:
Claims 113-150 relate to a method for treatment of the human or animal body by surgery or by therapy, as well as diagnostic methods, see PCT rule 39.1(iv). Nevertheless, a search has been made for these claims. The search has been directed to the technical content of the claims.
2. ☐ Claims Nos.:
because they relate to parts of the international application that do not comply with the prescribed requirements to such an extent that no meaningful international search can be carried out, specifically:
3. ☐ Claims Nos.:
because they are dependent claims and are not drafted in accordance with the second and third sentences of Rule 6.4(a).

Box No. III Observations where unity of invention is lacking (Continuation of item 3 of first sheet)

This International Searching Authority found multiple inventions in this international application, as follows:

1. ☐ As all required additional search fees were timely paid by the applicant, this international search report covers all searchable claims.
2. ☐ As all searchable claims could be searched without effort justifying additional fees, this Authority did not invite payment of additional fees.
3. ☐ As only some of the required additional search fees were timely paid by the applicant, this international search report covers only those claims for which fees were paid, specifically claims Nos.:
4. ☐ No required additional search fees were timely paid by the applicant. Consequently, this international search report is restricted to the invention first mentioned in the claims; it is covered by claims Nos.:

Remark on Protest

- ☐ The additional search fees were accompanied by the applicant's protest and, where applicable, the payment of a protest fee.
- ☐ The additional search fees were accompanied by the applicant's protest but the applicable protest fee was not paid within the time limit specified in the invitation.
- ☐ No protest accompanied the payment of additional search fees.

International patent classification (IPC)**A61F 2/46** (2006.01)**A61B 17/16** (2006.01)**Download your patent documents at www.prv.se**

The cited patent documents can be downloaded:

- From "Cited documents" found under our online services at www.prv.se (English version)
- From "Anförda dokument" found under "e-tjänster" at www.prv.se (Swedish version)

Use the application number as username. The password is **SQEIDOVJNM**.

Paper copies can be ordered at a cost of 50 SEK per copy from PRV InterPat (telephone number 08-782 28 85).

Cited literature, if any, will be enclosed in paper form.

INTERNATIONAL SEARCH REPORT
Information on patent family members

International application No.
PCT/SE2010/050823

US	20030130741	A1	10/07/2003	NONE		
US	20080221392	A1	11/09/2008	NONE		
US	5269785	A	14/12/1993	US	5403317 A	04/04/1995
WO	2008031245	A2	20/03/2008	NONE		
US	20040236424	A1	25/11/2004	NONE		
US	20060190078	A1	24/08/2006	NONE		
US	5120312	A	09/06/1992	WO	9116098 A	31/10/1991
DE	3343863	A1	13/06/1985	NONE		
WO	9501139	A1	12/01/1995	DE	69322169 D,T	24/06/1999
				EP	0663810 A,B	18/11/1998
US	6375684	B1	23/04/2002	AT	225149 T	15/10/2002
				AU	741944 B	13/12/2001
				AU	6006398 A	26/08/1998
				CA	2280119 A	13/08/1998
				DE	69808438 D,T	12/06/2003
				EP	0966240 A,B	02/10/2002
				JP	2001511038 T	07/08/2001
				NL	1005234 C	11/08/1998
				WO	9834567 A	13/08/1998
US	20040247641	A1	09/12/2004	NONE		
US	20090043344	A1	12/02/2009	NONE		

专利名称(译)	髌关节器械和方法		
公开(公告)号	EP2451408A1	公开(公告)日	2012-05-16
申请号	EP2010797411	申请日	2010-07-12
[标]申请(专利权)人(译)	米卢克斯控股股份有限公司		
申请(专利权)人(译)	MILUX HOLDING SA		
当前申请(专利权)人(译)	MILUX HOLDING SA		
[标]发明人	FORSELL PETER		
发明人	FORSELL, PETER		
IPC分类号	A61F2/46 A61B17/16 A61F2/36		
CPC分类号	A61B1/317 A61B6/12 A61B17/1615 A61B17/1631 A61B17/1666 A61B17/1668 A61B17/686 A61B17/8805 A61B17/8875 A61F2/3603 A61F2/4607 A61F2002/30469 A61F2002/30471 A61F2002/30495 A61F2002/305 A61F2002/30594 A61F2002/30616 A61F2002/30818 A61F2220/0025 A61B17/3423 A61B17/3474 A61B2018/202 A61B2018/206 A61F2/4609 A61F2002/30494 A61F2002/4622 A61F2002/4628		
代理机构(译)	豪格伦德 , LARS		
优先权	0900981 2009-07-10 SE 0900957 2009-07-10 SE 0900959 2009-07-10 SE 0900960 2009-07-10 SE 0900962 2009-07-10 SE 0900963 2009-07-10 SE 0900965 2009-07-10 SE 0900966 2009-07-10 SE 0900968 2009-07-10 SE 0900969 2009-07-10 SE 0900970 2009-07-10 SE 0900972 2009-07-10 SE 0900973 2009-07-10 SE 0900974 2009-07-10 SE 0900976 2009-07-10 SE 0900978 2009-07-10 SE 0900958 2009-07-10 SE 61/229738 2009-07-30 US 61/229739 2009-07-30 US 61/229743 2009-07-30 US 61/229745 2009-07-30 US 61/229746 2009-07-30 US 61/229747 2009-07-30 US 61/229748 2009-07-30 US 61/229751 2009-07-30 US 61/229752 2009-07-30 US 61/229755 2009-07-30 US 61/229761 2009-07-30 US 61/229767 2009-07-30 US		

61/229778 2009-07-30 US
61/229786 2009-07-30 US
61/229789 2009-07-30 US
61/229796 2009-07-30 US
61/229735 2009-07-30 US
13/382840 2012-01-06 US

其他公开文献

EP2451408A4

外部链接

[Espacenet](#)

摘要(译)

提供了一种用于在人类患者中操作髋关节骨关节炎的手术器械。髋关节包括作为骨盆骨的一部分的髋臼和作为股骨的近端部分的股骨头股骨。手术器械适于帮助从所述人类患者的骨盆骨的腹侧操作髋关节骨关节炎。