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(54) **ULTRASONIC DIAGNOSTIC APPARATUS**

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(57) **ABSTRACT**

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(Continued)

An ultrasonic diagnostic apparatus disclosed herein comprises an ultrasonic probe which generates an ultrasonic beam, a volume data set collecting unit which collects a plurality of volume data sets corresponding to a plurality of three-dimensional scan ranges via the ultrasonic probe, the plurality of three-dimensional scan ranges partly overlapping one another, a region of interest setting unit which sets, in accordance with a user instruction, a region of interest on a first tomogram generated from particular one of the plurality of volume data sets, a tomogram generating unit which generates the first tomogram from the particular volume data set and also generates a second tomogram associated with a section including the region of interest from another volume data set corresponding to the three-dimensional scan range including the region of interest, and a display unit which displays the first tomogram and the second tomogram.

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(2013.01)

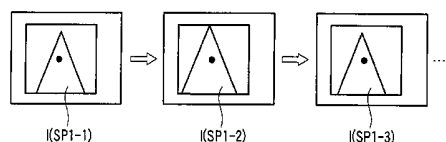
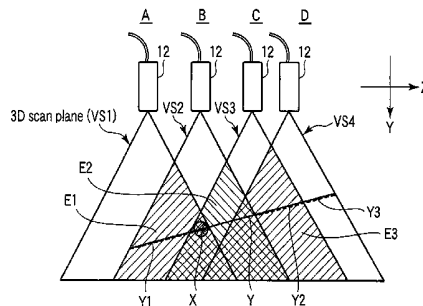
(58) **Field of Classification Search**

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19 Claims, 6 Drawing Sheets



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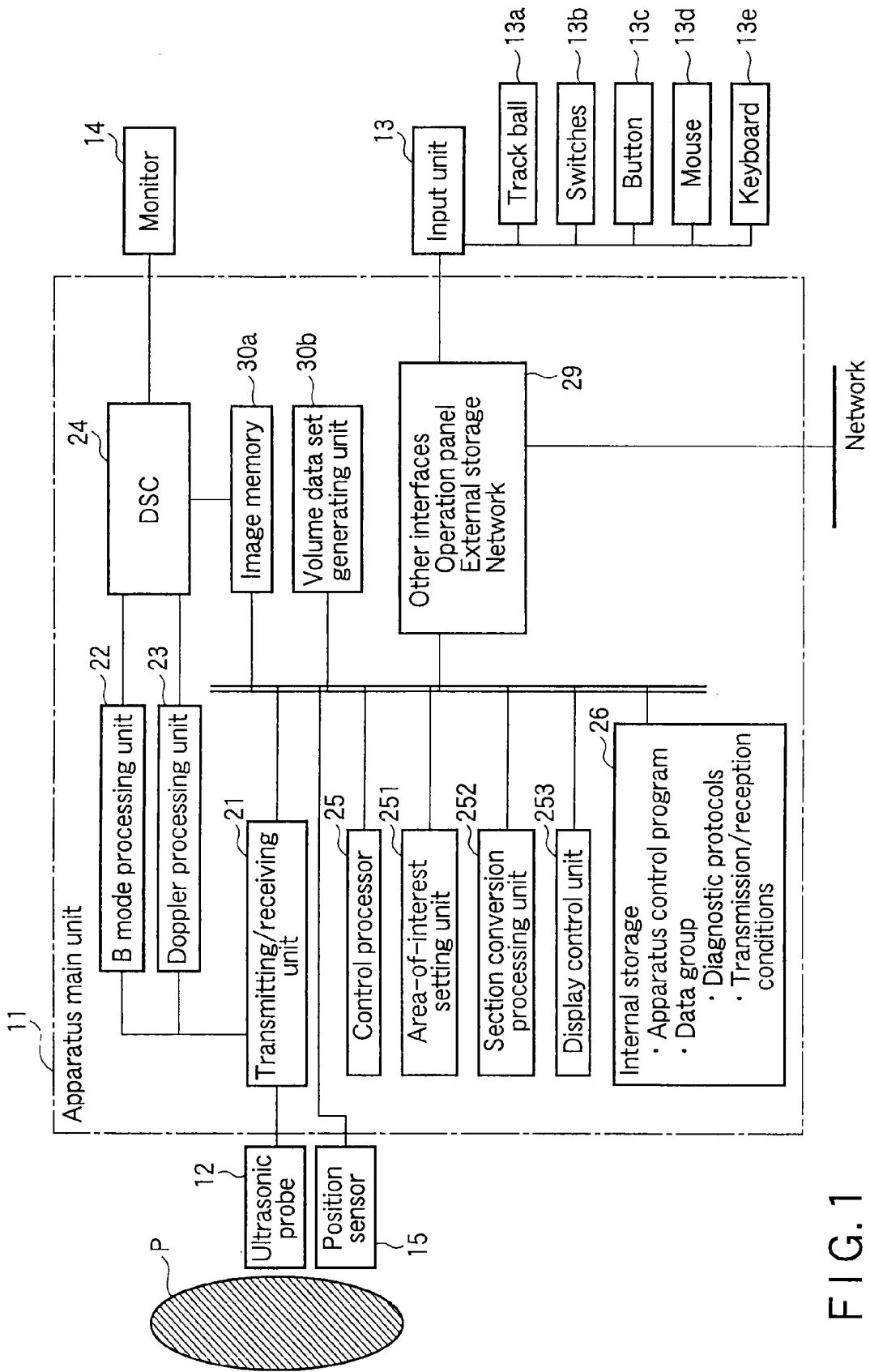


FIG. 1

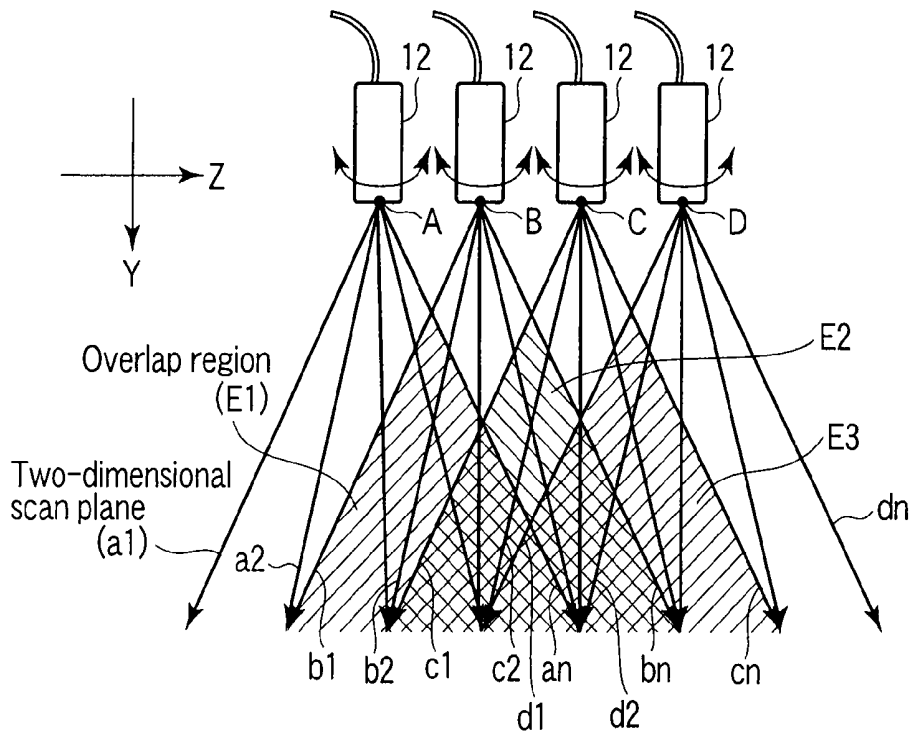


FIG. 2

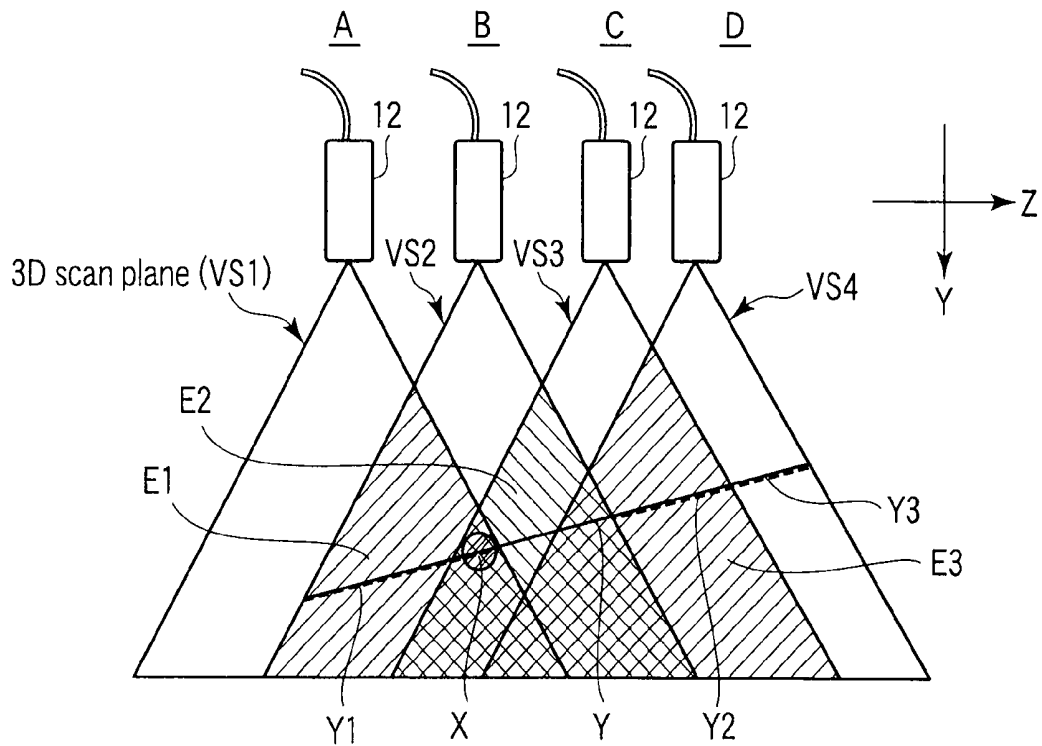


FIG. 3

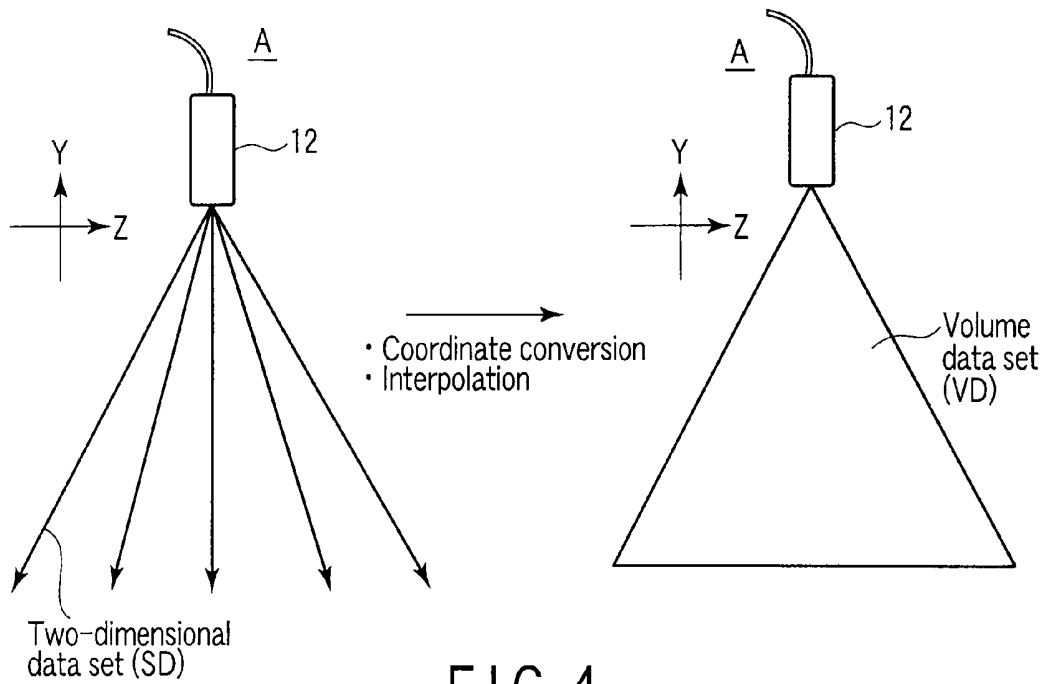


FIG. 4

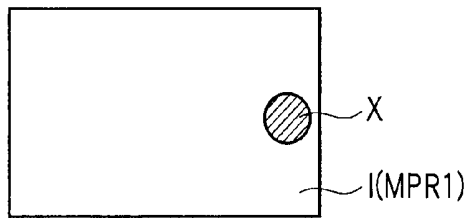


FIG. 5A

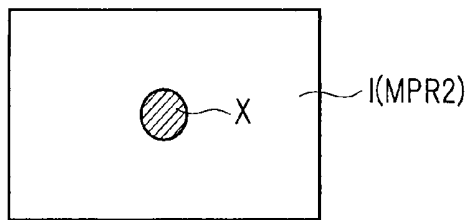


FIG. 5B

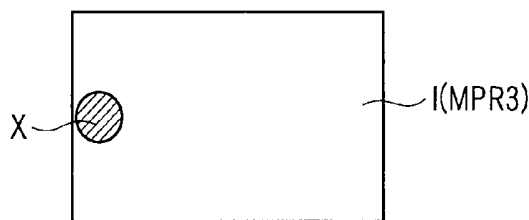


FIG. 5C

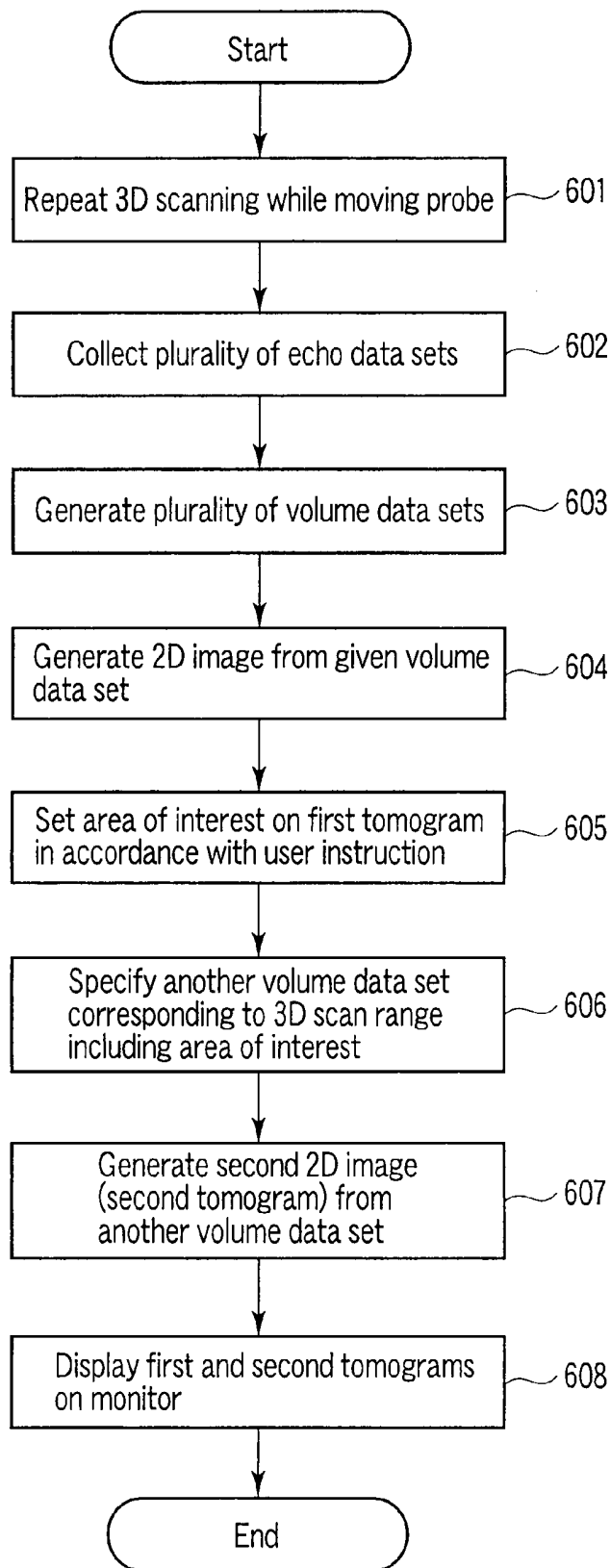
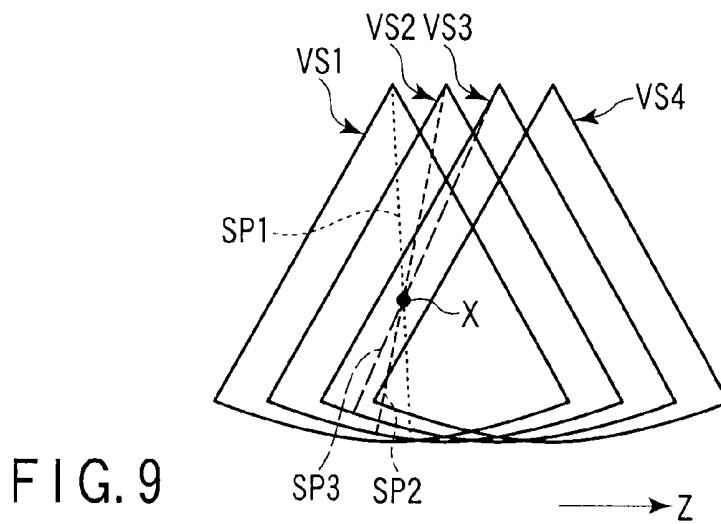
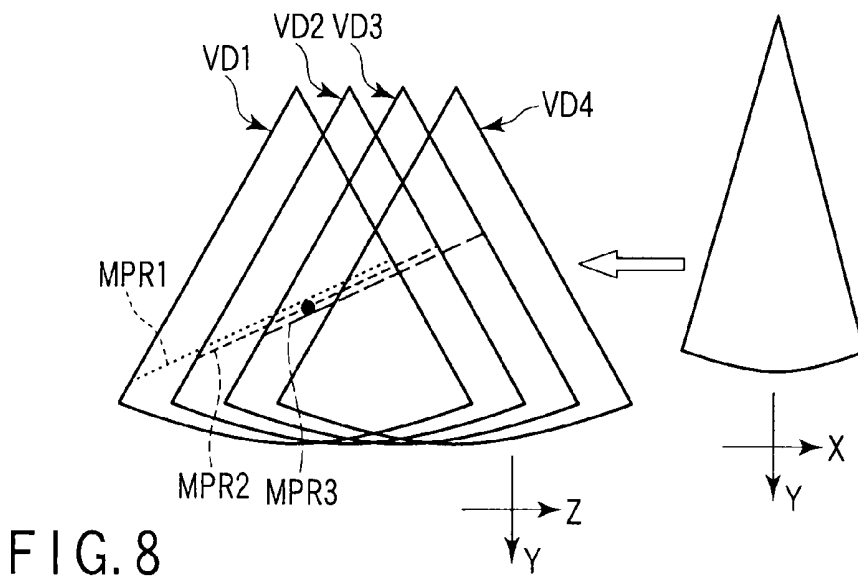
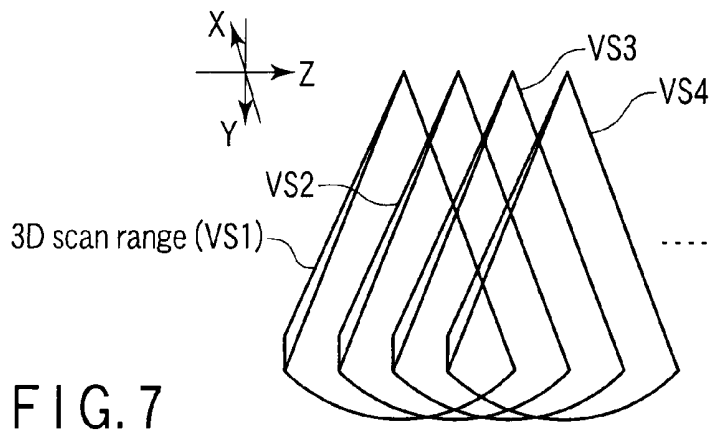


FIG. 6



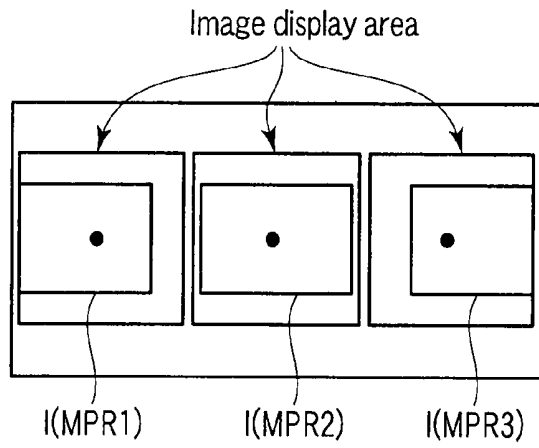


FIG. 10

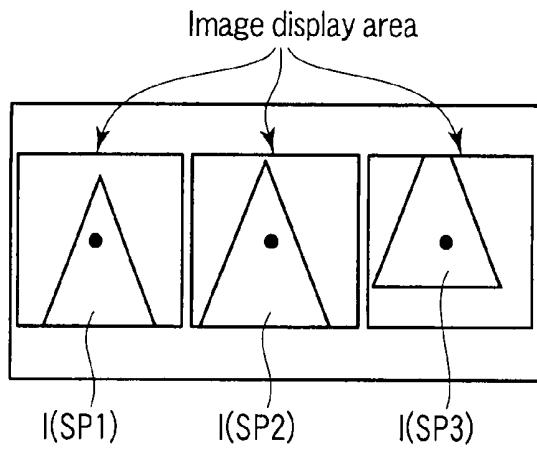


FIG. 11

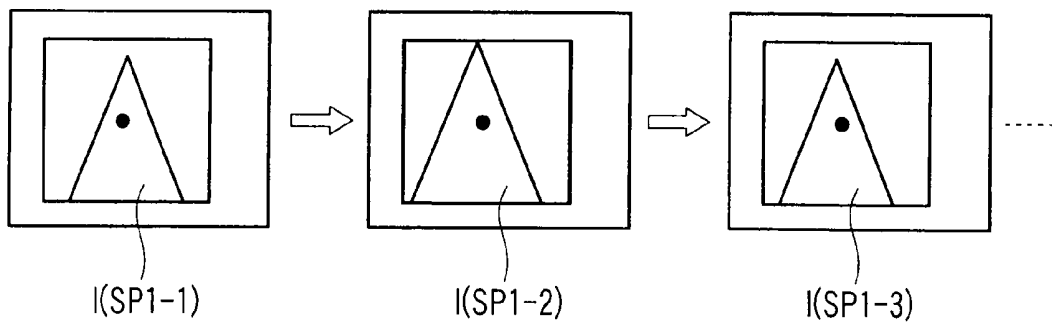


FIG. 12

ULTRASONIC DIAGNOSTIC APPARATUS

CROSS-REFERENCE TO RELATED
APPLICATIONS

This application is based upon and claims the benefit of priority from prior Japanese Patent Application No. 2008-151812, filed Jun. 10, 2008, the entire contents of which are incorporated herein by reference.

BACKGROUND OF THE INVENTION

1. Field of the Invention

The present invention relates to an ultrasonic diagnostic apparatus capable of three-dimensional (3D) scanning.

2. Description of the Related Art

An ultrasonic diagnostic apparatus enables real-time acquisition of the pulsation of a heart or the motion of a fetus by simple operation of applying an ultrasonic probe to the surface of a body. Moreover, the ultrasonic diagnostic apparatus is free of exposure to radiation unlike X-rays and is thus highly secure and enables repeated examinations, which advantageously allows the use in, for example, obstetrical services or home care services. Further, the ultrasonic diagnostic apparatus is easy to use in that it is smaller in system scale than other diagnostic apparatuses such as X-ray, CT and MRI diagnostic apparatuses and can be easily moved to a bedside for examinations.

On the other hand, in a conventional examination using the ultrasonic diagnostic apparatus, an engineer who uses the ultrasonic probe for scanning changes the way of applying the probe to a region of interest to search for an image that makes the region of interest visible. The image thus obtained is preserved for a doctor to make a diagnosis.

In this case, in order to enable a field of view to be enlarged during the diagnosis by the doctor, a plurality of ultrasonic vibration units are provided to pick up two-dimensional images, and these two-dimensional images are synthesized and then displayed, as disclosed in Jpn. Pat. Appln. KOKAI Publication No. 55-103839.

However, in such a method, the doctor interprets the image within the range of the two-dimensional images of a part which has been scanned by the engineer with suspicion. Therefore, the problem is that when the engineer has overlooked, for example, a tumor during the scanning with the ultrasonic probe, the doctor is unable to detect the tumor.

According to a method that tends to be used in the United States nowadays, the engineer only scans a predetermined region with the ultrasonic probe and preserves images of the region, and the doctor interprets the data and makes a diagnosis. That is to say, the engineer only performs scanning, and the doctor interprets the scanning result and makes a diagnosis. Thus, the engineer is in charge of scanning, and the doctor is in charge of interpretation, so that the two tasks are separated.

On the other hand, there has recently been developed and commercialized an apparatus which performs a so-called three-dimensional scan by applying an ultrasonic beam to a target part so that the target part can be volumetrically observed over time.

The advantage of such a three-dimensional scan capable of collecting volume data sets is that an objective diagnosis can be made. Specifically, as described above, it has heretofore been the case that the doctor makes a diagnosis only using the image of the part which has been scanned by the engineer with suspicion, so that the doctor is unable to detect any new problem in the parts overlooked by the engineer.

However, the volume data sets acquired by the engineer by the three-dimensional scanning enables the doctor to reconstruct a given sectional image for observation, such that a diagnosis can be said to be more objective.

Accordingly, it is easily presumed that when the role of the engineer who performs scanning is clearly separated from the role of the doctor who makes a diagnosis as described above, the conventional interpretation with the two-dimensional images may be replaced the interpretation with the volume data sets.

On the other hand, in such a three-dimensional scan, the volume data sets are collected in real time. As a result, the volume of data handled is so great that considerable labor and time are required to reconstruct a given sectional image from the acquired volume data sets to detect a problematic part. Moreover, when the engineer is only allowed to simply perform a scan of the predetermined region as described above, images that can be acquired are limited by the way that the engineer applies the probe at the previous stage. Therefore, even if the doctor finds a part suspected of being affected by a disease as a result of interpreting the images, it is not possible to change the way of applying the probe to acquire an image that clearly shows the characteristics of this part. It is thus difficult to make a high-quality and accurate ultrasonic diagnosis.

BRIEF SUMMARY OF THE INVENTION

It is an object of the present invention to provide an ultrasonic diagnostic apparatus which minimizes reexaminations attributed to unclarity of an image including a part of interest.

According to one aspect of the present invention, there is provided an ultrasonic diagnostic apparatus comprising an ultrasonic probe **12** which generates an ultrasonic beam; a volume data set collecting unit **30b** which collects a plurality of volume data sets corresponding to a plurality of three-dimensional scan ranges via the ultrasonic probe, the plurality of three-dimensional scan ranges partly overlapping one another; a region of interest setting unit **251** which sets, in accordance with a user instruction, a region of interest on a first tomogram generated from particular one of the plurality of volume data sets; a tomogram generating unit **252** which generates the first tomogram from the particular volume data set and also generates a second tomogram associated with a section including the region of interest from another volume data set corresponding to the three-dimensional scan range including the region of interest; and a display unit **253** which displays the first tomogram and the second tomogram.

Additional objects and advantages of the invention will be set forth in the description which follows, and in part will be obvious from the description, or may be learned by practice of the invention. The objects and advantages of the invention may be realized and obtained by means of the instrumentalities and combinations particularly pointed out hereinafter.

BRIEF DESCRIPTION OF THE SEVERAL
VIEWS OF THE DRAWING

The accompanying drawings, which are incorporated in and constitute a part of the specification, illustrate embodiments of the invention, and together with the general description given above and the detailed description of the embodiments given below, serve to explain the principles of the invention.

FIG. 1 is a schematic diagram showing the configuration of an ultrasonic diagnostic apparatus according to an embodiment of the present invention;

FIG. 2 is a diagram showing an example of data acquired by moving and operating an ultrasonic probe in the present embodiment;

FIG. 3 is a diagram showing an example of the generation of time-series volume data sets in the present embodiment;

FIG. 4 is a diagram explaining a voxel conversion for generating the time-series volume data set in the present embodiment;

FIG. 5A is a diagram showing an example of display on a monitor in the present embodiment;

FIG. 5B is a diagram showing an example of display on the monitor in the present embodiment;

FIG. 5C is a diagram showing an example of display on the monitor in the present embodiment;

FIG. 6 is a flowchart explaining operation in the present embodiment;

FIG. 7 is a diagram showing a plurality of three-dimensional scan ranges for repeated three-dimensional scanning in the present embodiment;

FIG. 8 is a diagram showing sections determined on other volumes with respect to a region of interest and a section that are designated on a particular volume in the present embodiment;

FIG. 9 is a diagram showing sections determined on other volumes with respect to a region of interest and a section that are designated on a particular volume in the present embodiment;

FIG. 10 is a diagram showing an example of image display corresponding to FIG. 8;

FIG. 11 is a diagram showing an example of image display corresponding to FIG. 9; and

FIG. 12 is a diagram showing an example of image display according to a modification of the present embodiment.

DETAILED DESCRIPTION OF THE INVENTION

An embodiment of the present invention will hereinafter be described with reference to the drawings.

FIG. 1 shows the configuration of an ultrasonic diagnostic apparatus according to the present embodiment. An apparatus main unit 11 is connected to an ultrasonic probe 12, an input unit 13 and a monitor 14. The ultrasonic probe 12 has a plurality of piezoelectric vibrators. The plurality of piezoelectric vibrators are two-dimensionally arranged to correspond to electronic three-dimensional (3D) scanning. The plurality of piezoelectric vibrators may otherwise be one-dimensionally arranged to correspond to mechanical 3D scanning. The 3D scanning is a single operation for collecting all of a plurality of echo signals in a 3D scan range, and is successively repeated in the 3D scan range at given periods. The 3D scanning includes a plurality of 2D scans. The two-dimensional scanning is a single operation for collecting all of a plurality of echo signals in a 2D scan plane by an ultrasonic beam, and is successively repeated at given periods. The 2D scanning is repeated while the angle of the two-dimensional scan plane is being changed, such that the 3D scanning is completed. In addition, image data generated from the echo signals collected by the 2D scanning is referred to as a 2D data set (SD), while image data generated from the echo signals collected by the 3D scanning is distinctively referred to as a volume data set (VD). More-

over, a position sensor 15 is provided to measure the position of the 3D scanning from the position of the ultrasonic probe 12.

The ultrasonic probe 12 is supplied with a drive signal from an ultrasonic wave transmitting/receiving unit 21. Thus, an ultrasonic beam is generated from the ultrasonic probe 12. Ultrasonic waves are successively reflected by a discontinuous plane of acoustic impedance in a subject P. The ultrasonic probe 12 converts the wave reflected from the subject P into an electric signal, and outputs the electric signal as an echo signal. The amplitude of the echo signal is reflected in the difference of the acoustic impedance. The frequency of the echo signal is shifted from a transmission frequency by a velocity component of the ultrasonic beam in a moving object such as blood or a heart wall.

The input unit 13 has input means such as a track ball 13a, various switches 13b, a button 13c, a mouse 13d, and a keyboard 13e. A user instruction, for example, to select a volume data set and to set a region of interest to a given position on the sectional image generated from the select volume data set is input to the apparatus main unit 11 via the input unit 13. A display control unit 253 generates display screen data including images, etc. The generated display screen data is displayed on the monitor 14 via a digital scan converter 24.

The ultrasonic wave transmitting/receiving unit 21 has, for example, an unshown rate pulse generating circuit, a delay circuit and a pulser circuit. The rate pulse generating circuit generates a rate pulse for forming transmission ultrasonic waves at a predetermined rate frequency fr Hz (period: $1/fr$ second). The delay circuit provides the rate pulse for each channel with a delay time necessary to converge the ultrasonic waves into a beam shape and determine transmission directional characteristics. This delay information is changed, so that the direction of transmission from the surface of a probe vibrator can be adjusted to any direction. The pulser circuit generates a drive pulse for each channel synchronously with the rate pulse. The ultrasonic wave transmitting/receiving unit 21 has a function capable of instantaneously changing, for example, the delay information, the transmission frequency and a transmission drive voltage under the instruction of a control processor 25. In particular, the transmission drive voltage is changed by a mechanism which electrically switches a linear amplifier type emitter circuit capable of instantaneously changing its value or a plurality of power units. The ultrasonic wave transmitting/receiving unit 21 also has an unshown amplifier circuit, an A/D converter, an adder, etc. The amplifier circuit amplifies, channel by channel, the echo signals taken in via the ultrasonic probe 12. The A/D converter provides the amplified echo signal with a delay time necessary to determine reception directional characteristics. The adder adds the delayed echo signal. Due to this addition, a reflection component from a direction corresponding to the reception directional characteristics of the echo signal is emphasized, and a synthetic beam for ultrasonic wave transmission/reception is formed by the reception directional characteristics and the transmission directional characteristics.

A B mode processing unit 22 generates B mode image data in which signal intensities are expressed by the strength of luminance, from the echo signal coming from the ultrasonic wave transmitting/receiving unit 21 by logarithmic amplifying processing or envelope detecting processing. The B mode image data is transmitted to the image generating circuit 24, and displayed on the monitor 14 as a B mode image which expresses the strength of a reflected wave by luminance.

A Doppler processing unit **23** performs a frequency analysis of velocity information from the echo signal received from the ultrasonic wave transmitting/receiving unit **21**, extracts a Doppler component of the moving object such as blood or a heart attributed to a Doppler effect, and obtains its movement information on, for example, an average velocity, dispersion and power with regard to multiple points. Obtained blood flow information is sent to the digital scan converter **24**, and displayed in color on the monitor **14** as an average velocity image, a dispersion image, a power image or a combination of these images.

The digital scan converter **24** converts a scan line signal sequence of ultrasonic scanning into a scan line signal sequence in a general video format typified in, for example, televisions, and generates an ultrasonic diagnostic image as a display image.

An internal storage **26** stores a control program for performing a later-described scan sequence, image generation and display processing, diagnostic information (e.g., patient IDs, doctor's observations), diagnostic protocols, transmission/reception conditions and other data groups. In particular, the internal storage **26** saves the control program for performing the scan sequence for ultrasonic wave transmission/reception. The internal storage **26** is also used to save images in a later-described image memory **30a** if necessary. Data in the internal storage **26** can be transferred to external peripheral equipment via an interface circuit **29**.

The interface unit **29** is an interface associated with the input unit **13**, a network and a new external storage (not shown). Data on an ultrasonic image and the result of an analysis obtained by this apparatus can be transferred by the interface unit **29** to other devices via the network.

The image memory **30a** stores a volume data set generated by coordinate conversion and interpolation processing from the 2D data set which has been generated in the B mode processing unit **22** or the Doppler processing unit **23** and from a plurality of 2D data sets in a volume data set generating unit **30b**. In addition, the 2D data set and the volume data set are typically, but not exclusively, B mode images representing the morphology of the subject, and may be Doppler images representing moving velocity spatial distribution of the moving object such as blood or a heart.

The control processor **25** has a function as an information processor (calculator), and performs overall control of the apparatus main unit **11** in accordance with the control program.

A region of interest setting unit **251** sets, in accordance with a user instruction, a region of interest on a tomogram (first tomogram) which has been generated by a section conversion processing unit **252** from a particular volume data set selected from a plurality of volume data sets in accordance with a user instruction. The section conversion processing unit **252** generates the first tomogram from the particular volume data set, and also specifies at least another volume data set corresponding to a three-dimensional scan range including the region of interest, and generates a tomogram (second tomogram) associated with a section including the region of interest from the another volume data set.

The display control unit **253** constructs a display screen including the tomogram generated in the section conversion processing unit **252**.

Now, the operation in such a configuration of the embodiment is described in accordance with a flowchart shown in FIG. 6.

The ultrasonic wave transmitting/receiving unit **21** repeats 3D scanning via the ultrasonic probe **12** (step **601**).

As shown in FIGS. 2, 3 and 7, an operator moves the ultrasonic probe **12** little by little on the surface of the body of the subject during the repetition of the 3D scanning. The direction of the movement is on a Z-axis. A plurality of echo data sets at different positions A, B, C, D of the ultrasonic probe **12** are collected by the movement (step **602**), and a volume data set is generated by the volume data set generating unit **30b** as shown in FIG. 4 (step **603**).

The position of the 3D scanning is measured by the position sensor **15** for measuring the position of the ultrasonic probe **12**. Otherwise, it is possible to use, instead of the position sensor **15**, for example, a (auto-)correlation function representing the correlation between the volume data sets, or mutual information for obtaining a difference in distance between data from the position information in the volume data sets.

A plurality of three-dimensional scan ranges VS1, VS2, VS3, VS4 corresponding to the plurality of volume data sets, respectively, partly overlap one another. Here, the three-dimensional scan ranges VS1, VS2 overlap each other in an overlap region E1, the three-dimensional scan ranges VS2, VS3 overlap each other in an overlap region E2, and the three-dimensional scan ranges VS3, VS4 overlap each other in an overlap region E3. Moreover, the three-dimensional scan range VS1 also overlaps the three-dimensional scan ranges VS3, VS4 in addition to the three-dimensional scan range VS2. The three-dimensional scan range VS2 also overlaps the three-dimensional scan range VS4 in addition to the three-dimensional scan ranges VS1, VS3.

Then, an interpreter selects particular one of volume data sets VD1 to VD4, for example, the volume data set VD2 by the input operation of the input unit **13**. A tomogram (first tomogram) associated with a predetermined initial section is generated from the selected volume data set VD2 by the section conversion processing unit **252**, and displayed on the monitor **14** (step **604**). The initial section is a two-dimensional scan plane located, for example, in the center of the three-dimensional scan range VS2. The interpreter shifts the initial section a given distance in a given direction and rotates the section a given angle on a given axis (XYZ) as needed, thereby finally determining a section suitable for a diagnosis. The determined section is indicated by Y in FIG. 3 and indicated by MPR2 in FIG. 8. The tomogram (first tomogram) associated with the determined section is generated from the volume data set VD2 by the section conversion processing unit **252**, and displayed on the monitor **14**.

The region of interest setting unit **251** sets a region of interest at a designated position on the first tomogram, for example, on a tumor X as shown in FIG. 5B in accordance with the operation of the input unit **13** by the interpreter based on a user instruction (step **605**).

The section conversion processing unit **252** judges whether the region of interest set on the first tomogram is included in the three-dimensional scan ranges VS1, VS3, VS4 of the other volume data sets VD1, VD3, VD4 (step **606**). The section conversion processing unit **252** generates tomograms (second tomograms) from the volume data sets VD1, VD3 corresponding to the three-dimensional scan ranges including the region of interest, here, the three-dimensional scan ranges VS1, VS3. As shown in FIG. 8, second tomogram sections MPR1, MPR3 are set to sections which are parallel with and partly overlap a determined section MPR2. The tomograms (second tomograms) associated with the set sections MPR1, MPR3 are respectively

generated from the volume data sets VD1, VD3 by the section conversion processing unit 252, and displayed on the monitor 14 (steps 607, 608).

The region of interest is observed on the tomogram (first tomogram) derived from one three-dimensional scanning, while the region of interest can also be observed on the tomogram (second tomogram) derived from the other three-dimensional scanning. Even when the quality of the first tomogram is relatively low and is not suitable for interpretation, this can be compensated for by the second tomogram. Thus, an improvement in the accuracy of interpretation can be expected. Moreover, chances of rescanning can also be reduced.

Furthermore, in the 3D scanning, the volume data sets are collected, and the volume of data handled is therefore great. However, by only setting a region of interest for the volume data sets, a tomogram that provides a multidirectional view of the region of interest can be easily obtained, so that an ultrasonic diagnostic can be efficiently carried out.

As described above, the second tomogram sections MPR1, MPR3 are set to sections which are parallel with and partly overlap the initial section MPR2. However, this is not a limitation. A tomogram (original tomogram) of the two-dimensional scan plane has higher spatial resolution and higher quality than the tomogram generated from the volume data set by the section conversion processing. When a particular mode is selected, the first and second tomograms can be limited to the tomograms of the two-dimensional scan plane.

As shown in FIG. 9, a region of interest X is designated on the tomogram (first tomogram) of a two-dimensional scan plane SP2 within the three-dimensional scan range VS2. The section conversion processing unit 252 judges whether the region of interest X set on the first tomogram is included in the three-dimensional scan ranges VS1, VS3, VS4 of the other volume data sets VD1, VD3, VD4. The section conversion processing unit 252 sets two-dimensional scan planes SP1, SP3 which are included in the three-dimensional scan ranges VS1, VS3 and which pass the region of interest X. Tomograms (second tomograms) I(SP1), I(SP3) collected in the set two-dimensional scan planes SP1, SP3 are read from the image memory 30a.

Next, the display of the tomograms is described. Tomograms I(MPR1), I(MPR2), I(MPR3) corresponding to the volume data sets VD1, VD2, VD3 are displayed on the monitor 14 (FIG. 5A, FIG. 5B, FIG. 5C). The tomogram I(MPR1) is acquired by scanning with the ultrasonic probe 12 at the position of a point A, and the tumor X located in the overlap region E1 is displayed on the right end of the tomogram I(MPR1). Moreover, the tomogram I(MPR3) is acquired by scanning with the ultrasonic probe 12 at the position of a point C, and the tumor X located in the overlap region E2 is displayed on the left end of the tomogram I(MPR3).

Consequently, the interpreter can simultaneously observe the plurality of tomograms I(MPR1), I(MPR2), I(MPR3) including the same region of interest on the monitor 14 as a result of a plurality of three-dimensional scans.

As shown in FIG. 10, the display control unit 253 shifts the display positions of the plurality of tomograms I(MPR1), I(MPR2), I(MPR3) including the same region of interest so that the image of the region of interest X may be located in the center of each image display area on the monitor 14. As shown in FIG. 11, in the case where the tomograms I(SP1), I(SP2), I(SP3) collected in the two-dimensional scan planes SP1, SP2, SP3, the display control unit 253 also shifts the display positions of the tomograms I(SP1), I(SP2), I(SP3) so

that the image of the region of interest X may be located in the center of each image display area on the monitor 14.

As the region of interest X is always located in the center of each display area, the interpreter does not have to search for the region of interest X, thereby allowing the interpretation work to be efficient.

Although the tomograms of all the volume data sets acquired for the points A to D are used in the example described above, the volume data sets can be thinned out and used. For example, a volume data set acquired every moving distance is used, and the positions of the tumor in the tomograms of these volume data sets can be displayed in association with one other.

(Modification)

In the embodiment described above, a strait line Y is set as a region of interest in a two-dimensional tomogram of a volume data set, and a tomogram sliced off along the strait line Y is displayed on the monitor 14. However, for example, a cubic region of interest such as a spherical region of interest including a part of interest may be set in a three-dimensional (3D) image of the volume data set, and a corresponding 3D image may be generated from each volume data set on the basis of the region of interest and displayed on the monitor 14.

The idea of the present embodiment generates the following application. When three-dimensional scanning is repeated at the same position, a plurality of volume data sets associated with the same three-dimensional scan range are generated. A tomogram associated with a given section including a region of interest is generated from a particular volume data set and displayed. A plurality of tomograms at different scanning times associated with the same section are generated. As shown in FIG. 12, tomograms I(SP1-1), I(SP1-2), I(SP1-3) are shifted so that the image of the region of interest in each tomogram may be located in the center of each image display area on the monitor 14.

Furthermore, the present invention is not limited to the embodiment described above, and various modifications can be made without departing from the spirit thereof at the stage of carrying out the invention. For example, a plurality of tomograms A2 to D2 are displayed on the monitor 14 in the embodiment described above. Otherwise, one of the tomograms alone may be displayed on the monitor 14 so that the display is sequentially switched to the other tomograms, for example, by operating the track ball 13a of the input unit 13. Moreover, in the embodiment described above, a region of interest is set so that a tomogram including the region of interest is generated from the volume data sets and displayed. However, a tomogram including the region of interest may be selected from time-series volume data sets acquired at the points A to D before a voxel conversion and displayed. Thus, since the time-series volume data sets before the voxel conversion have greater volumes of data than the volume data sets after the voxel conversion, such time-series volume data sets can be used to generate an image having high resolution.

Additional advantages and modifications will readily occur to those skilled in the art. Therefore, the invention in its broader aspects is not limited to the specific details and representative embodiments shown and described herein. Accordingly, various modifications may be made without departing from the spirit or scope of the general inventive concept as defined by the appended claims and their equivalents.

What is claimed is:

1. An ultrasonic diagnostic apparatus, comprising:
an ultrasonic probe configured to generate an ultrasonic beam;
a volume data set collector configured to collect a plurality of volume data sets corresponding to a plurality of three-dimensional scan ranges via the ultrasonic probe, the plurality of three-dimensional scan ranges partly overlapping one another;
a region of interest setting device configured to set, in accordance with a user instruction, a region of interest on a first tomogram generated from a particular one of the plurality of volume data sets, the region of interest being set within a scan range of the plurality of three-dimensional scan ranges that corresponds to the particular one of the plurality of volume data sets;
a tomogram generator configured to generate the first tomogram from the particular one of the volume data sets and also generate a second tomogram associated with a section including the region of interest from another volume data set of the plurality of volume data sets that has a corresponding three-dimensional scan range that includes the region of interest, wherein the tomogram generator specifies a position of the second tomogram in the another volume data set; and
a display configured to display the first tomogram and the second tomogram.
2. The ultrasonic diagnostic apparatus according to claim 1, wherein the tomogram generator is configured to generate the first and second tomograms so that a section of the second tomogram partly overlaps a section of the first tomogram.
3. The ultrasonic diagnostic apparatus according to claim 1, wherein the tomogram generator is configured to generate the first and second tomograms so that sections of the first and second tomograms are two-dimensional scan planes formed by the ultrasonic beam.
4. The ultrasonic diagnostic apparatus according to claim 1, wherein the tomogram generator is configured to generate the first and second tomograms so that a section of the second tomogram intersects with a section of the first tomogram.
5. The ultrasonic diagnostic apparatus according to claim 1, further comprising a display controller configured to display the first tomogram in a first display region of the display and to display the second tomogram in a second display region of the display, wherein a position of the region of interest displayed within the second display region is the same as a position of the region of interest displayed within the first display region.
6. The ultrasonic diagnostic apparatus according to claim 1, further comprising an operation interface operated by a user to designate a location of the region of interest on the first tomogram.
7. The ultrasonic diagnostic apparatus according to claim 1, further comprising a display controller configured to display the first tomogram and the second tomogram simultaneously or in a switched manner.
8. The ultrasonic diagnostic apparatus according to claim 1, further comprising a display controller configured to display the first tomogram and the second tomogram in an overlapping manner so that the region of interests in the first and second tomograms are in alignment.
9. The ultrasonic diagnostic apparatus according to claim 1, further comprising a synthesizer configured to generate

one synthetic image including an average luminance or maximum luminance from the first tomogram and the second tomogram.

10. The ultrasonic diagnostic apparatus according to claim 1, wherein the tomogram generator is configured to designate the another volume data set corresponding to the three-dimensional scan range that includes the region of interest.

11. An ultrasonic diagnostic apparatus, comprising:
an ultrasonic probe which generates an ultrasonic beam;
a volume data set collector configured to scan a three-dimensional scan range to collect a plurality of volume data sets via the ultrasonic probe;
a region of interest setting device configured to set, in accordance with a user instruction, a region of interest on a first tomogram generated from a particular one of the plurality of volume data sets, the region of interest being set within the three-dimensional scan range;
a tomogram generator configured to generate the first tomogram from the particular one of the volume data sets and also generate a second tomogram associated with a section including the region of interest from another volume data set of the plurality of volume data sets that includes the region of interest, wherein the tomogram generator specifies a position of the second tomogram in the another volume data set; and
a display configured to display the first tomogram and the second tomogram.

12. The ultrasonic diagnostic apparatus according to claim 11, wherein the tomogram generator is configured to generate the first and second tomograms so that a section of the second tomogram is the same as a section of the first tomogram.

13. The ultrasonic diagnostic apparatus according to claim 11, wherein the tomogram generator is configured to generate the first and second tomograms so that a section of the second tomogram is a two-dimensional scan plane formed by the ultrasonic beam.

14. The ultrasonic diagnostic apparatus according to claim 11, wherein the tomogram generator is configured to generate the first and second tomograms so that a section of the second tomogram intersects with a section of the first tomogram.

15. The ultrasonic diagnostic apparatus according to claim 11, further comprising a display controller configured to display the first tomogram in a first display region of the display and to display the second tomogram in a second display region of the display, wherein a position of the region of interest displayed within the second display region is the same as a position of the region of interest displayed within the first display region.

16. The ultrasonic diagnostic apparatus according to claim 11, further comprising an operation interface operated by a user to designate a location of the region of interest on the first tomogram.

17. The ultrasonic diagnostic apparatus according to claim 11, further comprising a display controller configured to display the first tomogram and the second tomogram simultaneously or in a switched manner.

18. The ultrasonic diagnostic apparatus according to claim 11, further comprising a display controller configured to display the first tomogram and the second tomogram in an overlapping manner so that the region of interests in the first and second tomograms are in alignment.

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19. The ultrasonic diagnostic apparatus according to claim 11, further comprising a synthesizer configured to generate one synthetic image including an average luminance or maximum luminance from the first tomogram and the second tomogram.

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摘要(译)

这里公开的超声诊断装置包括产生超声波束的超声波探头，体积数据集收集单元，其通过超声波探头收集对应于多个三维扫描范围的多个个体数据集，多个三个 - 尺寸扫描范围部分地彼此重叠，感兴趣区域设定单元根据用户指令设定从多个个体数据集中的特定一个产生的第一X线断层图上的感兴趣区域，产生X线断层图产生单元来自特定体数据集的第一断层图像还产生与包括来自与包括感兴趣区域的三维扫描范围相对应的另一体数据集的感兴趣区域的部分相关联的第二断层图像，以及显示该第二断层图像的显示单元。第一个断层扫描图和第二个断层扫描图。

