



US 20120095342A1

(19) **United States**(12) **Patent Application Publication**
LEE(10) **Pub. No.: US 2012/0095342 A1**(43) **Pub. Date: Apr. 19, 2012**(54) **PROVIDING AN ULTRASOUND SPATIAL
COMPOUND IMAGE BASED ON CENTER
LINES OF ULTRASOUND IMAGES IN AN
ULTRASOUND SYSTEM**(52) **U.S. Cl. 600/447**(75) **Inventor: Kwang Ju LEE, Seoul (KR)**(73) **Assignee: SAMSUNG MEDISON CO.,
LTD.**(21) **Appl. No.: 13/221,330**(22) **Filed: Aug. 30, 2011**(30) **Foreign Application Priority Data**

Oct. 19, 2010 (KR) 10-2010-0101608

Publication Classification(51) **Int. Cl.**
A61B 8/14 (2006.01)(57) **ABSTRACT**

Embodiments for providing an ultrasound spatial compound image are disclosed. In one embodiment, by way of non-limiting example, an ultrasound system comprises: an ultrasound data acquisition unit configured to acquire ultrasound data by transmitting and receiving ultrasound signals; and a processing unit in communication with the ultrasound data acquisition unit, the processing unit being configured to set a plurality of center lines based on a virtual common point corresponding to predetermined scan-lines, move the virtual common point along each of the center lines to set a plurality of scan-lines, form a plurality of ultrasound images corresponding to the center lines based on the ultrasound data, and perform spatial compounding upon the ultrasound images to form an ultrasound spatial compound image, wherein the ultrasound data acquisition unit is configured to acquire the ultrasound data based on the plurality of scan-lines.

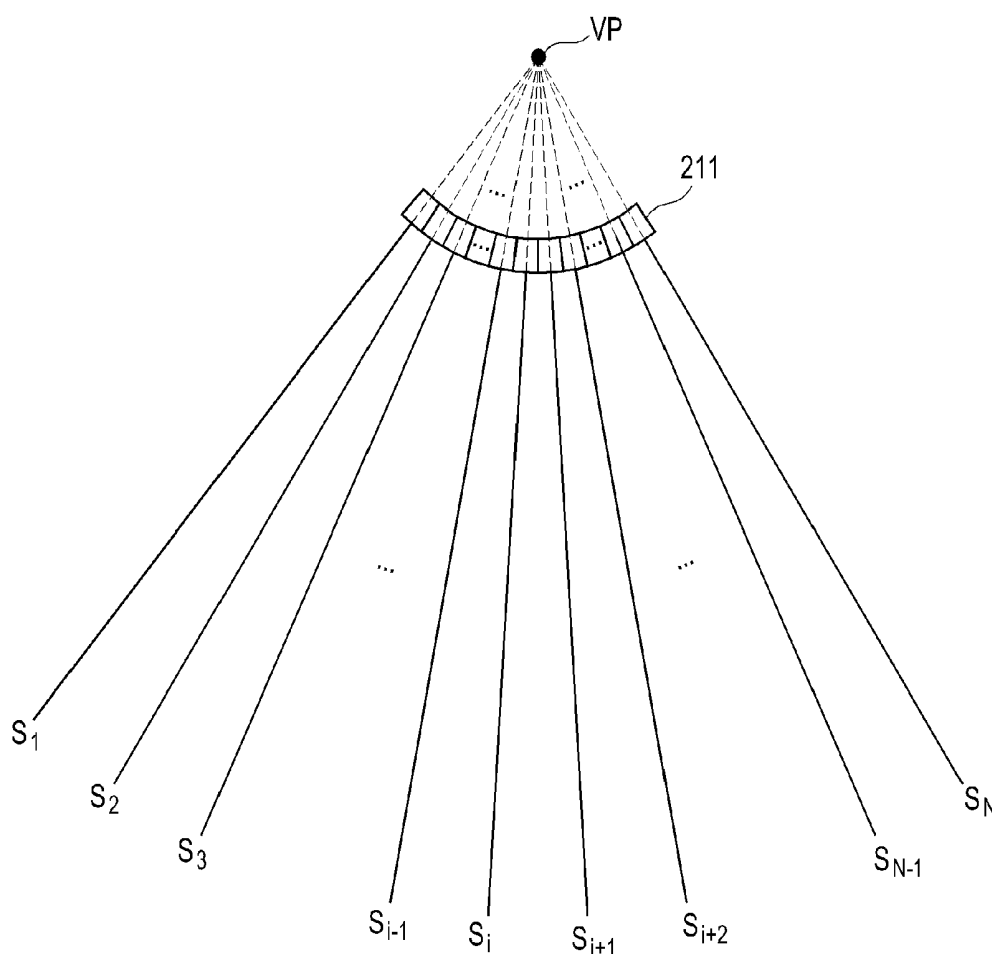


FIG. 1

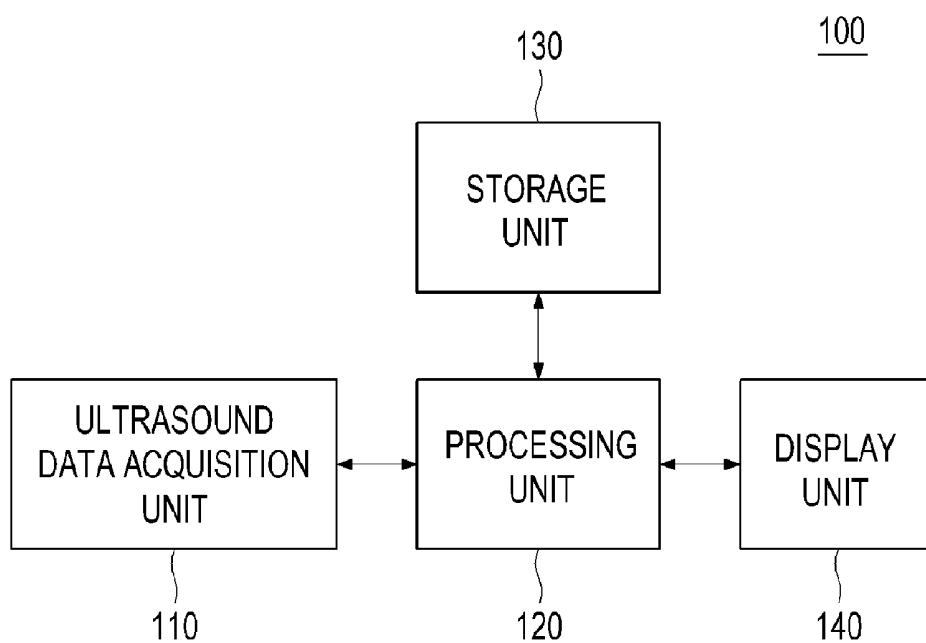


FIG. 2

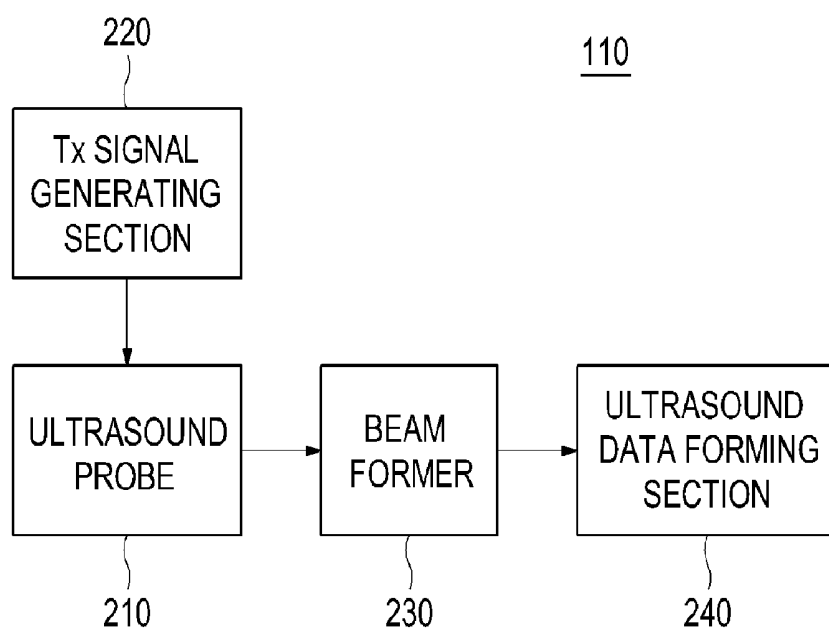


FIG. 3

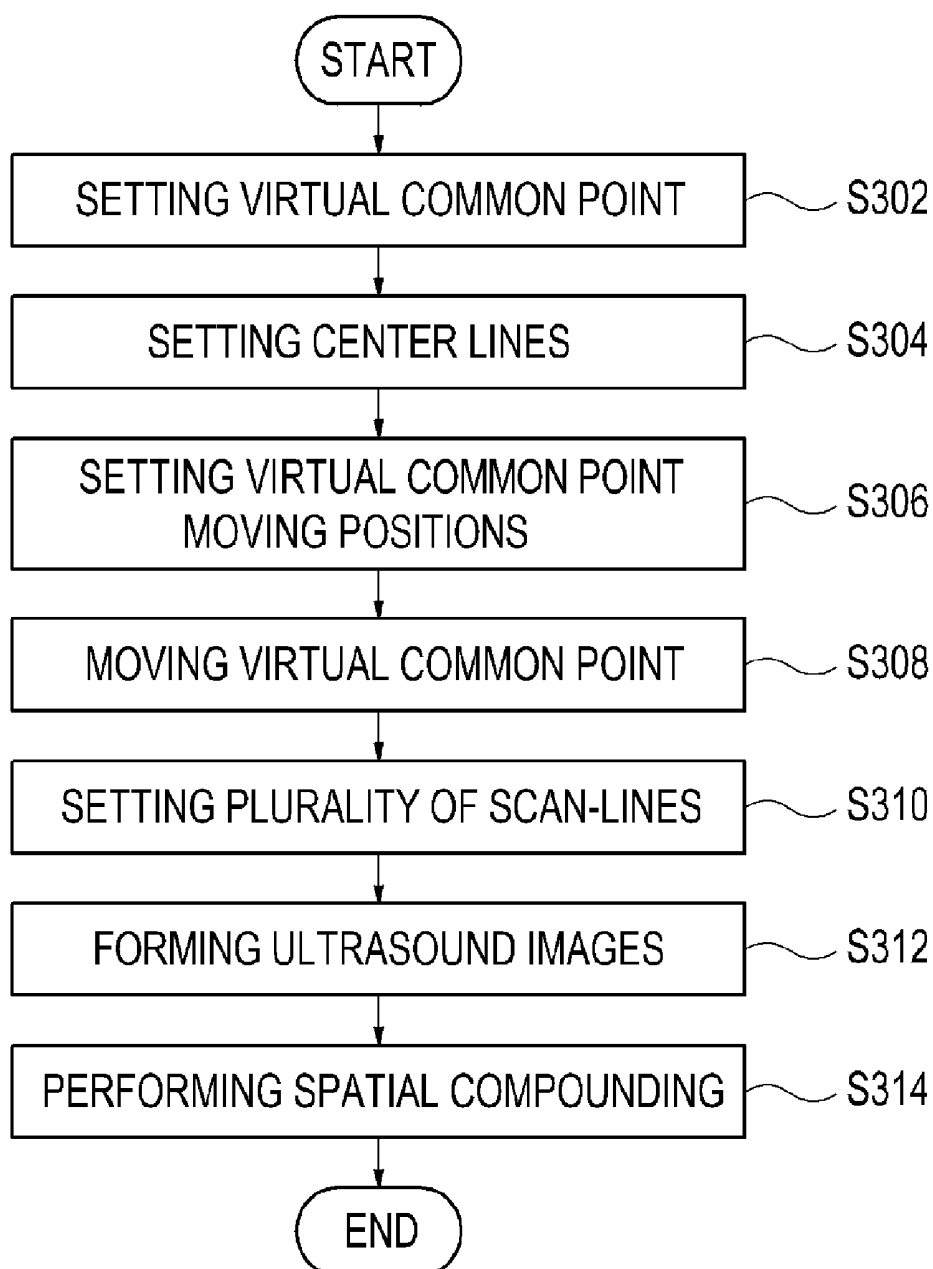


FIG. 4

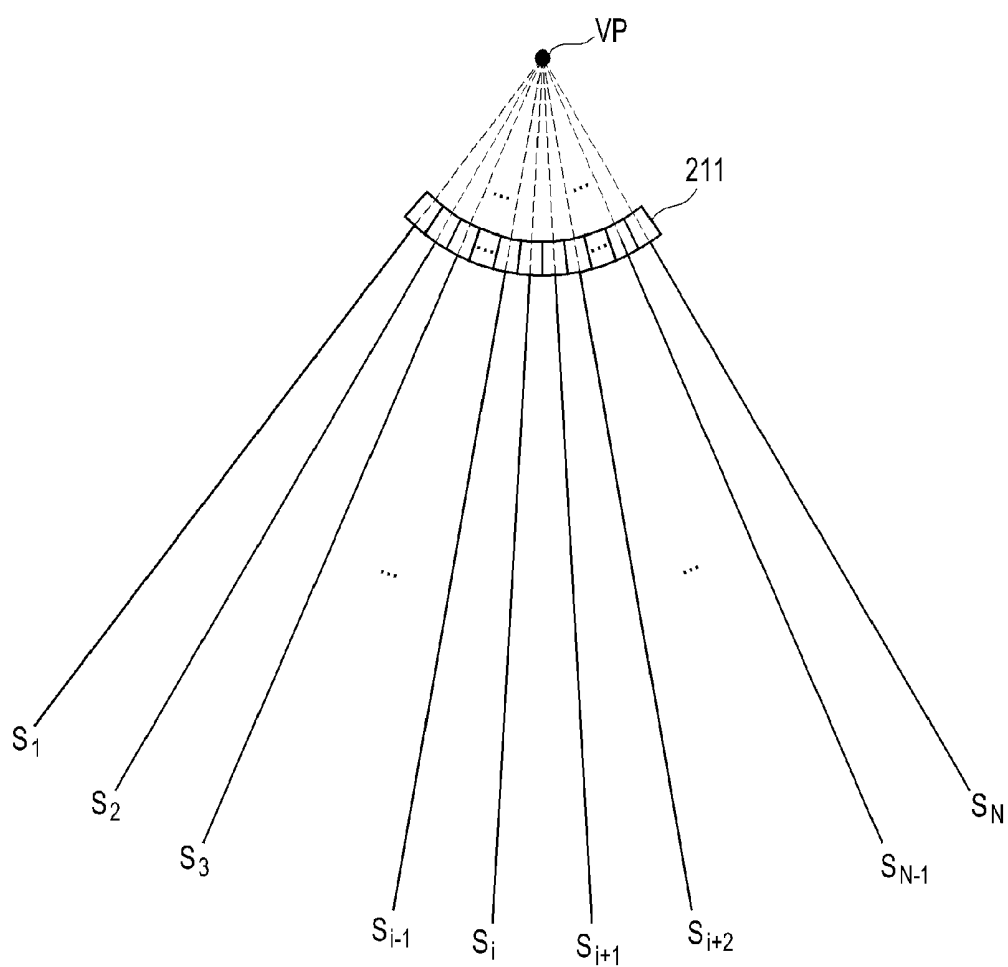


FIG. 5

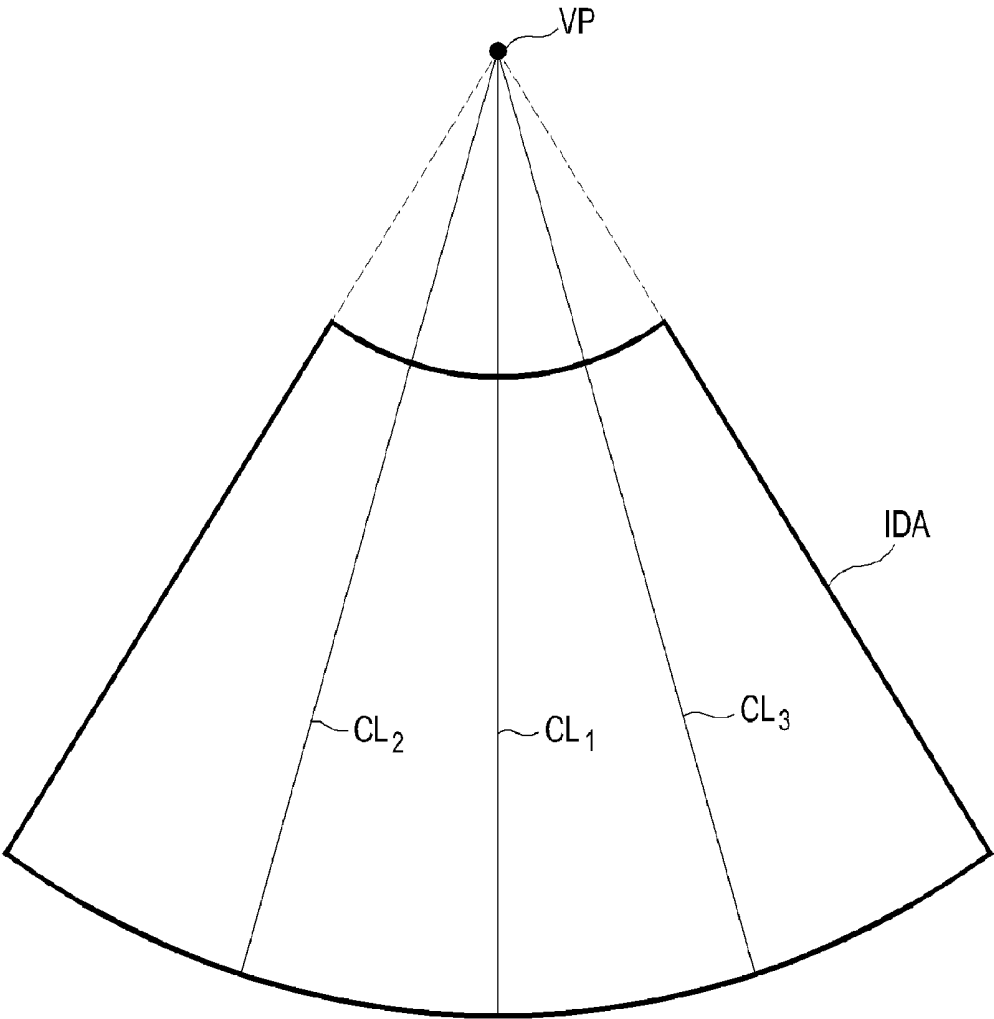


FIG. 6

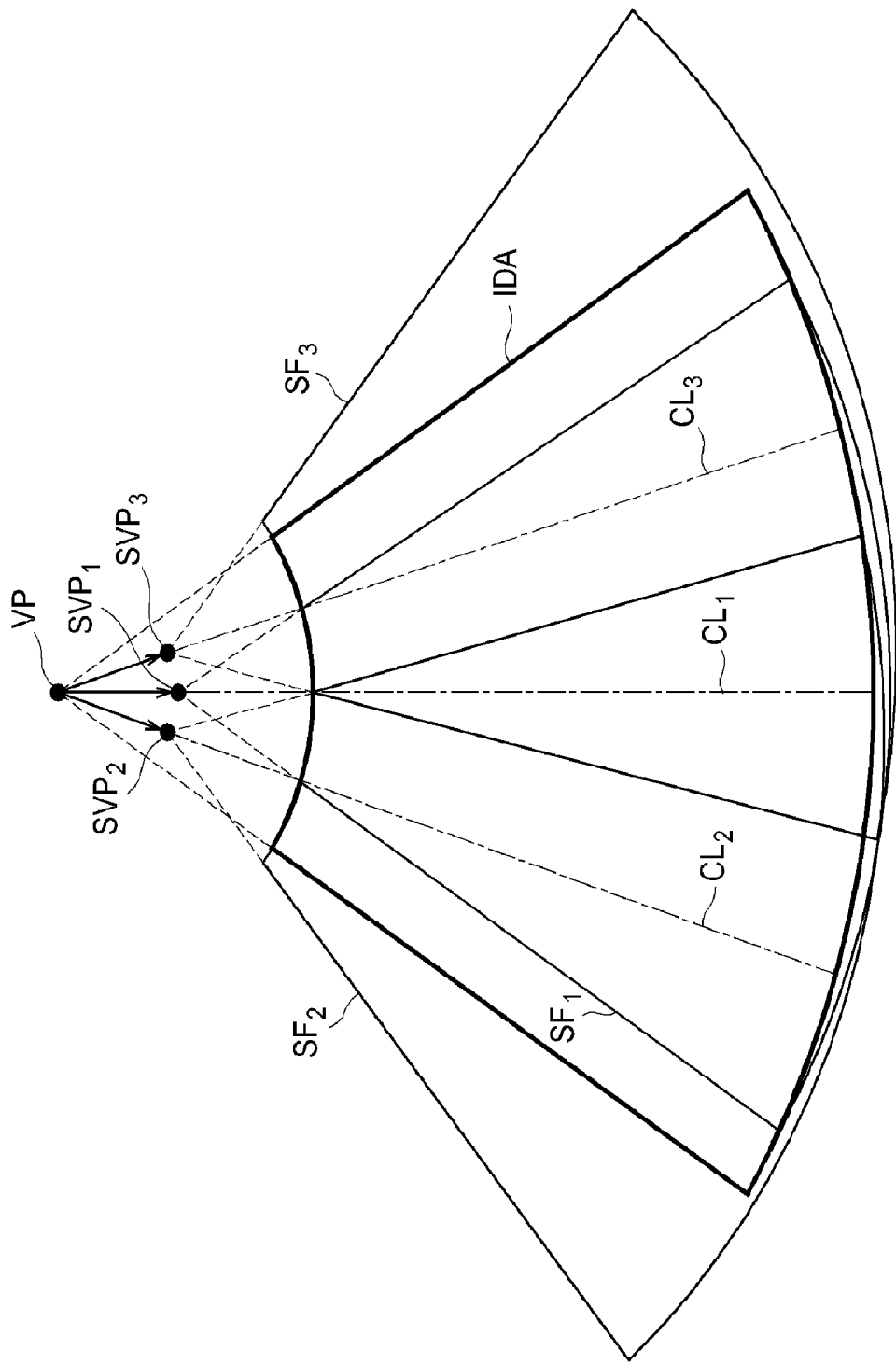


FIG. 7

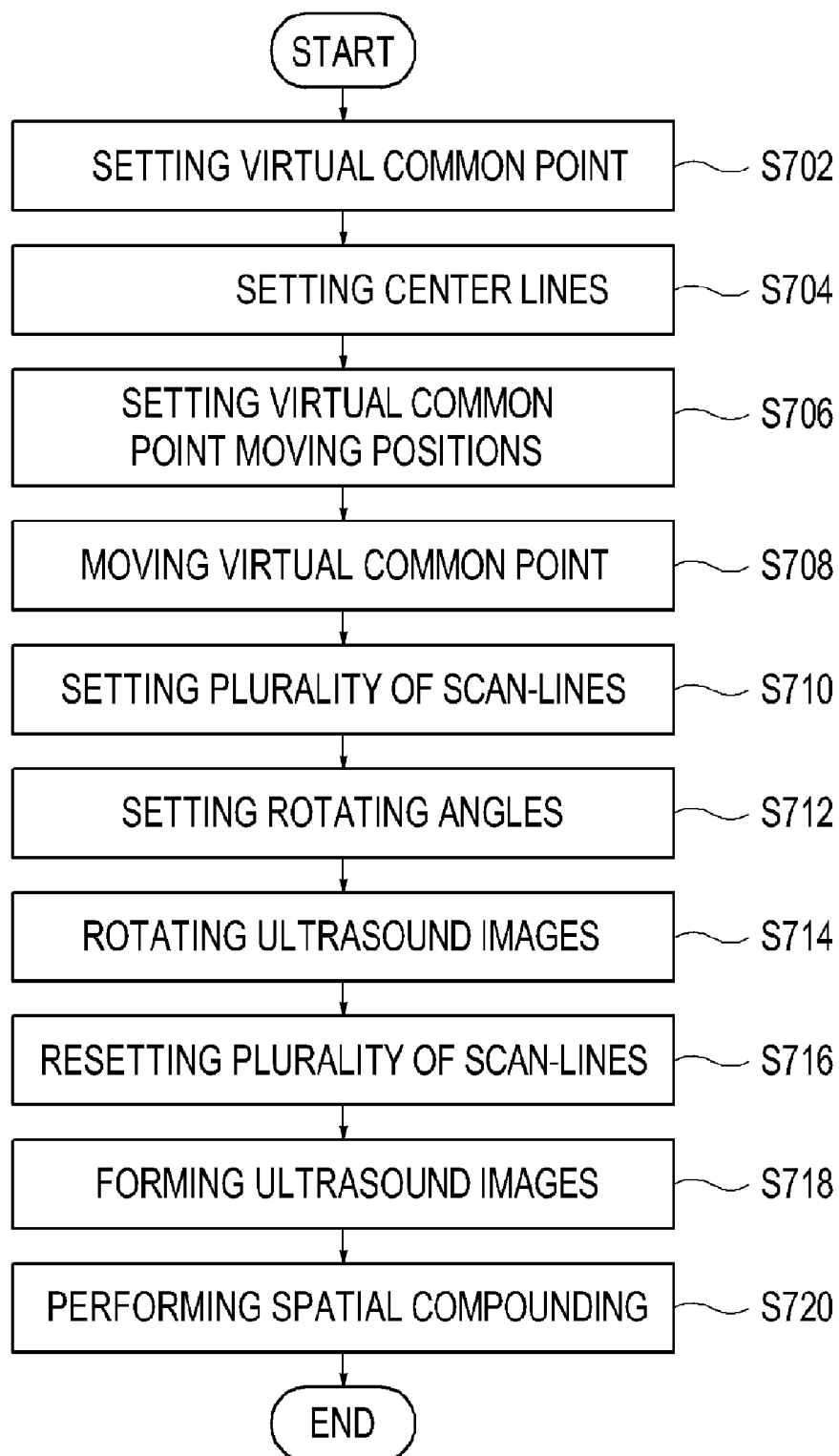


FIG. 8

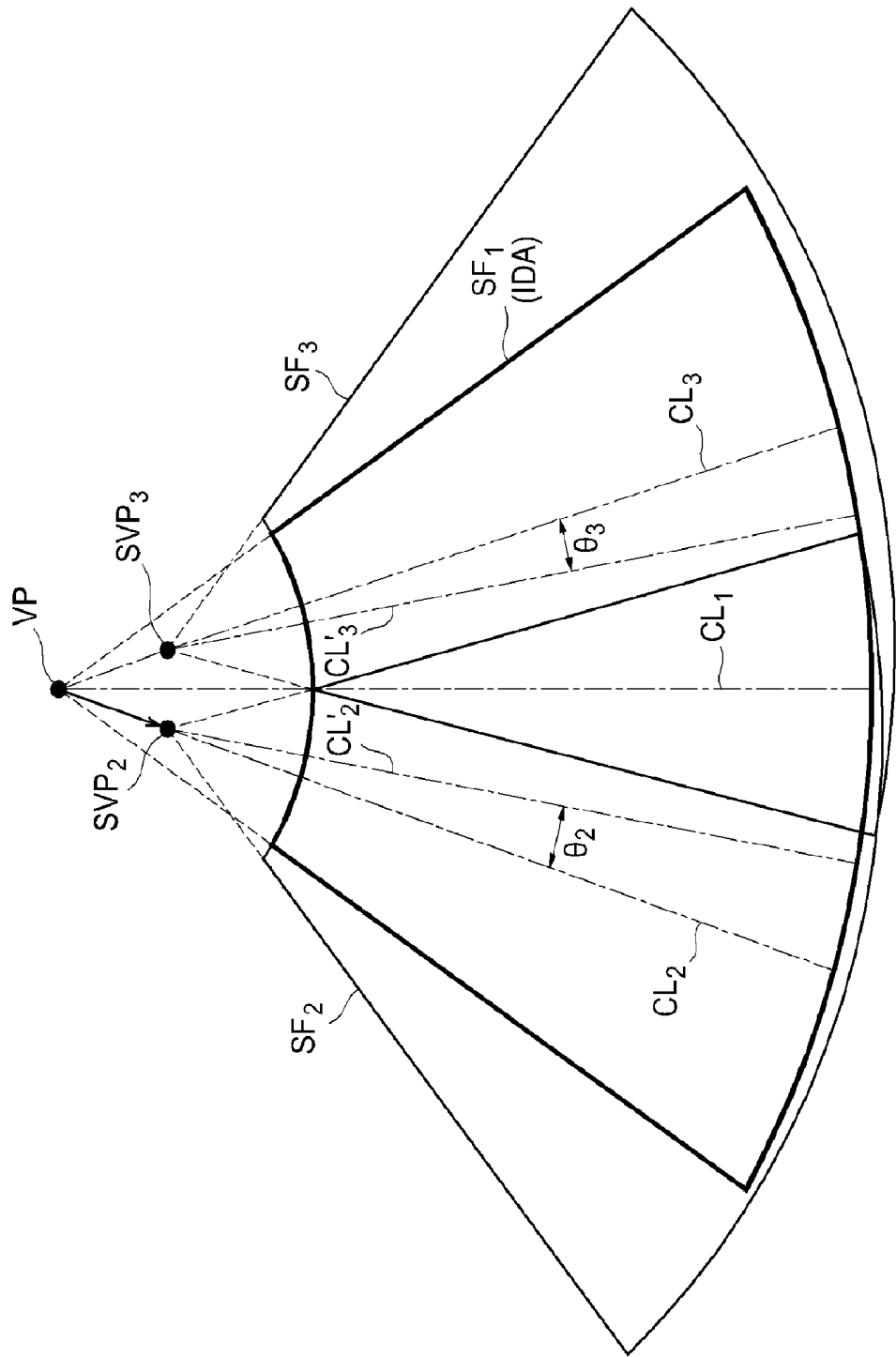


FIG. 9

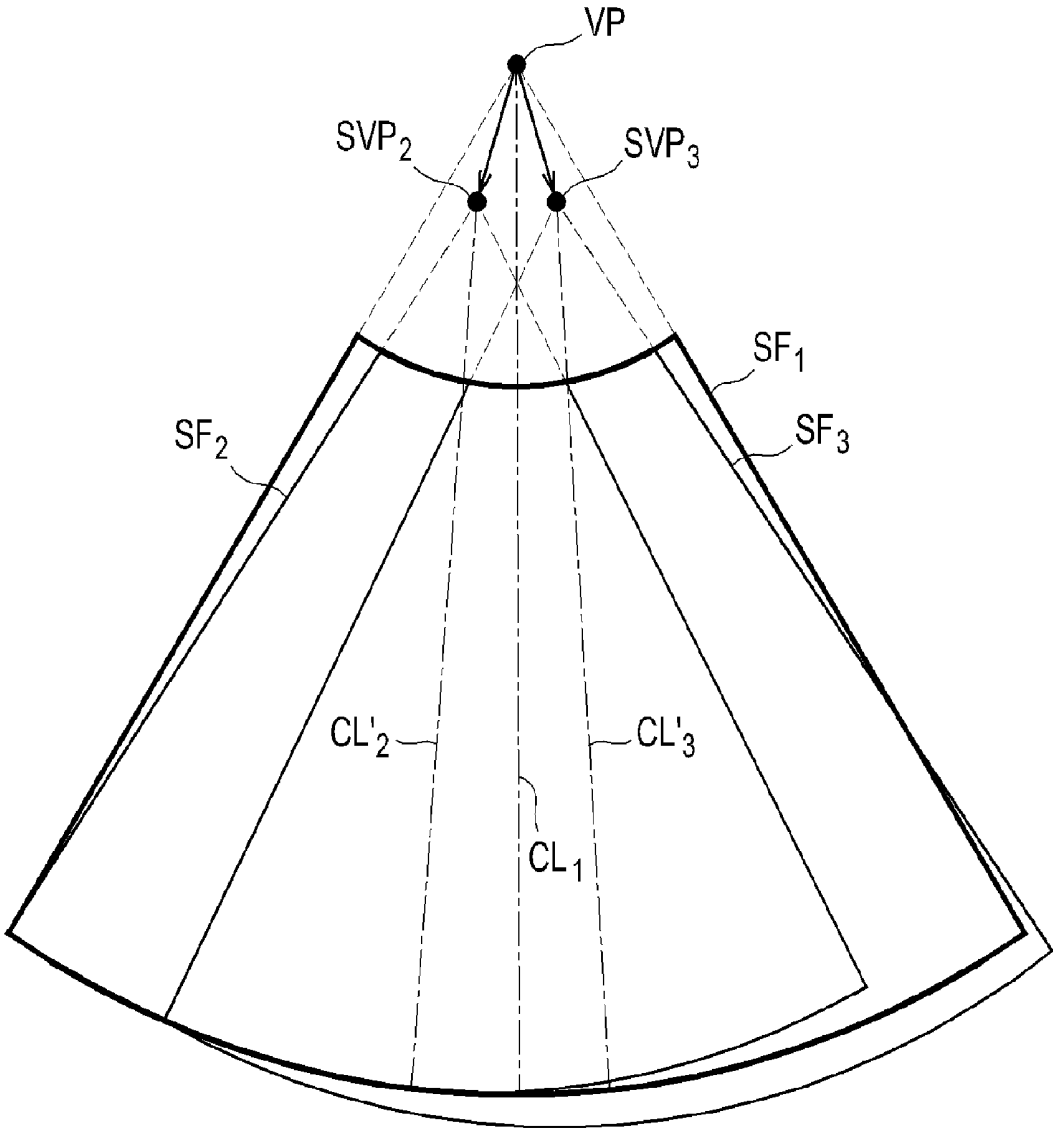


FIG. 10

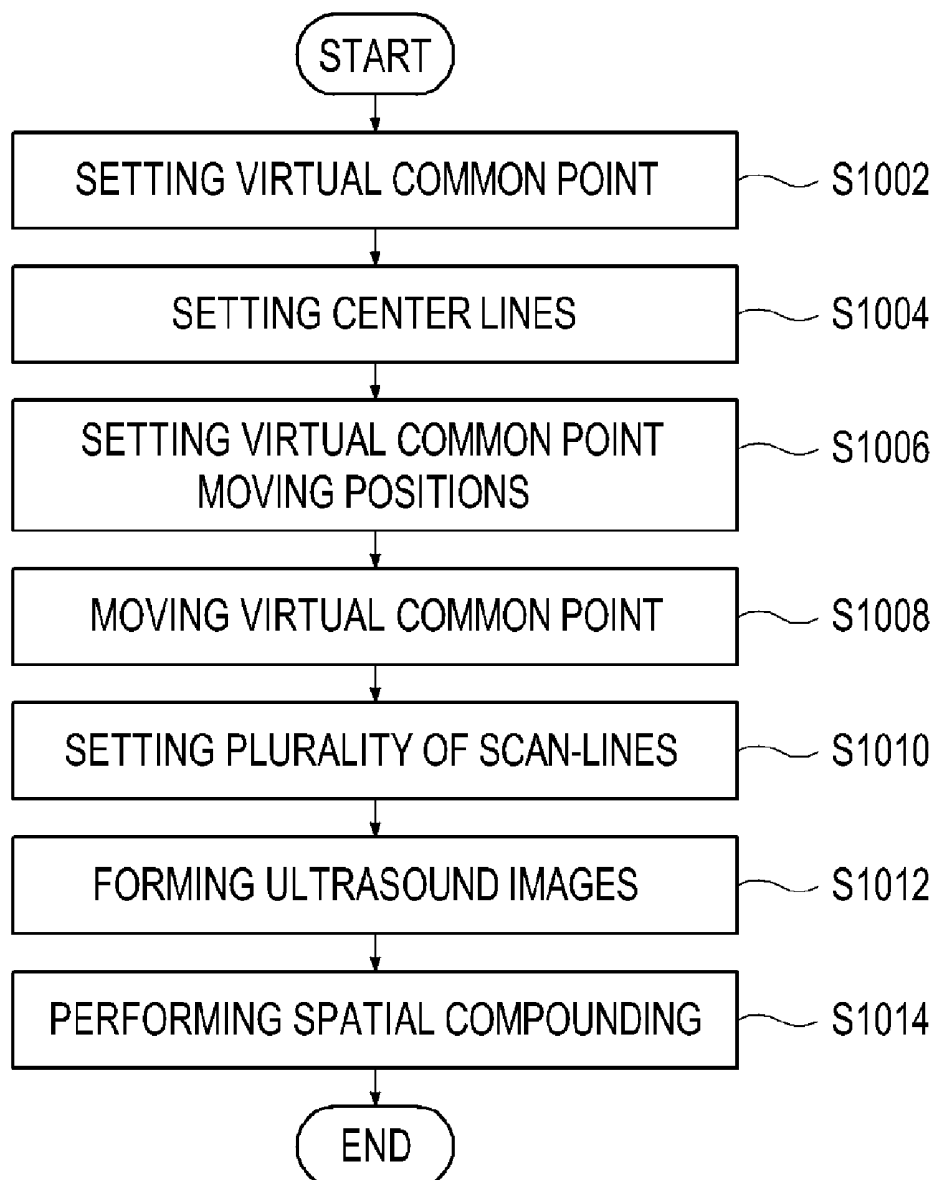
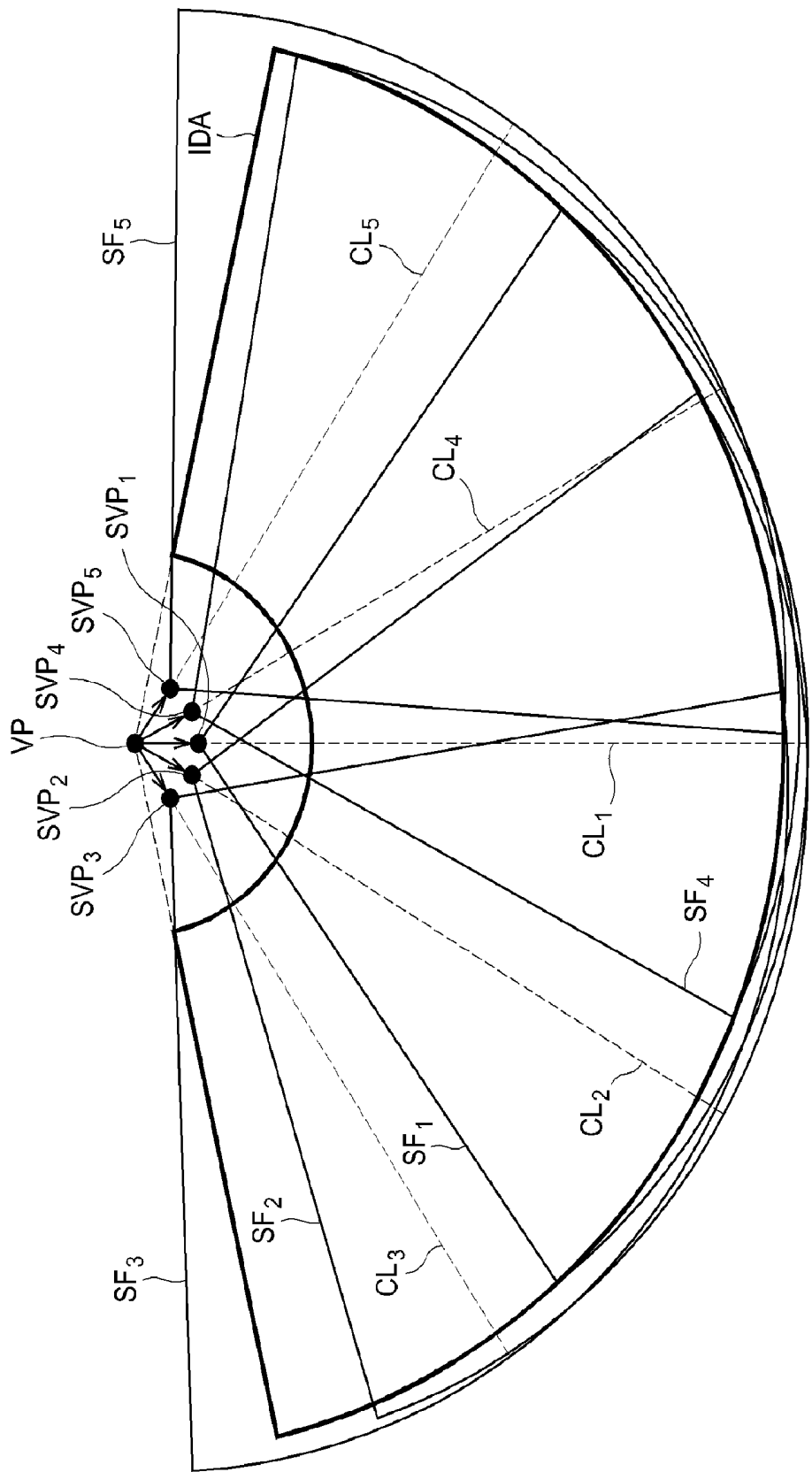


FIG. 11



**PROVIDING AN ULTRASOUND SPATIAL
COMPOUND IMAGE BASED ON CENTER
LINES OF ULTRASOUND IMAGES IN AN
ULTRASOUND SYSTEM**

**CROSS-REFERENCE TO RELATED
APPLICATION**

[0001] The present application claims priority from Korean Patent Application No. 10-2010-0101608 filed on Oct. 19, 2010, the entire subject matter of which is incorporated herein by reference.

TECHNICAL FIELD

[0002] The present disclosure generally relates to ultrasound systems, and more particularly to providing an ultrasound spatial compound image based on center lines of ultrasound images in an ultrasound system.

BACKGROUND

[0003] An ultrasound system has become an important and popular diagnostic tool since it has a wide range of applications. Specifically, due to its non-invasive and non-destructive nature, the ultrasound system has been extensively used in the medical profession. Modern high-performance ultrasound systems and techniques are commonly used to produce two-dimensional or three-dimensional ultrasound images of internal features of a target object (e.g., human organs).

[0004] The ultrasound system may transmit and receive ultrasound signals to and from a living body to thereby form a 2D (two-dimensional) ultrasound image or a 3D (three-dimensional) ultrasound image. Various techniques have been studied to enhance resolution of the ultrasound image. Spatial compounding is known as one of such techniques.

[0005] The spatial compounding is an imaging technique for forming a compound image by combining ultrasound images. That is, the ultrasound system forms a plurality of ultrasound images and performs the spatial compounding upon the ultrasound images to form an ultrasound spatial compound image.

[0006] The ultrasound system disposes scan-lines set a virtual common point, at which a plurality of scan-lines intersect, and moves the virtual common point to a particular position to thereby set a plurality of scan-lines corresponding to each of the ultrasound images. However, there is a problem since a steering angle corresponding to a particular scan-line becomes very large and effects of spatial compounding in the center of an image display area for displaying an ultrasound image decrease.

SUMMARY

[0007] Embodiments for providing an ultrasound spatial compound image in an ultrasound system are disclosed herein. In one embodiment, by way of non-limiting example, an ultrasound system comprises: an ultrasound data acquisition unit configured to acquire ultrasound data by transmitting and receiving ultrasound signals; and a processing unit in communication with the ultrasound data acquisition unit, the processing unit being configured to set a plurality of center lines on a basis of a virtual common point corresponding to predetermined scan-lines, move the virtual common point along each of the center lines to set a plurality of scan-lines, form a plurality of ultrasound images corresponding to the center lines based on the ultrasound data, and perform spatial

compounding upon the ultrasound images to form an ultrasound spatial compound image, wherein the ultrasound data acquisition unit is configured to acquire the ultrasound data based on the plurality of scan-lines.

[0008] In another embodiment, there is a method of providing an ultrasound spatial compound image, comprising: a) setting a plurality of center lines based on a virtual common point corresponding to predetermined scan-lines; b) moving the virtual common point along each of the center lines to set a plurality of scan-lines; c) acquiring ultrasound data by transmitting and receiving ultrasound signals based on the plurality of scan-lines; d) forming a plurality of ultrasound images corresponding to the center lines based on the ultrasound data; and e) performing spatial compounding upon the ultrasound images to form an ultrasound spatial compound image.

[0009] In yet another embodiment, there is provided a computer readable medium comprising computer executable instructions configured to perform the following acts: a) setting a plurality of center lines based on a virtual common point corresponding to predetermined scan-lines; b) moving the virtual common point along each of the center lines to set a plurality of scan-lines; c) acquiring ultrasound data by transmitting and receiving ultrasound signals based on the plurality of scan-lines; d) forming a plurality of ultrasound images corresponding to the center lines based on the ultrasound data; and e) performing spatial compounding upon the ultrasound images to form an ultrasound spatial compound image.

[0010] This summary is provided to introduce a selection of concepts in a simplified form that are further described below in the Detailed Description. This Summary is not intended to identify key or essential features of the claimed subject matter, nor is it intended to be used in determining the scope of the claimed subject matter.

BRIEF DESCRIPTION OF THE DRAWINGS

[0011] FIG. 1 is a block diagram showing an illustrative embodiment of an ultrasound system.

[0012] FIG. 2 is a block diagram showing an illustrative embodiment of an ultrasound data acquisition unit.

[0013] FIG. 3 is a flow chart showing a process of forming an ultrasound spatial compound image in accordance with a first embodiment.

[0014] FIG. 4 is a schematic diagram showing an example of a plurality of scan-lines and a virtual common point.

[0015] FIG. 5 is a schematic diagram showing an example of setting center lines in accordance with the first embodiment.

[0016] FIG. 6 is a schematic diagram showing an example of sub-virtual common points and ultrasound images in accordance with the first embodiment.

[0017] FIG. 7 is a flow chart showing a process of forming an ultrasound spatial compound image in accordance with a second embodiment.

[0018] FIG. 8 is a schematic diagram showing an example of setting center lines in accordance with the second embodiment.

[0019] FIG. 9 is a schematic diagram showing an example of sub-virtual common point and ultrasound images in accordance with the second embodiment.

[0020] FIG. 10 is a flow chart showing a process of forming an ultrasound spatial compound image in accordance with a third embodiment.

[0021] FIG. 11 is a schematic diagram showing an example of center lines, sub-virtual common points and ultrasound images in accordance with the third embodiment.

DETAILED DESCRIPTION

[0022] A detailed description may be provided with reference to the accompanying drawings. One of ordinary skill in the art may realize that the following description is illustrative only and is not in any way limiting. Other embodiments of the present invention may readily suggest themselves to such skilled persons having the benefit of this disclosure.

First Embodiment

[0023] Referring to FIG. 1, an ultrasound system 100 in accordance with an illustrative embodiment is shown. As depicted therein, the ultrasound system 100 may include an ultrasound data acquisition unit 110. The ultrasound data acquisition unit 110 may be configured to transmit and receive ultrasound signals to and from a living body and output ultrasound data. The living body may include a plurality of target objects (e.g., blood vessels, a heart, etc.).

[0024] FIG. 2 is a block diagram showing an illustrative embodiment of the ultrasound data acquisition unit 110. Referring to FIG. 2, the ultrasound data acquisition unit 110 may include an ultrasound probe 210. The ultrasound probe 210 may include a plurality of elements 211 (see FIG. 4) for reciprocally converting between ultrasound signals and electrical signals. The ultrasound probe 210 may be configured to transmit ultrasound signals to the living body along each of the scan-lines. The ultrasound probe 210 may be further configured to receive ultrasound signals (i.e., ultrasound echo signals) from the living body to output received signals. The received signals may be analog signals. The ultrasound probe 210 may include a convex probe. However, it should be noted herein that the ultrasound probe 210 may not be limited thereto.

[0025] The ultrasound data acquisition unit 110 may further include a transmit (Tx) signal generating section 220. The Tx signal generating section 220 may be configured to control the transmission of the ultrasound signals. The Tx signal generating section 220 may be further configured to generate electrical signals ("Tx signals") for obtaining at least one ultrasound image in consideration of the elements and focal points. The ultrasound image may include a brightness mode image. However, it should be noted herein that the ultrasound image may not be limited thereto.

[0026] In one embodiment, the Tx signal generating section 220 may be configured to generate first Tx signals for obtaining a first ultrasound image SF_1 , as shown in FIG. 6. Thus, the ultrasound probe 210 may be configured to convert the first Tx signals provided from the Tx signal generating section 220 into the ultrasound signals, transmit the ultrasound signals to the living body and receive the ultrasound echo signals from the living body to thereby output first received signals. The Tx signal generating section 220 may be further configured to generate second Tx signals for obtaining a second ultrasound image SF_2 , as shown in FIG. 6. Thus, the ultrasound probe 210 may be configured to convert the second Tx signals provided from the Tx signal generating section 220 into the ultrasound signals, transmit the ultrasound signals to the living body and receive the ultrasound echo signals from the living body to thereby output second received signals. The Tx signal generating section 220 may be further configured to

generate third Tx signals for obtaining a third ultrasound image SF_3 , as shown in FIG. 6. Thus, the ultrasound probe 210 may be configured to convert the third Tx signals provided from the Tx signal generating section 220 into the ultrasound signals, transmit the ultrasound signals to the living body and receive the ultrasound echo signals from the living body to thereby output third received signals.

[0027] The number of ultrasound images may be determined depending on the number of the ultrasound images, which are needed to form an ultrasound spatial compound image.

[0028] The ultrasound data acquisition unit 110 may further include a beam former 230. The beam former 230 may be configured to convert the received signals provided from the ultrasound probe 210 into digital signals. The beam former 230 may be further configured to apply delays to the digital signals in consideration of the elements and the focal points to thereby output digital receive-focused signals.

[0029] In one embodiment, the beam former 230 may be configured to convert the first received signals provided from the ultrasound probe 210 into first digital signals. The beam former 230 may be further configured to apply delays to the first digital signals in consideration of the elements and the focal points to thereby output first digital receive-focused signals. The beam former 230 may be further configured to convert the second received signals provided from the ultrasound probe 210 into second digital signals. The beam former 230 may be further configured to apply delays to the second digital signals in consideration of the elements and the focal points to thereby output second digital receive-focused signals. The beam former 230 may be further configured to convert the third received signals provided from the ultrasound probe 210 into third digital signals. The beam former 230 may be further configured to apply delays to the third digital signals in consideration of the elements and the focal points to thereby output third digital receive-focused signals.

[0030] The ultrasound data acquisition unit 110 may further include an ultrasound data forming section 240. The ultrasound data forming section 240 may be configured to form ultrasound data corresponding to the ultrasound image based on the digital receive-focused signals provided from the beam former 230. The ultrasound data may include radio frequency data. However, it should be noted herein that the ultrasound data may not be limited thereto. The ultrasound data forming section 240 may be further configured to perform signal processing (e.g., gain control, etc) upon the digital receive-focused signals.

[0031] In one embodiment, the ultrasound data forming section 240 may be configured to form first ultrasound data corresponding to the first ultrasound image SF_1 based on the first digital receive-focused signals provided from the beam former 230. The ultrasound data forming section 240 may be further configured to form second ultrasound data corresponding to the second ultrasound image SF_2 based on the second digital receive-focused signals provided from the beam former 230. The ultrasound data forming section 240 may be further configured to form third ultrasound data corresponding to the third ultrasound image SF_3 based on the third digital receive-focused signals provided from the beam former 230.

[0032] Alternatively, the ultrasound data acquisition unit 110 may be further configured to acquire the ultrasound data from an external or internal storage unit (not shown) connected to the ultrasound system 100.

[0033] Referring back to FIG. 1, the ultrasound system 100 may further include a processing unit 120 in communication with the ultrasound data acquisition unit 110. The processing unit 120 may include a central processing unit, a microprocessor or a graphic processing unit. However, it should be noted herein that the processing unit 120 may not be limited thereto.

[0034] FIG. 3 is a flow chart showing a process of forming an ultrasound spatial compound image in accordance with a first embodiment. The processing unit 120 may be configured to set a virtual common point VP corresponding to scan-lines S_1 to S_N in consideration of positions of the elements 211 as shown in FIG. 4, at step S302 in FIG. 3. The virtual common point VP may be a point at which the scan-lines S_1 to S_N intersect by extending the scan-lines S_1 to S_N to back of the elements 211.

[0035] The processing unit 120 may be configured to set center lines corresponding to the ultrasound images based on the virtual common point VP, at step S304 in FIG. 3. Herein, the center lines may converge into the virtual common point VP. Each of the ultrasound images may include a part of an image display area. The image display area may be an area capable of displaying an ultrasound image without steering the scan-lines S_1 to S_N .

[0036] In one embodiment, the processing unit 120 may be configured to set a first center line CL_1 corresponding to the first ultrasound image SF_1 , which includes a part of the image display area IDA, based on the virtual common point VP, as shown in FIG. 5. The processing unit 120 may be further configured to set a second center line CL_2 corresponding to the second ultrasound image SF_2 , which includes a part of the image display area IDA, based on the virtual common point VP, as shown in FIG. 5. The processing unit 120 may be further configured to set a third center line CL_3 corresponding to the third ultrasound image SF_3 , which includes a part of the image display area IDA, based on the virtual common point VP, as shown in FIG. 5. Angles between adjacent center lines may be same or different. That is, an angle between the first center line CL_1 and the second center line CL_2 and an angle between the first center line CL_1 and the third center line CL_3 may be same or different.

[0037] The number of center lines may be determined depending on the number of the ultrasound images to be compounded.

[0038] The processing unit 120 may be configured to set virtual common point moving positions corresponding to the center lines based on the virtual common point VP, at step S306 in FIG. 3. The virtual common point moving position may be a position for moving the virtual common point VP to a predetermined distance along a center line in order to form an ultrasound image corresponding to the center line. The processing unit 120 may be configured to move the virtual common point VP to the virtual common point moving positions to set sub-virtual common points corresponding to the ultrasound images, at step S308 in FIG. 3.

[0039] The processing unit 120 may be configured to set a first virtual common point moving position for moving the virtual common point VP along the first center line CL_1 . The processing unit 120 may be further configured to move the virtual common point VP to the first virtual common point moving position to set a first sub-virtual common point SVP_1 corresponding to the first ultrasound image SF_1 , as shown in FIG. 6. The processing unit 120 may be further configured to set a second virtual common point moving position for mov-

ing the virtual common point VP along the second center line CL_2 . The processing unit 120 may be further configured to move the virtual common point VP to the second virtual common point moving position to set a second sub-virtual common point SVP_2 corresponding to the second ultrasound image SF_2 , as shown in FIG. 6. The processing unit 120 may be further configured to set a third virtual common point moving position for moving the virtual common point VP along the third center line CL_3 . The processing unit 120 may be further configured to move the virtual common point VP to the third common point moving position to set a third sub-virtual common point SVP_3 corresponding to the third ultrasound image SF_3 , as shown in FIG. 6.

[0040] The processing unit 120 may be configured to set a plurality of scan-lines corresponding to each of the ultrasound images based on the virtual common point, the sub-virtual common points and the center lines, at step S310 in FIG. 3. Thus, the ultrasound data acquisition unit 110 may be configured to transmit the ultrasound signals to the living body along the scan-lines and receive the ultrasound echo signals from the living body to acquire the ultrasound data corresponding to each of the ultrasound images.

[0041] As one example, the processing unit 120 may be configured to set a reference ultrasound image from the ultrasound images SF_1 to SF_3 . The processing unit 120 may set the first ultrasound image SF_1 as the reference ultrasound image. The processing unit 120 may be further configured to detect an element corresponding to the second center line CL_2 from the plurality of elements 211 based on the reference ultrasound image. That is, the processing unit 120 may detect the element, through which the second center line CL_2 adjacent to the first center line CL_1 corresponding to the reference ultrasound image (i.e., first ultrasound image SF_1) passes. The processing unit 120 may be further configured to detect a center point of the element. The processing unit 120 may be further configured to set a scan-line, which passes through the center point of the element based on the first sub-virtual common point SVP_1 corresponding to the reference ultrasound image, as a reference scan-line (i.e., first scan-line) of the first ultrasound image SF_1 . The processing unit 120 may be further configured to set a plurality of scan-lines (i.e., steering angles corresponding to of the scan-lines) corresponding to the first ultrasound image SF_1 based on the first scan-line of the first ultrasound image SF_1 . The methods of setting the scan-lines based on the first scan-line are well known in the art. Thus, they have not been described in detail so as not to unnecessarily obscure the present disclosure. The processing unit 120 may be further configured to rotate the first center line CL_1 to the second center line CL_2 based on the virtual common point VP to set a plurality of scan-lines corresponding to the second ultrasound image SF_2 . The processing unit 120 may be also configured to rotate the first center line CL_1 to the second center line CL_3 based on the virtual common point VP to set a plurality of scan-lines corresponding to the third ultrasound image SF_3 .

[0042] As another example, the processing unit 120 may be configured to set a reference ultrasound image from the ultrasound images SF_1 to SF_3 . The processing unit 120 may set the first ultrasound SF_1 as the reference ultrasound image. The processing unit 120 may be further configured to detect an element corresponding to the second center line CL_2 from the plurality of elements 211 based on the reference ultrasound image. That is, processing unit 120 may detect the element, through which the second center line CL_2 adjacent to the first

center line CL_1 corresponding to the reference ultrasound image passes. The processing unit **120** may be further configured to detect a center point of the element. The processing unit **120** may be also configured to set a scan-line, which passes through the center point of the element on a basis of the first sub-virtual common point SVP_1 corresponding the reference ultrasound image, as a reference scan-line (i.e., last scan-line) of the first ultrasound image SF_1 (i.e., reference ultrasound image). The processing unit **120** may be further configured to rotate the first center line CL_1 to second center line CL_2 based on the virtual common point VP to set a plurality of scan-lines corresponding to the second ultrasound image SF_2 . The processing unit **120** may be additionally configured to rotate the first center line CL_1 to the third center line CL_3 based on the virtual common point VP to set a plurality of scan-lines corresponding to the third ultrasound image SF_3 .

[0043] As yet another embodiment, the processing unit **120** may be configured to set a reference ultrasound image from the ultrasound images SF_1 to SF_3 . The processing unit **120** may set the first ultrasound image SF_1 as the reference ultrasound image. The processing unit **120** may be further configured to detect a center point of a first element from the plurality of elements **211**. The processing unit **120** may be also configured to set a scan-line, which passes through the center point of the first element on a basis of the first sub-virtual common point SVP_1 , as a reference scan-line (i.e., first scan-line) of the reference ultrasound image. The processing unit **120** may be configured to calculate an angle between the first scan-line S_1 shown in FIG. 4 and the first scan-line of the reference ultrasound image. That is, the processing unit **120** may calculate a steering angle of the scan-line S_1 shown in FIG. 4 when the virtual common point VP is moved to the first sub-virtual common point SVP_1 . The processing unit **120** may be further configured to determine whether the calculated angle exists within a predetermined range (e.g., $0 < \text{range} \leq \text{a maximum directivity angle of the ultrasound probe } 210$). If it is determined that the calculated angle does not exist within the predetermined range, then the processing unit **120** may be further configured to detect a center point of a second element from the plurality of elements **211**. The processing unit **120** may be also configured to set a scan-line, which passes through the center point of the second element based on the first sub-virtual common point SVP_1 , as a first scan-line of the reference ultrasound image (i.e., first ultrasound image SF_1). The processing unit **120** may be further configured to calculate an angle between the scan-line S_2 shown in FIG. 4 and the first scan-line of the reference ultrasound image. That is, the processing unit **120** may calculate a steering angle of the scan-line S_2 shown in FIG. 4 when the virtual common point VP is moved to the first sub-virtual common point SVP_1 . The processing unit **120** may be further configured to determine whether the calculated angle exists within the predetermined range. If it is determined that the calculated angle exists within the predetermined range, then the processing unit **120** may be further configured to set a plurality of scan-lines (i.e., steering angles corresponding to the scan-lines) of the reference ultrasound image (i.e., first ultrasound image SF_1) based on the first scan-line of the reference ultrasound image. The processing unit **120** may be further configured to rotate the first center line CL_1 to second center line CL_2 based on the virtual common point VP to set a plurality of scan-lines corresponding to the second ultrasound image SF_2 . The processing unit **120** may be further

configured to rotate the first center line CL_1 to the third center line CL_3 based on the virtual common point VP to set a plurality of scan-lines corresponding to the third ultrasound image SF_3 .

[0044] Although it is described that the processing unit **120** may be configured to set the plurality of scan-lines corresponding to the first ultrasound image based on the first element of the elements **211** and the first scan-line of the first ultrasound image, the processing unit **120** may be further configured to set the plurality of scan-lines corresponding to the first ultrasound image based on the first element of the elements **211** and a last scan-line of the first ultrasound image.

[0045] The processing unit **120** may be configured to form the ultrasound images based on the ultrasound data provided from the ultrasound data acquisition unit **110**, at step S312 in FIG. 3.

[0046] In one embodiment, the processing unit **120** may be configured to form the first ultrasound image SF_1 based on the first ultrasound data provided from the ultrasound data acquisition unit **110**, as shown in FIG. 6. The processing unit **120** may be further configured to form the second ultrasound image SF_2 based on the second ultrasound data provided from the ultrasound data acquisition unit **110**, as shown in FIG. 6. The processing unit **120** may be further configured to form the third ultrasound image SF_3 based on the third ultrasound data provided from the ultrasound data acquisition unit **110**, as shown in FIG. 6.

[0047] The processing unit **120** may be configured to perform spatial compounding upon the ultrasound images to form an ultrasound spatial compound image, at step S314 in FIG. 3. The methods of performing the spatial compounding are well known in the art. Thus, they have not been described in detail so as not to unnecessarily obscure the present disclosure. For example, the processing unit **120** may perform the spatial compounding by calculating a mean brightness value corresponding to each of the pixels of the ultrasound images.

[0048] Referring back to FIG. 1, the ultrasound system **100** may further include a storage unit **130**. The storage unit **130** may store the ultrasound data acquired by the ultrasound data acquisition unit **110**. The storage unit **130** may further store the ultrasound images formed by the processing unit **120**.

[0049] The ultrasound system **100** may further include a display unit **140**. The display unit **140** may be configured to display the ultrasound spatial compound image. The display unit **140** may be also configured to display the ultrasound images.

Second Embodiment

[0050] Referring to FIG. 2, the ultrasound probe **210** may include the plurality of elements **211** (see FIG. 4) for reciprocally converting between ultrasound signals and electrical signals. The ultrasound probe **210** may be configured to transmit the ultrasound signals to the living body along the scan-lines. The ultrasound probe **210** may be further configured to receive the ultrasound echo signals from the living body to output the received signals.

[0051] The Tx signal generating section **220** may be configured to control the transmission of the ultrasound signals. The Tx signal generating section **220** may be further configured to generate the Tx signals for obtaining at least one ultrasound image in consideration of the elements and the focal points.

[0052] The Tx signal generating section 220 may be configured to generate first Tx signals for obtaining a first ultrasound image SF_1 , as shown in FIG. 9. Thus, the ultrasound probe 210 may be configured to convert the first Tx signals provided from the Tx signal generating section 220 into the ultrasound signals, transmit the ultrasound signals to the living body and receive the ultrasound echo signals from the living body to thereby output first received signals. The Tx signal generating section 220 may be further configured to generate second Tx signals for obtaining a second ultrasound image SF_2 , as shown in FIG. 9. Thus, the ultrasound probe 210 may be configured to convert the second Tx signals provided from the Tx signal generating section 220 into the ultrasound signals, transmit the ultrasound signals to the living body and receive the ultrasound echo signals from the living body to thereby output second received signals. The Tx signal generating section 220 may be further configured to generate third Tx signals for obtaining a third ultrasound image SF_3 , as shown in FIG. 9. Thus, the ultrasound probe 210 may be configured to convert the third Tx signals provided from the Tx signal generating section 220 into the ultrasound signals, transmit the ultrasound signals to the living body and receive the ultrasound echo signals from the living body to thereby output third received signals.

[0053] The beam former 230 may be configured to convert the received signals provided from the ultrasound probe 210 into digital signals. The beam former 230 may be further configured to apply delays to the digital signals in consideration of the elements and the focal points to thereby output digital receive-focused signals.

[0054] In one embodiment, the beam former 230 may be configured to convert the first received signals provided from the ultrasound probe 210 into first digital signals. The beam former 230 may be further configured to apply delays to the first digital signals in consideration of the elements and the focal points to thereby output first digital receive-focused signals. The beam former 230 may be further configured to convert the second received signals provided from the ultrasound probe 210 into second digital signals. The beam former 230 may be also configured to apply delays to the second digital signals in consideration of the elements and the focal points to thereby output second digital receive-focused signals. The beam former 230 may be further configured to convert the third received signals provided from the ultrasound probe 210 into third digital signals. The beam former 230 may be also configured to apply delays to the third digital signals in consideration of the elements and the focal points to thereby output third digital receive-focused signals.

[0055] The ultrasound data forming section 240 may be configured to form ultrasound data based on the digital receive-focused signals provided from the beam former 230. The ultrasound data may include radio frequency data. However, it should be noted herein that the ultrasound data may not be limited thereto. The ultrasound data forming section 240 may be further configured to perform signal processing (e.g., gain control, etc) upon the digital receive-focused signals.

[0056] The ultrasound data forming section 240 may be configured to form first ultrasound data corresponding to the first ultrasound image SF_1 shown in FIG. 9 based on the first digital receive-focused signals provided from the beam former 230. The ultrasound data forming section 240 may be further configured to form second ultrasound data corresponding to the second ultrasound image SF_2 shown in FIG.

9 based on the second digital receive-focused signals provided from the beam former 230. The ultrasound data forming section 240 may be also configured to form third ultrasound data corresponding to the third ultrasound image SF_3 shown in FIG. 9 based on the third digital receive-focused signals provided from the beam former 230.

[0057] FIG. 7 is a flow chart showing a process of forming an ultrasound spatial compound image in accordance with a second embodiment. The processing unit 120 may be configured to set the virtual common point VP corresponding to the scan-lines S_1 to S_N in consideration of positions of the elements 211 as shown in FIG. 4, at step S702 in FIG. 7.

[0058] The processing unit 120 may be configured to set center lines corresponding to the ultrasound images based on the virtual common point VP, at step S704 in FIG. 7.

[0059] In one embodiment, the processing unit 120 may be configured to set a first center line CL_1 corresponding to the first ultrasound image SF_1 , which includes the image display area IDA, based on the virtual common point VP as shown in FIG. 8. The processing unit 120 may be further configured to set a second center line CL_2 corresponding to the second ultrasound image SF_2 , which includes a part of the image display area IDA, based on the virtual common point VP, as shown in FIG. 8. The processing unit 120 may be also configured to set a third center line CL_3 corresponding to the third ultrasound image SF_3 , which includes a part of the image display area IDA, based on the virtual common point VP as shown in FIG. 8. Angles between adjacent center lines may be same or different. That is, an angle between the first center line CL_1 and the second center line CL_2 and an angle between the first center line CL_1 and the third center line CL_3 may be same or different.

[0060] The number of center lines may be determined depending on the number of the ultrasound images to be compounded.

[0061] The processing unit 120 may be configured to set virtual common point moving positions corresponding to the center lines based on the virtual common point VP, at step S706 in FIG. 7. The processing unit 120 may be configured to move the virtual common point VP to the virtual common point moving positions to set sub-virtual common points corresponding to the ultrasound images, at step S708 in FIG. 7.

[0062] In one embodiment, the processing unit 120 may be configured to set a first virtual common point moving position for moving the virtual common point VP along the first center line CL_1 . The first virtual common point moving position corresponds to the virtual common point VP. That is, the processing unit 120 may set the first virtual common point moving position, to which the virtual common point VP is not moved, in order to obtain the first ultrasound image SF_1 . The first ultrasound image SF_1 may be set as a reference ultrasound image. The processing unit 120 may be further configured to set a second virtual common point moving position for moving the virtual common point VP along the second center line CL_2 . The processing unit 120 may be also configured to move the virtual common point VP to the second virtual common point moving position to set a second sub-virtual common point SVP_2 corresponding to the second ultrasound image SF_2 , as shown in FIG. 8. The processing unit 120 may be further configured to set a third virtual common point moving position for moving the virtual common point VP along the center line CL_3 . The processing unit 120 may be further configured to move the virtual common point VP to

the third virtual common point moving position to set a third sub-virtual common point SVP_3 corresponding to the third ultrasound image SF_3 , as shown in FIG. 8.

[0063] The processing unit 120 may be configured to set a plurality of scan-lines corresponding to each of the ultrasound images based on the virtual common point, the sub-virtual common points and the center lines, at step S710 in FIG. 7. Thus, the ultrasound data acquisition unit 110 may be configured to transmit the ultrasound signals to the living body along the scan-lines and receive the ultrasound echo signals from the living body to acquire the ultrasound data corresponding to each of the ultrasound images.

[0064] As one example, the processing unit 120 may be configured to set a plurality of scan-lines corresponding to the first ultrasound image SF_1 based on the virtual common point VP. The scan-lines of the first ultrasound image SF_1 correspond to the scan-lines S_1 to S_N shown in FIG. 4. The processing unit 120 may be further configured to detect an element corresponding to the second center line CL_2 from the plurality of elements 211. That is, the processing unit 120 may detect the element, through which the second center line CL_2 passes, from the plurality of elements 211. The processing unit 120 may be further configured to detect a center point of the element. The processing unit 120 may be also configured to rotate the second center line CL_2 to the first center line CL_1 based on the virtual common point VP. The processing unit 120 may be further configured to set a scan-line, which passes through the center point of the element, as a first scan-line of the second ultrasound image SF_2 based on the second sub-virtual common point SVP_2 . The processing unit 120 may be also configured to set a plurality of scan-lines (i.e., steering angles corresponding to the scan-lines) corresponding to the second ultrasound image SF_2 based on the first scan-line of the second ultrasound image SF_2 . The methods of setting the scan-lines based on the first scan-line are well known in the art. Thus, they have not been described in detail so as not to unnecessarily obscure the present disclosure. The processing unit 120 may be further configured to reconvey the second center line CL_2 based on the virtual common point VP. The processing unit 120 may be further configured to detect an element corresponding to the third center line CL_3 from the plurality of elements 211. That is, the processing unit 120 may detect the element, through which the third center line CL_3 passes, from the plurality of elements 211. The processing unit 120 may be further configured to detect a center point of the element. The processing unit 120 may be also configured to rotate the third center line CL_3 to the first center line CL_1 based on the virtual common point VP. The processing unit 120 may be further configured to set a scan-line, which passes through the center point of the element as a first scan-line of the third ultrasound image SF_3 based on the third sub-virtual common point SVP_3 . The processing unit 120 may be further configured to set a plurality of scan-lines (i.e., steering angles corresponding to the scan-lines) corresponding to the third ultrasound image SF_3 based on the first scan-line of the third ultrasound image SF_3 . The processing unit 120 may be configured to reconvey the third center line CL_3 based on the virtual common point VP.

[0065] As another example, the processing unit 120 may be configured to set a plurality of scan-lines corresponding to the first ultrasound image SF_1 based on the virtual common point VP. The scan-lines of the first ultrasound image SF_1 correspond to the scan-lines S_1 to S_N shown in FIG. 4. The processing unit 120 may be further configured to detect an ele-

ment corresponding to the second center line CL_2 from the plurality of elements 211. That is, the processing unit 120 may detect the element, through which the second center line CL_2 passes, from the plurality of elements 211. The processing unit 120 may be further configured to detect a center point of the element. The processing unit 120 may be further configured to rotate the second center line CL_2 to the first center line CL_1 based on the virtual common point VP. The processing unit 120 may be further configured to set a scan-line, which passes through the center point of the element, as a reference scan-line (i.e., last scan-line) of the second ultrasound image SF_2 based on the second sub-virtual common point SVP_2 . The processing unit 120 may be further configured to set a plurality of scan-lines (i.e., steering angles corresponding to the scan-lines) corresponding to the second ultrasound image SF_2 based on the last scan-line of the second ultrasound image SF_2 . The methods of setting the scan-lines based on the last scan-line are well known in the art. Thus, they have not been described in detail so as not to unnecessarily obscure the present disclosure. The processing unit 120 may be further configured to reconvey the second center line CL_2 based on the virtual common point VP. The processing unit 120 may be further configured to detect an element corresponding to the third center line CL_3 from the plurality of elements 211. That is, the processing unit 120 may detect the element, through which the third center line CL_3 passes, from the plurality of elements 211. The processing unit 120 may be further configured to detect a center point of the element. The processing unit 120 may be also configured to rotate the third center line CL_3 to first center line CL_1 based on the virtual common point VP. The processing unit 120 may be further configured to set a scan-line, which passes through the center point of the element as a last scan-line of the third ultrasound image SF_3 based on the third sub-virtual common point SVP_3 . The processing unit 120 may be further configured to set a plurality of scan-lines (i.e., steering angles corresponding to the scan-lines) corresponding to the third ultrasound image SF_3 based on the last scan-line of the third ultrasound image SF_3 . The processing unit 120 may be further configured to reconvey the third center line CL_3 based on the virtual common point VP.

[0066] As yet another example, the processing unit 120 may be configured to set a plurality of scan-lines corresponding to the first ultrasound image SF_1 based on the virtual common point VP. The scan-lines of the first ultrasound image SF_1 correspond to the scan-lines S_1 to S_N shown in FIG. 4. The processing unit 120 may be further configured to rotate the second center line CL_2 to the first center line CL_1 based on the virtual common point VP. The processing unit 120 may be further configured to detect a center point of a first element from the plurality of elements 211. The processing unit 120 may be further configured to set a scan-line, which passes through the center point of the first element, as a reference scan-line (i.e., first scan-line) of the second ultrasound image SF_2 based on the second sub-virtual common point SVP_2 . The processing unit 120 may be further configured to calculate an angle between the scan-line S_1 shown in FIG. 4 and the first scan-line of the second ultrasound image SF_2 . The processing unit 120 may be further configured to determine whether the calculated angle exists within a predetermined range (e.g., $0 < \text{range} \leq \text{a maximum directivity angle of the ultrasound probe 210}$). If it is determined that the calculated angle does not exist within the predetermined range, then the processing unit 120 may be further configured to detect a center point of

a second element from the plurality of elements **211**. The processing unit **120** may be further configured to set a scan-line, which passes through the center point of the second element on a basis of the second sub-virtual common point SVP_2 , as the first scan-line of the second ultrasound image SF_2 . The processing unit **120** may be also configured to calculate an angle between the scan-line S_2 shown in FIG. 4 and the first scan-line of the second ultrasound image SF_2 . The processing unit **120** may be further configured to determine whether the calculated angle exists within the predetermined range. If it is determined that the calculated angle exists within the predetermined angle, then the processing unit **120** may be further configured to set a plurality of scan-lines corresponding to the second ultrasound image SF_2 based on the first scan-line of the second ultrasound image SF_2 . The processing unit **120** may be further configured to set a plurality of scan-lines corresponding to the third ultrasound image SF_3 , as mentioned above.

[0067] Although it is described that the processing unit **120** may be configured to set the plurality of scan-lines based on the first element and the first scan-line, the processing unit **120** may be further configured to set the plurality of scan-lines based on a last element and a last scan-line.

[0068] The processing unit **120** may be configured to set rotating angles corresponding to the center lines, at step **S712** in FIG. 7. The rotating angle is an angle for the ultrasound images including the part of the image display area IDA into the image display area IDA.

[0069] In one embodiment, the processing unit **120** may be configured to set a first rotating angle corresponding to the first center line CL_1 based on the first sub-virtual common point (i.e., virtual common point VP). The first rotating angle is an angle for rotating the first ultrasound image SF_1 into the image display area IDA based on the first sub-virtual common point, and is 0. The processing unit **120** may be further configured to set a second rotating angle θ_2 corresponding to the second center line CL_2 based on the second sub-virtual common point SVP_2 as shown in FIG. 8. The second rotating angle θ_2 is an angle for rotating the second ultrasound image SF_2 into the image display area IDA based on the second sub-virtual common point SVP_2 . The processing unit **120** may be further configured to set a third rotating angle θ_3 corresponding to the third center line CL_3 based on the third sub-virtual common point SVP_3 as shown in FIG. 8. The third rotating angle θ_3 is an angle for rotating the third ultrasound image SF_3 into the image display area IDA based on the third sub-virtual common point SVP_3 .

[0070] The processing unit **120** may be configured to rotate the ultrasound images into the image display area IDA based on the rotating angles and the sub-virtual common points, at step **S714** in FIG. 7.

[0071] In one embodiment, the processing unit **120** may be configured to rotate the second center line CL_2 to a new second center line CL_2' corresponding to the second rotating angle θ_2 based on the second sub-virtual common point SVP_2 , as shown in FIG. 9. Thus, the second ultrasound image SF_2 may be rotated into the image display area IDA, as shown in FIG. 9. The processing unit **120** may be further configured to rotate the third center line CL_3 to a new third center line CL_3' corresponding to the third rotating angle θ_3 based on the third sub-virtual common point SVP_3 , as shown in FIG. 9. Thus, the third ultrasound image SF_3 may be rotated into the image display area IDA, as shown in FIG. 9.

[0072] The processing unit **120** may be configured to reset a plurality of scan-lines corresponding to each of the ultrasound images based on the rotating angles, at step **S716** in FIG. 7. Thus, the ultrasound data acquisition unit **110** may be configured to transmit the ultrasound signals to the living body along the reset scan-lines and receive the ultrasound echo signals from the living body to thereby acquire the ultrasound data corresponding to each of the ultrasound images.

[0073] In one embodiment, the processing unit **120** may be configured to reset the plurality of scan-lines corresponding to the second ultrasound image SF_2 , which is rotated into the image display area IDA based on the second rotating angle θ_2 . The processing unit **120** may be further configured to reset the plurality of scan-lines corresponding to the third ultrasound image SF_3 , which is rotated into the image display area IDA based on the third rotating angle θ_3 .

[0074] The processing unit **120** may be configured to form the ultrasound images based on the ultrasound data provided from the ultrasound data acquisition unit **110**, at step **S718** in FIG. 7.

[0075] In one embodiment, the processing unit **120** may be configured to form the first ultrasound image SF_1 based on the first ultrasound data provided from the ultrasound data acquisition unit **110**, as shown in FIG. 9. The processing unit **120** may be further configured to form the second ultrasound image SF_2 based on the second ultrasound data provided from the ultrasound data acquisition unit **110**, as shown in FIG. 9. The processing unit **120** may be further configured to form the third ultrasound image SF_3 based on the third ultrasound data provided from the ultrasound data acquisition unit **110**, as shown in FIG. 9.

[0076] The processing unit **120** may be configured to perform spatial compounding upon the ultrasound images to form an ultrasound spatial compound image, at step **S720** in FIG. 7. The methods of performing the spatial compounding are well known in the art. Thus, they have not been described in detail so as not to unnecessarily obscure the present disclosure. For example, the processing unit **120** may perform the spatial compounding by calculating a mean brightness value corresponding to each of the pixels of the ultrasound images.

Third Embodiment

[0077] Referring to FIG. 2, the ultrasound probe **210** may include a plurality of elements **211** (see FIG. 4) for reciprocally converting between ultrasound signals and electrical signals. The ultrasound probe **210** may be configured to transmit ultrasound signals to the living body along the scan-lines. The ultrasound probe **210** may be further configured to receive ultrasound signals (i.e., ultrasound echo signals) from the living body to output received signals. The received signals may be analog signals. The ultrasound probe **210** may include a wide view angle probe. However, it should be noted herein that the ultrasound probe **210** may not be limited thereto.

[0078] The Tx signal generating section **220** may be configured to control the transmission of the ultrasound signals. The Tx signal generating section **220** may be further configured to generate the Tx signals for obtaining at least one ultrasound image in consideration of the elements and the focal points.

[0079] In one embodiment, the Tx signal generating section **220** may be configured to generate first Tx signals for obtain-

ing a first ultrasound image SF_1 shown in FIG. 11. Thus, the ultrasound probe 210 may be configured to convert the first Tx signals provided from the Tx signal generating section 220 into the ultrasound signals, transmit the ultrasound signals to the living body and receive the ultrasound echo signals from the living body to thereby output first received signals. The Tx signal generating section 220 may be further configured to generate second Tx signals for obtaining a second ultrasound image SF_2 shown in FIG. 11. Thus, the ultrasound probe 210 may be configured to convert the second Tx signals provided from the Tx signal generating section 220 into the ultrasound signals, transmit the ultrasound signals to the living body and receive the ultrasound echo signals from the living body to thereby output second received signals. The Tx signal generating section 220 may be further configured to generate third Tx signals for obtaining a third ultrasound image SF_3 shown in FIG. 11. As such, the ultrasound probe 210 may be configured to convert the third Tx signals provided from the Tx signal generating section 220 into the ultrasound signals, transmit the ultrasound signals to the living body and receive the ultrasound echo signals from the living body to thereby output third received signals. The Tx signal generating section 220 may be further configured to generate fourth Tx signals for obtaining a fourth ultrasound image SF_4 shown in FIG. 11. Thus, the ultrasound probe 210 may be configured to convert the fourth Tx signals provided from the Tx signal generating section 220 into the ultrasound signals, transmit the ultrasound signals to living body and receive the ultrasound echo signals from the living body to thereby output fourth received signals. The Tx signal generating section 220 may be further configured to generate fifth Tx signals for obtaining a fifth ultrasound image SF_5 shown in FIG. 11. Accordingly, the ultrasound probe 210 may be configured to convert the fifth Tx signals provided from the Tx signal generating section 220 into the ultrasound signals, transmit the ultrasound signals to the living body and receive the ultrasound echo signals from the living body to thereby output fifth received signals.

[0080] The beam former 230 may be configured to convert the received signals provided from the ultrasound probe 210 into digital signals. The beam former 230 may be further configured to apply delays to the digital signals in consideration of the elements and the focal points to thereby output digital receive-focused signals.

[0081] In one embodiment, the beam former 230 may be configured to convert the first received signals provided from the ultrasound probe 210 into first digital signals. The beam former 230 may be further configured to apply delays to the first digital signals in consideration of the elements and the focal points to thereby output first digital receive-focused signals. The beam former 230 may be further configured to convert the second received signals provided from the ultrasound probe 210 into second digital signals. The beam former 230 may be further configured to apply delays to the second digital signals in consideration of the elements and the focal points to thereby output second digital receive-focused signals. The beam former 230 may be further configured to convert the third received signals provided from the ultrasound probe 210 into third digital signals. The beam former 230 may be also configured to apply delays to the third digital signals in consideration of the elements and the focal points to thereby output third digital receive-focused signals. The beam former 230 may be further configured to convert the fourth received signals provided from the ultrasound probe

210 into fourth digital signals. The beam former 230 may be further configured to apply delays to the fourth digital signals in consideration of the elements and the focal points to thereby output fourth digital receive-focused signals. The beam former 230 may be additionally configured to convert the fifth received signals provided from the ultrasound probe 210 into fifth digital signals. The beam former 230 may be further configured to apply delays to the fifth digital signals in consideration of the elements and the focal points to thereby output fifth digital receive-focused signals.

[0082] The ultrasound data forming section 240 may be configured to form ultrasound data based on the digital receive-focused signals provided from the beam former 230. The ultrasound data may include radio frequency data. However, it should be noted herein that the ultrasound data may not be limited thereto. The ultrasound data forming section 240 may be further configured to perform the signal processing (e.g., gain control, etc) upon the digital receive-focused signals.

[0083] In one embodiment, the ultrasound data forming section 240 may be configured to form first ultrasound data corresponding to the first ultrasound image SF_1 shown in FIG. 11 based on the first digital receive-focused signals. The ultrasound data forming section 240 may be further configured to form second ultrasound data corresponding to the second ultrasound image SF_2 shown in FIG. 11 based on the second digital receive-focused signals. The ultrasound data forming section 240 may be also configured to form third ultrasound data corresponding to the third ultrasound image SF_3 shown in FIG. 11 based on the third digital receive-focused signals. The ultrasound data forming section 240 may be further configured to form fourth ultrasound data corresponding to the fourth ultrasound image SF_4 shown in FIG. 11 based on the fourth digital receive-focused signals. The ultrasound data forming section 240 may be configured to form fifth ultrasound data corresponding to fifth ultrasound image SF_5 shown in FIG. 11 based on the fifth digital receive-focused signals.

[0084] FIG. 10 is a flow chart showing a process of forming an ultrasound spatial compound image in accordance with a third embodiment. The processing unit 120 may be configured to set the virtual common point VP corresponding to the scan-lines S_1 to S_N in consideration of positions of the elements 211 as shown in FIG. 4, at step S1002 in FIG. 10.

[0085] The processing unit 120 may be configured to center lines corresponding to the ultrasound images on a basis of the virtual common point VP, at step S1004 in FIG. 10.

[0086] In one embodiment, the processing unit 120 may be configured to set a first center line CL_1 corresponding to the first ultrasound image SF_1 , which includes a part of the image display area IDA, based on the virtual common point VP as shown in FIG. 11. The processing unit 120 may be further configured to set a second center line CL_2 corresponding to the second ultrasound image SF_2 , which includes a part of the image display area IDA, based on the virtual common point VP as shown in FIG. 11. The processing unit 120 may be further configured to set a third center line CL_3 corresponding to the third ultrasound image SF_3 , which includes a part of the image display area IDA, based on the virtual common point VP as shown in FIG. 11. The processing unit 120 may be also configured to set a fourth center line CL_4 corresponding to the fourth ultrasound image SF_4 , which includes a part of the image display area IDA, based on the virtual common point VP as shown in FIG. 11. The processing unit 120 may be

further configured to set a fifth center line CL_5 corresponding to the fifth ultrasound image SF_5 , which includes a part of the image display area IDA, based on the virtual common point VP as shown in FIG. 11. Angles between the adjacent center lines may be same or different. That is, an angle between the first center line CL_1 and the second center line CL_2 , an angle between the second center line CL_2 and the third center line CL_3 , an angle between the first center line CL_1 and the fourth center line CL_4 , and an angle between the fourth center line CL_4 and the fifth center line CL_5 may be same or different.

[0087] The number of ultrasound images may be determined depending on the number of the ultrasound images to be compounded.

[0088] The processing unit 120 may be configured to set virtual common point moving positions corresponding to the center lines based on the virtual common point VP, at step S1006 in FIG. 10. The processing unit 120 may be configured to move the virtual common point VP to the virtual common point moving positions to set sub-virtual common points corresponding to the ultrasound images, at step S1008 in FIG. 10.

[0089] In one embodiment, the processing unit 120 may be configured to set a first virtual common point moving position for moving the virtual common point VP along the first center line CL_1 . The processing unit 120 may be further configured to move the virtual common point VP to the first virtual common point moving position to set a first sub-virtual common point SVP_1 corresponding to the first ultrasound image SF_1 as shown in FIG. 11. The processing unit 120 may be also configured to set a second virtual common point moving position for moving the virtual common point VP along the second center line CL_2 . The processing unit 120 may be further configured to move the virtual common point VP to the second virtual common point moving position to set a second virtual common point SVP_2 corresponding to the second ultrasound image SF_2 as shown in FIG. 11. The processing unit 120 may be additionally configured to set a third virtual common point moving position for moving the virtual common point VP along the third center line CL_3 . The processing unit 120 may be further configured to move the virtual common point VP to the third virtual common point moving position to set a third sub-virtual common point SVP_3 corresponding to the third ultrasound image SF_3 as shown in FIG. 11. The processing unit 120 may be further configured to set a fourth virtual common point moving position for moving the virtual common point VP along the fourth center line CL_4 . The processing unit 120 may be configured to move the virtual common point VP to the fourth virtual common point moving position to set a fourth sub-virtual common point SVP_4 corresponding to the fourth ultrasound image SF_4 as shown in FIG. 11. The processing unit 120 may be further configured to set a fifth virtual common point moving position for moving the virtual common point VP along the fifth center line CL_5 . The processing unit 120 may be also configured to move the virtual common point VP to the fifth virtual common point moving position to set a fifth sub-virtual common point SVP_5 corresponding to the fifth ultrasound image SF_5 as shown in FIG. 11.

[0090] The processing unit 120 may be configured to set a plurality of scan-lines corresponding to each of the ultrasound images based on the virtual common point, the sub-virtual common points and the center lines, at step S1010 in FIG. 10. Thus, the ultrasound data acquisition unit 110 may be configured to transmit the ultrasound signals to the living

body along the scan-lines and receive the ultrasound echo signals from the living body to acquire the ultrasound data corresponding to each of the ultrasound images.

[0091] The methods of setting the plurality of scan-lines in the embodiment are similar to the methods of setting the plurality of scan-lines in the first embodiment. Thus, they have not been described in detail so as not to unnecessarily obscure the present disclosure.

[0092] The processing unit 120 may be configured to form the ultrasound images based on the ultrasound data provided from the ultrasound data acquisition unit 110, at step S1012 in FIG. 10.

[0093] In one embodiment, the processing unit 120 may be configured to form the first ultrasound image SF_1 based on the first ultrasound data provided from the ultrasound data acquisition unit 110, as shown in FIG. 11. The processing unit 120 may be further configured to form the second ultrasound image SF_2 based on the second ultrasound data provided from the ultrasound data acquisition unit 110, as shown in FIG. 11. The processing unit 120 may be also configured to form the third ultrasound image SF_3 based on the third ultrasound data provided from the ultrasound data acquisition unit 110, as shown in FIG. 11. The processing unit 120 may be further configured to form the fourth ultrasound image SF_4 based on the fourth ultrasound data provided from the ultrasound data acquisition unit 110, as shown in FIG. 11. The processing unit 120 may be further configured to form the fifth ultrasound image SF_5 based on the fifth ultrasound data provided from the ultrasound data acquisition unit 110, as shown in FIG. 11.

[0094] The processing unit 120 may be configured to perform spatial compounding upon the ultrasound images to form an ultrasound spatial compound image, at step S1014 in FIG. 10. The methods of performing the spatial compounding are well known in the art. Thus, they have not been described in detail so as not to unnecessarily obscure the present disclosure. For example, the processing unit 120 may perform the spatial compounding by calculating a mean brightness value corresponding to each of the pixels of the ultrasound images.

[0095] In another embodiment, the present invention may provide a computer readable medium comprising computer executable instructions configured to perform the following acts: a) setting a plurality of center lines based on a virtual common point corresponding to predetermined scan-lines; b) moving the virtual common point along each of the center lines to set a plurality of scan-lines; c) acquiring ultrasound data by transmitting and receiving ultrasound signals based on the plurality of scan-lines; d) forming a plurality of ultrasound images corresponding to the center lines based on the ultrasound data; and e) performing spatial compounding upon the ultrasound images to form an ultrasound spatial compound image. The computer readable medium may comprise a floppy disk, a hard disk, a memory, a compact disk, a digital video disk, etc.

[0096] Although embodiments have been described with reference to a number of illustrative embodiments thereof, it should be understood that numerous other modifications and embodiments can be devised by those skilled in the art that will fall within the spirit and scope of the principles of this disclosure. More particularly, numerous variations and modifications are possible in the component parts and/or arrangements of the subject combination arrangement within the scope of the disclosure, the drawings and the appended claims. In addition to variations and modifications in the

component parts and/or arrangements, alternative uses will also be apparent to those skilled in the art.

What is claimed is:

1. An ultrasound system, comprising:
an ultrasound data acquisition unit configured to acquire ultrasound data by transmitting and receiving ultrasound signals; and
a processing unit in communication with the ultrasound data acquisition unit, the processing unit being configured to set a plurality of center lines based on a virtual common point corresponding to predetermined scan-lines, move the virtual common point along each of the center lines to set a plurality of scan-lines, form a plurality of ultrasound images corresponding to the center lines based on the ultrasound data, and perform spatial compounding upon the ultrasound images to form an ultrasound spatial compound image,
wherein the ultrasound data acquisition unit is configured to acquire the ultrasound data based on the plurality of scan-lines.
2. The ultrasound system of claim 1, wherein the ultrasound data acquisition unit includes an ultrasound probe having a plurality of elements.
3. The ultrasound system of claim 2, wherein the processing unit is configured to:
set virtual common point moving positions on the center lines;
move the virtual common point to each of the virtual common point moving positions along each of the center lines to set sub-virtual common points corresponding to the ultrasound images; and
set the plurality of scan-lines corresponding to each of the ultrasound images based on the virtual common point, the sub-virtual common points and the center lines.
4. The ultrasound system of claim 3, wherein the processing unit is configured to:
set a reference ultrasound image from the ultrasound images;
detect an element of an ultrasound probe, through which remaining center lines adjacent to the center line corresponding to the reference ultrasound image pass;
detect a center point of the element;
set a reference scan-line passing through the center point of the element a basis of the sub-virtual common point corresponding to the reference ultrasound image;
set the plurality of scan-lines corresponding to the reference ultrasound image based on the reference scan-line; and
rotate the center line corresponding to the reference ultrasound image to the remaining center lines corresponding to remaining ultrasound images to set the plurality of scan-lines corresponding to the remaining ultrasound images.
5. The ultrasound system of claim 4, wherein the reference scan-line is a first scan-line or a last scan-line of the reference ultrasound image.
6. The ultrasound system of claim 3, wherein the processing unit is configured to:
set a reference ultrasound image from the ultrasound images;
detect center points of elements of an ultrasound probe;
detect a center point for setting a reference scan-line of the reference ultrasound image from the center points;

- set the reference scan-line passing through the center point on a basis of the sub-virtual common point corresponding to the reference ultrasound image;
- set the plurality of scan-lines corresponding to the reference ultrasound image based on the reference scan-line; and
rotate the center line corresponding to the reference ultrasound image to remaining center lines corresponding to remaining ultrasound images to set the plurality of scan-lines corresponding to the remaining ultrasound images.
7. The ultrasound system of claim 6, wherein the reference scan-line is a first scan-line or a last scan-line of the reference ultrasound image.
8. The ultrasound system of claim 3, wherein the processing unit is configured to set the virtual common point as one of the sub-virtual common points.
9. The ultrasound system of claim 8, wherein the processing unit is configured to:
set a reference ultrasound image from the ultrasound images, wherein the reference ultrasound image has the virtual common point as one of the sub-virtual common points;
detect elements of an ultrasound probe, through which remaining center lines adjacent to the center line corresponding to the reference ultrasound image pass;
detect center points of the elements;
rotate remaining center lines corresponding to remaining ultrasound images to the center line corresponding to the reference ultrasound image;
set reference scan-lines passing through center points on a basis of the sub-virtual common points corresponding to the remaining ultrasound images;
set the plurality of scan-lines corresponding to the remaining ultrasound images based on the reference scan-lines; and
reconvey the center lines corresponding to the remaining ultrasound images.
10. The ultrasound system of claim 9, wherein each of the reference scan-lines is a first scan-line or a last scan-line of the reference ultrasound image.
11. The ultrasound system of claim 9, wherein the processing unit is further configured to:
set rotating angles for rotating the remaining ultrasound images based on the sub-virtual common points corresponding to the remaining the ultrasound images;
rotate the remaining ultrasound images to the rotating angles based on the sub-virtual common points corresponding to the remaining ultrasound images; and
reset the plurality of scan-lines corresponding to the remaining ultrasound images based on the rotating angles.
12. A method of providing an ultrasound spatial compound image, comprising:
a) setting a plurality of center lines on a basis of a virtual common point corresponding to predetermined scan-lines;
b) moving the virtual common point along each of the center lines to set a plurality of scan-lines;
c) acquiring ultrasound data by transmitting and receiving ultrasound signals based on the plurality of scan-lines;
d) forming a plurality of ultrasound images corresponding to the center lines based on the ultrasound data; and
e) performing spatial compounding upon the ultrasound images to form an ultrasound spatial compound image.

13. The method of claim **12**, wherein the step b) comprises:
b1) setting virtual common point moving positions on the center lines;

b2) moving the virtual common point to each of the virtual common point moving positions along each of the center lines to set sub-virtual common points corresponding to the ultrasound images; and

b3) setting the plurality of scan-lines corresponding to each of the ultrasound images based on the virtual common point, the sub-virtual common points and the center lines.

14. The method of claim **13**, wherein the step b3) comprises:

setting a reference ultrasound image from the ultrasound images;

detecting an element of an ultrasound probe, through which remaining center lines adjacent to the center line corresponding to the reference ultrasound image pass;

detecting a center point of the element;

setting a reference scan-line passing through the center point of the element a basis of the sub-virtual common point corresponding to the reference ultrasound image;

setting the plurality of scan-lines corresponding to the reference ultrasound image based on the reference scan-line; and

rotating the center line corresponding to the reference ultrasound image to the remaining center lines corresponding to remaining ultrasound images to set the plurality of scan-lines corresponding to the remaining ultrasound images.

15. The method of claim **14**, wherein the reference scan-line is a first scan-line or a last scan-line of the reference ultrasound image.

16. The method of claim **13**, wherein the step b3) comprises:

setting a reference ultrasound image from the ultrasound images;

detecting center points of elements of an ultrasound probe;

detecting a center point for setting a reference scan-line of the reference ultrasound image from the center points;

setting the reference scan-line passing through the center point on a basis of the sub-virtual common point corresponding to the reference ultrasound image;

setting the plurality of scan-lines corresponding to the reference ultrasound image based on the reference scan-line; and

rotating the center line corresponding to the reference ultrasound image to remaining center lines corresponding to remaining ultrasound images to set the plurality of scan-lines corresponding to the remaining ultrasound images.

17. The method of claim **16**, wherein the reference scan-line is a first scan-line or a last scan-line of the reference ultrasound image.

18. The method of claim **13**, wherein the step b1) comprises:

setting the virtual common point as one of the sub-virtual common points.

19. The method of claim **18**, wherein the step b3) comprises:

setting a reference ultrasound image from the ultrasound images, wherein the reference ultrasound image has the virtual common point as one of the sub-virtual common points;

detecting elements of an ultrasound probe, through which remaining center lines adjacent to the center line corresponding to the reference ultrasound image pass;

detecting center points of the elements;

rotating remaining center lines corresponding to remaining ultrasound images to the center line corresponding to the reference ultrasound image;

setting reference scan-lines passing through center points based on the sub-virtual common points corresponding to the remaining ultrasound images;

setting the plurality of scan-lines corresponding to the remaining ultrasound images based on the reference scan-lines; and

reconveying the center lines corresponding to the remaining ultrasound images.

20. The method of claim **19**, wherein each of the reference scan-lines is a first scan-line or a last scan-line of the reference ultrasound image.

21. The method of claim **19**, wherein the step b) further comprises:

setting rotating angles for rotating the remaining ultrasound images based on the sub-virtual common points corresponding to the remaining the ultrasound images;

rotating the remaining ultrasound images to the rotating angles based on the sub-virtual common points corresponding to the remaining ultrasound images; and

resetting the plurality of scan-lines corresponding to the remaining ultrasound images based on the rotating angles.

22. A computer readable medium comprising computer executable instructions configured to perform following acts:

a) setting a plurality of center lines based on a virtual common point corresponding to predetermined scan-lines;

b) moving the virtual common point along each of the center lines to set a plurality of scan-lines;

c) acquiring ultrasound data by transmitting and receiving ultrasound signals based on the plurality of scan-lines;

d) forming a plurality of ultrasound images corresponding to the center lines based on the ultrasound data; and

e) performing spatial compounding upon the ultrasound images to form an ultrasound spatial compound image.

* * * * *

专利名称(译)	在超声系统中基于超声图像的中心线提供超声空间复合图像		
公开(公告)号	US20120095342A1	公开(公告)日	2012-04-19
申请号	US13/221330	申请日	2011-08-30
[标]申请(专利权)人(译)	三星麦迪森株式会社		
申请(专利权)人(译)	三星MEDISON CO. , LTD.		
当前申请(专利权)人(译)	三星MEDISON CO. , LTD.		
[标]发明人	LEE KWANG JU		
发明人	LEE, KWANG JU		
IPC分类号	A61B8/14		
CPC分类号	G01S15/8995 G01S7/52085 A61B8/5253 G01S15/8915		
优先权	1020100101608 2010-10-19 KR		
其他公开文献	US9151841		
外部链接	Espacenet USPTO		

摘要(译)

公开了用于提供超声空间复合图像的实施例。在一个实施例中，作为非限制性示例，超声系统包括：超声数据获取单元，被配置为通过发送和接收超声信号来获取超声数据；处理单元，用于与超声数据采集单元通信的处理单元，处理单元，用于基于与预定扫描线对应的虚拟公共点设置多条中心线，沿每条中心线移动虚拟公共点设置多条扫描线，基于超声数据形成与中心线对应的多个超声图像，并对超声图像进行空间复合以形成超声空间复合图像，其中，超声数据获取单元被配置为基于多条扫描线获取超声数据。

