



US 20150157298A1

(19) **United States**(12) **Patent Application Publication**
PARK et al.(10) **Pub. No.: US 2015/0157298 A1**(43) **Pub. Date: Jun. 11, 2015**(54) **APPARATUS AND METHOD FOR
COMBINING THREE DIMENSIONAL
ULTRASOUND IMAGES***G06T 19/20* (2006.01)*G06K 9/46* (2006.01)*A61B 8/00* (2006.01)*G06T 7/00* (2006.01)(71) Applicants: **Samsung Electronics Co., Ltd.**,
Suwon-si (KR); **SAMSUNG LIFE
WELFARE FOUNDATION**, Seoul
(KR)(52) **U.S. Cl.**CPC *A61B 8/5253* (2013.01); *A61B 8/5207*
(2013.01); *A61B 8/469* (2013.01); *A61B 8/466*
(2013.01); *A61B 8/085* (2013.01); *A61B*
8/0875 (2013.01); *A61B 8/0891* (2013.01);
G06T 7/0012 (2013.01); *G06T 19/20*
(2013.01); *G06K 9/46* (2013.01); *G06T 7/40*
(2013.01); *G06T 2207/30008* (2013.01); *G06T*
2207/30101 (2013.01); *G06T 2207/10132*
(2013.01)(72) Inventors: **Moon-Ho PARK**, Hwaseong-si (KR);
Ye-Hoon KIM, Seoul (KR);
Yeong-Kyeong SEONG, Yongin-si
(KR); **Back-Hwan CHO**, Seoul (KR);
Min-Woo LEE, Seoul (KR)(73) Assignees: **SAMSUNG LIFE WELFARE
FOUNDATION**, Seoul (KR);
**SAMSUNG ELECTRONICS CO.,
LTD.**, Suwon-si (KR)

(57)

ABSTRACT

An apparatus and a method for combining three-dimensional ultrasound images are provide. The method involves obtaining a plurality of three-dimensional ultrasound image data that corresponds to a Region of Interest (ROI); detecting one or more landmarks, using a parameter for detection; outputting the detection result and receiving a response from a user; registering each of one or more selected landmarks as link information according to a received response from the user; and generating a combined three-dimensional ultrasound image by combining at least two pieces of three-dimensional ultrasound image data using at least one of the one or more selected landmarks registered as the link information, wherein the at least two pieces of three-dimensional ultrasound image data commonly comprise the at least one of the one or more selected landmarks.

(21) Appl. No.: **14/325,764**(22) Filed: **Jul. 8, 2014**(30) **Foreign Application Priority Data**

Dec. 11, 2013 (KR) 10-2013-0154050

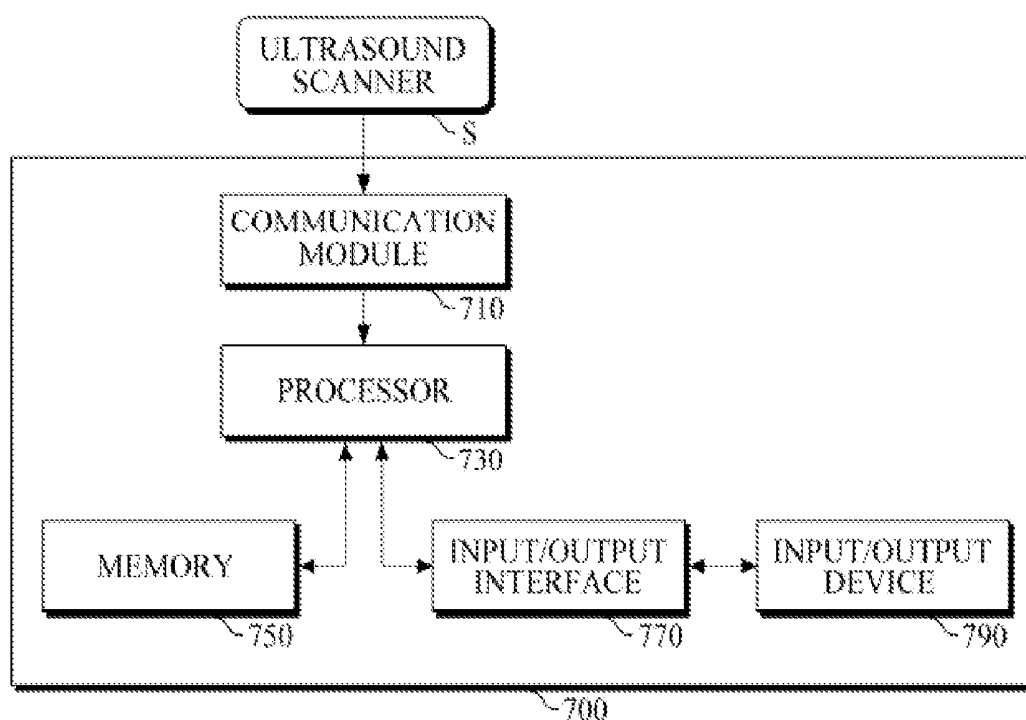
Publication Classification(51) **Int. Cl.***A61B 8/08* (2006.01)*G06T 7/40* (2006.01)

FIG. 1

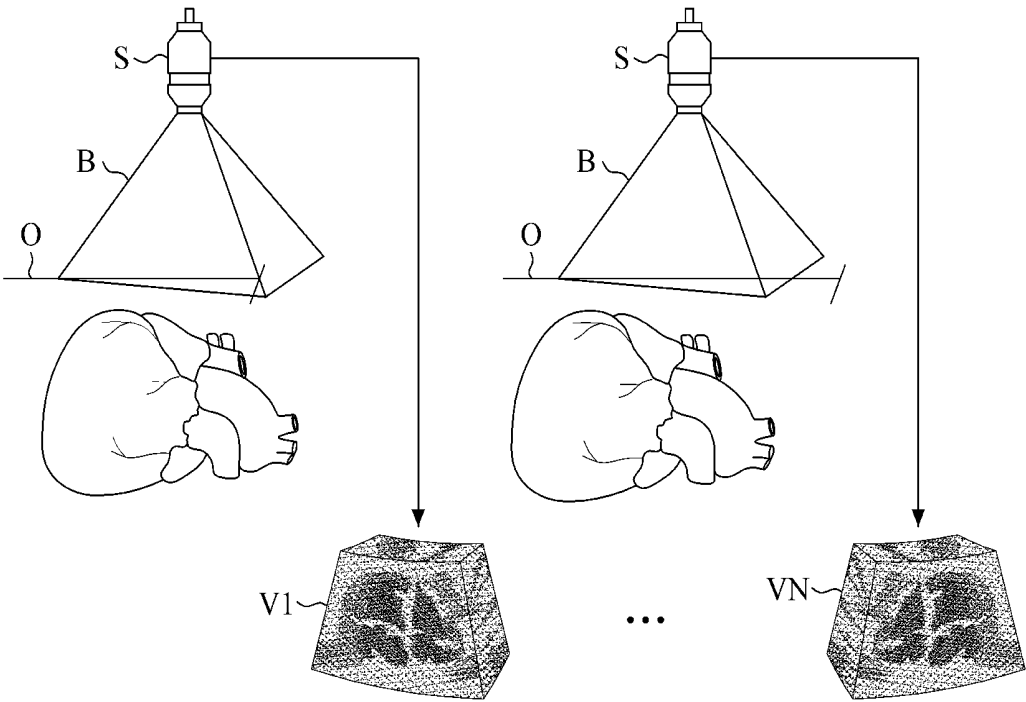


FIG. 2

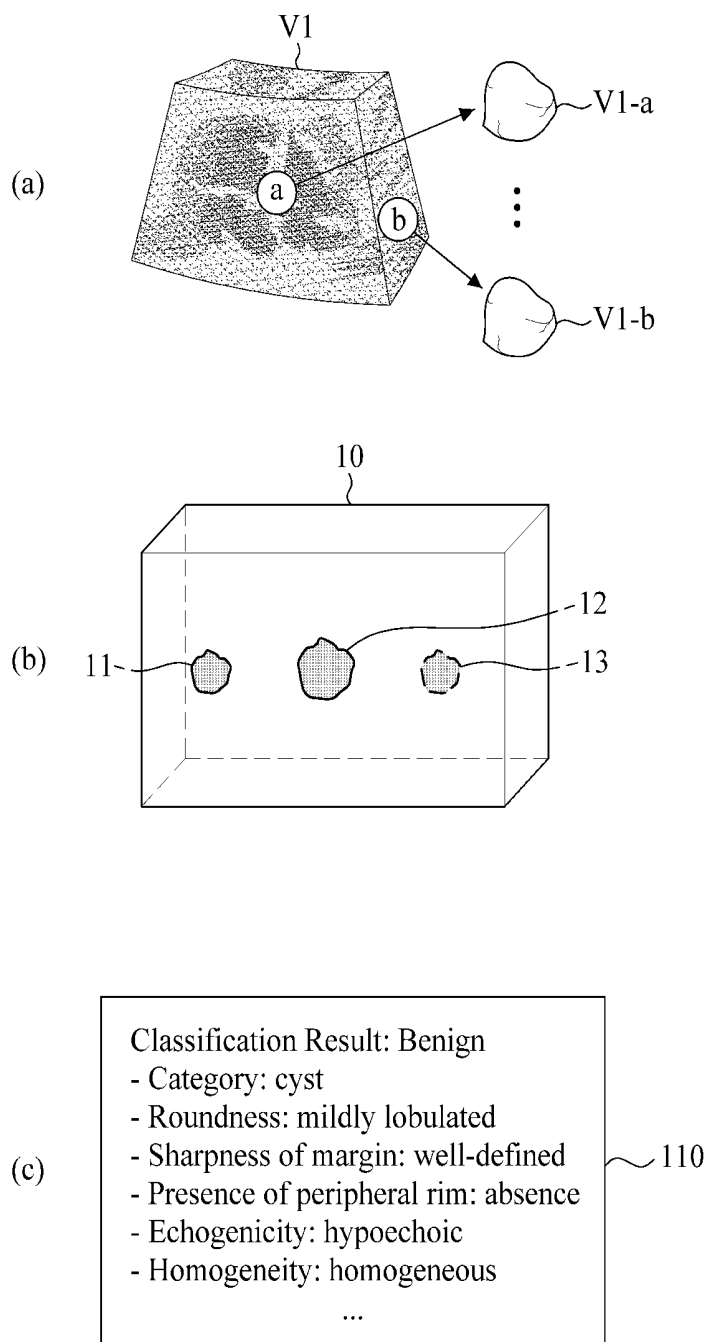


FIG. 3

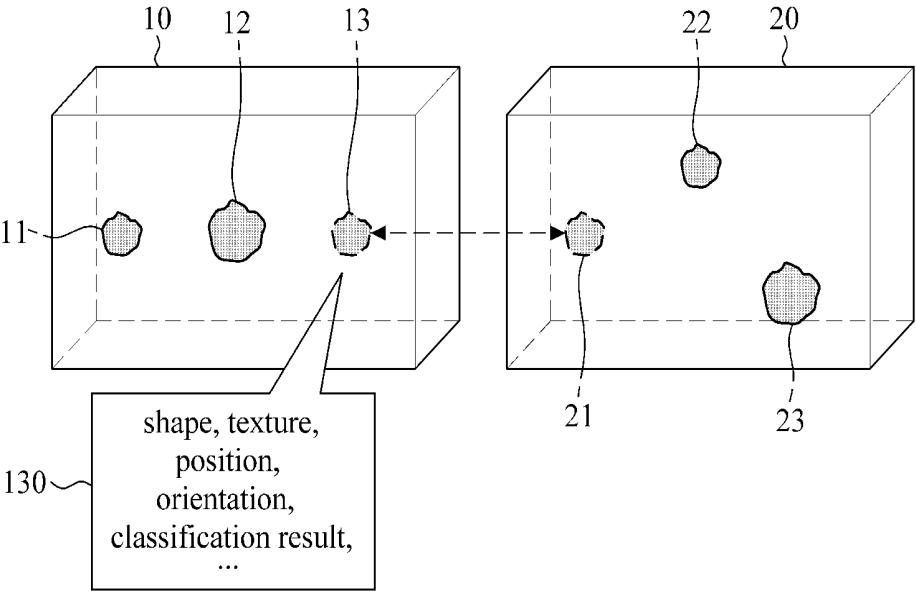


FIG. 4

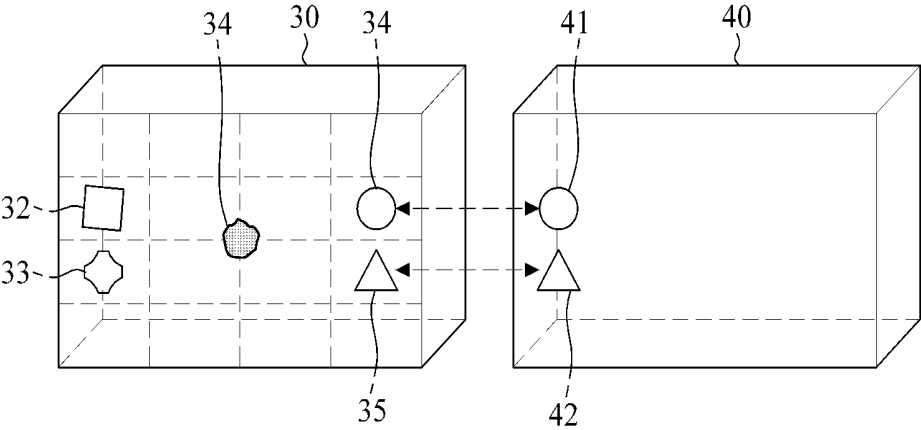


FIG. 5

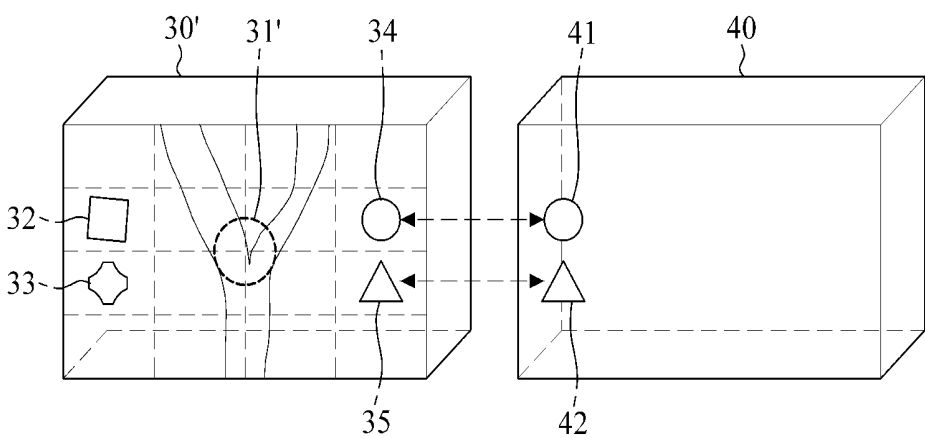


FIG. 6

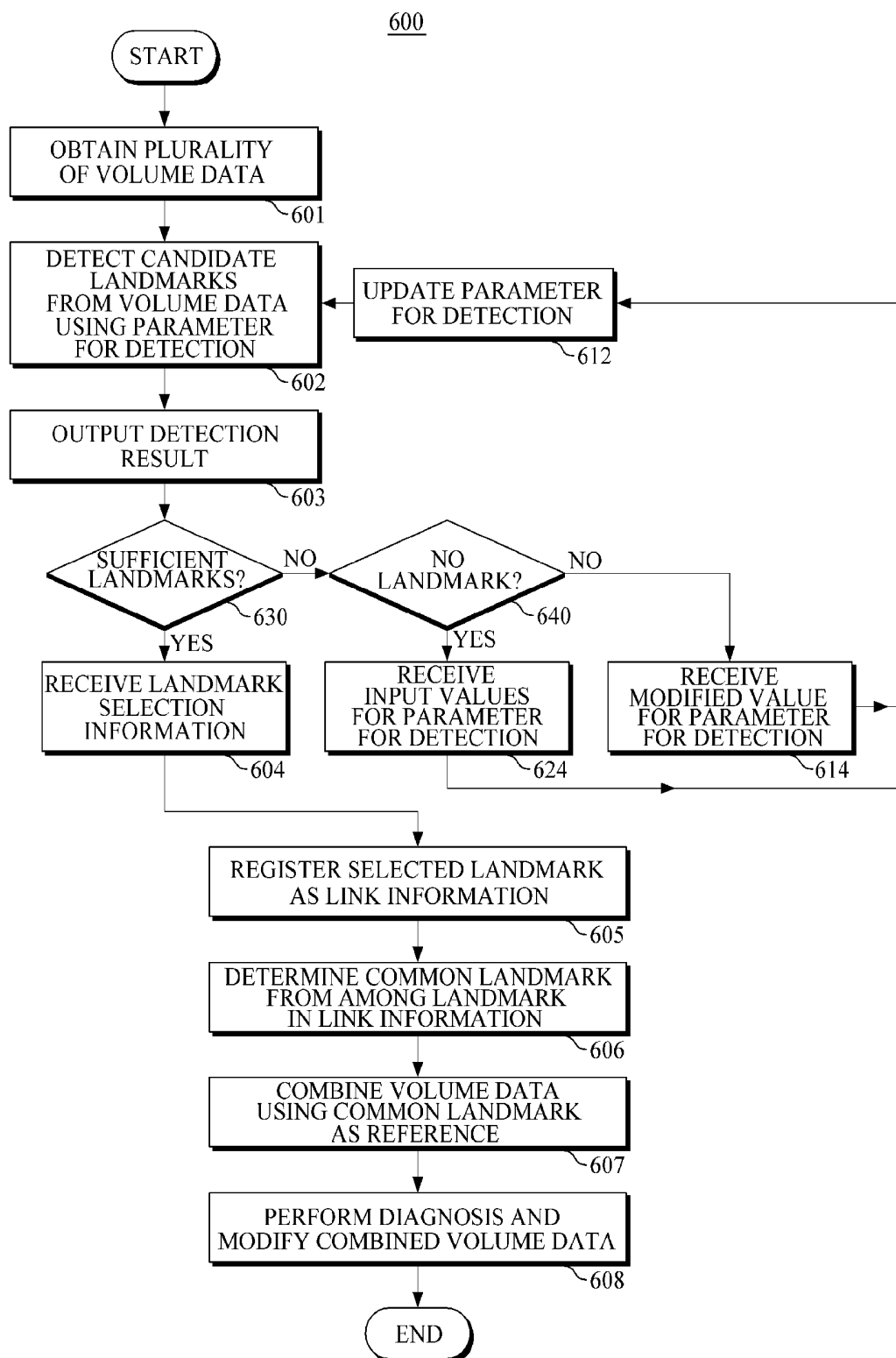
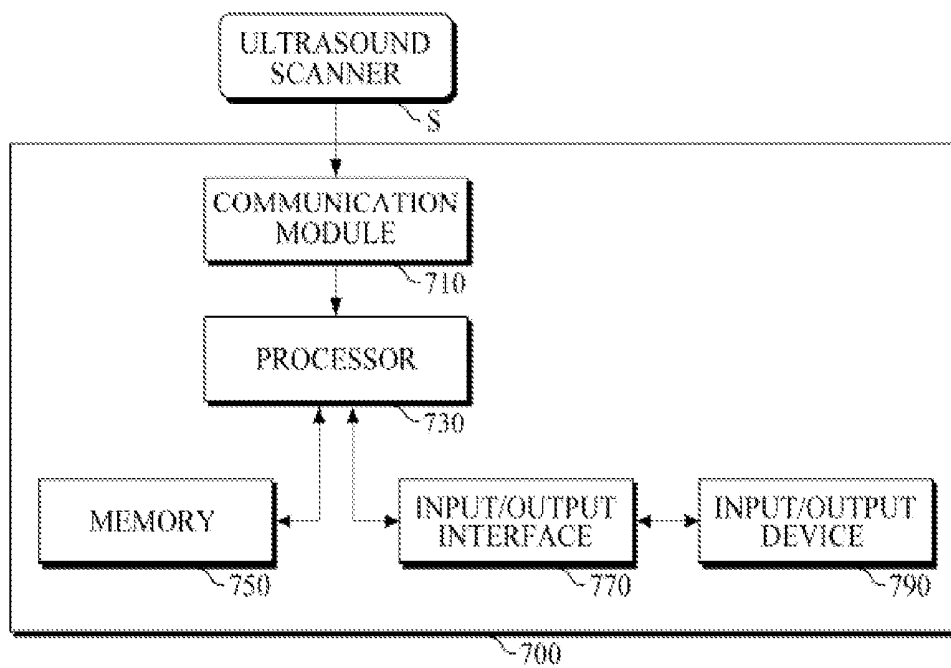


FIG. 7



APPARATUS AND METHOD FOR COMBINING THREE DIMENSIONAL ULTRASOUND IMAGES

CROSS-REFERENCE TO RELATED APPLICATION(S)

[0001] This application claims the benefit under 35 USC 119(a) of Korean Patent Application No. 10-2013-0154050 filed on Dec. 11, 2013, in the Korean Intellectual Property Office, the entire disclosure of which is incorporated herein by references for all purposes.

BACKGROUND

[0002] 1. Field

[0003] The following description relates to an apparatus and a method of combining three-dimensional (3D) ultrasound images in order to obtain a combined 3D ultrasound image.

[0004] 2. Description of Related Art

[0005] Ultrasound imaging is a technology related to transmitting inaudible high frequency sound waves having a frequency between 20 kHz and 150 MHz into an object and visualizing the internal structure of the object based on the waves reflected off from the internal structure of the object. Ultrasound image diagnosis techniques are classified into various modes according to how an image is displayed to the user. For example, brightness mode (B-mode) image diagnosis technique displays two-dimensional gray images that are used for general ultrasound diagnosis. Furthermore, an ultrasonic phased array transducer has two-dimensionally arranged elements that are lineally arranged therein for generating two-dimensional images; such an ultrasonic phased array transducer may steer or focus an ultrasonic beam. As a result, information regarding different section layers is obtained, and a three-dimensional image can be obtained by combining information regarding the different slices into one image. In addition, a real-time three-dimensional image (or four-dimensional image) may be realized, if the slices are combined substantially in real time.

[0006] However, due to a limited spatial range for capturing an ultrasound image, it is almost impossible to fully capture a Region of Interest (ROI) by one scan. For this reason, the same ROI is scanned at different locations, and a plurality of ultrasound images that partially overlap with each other are obtained. To put it simply, for accurate and thorough diagnosis on an ROI, a plurality of ultrasound images are analyzed, and the analyzing of each of the ultrasound images that belongs to the same ROI and the bringing about of an integrated and accurate diagnosis result therefrom are complicated and require expertise.

[0007] For example, a method for combining three-dimensional ultrasound images including a plurality of different special areas may involve comparing all or some of the pixels of a plurality of slices included in the three-dimensional ultrasound images with reference to locations and directions of the pixels. In this example, all the pixels/voxels of the three-dimensional images are compared with each other in order to combine the images; thus, a large amount of computation must be performed, requiring the use of a high-performance computing device and the consumption of a long processing time for performing the computation. Further, in an example in which a method for combining three-dimensional images by extracting characteristic shapes from the images and com-

paring the extracted shapes with each other is applied, there may be instances in which no characteristic shape, too few characteristic shapes or too many characteristic shapes are found; thus, the process of image combination may turn into a challenge. In yet another example, a method of combining three dimensional images using specific anatomical features (for example, blood vessel and bone) may be used for image combination. In this case, it is hard to interconnect three-dimensional images if an anatomical feature does not exist in each of the three-dimensional images that are being combined.

SUMMARY

[0008] This Summary is provided to introduce a selection of concepts in a simplified form that are further described below in the Detailed Description. This Summary is not intended to identify key features or essential features of the claimed subject matter, nor is it intended to be used as an aid in determining the scope of the claimed subject matter.

[0009] In one general aspect, a method for combining a plurality of three-dimensional ultrasound image data, involving: obtaining a plurality of three-dimensional ultrasound image data that corresponds to a Region of Interest (ROI); detecting one or more landmarks, using a parameter for detection, the one or more landmarks each comprising at least one feature distinct from surroundings thereof; outputting the detection result and receiving a response from a user; registering each of one or more selected landmarks as link information according to a received response from the user; and generating a combined three-dimensional ultrasound image by combining at least two pieces of three-dimensional ultrasound image data using at least one of the one or more selected landmarks registered as the link information, wherein the at least two pieces of three-dimensional ultrasound image data commonly include the at least one of the one or more selected landmarks.

[0010] The plurality of three-dimensional ultrasound image data may partially overlap with each other and may correspond to different locations of the ROI, and the detecting may comprise: performing diagnosis on each of the plurality of three-dimensional ultrasound image data using the parameter for detection, and detecting one or more landmarks based on the diagnosis, the one or more landmarks each having volume greater than a predetermined reference value.

[0011] The method may further involve: updating the parameter for detection; performing diagnosis on the combined three-dimensional ultrasound image data using the updated parameter for detection; and modifying the combined three-dimensional image data based on the diagnosis result.

[0012] The outputting of the detection result and the receiving of the response from the user may involve outputting one or more candidate landmarks as the detection result, and waiting to receive, as the response from the user, information that indicates one or more landmarks selected by the user from among the one or more candidate landmarks.

[0013] The outputting of the detection result and the receiving of the response from the user may involve: outputting one or more candidate landmarks as the detection result, and waiting to receive a modified parameter for detection as the response from the user; updating a parameter for detection based on the modified parameter for detection; and re-outputting one or more candidate landmarks after performing diagnosis on each of the plurality of three-dimensional ultrasound

image data using the updated parameter for detection, and waiting to receive, as the response from the user, information that indicates one or more landmarks selected by the user from among the one or more candidate landmarks.

[0014] The outputting of the detection result and the receiving of the response from the user may involve: outputting, as the detection result, information indicating that no candidate landmark is detected, and waiting, as the response from the user, a new parameter for detection; updating the parameter for detection based on the new parameter for detection; and re-outputting one or more candidate landmarks after performing diagnosis on each of the plurality of three-dimensional ultrasound image data using the updated parameter for detection, and waiting, as the response from the user, information that indicates one or more landmark selected by the user from among the one or more candidate landmarks.

[0015] The parameter for detection may involve at least one of a classification result which indicates either benignity or malignancy, category, roundness, sharpness of margin, presence of peripheral rim, echogenicity, and homogeneity.

[0016] The parameter for detection may involve information that relates to at least one of an entire shape, texture of an outer surface and posture.

[0017] The parameter for detection may further involve link information that relates to at least one of anatomical features, such as a blood vessel and bone, which are located close to a landmark.

[0018] In another general aspect, an apparatus for combining three-dimensional ultrasound image includes: a processor configured to obtain a plurality of partially-overlapping three-dimensional ultrasound image data corresponding to different locations of a Region of Interest (ROI), and to detect from each of the plurality of three-dimensional ultrasound image data one or more landmarks using a parameter for detection, the one or more landmarks each comprising at least one feature distinct from surroundings thereof; an input/output device configured to output a detection result and to receive a response from a user, wherein the processor is configured to register the one or more selected landmarks as link information based on the received response, and to generate a combined three-dimensional ultrasound image by combining at least two pieces of three-dimensional ultrasound image data using at least one of the one or more selected landmarks registered as the link information, the at least two pieces of three-dimensional ultrasound image data commonly comprising the at least one of the one or more selected landmarks.

[0019] The plurality of three-dimensional ultrasound image data may partially overlap with each other and may correspond to different locations of the ROI, and the processor may be configured to perform diagnosis on each of the plurality of three-dimensional ultrasound image data using the parameter for detection and detects the one or more landmarks based on the diagnosis, the one or more landmarks each having volume greater than a predetermined reference value.

[0020] The processor may be further configured to perform diagnosis on the combined three-dimensional ultrasound image data using an updated parameter for detection and to modify the combined three-dimensional image data based on the diagnosis result.

[0021] The input/output device may be configured to output the detection result and to receive the response from the user by: outputting one or more candidate landmarks as the

detection result, and waiting to receive, as the response from the user, information that indicates one or more landmarks selected by the user from the one or more candidate landmarks.

[0022] The input/output device may be configured to output the detection result and to receive the response from the user by: outputting one or more candidate landmarks as the detection result, and waiting to receive a modified parameter for detection as the response from the user, the parameter for detection being updated based on the altered parameter for detection, and re-outputting one and more candidate landmarks after performing diagnosis on the combined three-dimensional ultrasound image data using the updated parameter for detection, and waiting, as the response from the user, information that indicates one or more landmarks selected by the user from the one or more re-output candidate landmarks.

[0023] The input/output device may be configured to output the detection result and to receive the response from the user by: outputting the detection result indicating that no landmark is detected, and waiting to receive a new parameter for detection as the response from the user, the parameter for detection being updated based on the new parameter for detection, and outputting one or more candidate landmarks after re-performing diagnosis on the combined three-dimensional ultrasound image data using the updated parameter for detection, and waiting, as the response from the user, information that indicates one or more landmark selected by the user from among the one or more candidate landmarks.

[0024] The parameter for detection may include information relating to at least one of a classification result that indicates either benignity or malignancy, category, roundness, sharpness of margin, presence of peripheral rim, echogenicity, and homogeneity.

[0025] The parameter for detection may include at least one of shape, texture of outer surface and orientation.

[0026] The parameter for detection may further include link information relating to at least one of anatomical features, such as blood vessel and bone, which are close the landmark.

[0027] In another general aspect, there is provided a non-transitory computer readable medium storing instructions configured to cause a computing device to perform the above described method.

[0028] Other features and aspects will be apparent from the following detailed description, the drawings, and the claims.

BRIEF DESCRIPTION OF THE DRAWINGS

[0029] FIG. 1 is a diagram illustrating an example of an operation of obtaining three-dimensional ultrasound images that are used in a method for combining three-dimensional ultrasound images to obtain a combined three-dimensional ultrasound image.

[0030] FIG. 2 is a diagram illustrating an example of an operation of extracting one or more landmarks from each three-dimensional ultrasound image in a method for combining three-dimensional ultrasound images.

[0031] FIG. 3 is a diagram illustrating an example of an operation of discovering one common landmark from two three-dimensional ultrasound images using a well-known lesion in a method for combining three-dimensional ultrasound images.

[0032] FIG. 4 is a diagram illustrating an example of an operation of extracting a common landmark from two three-dimensional ultrasound images based on a feature selected by

a user, such as a similar or virtual lesion, in a method for combining three-dimensional ultrasound images.

[0033] FIG. 5 is a diagram illustrating an example of an operation of extracting a common landmark from two three-dimensional ultrasound images additionally using anatomical features of the two three-dimensional ultrasound images in a method for combining three-dimensional ultrasound images.

[0034] FIG. 6 is a flow chart illustrating an example of a method for combining three-dimensional ultrasound images.

[0035] FIG. 7 is a block diagram illustrating an example of an apparatus for combining three-dimensional ultrasound images, that apparatus being capable of implementing a method for combining three-dimensional ultrasound images according to an example of the present disclosure.

[0036] Throughout the drawings and the detailed description, unless otherwise described or provided, the same drawing reference numerals will be understood to refer to the same elements, features, and structures. The drawings may not be to scale, and the relative size, proportions, and depiction of elements in the drawings may be exaggerated for clarity, illustration, and convenience.

DETAILED DESCRIPTION

[0037] The following detailed description is provided to assist the reader in gaining a comprehensive understanding of the methods, apparatuses, and/or systems described herein. However, various changes, modifications, and equivalents of the systems, apparatuses and/or methods described herein will be apparent to one of ordinary skill in the art. The progression of processing steps and/or operations described is an example; however, the sequence of and/or operations is not limited to that set forth herein and may be changed as is known in the art, with the exception of steps and/or operations necessarily occurring in a certain order. Also, descriptions of functions and constructions that are well known to one of ordinary skill in the art may be omitted for increased clarity and conciseness.

[0038] The features described herein may be embodied in different forms, and are not to be construed as being limited to the examples described herein. Rather, the examples described herein have been provided so that this disclosure will be thorough and complete, and will convey the full scope of the disclosure to one of ordinary skill in the art.

[0039] Hereinafter, an example of an apparatus for combining three-dimensional (3D) ultrasound image data and an example of a method for combining 3D ultrasound image data are provided. FIG. 6 is a flow chart that illustrates an example of the method in detail. FIGS. 1 to 5 are schematic views to provide intuitive recognition of each operation of the flow chart illustrated in FIG. 6. FIG. 7 illustrates an example of an apparatus that employs a method for combining 3D ultrasound image data.

[0040] Referring to FIG. 6, a method 600 for combining 3D ultrasound image data involves operation 601 of acquiring a plurality of volume data, operation 602 of detecting one or more candidate landmarks using a parameter for detection, operation 603 of outputting a detection result, operation 604, 614 and 624 of receiving information from a user input, operation 612 of updating the parameter for detection, operation 605 of registering link information, operation 606 of determining a common landmark, operation 607 of combining the plurality of volume data, and operation 608 of diagnosing and modifying a combined volume data.

[0041] In operation 601, a plurality of volume data is obtained. The plurality of volume data divides a spatial Region of Interest (ROI) or presents the spatial ROI three-dimensionally at different locations. Herein, each piece of 'volume data' refers to a piece of 3D ultrasound image data obtained through scanning or imaging performed by a 3D ultrasound scanner.

[0042] In operation 602, in order to detect one or more candidate landmarks, diagnosis is performed on each of the obtained pieces of volume data based on a parameter for detection. In this example, a diagnosis may refer to an analysis of the data for detection of lesions or lack of lesions, or for detection of lesion like features or distinctive features such as types of tissues, vessels, nodes, bones other than a lesion.

[0043] In operation 603, the detection result is output through a monitor or a display device.

[0044] In operation 604, 614 and 624, a user checks an output detection results, and responds to the detected result in various ways. The embodiment illustrated in FIG. 6, a user is able to input information in three different ways. However, the embodiment is merely provided as an example, and aspects of the present disclosure are not limited thereto.

[0045] In operation 612, a parameter for detection is updated. The parameter for detection is used to detect one or more landmarks based on information input by the user.

[0046] In operation 605, one or more selected landmarks are each registered. The one or more selected landmarks are detected based on the information input by the user, as link information to be used for combining volume data.

[0047] In operation 606, a landmark is identified among landmarks that are commonly included in at least two pieces of volume data and are registered as link information. In addition, the identified landmark is determined as a common landmark.

[0048] In operation 607, a combined volume data is generated by combining a plurality of volume data using the common landmark.

[0049] In operation 608, diagnosis is performed on the combined volume data using a used parameter for detection, and the combined volume data is modified based on the diagnosis result.

[0050] Hereinafter, each operation of the method 600 for combining 3D ultrasound image data is described in detail.

[0051] FIG. 1 is a schematic view illustrating an example of operation 601 of obtaining a plurality of volume data that present the same spatial ROI three-dimensionally from different locations. The operation 601 may correspond to the operation 601 illustrated in FIG. 6. Each piece of volume data may be a piece of three-dimensional ultrasound image data that is obtained by using an ultrasound image diagnosis technique for the medical diagnosis of a human body's organ. In FIG. 1, heart is illustrated as an example of the organ, and an example of a procedure of obtaining volume data of the heart is illustrated. An object O of which volume data is obtained may be organs, such as fetus, breast, uterus, heart and the like. The ultrasound image diagnosis apparatus includes a scanner S in which a 3D ultrasound converter is embedded. The ultrasound image diagnosis apparatus puts the scanner S to contact with the surface of a human body, and scans by forming an ultrasound beam B of a particular frequency according to an imaging location or purpose. As a result, the ultrasound image diagnosis apparatus may obtain a plurality of volume data (V1, . . . , VN) regarding a single ROI.

[0052] Each of the plurality of volume data ($V_1, \dots, V_N$) has the same volume size, and partially overlaps with one other. In addition, each of the plurality of volume data ($V_1, \dots, V_N$) may include data of a different spatial region that other volume data do not cover. Further, each of the plurality of volume data ($V_1, \dots, V_N$) may include segmented information that describes only a part of an object, rather than the entire object, for which a consistent medical diagnosis is required. Thus, for the consistent medical diagnosis, in one example, a plurality of volume data is combined into a combined volume data regarding the same spatial ROI. By combining a plurality of volume data, which spatially segment the same spatial ROI, into an integrated combined volume data, it is possible to reduce the instances of failing to detect a lesion. On the other hand, when the diagnosis is performed on the plurality of volume data separately, some lesions may not be detected. For example, a lesion may span over more than one segment of volume data, making its detection difficult from analyzing the individual segment. The combined volume data may make it easy to compare diagnostic image data with different modalities, such as CT images and MRI images, with each other.

[0053] In FIG. 2, an example of operation 602 of detecting some data from each piece of volume data as a portion, that is, a landmark, is illustrated. The landmark has volume greater than a predetermined reference value and includes at least one feature distinct from the surroundings thereof. The landmark is detected using a parameter for detection.

[0054] Referring to FIG. 2, an example of a procedure of analyzing each piece of volume data and identifying a distinct portion of each piece of volume data as a landmark is illustrated. As illustrated in FIG. 2 (a), unique features may be found at the locations of VI-a and VI-b, so that the found features may be identified as a landmark VI-a and a landmark VI-b, respectively. Although FIG. 2 (a) demonstrates an example in which two landmarks are found, there is no limitation on the number of found landmarks. In some instances, no landmark may be found.

[0055] In the example illustrated in FIG. 2 (b), identified landmarks 11, 12 and 13 are displayed within volume data 10. Each of the identified landmarks 11, 12 and 13 may be identified based on identification information 110 (See FIG. 2 (c)). In other words, each landmark is associated with different identification information.

[0056] Different landmarks may belong to the same category (e.g., cyst), and each of the landmarks belonging to the same category may have different shape, size and location. Therefore, only one identical landmark exists within a piece of volume data, and it is impossible for one piece of volume data to include two or more identical landmarks.

[0057] However, a plurality of volume data may include one or more identical landmarks. A plurality of volume data including an identical landmark indicates that each of a plurality of volume data overlaps with one other at a location of the identical landmark. Therefore, it is possible to combine a plurality of volume data into a combined volume data using the identical landmark as a reference.

[0058] A 'landmark' used hereinafter refers to three-dimensional image data, which is greater than a predetermined reference value, such as 0.1 cm^3 or 1 cm^3 and composes a part of volume data including the three-dimensional image data. Properties of voxels composing the landmark are different from those of voxels in the surroundings of the landmark.

Thus, the landmark and the surroundings thereof may be distinguished from each other according to voxel properties.

[0059] According to an example, a landmark may indicate a well-known lesion. A lesion may include a malignant or benign tumor, but aspects of the present disclosure are not limited thereto. In addition, according to another example, a landmark is not limited as a lesion. That is, a landmark may not be a lesion as long as it has properties that make the landmark distinct from its surroundings in the corresponding volume data. For example, a landmark may be a well-known lesion or a similar/virtual lesion designated by a user. In addition, a landmark may be a feature that can be found at a specific location in a piece of volume data and distinct from the surroundings thereof, and the feature may have nothing to do with a lesion.

[0060] A parameter for detection is reference information that is used for detecting a landmark. The parameter for detection may be a parameter that is previously stored in a storage device, such as a memory in a computer, or a parameter that is updated by a user from an existing parameter or based on a new input from a user.

[0061] A parameter for detection may be reference information that is useful for detecting a unique lesion distinct from the surroundings as a landmark. For example, the parameter may include information relating to at least one of a classification result that indicates either benignity or malignancy, category, roundness, sharpness of margin, presence of peripheral rim, echogenicity, and homogeneity of the landmark. The fact that a parameter for detection includes information relating to a classification result that indicates malignancy or benignity indicates that the parameter itself includes information indicating either benignity or malignancy or that the parameter includes more specific and analytic information regarding the classification result, such as brightness or saturation of a pixel. Such a parameter for detection may be information that is predetermined with respect to a well-known lesion.

[0062] Furthermore, a parameter for detection may be information that is useful for detecting a unique landmark that is not substantially a lesion, but something that is similar to or may be assumed to be a lesion. For example, the parameter may include link information relating to at least one of shape, texture of outer surface and orientation of the landmark. Such a parameter may be used in the event that it is difficult to detect a landmark using well-known lesion information or in the event that only few landmarks are found so that it is a challenge to combine a plurality of volume data into a combined volume data; however, aspects of the present disclosure are not limited thereto. For example, it may be understood that information relating to at least one of shape, texture of outer surface and orientation of the landmark may be used as a parameter for detection, regardless of whether a lesion exist or not.

[0063] A parameter for detection, which is used for detecting a landmark, may further include link information relating to at least one of anatomical features, such as blood vessel or bone, in addition to information relating to the lesion and/or the similar/virtual lesion. The anatomic features are information that helps improve accuracy of combination of volume data, so that the anatomic features may be utilized as a landmark or a reference for verifying the accuracy of combination.

[0064] Referring back to FIG. 6, a candidate landmark is detected by analyzing/diagnosing each piece of volume data

in **602**, and then a detection result is output, for example, to a display device in **603**. After checking the output detection result, a user may input an appropriate response through an input device, such as a keyboard, a mouse and a touch panel, in **604**, **614** or **624**.

[0065] The output detection result may include various types of content. For example, the detection result may include a sufficient number of landmarks that are worth of being selected. The “sufficient number of landmarks” may indicate that there may be one or more landmarks that are worth of being used for combining volume data. In still another example, the detection result may not include a sufficient number of landmarks. In yet another example, the detection result may not include any detected landmark. In the above examples, an operation of detecting a landmark needs to be repeated using a modified or new parameter for detection, rather than using an existing parameter for detection.

[0066] According to an embodiment, a user makes a determination as to whether an output detection result includes a sufficient number of landmarks, whether an output detection result includes landmarks that are not sufficient in numbers but worth of being selected, and/or whether an output detection result does not include any landmark that is worth of being selected, if at all. In other words, a user may manually make an important determination relating to a detected landmark, which may be included in link information necessary for combining volume data. The whole process is not carried out automatically, and a part of the process is carried out manually. Thus, the above-described method for combining three-dimensional ultrasound image may be a semi-automatic method. Compared with a fully-automatic method, such a semi-automatic method needs to be performed by a more skilled person. However, it has a beneficial effect of significantly reducing reference information and calculation, which are necessary for making a determination.

[0067] Referring to FIG. 6, operation **603** of outputting a detection result is followed by operations **630** and **640** in which a user makes a determination as to the output detection result by analyzing the detection result in operation **630** and **640**, and then operation of receiving a response from the user may be carried out. In FIG. 6, operations **630** and **640** of making a determination may include operation **630** of making a determination as to whether the output detection result includes a sufficient number of landmarks that are worth of being selected and operation **640** of making a determination as to whether the output detection result includes landmarks that are not sufficient in numbers but worth of being selected.

[0068] In one example, operation of receiving a response from a user corresponds to an example in which the output detection result includes a sufficient number of landmarks. In other words, it corresponds to a case in which a sufficient number of landmarks are detected by a parameter for detection during operation **602**, and one or more candidate landmarks are output for a user as a detection result in operation **603**. In operation **630**, the user may make a determination of YES, and then select a suitable candidate landmark from among the one or more displayed candidate landmarks. Then, a response, which includes the suitable landmark selected by the user as link information, is received from the user in operation **604**.

[0069] In another example, operations **614** and **624** of receiving a user response correspond to an example in which the output detection result does not include any landmark.

That is, operations **614** and **624** may correspond to an event in which no landmark is detected in operation **602** or a sufficient number of landmarks is not detected in operation **602**. In this event, it is necessary to modify or change the parameter for detection, which was used in operation **602**. In operation **630** of making a determination as to whether the output detection result includes a sufficient number of landmarks worth of being selected, a user may make a “NO” determination, and then make a “YES” or “NO” determination in operation **640** of making a determination as to whether the output detection result includes landmarks that are not sufficient in numbers but worth of being selected. When making a “YES” determination in operation **640**, the user may input a modified value to modify an existing parameter for detection. In this event, an operation of receiving a user response may be carried out as operation **614** of receiving a modified value to modify the existing parameter for detection. Alternatively, when making a “NO” determination in operation **640**, the user may input a value to designate a new parameter for detection, rather than an existing parameter for detection. In this event, operation of receiving a user response may be carried out as operation **624** of receiving an input values for a new parameter for detection.

[0070] In the event that the operation of receiving a user response is performed through operation **614** of modifying an existing parameter for detection, the user may input information used to modify a parameter for detection, and the modified parameter may be used in operation **602**. In this process, the parameter for detection is updated according to the user’s input in operation **612**. Then, in operation **602**, one or more candidate landmarks are re-detected using the updated parameter, and in operation **603**, the new detection result is output. Thus, operations **602** and **603** are repeated. Operation **614**, **612**, **602** and **603** may be performed repeatedly until a sufficient number of candidate landmarks is detected and a user selects one or more suitable landmark from among the detected candidate landmarks in operation **604**.

[0071] Alternatively, in the event that operation of receiving a user response is operation **624** of receiving a new parameter for detection, the user may input information on a new parameter for detection, rather than the parameter for detection that was used in operation **602**. Accordingly, the parameter for detection may be updated according to the user’s input in operation **612**. Then, operation **602** of re-detecting one or more candidate landmarks using the updated parameter for detection and operation of **603** of outputting the detection result may be performed repeatedly. The above-described operations may be performed repeatedly until a sufficient number of candidate landmarks is detected and a user selects one or more suitable landmarks from among the detected candidate landmarks in operation **604**.

[0072] In the event that the user selects suitable landmarks from among the output candidate landmarks in **604**, the selected landmarks are associated with respective identification information **110** and **130**, for example, as illustrated in FIGS. 2 and 3. The identification information **110** and **130** are ancillary data describing features of respective landmarks that are associated therewith. The identification information **110** and **130** may be used as reference information to determine whether landmarks detected from a different piece of volume data are identical to each other. In operation **605**, a landmark associated with identification information may be registered as link information, which may be used when combining volume data.

[0073] After one or more landmarks are detected from each piece of volume data and registered as link information, a combined volume data is generated by connecting the volume data in **607**. In this case, identification information of each of the registered landmarks is compared with that of another registered landmark, and at least two pieces of volume data that commonly include at least one of the registered landmarks, may be combined into a combined volume data using the registered landmark shared therebetween as reference.

[0074] FIGS. **3** to **5** illustrate examples of methods of connecting volume data to each other.

[0075] For example, FIG. **3** demonstrates two pieces of volume data **10** and **20**. The volume data **10** includes lesions, such as tumor, as landmarks **11**, **12** and **13**, respectively. The volume data **20** includes lesions, such as tumor, as landmarks **21**, **22** and **23**. In FIG. **3**, the landmark **13** that is the farthest right-side landmark of the volume data **10** and the landmark **21** that is the farthest left-side landmark of the volume data **20** are identified as the same landmark. In this example, the two pieces of volume data **10** and **20** may be combined with reference to the common landmarks **13** and **21**.

[0076] In this example, whether the landmark **13** and the landmark **21** are identical to each other may be determined by comparing contents of identification information **130** that is associated with the landmarks **13** and **21**. That is, whether the two landmarks are identical to each other is determined according to whether contents of identification information of one landmark are the same as those of the other landmark. The contents of identification information may be determined in a similar way of determining the above-discussed 'parameter for detection', and may include similar contents as those of the 'parameter for detection.'

[0077] The example illustrated in FIG. **4** demonstrates two pieces of volume data **30** and **40**. The volume data **30** includes one landmark **31** that is detected using lesion information as a parameter for detection. The volume data **30** includes landmarks **32**, **33**, **34** and **35** that are detected, not using existing lesion information, but using a parameter for detection, which is updated based on information modified or newly input by a user. The landmarks **32**, **33**, **34** and **35** are associated therewith respective unique identification information. Based on the identification information, the landmarks **34** and **35** may be identified to be the same as the landmarks **41** and **42** existing within the volume data **40**. That is, just like the landmarks **34** and **35**, the landmarks **41** and **42** are detected using the parameter for detection, which is updated based on information changed or modified by the user. Accordingly, in the example illustrated in FIG. **4**, the two pieces of volume data **30** and **40** may be combined into a combined volume data using the identical landmarks **34** and **41** and the landmarks **35** and **42** as reference, wherein the landmarks **34** and **42** are identified to be identical to each other and the landmarks **35** and **42** are identified to be identical to each other.

[0078] In addition, the example illustrated in FIG. **5** demonstrates two pieces of volume data **30'** and **40** that include no lesion. In the event there is no lesion, other features may be used as a landmark. For example, an anatomic feature may be used as a landmark **31'**, features of a similar/virtual lesion may be used as landmarks **32**, **33**, **34** and **35**, and information on a location of an anatomical feature, such as a blood vessel and bone, may be used as a landmark. In this example, the two pieces of volume data **30'** and **40** may be combined by using as reference the landmarks **34** and **41**, which are identified to

be identical to each other, and the landmarks **35** and **42**, which are identified to be identical each other.

[0079] Then, in operation **608**, diagnosis is automatically performed on the combined volume data, and the combined volume data is modified. For example, diagnosis is performed on a combined three-dimensional image data (a combined volume data) using parameters for detection, which were used for each piece of three-dimensional image data (each piece of volume data) contributing to the generation of the combined three-dimensional image data. Based on the diagnosis result, the combined three-dimensional image data may be modified.

[0080] As described above, the three-dimensional image combination technique for providing a combined image data from a plurality of three-dimensional ultrasound image data is performed by detecting a common landmark between at least two pieces of ultrasound image data, by generating a combined image data using the detected common landmark, and by helping a user to adjust a parameter used in detecting the common landmark. Accordingly, it is possible to reduce calculation necessary for combining ultrasound image data while avoiding the scenarios in which no landmark, too few landmarks or too many landmarks are extracted. Therefore, this example ensures that a combined image data will be generated from a plurality of three-dimensional ultrasound image data. In addition, diagnosis is automatically performed on the whole combined ultrasound image data using parameters that are used in generating the combined ultrasound image data, so accuracy of connecting the generated combined ultrasound image data is guaranteed. Furthermore, whether any lesion is omitted may be automatically checked as well.

[0081] The above-described examples and methods may be implemented by a software program driven by a computing device. In this case, the computing device may be an exclusive hardware device, various commercially-available standalone devices that may include desktop, laptop, notepad, tablet and smartphone, and a distributed computing system including a plurality of computing devices which operate through cooperation via a communication network. However, aspects of the present disclosure are not limited thereto. The software program includes a firmware, a module, a component, a routine, an application and the like, which are installed in a computing device to perform a designed function, but aspects of the present disclosure are not limited thereto.

[0082] As another aspect of the present disclosure, FIG. **7** demonstrates an example of an apparatus for combining three-dimensional images, which may include general components of a computing device that is capable of communication with a user.

[0083] Referring to FIG. **7**, an apparatus **700** for combining three-dimensional ultrasound images includes a communication module **710**, a processor **730**, a memory **750**, an input/output interface **770** and an input/output device **790**.

[0084] The communication module **710** is a component that is used to receive a plurality of volume data from an ultrasound scanner **S** and configured to receive data from the ultrasound scanner **S** over LAN, WAN, and wireless/wired communication. Although the apparatus **700** illustrated in the example of FIG. **7** does not include the ultrasound scanner **S**, aspects of the present disclosure are not limited thereto such that the apparatus **700** may include the ultrasound scanner **S**.

[0085] The processor **730** may have the above-described method to be installed and implemented therein. For example,

the processor 730 may include a microprocessor, CPU, programmable ROM, and EEPROM, but aspects of the present disclosure are not limited thereto.

[0086] The memory 750 includes a volatile/non-volatile memory and a removable/non-removable medium. The memory 750 may store an instruction that embodies a software program which implements the above-described method, as well as a parameter for detection, a landmark generated in response to the implementation, and identification information associated with the landmark. The memory 750 may be a non-transitory storage medium, the examples of which include floppy disk, hard disk, solid disk, optical disk, CD, DVD, USB, flash memory, magnetic disk, and magnetic tape; however, aspects of the present disclosure are not limited thereto.

[0087] The input/output device 790 may include an input device by which a user inputs an instruction or information to the processor 730 through the input/output interface 770 of the apparatus 700. An output device that uses the processor 770 outputs information to a user through the input/output interface 770. For example, the input/output device 790 may include a monitor, a display unit, a touch panel, a screen, a speaker, a keyboard, a keypad, a pointing device including a mouse, and a microphone. In one example, the input/output device 790 is a touch panel that outputs information to a user and allows a user to input an instruction. However, aspects of the present disclosure are not limited thereto.

[0088] According to an example, the apparatus 700 may include a computer readable medium that stores instructions that are executable in a computer. The 'computer readable medium' may include a storage medium configured to store an instruction and a signal medium for communication.

[0089] The storage medium may include the memory 750, a cache memory embedded in the processor 730 of FIG. 7, a volatile/non-volatile memory, and a removable/non-removable medium. The signal medium for communication is a medium composed of modulated signals, such as carrier signal, and may include a signal which a computing device uses over wired/wireless communication within a local entity or at a remote entity.

[0090] The methods and/or operations described above may be recorded, stored, or fixed in one or more non-transitory computer-readable storage media that includes program instructions to be implemented by a computer to cause a processor to execute or perform the program instructions. The media may also include, alone or in combination with the program instructions, data files, data structures, and the like. A non-transitory computer-readable storage medium may be any data storage device that is capable of storing the software or instructions and any associated data, data files, and data structures so that they can be read by a computer system or processing device. Examples of a non-transitory computer-readable storage medium include read-only memory (ROM), random-access memory (RAM), flash memory, CD-ROMs, CD-Rs, CD+Rs, CD-RWs, CD+RWs, DVD-ROMs, DVD-Rs, DVD+Rs, DVD-RWs, DVD+RWs, DVD-RAMs, BD-ROMs, BD-Rs, BD-R LTHs, BD-REs, magnetic tapes, floppy disks, magneto-optical data storage devices, optical data storage devices, hard disks, solid-state disks, or any other non-transitory computer-readable storage medium known to one of ordinary skill in the art. Examples of program instructions include machine code, such as produced by a compiler, and files containing higher level code that may be executed by the computer using an interpreter. The described hardware

devices may be configured to act as one or more software modules in order to perform the operations and methods described above, or vice versa. In addition, a computer-readable storage medium may be distributed among computer systems connected through a network and computer-readable codes or program instructions may be stored and executed in a decentralized manner. Also, functional programs, codes and code segments to implement those embodiments may be easily inferred by programmers who are skilled in the related art.

[0091] The various units, modules and methods described above may be implemented using one or more hardware components, one or more software components, or a combination of one or more hardware components and one or more software components. A hardware component may be, for example, a physical device that physically performs one or more operations, but is not limited thereto. Examples of hardware components include microphones, amplifiers, low-pass filters, high-pass filters, band-pass filters, analog-to-digital converters, digital-to-analog converters, and processing devices.

[0092] A software component may be implemented, for example, by a processing device controlled by software or instructions to perform one or more operations, but is not limited thereto. A computer, a computing device, controller, or other control device may cause the processing device to run the software or execute the instructions. One software component may be implemented by one processing device, or two or more software components may be implemented by one processing device, or one software component may be implemented by two or more processing devices, or two or more software components may be implemented by two or more processing devices.

[0093] A processing device may be implemented using one or more general-purpose or special-purpose computers, such as, for example, a processor, a controller and an arithmetic logic unit, a digital signal processor, a microcomputer, a field-programmable array, a programmable logic unit, a microprocessor, or any other device capable of running software or executing instructions. The processing device may run an operating system (OS), and may run one or more software applications that operate under the OS. The processing device may access, store, manipulate, process, and create data when running the software or executing the instructions. For simplicity, the singular term "processing device" may be used in the description, but one of ordinary skill in the art will appreciate that a processing device may include multiple processing elements and multiple types of processing elements. For example, a processing device may include one or more processors, or one or more processors and one or more controllers. In addition, different processing configurations are possible, such as parallel processors or multi-core processors.

[0094] A processing device configured to implement a software component to perform an operation A may include a processor programmed to run software or execute instructions to control the processor to perform operation A. In addition, a processing device configured to implement a software component to perform an operation A, an operation B, and an operation C may have various configurations, such as, for example, a processor configured to implement a software component to perform operations A, B, and C; a first processor configured to implement a software component to perform operation A, and a second processor configured to implement a software component to perform operations B

and C; a first processor configured to implement a software component to perform operations A and B, and a second processor configured to implement a software component to perform operation C; a first processor configured to implement a software component to perform operation A, a second processor configured to implement a software component to perform operation B, and a third processor configured to implement a software component to perform operation C; a first processor configured to implement a software component to perform operations A, B, and C, and a second processor configured to implement a software component to perform operations A, B, and C, or any other configuration of one or more processors each implementing one or more of operations A, B, and C. Although these examples refer to three operations A, B, C, the number of operations that may be implemented is not limited to three, but may be any number of operations required to achieve a desired result or perform a desired task.

[0095] While this disclosure includes specific examples, it will be apparent to one of ordinary skill in the art that various changes in form and details may be made in these examples without departing from the spirit and scope of the claims and their equivalents. The examples described herein are to be considered in a descriptive sense only, and not for purposes of limitation. Descriptions of features or aspects in each example are to be considered as being applicable to similar features or aspects in other examples. Suitable results may be achieved if the described techniques are performed in a different order, and/or if components in a described system, architecture, device, or circuit are combined in a different manner and/or replaced or supplemented by other components or their equivalents. Therefore, the scope of the disclosure is defined not by the detailed description, but by the claims and their equivalents, and all variations within the scope of the claims and their equivalents are to be construed as being included in the disclosure.

What is claimed is:

1. A method for combining a plurality of three-dimensional ultrasound image data, comprising:

obtaining a plurality of three-dimensional ultrasound image data that corresponds to a Region of Interest (ROI);

detecting one or more landmarks, using a parameter for detection, the one or more landmarks each comprising at least one feature distinct from surroundings thereof;

outputting the detection result and receiving a response from a user;

registering each of one or more selected landmarks as link information according to a received response from the user; and

generating a combined three-dimensional ultrasound image by combining at least two pieces of three-dimensional ultrasound image data using at least one of the one or more selected landmarks registered as the link information, wherein the at least two pieces of three-dimensional ultrasound image data commonly comprise the at least one of the one or more selected landmarks.

2. The method of claim 1, wherein the plurality of three-dimensional ultrasound image data partially overlaps with each other and corresponds to different locations of the ROI, and the detecting comprising: performing diagnosis on each of the plurality of three-dimensional ultrasound image data using the parameter for detection, and detecting one or more

landmarks based on the diagnosis, the one or more landmarks each having volume greater than a predetermined reference value.

3. The method of claim 2, further comprising:

updating the parameter for detection;

performing diagnosis on the combined three-dimensional ultrasound image data using the updated parameter for detection; and

modifying the combined three-dimensional image data based on the diagnosis result.

4. The method of claim 1, wherein the outputting of the detection result and the receiving of the response from the user comprise outputting one or more candidate landmarks as the detection result, and waiting to receive, as the response from the user, information that indicates one or more landmarks selected by the user from among the one or more candidate landmarks.

5. The method of claim 2, wherein the outputting of the detection result and the receiving of the response from the user comprise:

outputting one or more candidate landmarks as the detection result, and waiting to receive a modified parameter for detection as the response from the user;

updating a parameter for detection based on the modified parameter for detection; and

re-outputting one or more candidate landmarks after performing diagnosis on each of the plurality of three-dimensional ultrasound image data using the updated parameter for detection, and waiting to receive, as the response from the user, information that indicates one or more landmarks selected by the user from among the one or more candidate landmarks.

6. The method of claim 2, wherein the outputting of the detection result and the receiving of the response from the user comprise

outputting, as the detection result, information indicating that no candidate landmark is detected, and waiting, as the response from the user, a new parameter for detection;

updating the parameter for detection based on the new parameter for detection; and

re-outputting one or more candidate landmarks after performing diagnosis on each of the plurality of three-dimensional ultrasound image data using the updated parameter for detection, and waiting, as the response from the user, information that indicates one or more landmark selected by the user from among the one or more candidate landmarks.

7. The method of claim 1, wherein the parameter for detection comprises at least one of a classification result which indicates either benignity or malignancy, category, roundness, sharpness of margin, presence of peripheral rim, echogenicity, and homogeneity.

8. The method of claim 1, wherein the parameter for detection comprises information that relates to at least one of an entire shape, texture of an outer surface and posture.

9. The method of claim 7, wherein the parameter for detection further comprises link information that relates to at least one of anatomical features, such as a blood vessel and bone, which are located close to a landmark.

10. An apparatus for combining three-dimensional ultrasound image, the apparatus comprising:

a processor configured to obtain a plurality of partially-overlapping three-dimensional ultrasound image data

corresponding to different locations of a Region of Interest (ROI), and to detect from each of the plurality of three-dimensional ultrasound image data one or more landmarks using a parameter for detection, the one or more landmarks each comprising at least one feature distinct from surroundings thereof;

an input/output device configured to output a detection result and to receive a response from a user,

wherein the processor is configured to register the one or more selected landmarks as link information based on the received response, and to generate a combined three-dimensional ultrasound image by combining at least two pieces of three-dimensional ultrasound image data using at least one of the one or more selected landmarks registered as the link information, the at least two pieces of three-dimensional ultrasound image data commonly comprising the at least one of the one or more selected landmarks.

11. The apparatus of claim 10, wherein the plurality of three-dimensional ultrasound image data partially overlaps with each other and corresponds to different locations of the ROI, and the processor is configured to perform diagnosis on each of the plurality of three-dimensional ultrasound image data using the parameter for detection and detects the one or more landmarks based on the diagnosis, the one or more landmarks each having volume greater than a predetermined reference value.

12. The apparatus of claim 11, wherein the processor is further configured to perform diagnosis on the combined three-dimensional ultrasound image data using an updated parameter for detection and to modify the combined three-dimensional image data based on the diagnosis result.

13. The apparatus of claim 11, wherein the input/output device is configured to output the detection result and to receive the response from the user by:

outputting one or more candidate landmarks as the detection result, and waiting to receive, as the response from the user, information that indicates one or more landmarks selected by the user from the one or more candidate landmarks.

14. The apparatus of claim 11, wherein the input/output device is configured to output the detection result and to receive the response from the user by:

outputting one or more candidate landmarks as the detection result, and waiting to receive a modified parameter for detection as the response from the user, the parameter for detection being updated based on the altered parameter for detection, and

re-outputting one and more candidate landmarks after performing diagnosis on the combined three-dimensional ultrasound image data using the updated parameter for detection, and waiting, as the response from the user, information that indicates one or more landmarks selected by the user from the one or more re-output candidate landmarks.

15. The apparatus of claim 11, wherein the input/output device is configured to output the detection result and to receive the response from the user by:

outputting the detection result indicating that no landmark is detected, and waiting to receive a new parameter for detection as the response from the user, the parameter for detection being updated based on the new parameter for detection, and

outputting one or more candidate landmarks after re-performing diagnosis on the combined three-dimensional ultrasound image data using the updated parameter for detection, and waiting, as the response from the user, information that indicates one or more landmark selected by the user from among the one or more candidate landmarks.

16. The apparatus of claim 10, wherein the parameter for detection comprises information relating to at least one of a classification result that indicates either benignity or malignancy, category, roundness, sharpness of margin, presence of peripheral rim, echogenicity, and homogeneity.

17. The apparatus of claim 10, wherein the parameter for detection comprises at least one of shape, texture of outer surface and orientation.

18. The apparatus of claim 15, wherein the parameter for detection further comprises link information relating to at least one of anatomical features, such as blood vessel and bone, which are close the landmark.

19. A non-transitory computer readable medium storing instructions configured to cause a computing device to perform the method of claim 1.

* * * * *

专利名称(译)	用于组合三维超声图像的设备和方法		
公开(公告)号	US20150157298A1	公开(公告)日	2015-06-11
申请号	US14/325764	申请日	2014-07-08
[标]申请(专利权)人(译)	三星电子株式会社 社会福祉法人三星生命公益财团		
申请(专利权)人(译)	SAMSUNG ELECTRONICS CO. , LTD. 三星生命福利基金		
当前申请(专利权)人(译)	三星生命公益基金会		
[标]发明人	PARK MOON HO KIM YE HOON SEONG YEONG KYEONG CHO BAEK HWAN LEE MIN WOO		
发明人	PARK, MOON-HO KIM, YE-HOON SEONG, YEONG-KYEONG CHO, BAEK-HWAN LEE, MIN-WOO		
IPC分类号	A61B8/08 G06T7/40 G06T19/20 G06K9/46 A61B8/00 G06T7/00		
CPC分类号	A61B8/5253 A61B8/5207 A61B8/469 A61B8/466 A61B8/085 A61B8/0875 G06T2207/10132 G06T7/0012 G06T19/20 G06K9/46 G06T7/40 G06T2207/30008 G06T2207/30101 A61B8/0891 G06T7/33 G06T2207/10136 G06T2207/30048		
优先权	1020130154050 2013-12-11 KR		
其他公开文献	US9504450		
外部链接	Espacenet USPTO		

摘要(译)

提供了一种用于组合三维超声图像的设备和方法。该方法涉及获得对应于感兴趣区域 (ROI) 的多个三维超声图像数据;使用检测参数检测一个或多个地标;输出检测结果并接收用户的响应;根据从用户接收的响应,将一个或多个所选地标中的每一个登记为链接信息;通过使用登记为链接信息的一个或多个所选地标中的至少一个来组合至少两个三维超声图像数据来生成组合三维超声图像,其中所述至少两个三维超声图像数据通常包括一个或多个所选地标中的至少一个。

