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(54) **METHOD AND SYSTEM FOR ULTRASOUND IMAGING OF A BIOPSY NEEDLE**

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(57) **ABSTRACT**

A method, system, computer program product, and user interface for real-time ultrasonic visualization enhancement of a biopsy needle are disclosed in which a wide range of needle positions with respect to the ultrasound probe axis and with respect to the imaged plane are accommodated. Ordinary frames are compounded with special purpose frames, the special purpose frames having transmit and receive parameters adapted to highlight reception of echoes from the biopsy needle. Preferably, an elevation beam width associated with the special purpose ultrasound frames is wider than an elevation beam width associated with the ordinary ultrasound frames. Preferably, the beams of the special purpose ultrasound frames are steered such that they are incident upon the biopsy needle at an increased angle as compared to the angle of incidence for ordinary ultrasound frames. A method for automatically and adaptively determining the depth and orientation of a biopsy needle is also described, whereby beam steering parameters, focus parameters, etc. may be automatically and adaptively computed. The user may optionally provide selected beam steering parameters to the ultrasound imaging system using a simple, intuitive user interface.

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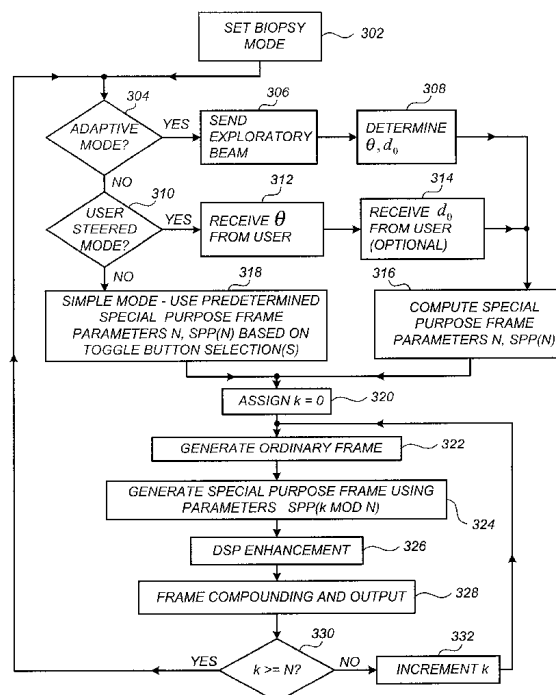
(58) Field of Search 600/437, 443,
600/447, 461, 463, 467, 471; 128/916

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29 Claims, 8 Drawing Sheets



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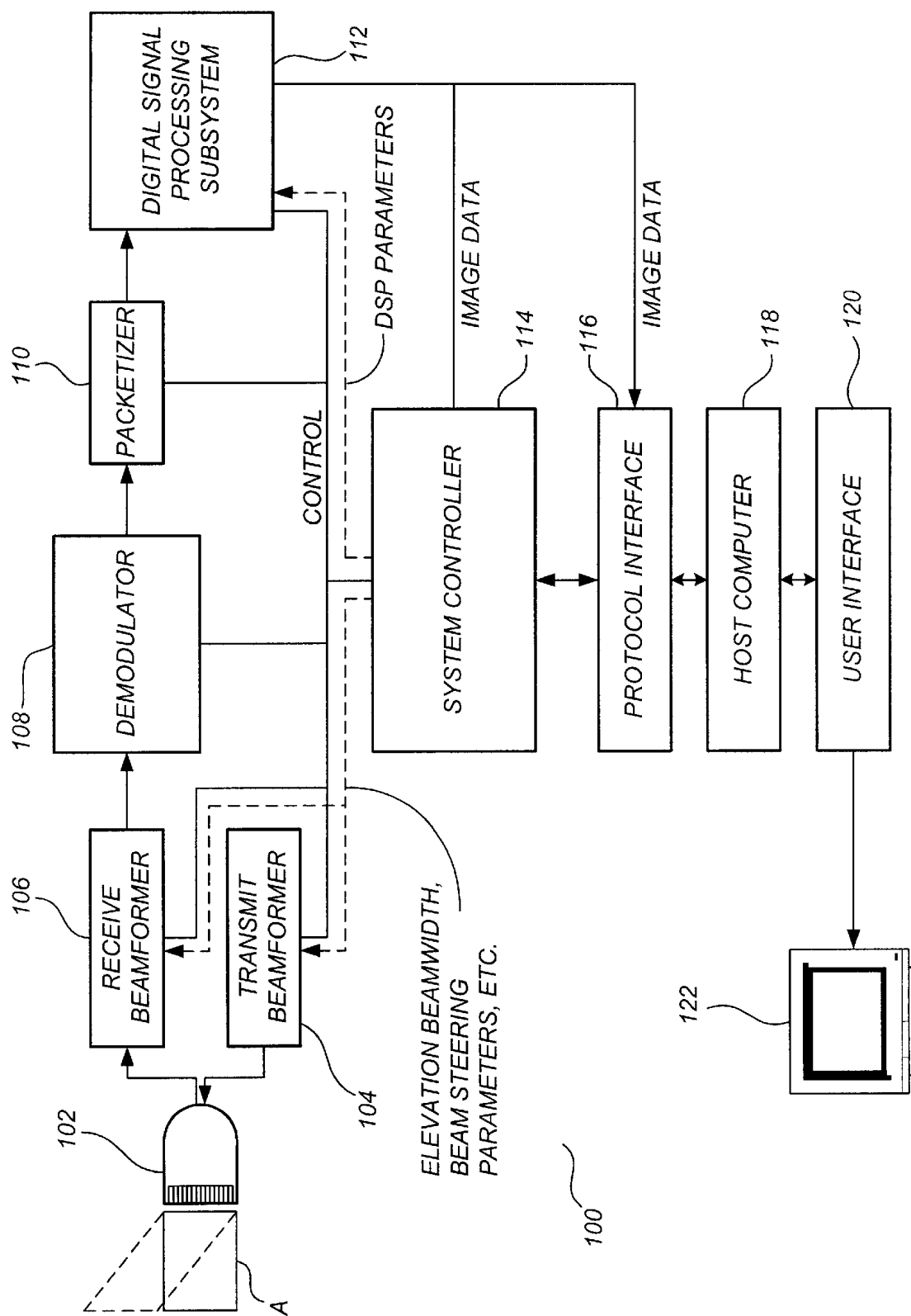


FIG. 1

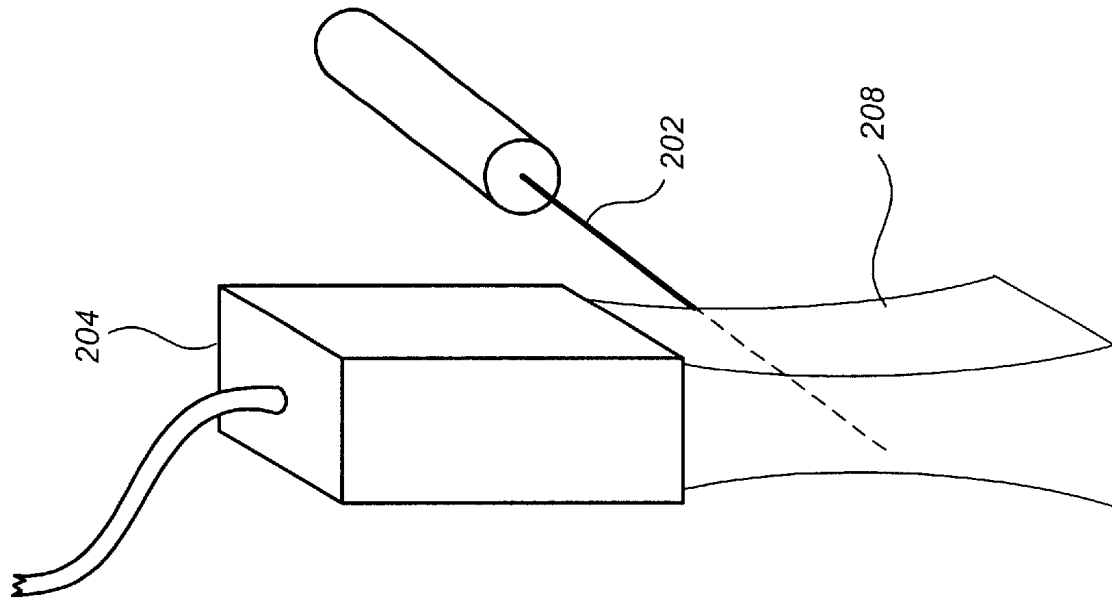


FIG. 2B

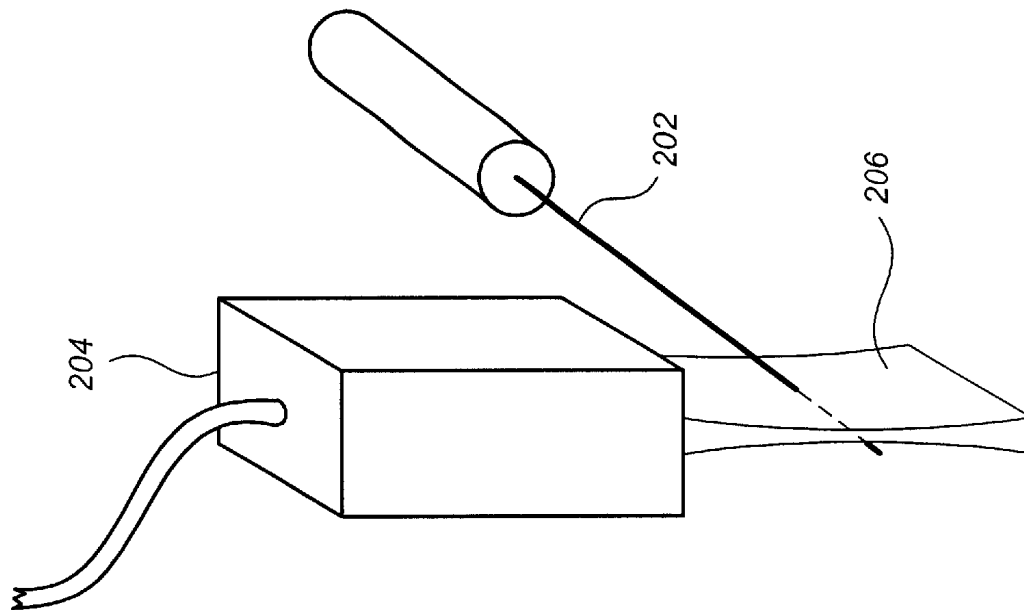


FIG. 2A

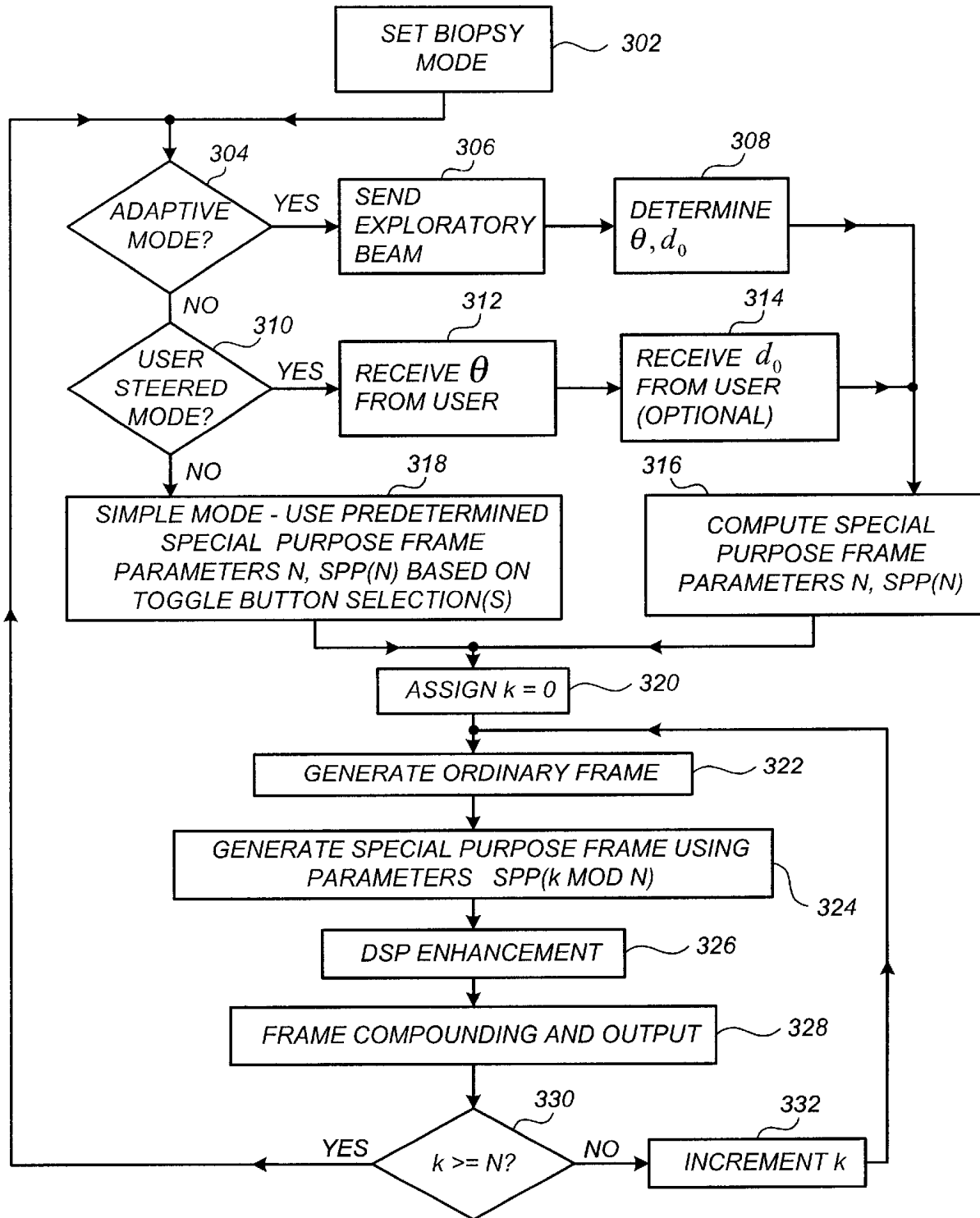


FIG. 3

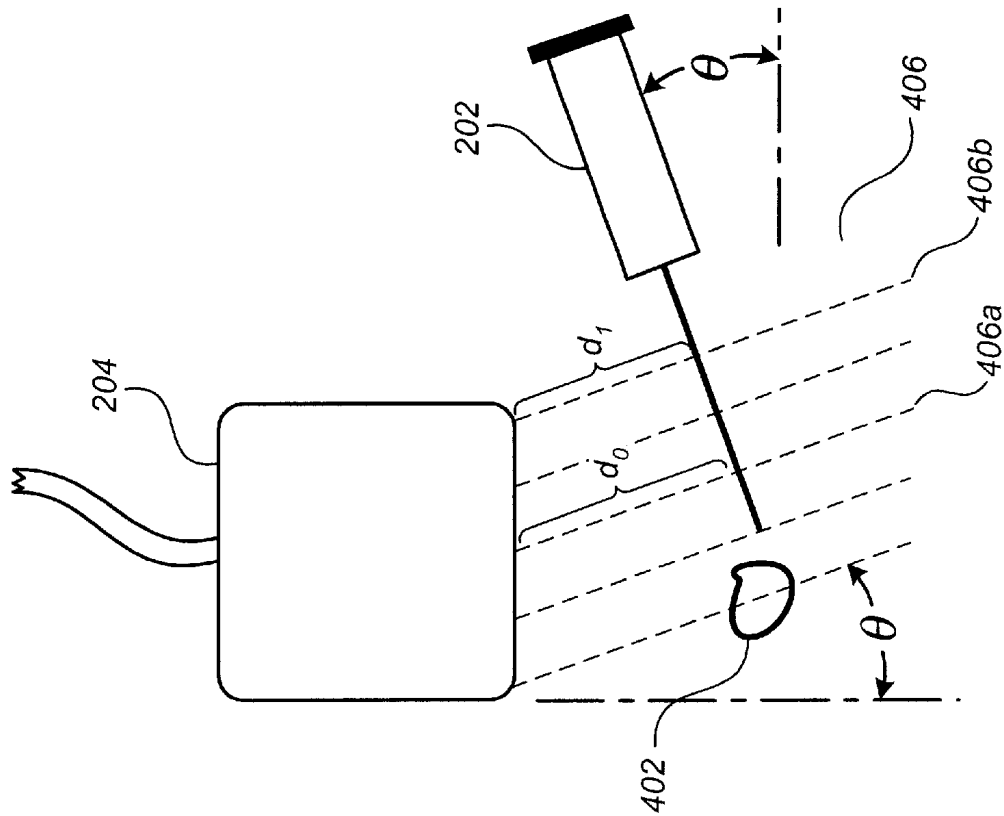


FIG. 4B

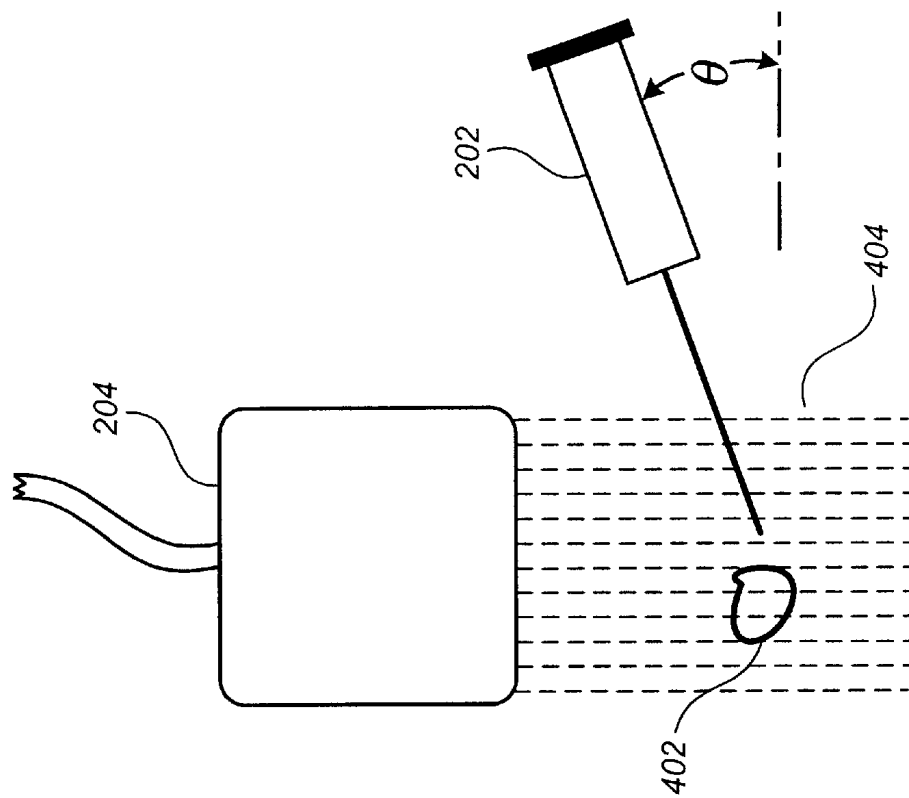


FIG. 4A

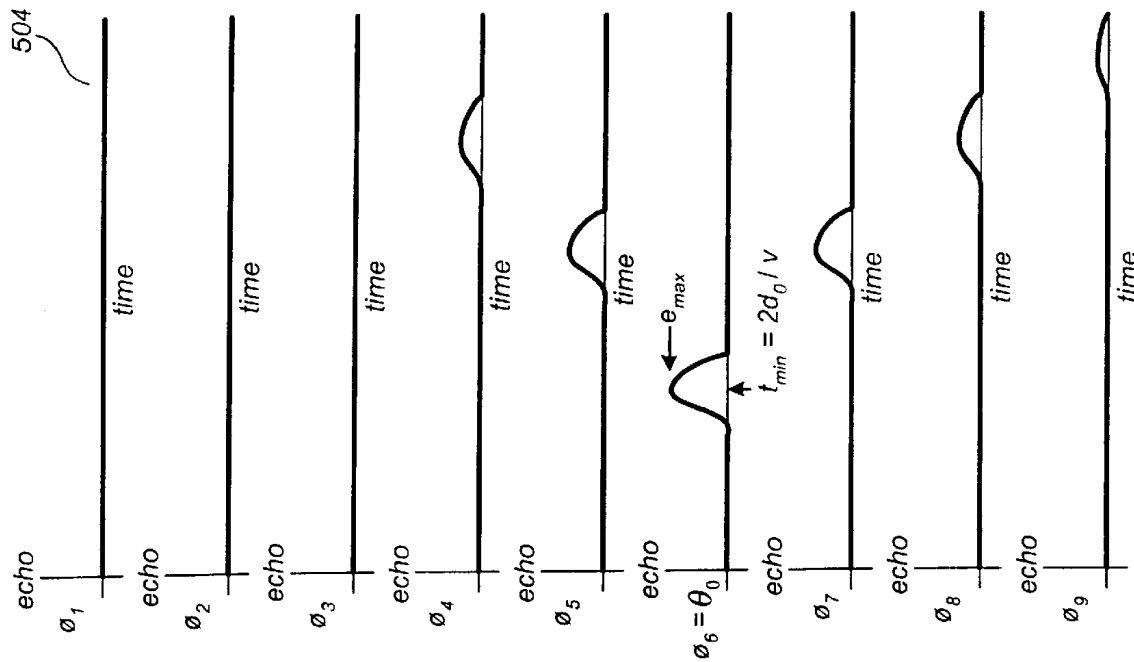


FIG. 5B

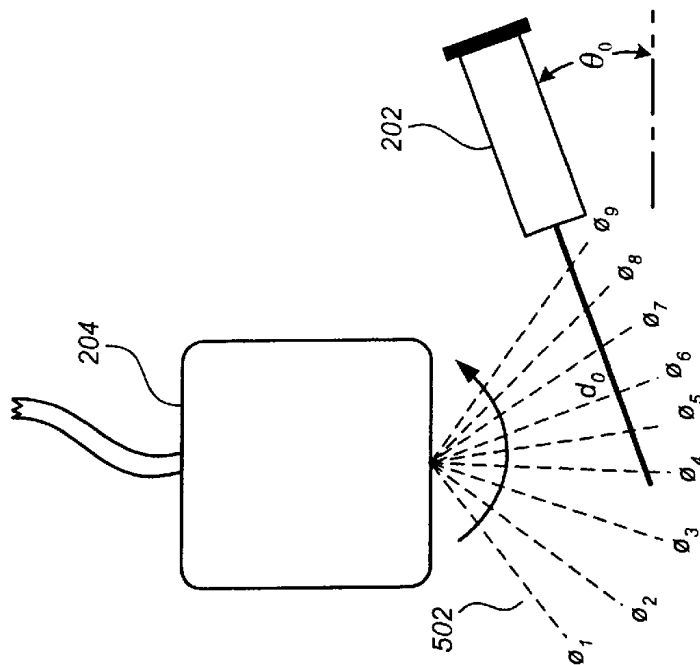


FIG. 5A

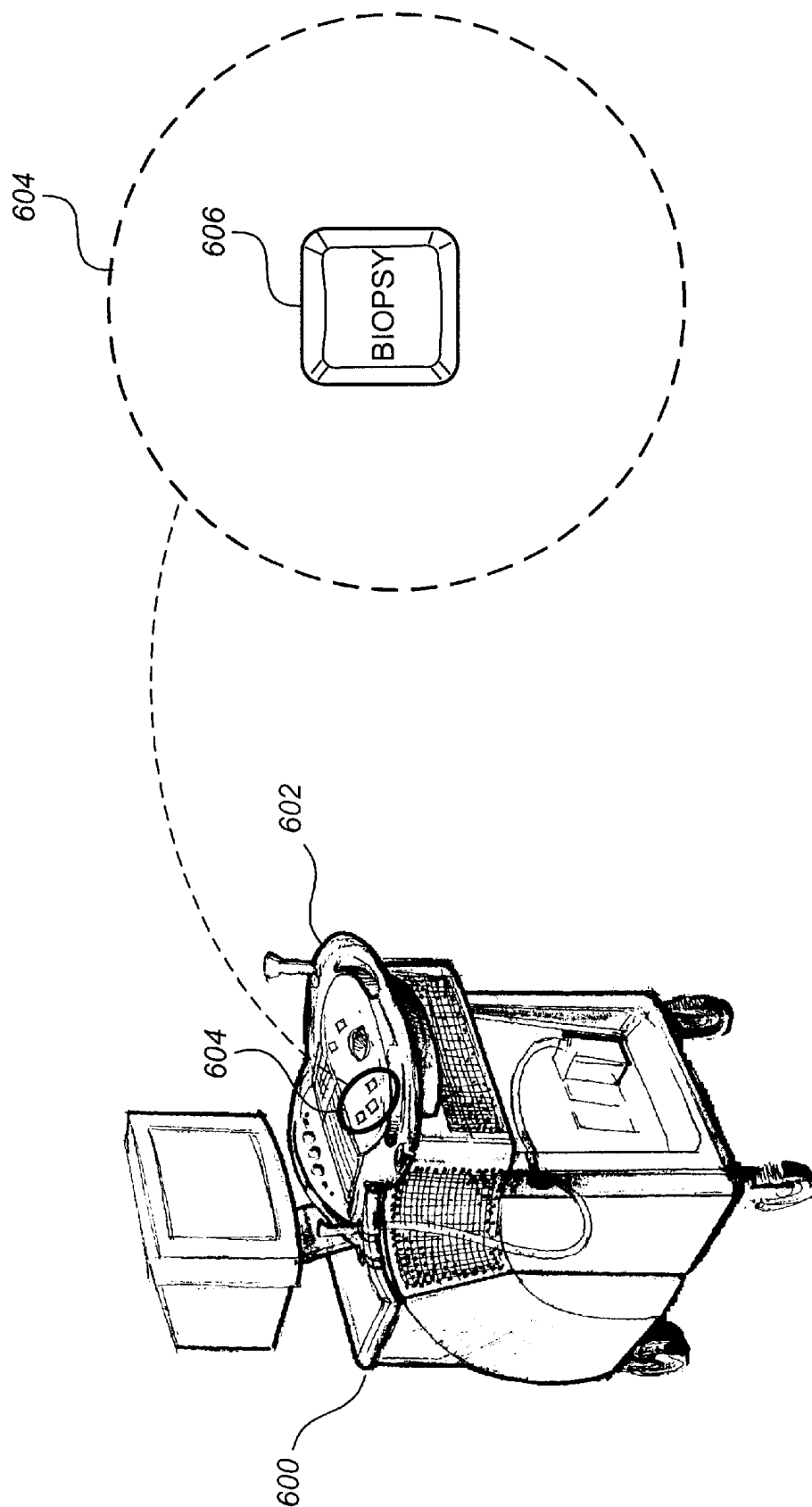


FIG. 6

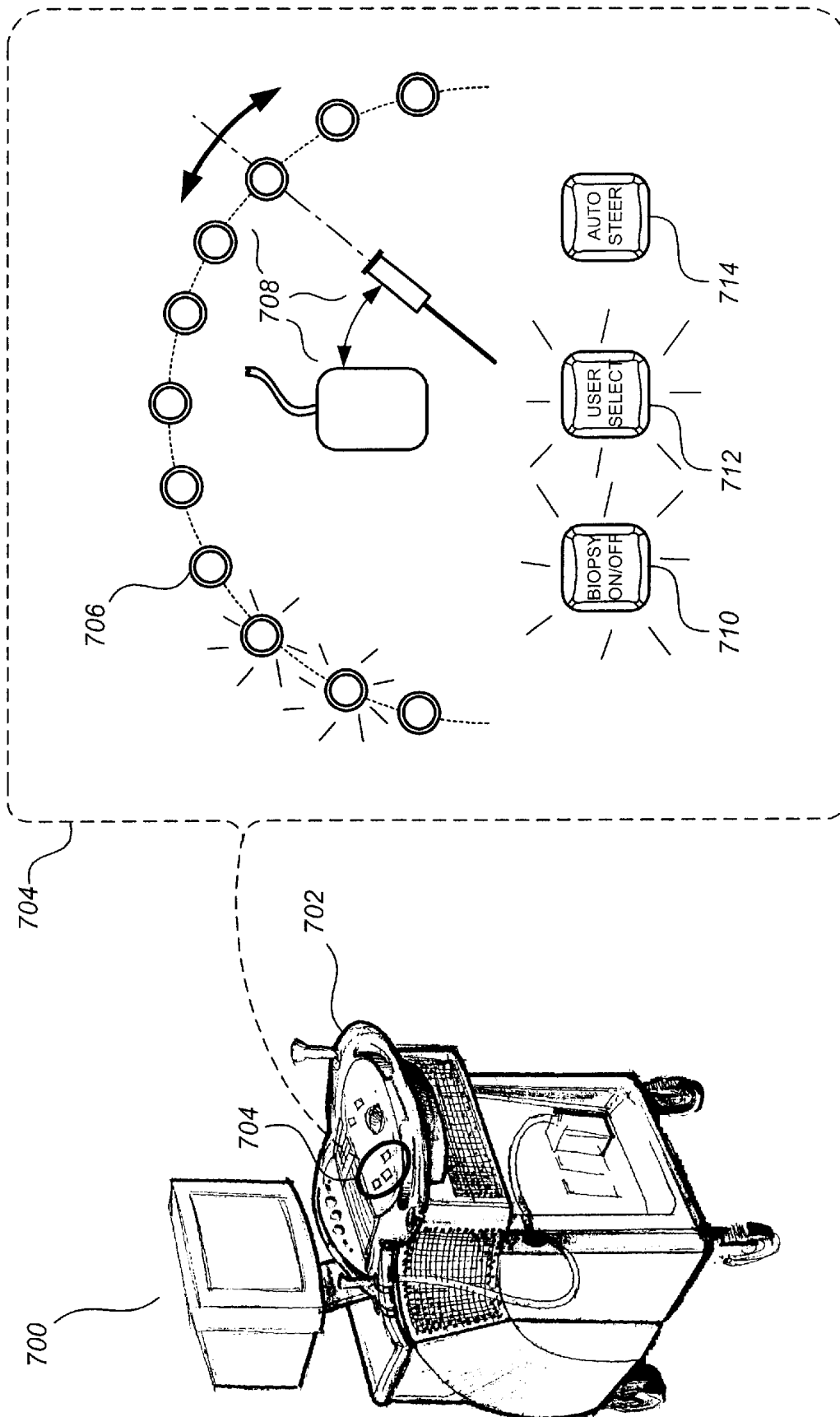


FIG. 7

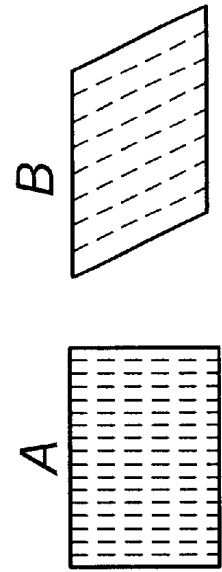
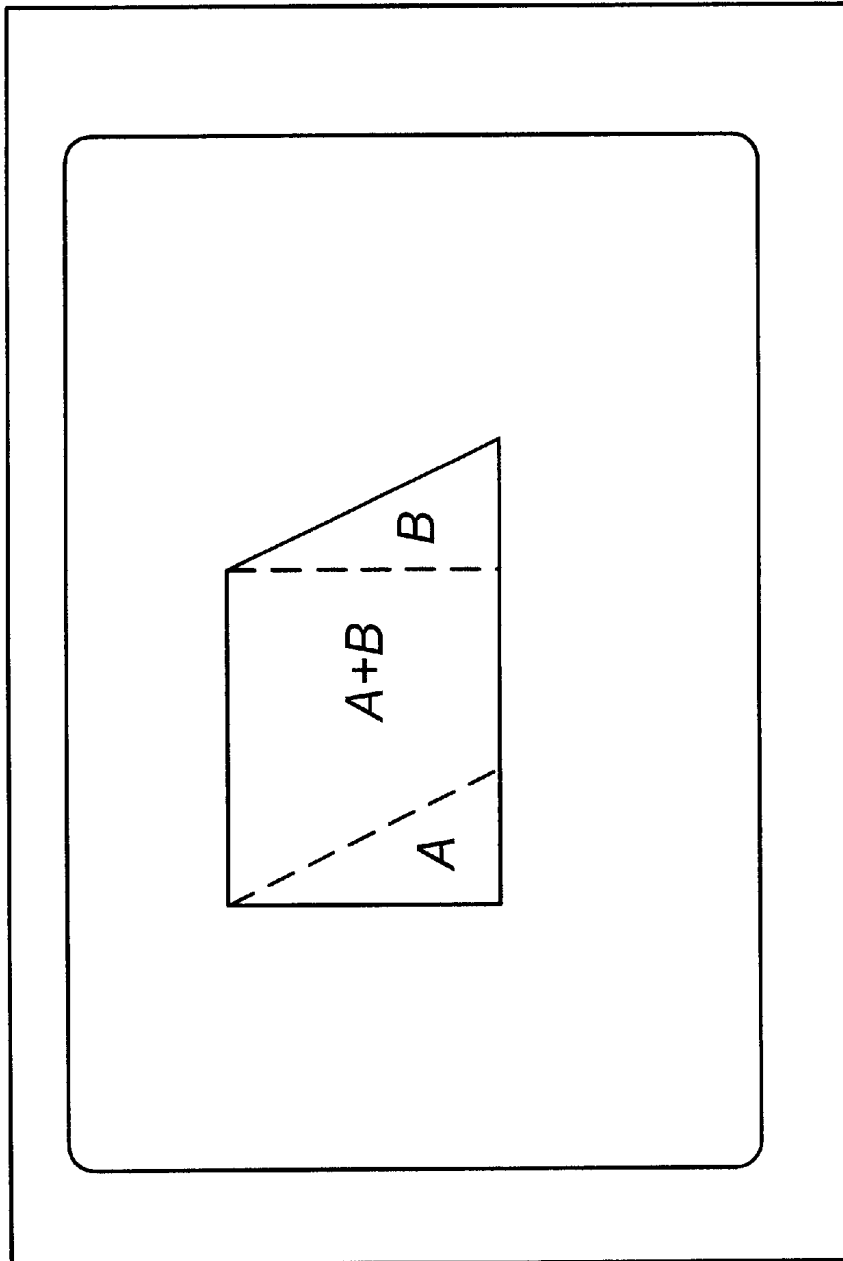


FIG. 8

METHOD AND SYSTEM FOR ULTRASOUND IMAGING OF A BIOPSY NEEDLE

FIELD

This patent specification relates to medical ultrasound imaging systems. In particular, it relates to a method and system for enhanced ultrasonic viewing of a specular instrument such as a biopsy needle inserted into the body during a medical procedure.

BACKGROUND

Ultrasound imaging systems are being increasingly used in medical diagnosis, surgery, and treatment because they are non-invasive, easy to use, capable of real-time operation, and do not subject patients to the dangers of electromagnetic radiation. Instead of electromagnetic radiation, an ultrasound imaging system transmits sound waves of very high frequency (e.g., 1 MHz to 15 MHz) into the patient and processes echoes scattered from structures in the patient's body to derive and display information relating to these structures.

Among the many practical applications of ultrasound imaging systems is their use during invasive or partially invasive medical procedures for allowing the medical professional to better visualize and control the procedure. For example, a breast biopsy is a medical procedure in which a specialized biopsy needle is inserted into the breast to extract tissue samples of a suspicious lesion or tumor. The biopsy needle must be accurately guided so that its tip enters the lesion. Using an ultrasound imaging system, the physician or other medical professional (hereinafter "user") can guide the biopsy needle by viewing real-time ultrasound images of the biopsy needle with respect to the target lesion.

A problem, however, arises in practical clinical applications as a result of the thin, specular nature of most biopsy needles. Because they are elongated and narrow, biopsy needles often elude the plane of the ultrasound slice being imaged. When they do intersect this plane, it is often for only brief intervals of time or space.

Another problem arises from the smooth, metallic nature of most biopsy needles. These needles are specular reflectors that, unlike the tissues in the patient's body, do not reflect incident ultrasound pulses in a diffuse manner. This makes the biopsy needle difficult to perceive in the ultrasound output image unless the incident ultrasound pulses approach the biopsy needle at angles close to ninety degrees. Only for those angles close to ninety degrees will the incident pulses be reflected back to the probe transducer array and properly detected. This problem is alleviated somewhat for abdominal procedures (e.g. for heart, liver, and prenatal procedures) that predominantly use curvilinear imaging formats. For curvilinear imaging formats, the scan lines spread out over a substantial ranges of angles, some of which are perpendicular, or close to perpendicular, to the biopsy needle. In contrast, the predominant imaging format for breast biopsy procedures is the linear format, in which the scan lines are generally parallel to each other, thereby making biopsy needle visualization more difficult for many angles. Nevertheless, it is to be appreciated that the preferred embodiments described infra may be used to enhance needle visualization for any type of imaging format, including linear formats, steered linear formats, curvilinear formats, sector formats, vector formats, and other formats.

U.S. Pat. No. 6,048,312 (hereinafter "the '312 patent"), which is incorporated by reference herein, discusses a

method for three-dimensional ultrasound imaging of a needle-like instrument, such as a biopsy needle, in which the transmitted ultrasound beams are steered to increase the angle at which they impinge upon the biopsy needle. This increases the system's sensitivity to the needle because the reflections from the needle are directed closer to the transducer array. The steered image frames, i.e., the image frames formed from the steered ultrasound beams, may be superimposed with non-steered image frames to form a composite image, and the needle may be highlighted using an intensity-mapping procedure. When the position of the biopsy needle is undetermined, a non-steered first image frame may be combined with a second image frame acquired by steering the beam at a constant first steering angle and with a third image frame acquired by steering the beam at a constant second steering angle, to increase visibility of the biopsy needle.

However, the '312 patent leaves several problems associated with biopsy needle imaging unresolved. For example, while the beams are steered by a transmitter and receiver that "are operated under control of a host computer or master controller [] responsive to commands by a human operator," (col. 5, lines 63-65), the nature of the system's determination of the biopsy needle position is not clear. As another example, the acquired 2-D ultrasound slices have reduced visibility of the biopsy needle when it is positioned out-of-plane with respect to the ultrasound slice. As described supra, this problem is caused by the elongated, narrow shape of the biopsy needle. This problem can be at least partially remedied by a method disclosed in the '312 patent, a "cut plane rotate" method, in which the user graphically manipulates a slice within a 3-D volume construction of the target region until the biopsy needle is coplanar with the slice, wherein data from the 3D volume corresponding to the slice is then displayed (col. 11, lines 18-44). However, this process is highly computationally intensive, and may therefore be difficult to achieve in a real-time system in a cost-effective manner. Moreover, this procedure demands a substantial amount of user attention and manipulation of the ultrasound user interface. Often, the user is already highly occupied with the biopsy procedure being performed, and does not want to devote an undue amount of time and attention to a system that is supposed to be making things easier.

Accordingly, it would be desirable to provide an ultrasound system with real-time biopsy needle visualization enhancement for a wide range of needle positions with respect to the probe.

It would be further desirable to provide such an ultrasound system in which biopsy needle visualization may be enhanced when the needle position is not predetermined or provided to the system by the user.

It would be further desirable to provide such an ultrasound system having an optional mode in which estimates of the position of the biopsy needle may be easily provided by the user, the ultrasound system having an intuitive, easy-to-use user interface that does not require excessive user manipulation.

It would be even further desirable to provide such an ultrasound system in which biopsy needle visualization may be enhanced even when the biopsy needle may wander or deviate from the plane of the ultrasound slice being imaged.

It would be still further desirable to provide such an ultrasound system that provides such biopsy needle visualization enhancement without requiring the computational intensity associated with 3-D volume construction.

SUMMARY

A method and system for real-time visualization enhancement of a biopsy needle are provided, wherein a wide range of needle positions with respect to the probe axis and with respect to the imaged plane are accommodated. Ordinary ultrasound frames are compounded with special purpose ultrasound frames and then output to a real-time display, the special purpose ultrasound frames having transmit and receive parameters adapted to highlight reception of ultrasound echoes from the biopsy needle. In one preferred embodiment, an elevation beam width associated with the special purpose ultrasound frames is wider than an elevation beam width associated with the ordinary ultrasound frames. This reduces sensitivity to the position of the biopsy needle with respect to the imaged plane, and increases reception of biopsy needle echoes in cases where the biopsy needle deviates from the imaged plane. Methods for increasing the elevation beam width of the special purpose frames include lowering the operating frequency and managing the elevation aperture.

Preferably, the beams of the special purpose ultrasound frames are steered such that they are incident upon the biopsy needle at an increased angle as compared to the angle of incidence for ordinary ultrasound frames. For cases in which both the biopsy needle depth and the biopsy needle angle are known, each scan line of the special purpose ultrasound frames has an independently-assigned lateral focus depth equal to a distance between the transducer array and the biopsy needle along that scan line. The biopsy needle image is improved because each point on the needle is in focus with respect to the lateral dimension of the ultrasound image. Edge enhancement, noise/clutter suppression, thresholding, segmentation, or other image processing algorithms may be performed on the special purpose frames prior to compounding. Lesion-enhancement algorithms may also be applied to the special purpose frames and/or to the ordinary frames, wherein both the target lesion and the biopsy needle appear highlighted on the user display.

Processing time for the special purpose frames may be reduced, and therefore overall frame rate increased, by reducing the number of scan lines in the special purpose frame. Because the biopsy needle shape is predictably straight, it has been found that needle image quality does not appreciably deteriorate even when the number of scan lines is decreased by 50 percent or more from the number of scan lines in the ordinary image. Furthermore, several of the image processing algorithms performed on the special purpose frames, including edge enhancement and noise/clutter suppression, may be one-dimensional in nature and separately applied to the scan lines for further reducing processing time.

Values for the needle depth and orientation may be fixed to a known value (e.g., where a fixed mechanical needle guide is used), may be provided by a position sensing system, may be provided by the user, or may be automatically and dynamically determined in accordance with a preferred embodiment described herein. According to a preferred embodiment, a fast method for automatically determining the depth and orientation of a biopsy needle is provided, wherein an exploratory beam is swept across the target region, at periodic or non-periodic intervals, across a wide range of angles. Echoes from the exploratory beam are then processed in a substantially one-dimensional algorithm, or optionally in a two-dimensional algorithm, to determine the depth and orientation of the biopsy needle. The ultrasound beams for the special purpose frames may then be

steered to the computed orientation and laterally focused according to the computed depth. The ultrasound system thereby automatically adapts to the position of the biopsy needle for providing enhanced visualization thereof.

According to another preferred embodiment, a simplified method and user interface therefor are provided for enhancing biopsy needle visualization, in which respective special purpose frames are steered at a plurality of predetermined angles, wherein the special purpose frames are compounded with ordinary frames and output to a display. In one preferred embodiment, only a few angles (e.g., +30 degrees and -30 degrees) are taken for the special purpose frames. In another preferred embodiment, a plurality of angles are used, the number of angles being not less than a quotient of a maximum field angle divided by a critical separation angle. It has been found that this critical separation angle is typically between about 10 to 16 degrees. In one embodiment, a single toggle button is provided to the user that activates a needle enhancement mode and selects the number of steering angles to be used. In another preferred embodiment, a plurality of toggled selection buttons is presented to the user in a spatial pattern that emulates predetermined ranges of needle angles, whereby the user may intuitively select the number and direction of steering angles to be used for the special purpose frames.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 illustrates a functional block diagram of an ultrasound system according to a preferred embodiment;

FIGS. 2A and 2B illustrate ultrasound elevation beam widths corresponding to an ordinary ultrasound frame and a special purpose ultrasound frame, respectively, in accordance with a preferred embodiment;

FIG. 3 illustrates steps for enhancing needle visualization according to a preferred embodiment;

FIGS. 4A and 4B illustrate ultrasound probe, biopsy needle, and scan line positions and orientations corresponding to an ordinary frame and a special purpose frame, respectively, in accordance with a preferred embodiment;

FIGS. 5A and 5B illustrate an exploratory ultrasound beam and echoes corresponding thereto, respectively, during an adaptive needle position detection process in accordance with a preferred embodiment;

FIG. 6 illustrates a user interface for biopsy needle visualization in accordance with a preferred embodiment;

FIG. 7 illustrates another user interface for biopsy needle visualization in accordance with a preferred embodiment; and

FIG. 8 illustrates an example of an output image in accordance with a preferred embodiment.

DETAILED DESCRIPTION

FIG. 1 illustrates a block diagram of an ultrasound imaging system 100 in accordance with a preferred embodiment. Ultrasound imaging system 100 comprises a transducer 102, a transmit beamformer 104, a receive beamformer 106, a demodulator 108, a packetizer 110, a digital signal processing (DSP) subsystem 112, a system controller 114, a protocol interface 116, a host computer 118, a user interface 120, and a display 122. Although many ultrasound system architectures may be readily adapted for use in accordance with the preferred embodiments, ultrasound imaging system 100 is preferably similar to the those described in the commonly assigned U.S. Ser. No. 09/224,635, filed Dec. 31, 1998, U.S. Ser. No. 09/449,095 filed Nov. 24, 1999, and U.S. Ser. No.

09/721,889 filed Apr. 1, 2001, which are incorporated herein by reference, or to the ultrasound imaging system currently named the USI-2000™ available from U-Systems, Inc. of San Jose, Calif. These ultrasound imaging systems have been found particularly suitable for implementing biopsy needle enhancement according to the preferred embodiments because their modular, scalable, and flexible architectures readily allow different sets of transmit parameters, receive parameters, and frame processing parameters to be dynamically assigned on a per-frame basis. Thus, these systems are readily adaptable for generating (i) an ordinary frame, directed to imaging the target region tissues, according to a first set of parameters, and immediately thereafter generating (ii) a special purpose frame, directed to imaging the biopsy needle, according to a second set of parameters different than the first set of parameters.

Transducer **102** comprises an array of transducer elements that transmits focused acoustic signals into a target responsive to signals generated by the transmit beamformer **104**. In a preferred embodiment, transducer **102** transmits acoustic pulses into an area **A** that is relative to the transducer, the pulse parameters and orientation of area **A** being different for ordinary ultrasound frames than for special purpose frames. Responsive to control signals and parameters received from system controller **114**, including elevation beamwidth parameters, beam steering parameters, and other parameters, transmit beamformer **104** generates signals that are converted into acoustic interrogation signals by transducer **102** and introduced into the target. Transducer **102** also receives acoustic echoes from the target and converts them into signals for forwarding to receive beamformer **106**. Receive beamformer **106** receives the signals and converts them into a single-channel RF signal, also doing so in accordance with elevation beamwidth parameters, beam steering parameters, and other parameters provided by system controller **114**.

Demodulator **108** receives the single-channel RF signal and generates component frames therefrom, which are then packetized by packetizer **110** and fed to DSP subsystem **112**. In accordance with control signals and parameters received from system controller **114** that dictate the one-, two-, and/or three-dimensional signal processing functions required, DSP subsystem **112** continuously generates processed images corresponding to the ordinary frames and special purpose frames, including compound images resulting from predetermined combinations of the ordinary and special purpose frames. The output image data is transferred to protocol interface **116**, but may optionally be further processed by system controller **114**. The compound output image frames are then transferred to host computer **118** which performs scan conversion on the signals for transmission to user interface **120** and ultimate display by display **122**.

It is to be appreciated that while one particularly suitable ultrasound system is disclosed supra, biopsy needle visualization enhancement according to the preferred embodiments may be carried out using any of a variety of types of ultrasound hardware and software. Given the present disclosure, those skilled in the art will be readily able to implement ultrasound system hardware and software configurations capable of achieving the functionalities described herein.

FIGS. **2A** and **2B** illustrate ultrasound elevation beam widths corresponding to an ordinary ultrasound frame and a special purpose ultrasound frame, respectively, in accordance with a preferred embodiment. Shown in FIG. **2A** is a biopsy needle **202** positioned with respect to an ultrasound probe **204**. An ordinary frame slice **206**, corresponding to a coverage volume of an ordinary ultrasound frame, extends

downward from the ultrasound probe **204** in the plane thereof. For simplicity and clarity of explanation, the biopsy needle **202** in the example of FIG. **2A** is almost parallel to the transducer array of the ultrasound probe **204**, the non-parallel case being described further infra. However, as often happens during biopsy procedures, the biopsy needle **202** is slightly out-of-plane with respect to the ordinary frame slice **206**.

Because ordinary frames are intended for the optimal imaging of target tissue, including the lesion that is the object of the biopsy procedure, the ordinary frame slice **206** is generally narrow in the elevation direction (i.e., the left-to-right direction in FIG. **2A**). This is because as the elevation beam width increases, an averaging effect occurs in the elevation direction and the output ultrasound image has less clarity as compared to ultrasound images generated with thinner elevation beam widths. Disadvantageously, however, when the position of the biopsy needle **202** is slightly out-of-plane with respect to the ordinary frame slice **206**, as in the case of FIG. **2A**, it only intersects that slice for a brief interval. Accordingly, if only ordinary frames were used, much of the biopsy needle **202** of FIG. **2A** would not appear on the output display.

According to a preferred embodiment, because so much information is already known about the biopsy needle **202**, it is not required that the biopsy needle **202** be imaged using the thin, high-resolution slices of the ordinary frames. Rather, it is more important to capture as much of the biopsy needle as possible, albeit at a lesser resolution, then it is to capture smaller portions of the biopsy needle at the same high resolution as the target lesion. This is especially true because much information about the biopsy needle is already known (e.g., it is narrow and straight), and so the image of the biopsy needle **202** is highly amenable to digital signal processing techniques to sharpen and enhance it prior to display. Moreover, even if little or no digital signal processing techniques are applied and the needle image is slightly out of focus on the output display, this display can still be more useful to the user than a display which shows a clearer, but very small, portion of the biopsy needle.

Accordingly, shown in FIG. **2B** is a special purpose frame slice **208** that is substantially wider in the elevation direction than the ordinary frame slice **206**. According to a preferred embodiment, the special purpose frames are received, are optionally digitally enhanced, and are compounded with ordinary frames for output to a display monitor. The special purpose frames are transmitted and received according to special purpose frame parameters that dictate the elevation beam width, focus, steering angle, and other parameters. Importantly, successive special purpose frames are not necessarily required to have the same parameters. For example, it may be advantageous to alternate between two types of special purpose frames having different elevation beam widths, e.g., one type having an elevation beamwidth twice the ordinary frame elevation beam width, and another type having an elevation beamwidth three times the ordinary frame elevation beam width. Moreover, the special purpose frame parameters may vary dynamically. For example, they may vary their steering parameters dynamically according to the current orientation of the biopsy needle **202**, as described further infra. By way of notation, a k^{th} set or vector of special purpose frame parameters will be denoted $SPP(k)$ herein. Where there are N vectors of special purpose frame parameters, they can accordingly be contained in a N -vector array $SPP(N)$. Advantageously, in addition to having wider elevation beam widths than the ordinary frames, the special purpose frames may also be steered to impinge upon the

needle at an increased angle, and can be laterally focused on a line-by-line basis to the needle depth, as will be described further infra with respect to FIGS. 4A and 4B.

Any of several methods known in the art may be used to adjust the elevation beam width of the special purpose frames. For 1-D transducer arrays containing only a single row of transducer elements, the elevation beam width can be increased by reducing the operating frequency. By way of example and not by way of limitation, because the elevation beam width is generally inversely proportional to the operating frequency, a reduction of the operating frequency from 7 MHz to 5 MHz can increase the elevation beam width by about 30 percent. For "1.5-D" and 2-D transducer arrays management of the elevation aperture is an additional method of increasing the elevation beam width. By way of example and not by way of limitation, the "F-number" for the transducer array can be increased to increase the elevation beam width. Doubling the "F-number" will usually double the elevation beam width at each depth, and will have the further advantage of quadrupling the depth of focus in the elevation direction. By way of further example, an elevation beamwidth aperture apodization window, such as a Hamming window, may be used to make the effective aperture narrower, thereby increasing the elevation beam width.

Any of a variety of compounding algorithms may be used in accordance with the preferred embodiments. For example, a simple compound image comprising two frames, one ordinary frame compounded with one special purpose frame, could be output to the display. Alternatively, a different number of special purpose frames could be associated and compounded with a single ordinary frame. Even further, more than one ordinary frame may be compounded together with a single special purpose frame which could, for example, yield the additional benefit of speckle reduction in addition to needle visualization enhancement. According to one preferred embodiment, the image re-registration portion of the image compounding algorithms may be carried out using a 0^{th} order interpolation algorithm, as opposed to a bilinear or other more complicated interpolation algorithm, for further reducing the processing time and increasing the frame rate. This has been found to yield good results because, as discussed supra, "perfection" is not necessarily required in displaying the biopsy needle. It is the biopsy needle's position and orientation, and not its visual features, that are of primary importance to the medical professional during the biopsy procedure.

For cases in which the special purpose frame angles are different than the normal angle of the ordinary frames, an additional section having a right-triangular shape will be appended to the normally-rectangular output image e.g., as illustrated in FIG. 8. The resulting novel output image is half-trapezoidal in shape, comprising a rectangular portion containing the ordinary frame information (A), and as enhanced by the special purpose frame information (A+B), and a right-triangular portion (B) containing only the special purpose frame information. In addition to containing the imaged biopsy needle, the right-triangular portion may also comprise an appreciable amount of target image information depending on the digital signal processing algorithms that were used to highlight the needle, suppress clutter, etc.

Any of a variety of digital signal processing algorithms may be used in accordance with the preferred embodiments on the special purpose frames and/or the ordinary frames. In one embodiment, needle enhancement algorithms are performed on the special purpose frames, while lesion enhancement algorithms are performed on the ordinary frames, with

both the biopsy needle and the target lesion being enhanced on the output display. For example, the needle can be highlighted with a first color and/or brightness level, while the lesion can be highlighted with a second color and/or the border of the lesion can be circumscribed in a highlighted color. In another embodiment, only the needle is enhanced and highlighted on the display. The needle enhancement algorithms may include, but are not limited to, low-pass filtering, thresholding, edge enhancement, contrast enhancement, and other algorithms.

As an alternative or addition to being enhanced using convolution-style image processing algorithms, straight-line-seeking image segmentation algorithms may be used to identify the biopsy needle in terms of a point-slope equation or other form of abbreviated identification that is more efficient than a bitmap-type representation. Substantial time can be saved by mapping only those image elements associated with the biopsy needle onto the ordinary frames prior to display. Segmentation algorithms and other digital signal processing algorithms can be found, for example, in Gonzalez, *Digital Image Processing*, Addison-Wesley Publishing Co. (1992), which is incorporated by reference herein. Lesion detection algorithms can be found, for example, in Cheng, X. Y.; Akiyama, I.; Itoh, K.; Wang, Y.; Taniguchi, N.; Nakajima, M., "Automated Detection of Breast Tumors in Ultrasonic Images Using Fuzzy Reasoning," Proceedings of the International Conference on Image Processing, Volume III, pp. 420-423, IEEE Computer Society (Oct. 26-29, 1997), and Cheng, Xiangyong, A Study on Automated Extraction of Breast Tumors Using Three Dimensional Ultrasonic Echography, Ph.D. Thesis, Keio University, Japan (1997), which are incorporated by reference herein.

According to one preferred embodiment, the user can choose at any time from among three different modes for carrying out biopsy needle visualization enhancement. As will be discussed further infra with respect to FIGS. 5A and 5B, an adaptive mode automatically detects the position of the needle with respect to the probe, in terms of both an angle θ and a depth d_0 , and automatically steers the beam toward the needle. In a user steered mode, the user may directly manipulate the steering angle θ of the special purpose frame beams, and may optionally input the needle depth d_0 as well. This can be done using a trackball, keyboard input, or other input means. In a simple mode, a small set of steering angles is preselected by the user using an intuitive, easy-to-use interface, the ultrasound system toggles among these steering angles in successive special purpose frames.

All three of the above modes (adaptive, user steered, and simple) may provide enhanced biopsy needle viewing resulting from increased elevation beam width, in accordance with the preferred embodiment described supra. However, each of these modes offers relative advantages and disadvantages with respect to each other, and the user may advantageously select among these modes for the purpose at hand. For example, while the adaptive mode is easy-to-use and yields good imaging results by automatically steering and laterally focusing the ultrasound beam, the overall output frame rate may generally be higher in the user steered mode. As another example, while the simple mode is easiest to use, it may also have a slower frame rate than the user steered mode as the number of preselected angles increases.

FIG. 3 illustrates steps for enhancing needle visualization according to a preferred embodiment. At step 302, the user causes the system to enter a biopsy mode. At step 304, it is determined whether an adaptive mode has been selected by

the user, and if so, at steps **306** and **308** an exploratory beam is swept across the target region and the needle position parameters θ and d_0 are determined using the preferred method described infra with respect to FIGS. **5A** and **5B**. At step **316**, special purpose frame parameters N and $SPP(N)$ are computed according to the detected values for θ and d_0 . As an alternative embodiment to the exploratory beam method, position sensors may be attached to the probe and to the needle and the needle angle and depth may be determined from position sensor readings.

If the system is in a user steered mode (step **310**), the values for θ and (optionally) d_0 are received from the user and the special purpose frame parameters N and $SPP(N)$ are computed therefrom. If neither the adaptive mode nor the user steered mode is being used, then at step **318** a set of predetermined simple mode parameters N , $SPP(N)$ are used according to the simple-mode user interface buttons that the user has engaged.

At step **320**, a counter variable k is set to 0. At step **322**, and ordinary frame is generated. At step **324**, a special purpose frame is generated using the k^{th} set of special purpose frame parameters $SPP(k)$. At step **326**, DSP enhancement procedures are performed on the ordinary frame and/or the special purpose frame. At step **328**, frame compounding and output are performed. At step **330**, if the number of special purpose parameter sets N has been reached, the algorithm continues again at step **304**. If not, then k is incremented and the next ordinary frame is generated at step **322**.

Many variations of the ordering of the above steps may be used according to the preferred embodiments. For example, although θ and d_0 are only updated after every "N" special purpose frames in the embodiment of FIG. **3** (representing one cycle through the "N" sets of different parameters), in another preferred embodiment these values may be refreshed for every special purpose frame. Additionally, many variations in the nature and timing of frame compounding are within the scope of the preferred embodiments.

FIGS. **4A** and **4B** illustrate ultrasound probe, biopsy needle, and scan line positions and orientations corresponding to an ordinary frame and a special purpose frame, respectively, in accordance with a preferred embodiment. Shown in FIG. **4A** is the biopsy needle **202** positioned at an angle θ with respect to the transducer surface of ultrasound probe **204**. Ordinary frame scan lines **404** impinge upon the biopsy needle **202** at an angle of θ degrees from the perpendicular. Generally speaking, the ordinary frame scan lines **404** will be closely spaced in the lateral direction to optimize the image resolution of the target lesion **402**. The elevation beamwidth associated with the ordinary frame of FIG. **4A** is shown in FIG. **2A**. It has been found that variations of the angle of incidence of the scan lines from the perpendicular to the biopsy needle **202** beyond about 8 degrees will often cause substantial degradation in the image quality of the biopsy needle. Accordingly, if only ordinary frames were used on the output display and the angle θ was in excess of about 5 to 8 degrees, needle image quality would suffer substantially.

Shown in FIG. **4B** are the biopsy needle **202** and ultrasound probe **204** during a special purpose frame, whose scan lines are shown as elements **406**. Special purpose frame scan lines **406** impinge upon the biopsy needle **202** at a 90 degree angle. Where 90 degree angles are not achievable, this angle is as close as practicable to a 90 degree angle. In accordance with a preferred embodiment, the lateral focusing of special

purpose frame scan lines **406** is performed on a per-scan-line basis. In particular, successive scan lines are laterally focused at different depths corresponding to the differing distances between the transducer array and the biopsy needle at different points along the transducer array. These differing distances are graphically depicted in FIG. **4B**, in which the transducer array is separated from the biopsy needle by a distance d_0 along a first scan line **406a** near the center of the transducer array, the separation is a shorter distance d_1 along a second scan line **406b** near the edge of the transducer array. Thus, according to the preferred embodiment, the scan line **406a** is laterally focused at the depth d_0 , while the scan line **406b** is laterally focused at the depth d_1 , and likewise-computed lateral focus depths are assigned for all of the special purpose frame scan lines **406**. The elevation beam width associated with the special purpose frame of FIG. **4B** is shown in FIG. **2B**.

As indicated by the wider spacing of the special purpose frame scan lines **406** in FIG. **4B**, the number of scan lines for the special purpose frames may be reduced without substantial reduction in needle image quality. Because the biopsy needle shape is predictably straight, it has been found that needle image quality does not appreciably deteriorate even when the number of scan lines is decreased by 50 percent or more from the number of scan lines in the ordinary image. This leads to a substantial savings in processing time and a corresponding increase in overall frame rate.

FIGS. **5A** and **5B** illustrate an exploratory ultrasound beam **502** and echo signals **504** therefrom, respectively, during an adaptive needle position detection process in accordance with a preferred embodiment. At periodic or nonperiodic intervals sufficient to keep up with a moving needle, an exploratory beam is fired along the direction ϕ_1 , then ϕ_2 , then ϕ_3 , etc., as shown in FIG. **5A**, until a large arc is subtended. The exploratory pulses sent along directions that do not intersect the biopsy needle **202** are not reflected, whereas exploratory pulses sent along directions to do intersect the needle are reflected back. Those exploratory pulses that are reflected back will be measured with delay times and strengths that reflect the closeness to the needle, and the incidence angle with the needle, along the pulse direction. As indicated in FIG. **5B**, the strongest and closest reading at ϕ_0 corresponds to the angle θ_0 of the needle, as well as the distance d_0 to the needle according to the relation $t_{min}=2d_0/v$, where v is the velocity of sound in the target tissue. Any of a variety of algorithms may be used to select among the signal echoes to determine θ_0 and d_0 . In one preferred embodiment, this algorithm simply chooses the angle ϕ corresponding to the earliest reflection. More processing may be done to overcome the effects of noise, clutter, etc., in determining the needle angle and distance (e.g., low pass filtering, verifying that the earliest returned pulse corresponds to the largest-magnitude returned pulse, etc.).

FIG. **6** illustrates a user interface **604** for biopsy needle visualization in accordance with a preferred embodiment, as incorporated into an ultrasound system **600** having an overall user interface **602**. In this simplest preferred embodiment, a single "biopsy" key **606** is provided to the user that toggles among different states. One set of states is presented here by way of nonlimiting example. In a first state, the biopsy feature is disabled. After pressing the biopsy key **606** once, a second state is entered, wherein a predetermined number (in particular, $N=3$) of special purpose frames are successively compounded with ordinary frames, and wherein the special purpose frame parameters $SPP(1)$, $SPP(2)$, and $SPP(3)$ have lateral beam steering

angles of -15 degrees, 0 degrees, and $+15$ degrees, respectively. Preferably, each of the special purpose frame parameters SPP(1), SPP(2), and SPP(3) also has an elevation beam width that is greater than the elevation beam width of the ordinary frames.

If the biopsy key **606** is pressed again, a third state is entered in which only one special purpose frame is compounded with ordinary frames, wherein the steering angle of this one special purpose frame is equal to $+15$ degrees. If the biopsy key **606** is pressed again, a fourth state is entered in which this angle changes to 0 degrees. If the biopsy key **606** is pressed again, a fifth state is entered and this angle changes to -15 degrees. Finally, biopsy key **606** is pressed again, the system returns to the first state. While the above parameters are presented by way of example to clearly illustrate a preferred embodiment, it is to be appreciated that a wide variety of predetermined parameters may be used without departing from the scope of the preferred embodiments.

FIG. 7 illustrates a user interface **704** for biopsy needle visualization in accordance with a preferred embodiment, as incorporated into an ultrasound system **700** having an overall user interface **702**. A plurality of needle angle buttons **706** are provided in a semicircular arrangement around an explanatory diagram **708** that clearly illustrates their purpose. Each of the needle angle buttons **706** is a toggle button having an ON state and an OFF state, the ON state causing the key to be backlit. When a given needle angle button **706** is ON, a special purpose frame having a steering angle corresponding to the direction indicated by that needle angle button is activated. In particular, the steering angle is perpendicular to, or as close as perpendicular as practicable to, a needle direction indicated by an imaginary line running from that needle angle button to the center of the semicircle formed by the needle angle buttons **706**. For each ON button, the number of special purpose frame parameter sets "N" is incremented by one, and one additional set of parameters is added to the special purpose frame parameters SPP(N). Successive special purpose frame parameter sets SPP(k) are cycled through corresponding to the number of ON buttons, and a compound image is formed from the ordinary image and the "N" special purpose frames. The user may have as many ON buttons as they like, with the understanding that greater angular coverage resulting from additional ON buttons will also reduce the overall frame rate. In the example of FIG. 7, the user has selected two needle angle buttons **706** corresponding to -45 and -60 degrees. Accordingly, there are two different special purpose frame parameters SPP(1) and SPP(2) interleaved between ordinary frames and steered such that they would normally impinge upon needles oriented at -45 and -60 degrees, respectively. In another preferred embodiment, each special purpose frame may be separately compounded with neighboring ordinary frames as they are generated, in which case the frame rate will not decrease as the number of ON buttons is increased.

The overall scheme represented by needle angle buttons **706** is activated by a USER SELECT key **712**, as shown in FIG. 7. At any time, the user may switch into the adaptive mode, in which the biopsy needle angle and distance are automatically and adaptively detected, by pressing an AUTO STEER key **714**. The overall biopsy needle visualization enhancement mode is entered and exited by pressing the BIOPSY ON/OFF key **710**.

According to a preferred embodiment, needle angle buttons **706** have angular spacings from each other no greater than a predetermined critical angle. In a particular preferred

embodiment, this critical angle is about 10 to 16 degrees such that, when the proper needle angle buttons are selected, the steering angle of the special purpose frames is never greater than 5 to 8 degrees, respectively, away from the optimal 90 degree angle of incidence with the biopsy needle. As described supra, the image quality of the biopsy needle begins to decrease drastically when this angle is greater than about 5 to 8 degrees. In the embodiment of FIG. 7, the needle angle buttons **706** are placed about 15 degrees apart.

Many variations of the user interface **704** of FIG. 7 are within the scope of the preferred embodiments including, without limitation, virtual-type user interfaces in which the buttons are actually icons on a user display that are clicked and unclicked using a mouse (see, e.g., U.S. Pat. No. 6,063,030, which is incorporated by reference herein). It is to be appreciated that special purpose frames, while containing parameters directed to optimizing biopsy needle viewing, will often provide at least some useful imaging information regarding the lesion. This at least partially offsets the decreases in the ordinary frame rate brought about by the insertion of special purpose frames into the imaging process, as the inserted frames may also add useful information regarding the lesion.

In an additional preferred embodiment, the special purpose frame beams are steered in the elevation direction in addition to the lateral direction, such that they have an increased angle of incidence to the needle with respect to the elevation direction as well. This preferred embodiment requires the use of 2-D ultrasound probes that, as known in the art, are capable of beam steering in the elevation direction as well as in the lateral direction. Upon segmentation, the needle may be then be projected onto the plane of the ultrasound slice 3-dimensional projection algorithm.

Whereas many alterations and modifications of the present invention will no doubt become apparent to a person of ordinary skill in the art after having read the foregoing description, it is to be understood that the particular embodiments shown and described by way of illustration are in no way intended to be considered limiting. For example, while presented supra in the context of breast lesion biopsy procedures, the preferred embodiments are readily applicable to any type of ultrasound-guided medical procedure in which a specular instrument needs to be imaged. Even further, the preferred embodiments may be readily extended to any of a variety of ultrasound-guided activities, be they medical or non-medical, in which a specular instrument needs to be imaged as it is manipulated beneath a surface or inside a cavity. Moreover, although presented supra in the context of B-mode imaging, the preferred embodiments are readily applied to color flow mode, power Doppler mode, or other two- or three-dimensional ultrasound imaging modes. Therefore, reference to the details of the preferred embodiments are not intended to limit their scope, which is limited only by the scope of the claims set forth below.

What is claimed is:

1. A method for generating an ultrasound display of a target region into which a specular reflector is inserted, comprising the steps of:

generating a first frame according to a first set of frame parameters directed to the imaging of the target region; generating a second frame according to a second set of frame parameters directed to the imaging of the specular reflector;

modifying said first frame with information from said second frame relating to a location and orientation of the specular reflector; and

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displaying an output image derived from said modified first frame;

wherein said first and second sets of frame parameters are selected such that an elevation beam width of said second frame is greater than an elevation beam width of said first frame.

2. The method of claim 1, wherein said step of modifying said first frame with information from said second frame comprises the step of compounding said first frame with said second frame.

3. The method of claim 2, further comprising the step of digitally enhancing said second frame to highlight the specular reflector prior to said compounding step.

4. The method of claim 3, said specular reflector being inserted into the target region as part of a medical procedure in which the specular reflector is required to approach a lesion in the target region, further comprising the step of digitally enhancing said first frame to highlight the lesion prior to said compounding step.

5. The method of claim 1, wherein said first and second sets of frame parameters are selected such that said second frame comprises fewer scan lines than said first frame.

6. The method of claim 1, wherein said first and second sets of frame parameters are selected such that scan lines associated with said second frame are incident upon the specular reflector at an angle that is closer to a normal direction as compared to a corresponding scan line incidence angle for said first frame.

7. The method of claim 6, said first and second frames being generated from ultrasonic beams generated by an ultrasound probe having an array of transducers thereon, said specular reflector forming a first angle with respect to said transducer array, wherein said second set of frame parameters is computed to steer the scan lines associated with said second frame at a steering angle with respect to an axis of the ultrasound probe, and wherein said steering angle is closer to said first angle than a corresponding scan line angle associated with said first frame.

8. The method of claim 7, wherein said first angle and said steering angle are fixed at a predetermined value.

9. The method of claim 7, wherein said first angle varies depending on a manual positioning of the specular reflector and the ultrasound probe by a user, and wherein said first angle is determined using position sensing equipment affixed to said specular reflector and to said ultrasound probe, respectively, for allowing dynamic computation of said steering angle.

10. The method of claim 7, wherein said first angle varies depending on a manual positioning of the specular reflector and the ultrasound probe by a user, and wherein said first angle is automatically measured by performing the steps of:

sweeping a series of exploratory ultrasound pulses across a range of angles in said target region; and

using echoes corresponding to said exploratory ultrasound pulses to compute a measure of said first angle; wherein said steering angle is dynamically computed based on said measure of said first angle.

11. The method of claim 7, wherein lateral focusing depths associated with respective scan lines of said second frame vary on a per-scan-line basis, according to a varying distance along each scan line between the transducer array and the specular reflector.

12. The method of claim 1, wherein said specular reflector comprises a biopsy needle.

13. A simplified user interface apparatus for receiving user inputs that dictate enhanced biopsy needle visualization parameters in an ultrasound system, the enhanced biopsy

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needle visualization parameters including a state identifier that identifies one of a plurality of needle enhancement modes, said apparatus comprising a single key that toggles among said plurality of needle enhancement modes upon actuation by the user, wherein said plurality of needle enhancement modes comprises a first mode in which needle enhancement is deactivated and a second mode in which a first needle enhancement frame steered at a first fixed steering angle is compounded with an ordinary frame and output to a display.

14. The simplified user interface apparatus of claim 13, wherein said plurality of needle enhancement modes further comprises a third mode in which a first needle enhancement frame steered at said first fixed steering angle and a second needle enhancement frame steered at a second fixed steering angle are compounded with an ordinary frame and output to the display.

15. The simplified user interface apparatus of claim 14, wherein said plurality of needle enhancement modes further comprises a fourth mode in which a first needle enhancement frame steered at said first fixed steering angle, a second needle enhancement frame steered at said second fixed steering angle, and a third needle enhancement frame steered at a third fixed steering angle are compounded with an ordinary frame and output to a display.

16. A simplified user interface apparatus for receiving user inputs that dictate enhanced biopsy needle visualization parameters in an ultrasound system, the enhanced biopsy needle visualization parameters including one or more biopsy needle angles for which special purpose needle detection frames are to interrogate a target region, said apparatus comprising an array of ON/OFF buttons spatially arranged such that each ON/OFF button spatially emulates an angle at which a biopsy needle is oriented with respect to an ultrasound probe, wherein said biopsy needle angle parameters are determined at any given time by a number and orientation of those ON/OFF buttons that are in an ON state.

17. The simplified user interface of claim 16, wherein said array of ON/OFF buttons forms a semicircular pattern around an explanatory icon, said explanatory icon comprising a representation of an ultrasound probe and a biopsy needle positioned at an angle thereto.

18. The simplified user interface of claim 16, wherein the number and positioning of said ON/OFF buttons is such that said ON/OFF buttons correspond to biopsy needle angles separated by not greater than two times a critical angle of the ultrasound system being used, said critical angle corresponding to an angular deviation of an ultrasound beam from a perpendicular to a biopsy needle beyond which an ultrasound image of the biopsy needle experiences substantial deterioration.

19. The simplified user interface of claim 18, wherein said critical angle is about 5 to 8 degrees.

20. A method for generating an ultrasound display of a target region into which a specular reflector is inserted, the ultrasound display resulting from ultrasonic beams generated by an ultrasound probe having an array of transducers thereon, the specular reflector forming a first angle with respect to the transducer array, comprising the steps of:

generating a first frame according to a first set of frame parameters directed to the imaging of the target region;

generating a second frame according to a second set of frame parameters directed to the imaging of the specular reflector;

modifying said first frame with information from said second frame relating to the location and orientation of the specular reflector; and

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displaying an output image derived from said modified first frame;

wherein said first and second sets of frame parameters are selected such that scan lines associated with said second frame are steered at a steering angle with respect to an axis of the ultrasound probe, said steering angle being closer to the first angle than a corresponding angle associated with scan lines of said first frame;

and wherein lateral focusing depths associated with respective scan lines of said second frame vary on a per-scan-line basis, according to a varying distance along each scan line between the transducer array and the specular reflector.

21. The method of claim **20**, wherein said first and second sets of frame parameters are selected such that an elevation beam width of said second frame is greater than an elevation beam width of said first frame.

22. The method of claim **20**, wherein said step of modifying said first frame with information from said second frame comprises the step of compounding said first frame with said second frame.

23. The method of claim **22**, further comprising the step of digitally enhancing said second frame to highlight the specular reflector prior to said compounding step.

24. The method of claim **23**, said specular reflector being inserted into the target region as part of a medical procedure in which the specular reflector is required to approach a lesion in the target region, further comprising the step of digitally enhancing said first frame to highlight the lesion prior to said compounding step.

25. The method of claim **20**, wherein said first and second sets of frame parameters are selected such that said second frame comprises fewer scan lines than said first frame.

26. The method of claim **20**, wherein said first angle varies depending on a manual positioning of the specular reflector and the ultrasound probe by a user, and wherein said first angle is automatically measured by performing the steps of:

sweeping a series of exploratory ultrasound pulses across a range of angles in said target region; and

using echoes corresponding to said exploratory ultrasound pulses to compute a measure of said first angle; wherein said steering angle is dynamically computed based on said measure of said first angle.

27. The method of claim **20**, wherein said specular reflector comprises a biopsy needle.

28. A computer program product, resident on a computer-readable medium, for use in an ultrasound system, the computer program product for use by the ultrasound system

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in generating an ultrasound display of a target region into which a specular reflector is inserted, comprising:

computer code for generating a first frame according to a first set of frame parameters directed to the imaging of the target region;

computer code for generating a second frame according to a second set of frame parameters directed to the imaging of the specular reflector;

computer code for modifying said first frame with information from said second frame relating to a location and orientation of the specular reflector; and

computer code for displaying an output image derived from said modified first frame;

wherein said first and second sets of frame parameters are selected such that an elevation beam width of said second frame is greater than an elevation beam width of said first frame.

29. A computer program product, resident on a computer-readable medium, for use in an ultrasound system having an ultrasound probe with an array of transducers thereon, the computer program product for use by the ultrasound system in generating an ultrasound display of a target region into which a specular reflector is inserted, the specular reflector forming a first angle with respect to the transducer array, comprising:

computer code for generating a first frame according to a first set of frame parameters directed to the imaging of the target region;

computer code for generating a second frame according to a second set of frame parameters directed to the imaging of the specular reflector;

computer code for modifying said first frame with information from said second frame relating to the location and orientation of the specular reflector; and

computer code for displaying an output image derived from said modified first frame;

wherein said first and second sets of frame parameters are selected such that scan lines associated with said second frame are steered at a steering angle with respect to an axis of the ultrasound probe, said steering angle being closer to said first angle than a corresponding angle associated with scan lines of said first frame;

and wherein lateral focusing depths associated with respective scan lines of said second frame vary on a per-scan-line basis, according to a varying distance along each scan line between the transducer array and the specular reflector.

* * * * *

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摘要(译)

公开了一种用于活检针的实时超声可视化增强的方法，系统，计算机程序产品和用户界面，其中容纳了相对于超声探头轴线和相对于成像平面的宽范围的针位置。普通帧与专用帧复合，专用帧具有适于突出接收来自活检针的回波的发送和接收参数。优选地，与专用超声帧相关联的仰角波束宽度与与普通超声波束相关联的仰角波束宽度宽。优选地，特殊用途超声波束的波束被操纵，使得它们与普通超声波束的入射角相比以增大的角度入射在活检针上。还描述了一种用于自动且自适应地确定活检针的深度和方向的方法，由此可以自动且自适应地计算波束控制参数，聚焦参数等。用户可以可选地使用简单，直观的用户界面向超声成像系统提供所选择的波束控制参数。

