



(12) **EUROPEAN PATENT APPLICATION**

(43) Date of publication:
22.02.2017 Bulletin 2017/08

(51) Int Cl.:
G01S 15/89 (2006.01) **G01S 7/52** (2006.01)
A61B 8/08 (2006.01)

(21) Application number: **16183089.8**

(22) Date of filing: **05.08.2016**

(84) Designated Contracting States:
AL AT BE BG CH CY CZ DE DK EE ES FI FR GB GR HR HU IE IS IT LI LT LU LV MC MK MT NL NO PL PT RO RS SE SI SK SM TR
Designated Extension States:
BA ME
Designated Validation States:
MA MD

(71) Applicant: **FUJIFILM Corporation**
Tokyo 106-8620 (JP)

(72) Inventor: **YAMAMOTO, Katsuya**
Ashigara-kami-gun,
Kanagawa 258-8538 (JP)

(74) Representative: **Klunker . Schmitt-Nilson . Hirsch**
Patentanwälte
Destouchesstraße 68
80796 München (DE)

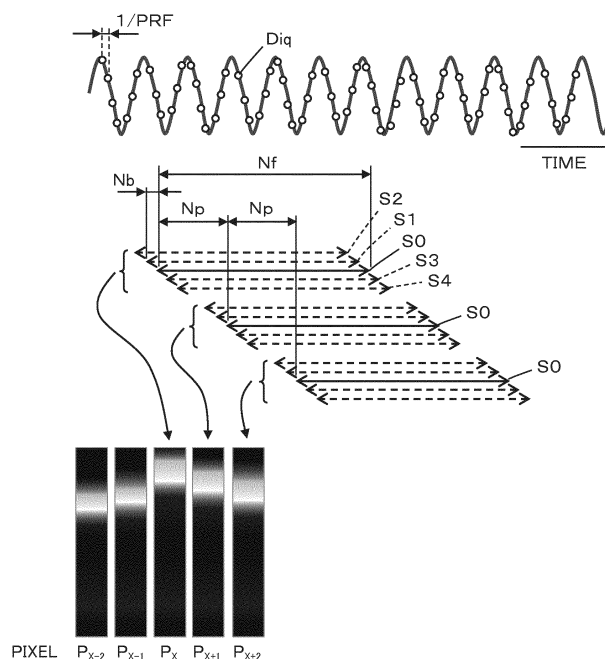
(30) Priority: **17.08.2015 JP 2015160356**

(54) **ULTRASOUND DIAGNOSTIC APPARATUS AND DOPPLER WAVEFORM IMAGE GENERATING METHOD**

(57) An ultrasound diagnostic apparatus includes a quadrature detection section configured to perform quadrature detection on reception radio-frequency data generated by a reception circuit to generate complex data (Diq), a frequency analyzer configured to perform a first frequency analysis using a group (S0) of the complex data (Diq) of a set number (Nf) of sample points starting from a first start point and a second frequency analysis using at least one group (S1, ..., S4) of the complex data

(Diq) of the set number (Nf) of sample points starting from a second start point that is different from the first start point, and to acquire a spectral signal corresponding to each pixel of a Doppler waveform image based on results of the first frequency analysis and the second frequency analysis, and a Doppler waveform image generator configured to generate the Doppler waveform image using the spectral signal.

FIG. 5



Description**BACKGROUND OF THE INVENTION**

[0001] The present invention relates to an ultrasound diagnostic apparatus and a method for generating a Doppler waveform image and particularly to an ultrasound diagnostic apparatus for generating a Doppler waveform image through the pulsed Doppler technique or continuous wave Doppler technique.

[0002] Conventionally, an ultrasound diagnostic apparatus using ultrasound images has been in a practical use in the medical field. In general, this type of ultrasound diagnostic apparatus comprises an ultrasound probe having a built-in transducer array and an apparatus body connected to the ultrasound probe. The ultrasound probe transmits an ultrasonic beam toward the inside of a subject's body and receives ultrasonic echoes from the subject, and the apparatus body electrically processes the reception signals to generate a B-mode (brightness mode) image.

[0003] In addition, for the purpose of obtaining blood flow information, an approach where a Doppler waveform image is generated through the pulsed Doppler technique or the like and displayed with a B-mode image on a display has been adopted.

[0004] Accordingly, an ultrasound diagnostic apparatus that performs Doppler processing together with B-mode processing has been disclosed in JP2003-79625A, for example.

[0005] In the pulsed Doppler technique, using a transducer array, transmittance of an ultrasonic pulse toward a subject's body and reception of an ultrasonic echo from the subject are repeated at intervals of the pulse repetition frequency (PRF). A reception signal obtained from the transducer array at each transmission and reception of an ultrasonic wave is subjected to phasing addition and thereafter converted into complex data containing a Doppler component through quadrature detection, and the complex data at sample points obtained in a predetermined time width is Fourier-transformed, whereby a spectral signal is acquired. Fourier transformation is continuously carried out at intervals of a predetermined number of sample points, and a Doppler waveform image representing changes in the flow rate with respect to the time axis is generated based on acquired spectral signals.

[0006] However, due to interferences between speckle signals or Doppler signals themselves occurring in transmission and reception of ultrasonic waves, for example, black lines appear in a Doppler waveform image thus generated, leading to deterioration of image quality.

[0007] Accordingly, a Doppler waveform image data has been conventionally subjected to smoothing treatment in the time direction and the frequency direction to thereby obscure the black lines.

[0008] However, the resolution would deteriorate in the time direction as smoothing treatment is performed, whereas the time resolution would deteriorate if it is attempted to improve the image quality. Reversely, if deterioration of the time resolution is suppressed, the black lines would stand out, deteriorating the image quality. This has been a problem.

SUMMARY OF THE INVENTION

[0009] The present invention has been made to solve the above-described problem of the prior art and has an object to provide an ultrasound diagnostic apparatus and a Doppler waveform image generating method that can suppress generation of black lines in a Doppler waveform image without a decrease in the time resolution to thereby improve the image quality.

[0010] An ultrasound diagnostic apparatus according to the present invention comprises:

a transducer array;

a transmission circuit configured to transmit an ultrasonic beam from the transducer array toward a subject,

a reception circuit configured to process a reception signal outputted from the transducer array having received ultrasonic echoes from the subject to generate reception radio-frequency data that has undergone phasing addition, a quadrature detection section configured to perform quadrature detection on the reception radio-frequency data generated by the reception circuit to generate complex data,

a frequency analyzer configured to perform a first frequency analysis using the complex data of a set number of sample points starting from a first start point and a second frequency analysis using at least one group of the complex data of the set number of sample points starting from a second start point that is different from the first start point, and to acquire a spectral signal corresponding to each pixel of a Doppler waveform image based on results of the first frequency analysis and the second frequency analysis, and a Doppler waveform image generator configured to generate the Doppler waveform image using the spectral signal.

[0011] A method for generating a Doppler waveform image according to the present invention comprises the steps of:

transmitting an ultrasonic beam from a transducer array toward a subject,

generating reception radio-frequency data that has undergone phasing addition by processing reception signal outputted from the transducer array having received an ultrasonic echo from the subject,
 generating complex data by performing quadrature detection on the reception radio-frequency data,
 performing a first frequency analysis using the complex data of a preliminarily set number of sample points starting
 5 from a first start point and a second frequency analysis using at least one group of complex data of the preliminarily set number of sample points starting from a second start point that is different from the first start point to acquire a spectral signal corresponding to each pixel of a Doppler waveform image based on results of the first frequency analysis and the second frequency analysis, and
 generating the Doppler waveform image using the spectral signal.

BRIEF DESCRIPTION OF THE DRAWINGS

[0012]

FIG. 1 is a block diagram illustrating a configuration of an ultrasound diagnostic apparatus according to an embodiment 1 of the invention.
 FIG. 2 is a block diagram illustrating an internal configuration of a reception circuit in the embodiment 1.
 FIG. 3 is a block diagram illustrating an internal configuration of a B-mode processor in the embodiment 1.
 FIG. 4 is a block diagram illustrating an internal configuration of a Doppler processor in the embodiment 1.
 20 FIG. 5 is a diagram illustrating frequency analysis processing carried out by a FFT in the Doppler processor in the embodiment 1.
 FIG. 6 is a diagram illustrating a display image in a pulsed Doppler mode.
 FIG. 7A illustrates a conventional Doppler waveform image generated from an image data that has undergone smoothing treatment in the time direction, and FIG. 7B illustrates a Doppler waveform image generated in the
 25 embodiment 1.
 FIG. 8 is a diagram illustrating frequency analysis processing carried out by the FFT in the Doppler processor in an embodiment 2.

DETAILED DESCRIPTION OF THE INVENTION

[0013] Embodiments of the invention will be described below based on the appended drawings.

Embodiment 1

35 [0014] FIG. 1 illustrates a configuration of an ultrasound diagnostic apparatus according to an embodiment 1 of the invention. The ultrasound diagnostic apparatus includes a transducer array 1, a transmission circuit 2 and a reception circuit 3, the circuits being connected to the transducer array 1. To the reception circuit 3, a B-mode processor 4 and a Doppler processor 5 are connected in parallel, and a monitor 7 is connected to the B-mode processor 4 and the Doppler processor 5 via a display controller 6.

40 [0015] A transmission/reception controller 8 is connected to the transmission circuit 2 and the reception circuit 3, and an apparatus controller 9 is connected to the B-mode processor 4, the Doppler processor 5, the display controller 6 and the transmission/reception controller 8. In addition, an operation section 10 and a storage 11 are connected to the apparatus controller 9.

45 [0016] The transducer array 1 includes a plurality of ultrasound transducers arranged one-dimensionally or two-dimensionally. The ultrasound transducers transmit ultrasonic waves according to actuation signals supplied from the transmission circuit 2 and receive ultrasonic echoes from the subject to output reception signals. Each of the ultrasound transducers comprises an oscillator composed of a piezoelectric body and electrodes each provided on either end of the piezoelectric body. The piezoelectric body is composed of, for example, a piezoelectric ceramic represented by a lead zirconate titanate (PZT), a piezoelectric polymer represented by polyvinylidene fluoride (PVDF), or a piezoelectric
 50 monocrystal represented by lead magnesium niobate-lead titanate solid solution (PMN-PT).

[0017] When the electrodes of each of the oscillators are supplied with a pulsed voltage or a continuous-wave voltage, the piezoelectric body expands and contracts to cause the oscillator to generate pulsed or continuous ultrasonic waves. These ultrasonic waves are synthesized to form an ultrasonic beam. Besides, the oscillators receive propagating ultrasonic waves to contract, thereby generating electric signals, which will be outputted as reception signals of the ultrasonic
 55 waves.

[0018] The transmission circuit 2 includes, for example, a plurality of pulsers and adjusts the delay amounts for actuation signals based on a transmission delay pattern selected according to a control signal transmitted from the transmission/reception controller 8 so that the ultrasonic waves transmitted from a plurality of ultrasound transducers of the

transducer array 1 form an ultrasonic beam and supplies the ultrasound transducers with delay-adjusted actuation signals.

[0019] As illustrated in FIG. 2, the reception circuit 3 has a structure in which an amplifier 12, an A/D converter 13, and a beam former 14 are connected in series. The reception circuit 3 causes the amplifier 12 and the A/D converter 13 to amplify and A/D-convert the reception signals transmitted from the ultrasound transducers of the transducer array 1, and then causes the beam former 14 to perform reception focusing processing by providing the reception signals with respective delays according to the sound speed or sound speed distribution that is set based on a reception delay pattern selected according to the control signal from the transmission/reception controller 8 and adding them up. The reception focusing processing generates a reception radio-frequency data that has undergone phasing addition and has narrower focal points of ultrasonic echoes.

[0020] As illustrated in FIG. 3, the B-mode processor 4 has a structure in which a signal processor 15, a Digital Scan Converter (DSC) 16 and an image processor 17 are connected in series.

[0021] The signal processor 15 corrects the reception radio-frequency data generated by the reception circuit 3 in terms of attenuation caused due to distance based on the depth at which the ultrasonic waves are reflected, and then performs envelope detection processing to thereby generate a B-mode image signal which is tomographic image information on a tissue inside the subject.

[0022] The DSC 16 converts the B-mode image signal generated by the signal processor 15 into an image signal compatible with an ordinary television signal scanning mode (raster conversion).

[0023] The image processor 17 performs various types of necessary image processing such as gradation processing on the B-mode image signal entered from the DSC 16 and then outputs the B-mode image signal to the display controller 6.

[0024] The Doppler processor 5 generates a Doppler waveform image through the so-called pulsed Doppler technique and, as illustrated in FIG. 4, has a structure in which a quadrature detection section 18, a high pass filter 19, a Fast Fourier Transformer (FFT) 20 and a Doppler waveform image generator 21 are connected in series, and a data memory 22 is connected to an output terminal of the quadrature detection section 18.

[0025] The quadrature detection section 18 converts the reception radio-frequency data into complex data through quadrature detection, by combining the reception radio-frequency data generated by the reception circuit 3 with a carrier signal of a reference frequency.

[0026] The high pass filter 19 functions as a so-called wall filter and removes a frequency component derived from motion of a tissue in the subject's body from the complex data generated by the quadrature detection section 18.

[0027] The FFT 20 performs frequency analysis on the complex data including a plurality of sample points through Fourier transformation, thereby generating a spectral signal.

[0028] The Doppler waveform image generator 21 represents the spectral signal generated by the FFT 20 disposed along the time axis and represents a magnitude of each frequency component as brightness, whereby a Doppler waveform image signal is generated. In a Doppler waveform image, a horizontal axis represents the time axis, a vertical axis represents a Doppler shift frequency, i.e., flow velocity, and brightness of a waveform represents a power of each frequency component.

[0029] The data memory 22 stores the complex data to which the reception radio-frequency data was converted by the quadrature detection section 18.

[0030] The display controller 6 causes the monitor 7 to display a B-mode image based on the B-mode image signal generated by the B-mode processor 4 and to display a Doppler waveform image based on the Doppler waveform image signal generated by the Doppler processor 5 in the pulsed Doppler mode.

[0031] The monitor 7 includes a display device such as an LCD, for example, and displays the B-mode image and the Doppler waveform image under the control of the display controller 6.

[0032] The transmission/reception controller 8 controls the transmission circuit 2 and the reception circuit 3 such that transmission of an ultrasonic pulse to the subject and reception of an ultrasonic echo from the subject are repeated at intervals of the pulse repetition frequency (PRF) based on the various control signals sent by the apparatus controller 9.

[0033] The apparatus controller 9 controls the B-mode processor 4, the Doppler processor 5, the display controller 6 and the transmission/reception controller 8 based on an instruction input by an operator through the operation section 10. The FFT 20 of the Doppler processor 5 and the apparatus controller 9 constitute a frequency analyzer.

[0034] The operation section 10 is provided for the operator to perform input operations and may be composed of, for example, a keyboard, a mouse, a track ball, and/or a touch panel.

[0035] The storage 11 stores, for example, an operation program and may be constituted by, for example, a recording medium such as a hard disc, a flexible disk, an MO (Magneto-Optical Disk), an MT (Magnetic Tape), a RAM (Random Access Memory), a CD-ROM (Compact Disk Read Only Memory), a DVD-ROM (Digital Versatile Disk Read Only Memory), an SD card (Secure Digital Card), a CF card (Compact Flash Card), or a USB memory (Universal Serial Bus Memory), or a server.

[0036] Each of the B-mode processor 4, the Doppler processor 5, the display controller 6, the transmission/reception controller 8 and the apparatus controller 9 is formed by using a CPU and an operation program causing the CPU to execute various kinds of processing. However, these may be formed by using digital circuits. Also, the B-mode processor

4, the Doppler processor 5, the display controller 6, the transmission/reception controller 8 and the apparatus controller 9 may be constituted by partially or totally integrated into a single CPU.

[0037] Here, the operation of the FFT 20 in the Doppler processor 5 will be described referring to FIG. 5.

[0038] Under the control of the apparatus controller 9, the FFT 20 performs frequency analysis through Fourier transformation on complex data D_{iq} of a sample point group S_0 consisting of a plurality of sample points starting from a first start point, among complex data D_{iq} repeatedly obtained at intervals of the pulse repetition frequency (PRF), and, in addition to the sample point group S_0 , performs frequency analysis also on complex data D_{iq} of sample point groups S_1 to S_4 each consisting of a plurality of sample points starting from the second start point that is different from the first start point.

[0039] The sample point groups S_0 to S_4 each include a preliminarily set number of sample points N_f . The sample point group S_1 was obtained temporally earlier than the sample point group S_0 by a number of sample points N_b , and the sample point group S_2 was obtained temporally earlier than the sample point group S_1 further by a number of sample points N_b . In addition, the sample point group S_3 was obtained temporally later than the sample point group S_0 by a number of sample points N_b , and the sample point group S_4 was obtained temporally later than the sample point group S_3 further by a number of sample points N_b .

[0040] The FFT 20 acquires a single spectral signal corresponding to a pixel P_x based on a result of a first frequency analysis on the sample point group S_0 and a result of a second frequency analysis on the sample point groups S_1 to S_4 . In this process, the FFT 20 performs maximum value processing on the result of the first frequency analysis on the sample point group S_0 and on the result of the second frequency analysis on the sample point groups S_1 to S_4 , i.e., extracts the maximum power value of respective frequency components in each of the analysis results, whereby the FFT 20 can acquire the spectral signal corresponding to the pixel P_x .

[0041] Alternatively, the FFT 20 may perform averaging processing on the result of the first frequency analysis on the sample point group S_0 and on the second frequency analysis on the sample point groups S_1 to S_4 , i.e., calculate the average power value of respective frequency components in each of the analysis results to acquire the spectral signal corresponding to the pixel P_x .

[0042] Following the acquisition of the spectral signal corresponding to the pixel P_x , the FFT 20 acquires a spectral signal corresponding to a pixel P_{x+1} adjacent to the pixel P_x in the similar manner. That is, for the pixel P_{x+1} , the FFT 20 carries out not only the first frequency analysis on the complex data D_{iq} of the sample point group S_0 having the set number of sample points N_f starting from the first start point but also the second frequency analysis on the complex data D_{iq} of the sample point groups S_1 to S_4 each having the set number of sample points N_f starting from the second start point that is different from the first start point and acquires a single spectral signal corresponding to the pixel P_{x+1} based on the results of the first and second frequency analyses.

[0043] The first start point for the pixel P_x and the first start point for the pixel P_{x+1} are distanced from each other by the number of sample points N_p corresponding to a gap between adjacent pixels.

[0044] Accordingly, spectral signals respectively corresponding to the pixels of a Doppler waveform image are acquired. FIG. 5 shows examples of the spectral signals respectively corresponding to the five pixels P_{x-2} to P_{x+2} .

[0045] In an example, when the pulse repetition frequency (PRF) is 5,000 Hz, the sweep time T_s of the Doppler waveform image displayed on the monitor 7 is four seconds, the number of pixels PN along the time axis of the Doppler waveform image is 640, and the set number of sample points N_f on which the frequency analysis is performed is 128, the number of sample points N_p corresponding to a gap between adjacent pixels is expressed as $N_p = 5,000 \times 4/640 = 31$.

[0046] In addition, a number of sample points N_b between adjacent sample point groups S_0 to S_4 may be an arbitrary value from the minimum value $N_{b_{MIN}} = 1$ to the maximum value $N_{b_{MAX}}$. The maximum value $N_{b_{MAX}}$ is expressed by the following formula.

$$N_{b_{MAX}} = N_{p_{MAX}}/2 < (PRF_{MAX} \times T_{s_{MAX}}/PN)/2$$

[0047] In the formula, $N_{p_{MAX}}$ represents the maximum value of the number of sample points NP , PRF_{MAX} represents the maximum value of the pulse repetition frequency PRF , $T_{s_{MAX}}$ represents the maximum value of the sweep time T_s of the Doppler waveform image, and PN represents the number of pixels along the time axis of the Doppler waveform image.

[0048] For example, when the maximum value $T_{s_{MAX}}$ of the sweep time T_s is 10 seconds, the maximum value PRF_{MAX} of the pulse repetition frequency PRF is 15.6 kHz, and the maximum value $N_{p_{MAX}}$ of the number of sample points N_p is 244, the maximum value $N_{b_{MAX}}$ of the number of sample points $N_b = N_{p_{MAX}}/2 = 122$ is established.

[0049] Meanwhile, a value of a gap $2 \times N_b$ between the sample point group S_2 or S_4 and the sample point group S_0 is preferably set to a value smaller than 1/2 of the number of sample points N_p corresponding to the gap between adjacent pixels, the sample point group S_2 or S_4 being farthest from the sample point group S_0 among sample point

groups S1 to S4 surrounding the sample point group S0.

[0050] In FIG. 5, two sample point groups S1 and S2 that were obtained temporally earlier than the sample point group S0 and two sample point groups S3 and S4 that were obtained temporally later than the sample point group S0 are used as the sample point groups on which the second frequency analysis is performed. However, the number of sample point groups Ng on which the second frequency analysis is performed may be appropriately selected. In addition, the number of sample point groups obtained temporally earlier than the sample point group S0 and the number of sample point groups obtained temporally later than the sample point group S0 do not have to be same but may be different from each other.

[0051] The pulse repetition frequency PRF, the sweep time of the Doppler waveform image, the set number of sample points Nf on which the frequency analysis is performed, the number of sample points Nb between adjacent sample point groups, the number of surrounding sample point groups Ng on which the frequency analysis is performed and the acquisition method (maximum value processing or averaging processing) to acquire a single spectral signal corresponding to each pixel based on the results of first and second frequency analyses can be input into the apparatus controller 9 through the operation section 10.

[0052] Next, described is an operation of the ultrasound diagnostic apparatus according to the embodiment 1.

[0053] First, according to the actuation signal from the transmission circuit 2, a plurality of ultrasound transducers of the transducer array 1 transmit an ultrasonic beam, and the ultrasound transducers having received ultrasound echoes from a subject output reception signals to the reception circuit 3, the amplifier 12 amplifies the reception signals, which are subsequently A/D converted by the A/D converter 13 and then subjected to phasing addition at the beam former 14, whereby reception radio-frequency data is generated. The reception radio-frequency data is subjected to envelop detection processing by the signal processor 15 in the B-mode processor 4 to turn into a B-mode image signal, which is outputted to the display controller 6 via the DSC 16 and the image processor 17, whereupon the display controller 6 causes the monitor 7 to display the B-mode image.

[0054] Here, when an operator operates the operation section 10 and selects the pulsed Doppler mode, as illustrated in FIG. 6, a screen 31 of the monitor 7 is divided into two regions of a B-mode image 32 and a Doppler waveform image 33, and a gate 34 is displayed so as to be superimposed on the B-mode image 32. The gate 34 can move freely on the B-mode image 32 through the operation of the operation section 10, which is, for example, operated such that the gate 34 is positioned on a blood vessel 35 in order to measure a blood flow rate in the blood vessel 35 in the carotid arteries displayed in the B-mode image 32.

[0055] Here, it is assumed that the pulse repetition frequency PRF, the sweep time of the Doppler waveform image, the set number of sample points Nf, the number of sample points Nb between adjacent sample point groups, the number of sample point groups Ng on which the second frequency analysis is performed and the acquisition method (maximum value processing or averaging processing) to acquire a single spectral signal corresponding to each pixel based on the results of the first and second frequency analyses are preliminarily set in the apparatus controller 9 through the operation section 10.

[0056] Upon transmission of information on the position of the gate 34 from the apparatus controller 9 to the transmission/reception controller 8, the transmission/reception controller 8 controls the transmission circuit 2 and the reception circuit 3, whereby transmission of an ultrasonic pulse toward a specific direction, which passes the gate 34, and reception of an ultrasonic echo are repeated at intervals according to the pulse repetition frequency (PRF).

[0057] The reception radio-frequency data generated in the reception circuit 3 is converted into complex data by the quadrature detection section 18 in the Doppler processor 5, is stored in the data memory 22, and is outputted to the FFT 20 after frequency components derived from motions of body tissues in a subject are removed therefrom by the high pass filter 19.

[0058] The FFT 20 performs, based on the preliminarily set number of sample points Nf, the number of sample points Nb between adjacent sample point groups, the number of sample point groups Ng on which the second frequency analysis is performed, and the acquisition method for acquiring a spectral signal, the first frequency analysis using the complex data Diq in a single sample point group having the set number of sample points Nf from the first starting point and the second frequency analysis using the complex data Diq in the number of sample point groups Ng having the set number of sample points Nf each starting from the second start point, and acquires a spectral signal corresponding to each pixel based on the results of the first and second frequency analyses.

[0059] The Doppler waveform image generator 21 then generates a Doppler waveform image signal based on the spectral signals acquired by the FFT 20, and as illustrated in FIG. 6, the display controller 6 causes the monitor 7 to display the Doppler waveform image 33 in the screen 31. The horizontal axis represents the time axis of the Doppler waveform image 33, while the vertical axis represents a blood flow rate in the blood vessel 35. At this time, the Doppler waveform image signal generated from the spectral signal corresponding to each pixel does not undergo smoothing treatment either in the time direction or the frequency direction, and the Doppler waveform image 33 is displayed based on the Doppler waveform image signal generated by the Doppler waveform image generator 21.

[0060] Since transmission and reception of an ultrasonic beam for acquiring a B-mode image and transmission and

reception of an ultrasonic beam for acquiring a Doppler waveform image are performed in a time-division manner, the B-mode image 32 and the Doppler waveform image 33 can be simultaneously displayed in the screen 31 of the monitor 7.

[0061] As described above, since the FFT 20 under the control of the apparatus controller 9 performs, for each pixel, not only the first frequency analysis for frequency-analyzing complex data D_{iq} in a single sample point group having the set number of sample points N_f starting from the first start point but also the second frequency analysis for frequency-analyzing complex data D_{iq} in the number of sample point groups N_g each having the set number of sample points N_f starting from the second start point that is different from the first start point, and acquires a spectral signal corresponding to each pixel based on the results of the first and second frequency analyses, the necessity of smoothing treatment on image data of a Doppler waveform image conventionally required can be removed, whereby generation of black lines in a Doppler waveform image can be suppressed while the time resolution is prevented from decreasing.

[0062] In particular, illustrated in FIG. 7A is a Doppler waveform image generated by the conventional method where frequency analysis is performed only on complex data D_{iq} of the set number of sample points N_f starting from the first start point, not on the set number of sample points N_f starting from the second start point that is different from the first start point. In this example, the pulse repetition frequency PRF is set to 5,000 Hz, the sweep time of the Doppler waveform image to four seconds, the number of pixels along the time axis of the Doppler waveform image to 640, and the set number of sample points N_f used for frequency analysis to 128.

[0063] It is apparent that black lines BL appear in the Doppler waveform image.

[0064] On the other hand, illustrated in FIG. 7B is a Doppler waveform image generated by the method of the embodiment 1 where, having the pulse repetition frequency PRF, the sweep time of the Doppler waveform image, the number of pixels along the time axis of the Doppler waveform image, and the set number of sample points N_f used for frequency analysis being same as those in the case of FIG. 7A, the first frequency analysis using complex data D_{iq} in the sample point group S_0 having the set number of sample points N_f starting from the first start point, and the second frequency analysis using complex data D_{iq} in the sample point groups S_1 to S_4 each having the set number of sample points N_f starting from the second start point that is different from the first start point are carried out.

[0065] It is apparent that the black lines BL appearing in FIG. 7A have become obscure.

[0066] As described above, according to the invention, generation of black lines can be suppressed, and the image quality can be improved, without decrease in the time resolution.

[0067] In addition, since the complex data converted by the quadrature detection section 18 in the Doppler processor 5 is stored in the data memory 22, by changing at least one of the set number of sample points N_f to be used for frequency analysis, the number of sample points N_b between adjacent sample point groups, and the number of sample point groups N_g on which the second frequency analysis is performed and inputting the changed number through the operation section 10, a new Doppler waveform image can be generated under the changed condition.

Embodiment 2

[0068] In the embodiment 1 described above, two sample point groups S_1 and S_2 obtained temporally earlier than the sample point group S_0 and two sample point groups S_3 and S_4 obtained temporally later than the sample point group S_0 on which the first frequency analysis is performed are used in the second frequency analysis. However, as illustrated in FIG. 8, two sample point groups S_1 and S_2 obtained temporally earlier than the sample point group S_0 may be only used for the second frequency analysis to acquire a single spectral signal corresponding to each pixel based on the results of the first and the second frequency analyses. In this manner, also, generation of black lines can be suppressed, and the image quality may be improved without decrease in the time resolution.

[0069] In addition, one or three or more sample point groups obtained temporally earlier than the sample point group S_0 on which the first frequency analysis is performed may be used as sample point groups for the second frequency analysis.

[0070] Similarly, one or more sample point groups obtained temporally later than the sample point group S_0 on which the first frequency analysis is performed may be used for the second frequency analysis.

Claims

1. An ultrasound diagnostic apparatus comprising:

a transducer array;

a transmission circuit configured to transmit an ultrasonic beam from the transducer array toward a subject,

a reception circuit configured to process a reception signal outputted from the transducer array having received ultrasonic echoes from the subject to generate reception radio-frequency data that has undergone phasing addition,

a quadrature

e detection section configured to perform quadrature detection on the reception radio-frequency data generated by the reception circuit to generate complex data,

a frequency analyzer configured to perform a first frequency analysis using the complex data of a set number of sample points starting from a first start point and a second frequency analysis using at least one group of the complex data of the set number of sample points starting from a second start point that is different from the first start point, and to acquire a spectral signal corresponding to each pixel of a Doppler waveform image based on results of the first frequency analysis and the second frequency analysis, and

a Doppler waveform image generator configured to generate the Doppler waveform image using the spectral signal.

2. The ultrasound diagnostic apparatus according to claim 1, wherein the frequency analyzer extracts a maximum power value of respective frequency components in the results of the first frequency analysis and the second frequency analysis to thereby acquire the spectral signal corresponding to the each pixel.

3. The ultrasound diagnostic apparatus according to claim 1, wherein the frequency analyzer calculates an average power value of respective frequency components in the results of the first frequency analysis and the second frequency analysis to thereby acquire the spectral signal corresponding to the each pixel.

4. The ultrasound diagnostic apparatus according to one of claims 1-3, wherein the frequency analyzer performs, in the second frequency analysis, frequency analysis using at least one group of complex data of the set number of sample points starting from the second start point that is temporally earlier than the first start point by a predetermined number of sample points and performs frequency analysis using at least one group of complex data of the set number of sample points starting from the second start point that is temporally later than the first start point by a predetermined number of sample points.

5. The ultrasound diagnostic apparatus according to one of claims 1-4, further comprising a data memory configured to store complex data generated by the quadrature detection section, and an operation section configured to specify the set number and a number of sample points between the first start point and the second start point, wherein the frequency analyzer performs frequency analysis on the complex data stored in the data memory based on the set number and the number of sample points between the first start point and the second start point that are specified through the operation section.

6. The ultrasound diagnostic apparatus according to one of claims 1-5, wherein the reception circuit includes an analog/digital converter for converting the reception signal outputted from the transducer array into a digital signal, and a beam former for performing phasing addition on the reception signal that is converted into the digital signal.

7. The ultrasound diagnostic apparatus according to one of claims 1-6, further comprising a B-mode processor configured to generate a B-mode image based on the reception radio-frequency data generated by the reception circuit, and a monitor configured to display the Doppler waveform image generated by the Doppler waveform image generator and the B-mode image generated by the B-mode processor.

8. A method for generating a Doppler waveform image, comprising the steps of:

transmitting an ultrasonic beam from a transducer array toward a subject,

generating reception radio-frequency data that has undergone phasing addition by processing reception signal outputted from the transducer array having received an ultrasonic echo from the subject,

generating complex data by performing quadrature detection on the reception radio-frequency data,

performing a first frequency analysis using the complex data of a preliminarily set number of sample points starting from a first start point and a second frequency analysis using at least one group of complex data of the preliminarily set number of sample points starting from a second start point that is different from the first start point to acquire a spectral signal corresponding to each pixel of a Doppler waveform image based on results of the first frequency analysis and the second frequency analysis, and

generating the Doppler waveform image using the spectral signal.

FIG. 1

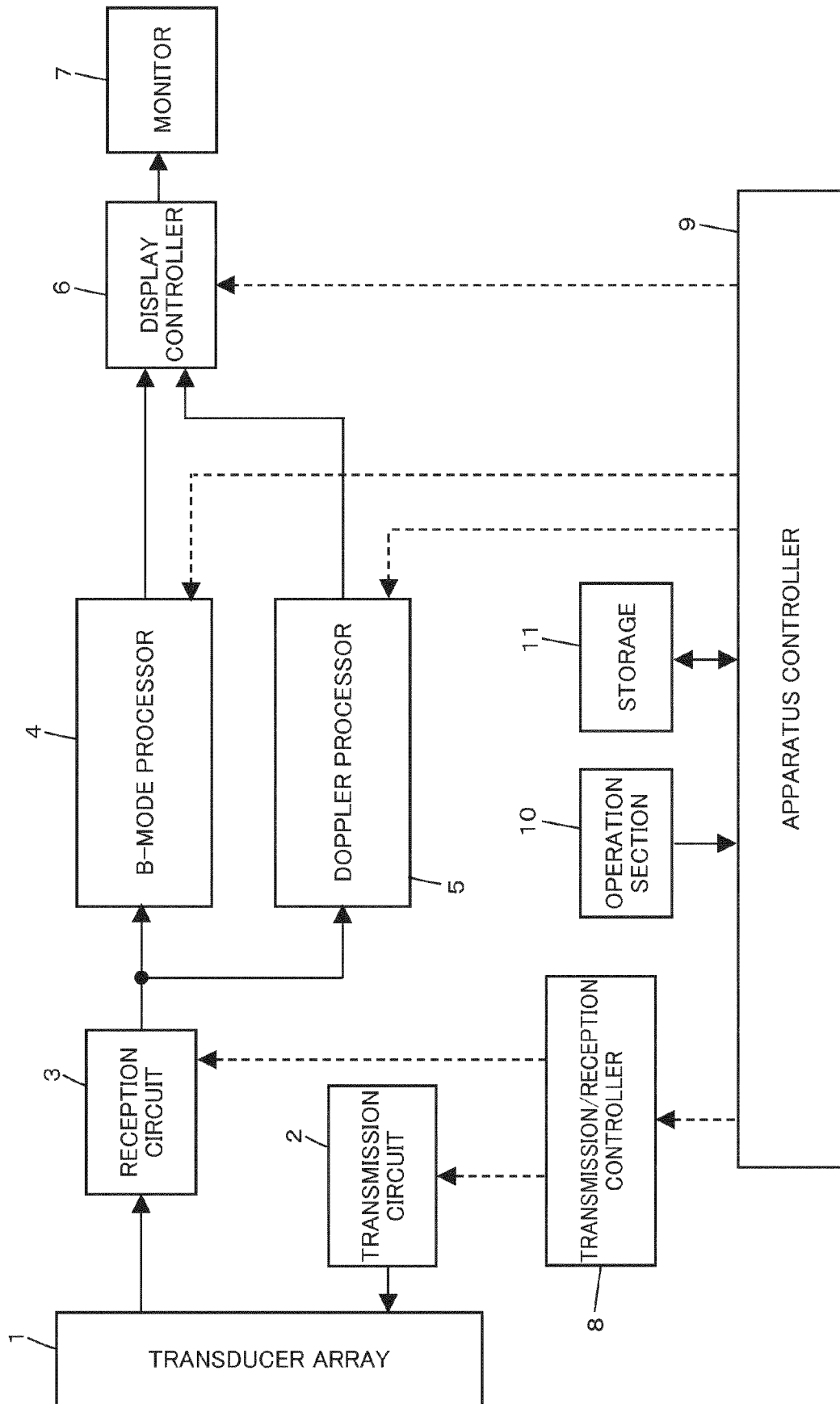


FIG. 2

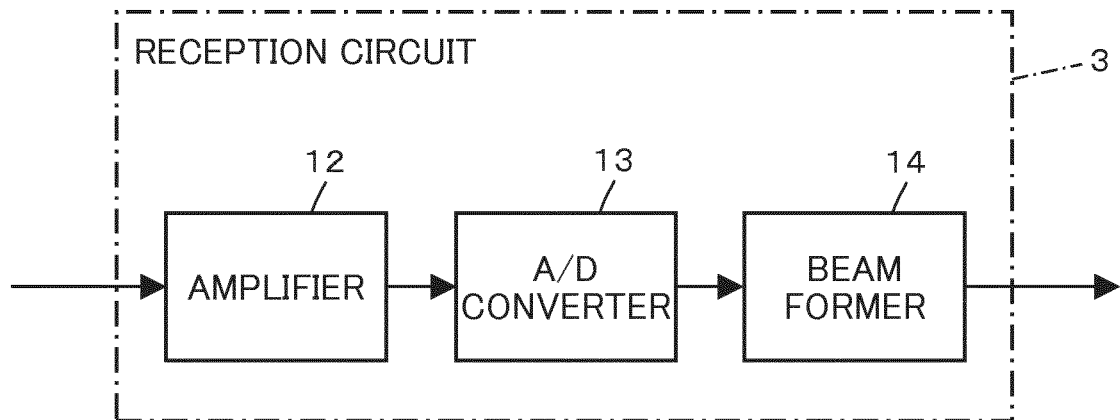


FIG. 3

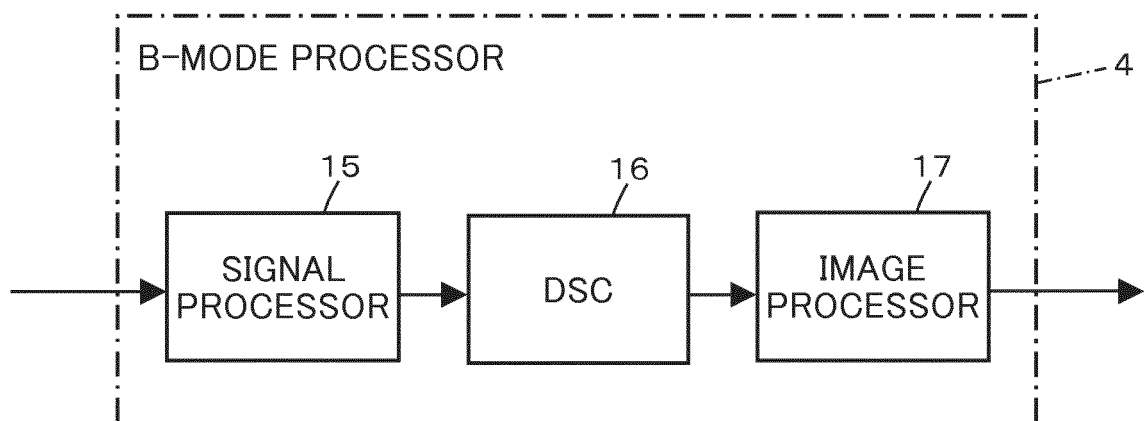


FIG. 4

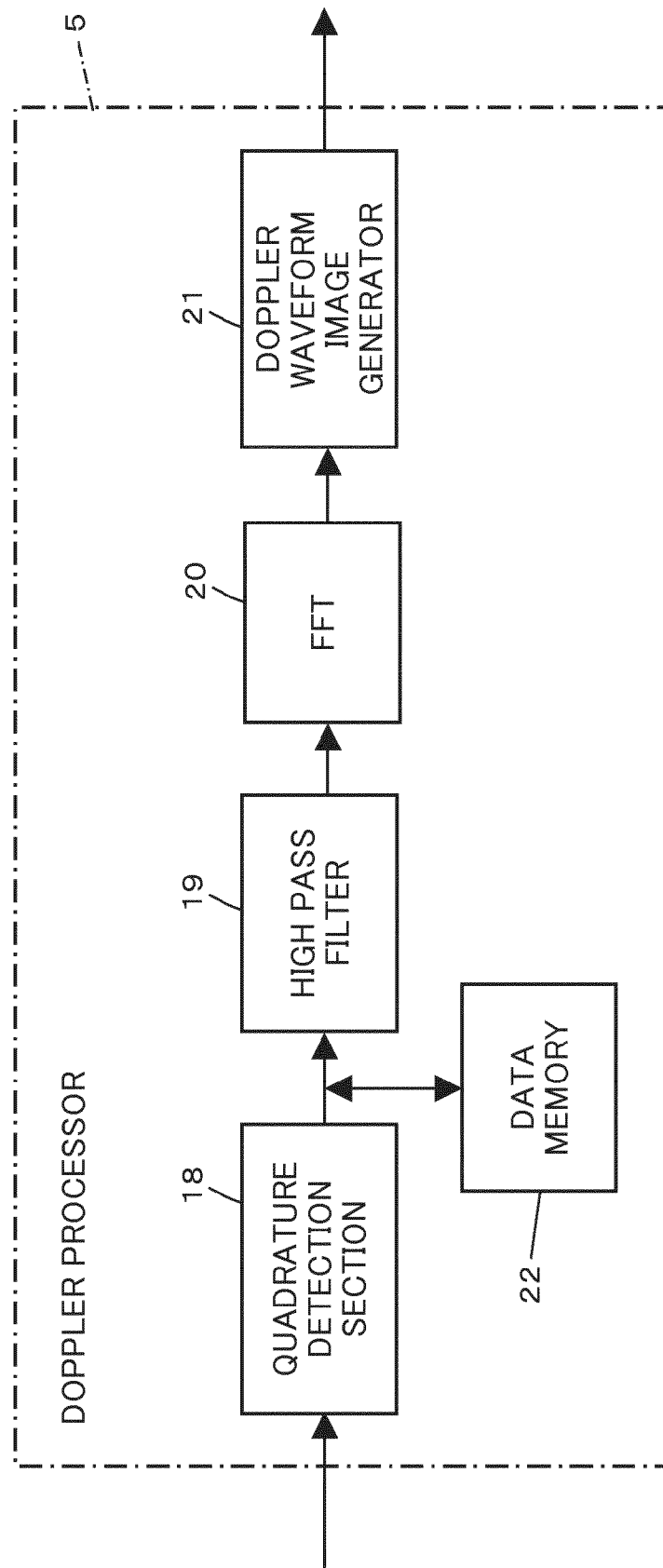


FIG. 5

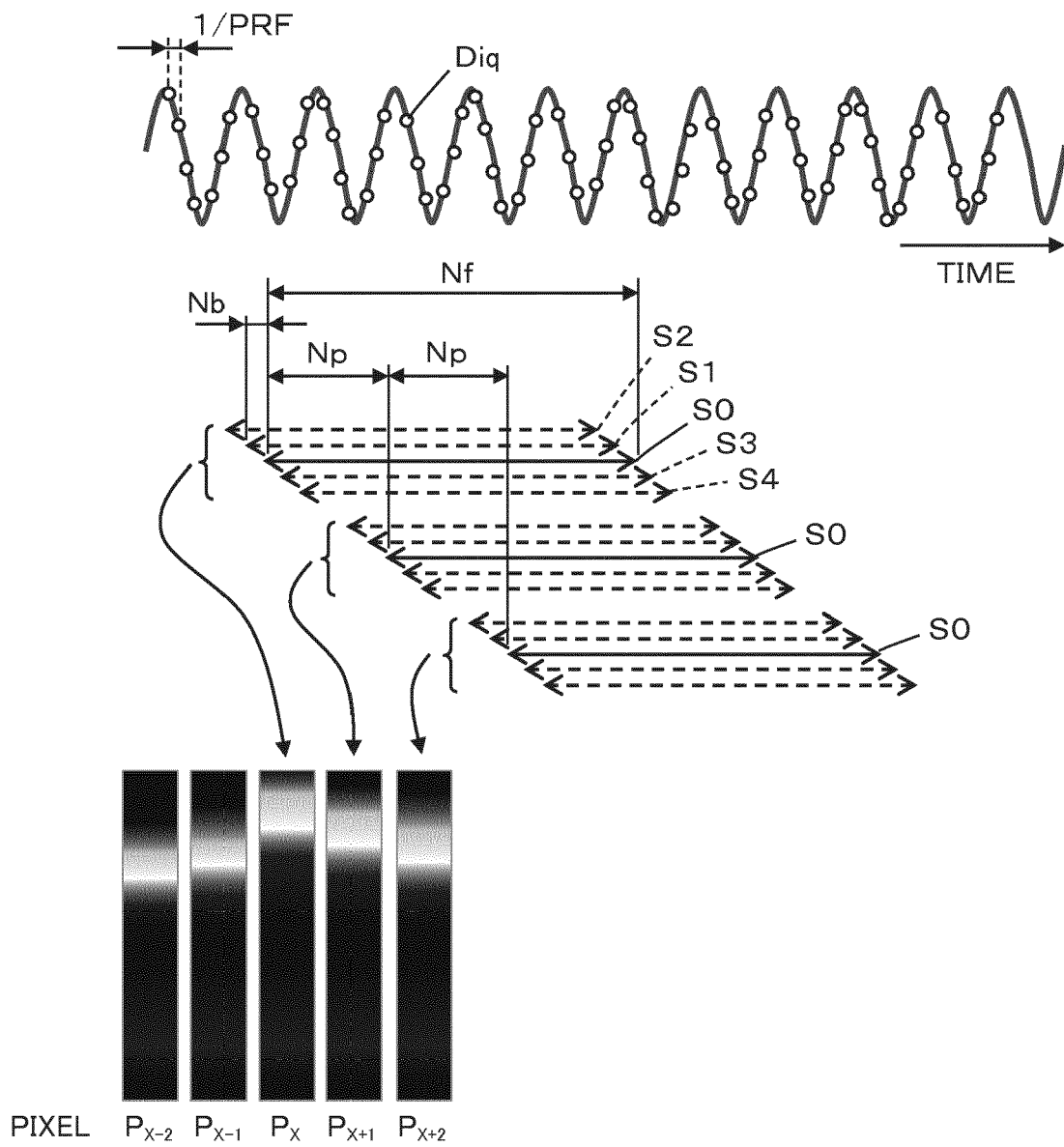


FIG. 6

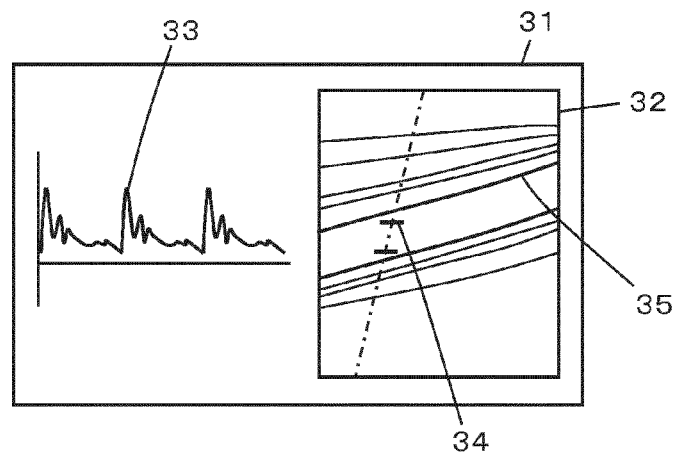


FIG. 7A

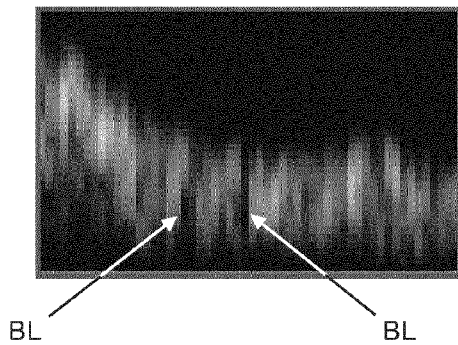


FIG. 7B

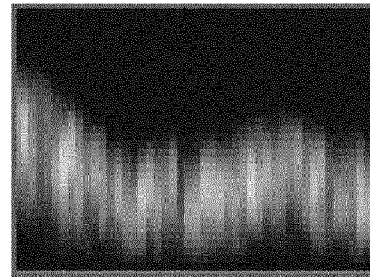
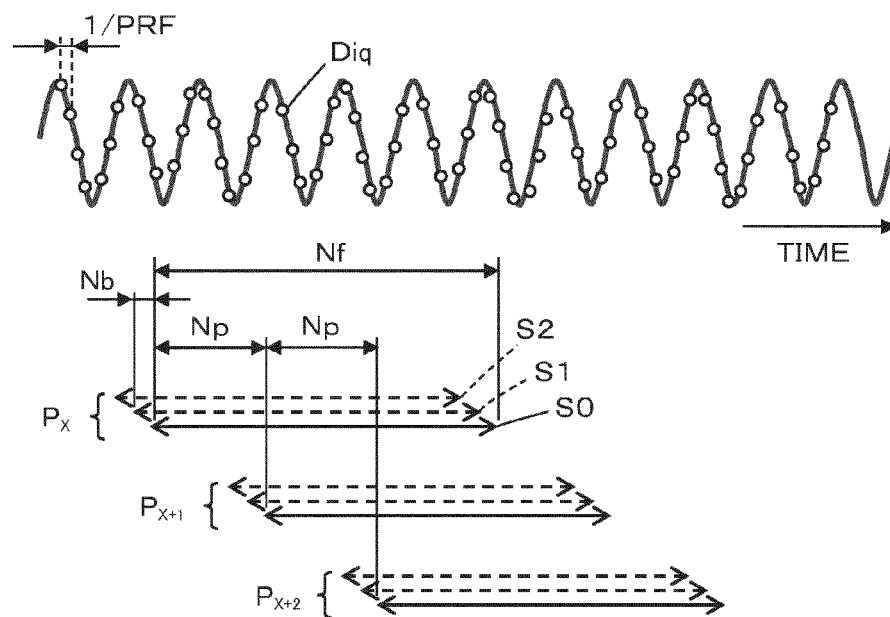


FIG. 8





EUROPEAN SEARCH REPORT

 Application Number
 EP 16 18 3089

5

10

15

20

25

30

35

40

45

50

55

DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (IPC)
X	US 2005/080329 A1 (UCHIBORI TAKANOBU [JP]) 14 April 2005 (2005-04-14) * abstract; figures 2, 3, 5A * * paragraphs [0040], [0042] - [0049] * * paragraphs [0053] - [0056], [0059] *	1-8	INV. G01S15/89 G01S7/52 A61B8/08
A	US 2006/084873 A1 (BABA TATSURO [JP] ET AL) 20 April 2006 (2006-04-20) * abstract; figure 2B * * paragraph [0041] - paragraph [0059] *	1,6,8	
			TECHNICAL FIELDS SEARCHED (IPC)
			G01S A61B
The present search report has been drawn up for all claims			
Place of search Munich		Date of completion of the search 8 December 2016	Examiner Knoll, Bernhard
CATEGORY OF CITED DOCUMENTS X : particularly relevant if taken alone Y : particularly relevant if combined with another document of the same category A : technological background O : non-written disclosure P : intermediate document T : theory or principle underlying the invention E : earlier patent document, but published on, or after the filing date D : document cited in the application L : document cited for other reasons & : member of the same patent family, corresponding document			

 1
 EPO FORM 1503 03/02 (P04C01)

**ANNEX TO THE EUROPEAN SEARCH REPORT
ON EUROPEAN PATENT APPLICATION NO.**

EP 16 18 3089

5

This annex lists the patent family members relating to the patent documents cited in the above-mentioned European search report.
The members are as contained in the European Patent Office EDP file on
The European Patent Office is in no way liable for these particulars which are merely given for the purpose of information.

08-12-2016

10

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
US 2005080329 A1	14-04-2005	JP 4245428 B2	25-03-2009
		JP 2005046194 A	24-02-2005
		US 2005080329 A1	14-04-2005

US 2006084873 A1	20-04-2006	CN 1768709 A	10-05-2006
		US 2006084873 A1	20-04-2006

15

20

25

30

35

40

45

50

55

EPO FORM P0459

For more details about this annex : see Official Journal of the European Patent Office, No. 12/82

REFERENCES CITED IN THE DESCRIPTION

This list of references cited by the applicant is for the reader's convenience only. It does not form part of the European patent document. Even though great care has been taken in compiling the references, errors or omissions cannot be excluded and the EPO disclaims all liability in this regard.

Patent documents cited in the description

- JP 2003079625 A [0004]

专利名称(译)	超声诊断设备和多普勒波形图像生成方法		
公开(公告)号	EP3133419A1	公开(公告)日	2017-02-22
申请号	EP2016183089	申请日	2016-08-05
[标]申请(专利权)人(译)	富士胶片株式会社		
申请(专利权)人(译)	富士胶片株式会社		
当前申请(专利权)人(译)	富士胶片株式会社		
[标]发明人	YAMAMOTO KATSUYA		
发明人	YAMAMOTO, KATSUYA		
IPC分类号	G01S15/89 G01S7/52 A61B8/08		
CPC分类号	A61B8/06 A61B8/44 A61B8/4444 A61B8/4488 A61B8/488 A61B8/52 A61B8/54 A61B8/14 A61B8/463 A61B8/469 A61B8/5207 G01S7/52046 G01S7/52066 G01S7/52074 G01S15/8915 G01S15/8979		
审查员(译)	KNOLL伯恩哈德		
优先权	2015160356 2015-08-17 JP		
其他公开文献	EP3133419B1		
外部链接	Espacenet		

摘要(译)

超声波诊断装置包括：正交检测部，被配置为对由接收电路生成的接收射频数据执行正交检测以生成复数数据（ Diq ）；频率分析器，被配置为使用组（ $S0$ ）执行第一频率分析从第一起始点开始的采样点的集合数（ Nf ）的复数数据（ Diq ）和使用第一起始点的复数数据（ Diq ）的至少一个组（ $S1, \dots, S4$ ）的第二频率分析从与所述第一起始点不同的第二起始点开始的样本点的集合数（ Nf ），并基于所述第一频率分析的结果和所述第二频率的结果，获取与多普勒波形图像的每个像素对应的频谱信号分析，以及多普勒波形图像生成器，被配置为使用所述频谱信号生成所述多普勒波形图像。

