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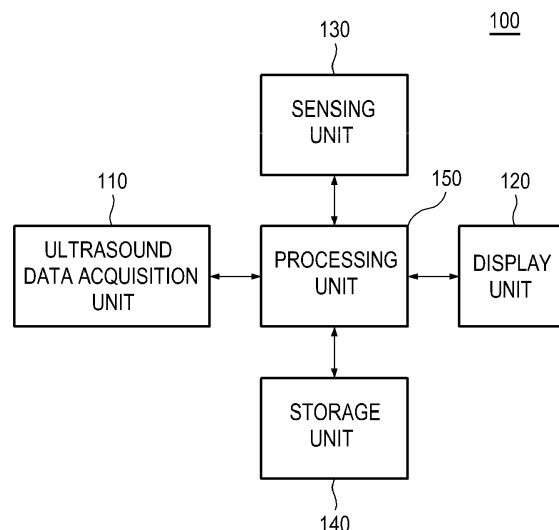
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(54) **Ultrasound system for providing an ultrasound image optimized for posture of a user**

(57) An ultrasound data acquisition unit configured to transmit ultrasound signals to a target object and receive ultrasound echo signals reflected from the target object to thereby acquire ultrasound data; a display unit including a monitor and being configured to display an ultrasound image; a sensing unit installed on one side of the monitor and being configured to detect a position of a user, a distance between the user and the monitor, a height of the user with respect to the monitor and a viewing angle of the user toward the monitor to thereby form

and output sensing signals corresponding thereto; a storage unit configured to store optimal posture information for providing an optimal ultrasound image for the posture of the user; and a processing unit coupled to the ultrasound data acquisition unit, the sensing unit and the storage unit; the processing unit being configured to form the ultrasound image by using the ultrasound data and perform an optimal image processing for the posture of the user upon the ultrasound image based on the sensing signals and the optimal posture information.

FIG. 1



Description

CROSS-REFERENCE TO RELATED APPLICATION

[0001] This application is based upon and claims the benefit of priority from Korean Patent Application No. 10-2010-0119282 filed on November 29, 2010.

TECHNICAL FIELD

[0002] The present invention generally relates to ultrasound systems, and more particularly to an ultrasound system for providing an ultrasound image optimized according to the posture of a user.

BACKGROUND

[0003] An ultrasound system with non-invasive and non-destructive nature has been extensively used in the medical field to obtain information on an inside of a target object. Such an ultrasound system provides a doctor in real time with a high resolution image of the inside of the target object without the need to perform any surgical operation, which can be used to play an important role in the medical field.

[0004] The ultrasound system transmits ultrasound signals to the target object, receives the ultrasound signals (i.e., ultrasound echo signals) reflected from the target object, and performs signal processing upon the received ultrasound echo signals to thereby acquire ultrasound data. The ultrasound system performs scan conversion or rendering processing upon the acquired ultrasound data to form an ultrasound image. When using the ultrasound system, a user adjusts manually a position and/or an angle of a monitor in a three-dimensional direction (e.g., up/down and/or right/left) according to a position (i.e., posture) of the user. Such an ultrasound system is not user-friendly since the user adjusts manually the position and/or the angle of the monitor while acquiring the ultrasound images of the target object. Further, since the ultrasound system provides a fixed ultrasound image regardless of the posture of the user, the user must change his/her posture to see the ultrasound image displayed on the monitor.

SUMMARY

[0005] The present invention provides some embodiments of an ultrasound system for detecting the posture of a user and providing an optimal ultrasound image for the posture of the user.

[0006] According to one embodiment of the present invention, an ultrasound system comprises: an ultrasound data acquisition unit configured to transmit ultrasound signals to a target object and receive ultrasound echo signals reflected from the target object to thereby acquire ultrasound data; a display unit including a monitor configured to display an ultrasound image; a sensing unit

installed on one side of the monitor and configured to detect a position of a user, a distance between the user and the monitor, a height of the user with respect to the monitor and a viewing angle of the user toward the monitor to thereby form and output sensing signals corresponding thereto; a storage unit configured to store optimal posture information for providing an optimal ultrasound image for the posture of the user; and a processing unit coupled to the ultrasound data acquisition unit, the sensing unit and the storage unit, the processing unit being configured to form the ultrasound image by using the ultrasound data and perform an optimal image processing for the posture of the user upon the ultrasound image based on the sensing signals and the optimal posture information.

BRIEF DESCRIPTION OF THE DRAWINGS

[0007]

FIG. 1 is a block diagram showing an ultrasound system according to a first embodiment.

FIG. 2 is a block diagram showing an ultrasound data acquisition unit according to the first embodiment.

FIG. 3 is a schematic diagram showing an example of a sensing unit according to the first embodiment.

FIG. 4 is a schematic diagram showing another example of a sensing unit according to the first embodiment.

FIG. 5 is a flow chart showing a process of forming an optimal ultrasound image for posture of a user in accordance with the first embodiment.

FIG. 6 is a block diagram showing an ultrasound system according to a second embodiment.

FIG. 7 is a schematic diagram showing an example of a display unit according to the second embodiment.

FIG. 8 is a schematic diagram showing an example of a sensing unit according to the second embodiment.

FIG. 9 is a schematic diagram showing another example of a sensing unit according to the second embodiment.

FIG. 10 is a flow chart showing a process of forming an optimal ultrasound image for posture of a user in accordance with the second embodiment.

DETAILED DESCRIPTION

[0008] A first embodiment of the present disclosure will now be described in detail with reference to the drawings.

First Embodiment

[0009] FIG. 1 is a block diagram showing an ultrasound system according to a first embodiment of the present disclosure. Referring to FIG. 1, an ultrasound system 100 includes an ultrasound data acquisition unit 110, a display unit 120, a sensing unit 130, a storage unit 140 and a processing unit 150.

[0010] The ultrasound data acquisition unit 110 is configured to transmit ultrasound signals to a target object and receive the ultrasound signals (i.e., ultrasound echo signals) reflected from the target object to thereby acquire ultrasound data.

[0011] FIG. 2 is a block diagram showing the ultrasound data acquisition unit according to the first embodiment. Referring to FIG. 2, the ultrasound data acquisition unit 110 includes an ultrasound probe 210, a transmit signal generating section 220, a beam forming section 230 and an ultrasound data forming section 240.

[0012] The ultrasound probe 210 includes a plurality of transducer elements (not shown) configured to perform reciprocal conversion between electric signals and ultrasound signals. The ultrasound probe 210 is operable to transmit the ultrasound signals to the target object along each of a plurality of scan lines (not shown) and receive the ultrasound echo signals reflected from the target object, thereby forming receive signals. The receive signal is an analog signal. The ultrasound probe 210 may be at least one of a convex probe, a linear probe and the like.

The transmit signal generating section 220 is configured to control transmission of the ultrasound signals. The transmit signal generating section 220 is configured to generate the transmit signals for acquiring an ultrasound image in consideration of the transducer elements and focal points. The ultrasound image includes a brightness mode (B-mode) image, a spectral Doppler image, a color Doppler image, a three-dimensional ultrasound image, an elasticity image and the like. The ultrasound probe 210 is operable to convert the transmit signals provided from the transmit signal generating section 220 into the ultrasound signals and transmit the ultrasound signals to the target object. Further, the ultrasound probe 210 is operable to receive the ultrasound echo signals reflected from the target object to thereby form the receive signals.

[0013] The beam forming section 230 is configured to form digital signals by performing analog-to-digital conversion on the receive signals outputted from the ultrasound probe 210. The beam forming section 230 is further configured to form receive-focused beams by receive-focusing the digital signals in consideration of the transducer elements and the focal points.

[0014] The ultrasound data forming section 240 is con-

figured to form the ultrasound data corresponding to the ultrasound image by using the receive-focused beams provided from the beam forming section 230. The ultrasound data includes radio frequency (RF) data or in-phase/quadrature (IQ) data, although the ultrasound data may not be limited thereto. Further, the ultrasound data forming section 240 is also configured to perform a variety of signal processing (e.g., gain adjustment, etc.), which is necessary to form the ultrasound data, upon the receive-focused beams.

[0015] Referring back to FIG. 1, the display unit 120 displays the ultrasound image. In the present embodiment, the display unit 120 includes a monitor 121 (shown in FIGS. 3 and 4), the position and angle of which can be adjusted manually up and down and/or right and left, or a monitor fixed to the ultrasound system 100.

[0016] The sensing unit 130 may be installed on one side of the monitor 121. The sensing unit 130 is configured to detect a position of the user, a distance between the user and the monitor 121, a height of the user with respect to the monitor 121 and a viewing angle of the user toward the monitor 121 to thereby form and output the sensing signals corresponding thereto.

[0017] In one example, as shown in FIG. 3, the sensing unit 130, which is installed on one side (e.g., frame) of the monitor 121, includes first sensors FS₁ to FS₄ configured to detect the position of the user, the distance between the user and the monitor 121, the height of the user with respect to the monitor 121 and the viewing angle of the user toward the monitor 121 to thereby form and output the sensing signals corresponding thereto. Any device may be employed as the first sensors FS₁ to FS₄ as long as the device can detect the position of the user, the distance between the user and the monitor 121, the height of the user with respect to the monitor 121 and the viewing angle of the user toward the monitor 121, and form and output the sensing signals corresponding thereto. For example, the first sensors FS₁ to FS₄ may include at least one of a camera, a webcam and the like. The first sensors FS₁ to FS₄ may be provided inside or outside the monitor 121.

[0018] While the sensing unit 130 includes four first sensors FS₁ to FS₄ in the above-described example, one of ordinary skill in the art may fully understand that the number as well as the position of the first sensors can be varied as necessary, and not be limited to those described in the example.

[0019] In another example, as shown in FIG. 4, the sensing unit 130, which is installed on one side (i.e., frame) of the monitor 121, includes first sensors (FS₁ to FS₄) configured to detect the position of the user, the height of the user with respect to the monitor 121 and the viewing angle of the user toward the monitor 121 to thereby form and output first sensing signals corresponding thereto. The sensing unit 130 further includes second sensors SS₁ and SS₂ configured to detect the distance between the user and the monitor 121 to form and output second sensing signals corresponding thereto. Any de-

vice may be employed as the second sensors SS_1 and SS_2 as long as the device can detect the distance between the user and the monitor 121, and form and output the sensing signals corresponding thereto. For example, the second sensors SS_1 and SS_2 may include a distance detecting sensor. The second sensors SS_1 and SS_2 may be provided inside or outside the monitor 121.

[0020] While the sensing unit 130 includes two second sensors SS_1 and SS_2 in the above-described example, one of ordinary skill in the art will fully understand that the number as well as the position of the second sensor can be varied as necessary, and not be limited to those described in this example.

[0021] The storage unit 140 is configured to store optimal posture information necessary for providing optimal ultrasound image according to the posture of the user. In the present embodiment, the optimal posture information may include information on the optimal distance between the user and the monitor 121, the optimal height of the user with respect to the monitor 121 and the optimal viewing angle of the user toward the monitor 121.

[0022] The processing unit 150 is coupled to the ultrasound data acquisition unit 110, the sensing unit 130 and the storage unit 140. The processing unit 150 includes at least one of a central processing unit (CPU), a micro-processor, a graphic processing unit (GPU) and the like.

[0023] FIG. 5 is a flow chart showing a process of forming the optimal ultrasound image for the posture of the user in accordance with the first embodiment. Referring to FIG. 5, the processing unit 150 is configured to produce the ultrasound image by using the ultrasound data provided from the ultrasound data acquisition unit 110 at S502. The ultrasound image is produced through scan conversion or rendering processing. The produced ultrasound image may be displayed on the monitor 121 of the display unit 120.

[0024] The processing unit 150 is configured to form posture information, which indicates the posture of the user with respect to the monitor 121, based on the sensing signals provided from the sensing unit 130 at S504. In the present embodiment, the posture information includes the distance between the user and the monitor 121, the height of the user with respect to the monitor 121 and the viewing angle of the user toward the monitor 121. However, the posture information may not be limited thereto.

[0025] In one example, if the sensing signals are provided from the first sensors FS_1 to FS_4 , then the processing unit 150 is configured to detect the user's face (more preferably, the user's eyes) by using the provided sensing signals. The user's face can be detected through vision recognition (i.e., image recognition) and the like. By using the detected user's face as a reference point, the processing unit 150 may calculate the distance between the monitor 121 and the user, the height of the user with respect to the monitor 121 (i.e., height of the user's eyes with respect to the monitor 121) and the viewing angle of the user toward the monitor 121. Calculation of the

distance, height and viewing angle can be performed by using a variety of well-known methods so that the detailed description thereof will be omitted in the present embodiment. In this way, the processing unit 150 may form the posture information including the calculated distance, height and viewing angle.

[0026] In another example, if the first sensing signals are provided from the first sensors FS_1 to FS_4 , then the processing unit 150 is configured to detect the user's face (more preferably, the user's eyes) by using the provided first sensing signals. The processing unit 150 is configured to calculate the height of the user with respect to the monitor 121 (i.e., height of the user's eyes with respect to the monitor 121) and the viewing angle of the user toward the monitor 121 by utilizing the detected user's face as a reference point. Further, if the second sensing signals from the second sensors SS_1 and SS_2 , then the processing unit 150 is configured to calculate the distance between the monitor 121 and the user by using the provided second sensing signals. In this way, the processing unit 150 is configured to form the posture information including the calculated distance, height and viewing angle.

[0027] The processing unit 150 is configured to extract the optimal posture information from the storage unit 140 at S506 and compare the extracted optimal posture information with the posture information to thereby acquire posture difference information at S508. The posture difference information includes respective differential values of the distance, height and viewing angle.

[0028] The processing unit 150 is configured to perform image processing upon the ultrasound image based on the posture difference information and the posture information to obtain the optimal ultrasound image for the position of the user at S510. The ultrasound image with the optimal image processing performed may be displayed on the monitor 121 of the display unit 120.

[0029] In one example, if the ultrasound image is a two-dimensional or three-dimensional ultrasound image and the posture difference information includes the differential value of the distance, then the processing unit 150 may magnify or downscale the ultrasound image in proportion to the distance differential value included in the posture difference information. In another example, if the ultrasound image is a two-dimensional or three-dimensional ultrasound image and the posture difference information includes the differential value of the viewing angle, then the processing unit 150 is configured to vertically or horizontally magnify/downscale the ultrasound image, or tilt or extend the ultrasound image toward the user, in proportion to the viewing angle differential value included in the posture difference information. In another example, if the ultrasound image is a three-dimensional ultrasound image and the posture difference information includes the differential value of the viewing angle, then the processing unit 150 may rotate the three-dimensional ultrasound image based on the viewing angle differential value included in the posture difference information.

Second Embodiment

[0030] FIG. 6 is a block diagram showing a configuration of an ultrasound system in accordance with a second embodiment. Referring to FIG. 6, an ultrasound system 600 includes an ultrasound data acquisition unit 610, a display unit 620, a sensing unit 630, a storage unit 640 and a processing unit 650.

[0031] The ultrasound data acquisition unit 610 is configured to transmit ultrasound signals to a target object and receive the ultrasound echo signals reflected from the target object to thereby acquire ultrasound data corresponding to an ultrasound image. The ultrasound data acquisition unit 610 in the present embodiment may be identically configured with the ultrasound data acquisition unit 110 in the first embodiment and thus will not be described in detail in this embodiment.

[0032] The display unit 620 displays the ultrasound image. In the present embodiment, the display unit 620 includes a monitor 710 configured to display the ultrasound image, a driving section 720 configured to move the monitor 710 in a three-dimensional direction (e.g., back/forth or right/left) and a supporting section 730 configured to support the driving section 720, as shown in FIG. 7. The driving section 720 may be embodied with the well-known devices so that the detailed description thereof will be omitted in the present embodiment.

[0033] The sensing unit 630 is installed on one side of the monitor 710. The sensing unit 630 is configured to detect a position of the user, a distance between the user and the monitor 710, a height of the user with respect to the monitor 710, a viewing angle of the user toward the monitor 710 and a three-dimensional position of the monitor 710 to thereby form and output sensing signals corresponding thereto.

[0034] In one example, as shown in FIG. 8, the sensing unit 630, which is installed on one side (e.g., frame) of the monitor 710, includes first sensors FS_1 to FS_4 configured to detect the position of the user, the distance between the user and the monitor 710, the height of the user with respect to the monitor 710 and the viewing angle of the user toward the monitor 710 to thereby form and output first sensing signals corresponding thereto. The sensing unit 630 further includes second sensors TS_1 to TS_4 configured to detect a current posture (i.e., position) of the monitor 710 against the predetermined reference position of the monitor to thereby form and output second sensing signals corresponding thereto.

[0035] In the embodiment, any device may be employed as the first sensors FS_1 to FS_4 as long as the device can detect the position of the user, the distance between the user and the monitor 710, the height of the user with respect to the monitor and the viewing angle of the user toward the monitor 710, and form and output the sensing signals corresponding thereto. For example, the first sensors FS_1 to FS_4 include at least one of a camera, a webcam and the like. The first sensors FS_1 to FS_4 may be provided inside or outside the monitor 710.

Further, any device may be employed as the second sensors TS_1 to TS_4 as long as the device can detect the current attitude (i.e., position) of the monitor 710 against the predetermined reference position of the monitor, and form and output the sensing signals corresponding thereto. For example, the second sensors TS_1 to TS_4 include at least one of a gyro sensor, a tilt sensor and the like. The second sensors TS_1 to TS_4 may be provided inside or outside the monitor 710.

[0036] While the sensing unit 630 includes four first sensors FS_1 to FS_4 and four second sensors TS_1 to TS_4 in the above-described example, one of ordinary skill in the art will fully understand that the numbers as well as the positions of the first and second sensors can be varied as necessary, and not be limited to those described in this example.

[0037] In another example, as shown in FIG. 9, the sensing unit 630, which is installed on one side (e.g., frame) of the monitor 710, includes first sensors FS_1 to FS_4 configured to detect the position of the user, the height of the user with respect to the monitor 710 and the viewing angle of the user toward the monitor 710 to thereby form and output first sensing signals corresponding thereto. The sensing unit 630 further includes second sensors TS_1 to TS_4 configured to detect the current attitude (i.e., position) of the monitor 710 against the predetermined reference position of the monitor to thereby form and output second signals corresponding thereto. The sensing unit 630 further includes third sensors SS_1 to SS_4 configured to detect the distance between the user and the monitor 710 to thereby form and output third sensing signals corresponding thereto. Any device may be employed as the third sensors SS_1 to SS_4 as long as the device can detect the distance between the user and the monitor 710, and form and output the sensing signals corresponding thereto. For example, the third sensors SS_1 to SS_4 include a distance detecting sensor. The third sensors SS_1 to SS_4 may be provided inside or outside the monitor 710.

[0038] While the sensing unit 630 includes four first sensors FS_1 to FS_4 , four second sensors TS_1 to TS_4 and four third sensors SS_1 to SS_4 in the above-described example, one of ordinary skill in the art will fully understand that the numbers as well as the positions of the first to third sensors can be varied as necessary, and not be limited to those described in this example.

[0039] The storage unit 640 is configured to store optimal posture information for providing optimal ultrasound image for the posture of the user. In the present embodiment, the optimal posture information includes information on the optimal distance between the user and the monitor 710, the optimal height of the user with respect to the monitor 710 and the optimal viewing angle of the user toward the monitor 710.

[0040] The processing unit 650 is coupled to the ultrasound data acquisition unit 610, the display unit 620, the sensing unit 630 and the storage unit 640. The processing unit 650 includes at least one of a central processing

unit (CPU), a microprocessor unit, a graphic processing unit (GPU) and the like.

[0041] FIG. 10 is a flow chart showing a process of forming the optimal ultrasound image for the user's posture in accordance with the second embodiment. Referring to FIG. 10, the processing unit 650 is configured to produce the ultrasound image by using the ultrasound data provided from the ultrasound data acquisition unit 610 at S1002. The ultrasound image is displayed on the monitor 710 of the display unit 620. The ultrasound image is produced through scan conversion or rendering processing.

[0042] The processing unit 650 is configured to form posture information based on the sensing signals provided from the sensing unit 630 at S1004. In the present embodiment, the posture information includes first posture information indicating the posture of the user with respect to the monitor 710 and second posture information indicating the position (i.e., attitude) of the monitor 710. The first posture information includes the distance between the user and the monitor 710, the height of the user with respect to the monitor 710 and the viewing angle of the user toward the monitor 710. However, the posture information may not be limited thereto.

[0043] In one example, if the first sensing signals are provided from the first sensors FS_1 to FS_4 , then the processing unit 650 is configured to detect the user's face (more preferably, the user's eyes) by using the provided first sensing signals. The user's face is detected through vision recognition (i.e., image recognition) and the like. By using the detected user's face as a reference point, the processing unit 650 is configured to calculate the distance between the monitor 710 and the user, the height of the user with respect to the monitor 710 (i.e., height of the user's eyes with respect to the monitor 710) and the viewing angle of the user toward the monitor 710. The distance, height and viewing angle can be calculated by using a variety of well-known methods so that the detailed description thereof will be omitted in the present embodiment. In this way, the processing unit 650 is configured to form the first posture information including the calculated distance, height and viewing angle. Further, the processing unit 650, provided with the second sensing signals from the second sensors TS_1 to TS_4 , is configured to form the second posture information indicating the current attitude (e.g., tilt, rotation, etc.) of the monitor 710 by using the second sensing signals.

[0044] In another example, provided with the first sensing signals from the first sensors FS_1 to FS_4 , the processing unit 650 is configured to detect the user's face (more preferably, the user's eyes) by using the first sensing signals. The processing unit 650 is configured to calculate the height of the user with respect to the monitor 710 (i.e., height of the user's eyes with respect to the monitor 710) and the viewing angle of the user toward the monitor 710 by utilizing the detected user's face as a reference point. Further, the processing unit 650, provided with the third sensing signals from the third sensors SS_1 to SS_4 ,

may be configured to calculate the distance between the monitor 710 by using the third sensing signals. In this way, the processing unit 650 may be configured to form the first posture information including the calculated distance, height and viewing angle. Furthermore, the processing unit 650, provided with the second sensing signals from the second sensors TS_1 to TS_4 , may form the second posture information indicating the current attitude (e.g., tilt, rotation, etc.) of the monitor 710 by using the second sensing signals.

[0045] The processing unit 650 is configured to extract the optimal posture information from the storage unit 640 at S1006 and compare the extracted optimal posture information with the posture information to thereby acquire posture difference information at S1008. The posture difference information may include respective differential values of the distance, height and viewing angle. However, the posture information may not be limited thereto.

[0046] The processing unit 650 is configured to compute a moving range of the monitor 710 based on the posture difference information at S1010. In this embodiment, the moving range is the range within which the monitor 710 may be moved to face the user's full face. The moving range is computed by using various well-known methods. Thus, it will not be described in detail in the present embodiment.

[0047] Based on the posture information (i.e., the second posture information), the processing unit 650 is configured to compute a movable range, which is the maximum range within which the monitor 710 can be moved in a three-dimensional direction (e.g., back/forth, right/left or the like) to face the user's full face at S1012.

[0048] The processing unit 650 is configured to compare the computed moving range with the computed movable range at S1014. If it is determined that the moving range exceeds the movable range, then the processing unit 650 may move the monitor 710 as widely as the movable range by driving the driving section 720 at S1016. The processing unit 650 is configured to perform image processing upon the ultrasound image to obtain the optimal image for the posture of the user at S1018. For example, the processing unit 650 is configured to calculate the differential value between the moving range and the movable range and perform a process, which is similar to the step S510 in the first embodiment, in proportion to the calculated differential value.

[0049] Further, if it is determined that the moving range falls within the movable range, then the processing unit 650 may move the monitor 710 as widely as the moving range by driving the driving section 720 at S1020.

[0050] While the invention has been shown and described with reference to exemplary embodiments thereof, it will be understood by those skilled in the art that various changes in form and details may be made therein without departing from the scope of the invention as defined by the appended claims.

Claims**1.** An ultrasound system, comprising:

an ultrasound data acquisition unit configured to transmit ultrasound signals to a target object and receive ultrasound echo signals reflected from the target object to thereby acquire ultrasound data;
 a display unit including a monitor and being configured to display an ultrasound image;
 a sensing unit installed on one side of the monitor and being configured to detect a position of a user, a distance between the user and the monitor, a height of the user with respect to the monitor and a viewing angle of the user toward the monitor to thereby form and output sensing signals corresponding thereto;
 a storage unit configured to store optimal posture information necessary for providing an optimal ultrasound image according to a posture of the user; and
 a processing unit coupled to the ultrasound data acquisition unit, the sensing unit and the storage unit, the processing unit being configured to form the ultrasound image by using the ultrasound data and perform an optimal image processing for the posture of the user upon the ultrasound image based on the sensing signals and the optimal posture information.

2. The ultrasound system of Claim 1, wherein the sensing unit includes:

first sensors configured to detect the position of the user, the height of the user with respect to the monitor and the viewing angle of the user toward the monitor to thereby form and output first sensing signals corresponding thereto;
 and
 second sensors configured to detect the distance between the user and the monitor to thereby form and output second sensing signals corresponding thereto.

3. The ultrasound system of Claim 1, wherein the processing unit is configured to:

form posture information indicative of the position of the user with respect to the monitor based on the sensing signals,
 compare the optimal posture information with the posture information to form posture difference information, and
 perform the optimal image processing upon the ultrasound image based on the posture difference information and the posture information.

4. The ultrasound system of Claim 3, wherein the posture information includes the distance between the monitor and the user, the height of the user with respect to the monitor and the viewing angle of the user toward the monitor.**5.** The ultrasound system of Claim 3, wherein the processing unit is configured to:

detect the user's face based on the sensing signals, and
 calculate the distance between the monitor and the user, the height of the user with respect to the monitor and the viewing angle of the user toward the monitor by using the detected user's face as a reference point.

6. The ultrasound system of Claim 1, wherein the display unit further includes a driving section configured to move the monitor in a three-dimensional direction and the sensing unit is further configured to detect an attitude of the monitor.**7.** The ultrasound system of Claim 6, wherein the processing unit is further configured to drive the driving section to move the monitor.

FIG. 1

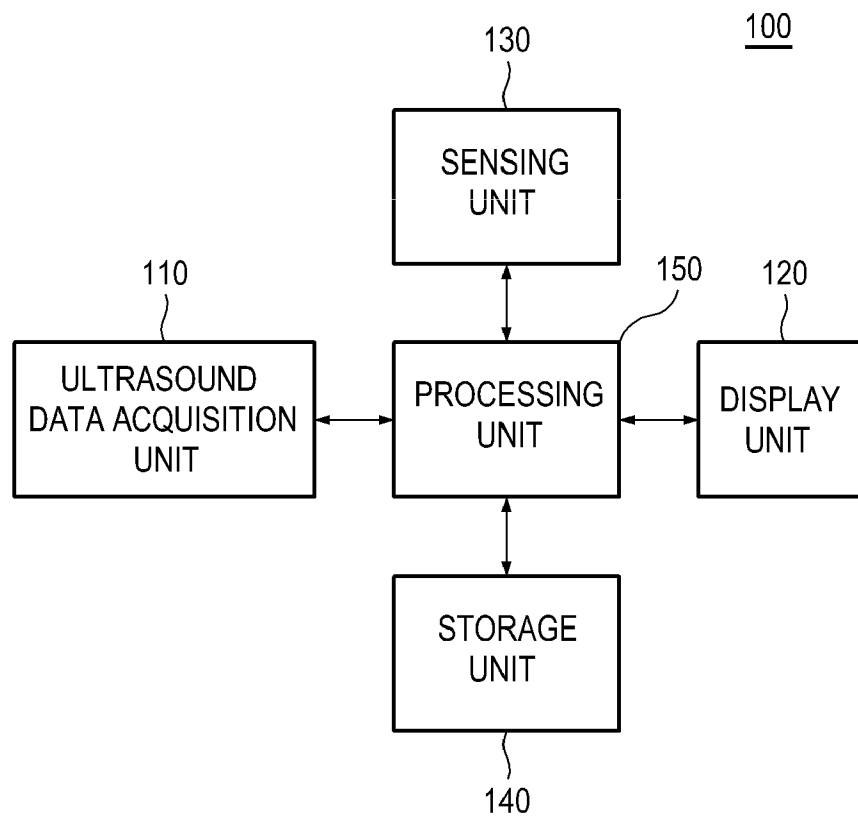


FIG. 2

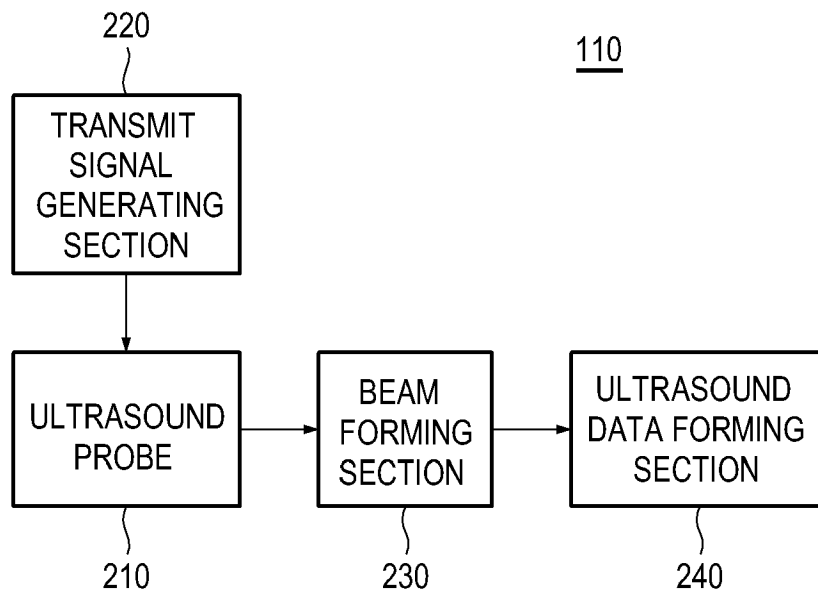


FIG. 3

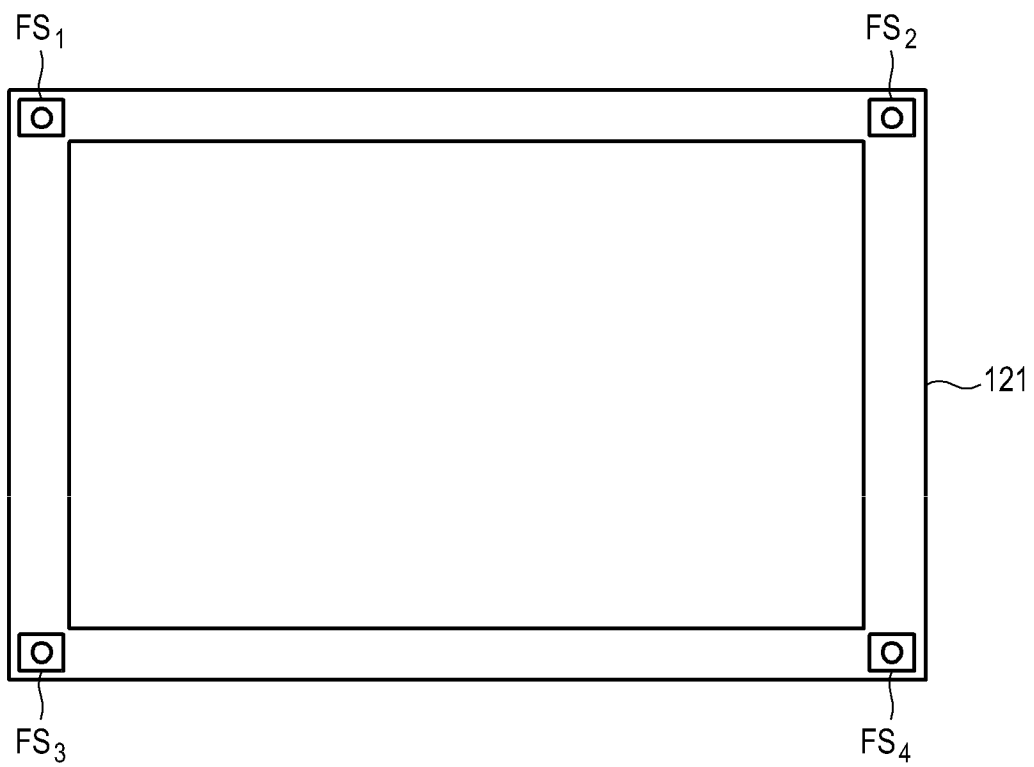


FIG. 4

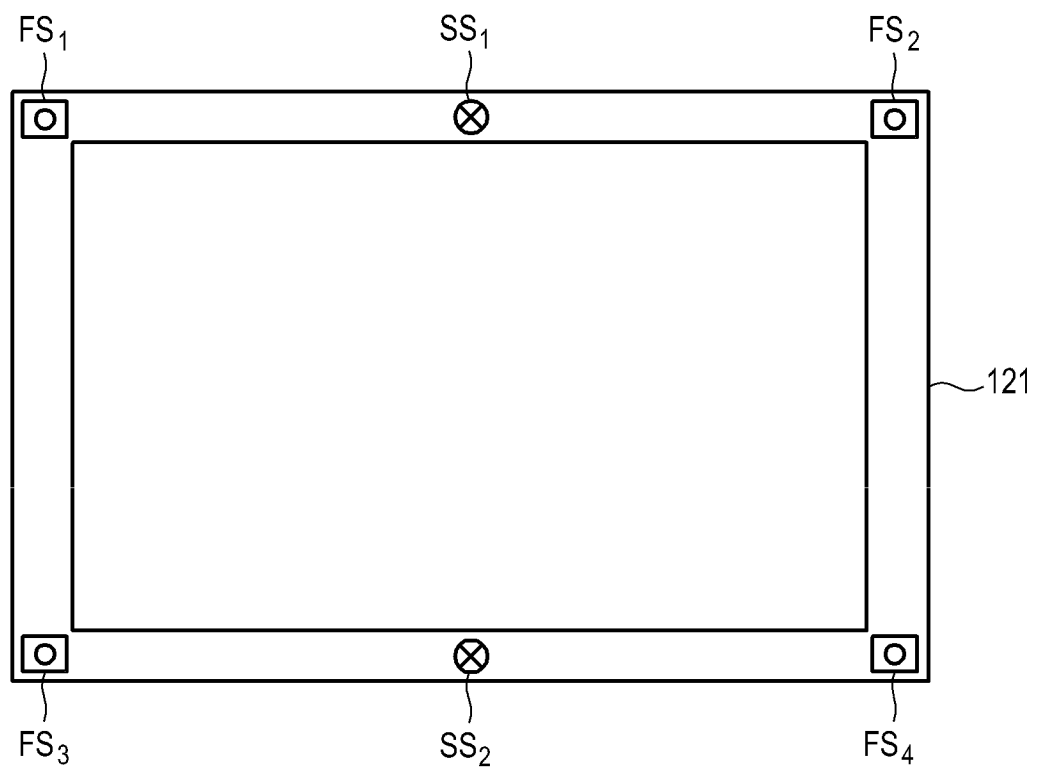


FIG. 5

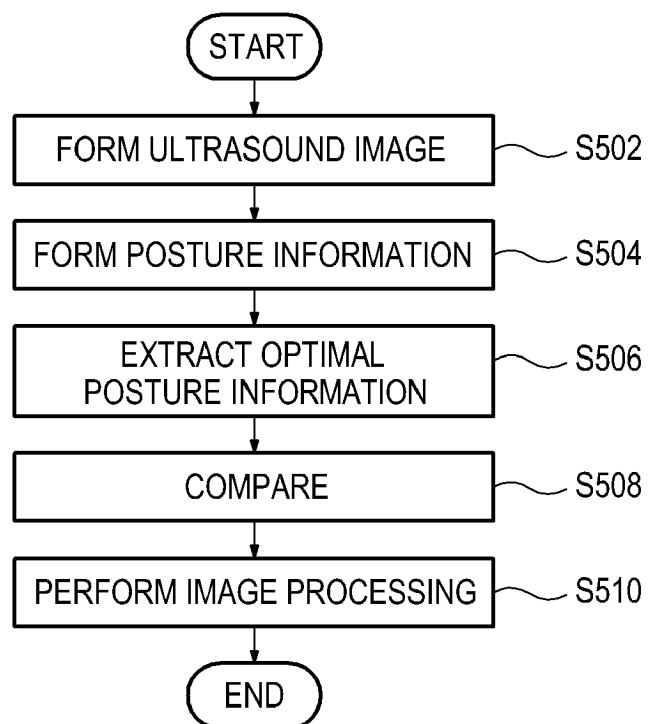


FIG. 6

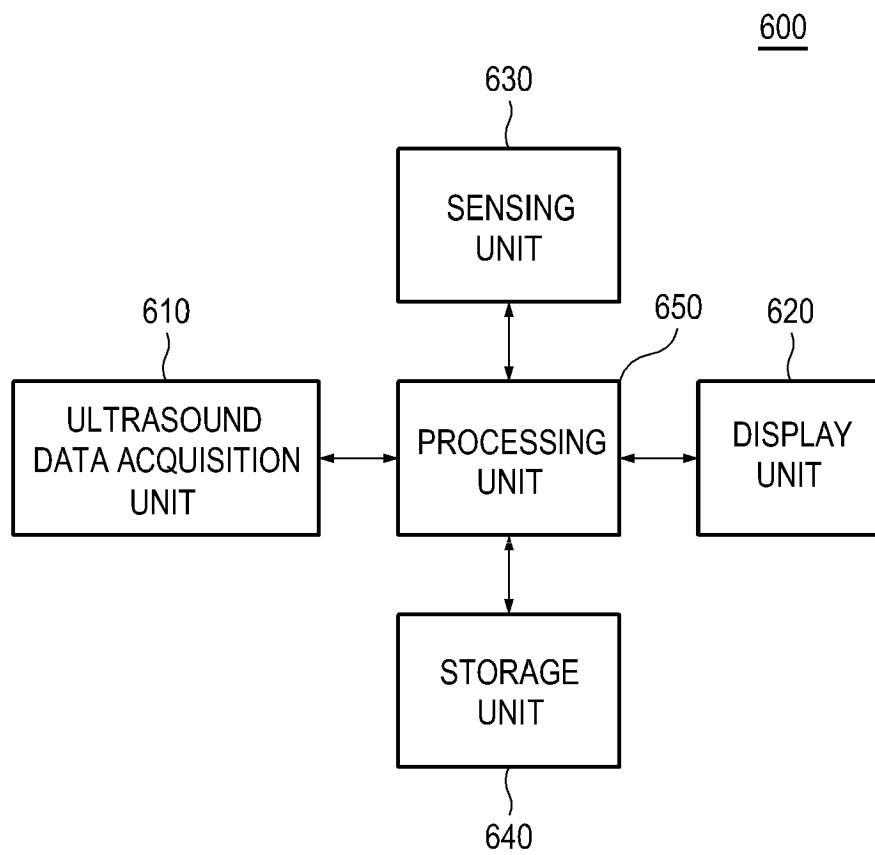


FIG. 7

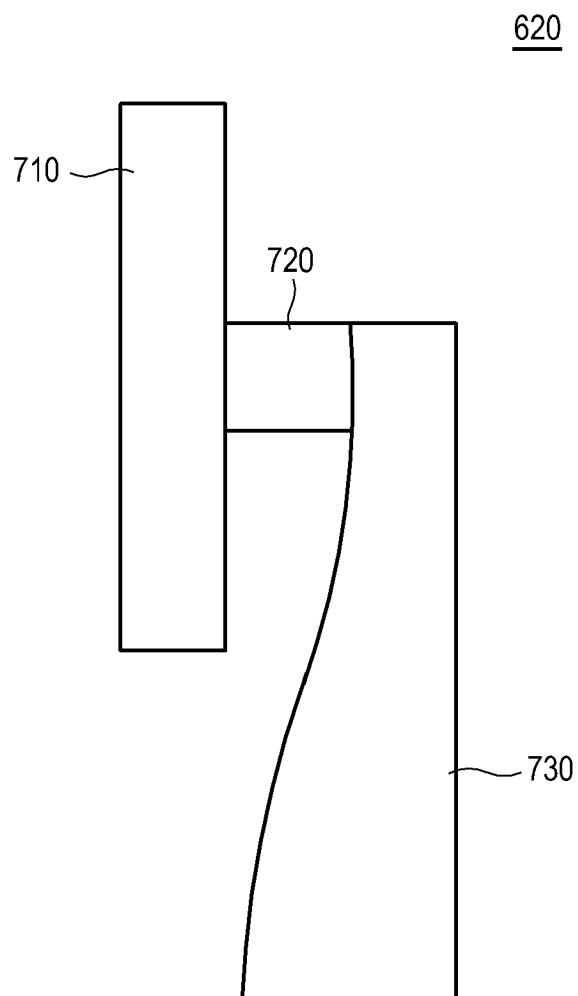


FIG. 8

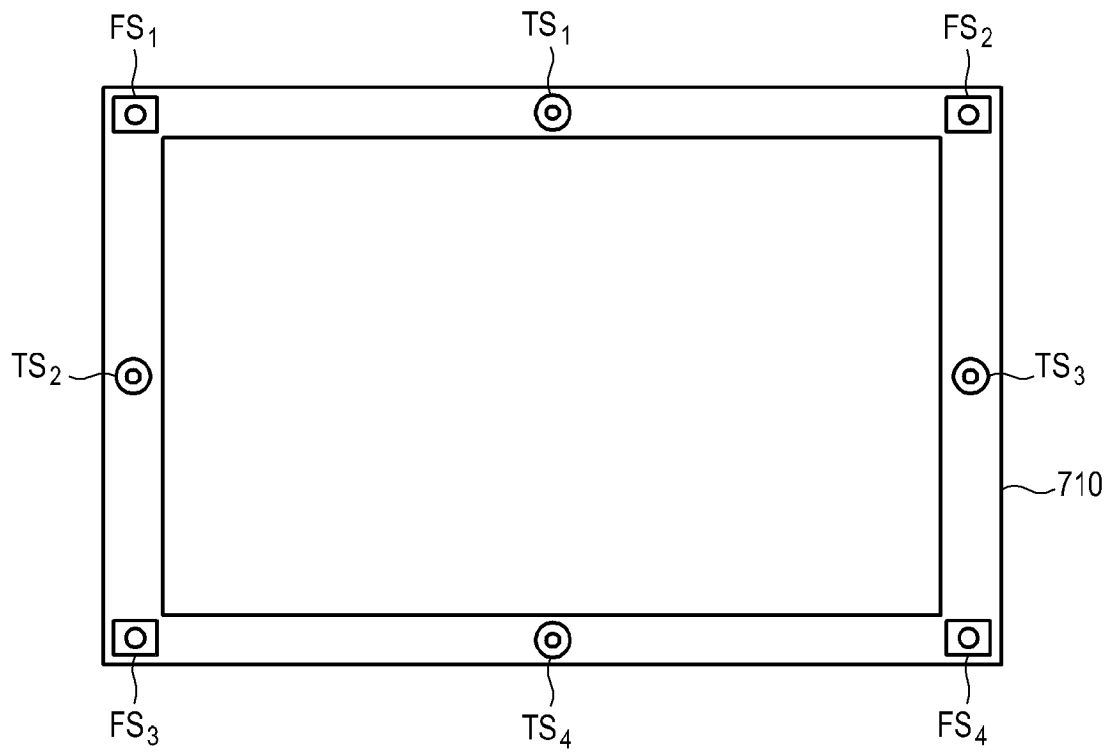


FIG. 9

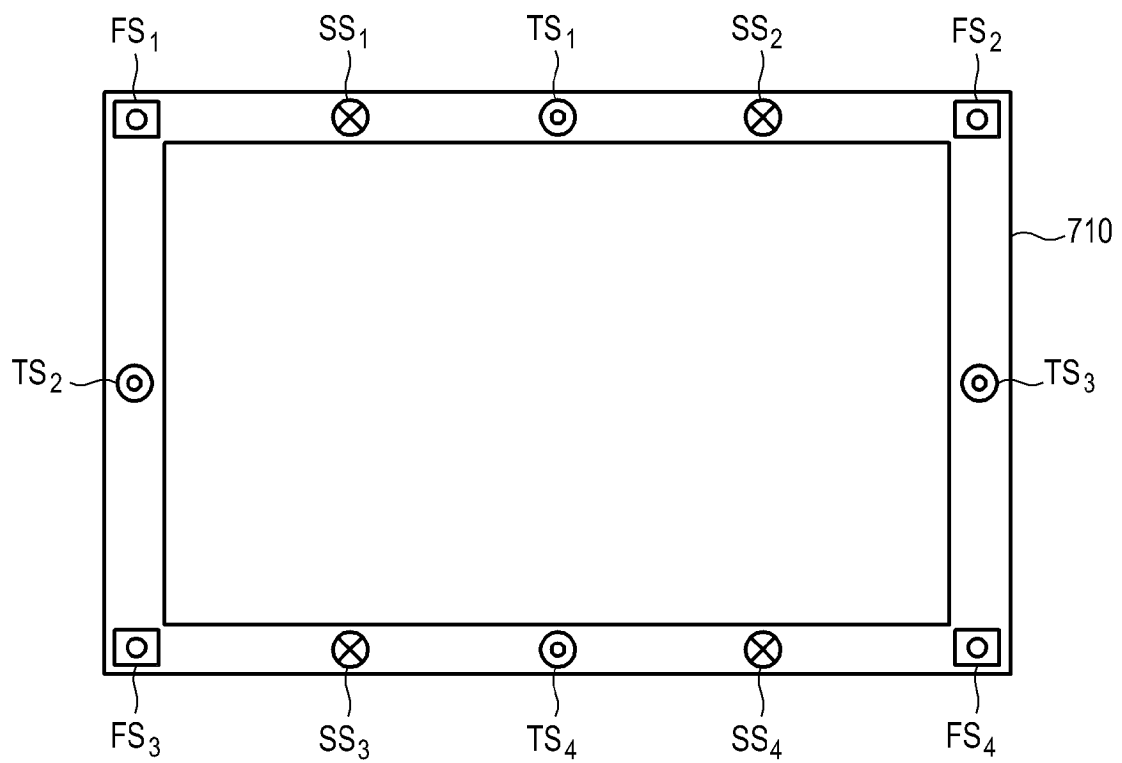
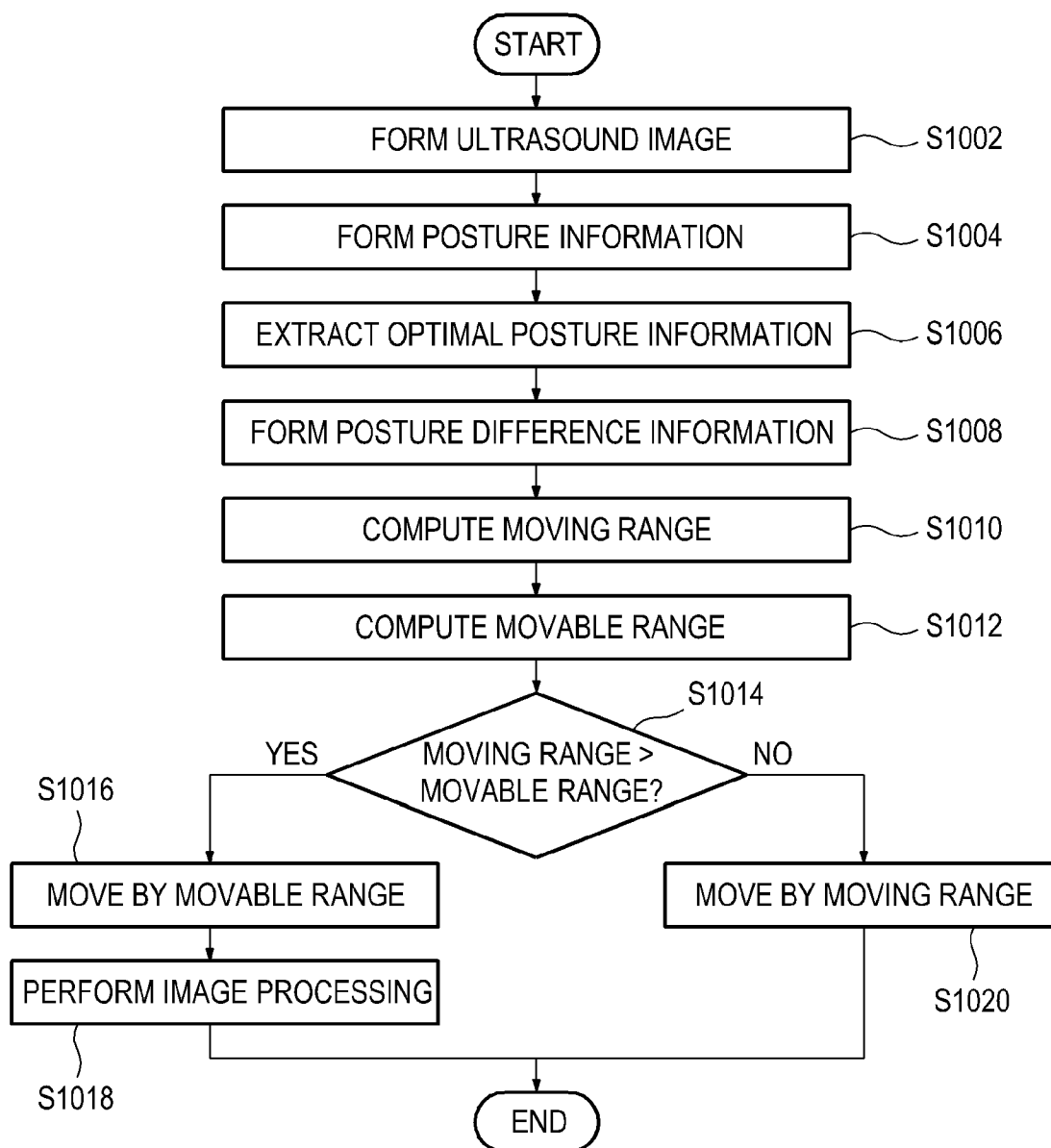


FIG. 10





EUROPEAN SEARCH REPORT

Application Number
EP 11 19 0551

DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (IPC)
A	JP 2006 167043 A (TOSHIBA CORP; TOSHIBA MEDICAL SYS CORP) 29 June 2006 (2006-06-29) * abstract * * paragraph [0010] - paragraph [0043] * * figures 1,3-6 *	1-7	INV. G06F1/16 A61B8/00 G01S7/52
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The present search report has been drawn up for all claims			
Place of search Munich		Date of completion of the search 2 March 2012	Examiner Artikis, T
CATEGORY OF CITED DOCUMENTS X : particularly relevant if taken alone Y : particularly relevant if combined with another document of the same category A : technological background O : non-written disclosure P : intermediate document T : theory or principle underlying the invention E : earlier patent document, but published on, or after the filing date D : document cited in the application L : document cited for other reasons & : member of the same patent family, corresponding document			

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EPO FORM 1503 03.82 (P04C01)

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EP 11 19 0551

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专利名称(译)	超声系统，用于提供针对用户姿势优化的超声图像		
公开(公告)号	EP2458472A1	公开(公告)日	2012-05-30
申请号	EP2011190551	申请日	2011-11-24
[标]申请(专利权)人(译)	三星麦迪森株式会社		
申请(专利权)人(译)	三星MEDISON CO. , LTD.		
当前申请(专利权)人(译)	三星MEDISON CO. , LTD.		
[标]发明人	KIM JUNG SOO		
发明人	KIM, JUNG SOO		
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代理机构(译)	SCHMID , WOLFGANG		
优先权	1020100119282 2010-11-29 KR		
其他公开文献	EP2458472B1		
外部链接	Espacenet		

摘要(译)

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