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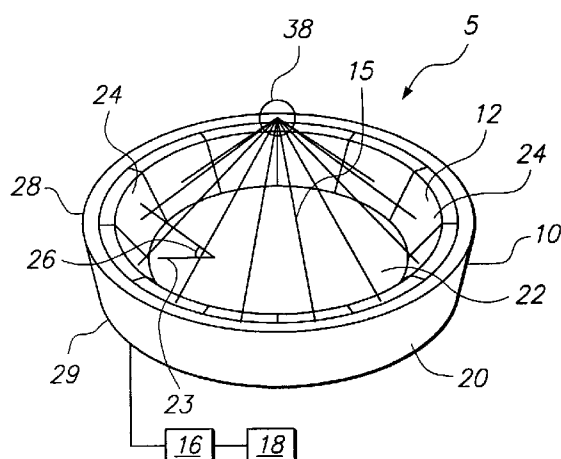
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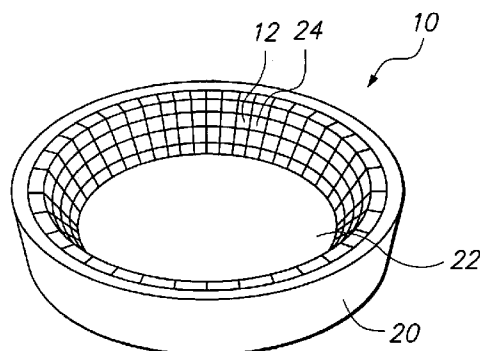
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For two-letter codes and other abbreviations, refer to the "Guidance Notes on Codes and Abbreviations" appearing at the beginning of each regular issue of the PCT Gazette.

(54) Title: FOCUSED ULTRASOUND SYSTEM FOR SURROUNDING A BODY TISSUE MASS



A



B

(57) Abstract: A focused ultrasound system includes an ultrasound transducer device forming an opening, and having a plurality of transducer elements positioned at least partially around the opening. A focused ultrasound system includes a structure having a first end for allowing an object to be inserted and a second end for allowing the object to exit, and a plurality of transducer elements coupled to the structure, the transducer elements located relative to each other in a formation that at least partially define an opening, wherein the transducer elements are configured to emit acoustic energy that converges at a focal zone.

FOCUSED ULTRASOUND SYSTEM FOR SURROUNDING
A BODY TISSUE MASS

FIELD OF INVENTION

This invention relates generally to apparatus for delivering diagnostic and/or
5 therapeutic ultrasound energy from a transducer disposed outside a body.

BACKGROUND

Devices and systems using acoustic energy, particularly within the ultrasonic
range, i.e., acoustic waves with a frequency greater than about twenty kilohertz (20kHz),
and more typically between fifty kiloHertz and ten MegaHertz (0.05-10 MHz), have been
10 used to diagnose and treat patients. Ultrasonic energy may be employed to obtain images
of a patient during a diagnostic or therapeutic procedure. In addition, ultrasound systems
have been used for treating tissue, e.g., by directing acoustic energy towards a target
tissue region within a patient, such as a cancerous or benign tumor, to coagulate, necrose,
generate mechanical damage (by cavitation) or otherwise heat the tissue region. For
15 example, one or more piezoelectric transducers may be disposed adjacent a patient's
body and used to deliver high intensity acoustic waves, such as ultrasonic waves, at an
internal tissue region of a patient to treat the tissue region. An exemplary focused
ultrasound system is disclosed in U.S. Patent No. 4,865,042 issued to Umemura et al.
The acoustic energy emitted from such a system may be focused at a desired focal zone
20 to deliver thermal energy to the target tissue region.

Focused ultrasound procedures may allow a patient to be treated while avoiding
invasive surgery. For example, a focused ultrasound system that includes a single

concave transducer has been used to treat breast, uterine and other tumors. Such transducer transmits an acoustic beam, which converges into a focus in target tissue to treat tissue. However, the acoustic beam may transverse through an organ, such as a breast nipple, or other sensitive areas, either before the beam converges into the focus (i.e., in a near field) or beyond the target tissue (i.e., in a far field). These areas have a high absorption coefficient compared to regular tissue, thereby risking damage to non targeted tissue at the near field and/or the far field. Also, in some cases, the acoustic beam may impinge on a tissue (e.g., bone tissue) that would not allow the beam to pass through by reflecting and/or absorbing most of the impinging energy. As a result, the acoustic beam may not reach the target tissue, and may generate undesired heating at the tissue surface that is blocking or interfering the acoustic beam. In some cases, the heating of bone tissue may also heat, and adversely affect, a nerve that is adjacent the bone tissue. A similar situation could happen with volumes in the body that are filled with air acting as total reflector for acoustic beam, thereby blocking the beam from propagating to the target tissue region.

Certain physical anatomy, e.g., a breast or an arm, can impose special problems in positioning an ultrasound transducer to effectively direct the ultrasound energy at the target tissue mass (e.g., a tumor underlying a nipple, or along one side of a bone), while reducing the risk of adversely impacting nearby healthy tissue.

SUMMARY OF THE INVENTION

In one embodiment of the invention, a focused ultrasound system includes an ultrasound transducer device forming an opening, the ultrasound device having a plurality of transducer elements positioned at least partially around the opening.

5 In another embodiment, a focused ultrasound system includes a structure having a first end configured to allow an object to be inserted there through, and a second end configured for allowing the object to exit there through, the structure defining an aperture, and a plurality of transducer elements coupled to the structure, the transducer elements positioned relative to each other in a formation such that acoustic energy
10 emitted from the transducer elements converges at a focal zone located in the aperture.

BRIEF DESCRIPTION OF THE DRAWINGS

Various embodiments of the invention are described hereinafter with reference to the figures. It should be noted that the figures are not drawn to scale and elements of
15 similar structures or functions are represented by like reference numerals throughout the figures, and in which:

FIG. 1 illustrates an ultrasound system having a transducer device in accordance with some embodiments of the invention;

FIG. 1B illustrates a transducer device having a plurality of rows of transducer
20 elements in accordance with other embodiments of the invention;

FIG. 2 illustrates a transducer device in accordance with still other embodiments of the invention;

FIG. 3 illustrates a transducer device in accordance with yet further embodiments of the invention, showing the transducer device having spaced apart transducer elements;

FIG. 4 illustrates a transducer device in accordance with still further embodiments of the invention, showing the transducer device having transducer elements that do not
5 face each other;

FIG. 5 illustrates a transducer device in accordance with yet further embodiments of the invention, showing the transducer device having a coupling membrane;

FIG. 6 illustrates the treatment of breast tissue using the transducer device of FIG. 1, for purposes of demonstration;

10 FIG. 7 illustrates treating tissue within an arm using the transducer device of FIG. 1, for purposes of demonstration;

FIG. 8 illustrates treating tissue within a body using the transducer device of FIG. 1, for purposes of demonstration; and

15 FIG. 9 illustrates treatment of brain tissue using the transducer device of FIG. 1, for purposes of demonstration.

DETAILED DESCRIPTION OF THE ILLUSTRATED EMBODIMENTS

FIG. 1 illustrates a focused ultrasound system 5 that includes a transducer device 10 constructed in accordance with some embodiments of the invention. The focused
20 ultrasound system 5 includes a drive circuitry 16 coupled to the transducer device 10, and a controller 18 coupled to the drive circuitry 16. The transducer device 10 is configured to deliver acoustic energy (represented by beam 15) to a target tissue region located inside a patient. The acoustic energy 15 may be used to coagulate, necrose, heat, or

otherwise treat the target tissue region, which may be a benign or malignant tumor within an organ or other tissue structure (not shown).

In the illustrated embodiments, the transducer device 10 includes a structure 20 and a plurality of transducer elements 12 secured to the structure 20. The transducer elements 12 are positioned in an arrangement or formation to thereby define an opening 22. During use, the opening 22 allows at least a portion of an object, such as a breast, be inserted from a first side 28 of the transducer device 10 and exit from a second side 29 of the transducer device 10. For examples, the opening 22 can have a cross sectional dimension that is between 50 cm to 100 cm (e.g., for accommodating a body), or between 10 cm to 50 cm (e.g., for accommodating a breast, an arm, a leg, or a head). Although the arrangement of the transducer elements 12 is shown to have a closed ring-configuration, in other embodiments, the arrangement can have an opened ring-configuration or a partial ring configuration. Also, instead of arranging the transducer elements 12 in a slanted orientation to form a partial conical configuration, in other embodiments, the transducer elements 12 can be oriented in a partial tube configuration (FIG. 2). In the illustrated embodiments, the arrangement of the transducer elements 12 has a circular ring-like configuration. Alternatively, the arrangement of the transducer elements 12 can also have a variety of shapes, such as an elliptical ring-shape, a rectangular ring-shape, or other customized shapes (e.g., a conformal shape that will follow the body contour within a tolerance). In the illustrated embodiments, the structure 20 has a ring-like configuration, but alternatively, can also have other shapes, forms, and/or configurations so long as it is capable of providing a platform or area to which the transducer elements 12 can be secured. The structure 20 may be substantially rigid, semi-

rigid, or substantially flexible, and can be made from a variety of materials, such as plastics, polymers, metals, and alloys. The structure 20 can be manufactured as a single unit, or alternatively, be assembled from a plurality of components that are parts of the transducer device 10. Electrodes and conducting wires (not shown) may also be provided
5 in a known manner for coupling the transducer elements 12 to the driver 16. The electrodes for the transducer elements 12 are preferably housed within the structure 20, and exit from the structure 20 for coupling to the driver 16 and/or the controller 18.

The transducer elements 12 are coupled to the driver 16 and/or controller 18 for generating and/or controlling the acoustic energy emitted by the transducer elements 12.
10 For example, the driver 16 may generate one or more electronic drive signals, which may be controlled by the controller 18. The transducer elements 12 convert the drive signals into acoustic energy 15, which may be focused using conventional methods. The controller 18 and/or driver 16 may be separate or integral components. It will be appreciated by one skilled in the art that the operations performed by the controller 18
15 and/or driver 16 may be performed by one or more controllers, processors, and/or other electronic components, including software and/or hardware components. The terms controller and control circuitry may be used herein interchangeably, and the terms driver and drive circuitry may be used herein interchangeably.

The driver 16, which may be an electrical oscillator, may generate drive signals in
20 the ultrasound frequency spectrum, e.g., as low as twenty kilohertz (20KHz), and as high as ten Megahertz (10 MHz). Preferably, the driver 16 provides drive signals to the transducer elements 12 at radio frequencies (RF), for example, between about 100 Kilohertz to ten Megahertz (0.1-10 MHz), and more preferably between about two

hundreds Kiloherertz and three Megahertz (0.2 and 3.0 MHz), which corresponds to wavelengths in tissue of approximately 7.5 to 0.5 mm. However, in other embodiments, the driver 16 can also be configured to operate in other ranges of frequencies. When the drive signals are provided to the transducer elements 12, the transducer elements 12 emit
5 acoustic energy 15 from its exposed surface, as is well known to those skilled in the art.

The controller 18 may control the amplitude, and therefore the intensity or power of the acoustic waves transmitted by the transducer elements 12. The controller 18 may also control a phase component of the drive signals to respective transducer elements 12 of the transducer device 10, e.g., to control a shape of a focal zone 38 generated by the
10 transducer elements 12 and/or to move the focal zone 38 to a desired location. For example, as is well known to those skilled in the art, the location of the focus can be determined by adjusting the phases of the individual elements in such a way that constructive interference is generated at the desired location, provided the sizes of the individual elements are small enough to allow significant contribution to the energy at the
15 focus at high steering angles and keep aberrations at an acceptable level.

As explained above, the transducer elements 12 convert the drive signals into acoustic energy, represented by energy beam 15. As the acoustic energy 15 passes through the patient's body, the acoustic energy 15 is absorbed in the tissue and converted to heat in the pass zone and at the focal zone within target region thereby raising the
20 temperature of tissue within the target region. The tissue temperature rise depends on the intensity (energy/cm²) in situ. The acoustic energy 15 may be focused on the target region to raise the temperature of the tissue to coagulate the tissue while minimizing damage to surrounding healthy tissue. Exemplary apparatus for measuring and/or

calibrating the energy output of a transducer device are described in U.S. Patent Application Publication Number 2003-0105398-A1.

In the illustrated embodiments, each of the transducer elements 12 may be a one-piece piezoceramic part, or alternatively, be composed of a mosaic arrangement of a plurality of small piezoceramic elements (e.g., phased array). The piezoceramic parts or the piezoceramic elements may have a variety of geometric shapes, such as hexagons, triangles, squares, and the like.

The transducer elements 12 can be individually controlled to change, e.g., a respective phase and/or amplitude of the respective acoustic waves in order to create a desired focal zone. If the transducer elements 12 include a plurality of piezoceramic elements, each of the piezoceramic elements may be coupled to a respective timing or delay element. The timing or delay elements may be implemented as a part of the ultrasound transducer device 10, the driver 16, or the controller 18.

In the illustrated embodiments, the transducer elements 12 are arranged in a formation about a circumference of the opening 22, and each transducer element 12 has a surface 24 that forms an angle 26 with a plane 23 in which the structure 20 approximately lies. In the example shown in FIG. 1, the angle 26 is approximately 300, but can also be other angles, such as 60° or 90° (FIG. 2), in other embodiments. Also, in the illustrated embodiments, the transducer elements 12 are fixedly secured to the structure 20 such that the angle 26 does not vary during use. In other embodiments, the transducer elements 12 can be rotatably secured to the structure 20 such that the angle 26 can be adjusted during use. In such cases, the transducer device 10 further includes a positioner for moving the transducer elements 12. The positioner can, for examples, include a motor, such as an

electric motor or a piezoelectric motor, a hydraulic, or a gimbal system, for changing the angle 26. In some embodiments, the structure 20 can include a plurality of movable sections to which one or more of the transducer elements 12 are secured. In such cases, the movable sections are installed on respective gimbals, and the transducer elements 12 are movable by operation of the gimbals. Also, in other embodiments, instead of positioning the transducer elements 12 in one degree of freedom, the transducer elements 12 can be configured to move in multiple degrees of freedom (e.g., two or up to six degrees of freedom relative to the opening 26).

In the illustrated embodiments, the transducer device 10 includes a single row (ring) of transducer elements 12. However, the scope of the invention should not be so limited. In alternative embodiments, the transducer device 10 can include a plurality of rows (e.g., adjacent rings) of transducer elements 12 (FIG. 1B). As shown in FIG. 1B, the transducer device 10 has four rows/rings of transducer elements 12, with each ring having twenty-nine transducer elements 12 for focusing and steering the beam. In some embodiments, the opening has a 10 cm cross sectional dimension, and the number of transducer elements 12 per ring could be 300 to 700. It should be noted that the number of rows (rings) of transducer elements 12, and the number of transducer elements 12 per row should not be limited to that shown in the example, and that in alternative embodiments, the transducer device 10 can have other numbers of rows and other numbers of transducer elements per row.

In the illustrated embodiments, the transducer elements 12 of the transducer device 10 substantially abut against adjacent transducer elements 12 such that the transducer elements 12 collectively define a substantially complete opening. In other

embodiments, the transducer elements 12 can be spaced apart from adjacent transducer elements 12 to partially define the opening 22 (FIG. 3). Such configuration may be beneficial because, while it still allows acoustic energy from different angles to converge, it reduces the number of transducer elements 12, thereby reducing cost. Also, the spacing
5 between adjacent transducer elements 12 can be used to house mechanical and/or electrical components of the transducer device 10. In the illustrated embodiments, the transducer device 10 further includes a guide rail 100 to which the transducer elements 12 are slidably coupled. Such configuration allows the positions of the transducer elements 12 about the perimeter of the opening 22 be adjusted by sliding the transducer elements
10 12 along the guide rail 100. The transducer elements 12 can also be movably coupled to the structure 20 using other mechanical joints, connections, and configurations. In other embodiments, the transducer elements 12 are fixedly secured to the structure 20, in which cases, the transducer device 10 does not include the guide rail 100 or similar mechanisms.

Also, in other embodiments, the transducer elements 12 can be so positioned such
15 that each of the transducer elements 12 does not face another transducer elements 12 (FIG. 4). As shown in FIG. 4, the transducer device 10 includes three transducer elements 12a-12c, with each transducer element 12 having a surface 24 that forms approximately a 90° angle 26 with the plane 23. Alternatively, the angle 26 can be different from 90°. Although three transducer elements 12 are shown, in other
20 embodiments, the transducer device 10 can have more or less than three transducer elements 12. In the illustrated embodiments, the transducer elements 12a-12c do not face each other, thereby allowing beam emerging from respective surfaces 24 of the transducer elements 12 to pass through the spacing between the transducer elements 12.

Such configuration has the advantage of preventing emerging beam from one transducer element from damaging another (e.g., opposing) transducer element. Such configuration also prevents beam emitted by one transducer element from being reflected by another transducer element. Also, in the illustrated embodiments, the structure 10 includes a plurality of openings 200 that allow beams emitted by the transducer elements 12 to exit, thereby preventing the beams from being reflected by the structure 10. Although the openings 200 are each shown to have a shape that resembles a rectangle, in other embodiments, the openings 200 can have other shapes. Also, in other embodiments, the transducer elements 12a-c are oriented at an angle (such as that similarly shown in FIG. 1), in which cases, the openings 200 can provide a similar advantage as that discussed previously.

Any embodiments of the transducer device described herein can further include a coupling membrane. FIG. 5 illustrates a transducer device 400 in accordance with other embodiments of the invention. The transducer device 400 is similar to the transducer device 10 of FIG. 1 except that it further includes a coupling membrane 402. The coupling membrane 402 can be, for examples, an inflatable body or a balloon. The coupling membrane 402 has an opening (not shown) adapted for receiving a medium for inflation of the membrane 402. After the coupling membrane 402 is inflated by the medium, it may be used to press against a surface of an object for acoustic coupling. The medium may be a liquid acoustic propagation medium for propagating or transmitting generated ultrasound from the transducer elements 12. The coupling membrane 402 and the medium preferably exhibit an acoustic impedance that essentially corresponds to that of body tissue. For example, the coupling membrane 402 is preferably made from a

polymer or a rubber, and degassed water is preferably used as the medium. During use, the coupling membrane 402 provides or improves an acoustic coupling between the transducer elements 12 and an object, such as a skin of a patient, while focused ultrasound energy is being delivered. In some embodiments, a cool medium can be used to inflate and/or circulate within the coupling membrane 402, thereby preventing excessive heat from being created at an interface between the coupling membrane 402 and a patient's skin, or by the transducer.

For purposes of demonstrating the forms and functionality of embodiments of the invention, various uses will now be described. Referring to FIG. 6, a method of using the system 5 to treat tissue within a breast 500 is illustrated. First, a coupling gel is applied on a breast skin 502. If the transducer device 10 includes the coupling membrane 402, the coupling membrane 402 is then inflated with a medium, such as degassed water. Next, the breast 500 is at least partially inserted into the opening 22 such that the transducer elements 12 at least partially circumscribe a portion of the breast 500. In the illustrated embodiments, the transducer device 10 is secured to a patient support (not shown) having an opening. The patient support supports the patient in a face-down position, while the opening of the patient support allows the patient's breast 500 to exit and be placed on the transducer device 10. In other embodiments, the transducer device 10 can be secured to a frame in an upright position such that the patient's breast 500 can be placed onto the transducer device 10 while the patient is in his/her upright position. The transducer device 10 can also be implemented as a hand-held instrument, thereby allowing a physician to place the transducer device 10 onto the patient.

If the transducer elements 12 are movable relative to the structure 20, the position and/or the orientation of the transducer elements 12 can be adjusted. After the transducer elements 12 have been desirably positioned relative to the breast 500, the transducer device 10 then delivers focused ultrasound energy to target tissue within the breast 500.

5 As can be appreciated by those skilled in the art, delivering focused ultrasound energy from a wide angle (e.g., from different positions around the breast 500) increases the surface area of the breast skin 502 through which beam energy from the transducer elements 12 is passing. This, in turn, prevents, or at least reduces the risk of, excessive energy density at a patient's skin and tissue, thereby preventing injury to the patient's
10 skin or non targeted tissue. Also, because beam energy is being delivered from the transducer elements 12 in a direction that is not directly towards a rib cage (e.g., beam energy is delivered in a direction approximately parallel to the rib cage), heating of the rib cage is prevented or at least reduced.

During the procedure, the driver 16 and/or the controller 18 may be used to
15 generate and/or to control the acoustic energy emitted by the transducer device 10. For example, the driver 16 and/or the controller 18 can control a phase of the transducer elements 12 to thereby adjust a position of the focal zone 38 and/or to change a shape of the focal zone 38 during use. If the transducer device 10 includes the positioner for moving the transducer elements 12, the driver 16 and/or the controller 18 can be used to
20 control the positioner to thereby adjust the position and/or shape of the focal zone. In some embodiments, the driver 16 and/or the controller 18 can cause the transducer elements 12 to deliver beam(s) for creating multiple focal zones 38, thereby allowing treatment of multiple target region simultaneously.

Also, in some embodiments, a feedback mechanism is provided to measure one or more of a size, shape, location, and intensity of the focal zone 38. For example, MRI simultaneous thermal imaging can be used to thermally map the focal zones. The measured size, shape, location, or density is then compared (e.g., by human operator or a processor, such as that described in U.S. Patent No. 6,618,620) with a desired size, shape, location, or intensity, respectively, of the focal zone 38. Based on the comparison, the phase and/or amplitude of the drive signals is changed to adjust a size, shape, location, and/or intensity of the focal zone 38. A position of one or more of the transducer elements 12 can also be changed in response to a result of the comparison. After a desired amount of ultrasound energy has been delivered, the breast 500 is then removed from the transducer device 10, or vice versa.

For further examples, the transducer device can be used to treat tissue within an arm (FIG. 7), within a body (FIG. 8), or within a head (FIG. 9) of a patient. As shown in FIGS. 7-9, delivering focused ultrasound energy from a wide angle (e.g., from different positions around the arm, the body, or the head) increases the surface area of the skin to which beam energy from the transducer elements is directed, and decreases energy density in the tissue pass zone. This, in turn, prevents, or at least reduces the risk of, excessive energy density at a patient's skin, at internal sensitive organs, or at bony surfaces, at the far field, thereby preventing injury to the patient's skin or internal non-targeted organs. Any of the ultrasound devices described herein may also be used to treat tissues at other parts of a body, such as bone tissue, muscle tissue, tissue within a neck, or brain tissue. Besides treating tissue, the same ultrasound device may also be used to deliver diagnostic ultrasound for imaging tissue.

Further, in other embodiments, any of the transducer devices described herein can be coupled to a positioner for controlling a position of the transducer device relative to a patient. For example, the transducer device 10 of FIG. 8 can be positioned by a positioner to move along a length of the arm to treat different tissue, including bone
5 tissue, along the arm. Similarly, the transducer devices 10 of FIGS. 8 and 9 can be positioned along the body and the head, respectively, to treat different tissue, or the beam could be steered electronically using transducer elements phase control.

CLAIMS

1. A focused ultrasound system, comprising:
an ultrasound transducer device forming an opening, the ultrasound device
having a plurality of transducer elements positioned at least partially around the
5 opening.
2. The system of claim 1, wherein the opening has a cross sectional dimension
between 5 cm and 100 cm.
- 10 3. The system of claim 1, wherein the opening has a cross sectional dimension
that allows at least a part of a portion of a body to be accommodated therein, wherein
the body portion is selected from the group consisting of a breast, an arm, a leg, a
body, a neck, and a head.
- 15 4. The system of any of claims 1 - 3, wherein each one of the plurality of the
transducer elements abuts against another one of the plurality of the transducer
elements.
5. The system of any of claims 1 - 3, wherein each one of the plurality of the
20 transducer elements is spaced from other ones of the plurality of transducer elements.
6. The system of any of claims 1 - 3, wherein the opening is approximately
circular.

7. The system of any of claims 1 - 5, wherein the opening has a shape that resembles a polygon.
8. The system of any of claims 1 - 5, wherein the opening has a shape having a
5 contour that resembles a part of a body contour.
9. The system of any of claims 1 - 8, further comprising a positioner for positioning one or more of the plurality of the transducer elements relative to another one or more of the plurality of transducer elements.
- 10
10. The system of claim 9, wherein the positioner comprises a gimbal system.
11. The system of claim 9, wherein the positioner comprises a piezoelectric motor.
- 15 12. The system of any of claims 1 - 11, further comprising a coupling membrane coupled to the ultrasound transducer device.
13. The focused ultrasound system of claim 1, the ultrasound transducer device comprising a structure having a first end configured to allow an object to be inserted
20 there through, and a second end configured for allowing the object to exit there through, the structure defining the opening; wherein the transducer elements are positioned relative to each other in a formation such that acoustic energy emitted from the transducer elements converges at a focal zone located in the opening.

14. The focused ultrasound system of claim 13, the structure having a contour that resembles a part of an external body contour.
15. The system of claim 13, further comprising control circuitry, wherein one or
5 more of a size, shape, location and intensity of the focal zone is determined, at least in part, by a phase, amplitude, or both, of respective drive signals generated by the control circuitry to emit ultrasound energy from the transducer elements.
16. The system of claim 13, wherein the opening has an ellipsoidal cross-section.
10
17. The system of any of claims 13 - 16, the structure comprising a plurality of movable sections, each section carrying a respective subset of the transducer elements.
- 15 18. The system of claim 17, wherein one or more of a size, shape, location and intensity of the focal zone is determined, at least in part, by movement of one or more of the sections relative to one or more other of the sections.
19. The system of claim 17, wherein the movable sections are installed on
20 respective gimbals.
20. The system of any of claims 13 - 19, further comprising feedback circuitry configured to measure one or more of a size, shape, location and intensity of the focal zone, the feedback circuitry further configured to determine a difference between a

measured focal zone size, shape, location, or intensity, and a desired focal zone size, shape, location, or intensity.

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FIG. 1A

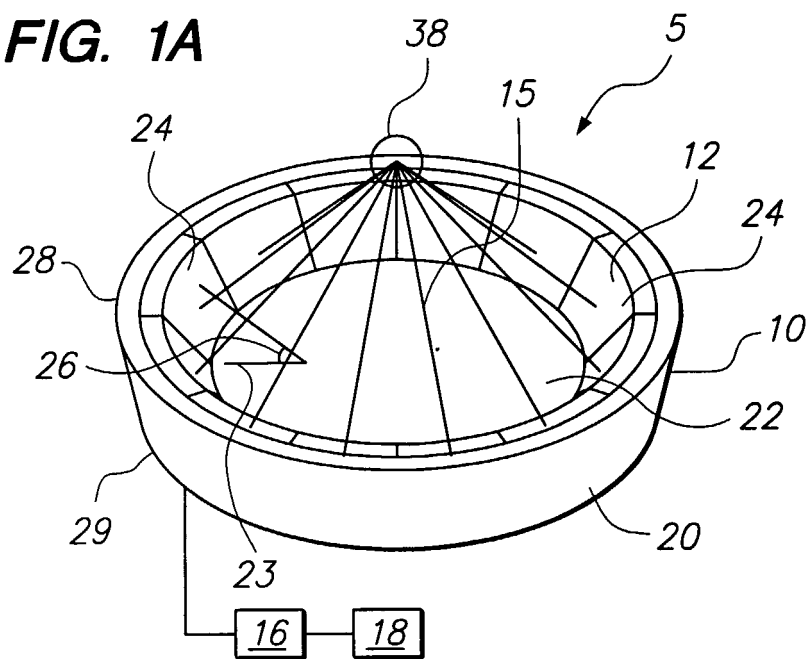


FIG. 1B

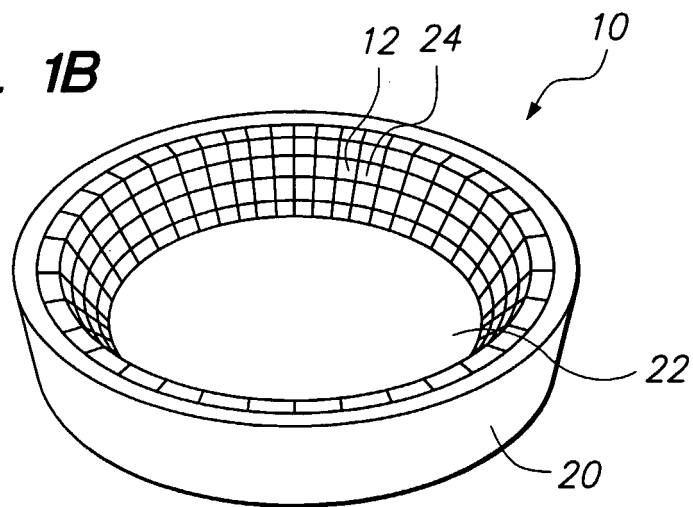
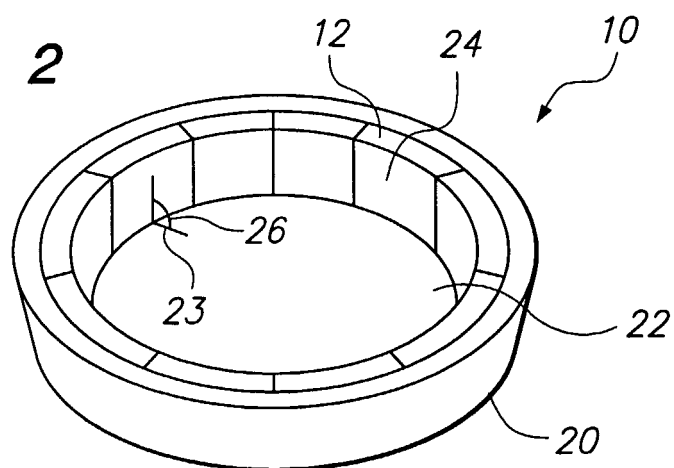


FIG. 2



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FIG. 3

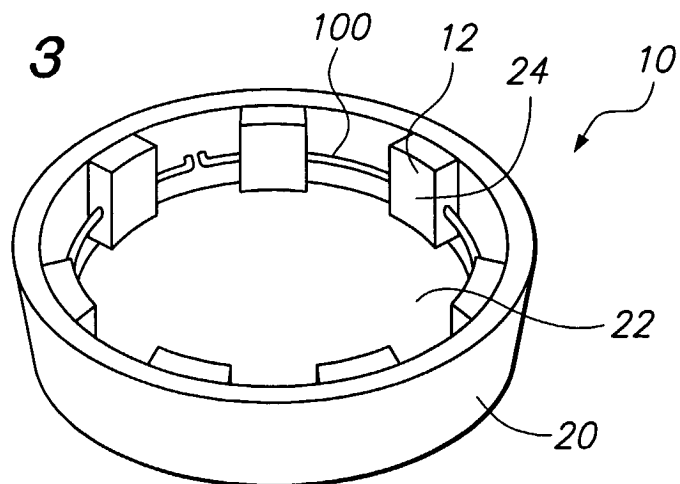


FIG. 4

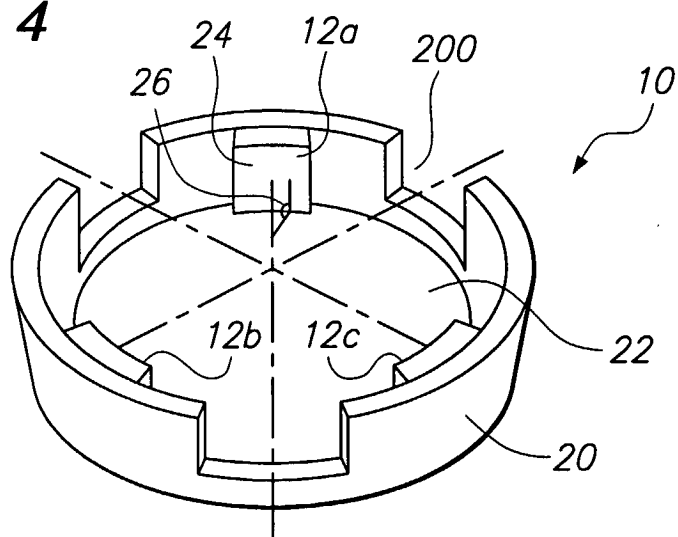
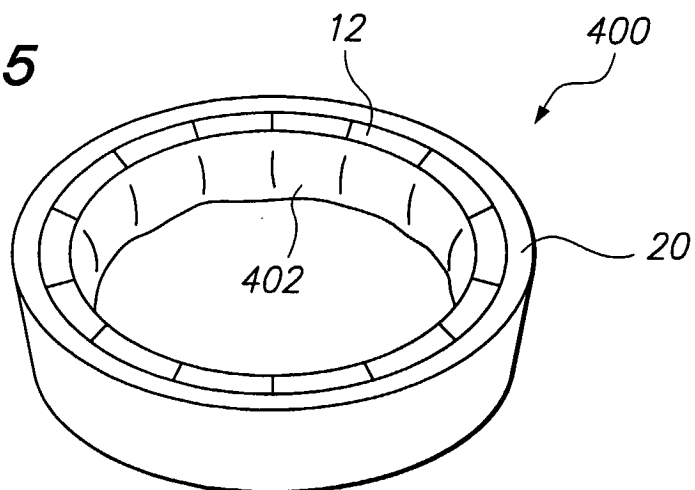
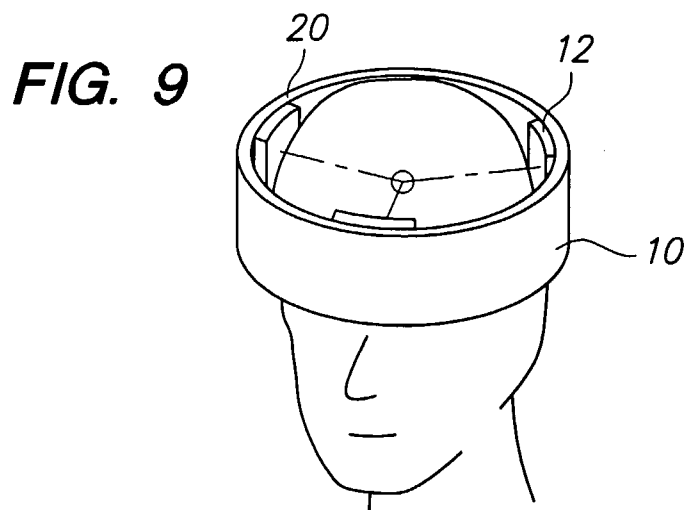
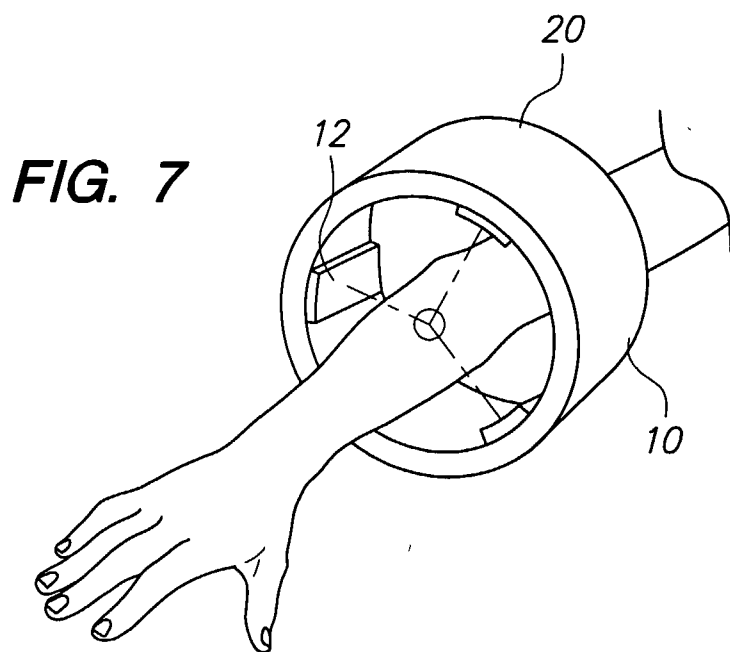
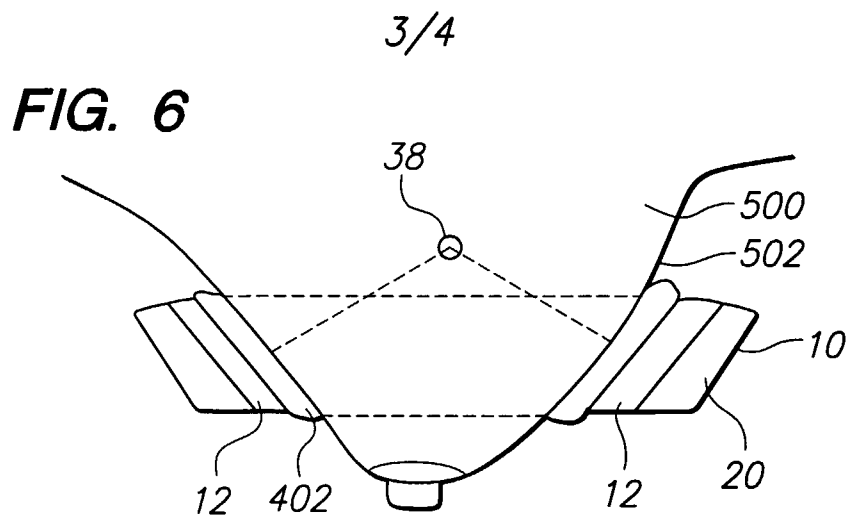


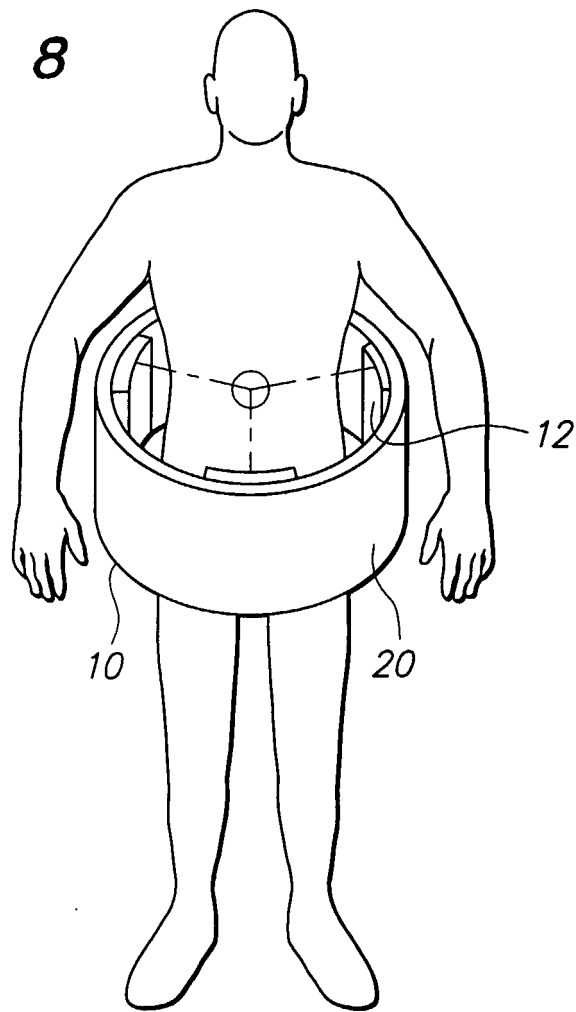
FIG. 5





4/4

FIG. 8



INTERNATIONAL SEARCH REPORT

International Application No
PC1/1B2005/002413

A. CLASSIFICATION OF SUBJECT MATTER
A61B8/00 A61N7/00 A61B18/12

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
A61B A61N

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

EPO-Internal

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 5 739 625 A (FALCUS ET AL) 14 April 1998 (1998-04-14) column 2, line 16 - column 3, line 10; claims 1-7; figure 2	1-9, 13, 14, 16-18
X	US 4 478 083 A (HASSLER ET AL) 23 October 1984 (1984-10-23) column 2, line 25 - column 6, line 19; claim 1; figure 6	1-6, 8
X	FR 2 806 611 A (KAFAI HOSSEIN) 28 September 2001 (2001-09-28) claim 1; figure 1	1-3, 5, 6
X	US 3 974 475 A (BURCKHARDT ET AL) 10 August 1976 (1976-08-10) column 3, line 23 - column 4, line 12; claim 1; figure 3	1-4, 6, 8

☒ Further documents are listed in the continuation of box C.

☒ Patent family members are listed in annex.

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T later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

X document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

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* & * document member of the same patent family

Date of the actual completion of the international search

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INTERNATIONAL SEARCH REPORT

International Application No
PC 17/1B2005/002413

C.(Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT

Category °	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 3 142 035 A (HARRIS WILBUR T) 21 July 1964 (1964-07-21) column 3, line 49 - line 72; figure 3 -----	1-3,5,6
X	US 3 992 693 A (MARTIN ET AL) 16 November 1976 (1976-11-16) column 2, line 53 - column 3, line 15; figures 1,3 -----	1-3,5,6
X	US 2 795 709 A (CAMP LEON WALTON) 11 June 1957 (1957-06-11) abstract; claim 1; figure 5 -----	1-4,6
A		5,7-20

INTERNATIONAL SEARCH REPORT

Information on patent family members

International Application No
PCT/IB2005/002413

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US 2795709	A	11-06-1957	NONE	

专利名称(译)	用于围绕身体组织块的聚焦超声系统		
公开(公告)号	EP1796545A1	公开(公告)日	2007-06-20
申请号	EP2005773991	申请日	2005-08-11
[标]申请(专利权)人(译)	因赛泰克有限公司		
申请(专利权)人(译)	InSightec的，图像引导治疗.，LTD.		
当前申请(专利权)人(译)	InSightec的有限公司.		
[标]发明人	VITEK SHUKI VORTMAN KOBI		
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优先权	10/927772 2004-08-26 US		
其他公开文献	EP1796545B1		
外部链接	Espacenet		

摘要(译)

聚焦超声系统包括形成开口的超声换能器装置，并且具有至少部分地围绕开口定位的多个换能器元件。聚焦超声系统包括具有用于允许物体插入的第一端和用于允许物体离开的第二端的结构，以及耦合到该结构的多个换能器元件，换能器元件相对于彼此定位在至少部分地限定开口的构造，其中换能器元件配置成发射在聚焦区域会聚的声能。