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(54) **Ultrasound system and method for providing change information of target object**

Ultraschallsystem und Verfahren zur Bereitstellung eines Zielobjekts

Système à ultrasons et procédé pour fournir des informations de modification d'objet cible

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Description

RELATED APPLICATIONS

[0001] This application claims the benefit of Korean Patent Application No. 10-2013-0049427, filed on May 2, 2013, in the Korean Intellectual Property Office, the disclosure of which is incorporated herein in its entirety by reference.

BACKGROUND

1. Field

[0002] One or more embodiments of the present invention relate to ultrasound systems, and more particularly, to ultrasound systems and methods for providing change information of a target object that has undergone radiofrequency ablation (RFA).

2. Description of the Related Art

[0003] When tumors occur in a target object (e.g., the liver) inside a living body, the tumors are typically removed by non-surgical method or surgical treatment. Since the surgical treatment usually removes a tumor by incising a surface of a living body, the cut surface is so wide as to leave a scar thereon and takes a long time to heal. Furthermore, the tumor is likely to recur, and in this case the tumor has to be removed with surgery again, thereby causing pain in a living body and considerable economic burden and health risk.

[0004] Recently, non-surgical techniques have been commonly used to remove tumors. Examples of non-surgical techniques may include transarterial chemoinfusion (TACE), percutaneous ethanol injection (PEI), systemic chemotherapy, and local ablation therapy. Among these, the local ablation therapy is known as the most effective technique for providing short-term treatment and improving a long-term survival rate. Some examples of the local ablation therapy are RFA, microwave endometrial ablation (MEA), and laser ablation. The RFA is the most effective treatment modality.

[0005] The RFA is a treatment technique that destroys only a tumor by application of RF-generated heat without incision to thereby cause necrosis. The RFA involves inserting a needle-tip electrode into a tumor within a living body, supplying RF from an RF generator to the needle-tip electrode, and burning the tumor with RF-generated heat to ablate it.

[0006] A conventional technique provides information about a progress of an RFA process by setting markers on ultrasound images obtained before and after the RFA process or superimposing ultrasound images obtained before and after the RFA process. Thus, the conventional technique has drawbacks in that it is difficult to consistently observe the progress of RFA from different planes and positions during RFA and accurately observe it due

to gas bubbles created during the RFA.

[0007] In the WO 2013/018003 A1 a method, system, and program product are provided for accurately visualizing soft tissue motion on an x-ray image. Real time ultrasound images are registered to an x-ray image space. A point of interest is defined. Motion of the selected point is determined from the real time ultrasound images. The determined motion is applied to the selected point on the x-ray image.

SUMMARY

[0008] One or more embodiments of the present invention include an ultrasound system and method for providing change information of a target object by performing image registration on a reference image acquired before radiofrequency ablation (RFA) and an ultrasound image acquired during the RFA and comparing the reference image and the ultrasound image that have undergone the image registration with each other.

[0009] Additional aspects will be set forth in part in the description which follows and, in part, will be apparent from the description, or may be learned by practice of the presented embodiments.

[0010] According to one or more embodiments of the present invention, an ultrasound system includes: a storage unit that stores image data of a living body containing a target object, which is acquired before undergoing RFA; an ultrasound probe that transmits an ultrasound signal to the living body during the RFA and receives an ultrasound echo signal reflected from the living body to create a reception signal; an ultrasound data acquisition unit configured to acquire ultrasound data by using the reception signal; and a processing unit that produces a reference image by using the image data and an ultrasound image by using the ultrasound data, performs image registration between the reference image and the ultrasound image, compares the reference image and the ultrasound image that have undergone the image registration with each other, and produces change information indicative of a change in the target object.

[0011] According to one or more embodiments of the present invention, a method of providing change information of a target object includes: transmitting an ultrasound signal to a living body containing the target object during radiofrequency ablation (RFA) and receiving an ultrasound echo signal reflected from the living body to acquire ultrasound data, through an ultrasound probe; extracting image data of the living body acquired before undergoing the RFA from a storage unit and producing a reference image; producing an ultrasound image by using the ultrasound data; performing image registration between the reference image and the ultrasound image; and comparing the reference image and the ultrasound image that have undergone the image registration with each other and producing the change information indicative of a change in the target object.

[0012] The ultrasound system and method for provid-

ing change information of a target object allow a user to view a size of a tumor before RFA, a targeted range of the RFA, and real-time progress status of the RFA, thereby achieving real-time monitoring of the progress of the RFA from various angles and positions during RFA.

[0013] The ultrasound systems and method are adapted to monitor a status corresponding to a portion of an image that is momentarily blurred due to gas bubbles through accumulation of images.

[0014] The ultrasound system and method may also be adapted to store the progress of a RFA process, thereby enabling a review of the progress.

[0015] The ultrasound system and method are also adapted to simultaneously observe the progress of an RFA process by using various modalities such as MRI, CT, ultrasound, and PET-CT.

BRIEF DESCRIPTION OF THE DRAWINGS

[0016] These and/or other aspects will become apparent and more readily appreciated from the following description of the embodiments, taken in conjunction with the accompanying drawings in which:

FIG. 1 is a schematic block diagram showing a configuration of an ultrasound system according to an exemplary embodiment of the present invention;

FIG. 2 is a block diagram showing a configuration of an ultrasound data acquisition unit in the ultrasound system of FIG. 1, according to an exemplary diagram of the present invention;

FIG. 3 is an exemplary diagram illustrating a plurality of frames;

FIG. 4 is a flowchart of a process of generating change information associated with radiofrequency ablation (RFA) according to an exemplary embodiment of the present invention;

FIG. 5 is a block diagram showing a configuration of an ultrasound system according to another exemplary embodiment of the present invention;

FIG. 6 is a block diagram showing a configuration of an ultrasound data acquisition unit in the ultrasound system of FIG. 5, according to an exemplary diagram of the present invention; and

FIG. 7 is a flowchart of a process of generating change information of an object associated with RFA according to another exemplary embodiment of the present invention.

DETAILED DESCRIPTION

[0017] Reference will now be made in detail to embodiments, examples of which are illustrated in the accompanying drawings, wherein like reference numerals refer to the like elements throughout. In this regard, the present embodiments may have different forms and should not be construed as being limited to the descriptions set forth herein. Accordingly, the embodiments are merely de-

scribed below, by referring to the figures, to explain aspects of the present description.

EMBODIMENT 1

[0018] FIG. 1 is a schematic block diagram showing a configuration of an ultrasound system 100 according to an exemplary embodiment of the present invention. Referring to FIG. 1, the ultrasound system 100 includes a storage unit 110, an ultrasound probe 120, an ultrasound data acquisition unit 130, a user input unit 140, a processing unit 150, and a display unit 160.

[0019] The storage unit 110 stores image data corresponding to an image of a living body including a target object (e.g., a tumor). According to the present embodiment, the image data corresponds to an image of a living body obtained before radiofrequency ablation (RFA). Furthermore, the image data may be two-dimensional (2D) or three-dimensional (3D) data. The image data may include magnetic resonance imaging (MRI) data, computed tomography (CT) data, ultrasound data, and positron emission tomography (PET)-CT data. The storage unit 110 may include a hard disk, a nonvolatile memory, Compact Disc-Read Only Memory (CD-ROM), and Digital Versatile Disc (DVD)-ROM.

[0020] The ultrasound probe 120 includes a plurality of transducer elements (not shown) that convert electrical signals into ultrasound signals, and vice versa. The ultrasound probe 120 is configured to transmit an ultrasound signal to a living body and receive an ultrasound echo signal reflected from the living body to generate an electrical signal (hereinafter, referred to as a "reception signal"). The reception signal is an analog signal. The ultrasound probe 120 includes a 3D probe, a 2D array probe, a convex probe, and a linear probe.

[0021] The ultrasound data acquisition unit 130 controls transmission of an ultrasound signal. The ultrasound data acquisition unit 130 also acquires ultrasound data corresponding to an ultrasound image of a living body by using a reception signal provided by the ultrasound probe 120. The ultrasound data acquisition unit 130 may be realized by an Application Specific Integrated Circuit (ASIC) or a processor including a central processing unit (CPU), a microprocessor, and a graphics processing unit (GPU).

[0022] FIG. 2 is a block diagram showing a configuration of the ultrasound data acquisition unit 130 in the ultrasound system of FIG. 1, according to an exemplary diagram of the present invention. Referring to FIG. 2, the ultrasound data acquisition unit 130 includes a transmitter 210, a receiver 220, and an ultrasound data forming section 230.

[0023] The transmitter 210 controls the transmission of an ultrasound signal. The transmitter 210 also produces an electrical signal (hereinafter, referred to as a "transmission signal") that is used to obtain an ultrasound image in consideration of the transducer elements. In the present embodiment, the transmitter 210 creates a trans-

mission signal that is used to obtain each of a plurality of ultrasound images during RFA.

[0024] In one embodiment, the transmitter 210 creates a transmission signal (hereinafter, referred to as a "first transmission signal") that is used to obtain each of a plurality of 2D images of a living body during RFA. The ultrasound probe 120 then converts the first transmission signal received from the transmitter 210 into an ultrasound signal, transmits the ultrasound signal to the living body, and receives an ultrasound echo signal reflected from the living body to create a reception signal (hereinafter, referred to as a "first reception signal").

[0025] In another embodiment, as shown in FIG. 3, during RFA, the transmitter 210 creates a transmission signal (hereinafter, referred to as a "second transmission signal") that is used to obtain each of a plurality of 3D ultrasound images of a living body, i.e., a plurality of frames F_i ($1 \leq i \leq N$) corresponding to the plurality of 3D ultrasound images. The ultrasound probe 120 then converts the first transmission signal received from the transmitter 210 into an ultrasound signal, transmits the ultrasound signal to the living body, and receives an ultrasound echo signal reflected from the living body to create a reception signal (hereinafter, referred to as a "second reception signal").

[0026] The receiver 220 performs analog-to-digital conversion on the reception signal provided by the ultrasound probe 120 to produce a digital signal. The receiver 220 also performs reception beamforming on the digital signal in consideration of positions of the transducer elements to create a focused reception signal. Since the reception beamforming may be performed by using various known methods, a detailed description thereof is omitted here. In the present embodiment, during RFA, the receiver 220 performs analog-to-digital conversion on the reception signal received from the ultrasound probe 120 to produce a digital signal and carries out reception beamforming on the digital signal to create a focused reception signal.

[0027] In one embodiment, the receiver 220 performs analog-to-digital conversion on a first reception signal provided by the ultrasound probe 120 to produce a digital signal (hereinafter, referred to as a "first digital signal"). The receiver 220 may also perform reception beamforming on the first digital signal in consideration of the transducer elements to create a focused reception signal (hereinafter, referred to as a "first focused reception signal").

[0028] In another embodiment, the receiver 220 performs analog-to-digital conversion on a first reception signal provided by the ultrasound probe 120 to produce a digital signal (hereinafter, referred to as a "second digital signal"). The receiver 220 may also perform reception beamforming on the second digital signal in consideration of the transducer elements to create a focused reception signal (hereinafter, referred to as a "second focused reception signal").

[0029] The ultrasound data forming section 230 cre-

ates ultrasound data corresponding to an ultrasound image by using the focused reception signal provided by the receiver 220. The ultrasound data includes RF data, but is not limited thereto. The ultrasound data may be stored in the storage unit 110. The ultrasound data forming section 230 may also perform various signal processings, such as gain control, needed to form ultrasound data, on the focused reception signal. In the present embodiment, during RFA, the ultrasound data forming section 230 generates ultrasound data by using the focused reception signal received from the receiver 220.

[0030] In one embodiment, the ultrasound data forming section 230 generates ultrasound data (hereinafter, referred to as 'first ultrasound data') corresponding to a 2D ultrasound image obtained during RFA, by using the first focused reception signal provided by the receiver 220.

[0031] In another embodiment, the ultrasound data forming section 230 generates ultrasound data (hereinafter, referred to as 'second ultrasound data') corresponding to a 3D ultrasound image obtained during RFA, by using the second focused reception signal provided by the receiver 220.

[0032] Although the ultrasound data acquisition unit 130 has been described to acquire ultrasound data corresponding to an ultrasound image based on a reception signal provided by the ultrasound probe 120, the ultrasound data acquisition unit 130 may acquire ultrasound data from an external device (not shown) connected to the ultrasound system 100 in a wired or wireless manner.

[0033] Referring back to FIG. 1, the user input unit 140 receives user input information. In the present embodiment, the user input information includes information needed for setting a region of interest (ROI). That is, the information needed for setting an ROI may contain a size and a location of the ROI. The ROI may include a 2D or 3D ROI. However, the user input information is not limited thereto. The user input information may be stored in the storage unit 110. The user input unit 140 includes a control panel, a track ball, a touch screen, a keyboard, and a mouse.

[0034] The processing unit 150 is connected to the storage unit 110, the ultrasound probe 120, the ultrasound data acquisition unit 130, the user input unit 140, and the display unit 160 and controls operations of the storage unit 110, the ultrasound probe 120, the ultrasound data acquisition unit 130, the user input unit 140, and the display unit 160. The processing unit 150 may be a processor including a CPU, a microprocessor and a GPU, or an ASIC.

[0035] FIG. 4 is a flowchart of a process of generating change information associated with RFA according to an exemplary embodiment of the present invention. Referring to FIGS. 1 and 4, the processing unit 150 extracts image data from the storage unit 110 (S402) and produces an image (hereinafter, referred to as a "reference image") of a living body before undergoing RFA by using the extracted image data (S404). The reference image

may include an MRI image, a CT image, an ultrasound image, and a PET-CT image. The reference image may also include 2D and 3D images.

[0036] Upon receipt of ultrasound data from the ultrasound data acquisition unit 130, the processing unit 150 produces an ultrasound image UI_i ($i \geq 1$) of a living body that is undergoing the RFA by using the ultrasound data (S406). The ultrasound image UI_i includes a 2D or 3D ultrasound image.

[0037] The processing unit 150 performs image registration between the reference image and the ultrasound image UI_i (S408). Since the image registration may be performed by using various known methods, a detailed description thereof is omitted here.

[0038] The processing unit 150 then compares the reference image with the ultrasound image UI_i and detects an ultrasound image for producing change information about a target object (S410).

[0039] In one embodiment, the processing unit 150 compares values (i.e., brightness values) of pixels in the reference image with values (i.e., brightness values) of corresponding pixels in the ultrasound image UI_i , and if a brightness value difference between the reference image and the ultrasound image UI_i exceeds a preset threshold value, the processing unit 150 determines that the brightness values of pixels in the ultrasound image UI_i have undergone a rapid change due to gas bubbles generated during RFA and then removes the ultrasound image UI_i . On the other hand, if the brightness value difference between the reference image and the ultrasound image UI_i is less than or equal to the preset threshold value, the processing unit 150 sets the ultrasound image UI_i as an ultrasound image for producing change information about a target object.

[0040] In another embodiment, the processing unit 150 compares values (i.e., brightness values) of voxels in the reference image with values (i.e., brightness values) of corresponding voxels in the ultrasound image UI_i , and if a brightness value difference between the reference image and the ultrasound image UI_i exceeds a preset threshold value, the processing unit 150 determines that the brightness values of voxels in the ultrasound image UI_i has undergone a rapid change due to gas bubbles generated during RFA and removes the ultrasound image UI_i . On the other hand, if the brightness value difference between the reference image and the ultrasound image UI_i is less than or equal to the preset threshold value, the processing unit 150 sets the ultrasound image UI_i as an ultrasound image for producing change information about a target object.

[0041] The processing unit 150 controls the display of the reference image and the ultrasound image UI_i that have undergone image registration (S412). In one embodiment, the processing unit 150 controls the display unit 160 to display the reference image on one side of the display unit 160 while displaying the ultrasound image UI_i on the other side thereof. In another embodiment, the processing unit 150 controls the display unit 160 to dis-

play the reference image and the ultrasound image UI_i superimposed on top of each other.

[0042] The processing unit 150 sets ROIs on the reference image and the ultrasound image UI_i that have been image registered, based on input information provided by the user input unit 140 (S414).

[0043] In one embodiment, the processing unit 150 sets a point on the reference image based on input information that is used for setting a point on a target object in the reference image as an ROI. The processing unit 150 then performs edge detection on the reference image based on the set point to detect an edge of the target object. The edge may be detected using an edge mask such as a Sobel mask, a Prewitt mask, a Robert mask, and a Canny mask. Alternatively, the edge may be detected from a difference between eigen values using a structure tensor. The processing unit 150 then sets an ROI corresponding to the target object on the reference image by using the detected edge. The processing unit 150 also sets a point on the ultrasound image UI_i based on the point set on the reference image. The processing unit 150 then performs edge detection on the ultrasound image UI_i based on the set point to detect an edge of the target object. Thereafter, the processing unit 150 sets an ROI corresponding to the target object on the ultrasound image UI_i by using the detected edge.

[0044] In another embodiment, the processing unit 150 sets an ROI on the reference image based on input information that is used for setting an edge region of a target object in the reference image as an ROI. The processing unit 150 then performs edge detection on the ultrasound image UI_i that has been image registered to the reference image, based on the ROI set on the reference image, to detect an edge of the target object. The processing unit 150 sets an ROI corresponding to the target object on the ultrasound image UI_i by the detected edge.

[0045] The processing unit 150 performs image comparison based on the set ROIs (S416). The image comparison may be performed using a differential image, an intensity change, a texture change, signal phase, or signal attenuation. In one embodiment, the processing unit 150 performs image comparison between a current ultrasound image and the reference image. In another embodiment, the processor compares a current ultrasound image with a previous ultrasound image. In another embodiment, the processing unit 150 performs image comparison between a current ultrasound image and each of a predetermined number of previous ultrasound images. In another embodiment, the processing unit 150 performs image comparison among a reference image, a previous ultrasound image, and a current ultrasound image. In another embodiment, the processing unit 150 may perform image comparison among a reference image, a predetermined number of previous ultrasound images, and a current ultrasound image.

[0046] The processing unit 150 produces change information indicative of a change in a size of a target object

(S418). The change information may be stored in the storage unit 110.

[0047] In one embodiment, the processing unit 150 produces change information including an ROI corresponding to a target object in a reference image and an ROI corresponding to a target object in a current ultrasound image. The ROI corresponding to the target object in the reference image may have the same color as or a different color than the ROI corresponding to the target object in the current ultrasound image. Alternatively, the ROI corresponding to the target object in the reference image may have the same shape as or a different shape than the ROI corresponding to the target object in the current ultrasound image.

[0048] In another embodiment, the processing unit 150 produces change information including an ROI corresponding to a target object in a reference image, an ROI corresponding to a target object in a current ultrasound image, and information about a difference in size of a target object due to RFA. The ROI corresponding to the target object in the reference image may have the same color as or a different color than the ROI corresponding to the target object in the current ultrasound image. Alternatively, the ROI corresponding to the target object in the reference image may have the same shape as or a different shape than the ROI corresponding to the target object in the current ultrasound image. The information about a difference in size of the target object may be represented as a number or graph.

[0049] In another embodiment, the processing unit 150 produces change information including an ROI corresponding to a target object in a reference image, an ROI corresponding to a target object in a previous ultrasound image, an ROI corresponding to a target object in a current ultrasound image, and information about a difference in size of a target object due to RFA. The ROI corresponding to the target object in the reference image, the ROI corresponding to the target object in the previous ultrasound image, and the ROI corresponding to the target object in the current ultrasound image may have the same color as or different colors than one another. Alternatively, the ROI corresponding to the target object in the reference image, the ROI corresponding to the target object in the previous ultrasound image, and the ROI corresponding to the target object in the current ultrasound image may have the same shape as or different shapes than one another. The information about a difference in size of the target object may be represented as a number or graph.

[0050] In another embodiment, the processing unit 150 produces change information including an ROI corresponding to a target object in a reference image, an ROI corresponding to a target object in each of a predetermined number of previous ultrasound images, an ROI corresponding to a target object in a current ultrasound image, and information about a difference in size of a target object due to RFA. The ROI corresponding to the target object in the reference image, the ROI correspond-

ing to the target object in each of the predetermined number of previous ultrasound images, and the ROI corresponding to the target object in the current ultrasound image may have the same color as or different colors from one another. Alternatively, the ROI corresponding to the target object in the reference image, the ROI corresponding to the target object in each of the predetermined number of previous ultrasound images, and the ROI corresponding to the target object in the current ultrasound image may have the same shape as or different shapes from one another. The information about a difference in size of the target object may be represented as a number or graph.

[0051] In another embodiment, the processing unit 150 produces change information including an ROI corresponding to a target object in a reference image, an ROI corresponding to a target object in a current ultrasound image, and a marker (e.g., an arrow) for indicating a portion that is subjected to RFA in the current ultrasound image.

[0052] Selectively, the processing unit 150 compares a change (hereinafter, referred to as a 'first size change') in size of a target object in the reference image and in a previous ultrasound image UI_{i-1} with a change (hereinafter, referred to as a 'second size change') in size of a target object in the reference image and in the current ultrasound image UI_i and if a difference between the first and second size changes exceeds a preset threshold value, the processing unit 150 determines that an error occurs in the current ultrasound image UI_i and removes the current ultrasound image UI_i so as not to perform the above-described process.

[0053] Referring back to FIG. 1, the display unit 160 displays a reference image, an ultrasound image, and change information, all of which are generated by the processing unit 150. Examples of the display unit 160 may include a liquid crystal display (LCD), a light-emitting diode (LED) display, and an organic LED (OLED) display.

[0054] Selectively, although it is described above that the ultrasound data acquisition unit 130 and the processing unit 150 are realized as separate processors, they may be combined into a single processor.

EMBODIMENT 2

[0055] FIG. 5 is a block diagram showing a configuration of an ultrasound system 500 according to another exemplary embodiment of the present invention. Referring to FIG. 5, the ultrasound system 500 according to the present embodiment includes a storage unit 510, an ultrasound probe 520, an ultrasound data acquisition unit 530, a sensor unit 540, a user input unit 550, a processing unit 560, and a display unit 570.

[0056] The storage unit 510 stores image data corresponding to an image of a living body. Since the storage unit 560 has the same configuration and function as those of the storage unit 110 in FIG. 1, a detailed description thereof is omitted here.

[0057] The ultrasound probe 520 includes a plurality of transducer elements (not shown) that convert electrical signals into ultrasound signals, and vice versa. The ultrasound probe 520 is configured to transmit an ultrasound signal to a living body and receive an ultrasound echo signal reflected from the living body to generate a reception signal. The reception signal is an analog signal. In the present embodiment, the ultrasound probe 520 includes a freehand type probe.

[0058] The ultrasound data acquisition unit 530 controls transmission of an ultrasound signal. The ultrasound data acquisition unit 130 also acquires ultrasound data corresponding to an ultrasound image of a living body by using a reception signal provided by the ultrasound probe 520. The ultrasound data acquisition unit 130 may be realized by an ASIC or a processor including a CPU, a microprocessor, and a GPU.

[0059] FIG. 6 is a block diagram showing a configuration of the ultrasound data acquisition unit 530 in the ultrasound system 500, according to an exemplary diagram of the present invention. Referring to FIG. 6, the ultrasound data acquisition unit 530 includes a transmitter 610, a receiver 620, and an ultrasound data forming section 630.

[0060] The transmitter 610 controls the transmission of an ultrasound signal. The transmitter 610 also produces a transmission signal that is used to obtain an ultrasound image in consideration of the transducer elements. In the present embodiment, the transmitter 610 creates a transmission signal that is used to obtain each of a plurality of 3D ultrasound images during RFA.

[0061] The receiver 620 performs analog-to-digital conversion on a reception signal provided by the ultrasound probe 520 to produce a digital signal. The receiver 620 also performs reception beamforming on the digital signal in consideration of positions of the transducer elements to create a focused reception signal. In the present embodiment, during RFA, the receiver 620 performs analog-to-digital conversion on the reception signal received from the ultrasound probe 520 to produce a digital signal and carries out reception beamforming on the digital signal to create a focused reception signal.

[0062] The ultrasound data forming section 630 creates ultrasound data corresponding to an ultrasound image by using the focused reception signal provided by the receiver 620. The ultrasound data includes RF data, but is not limited thereto. The ultrasound data forming section 630 may also perform various signal processings, such as gain control, needed to form ultrasound data, on the focused reception signal. In the present embodiment, during RFA, the ultrasound data forming section 630 generates ultrasound data corresponding to a 3D ultrasound image by using the focused reception signal received from the receiver 620.

[0063] Referring back to FIG. 5, a sensor unit 540 senses a 3D position (orientation) of the ultrasound probe 520 and produces position information corresponding to the sensed 3D position. According to the present embodi-

ment, the sensor unit 540 senses a 3D position (orientation) of the ultrasound probe 520 based on a 3D position of a living body that will be subjected to RFA and produces position information corresponding to the sensed 3D position. The sensor unit 540 may be located so as to sense the 3D position of the ultrasound probe 520. For example, the sensor unit 540 may be disposed on one side of an exterior or interior surface of the ultrasound probe 520. The sensor unit 540 may be any device for sensing a 3D position of the ultrasound probe 520, such as an angular velocity sensor, a magnetic sensor, an acceleration sensor, a gravity sensor, and a gyro sensor.

[0064] The user input unit 550 receives user input information. In the present embodiment, the user input information includes information needed for setting a 3D ROI. That is, the information needed for setting a 3D ROI may contain a size and a location of the 3D ROI. However, the user input information is not limited thereto. The user input information may be stored in the storage unit 510. The user input unit 140 includes a control panel, a track ball, a touch screen, a keyboard, and a mouse.

[0065] The processing unit 560 is connected to the storage unit 510, the ultrasound probe 520, the ultrasound data acquisition unit 530, the sensor unit 540, the user input unit 550, and the display unit 570 and controls operations of the storage unit 510, the ultrasound probe 520, the ultrasound data acquisition unit 530, the sensor unit 540, the user input unit 550, and the display unit 570. The processing unit 560 includes a processor including a CPU, a microprocessor and a GPU, or an ASIC.

[0066] FIG. 7 is a flowchart of a process of generating change information of an object associated with RFA according to another exemplary embodiment of the present invention. Referring to FIGS. 5 and 7, the processing unit 560 extracts image data from the storage unit 510 (S702) and produces a 3D reference image of a living body before undergoing RFA by using the extracted image data (S704). The 3D reference image has 3D position information (geometric information) obtained based on a 3D position of a living body that will be subjected to RFA. The 3D reference image includes an MRI image, a CT image, an ultrasound image, and a PET-CT image.

[0067] Upon receipt of ultrasound data from the ultrasound data acquisition unit 530, the processing unit 560 produces a 3D ultrasound image UI_i ($i \geq 1$) of a living body that is undergoing the RFA by using the ultrasound data (S706).

[0068] The processing unit 560 performs image registration between the 3D reference image and the 3D ultrasound image UI_i based on position information of the 3D reference image and position information provided by the sensor unit 540 (S708). Since the image registration may be performed by using various known methods, a detailed description thereof is omitted here.

[0069] The processing unit 560 then compares the 3D reference image with the 3D ultrasound image UI_i and detects a 3D ultrasound image for producing change information about a target object (S710).

[0070] The processing unit 560 controls the display of the 3D reference image and the 3D ultrasound image U_i that have undergone image registration (S712). The processing unit 560 sets 3D ROIs on the 3D reference image and the 3D ultrasound image U_i that have been image registered, based on input information provided by the user input unit 550 (S714). The processing unit 560 performs comparison between the 3D reference image and the 3D ultrasound image U_i that have been image registered, based on the set 3D ROIs (S716). Thereafter, the processing unit 560 produces change information indicative of a change in a size of a target object (S718). Since the operations S710 through S718 of the method according to the present embodiment are performed in a similar manner to the operations S410 through S418 of the method according to Embodiment 1, a detailed description thereof is omitted here.

[0071] Referring back to FIG. 5, the display unit 570 displays a 3D reference image, a 3D ultrasound image and change information, all of which are generated by the processing unit 560. Examples of the display unit 570 may include an LCD, an LED display, and an OLED display.

[0072] Selectively, although it is described above that the ultrasound data acquisition unit 530 and the processing unit 560 are realized as separate processors, they may be combined into a single processor.

Claims

1. An ultrasound system (100) comprising:

a storage (110) that stores image data of a living body containing a target object, which is acquired before undergoing radiofrequency ablation RFA; an ultrasound probe (120) that transmits an ultrasound signal to the living body during the RFA and receives an ultrasound echo signal reflected from the living body to create a reception signal;
an ultrasound data acquirer (130) configured to acquire ultrasound data by using the reception signal; and
a processor (150) that

produces a reference image by using the image data and a plurality of ultrasound images by using the ultrasound data,
performs image registration between the reference image and each of the plurality of ultrasound images,
compares brightness values of the reference image and a brightness value of each of the plurality of ultrasound images that have undergone the image registration with each other,
compares a preset threshold value and a

brightness value difference between the reference image and each of the plurality of ultrasound images,
detects an ultrasound image for producing change information about the target object from among the plurality of ultrasound images based on the comparison of the preset threshold value and the brightness value difference, and
produces the change information indicative of a change in the target object based on the detection.

2. The system (100) of claim 1, wherein the processor (150) compares brightness values of pixels in the reference image with brightness values of corresponding pixels in each of the plurality of ultrasound images, removes the ultrasound image wherein a brightness value difference between the reference image and the ultrasound image exceeds the preset threshold value, and sets the ultrasound image as an ultrasound image for producing the change information about the target object wherein the brightness value difference between the reference image and the ultrasound image is less than or equal to the preset threshold value.

3. The system (100) of claim 1, wherein the processor (150) compares brightness values of voxels in the reference image with brightness values of corresponding voxels in each of the plurality of ultrasound images, removes the ultrasound image wherein a difference between voxels in the reference image and the ultrasound image exceeds the preset threshold value, and sets the ultrasound image as an ultrasound image for producing the change information about the target object wherein the difference between voxels in the reference image and the ultrasound image is less than or equal to the preset threshold value.

4. The system (100) of claim 1, further comprising a user input interface (140) configured to receive input information needed for setting a point on the target object in the reference image from a user.

5. The system (100) of claim 4, wherein the processor (150) sets the point on the reference image based on the input information, performs edge detection on the reference image based on the point to detect an edge of the target object, sets a region of interest (ROI) corresponding to the target object on the reference image by using the detected edge, sets a point on each of the plurality of ultrasound images based on the point set on the reference image, performs edge detection on each of the plurality of ultrasound images based on the point set on each of the plurality of ultrasound images to detect an edge

of the target object, and sets an ROI corresponding to the target object on each of the plurality of ultrasound images by using the detected edge.

6. The system (100) of claim 1, further comprising a user input interface (140) configured to receive input information needed for setting an edge region of the target object on the reference image as an ROI from a user.

7. The system (100) of claim 6, wherein the processor (150) sets the ROI on the reference image based on the input information, performs edge detection on each of the plurality of ultrasound images based on the ROI set on the reference image to detect an edge of the target object, and sets an ROI corresponding to the target object on each of the plurality of ultrasound images by using the detected edge.

8. A method of providing change information of a target object, the method comprising:

transmitting an ultrasound signal to a living body containing the target object during radiofrequency ablation RFA and receiving an ultrasound echo signal reflected from the living body to acquire ultrasound data, through an ultrasound probe (120);

extracting image data of the living body acquired before undergoing the RFA from a storage (110) and producing a reference image;

producing a plurality of ultrasound images by using the ultrasound data;

performing image registration between the reference image and each of the plurality of ultrasound images;

comparing brightness values of the reference image and brightness value of each of the plurality of ultrasound images that have undergone the image registration with each other;

comparing a preset threshold value and a brightness value difference between the reference image and each of the plurality of ultrasound images;

detecting an ultrasound image for producing change information about the target object from among the plurality of ultrasound images based on the comparison of the preset threshold value and a brightness value difference; and

producing the change information indicative of a change in the target object based on the detection.

9. The method of claim 8, wherein the detecting of the ultrasound image comprises:

comparing values of pixels in the reference image with values of corresponding pixels in each

of the plurality of ultrasound images;

removing the ultrasound image wherein a brightness value difference between the reference image and the ultrasound image exceeds the preset threshold value; and

setting the ultrasound image as an ultrasound image for producing the change information of the target object wherein the brightness value difference between the reference image and the ultrasound image is less than or equal to the preset threshold value.

10. The method of claim 8, wherein the detecting of the ultrasound image comprises:

comparing values of voxels in the reference image with values of corresponding voxels in each of the plurality of ultrasound images;

removing the ultrasound image wherein a difference between voxels in the reference image and the ultrasound image exceeds the preset threshold value;

setting the ultrasound image as an ultrasound image for producing change information about the target object wherein the difference between voxels in the reference image and the ultrasound image is less than or equal to the preset threshold value.

11. The method of claim 8, wherein the detecting of the ultrasound image further comprises receiving input information needed for setting a point on the target object in the reference image from a user.

12. The method of claim 8, wherein the detecting of the ultrasound image comprises:

setting the point on the reference image based on the input information;

performing edge detection on the reference image based on the point to detect an edge of the target object;

setting a region of interest (ROI) corresponding to the target object on the reference image by using the detected edge;

setting a point on each of the plurality of ultrasound images based on the point set on the reference image;

performing edge detection on each of the plurality of ultrasound images based on the point set on each of the plurality of ultrasound images to detect an edge of the target object; and setting an ROI corresponding to the target object on each of the plurality of ultrasound images by using the detected edge.

13. The method of claim 8, wherein the detecting of the ultrasound image further comprises receiving input

information needed for setting an edge region of the target object on the reference image as an ROI from a user.

Patentansprüche

1. Ultraschallsystem (100), welches Folgendes aufweist:

Einen Speicher (110), der Bilddaten eines lebenden Körpers speichert, das ein Zielobjekt enthält, das erlangt wird, bevor es einer Radiofrequenzablation RFA unterzogen wird;
eine Ultraschallsonde (120), die ein Ultraschallsignal zu dem lebenden Körper während der RFA überträgt und ein von dem lebenden Körper reflektiertes Ultraschallechosignal empfängt, um ein Empfangssignal zu erzeugen;
eine Ultraschalldatenerlangungseinheit (130), die dafür vorgesehen ist, Ultraschalldaten durch Verwenden des Empfangssignals zu erlangen; und
einen Prozessor (150), der
ein Referenzbild durch Verwenden der Bilddaten und eine Vielzahl von Ultraschallbildern durch Verwenden der Ultraschalldaten erzeugt, eine Bildregistrierung zwischen dem Referenzbild und jedem der Vielzahl von Ultraschallbildern erzeugt,
Helligkeitswerte des Referenzbilds und einen Helligkeitswert von jedem der Vielzahl von Ultraschallbildern, die der Bildregistrierung unterzogen worden sind, miteinander vergleicht, einen eingestellten Grenzwert und eine Helligkeitswertdifferenz zwischen dem Referenzbild und jedem der Vielzahl von Ultraschallbildern vergleicht,
ein Ultraschallbild zum Produzieren von Änderungsinformationen bezüglich des Zielobjekts aus der Vielzahl von Ultraschallbildern basierend auf dem Vergleich des eingestellten Grenzwerts und der Helligkeitswertdifferenz detektiert, und
die Austauschinformationen, die eine Änderung des Zielobjekts basierend auf der Detektion anzeigen, produziert.

2. System (100) nach Anspruch 1, wobei der Prozessor (150) Helligkeitswerte von Pixeln in dem Referenzbild mit Helligkeitswerten von entsprechenden Pixeln in jedem der Vielzahl von Ultraschallbildern vergleicht, das Ultraschallbild entfernt, bei dem eine Helligkeitswertdifferenz zwischen dem Referenzbild und dem Ultraschallbild den eingestellten Grenzwert überschreitet, und das Ultraschallbild als ein Ultraschallbild zum Produzieren der Änderungsinformationen bezüglich des Zielobjekts festlegt, bei dem

die Helligkeitswertdifferenz zwischen dem Referenzbild und dem Ultraschallbild weniger oder gleich dem eingestellten Grenzwert ist.

3. System (100) nach Anspruch 1, wobei der Prozessor (150) Helligkeitswerte von Voxeln in dem Referenzbild mit Helligkeitswerten von entsprechenden Voxeln in jedem der Vielzahl von Ultraschallbildern vergleicht, das Ultraschallbild entfernt, bei dem eine Differenz zwischen Voxeln in dem Referenzbild und dem Ultraschallbild den eingestellten Grenzwert überschreitet, und das Ultraschallbild als ein Ultraschallbild zum Produzieren der Änderungsinformationen bezüglich des Zielobjekts festlegt, bei dem der Unterschied zwischen Voxeln in dem Referenzbild und dem Ultraschallbild weniger oder gleich dem eingestellten Grenzwert ist.
4. System (100) nach Anspruch 1, welches des Weiteren eine Benutzereingabeschnittstelle (140) aufweist, die dafür vorgesehen ist, Eingabeinformationen zu empfangen, die zum Festlegen eines Punkts auf dem Zielobjekt in dem Referenzbild von einem Benutzer benötigt werden.
5. System (100) nach Anspruch 4, wobei der Prozessor (150) den Punkt auf dem Referenzbild basierend auf den Eingabeinformationen festlegt, eine Randdetektion an dem Referenzbild basierend auf dem Punkt durchführt, um einen Rand des Zielobjekts zu detektieren, einen interessierenden Bereich (ROI), der dem Zielobjekt auf dem Referenzbild entspricht, durch Verwenden des detektierten Rands festlegt, einen Punkt auf jedem der Vielzahl von Ultraschallbildern basierend auf dem Punkt festlegt, der auf dem Referenzbild festgelegt wurde, eine Randdetektion an jedem der Vielzahl von Ultraschallbildern basierend auf dem Punkt durchführt, der auf jedem der Vielzahl von Ultraschallbildern festgelegt wurde, um einen Rand des Zielobjekts zu detektieren, und einen ROI entsprechend dem Zielobjekt auf jedem der Vielzahl von Ultraschallbildern durch Verwenden des detektierten Rands festlegt.
6. System (100) nach Anspruch 1, welches des Weiteren eine Benutzereingabeschnittstelle (140) aufweist, die dafür vorgesehen ist, Eingabeinformationen zu empfangen, die zum Festlegen eines Randbereichs des Zielobjekts auf dem Referenzbild als einen ROI von einem Benutzer benötigt werden.
7. System (100) nach Anspruch 6, wobei der Prozessor (150) den ROI auf dem Referenzbild basierend auf den Eingabeinformationen festlegt, eine Randdetektion auf jedem der Vielzahl von Ultraschallbildern basierend auf dem ROI durchführt, der auf dem Referenzbild festgelegt wurde, um einen Rand des Zielobjekts zu detektieren, und einen ROI entsprechend

dem Zielobjekt auf jeder der Vielzahl von Ultraschallbildern durch Verwendung des detektierten Rands festlegt.

8. Verfahren zum Erzeugen von Änderungsinformationen eines Zielobjekts, wobei das Verfahren Folgendes aufweist:

Übertragen eines Ultraschallsignals zu einem lebenden Körper, der das Zielobjekt enthält und zwar, während einer Radiofrequenzablation RFA, und Empfangen eines Ultraschallechosignals, das von dem lebenden Körper reflektiert wurde, um Ultraschalldaten zu erlangen, und zwar durch eine Ultraschallsonde (120); Extrahieren von Bilddaten des lebenden Körpers, die erlangt wurden, bevor er der RFA unterzogen wurde, und zwar von einem Speicher (110), und Erzeugen eines Referenzbilds; Erzeugen einer Vielzahl von Ultraschallbildern durch Verwenden der Ultraschalldaten; Durchführen einer Bildregistrierung zwischen dem Referenzbild und jedem der Vielzahl von Ultraschallbildern; Vergleichen von Helligkeitswerten des Referenzbilds und einem Helligkeitswert von jedem der Vielzahl von Ultraschallbildern, die der Bildregistrierung unterzogen wurden, miteinander; Vergleichen eines eingestellten Grenzwerts und einer Helligkeitswertdifferenz zwischen dem Referenzbild und jedem der Vielzahl von Ultraschallbildern; Detektieren eines Ultraschallbilds zum Produzieren von Änderungsinformationen bezüglich des Zielobjekts aus der Vielzahl von Ultraschallbildern basierend auf dem Vergleich des eingestellten Grenzwerts und einer Helligkeitswertdifferenz; und Produzieren der Änderungsinformationen, die eine Änderung des Zielobjekts basierend auf der Detektion anzeigen.

9. Verfahren nach Anspruch 8, wobei das Detektieren des Ultraschallbilds Folgendes aufweist:

Vergleichen von Werten von Pixeln in dem Referenzbild mit Werten von entsprechenden Pixeln in jedem der Vielzahl von Ultraschallbildern; Entfernen des Ultraschallbilds, in dem eine Helligkeitswertdifferenz zwischen dem Referenzbild und dem Ultraschallbild den eingestellten Grenzwert überschreitet; und Festlegen des Ultraschallbilds als ein Ultraschallbild zum Produzieren der Änderungsinformationen bezüglich des Zielobjekts, bei dem die Helligkeitswertdifferenz zwischen dem Referenzbild und dem Ultraschallbild weniger oder

gleich dem eingestellten Grenzwert ist.

10. Verfahren nach Anspruch 8, wobei das Detektieren des Ultraschallbilds Folgendes aufweist:

Vergleichen von Werten von Voxeln in dem Referenzbild mit Werten von entsprechenden Voxeln in jedem der Vielzahl von Ultraschallbildern; Entfernen des Ultraschallbilds, in dem eine Differenz zwischen Voxeln in dem Referenzbild und dem Ultraschallbild den eingestellten Grenzwert überschreitet; Festlegen des Ultraschallbilds als ein Ultraschallbild zum Produzieren von Änderungsinformationen bezüglich des Zielobjekts, bei dem die Differenz zwischen Voxeln in dem Referenzbild und dem Ultraschallbild weniger oder gleich dem eingestellten Grenzwert ist.

11. Verfahren nach Anspruch 8, wobei das Detektieren des Ultraschallbilds des Weiteren das Empfangen von Eingabeinformationen aufweist, die zum Festlegen eines Punkts auf dem Zielobjekt in dem Referenzbild von einem Benutzer benötigt werden.

12. Verfahren nach Anspruch 8, wobei das Detektieren des Ultraschallbilds folgendes aufweist:

Festlegen des Punkts auf dem Referenzbild basierend auf den Eingabeinformationen; Durchführen einer Randdetektion auf dem Referenzbild basierend auf dem Punkt, um einen Rand des Zielobjekts zu detektieren; Festlegen eines interessierenden Bereichs ROI, der dem Zielobjekt auf dem Referenzbild entspricht, und zwar durch Verwenden des detektierten Rands; Festlegen eines Punkts auf jedem der Vielzahl von Ultraschallbildern basierend auf dem Punkt, der auf dem Referenzbild festgelegt wurde; Durchführen einer Randdetektion auf jedem der Vielzahl von Ultraschallbildern basierend auf dem Punkt, der auf jedem der Vielzahl von Ultraschallbildern festgelegt wurde, um einen Rand des Zielobjekts zu detektieren; und Festlegen eines ROI entsprechend dem Zielobjekt auf jeder der Vielzahl von Ultraschallbildern unter Verwendung des detektierten Rands.

13. Verfahren nach Anspruch 8, wobei das Detektieren des Ultraschallbilds des Weiteren das Empfangen von Eingabeinformationen beinhaltet, die zum Festlegen eines Randbereichs des Zielobjekts auf dem Referenzbild als ein ROI von einem Benutzer benötigt werden.

Revendications

1. Système ultrasonique (100) comportant :

une mémoire (110) qui mémorise une donnée image d'un corps vivant contenant un objet cible, qui est acquise avant que soit exécutée une ablation par radiofréquence RFA ;
 une sonde ultrasonique (120) qui transmet un signal ultrasonique au corps vivant pendant la RFA et qui reçoit un signal d'écho ultrasonique réfléchi par le corps vivant pour créer un signal de réception ;
 un acquéreur de données ultrasoniques (130) configuré pour acquérir des données ultrasoniques en utilisant le signal de réception ; et
 un processeur (150) qui produit une image de référence en utilisant la donnée image et une pluralité d'images ultrasoniques en utilisant les données ultrasoniques, effectue l'enregistrement d'images entre l'image de référence et chacune des pluralités d'images ultrasoniques,
 compare les valeurs de brillance de l'image de référence et une valeur de brillance de chacune des pluralités d'images ultrasoniques qui sont en dessous de l'enregistrement des images par rapport aux autres,
 compare une valeur de seuil prédéterminé et une valeur de brillance différente entre l'image de référence et chacune des pluralités d'images ultrasoniques,
 détecte une information d'image ultrasonique pour produire une information de changement entre l'objet cible parmi la pluralité d'images ultrasoniques basée sur la comparaison de la présente valeur prédéterminée de seuil et la différence des valeurs de brillances, et
 produire l'information de changement indiquant la modification de l'objet cible sur la base de la détection.

2. Système ultrasonique (100) de la revendication 1, dans lequel le processeur (150) compare les valeurs de brillance des pixels de l'image de référence avec les valeurs de brillances des pixels correspondants de chacune des pluralités des images ultrasoniques, élimine les images ultrasoniques dans lesquelles une valeur de différence entre l'image de référence et les images ultrasoniques dépasse la valeur de seuil prédéterminé, et fixe les images ultrasoniques comme une image ultrasonique pour procéder à l'information de modification concernant l'objet cible dans lequel la valeur de différence de brillance entre l'image de référence et les images ultrasoniques est inférieure à ou égale à la valeur de seuil prédéterminé.

3. Système ultrasonique (100) de la revendication 1, dans lequel le processeur (150) compare les valeurs de brillance de voxels dans l'image de référence avec les valeurs de brillance des voxels correspondants dans chacune des pluralités d'images ultrasoniques, élimine les images ultrasoniques dans lesquelles une valeur de différence entre les voxels de l'image de référence et les images ultrasoniques dépassent la valeur de seuil prédéterminé, et fixe l'image ultrasonique comme une image ultrasonique pour procéder à l'information de modification concernant l'objet cible, dans lequel la différence entre les voxels dans l'image de référence et l'image ultrasonique est inférieure ou égale à la valeur prédéterminée du seuil.

4. Système ultrasonique (100) de la revendication 1, comportant en outre une interface d'entrée d'utilisateur (140) configurée pour recevoir les informations d'entrée nécessaires pour fixer un point sur l'objet cible dans l'image de référence par l'utilisateur.

5. Système ultrasonique (100) de la revendication 4, dans lequel le processeur (150) fixe le point sur l'image de référence sur l'information d'entrée, effectue la détection de bord sur l'image de référence basée sur le point pour détecter un bord sur l'objet cible, fixe une région d'intérêt (ROI) qui correspond à l'objet cible sur l'image de référence en utilisant le bord détecté, fixe un point sur chacune des pluralités d'images ultrasoniques sur la base du point fixé sur l'image de référence, effectue la détection de bord sur chacune des pluralités d'images ultrasoniques sur la base du point fixé sur chacune des pluralités d'images ultrasoniques pour détecter un bord sur l'objet cible, et fixe un ROI correspondant à l'objet cible sur chacune des pluralités d'images ultrasoniques en utilisant le bord détecté.

6. Système ultrasonique (100) de la revendication 1, comprenant en outre une interface d'entrée utilisateur (140) configurée pour recevoir les informations d'entrée nécessaire pour fixer une zone de bord d'un objet cible sur l'image de référence comme une ROI d'un utilisateur.

7. Système ultrasonique (100) de la revendication 6, dans lequel le processeur (150) fixe la ROI sur l'image de référence basée sur l'information d'entrée, effectue une détection de bord sur chacune des pluralités d'images ultrasoniques sur la base de la ROI fixée sur l'image de référence pour détecter un bord de l'objet cible, et fixe une ROI correspondant à l'objet cible sur chacune des pluralités d'images ultrasoniques en utilisant le bord détecté.

8. Procédé pour fournir une information de changement d'un objet cible, le procédé comportant :

- la transmission d'un signal ultrasonique à un corps vivant contenant l'objet cible pendant une ablation par radiofréquence RFA et la réception d'un signal d'écho ultrasonique réfléchi par le corps vivant pour acquérir une donnée ultrasonique, au moyen d'une sonde ultrasonique (120) ;
 l'extraction d'une donnée image du corps vivant acquise avant d'effectuer la RFA d'une mémoire (110) et la production d'une image de référence ;
 la production d'une pluralité d'images ultrasoniques en utilisant la donnée ultrasonique ;
 la production de l'enregistrement d'image entre l'image de référence et chacune des pluralités d'images ultrasoniques ;
 la comparaison des valeurs de brillance de l'image de référence et des valeurs de brillance de chacune des pluralités d'images ultrasoniques qui sont en-dessous de l'enregistrement des images par rapport aux autres ;
 la comparaison d'une valeur de seuil prédéterminé et d'une différence de valeur de brillance entre l'image de référence et chacune des pluralités d'images ultrasoniques ;
 la détection d'une image ultrasonique pour donner une information de changement concernant l'objet cible par rapport à la pluralité des images ultrasoniques basée sur la comparaison de la valeur de seuil prédéterminé et de la valeur de la différence de la brillance; et
 la production du changement de l'information indiquant le changement de l'objet cible sur la détection.
9. Procédé selon la revendication 8, dans lequel la détection de l'image ultrasonique comprend :
- la comparaison des valeurs de pixels dans l'image de référence avec les valeurs des pixels correspondants de la pluralité des images ultrasoniques ;
 l'élimination de l'image ultrasonique dans laquelle la différence de valeur de la brillance entre l'image de référence et les images ultrasoniques dépasse la valeur de seuil prédéterminé ; et
 la détermination de l'image ultrasonique comme étant la valeur ultrasonique qui produit le changement d'information de l'objet cible, dans lequel la différence de valeur de brillance entre l'image de référence et les images ultrasoniques est inférieure ou égale à la valeur de seuil prédéterminé.
10. Procédé selon la revendication 8, dans lequel la détection de l'image ultrasonique comprend :
- la comparaison des valeurs des voxels de l'image de référence avec les valeurs des voxels correspondants de chacune des pluralités d'images ultrasoniques ;
 l'élimination de l'image ultrasonique dans laquelle la différence entre les voxels de l'image de référence et l'image ultrasonique excède la valeur du seuil prédéterminé ;
 la fixation de l'image ultrasonique comme une image ultrasonique pour opérer le changement de l'information concernant l'objet cible dans lequel la différence entre les voxels de l'image de référence et l'image ultrasonique est inférieure ou égale à la valeur du seuil prédéterminée.
11. Procédé selon la revendication 8, dans lequel la détection de l'image ultrasonique comprend en outre la réception d'informations d'entrées nécessaire pour fixer un point sur l'objet cible dans l'image de référence par l'utilisateur.
12. Procédé selon la revendication 8, dans lequel la détection de l'image ultrasonique comprend :
- la fixation du point sur l'image de référence, basée sur l'information entrée ;
 la réalisation de la détection de bord sur l'image de référence basée sur le point de détection d'un bord sur l'objet cible ;
 la fixation d'une région d'intérêt (ROI) correspondant à l'objet cible sur l'image de référence en utilisant le bord détecté ;
 la fixation d'un point sur chacune des pluralités d'images ultrasoniques basée sur le point fixé sur l'image de référence ;
 la réalisation de la détection de bord sur chacune des pluralités d'images ultrasoniques basée sur le point fixé sur chacune des pluralités d'images ultrasoniques pour détecter un bord sur l'objet cible ; et
 fixer une ROI correspondant à l'objet cible sur chacune des pluralités d'images ultrasoniques en utilisant le bord détecté.
13. Procédé selon la revendication 8, dans lequel la détection de l'image ultrasonique comprend en outre la réception d'informations d'entrées nécessaire pour fixer une zone de bord de l'objet cible sur l'image de référence comme un ROI d'un utilisateur.

FIG. 1

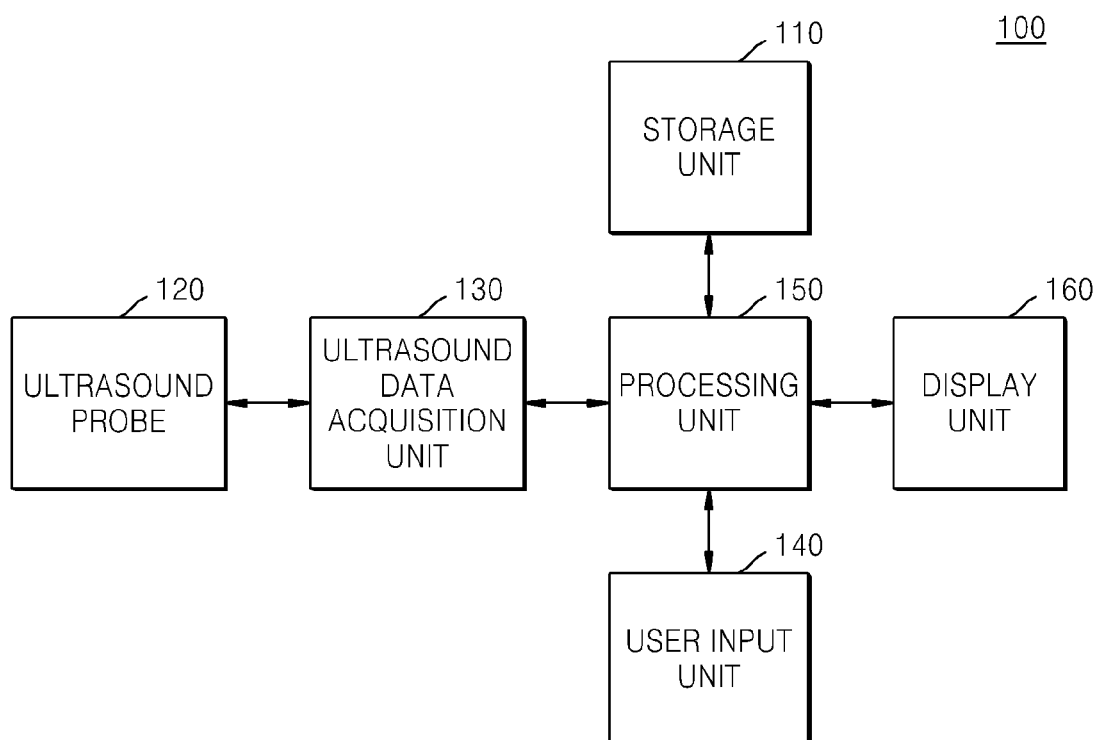


FIG. 2

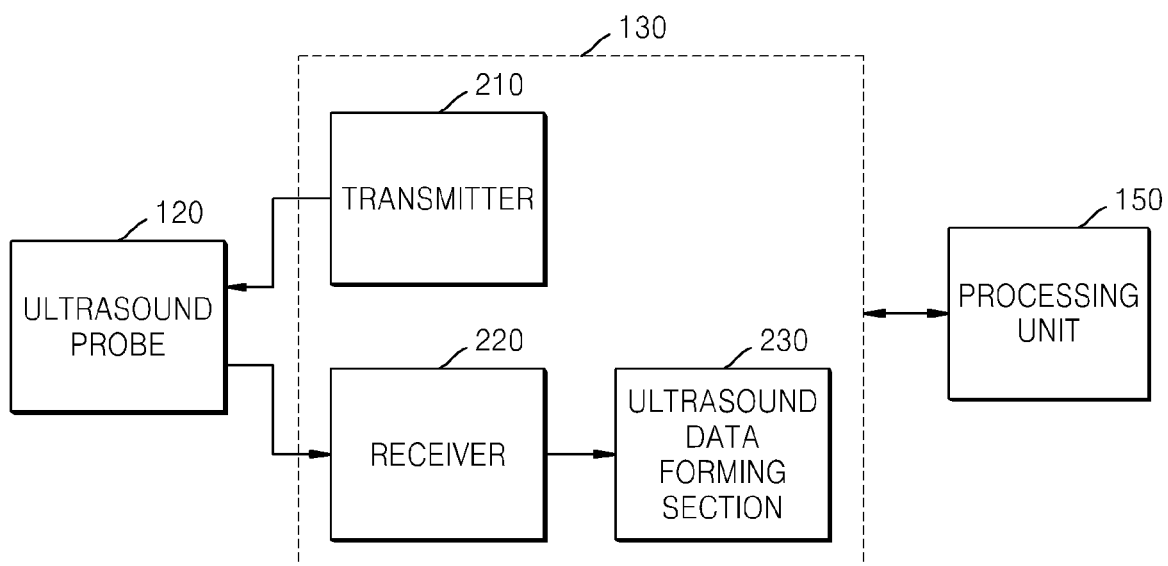


FIG. 3

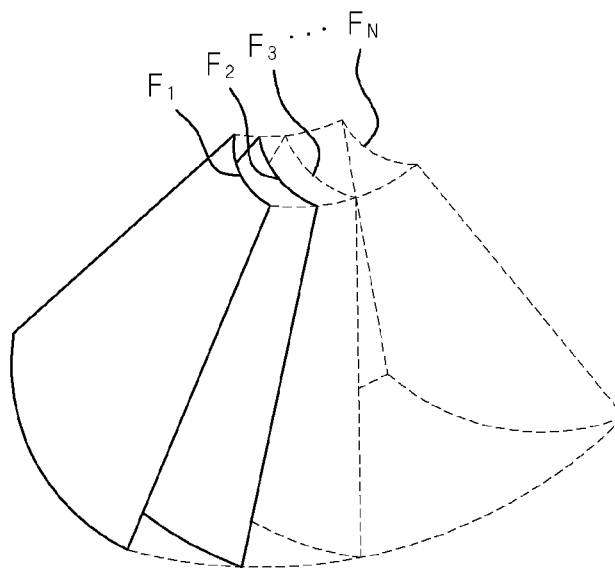


FIG. 4

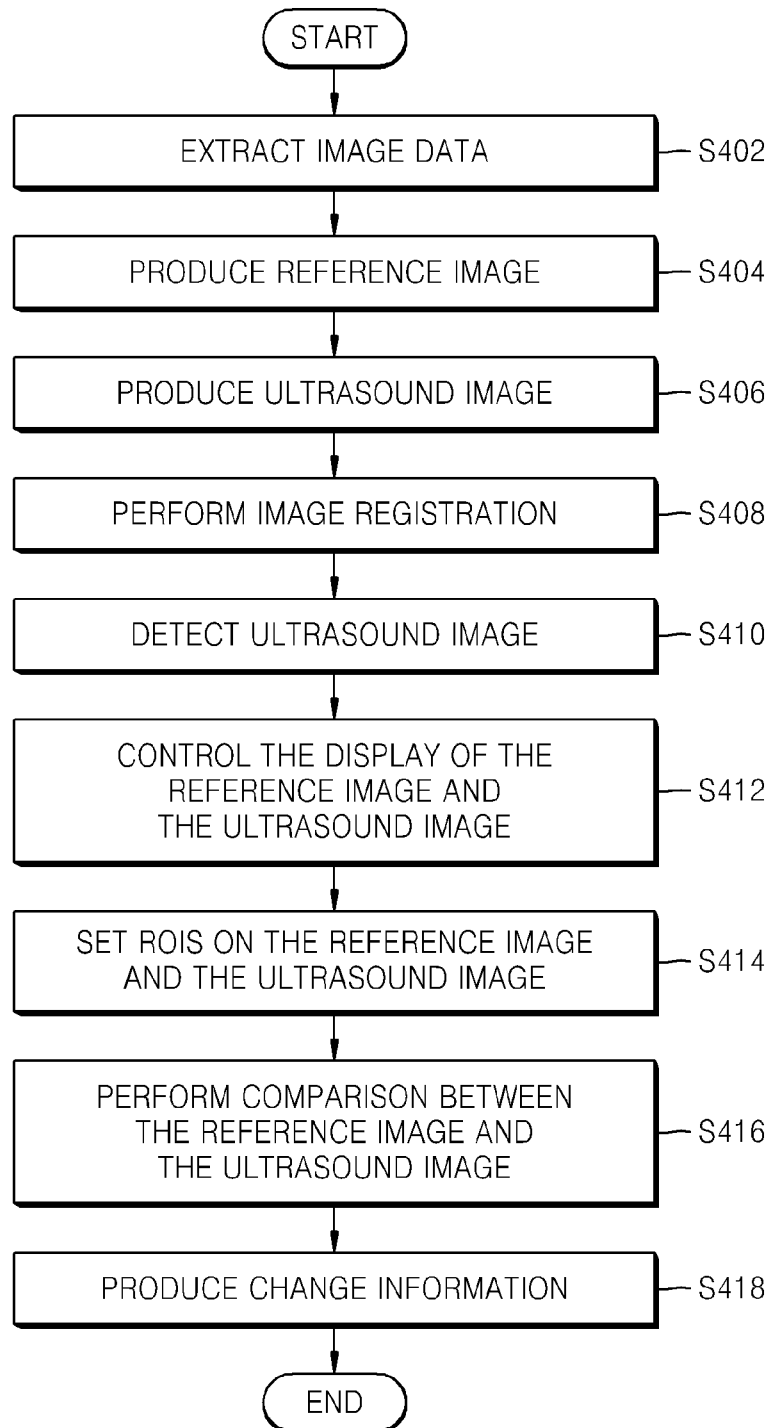


FIG. 5

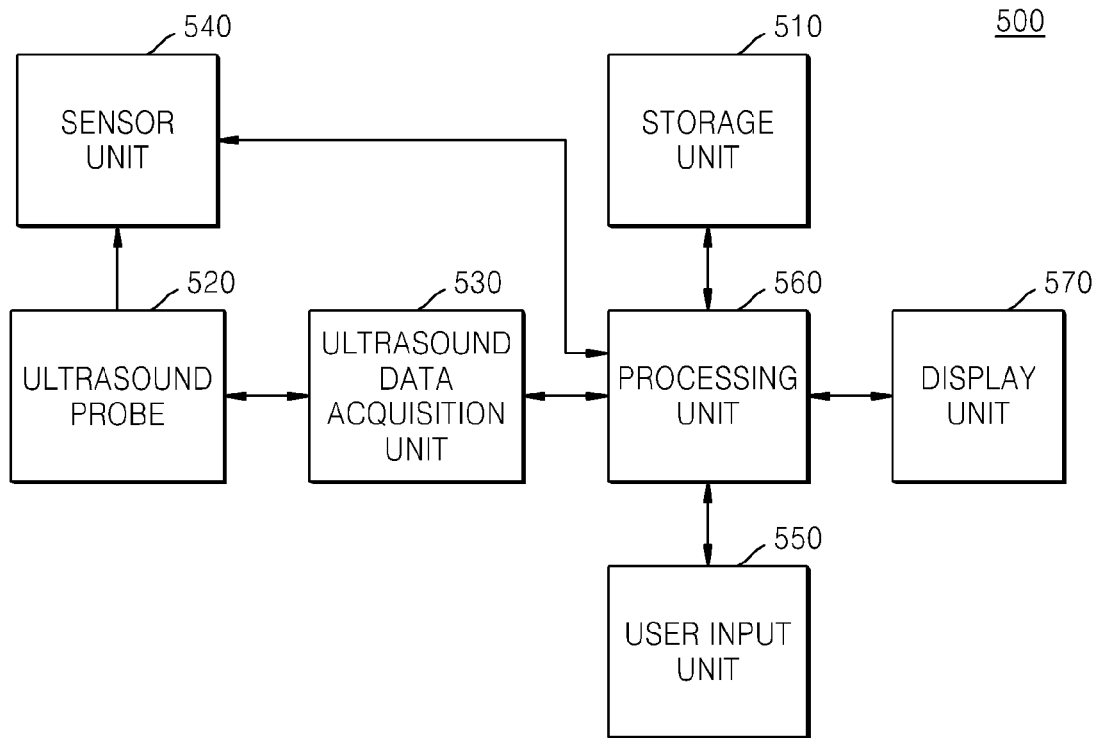


FIG. 6

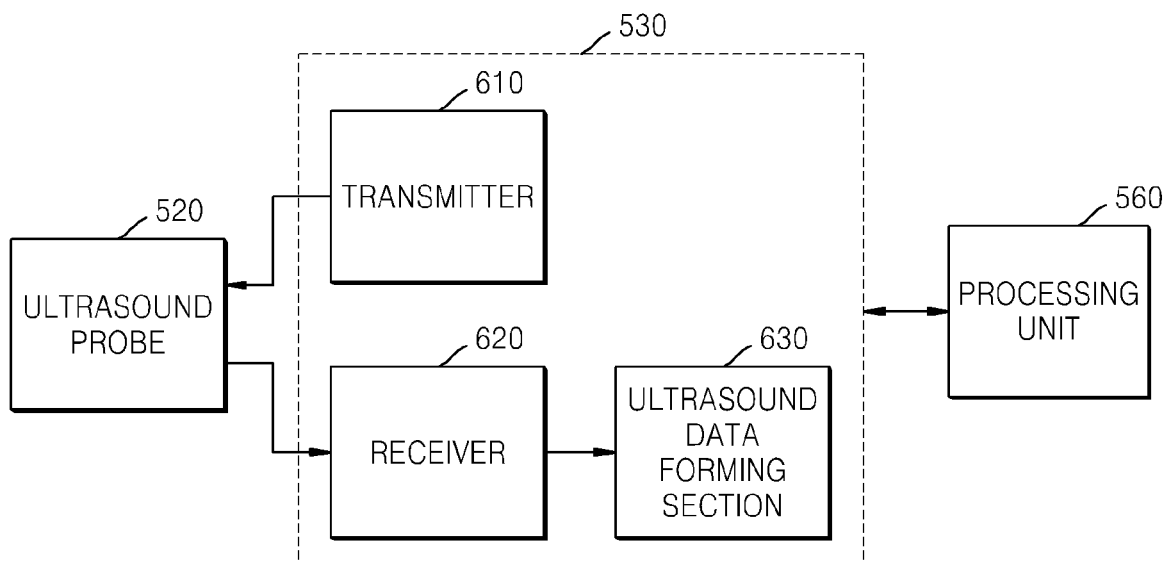
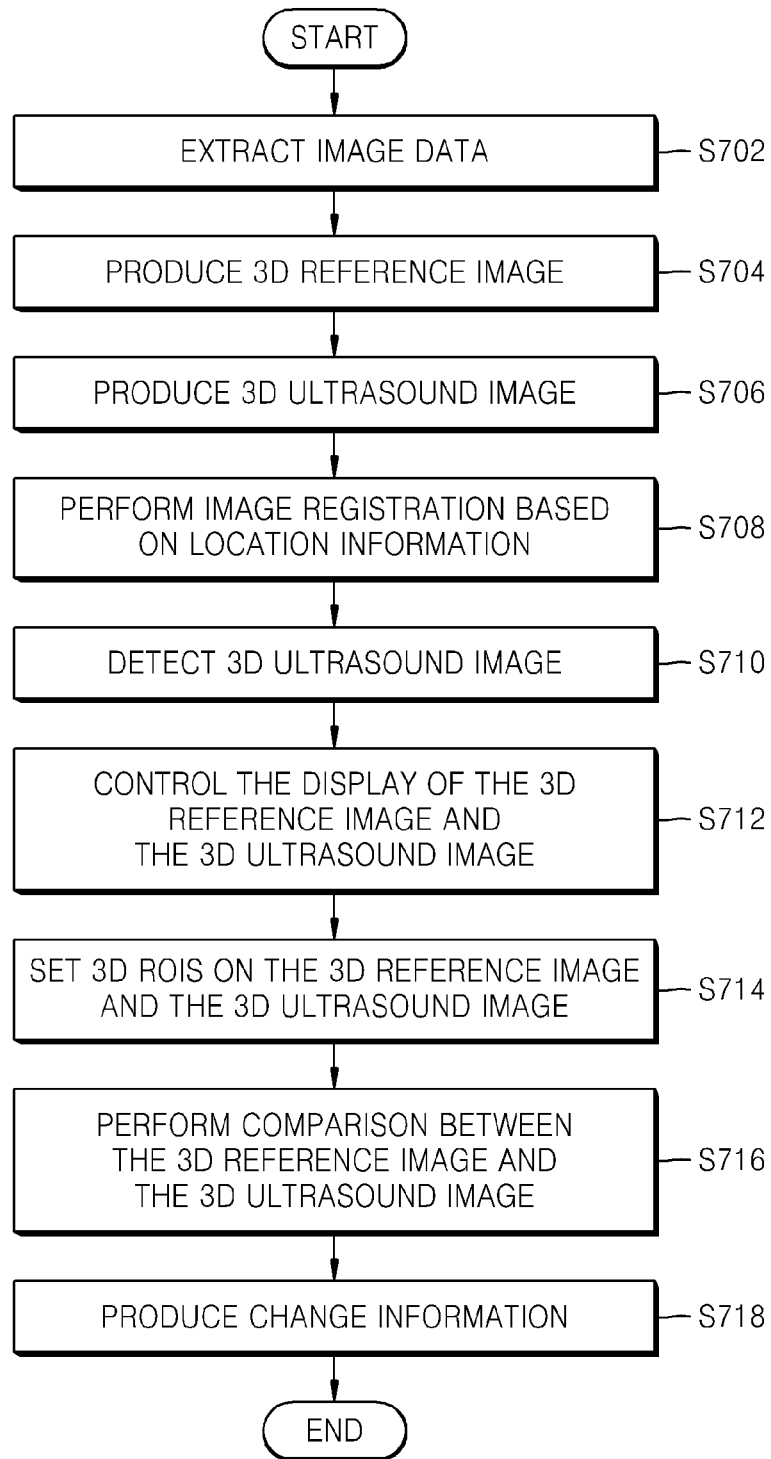


FIG. 7



REFERENCES CITED IN THE DESCRIPTION

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专利名称(译)	超声系统和提供目标物体的变化信息的方法		
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摘要(译)

提供了一种超声系统和方法，用于通过对在射频消融（RFA）之前获取的参考图像和在RFA期间获取的超声图像执行图像配准并且比较已经历的参考图像和超声图像来提供目标对象的改变信息。图像相互注册。

FIG. 1

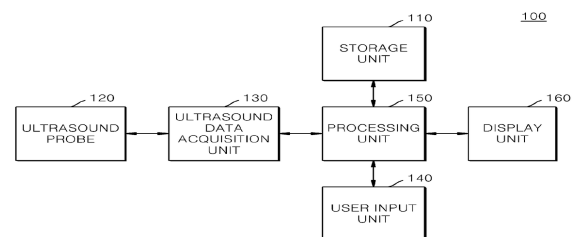


FIG. 2

