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(54) **CARDIOVASCULAR HEALTH MONITORING
DEVICE**

(52) **U.S. Cl.**

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5/6829 (2013.01)

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(57)

ABSTRACT

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CA2015/051120 on Nov. 2, 2015.

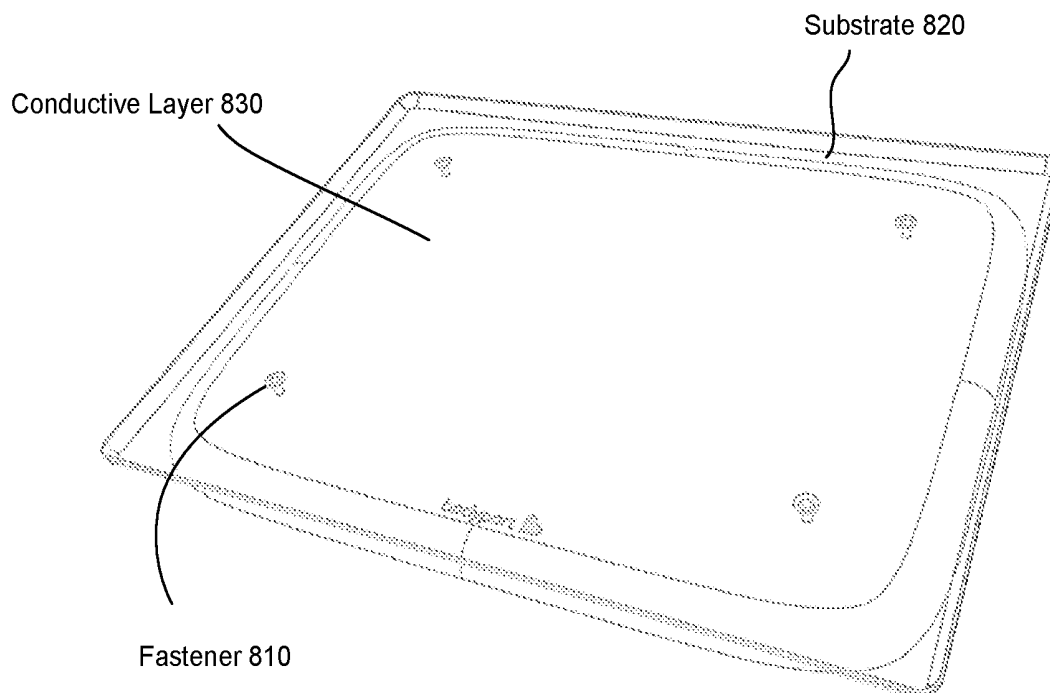
(60) Provisional application No. 62/191,318, filed on Jul.
10, 2015.

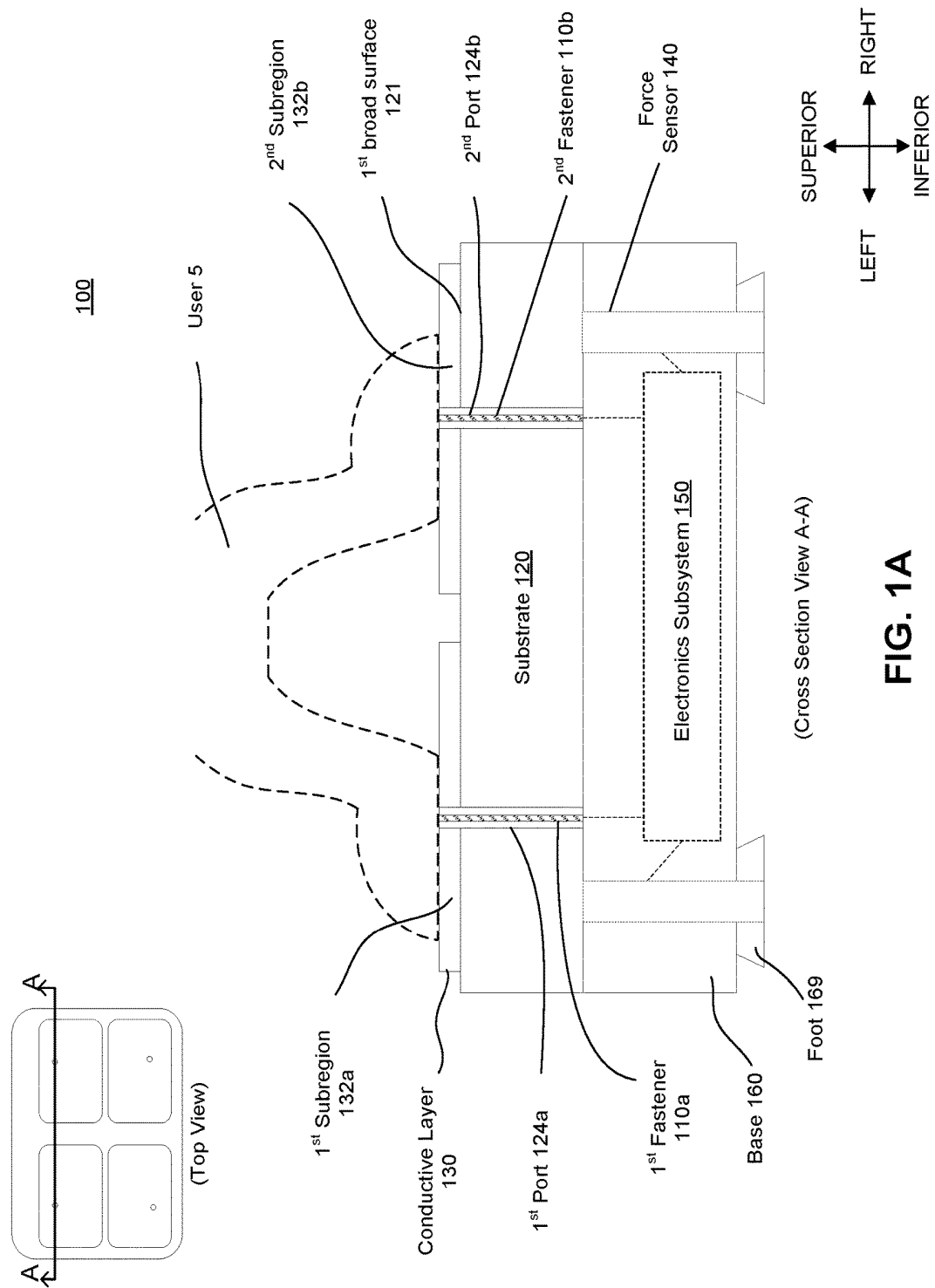
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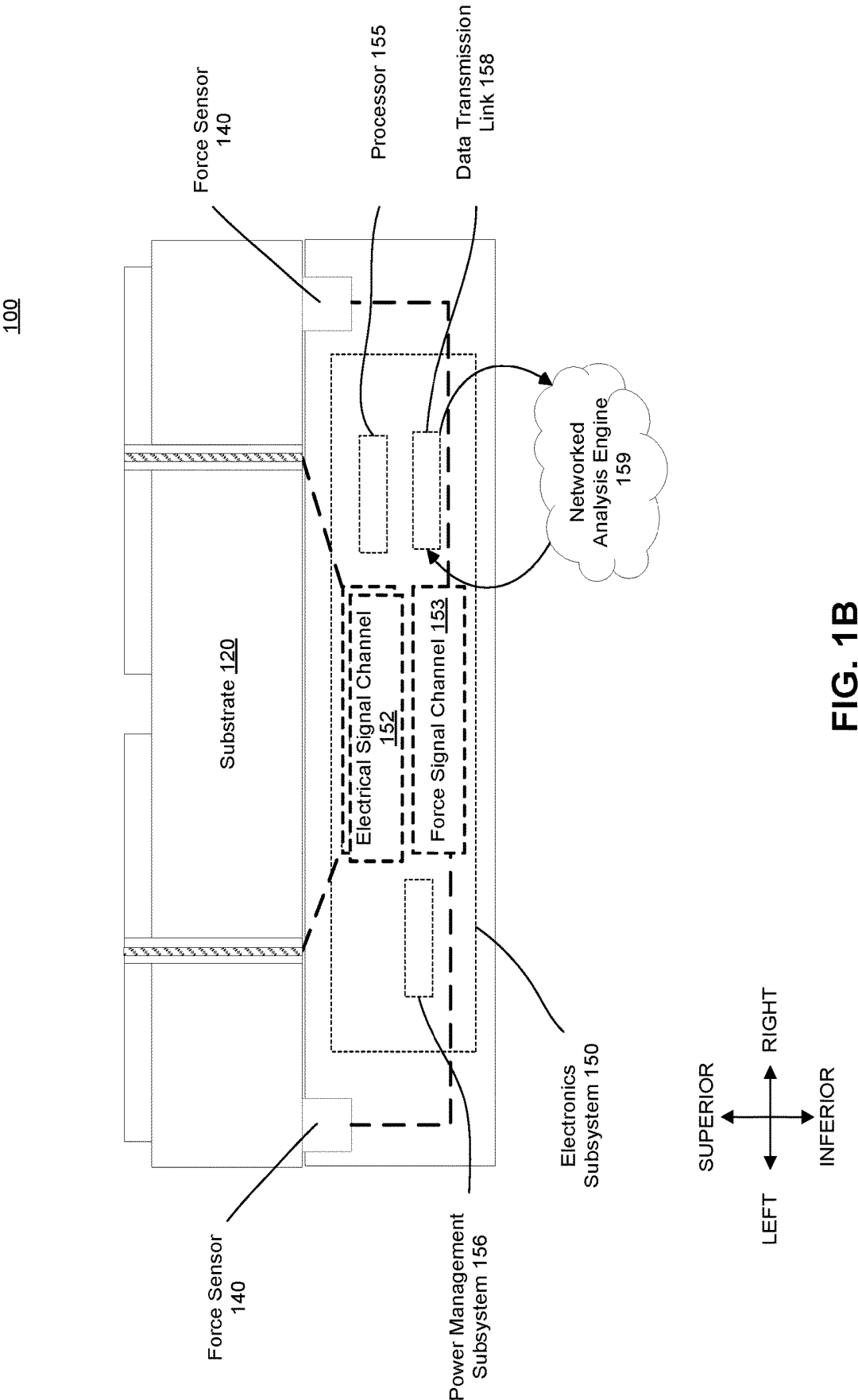
(51) **Int. Cl.**

A61B 5/0408 (2006.01)
A61B 5/00 (2006.01)
A61B 5/053 (2006.01)

A device for simultaneously acquiring electrocardiogram (ECG) signals, impedance plethysmogram (IPG) signals, ballistocardiogram (BCG) signals, and weight measurements through feet of a user. The device includes an electrically-conductive surface for contacting feet of the user and supporting weight of the user during use. The device also includes one or more force sensors for detecting forces and force variations across the electrically-conductive surface, electronics for processing electrical signals generated and/or detected from the electrically conductive surface, signals from the set of force sensors, and a base containing the electronics. The base is structurally coupled to the electrically-conductive surface by a set of conductive fasteners that transmit signals from the electrically-conductive surface to the electronics. The device can also include an integrated display for providing health insights to the user.







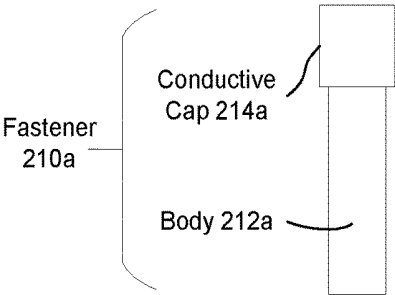


FIG. 2A

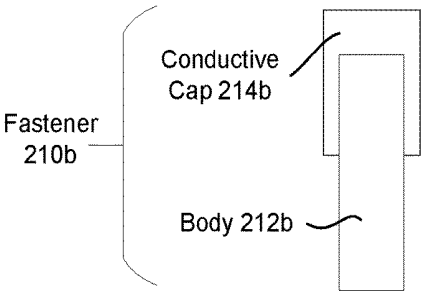


FIG. 2B

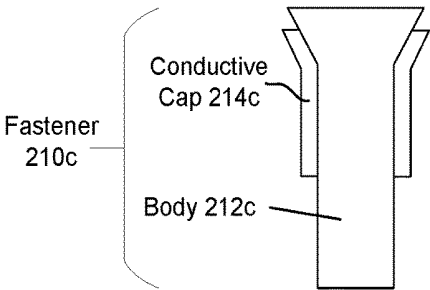


FIG. 2C

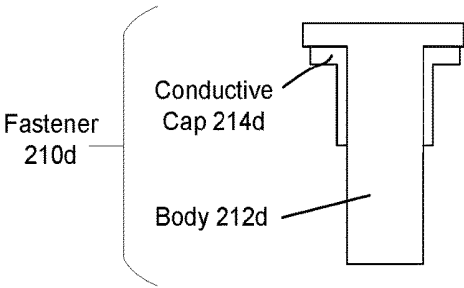
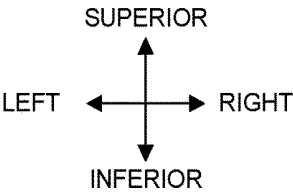


FIG. 2D



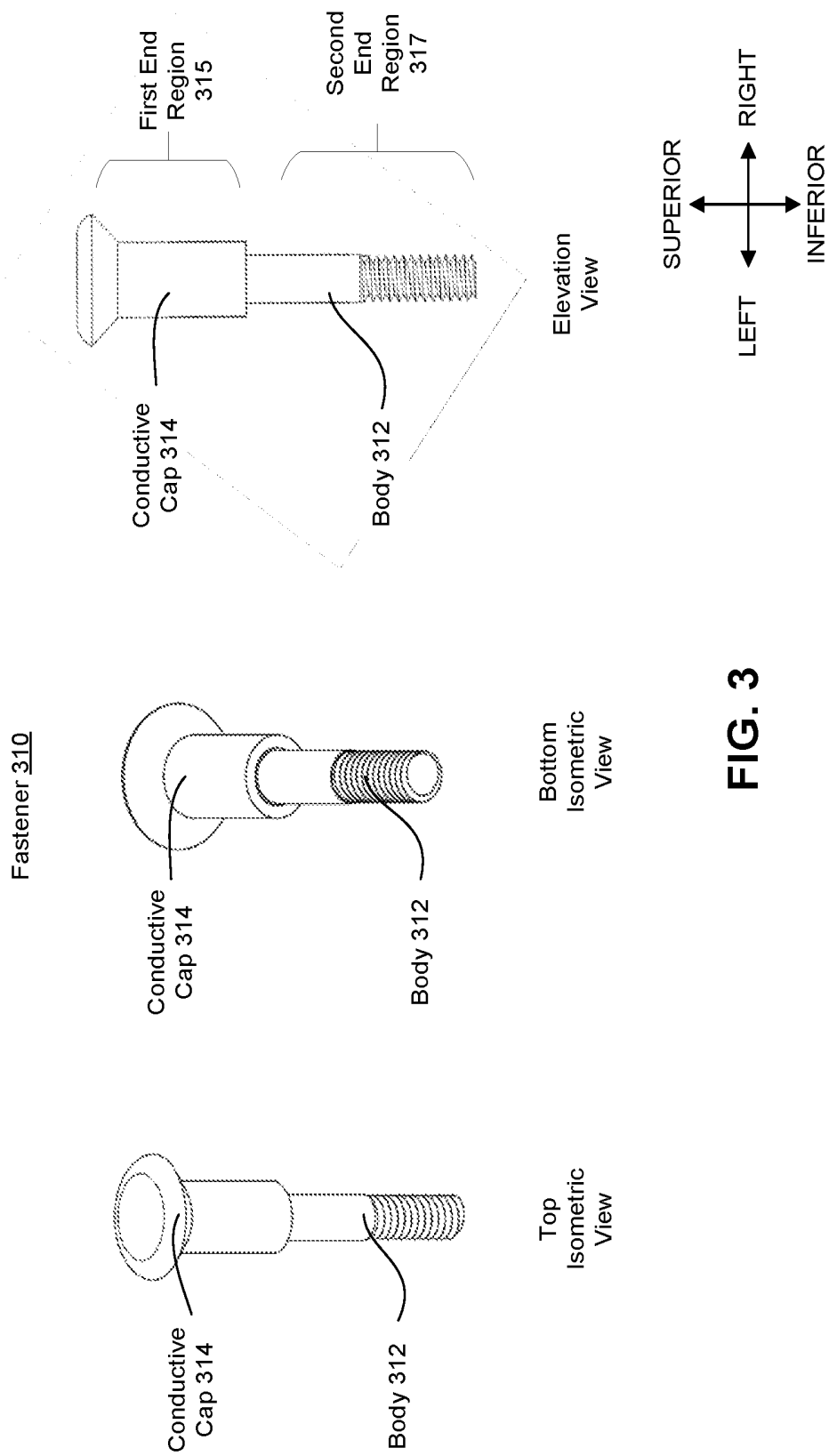


FIG. 3

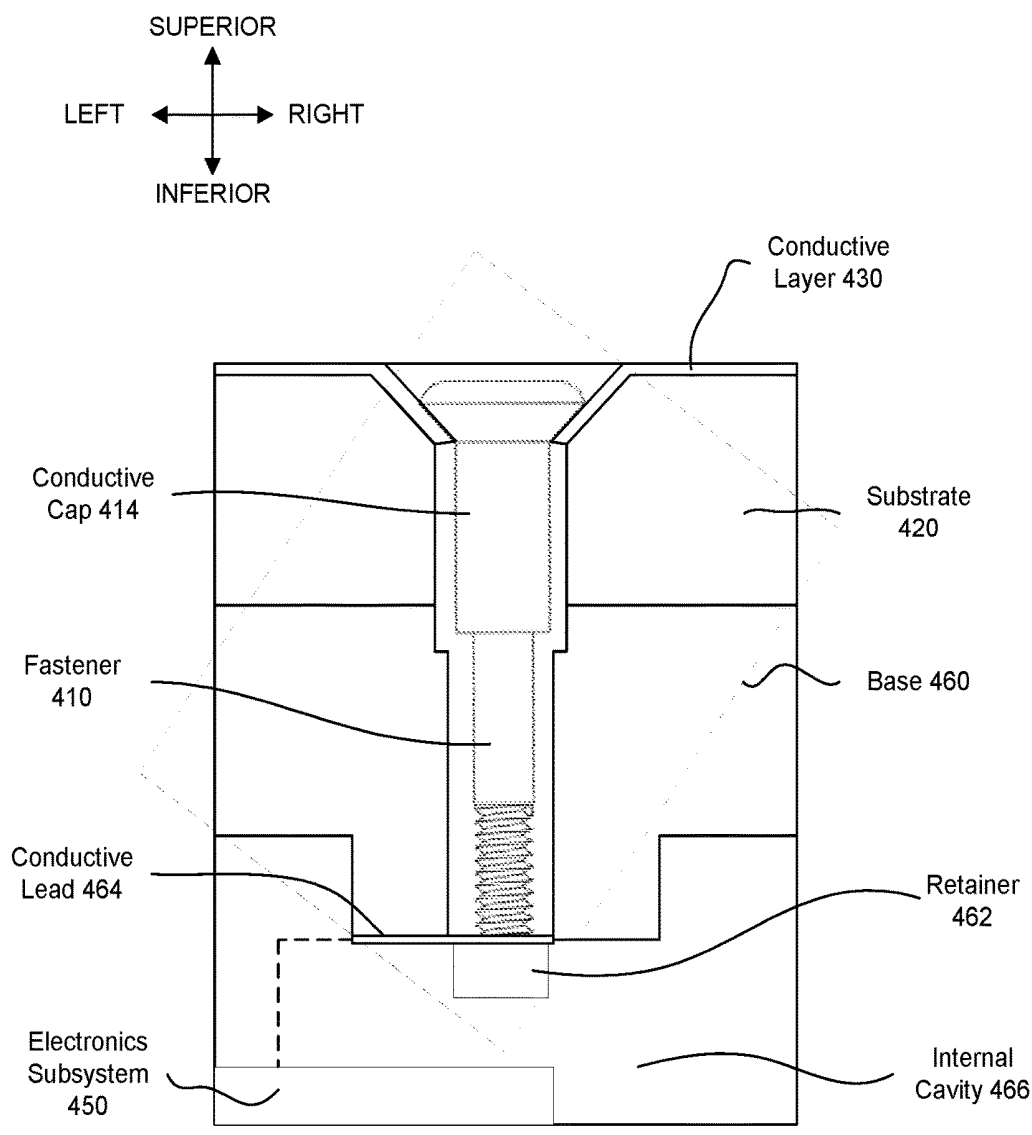


FIG. 4

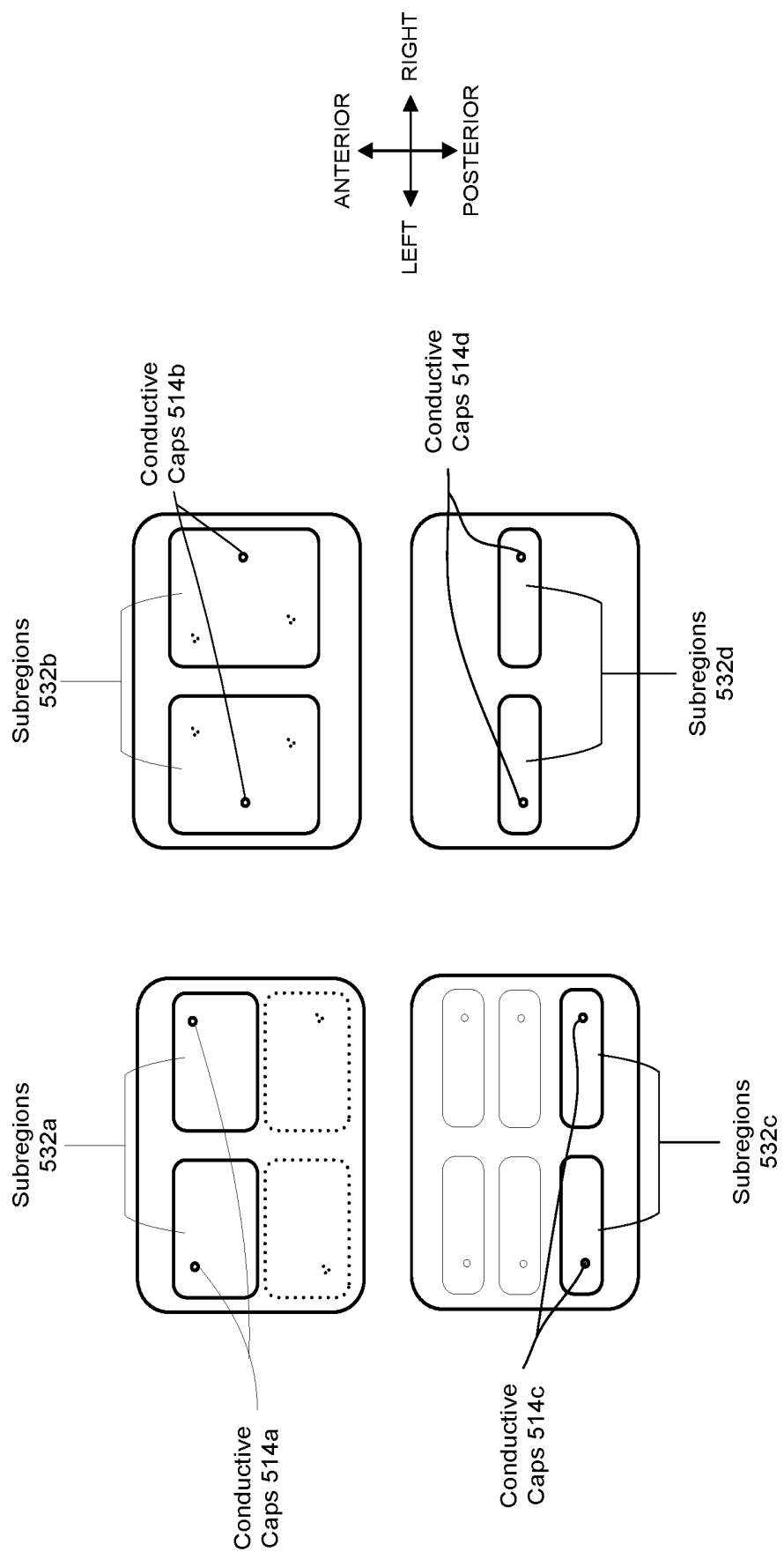


FIG. 5

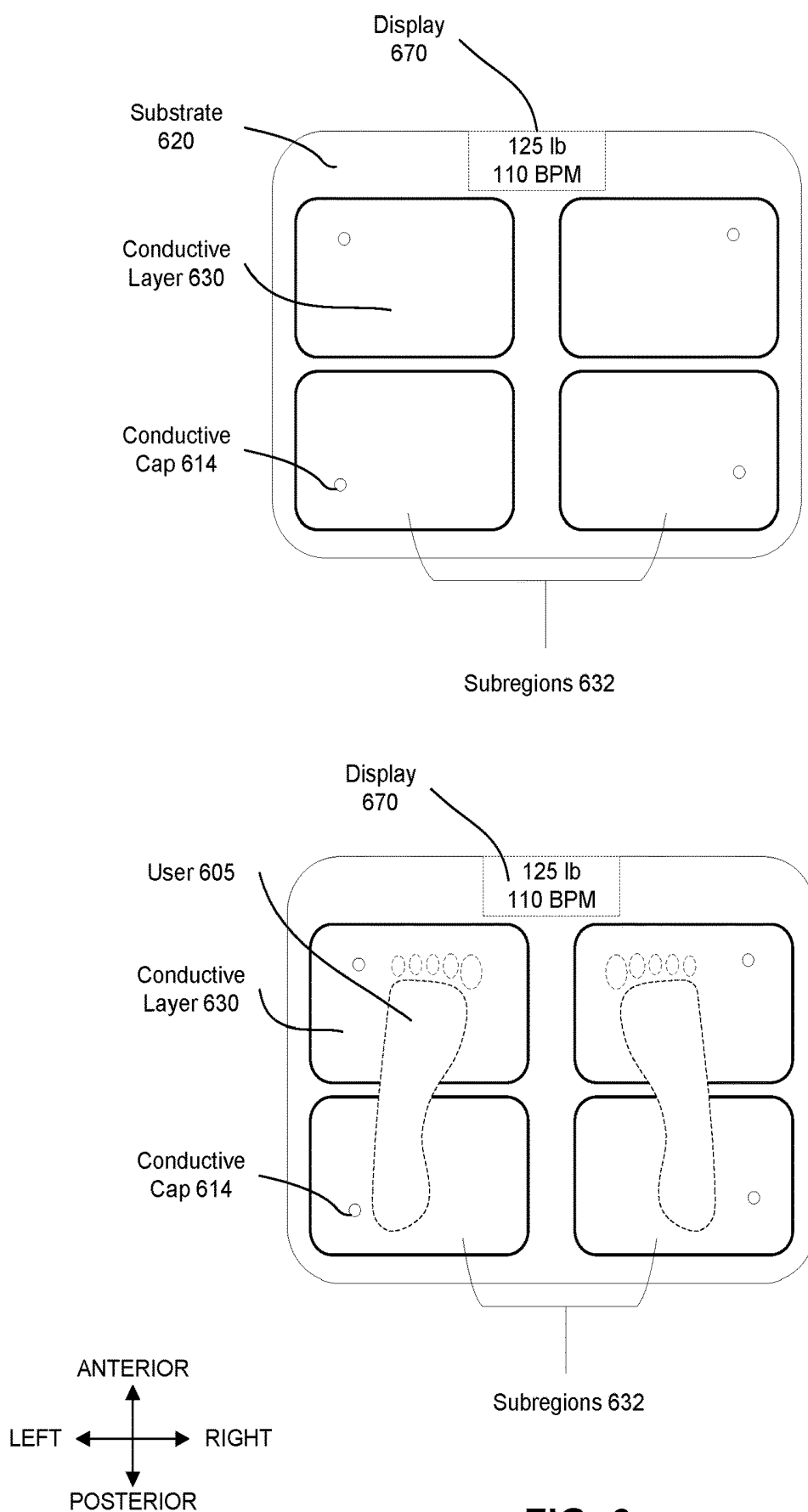


FIG. 6

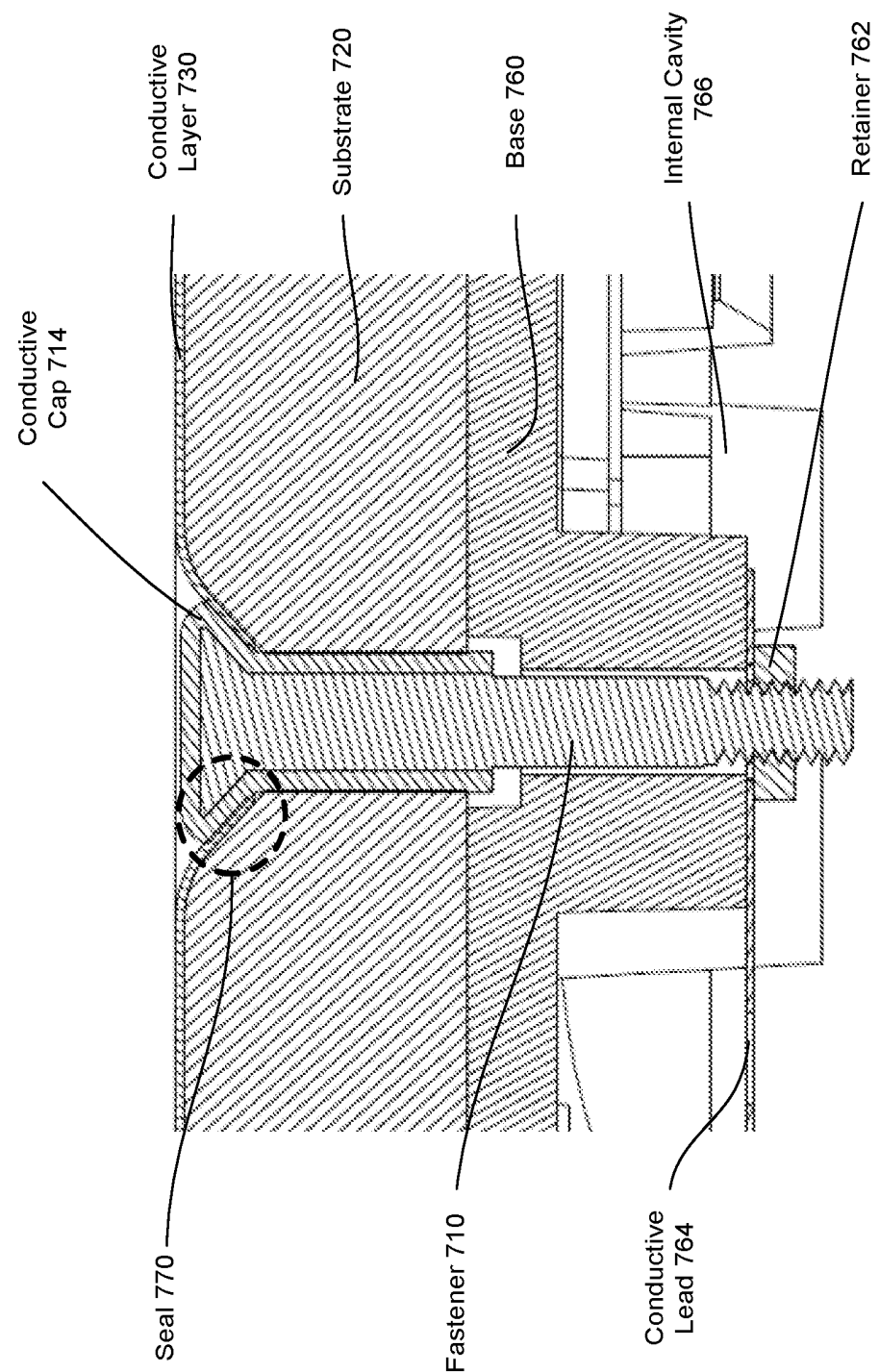


FIG. 7A

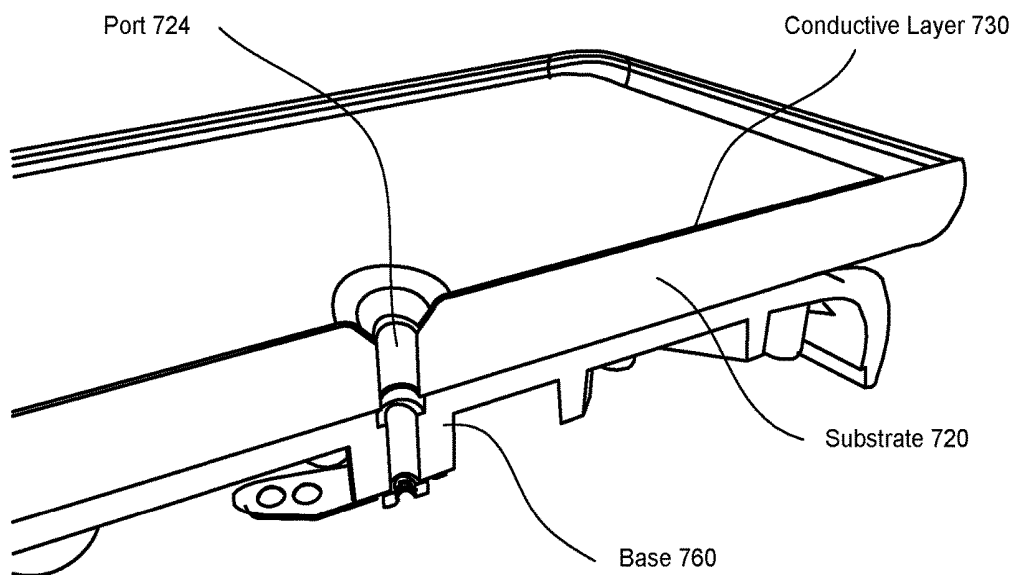


FIG. 7B

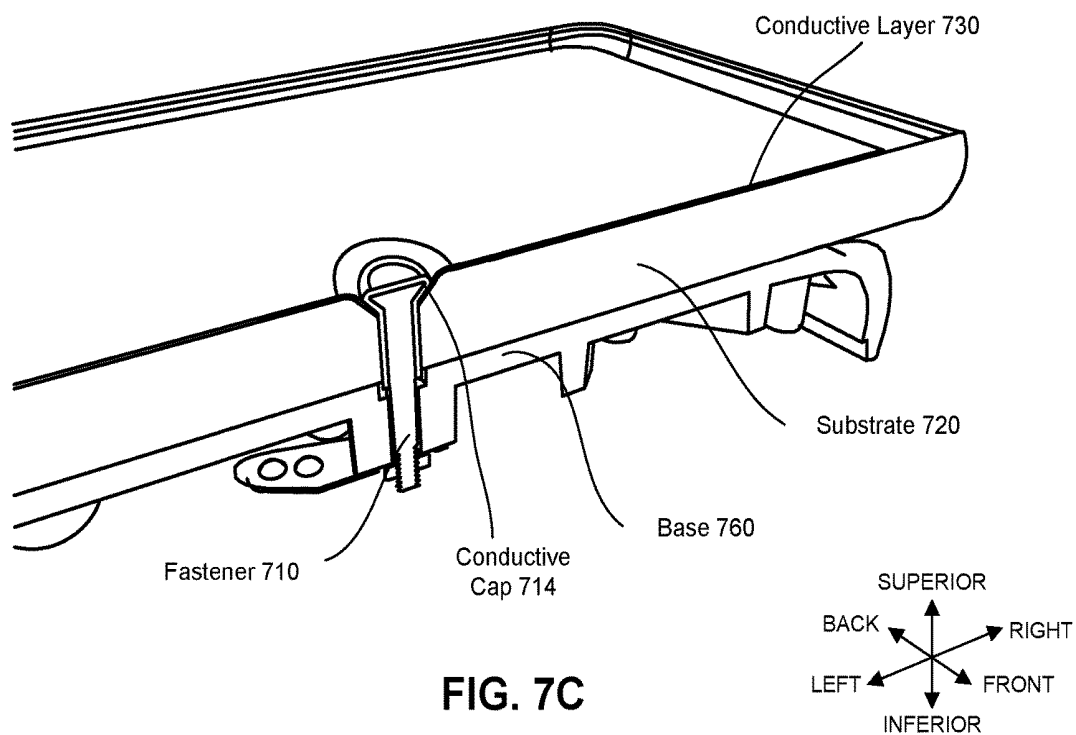


FIG. 7C

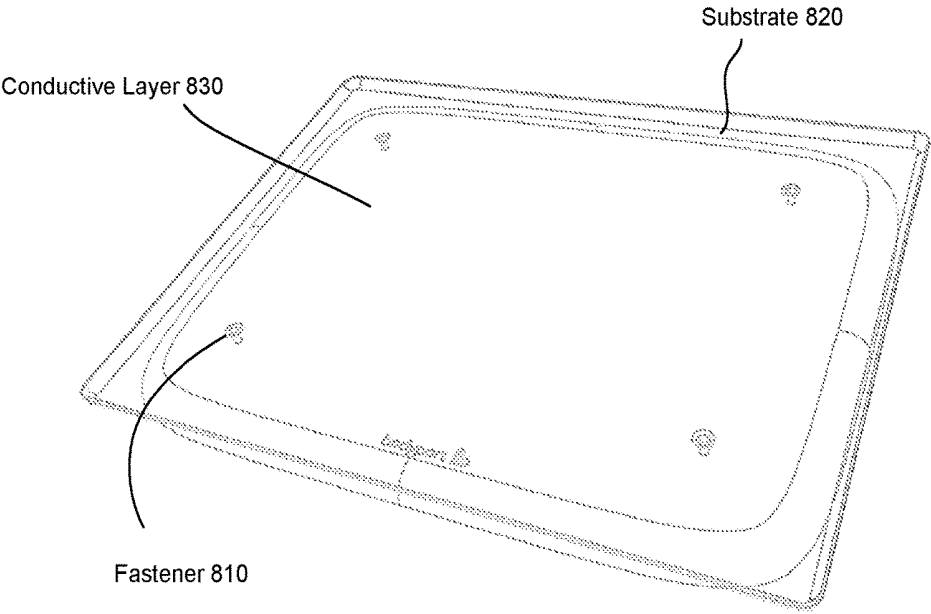


FIG. 8A

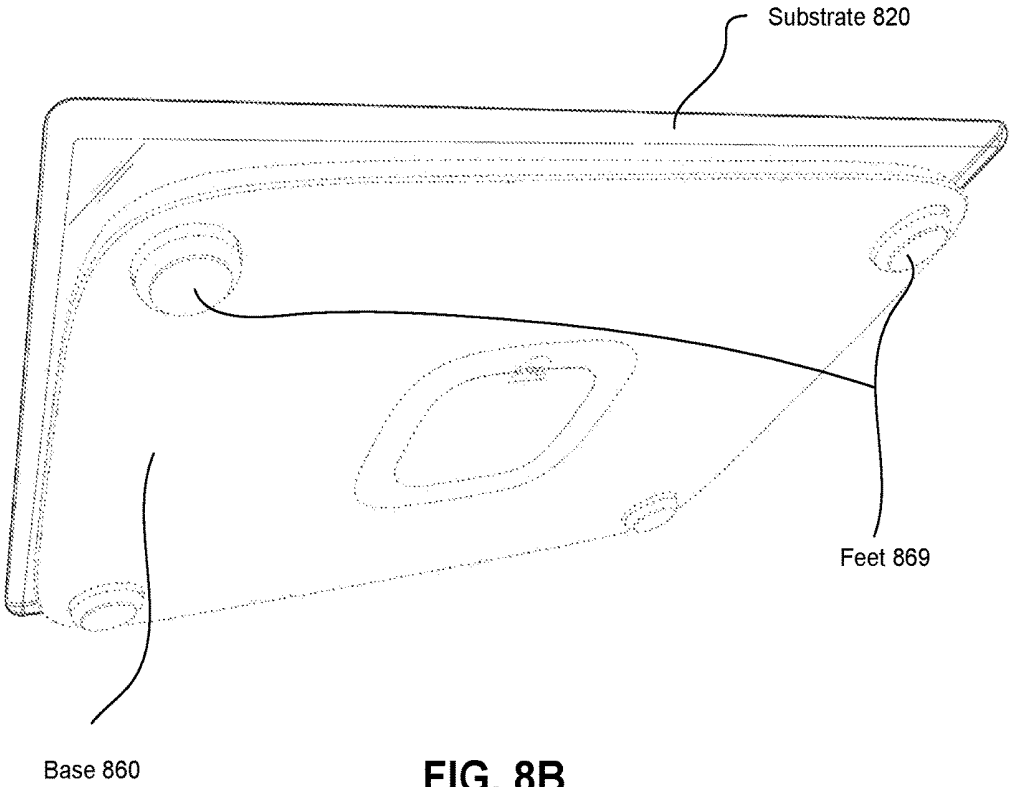


FIG. 8B

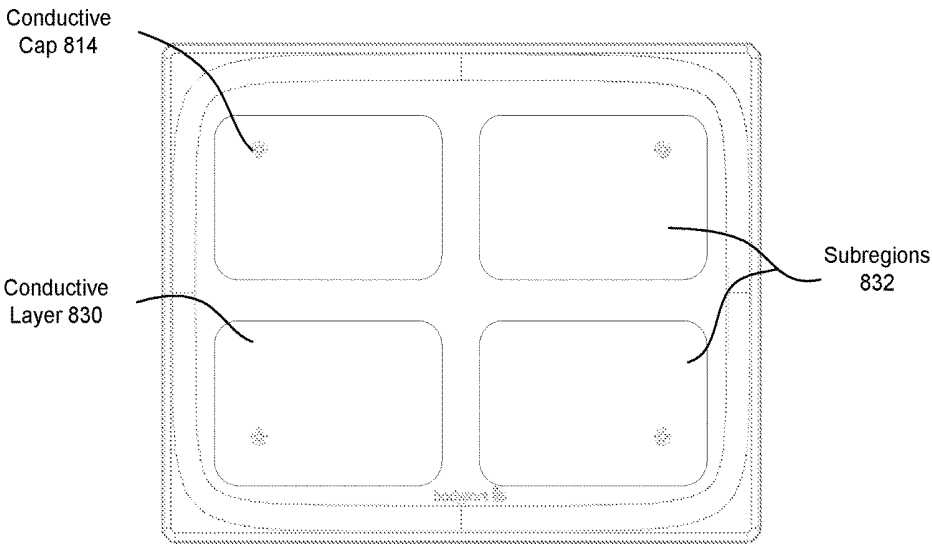


FIG. 8C

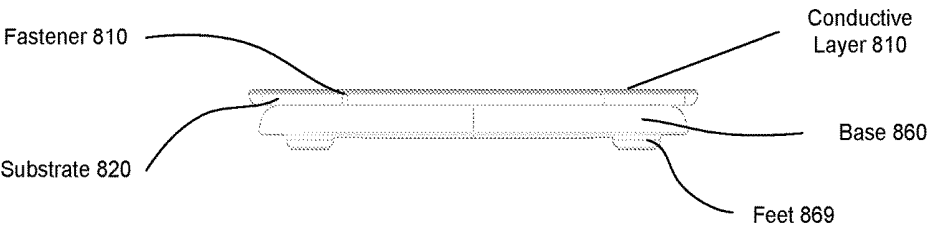


FIG. 8D

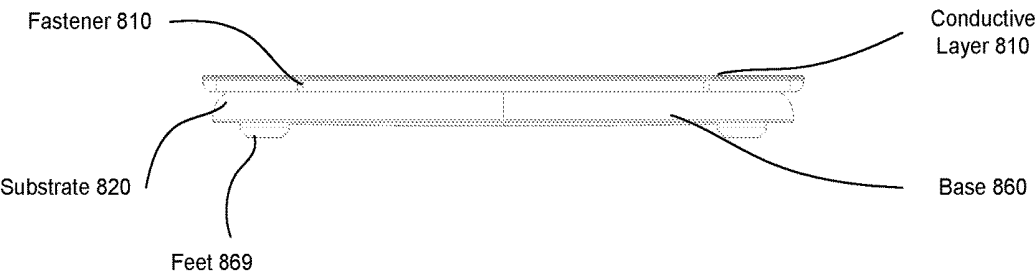


FIG. 8E

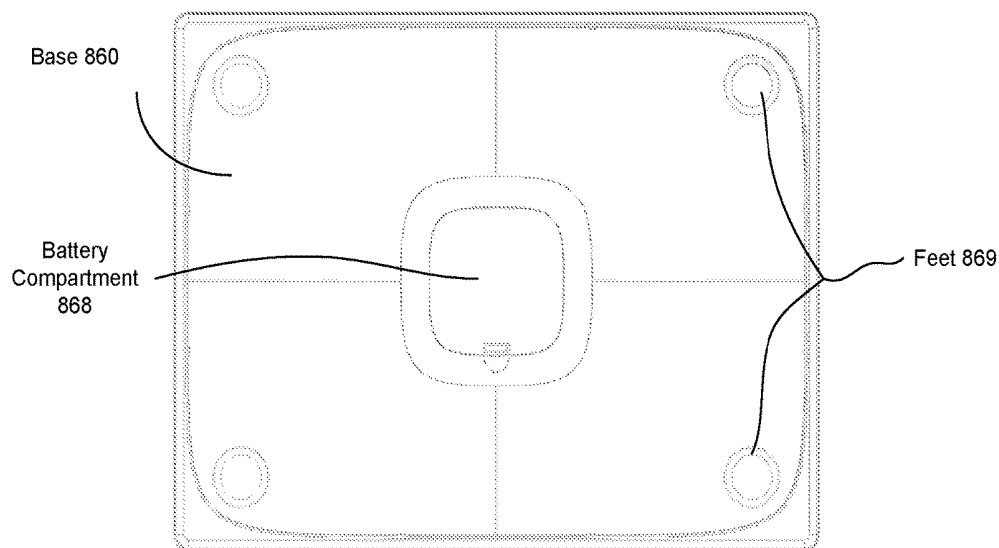


FIG. 8F

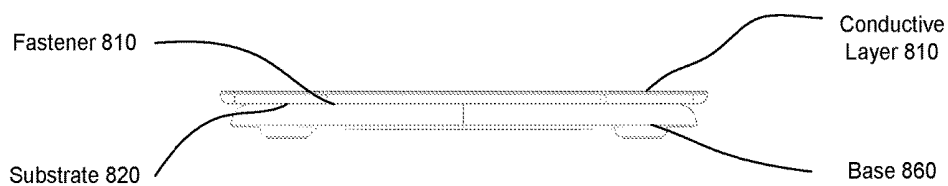


FIG. 8G

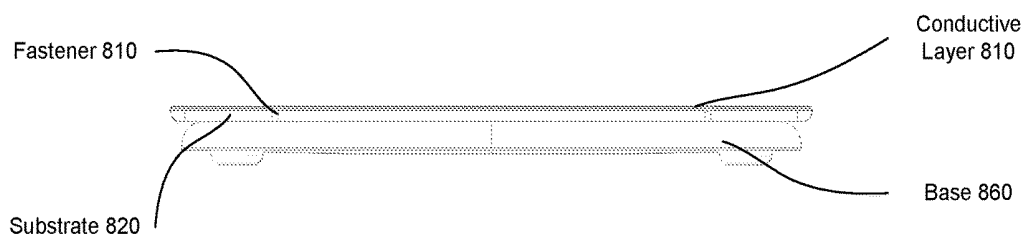


FIG. 8H

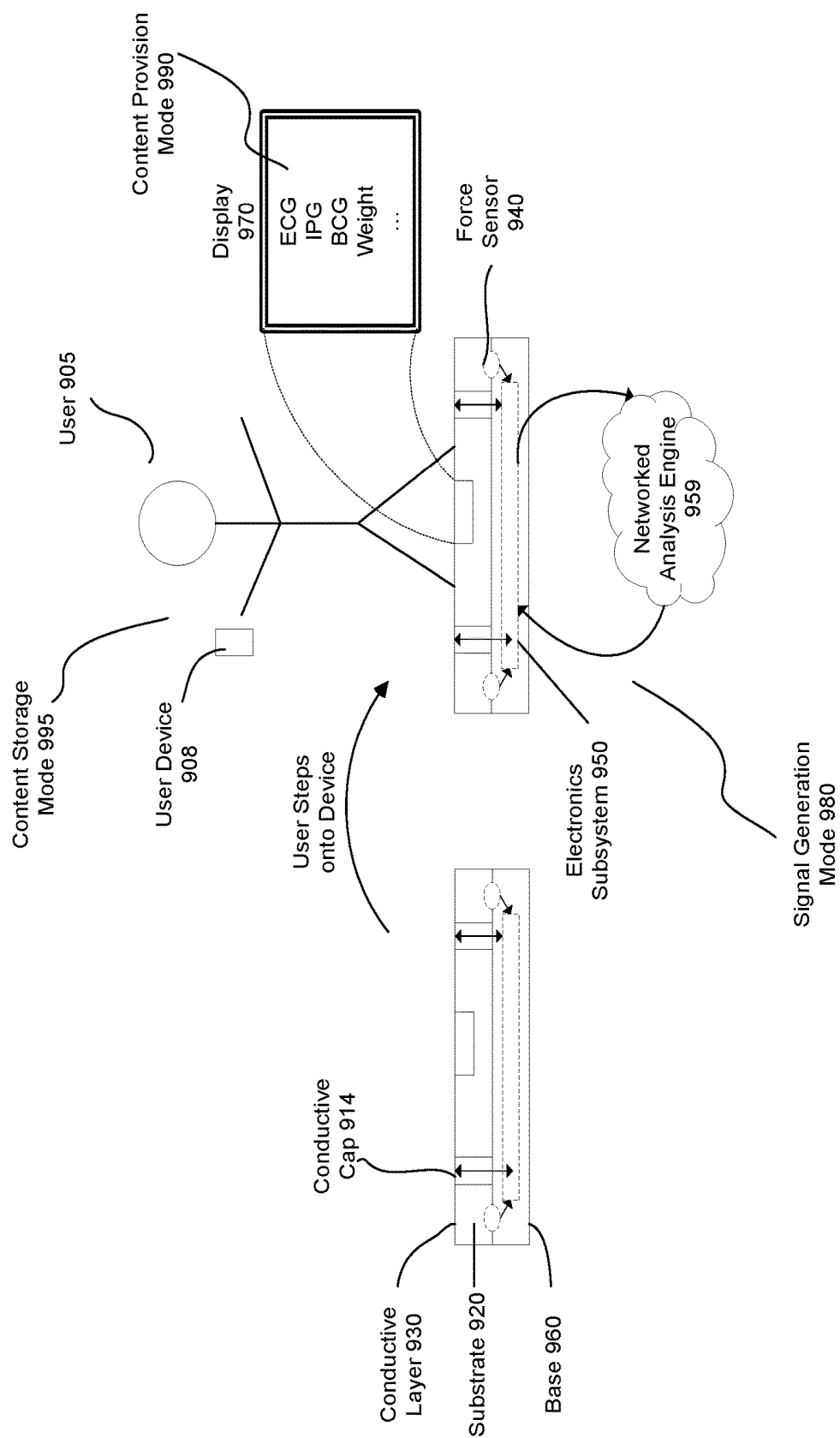


FIG. 9

CARDIOVASCULAR HEALTH MONITORING DEVICE

CROSS REFERENCE TO RELATED APPLICATIONS

[0001] This application is a continuation-in-part of co-pending U.S. application Ser. No. 15/743,154, filed on Jan. 9, 2018, which is a National State Entry of International Application No. PCT/CA2015/051120, filed on Nov. 2, 2015, which claims the benefit of priority to U.S. Provisional Application No. 62/191,318, filed on Jul. 10, 2015, all of which are incorporated by reference herein in their entirety. This application is also related to U.S. patent application Ser. No. _____ (Atty. Docket No. 35193-41270/US), filed on an even date herewith, and titled “CARDIOVASCULAR SIGNAL ACQUISITION, FUSION, AND NOISE MITIGATION,” and is also related to U.S. patent application Ser. No. _____ (Atty. Docket No. 35193-41271/US), filed on an even date herewith, and titled “CARDIOVASCULAR SIGNAL ACQUISITION, FUSION, AND NOISE MITIGATION,” the contents of both are hereby incorporated by reference.

BACKGROUND

[0002] This disclosure relates generally to user health monitoring, and more specifically to a device for acquiring and processing biometric signals.

[0003] About 1 of 3 U.S. adults (over 70 million people) have high blood pressure, but only approximately half of these individuals have their high blood pressure under control. High blood pressure is often called a “silent killer” because it typically produces no warning signs or symptoms, but is associated with increased risk factors for more serious conditions, such as heart disease and stroke. Frequent monitoring of blood pressure and other biometric parameters can enable early detection of abnormal or deteriorating health states; however, currently available home-use devices (e.g., pneumatic cuffs) are not user-friendly, are uncomfortable, are difficult to use, and are not designed to promote regular use, in relation to adherence to a health-monitoring regimen. Even further, devices for consumer use are limited in the types of signals they can acquire and effectively process to generate composite features relevant to different health states.

SUMMARY

[0004] Disclosed is a device for simultaneously acquiring electrical and/or force signals through feet of a user, where the electrical signals can include electrocardiogram (ECG) signals and/or impedance plethysmogram (IPG) signals, and the force-derived signals can include ballistocardiogram (BCG) signals and weight measurements. The device includes an electrically-conductive surface for contacting feet of the user and a substrate for supporting weight of the user during use. The device also includes one or more force sensors for detecting forces and force variations through the electrically-conductive surface, electronics for processing electrical signals generated from the electrically conductive surface and signals from the set of force sensors, and a base containing the electronics. The base is structurally coupled to the electrically-conductive surface by a set of conductive fasteners that transmit signals from the electrically-conduc-

tive surface to the electronics. The device can also include an integrated display for providing health insights to the user in different operation modes.

BRIEF DESCRIPTION OF THE DRAWINGS

[0005] FIG. 1A is a schematic of a system for health monitoring, in accordance with one or more embodiments.

[0006] FIG. 1B is a schematic of a portion of the system shown in FIG. 1A, in accordance with one or more embodiments.

[0007] FIG. 2A is a cross sectional view of a first embodiment of a fastener of a system for health monitoring.

[0008] FIG. 2B is a cross sectional view of a second embodiment of a fastener of a system for health monitoring.

[0009] FIG. 2C is a cross sectional view of a third embodiment of a fastener of a system for health monitoring.

[0010] FIG. 2D is a cross sectional view of a fourth embodiment of a fastener of a system for health monitoring.

[0011] FIG. 3 depicts a top isometric view (left), a bottom isometric view (middle), and an elevation view (right) of an embodiment of a fastener of a system for health monitoring.

[0012] FIG. 4 is a schematic of a portion of an embodiment of a system for health monitoring.

[0013] FIG. 5 depicts top views of conductive layer and conductive cap configurations of a first embodiment (top left), a second embodiment (top right), a third embodiment (bottom left), and a fourth embodiment (bottom right) of a system for health monitoring.

[0014] FIG. 6 is a top view of an embodiment of a system for health monitoring.

[0015] FIG. 7A is a schematic of a portion of an embodiment of a system for health monitoring.

[0016] FIG. 7B is a cross section isometric view of an environment of the embodiment of the system shown in FIG. 7A.

[0017] FIG. 7C is a cross section isometric view of an environment of the embodiment of the system shown in FIG. 7A.

[0018] FIG. 8A is an isometric view, from the top right, of an embodiment of a system for health monitoring.

[0019] FIG. 8B is an isometric view, from the bottom right, of the embodiment of the system shown in FIG. 8A.

[0020] FIG. 8C is a top view of the embodiment of the system shown in FIG. 8A.

[0021] FIG. 8D is a right side view of the embodiment of the system shown in FIG. 8A.

[0022] FIG. 8E is a front view of the embodiment of the system shown in FIG. 8A.

[0023] FIG. 8F is a bottom view of the embodiment of the system shown in FIG. 8A.

[0024] FIG. 8G is a left side view of the embodiment of the system shown in FIG. 8A.

[0025] FIG. 8H is a back view of the embodiment of the system shown in FIG. 8A.

[0026] FIG. 9 depicts operation modes of a system for health monitoring, in accordance with one or more embodiments.

[0027] The figures depict various embodiments for purposes of illustration only. One skilled in the art will readily recognize from the following discussion that alternative embodiments of the structures and methods illustrated herein may be employed without departing from the principles described herein.

DETAILED DESCRIPTION

1. System for Health Monitoring

[0028] FIG. 1A is a schematic of a system 100 for health monitoring, in accordance with one or more embodiments and FIG. 1B is a schematic of a portion of the system 100 shown in FIG. 1A, in accordance with one or more embodiments. The system 100 includes a first fastener 110a and a second fastener 110b, each of the first fastener 110a and the second fastener 110b comprising a body 112 and a conductive cap (described and shown in more detail below) coupled to an end region of a body 112. The system 100 further includes a substrate 120 with a first port 124a and a second port 124b each passing into a first broad surface 121 of the substrate 120. The first port 124a retains the first fastener 110a in position and the second port 124b retains the second fastener 110b in position, to facilitate coupling between elements of the system 100. The first broad surface 121 of the substrate 120 is coupled to a conductive layer 130.

[0029] The conductive layer 130 is separated into a first subregion 132a electrically coupled to a conductive portion of the first fastener 110a and a second subregion 132b electrically coupled to a conductive portion of the second fastener 110b. The first subregion 132a is electrically isolated from the second subregion 132b to prevent electrical bridging across the first subregion 132a and the second subregion 132b. The system 100 can also include a base 160 that functions to house or otherwise support one or more elements of the system 100, as described in more detail below. The base 160 is supported by the feet 169, and the feet 169 function as the points of contact between the base 160 and the ground.

[0030] The system 100 can also include a set of force sensors 140 in communication with the substrate 120 and an electronics subsystem 150, where the set of force sensors 140 function to generate and transmit force-derived signals that can be processed simultaneously with the electrical signals to derive comprehensive insights into a user's health and/or for noise mitigation purposes. The set of force sensors 140 can thus measure static and dynamic loads transferred to the substrate 110 when a user interacts with the system 100. The set of force sensors 140 form the main point of contact between the substrate 110 or the base 160, and feet 169. In one embodiment, the system 100 includes four force sensors positioned proximal the corners of the substrate 100 each sensor configured to a foot 169; however, in alternative embodiments, the system 100 can include other suitable numbers of force sensors positioned relative to the substrate 110 in another manner. In the embodiment of FIG. 1A, the set of force sensors 140 are load cells configured to generate an electrical signal that is proportional to a force being measured.

[0031] The electronics subsystem 150 shown in FIG. 1B includes an electrical signal channel 152 electrically coupled to the first fastener 110a and the second fastener 110b and a force signal channel 153 electrically coupled to the set of force sensors 140, and can include additional electrical signal channels and/or force signal channels (not shown in the cross-section view). The electrical signal channel 152 may transmit various bio-electrical signals such as electrocardiogram (ECG) and impedance plethysmogram (IPG), and the force signal channel 153 may transmit signals such as ballistocardiogram (BCG) signals and weight signals. The electronics subsystem 150 can also include current output

circuitry that injects a current (e.g., a current less than 1 mA, a current less than 5 mA, etc.) at a frequency (e.g., 2-100 kHz) in order to detect active electrical signals, such as IPG signals, from the user as the user interacts with the system 100. The electronics subsystem 150 can include a power management subsystem 156 that provides power to one or more components of the system 100, a data transmission link 158 for transmission of data to remote computing systems (e.g., such as a remote computing system hosting the network analysis engine 159 described below), and a processor 155 for providing control instructions to controllable elements of the system and/or coordinating operation states of the system 100. A networked analysis engine 159 can be in communication with the data transmission link 158 of the electronics subsystem 150. As such, the networked analysis engine 159 can be hosted remotely and can operate to process electrical data inputs and force-derived data inputs. The networked analysis engine 159 can also transmit outputs to other systems to promote health of a user interacting with the system 100.

[0032] The system 100 functions to provide a device that is user-friendly, comfortable, and configured to promote regular (e.g., daily, weekly, etc.) use by a user. The system can provide multiple types of signals that are relevant to different health states (e.g., different cardiovascular health states, other health states). The system can also provide an in-home solution that promotes regular use in order to encourage early detection of health issues, in particular cardiovascular health issues. In one or more embodiments, the system 100 can include a device having a form factor and functionality of a weighing scale, such that the device, while a user undergoes a routine weighing process, automatically generates electrical signal data and force signal data that can be co-processed for monitoring user health. As such, the device can be configured to unobtrusively and non-invasively collect and fuse multiple signal types, without overburdening the user.

1.1 System—Fasteners

[0033] In relation to FIG. 1A, the first fastener 110a and the second fastener 110b function to simultaneously provide structural support to and to couple elements of the system together (e.g., the substrate 120 to the base 160). The first fastener 110a and/or the second fastener 110b can additionally include electrically conductive regions that facilitate transmission of electrical signals generated in response to interactions with the feet of the user to the electronics subsystem 150. One or more portions of the first fastener 110a and/or the second fastener 110b can also function to seal respective openings in surfaces (e.g., a surface of the substrate 120, a surface of the base 160 of elements of the system 100, etc.) to protect sensitive components (e.g., components of the electronics subsystem 150) from fluid ingress during use of the system 100 by a user, or while stationed in an ambient environment.

[0034] The fasteners (e.g., fastener 110a, fastener 110b) can include one or more of: a screw, a pin, a nail, a bolt, or another fastener having another form factor. A portion (e.g., a first end region, a second end region) of a fastener can be threaded in order to cooperate with other retaining elements for coupling portions of the system 100 together. For instance, as shown in FIG. 1A, the first fastener 110a can pass into a first port 124a of the substrate 120 and the second fastener 110b can pass into a second port 124b of the

substrate **120** to physically couple the substrate **120** to the base **160** and/or provide electrical coupling with the conductive layer **130**.

[0035] As shown in FIG. 1A, the first fastener **110a** and the second fastener **110b** do not protrude from a surface of the conductive layer **130** configured to interface with the user, in relation to user comfort considerations. As such, a surface (e.g., head region) of a fastener can be flush with a surface of conductive layer **130**, in order to enable mating of two surfaces (e.g., co-planar surfaces, concentrically-oriented surfaces, other surfaces of the fastener(s) and of the conductive layer). This configuration enhances the reliability of the interconnection between the fastener(s) and the conductive layer, in comparison to point coupling with a conductive element. The interaction between the fastener (e.g., first fastener **110a**, second fastener **110b**) and its surrounding components (e.g., the conductive layer **130**) is described in greater detail below in relation to FIG. 7A. Alternatively, one or more portions of a head region of a fastener can be recessed within the conductive layer **130** and/or the substrate **120**. In alternative embodiments, however, one or more regions of a fastener can protrude from a surface of the substrate **120** and/or conductive layer **130**.

[0036] In relation to mechanical properties, the material(s) of the fastener **110a** and/or the fastener **110b** can have a compressive strength, a shear strength, a tensile strength, a strength in bending, an elastic modulus, a hardness, a derivative of the above mechanical properties and/or other properties that enable structural support of the user and/or other system elements in various operation modes associated with use of the system **100**.

[0037] As described above, the first fastener **110a** and/or the second fastener **110b** can function to transmit electrical signals detected from the body of the user **105** (e.g., through the feet of the user **105**), where the electrical signals can be associated with electrocardiogram (ECG) signals and/or impedance plethysmography (IPG) signals. Additionally or alternatively, the electrical signals can include one or more of: electromyography signals, body impedance/body composition, galvanic skin response or skin conductance signals, or other bioelectrical signals. As such, in relation to electrical properties, the material(s) of the first fastener **110a** and the second fastener **110b** can have a conductivity, resistivity, a derivative of the above electrical properties and/or other properties that enable electrical signal transmission from the conductive layer **130** to the electronics subsystem **150**. The material(s) of a first fastener **110a** and a second fastener **110b** can alternatively be selected to have desired electrical properties.

[0038] The fasteners (e.g., first fastener **110a**, second fastener **110b**) can thus be composed of a conductive material such as a metal, a conductive polymer, or another conductive material, in order to facilitate signal transmission. As described below, one or more embodiments of the fasteners (e.g., first fastener **110a**, second fastener **110b**) can be configured as a composite of multiple materials corresponding to different regions of a respective fastener, where the different regions and materials provide different functionalities. In relation to measurement of electrical signals, the conductive material(s) of the fasteners (e.g., first fastener **110a**, second fastener **110b**) can have a maximum resistivity of 5 Ohms. Alternatively, the material of the fasteners can have any suitable resistivity.

[0039] Several embodiments of a fastener (e.g., fastener **210a**, **210b**, **210c**, **210d**) are illustrated by the cross sectional views of FIG. 2A-2D. As shown in FIGS. 2A-2D, embodiments of a fastener can include a body (e.g., body **212a**, **212b**, **212c**, **212d**) and a conductive cap (e.g., conductive cap **214a**, **214b**, **214c**, **214d**). The body can be composed of a conductive material such as stainless steel, copper, and/or aluminum. The conductive cap can be composed of a conductive polymer such as a rubber (e.g. carbon doped silicone) or a conductive plastic. Alternatively, the conductive cap can be composed of another material such as a soft metal. In particular, the conductive cap is made of a material that is softer than material of the substrate in order to provide electrical coupling to the conductive layer (e.g., through multiple points or a region of contact) and compliance to protect the substrate from the fastener (e.g., to provide shock absorption). As described in more detail below, the conductive cap can be configured in a manner that can expose one or more portions of the fastener. For instance, the conductive cap can expose a top portion of a core material of the fastener, can ensheath a bottom of a head region of the fastener, or surround a bottom region and/or body of the fastener. Alternatively, the different regions of the fasteners (e.g., **210a**, **210b**, **210c**, **210d**) can be composed of any suitable material.

[0040] The longitudinal cross section of the body (**212a**, **212b**, **212c**, and **212d**) of a fastener shown in FIGS. 2A-2D is circular. However, in alternative embodiments, the longitudinal cross section of the body can be ellipsoidal, polygonal, or any other suitable shape. The conductive cap (e.g., conductive cap **214a**, **214b**, **214c**, **214d**) can be flat or convex or concave along an axial direction of a fastener. Furthermore, the cross section of the body (e.g., body **212a**, **212b**, **212c**, and **212d**) and the conductive cap (e.g., conductive cap **214a**, **214b**, **214c**, **214d**) can be constant or variable along the length of the body.

[0041] As shown in FIG. 2A, a first embodiment of a fastener **210a** includes a body **212a** and a conductive cap **214a**. FIG. 2A is a first embodiment where the conductive cap **214a** is coupled to an end region of the body **212a** (e.g., an end region configured to interface with a conductive layer) of the fastener **210a**. In the first embodiment, the width of the conductive cap **214a** is greater than the width of the body **212a**.

[0042] FIG. 2B is a second embodiment of a fastener **210b** including a conductive cap **214b** ensheathing a body **212b** of a fastener **210b**. In the second embodiment, the conductive cap **214b** is coupled to an end region and extends at least partially down the longitudinal side of the body **212b** of the fastener **210b**. The width of the conductive cap **214b** is greater than the width of the body **212b**.

[0043] FIG. 2C is a third embodiment of a fastener **210c** with a conductive cap **214c** and a body **212c**. The conductive cap **214c** is coupled to the sides of the body **212c** of the fastener **210c**, under a head region of the fastener **210c**. In the embodiment of FIG. 2C, the conductive cap **214c** does not interface with the superior surface of the body **212c**, such that the superior surface of the body **212c** is uncovered by the conductive cap **214c** and exposed. The conductive cap **214c** functions as a conical sheathing to couple the body **212c** to surrounding components, as described below in relation to FIG. 7A.

[0044] FIG. 2D is a fourth embodiment of a fastener **210d** including a conductive cap **214d** and a body **212d**. The

conductive cap **214d** is coupled to the sides of the body **212d** of the fastener **210d**, under a head region of fastener **210d**. The body **212d** is T-shaped (in a longitudinal cross section) and the conductive cap **214d** is configured as a sheath below the flange of the body **212d** to couple the body **212c** to the surrounding components, as described below in relation to FIG. 7A. Additionally, the superior surface of the body **212d** is uncovered by the conductive cap **214d** and exposed.

[0045] FIGS. 2C and 2D thus depict fastener configurations that have mating contacting faces over a wide surface area, where coupling of an interface (e.g., self-centering counter-sunk interface of the substrate) with a compliant interface material between the conductive layer coupled to the substrate (described in more detail below) and a respective fastener body provide desired mechanical and electrical contact characteristics.

[0046] As described above in relation to FIGS. 1A-1B and 2A-2D, a fastener can have characteristics (e.g., morphological characteristics, region-specific characteristics, electrical properties, mechanical properties, etc.) that vary depending upon the embodiment and requirements of the system **100**. One such embodiment is shown in FIG. 3, where FIG. 3 includes a top isometric view (left), a bottom isometric view (middle), and an elevation view (right) of an embodiment of a fastener **310** of a system **100** for health monitoring. The fastener **310** shown in FIG. 3 includes a body **312** composed of stainless steel and a conductive cap **314** composed of carbon-doped rubber; however, the fastener **310** and conductive cap **314** can alternatively be composed of other suitable materials, as described above. The fastener **310** shown in FIG. 3 has a length of 20.8 millimeters and 6 millimeters of M2.5 thread on the second end region **317** of the fastener **310**. The second end region **317** has a diameter of 2.3 millimeters and the first end region **315** has a diameter of 2.5 millimeters. In alternative embodiments, however, the fastener can have a length of 5-80 millimeters and a first end region **315** and/or a second end region **317** diameter of 0.5-15 millimeters. The fastener **310** includes a conductive cap **314** with a thickness of 0.55 millimeters ensheathing the first end region **315** of the fastener **310**. In alternative embodiments, however, the conductive cap **314** can have a thickness of 0.1-10 millimeters. The fastener **110** including the conductive cap **314** can alternatively have any other suitable dimensions.

[0047] The fastener **310** described by FIG. 3 can have characteristics that vary depending upon the embodiment and the requirements of the system **100**. For example, the fastener can have a conductive cap ensheathing both the first end region **315** and the second end region **317** functioning to seal at least a portion of the system, as described above. Furthermore, the fastener **310** can omit some elements shown by FIG. 3. For example, the fastener **310** can have a conductive body **312** without a conductive cap **314** to simplify the system **100** for various purposes (e.g., simplify the manufacturing process, promote easy repair, etc.).

1.2 System—Substrate

[0048] As shown in FIGS. 1A and 1B, the system includes a substrate **120** that functions as a surface on which to bond the conductive layer **130**. The substrate **120** facilitates electrical signal transmission from the conductive layer **130** (described below), through the fasteners, and toward the electronics subsystem **150**. The substrate **120** can also function to mechanically support the weight of a user **105** in

relation to weight measurements and other force-associated signal generation functionality. The substrate **120** can additionally function to enable display (e.g., with integrated display elements, with transparent materials, with translucent materials, etc.) of information to the user **105** described in later sections. The information can include information derived from analyses of signals generated by the system, instructions to the user, user verification information, or other types of information.

[0049] In morphology, the substrate **120** includes a first broad surface **121** to which the conductive layer **130** is coupled. The substrate **120** can also include a second broad surface to which one or more other elements of the system **100** are coupled, such as the base **160** described in more detail below. The first broad surface **121** of the substrate **120** is planar, but can alternatively include recessed and/or protruding regions defined at the broad surface. Recessed and/or protruding regions of the first broad surface **121** can be configured to guide placement of the feet of the user and can include features that are complimentary to the soles of the user's feet.

[0050] In relation to material composition, the substrate **120** can be composed of a single material or a composite material to provide suitable physical properties for support of the system **100** and the user **105**. For example, the substrate **120** can be composed of glass (e.g., tempered glass, frosted glass, float glass, chemically strengthened glass). Alternatively, the substrate can be composed of a metal, ceramic, natural stone, polymer, composite, or any combination of materials.

[0051] In relation to mechanical properties, the material(s) of the substrate **120** can have a compressive strength, a shear strength, a tensile strength, a strength in bending, an elastic modulus, a hardness, a derivative of the above mechanical properties and/or other properties that provide adequate structural support in unloaded states and/or loaded states (e.g., with the user **105** standing on the substrate) in relation to various operation modes associated with use of the system **100**.

[0052] In relation to electrical properties, the material(s) of the substrate **120** can have a conductivity, resistivity, a derivative of the above electrical properties and/or other properties that support electrical signal transmission from the user's body to the electronics subsystem **150**. The substrate **120** can be composed of an insulative material to function to prevent bridging between selectively conductive regions (e.g., of the conductive layer **130** described in more detail below), and/or to prevent excess noise propagating through the system from the conductive layer **130**. The bulk material(s) of the substrate **120** can alternatively be selected to have desired electrical properties.

[0053] In relation to optical properties, the material(s) of the substrate **120** can have a transparency or translucency suitable of conveying information to the user by way of an electronic display coupled to, positioned next to, or otherwise optically integrated with the substrate **120** in another manner. In other embodiments, the substrate **120** can be an opaque material. The material(s) of the substrate **120** can also be fabricated to or otherwise include optical elements (e.g., lenses, mirrors, filters, waveguides, etc.) manipulate (e.g., reflect, scatter, guide, shape, etc.) light.

[0054] Shown in FIG. 4, a schematic of a portion of an embodiment of a system **100** for health monitoring includes a substrate **420** coupled to a base **460** at one or more

positions of its broad surfaces. In one embodiment, the substrate **420** is coupled to a conductive layer **430** and a base **460** by one or more fasteners, including fastener **410** shown in the partial cross section view of FIG. **4**. The fastener **410** shown in FIG. **4** is electrically coupled to the conductive layer **430** by a conductive cap **414**. A second end region of the fastener **410**, away from the conductive cap **414**, is electrically coupled to a conductive lead **464** and is retained in position by a retainer **462** where, in variations, the retainer **462** can secure the fastener to a base, thereby coupling the substrate **420** to a base. The conductive lead **464** is electrically coupled to an electronics subsystem **450** which is housed in an internal cavity **466** of the device. According to the embodiment of FIG. **4**, the substrate **420** functions to serve as a foundation or support for other system **100** components.

1.3 System—Conductive Layer

[0055] As shown in FIG. **1A**, a conductive layer **130** is coupled to the substrate **120** and includes a set of subregions in electrical communication with the first fastener **110a** and the second fastener **110b**. The conductive layer **130** provides an interface to the feet of the user **105** for electrical signal acquisition. The conductive layer **130** has at least one broad surface that is planar (e.g., as a thin film coupled to or patterned onto the substrate **120**). Alternatively, the conductive layer can include recessed and/or protruding regions defined at the broad surface. Recessed and/or protruding regions of the broad surface can be configured to guide placement of the feet of the user and can include features that are complimentary to the soles of the user's feet. The conductive layer can thus vary in shape and size. According to the embodiment shown by FIG. **1A**, the conductive layer **130** includes at least two electrically isolated subregions **132a** and **132b**, containing a first port **124a** and a second port **124b**, respectively, to enable distinct signal routing from individual feet of the user, through respective subregions, and through respective fasteners, as described above. Various configurations of the conductive layer **130** are demonstrated by FIG. **5** described in greater detail below.

[0056] In material composition, the conductive layer **130** is composed of a conductive material that is safe for user interaction. The conductive layer **130** can be composed of waterproof or water resistant material (e.g., such that the user **105** can interact with the system directly after showering and/or the system can operate correctly within an environment with moisture). The conductive layer **130** can be composed of a material that is resistant to rust and not easily corrodible as the system may be stored in a bathroom where it is exposed to steam from a shower or bath. The conductive layer **130** can thus be composed of a single material or can be a composite material that provides suitable physical properties.

[0057] In relation to mechanical properties, the material(s) of the conductive layer **130** can have a compressive strength, a shear strength, a tensile strength, a strength in bending, an elastic modulus, a hardness, a derivative of the above mechanical properties and/or other properties that enable structural support of the user and/or other system elements in various operation modes associated with use of the system **100**. The material of the conductive layer **130** can have a hardness above a certain threshold such that minor scratches do not affect the aesthetic integrity or functionality of the system **100**.

[0058] In relation to electrical properties, the material(s) of the conductive layer **130** can have a conductivity, resistivity, a derivative of the above electrical properties and/or other properties that enable electrical signal transmission from the user **105** to the electronics subsystem **150**. The conductive layer **130** can be composed of a material (e.g., indium tin oxide, graphene, carbon nanotubes) with a desired pattern in relation to signal transduction through the system and/or the body of the user **105**. The bulk material(s) of the conductive layer **130** can alternatively be selected to have desired electrical properties.

[0059] In relation to optical properties, the material(s) of the conductive layer **130** can have a transparency or translucency suitable of conveying information to the user by way of an electronic display coupled to, positioned next to, or otherwise optically integrated with the conductive layer **130** in another manner. The material(s) of the conductive layer **130** can also be fabricated to include optical elements (e.g., lenses, mirrors, filters, waveguides, etc.) to manipulate (e.g., reflect, scatter, guide, shape, etc.) light.

[0060] The subregions **132a** and **132b** of the conductive layer **130** can be defined at the substrate in several configurations, some variations of which are shown in FIG. **5**. For instance, as shown in a first embodiment of FIG. **5** (top left), the conductive layer can be divided into a left subregion **532a** associated with a left conductive cap of a set of conductive caps **514a** and a right subregion **532a** associated with a right conductive cap of a set of conductive caps **514a**, where the left subregion is electrically separated from the right subregion (e.g., by a region that is not conductive or otherwise insulating). The first embodiment (top left) includes two optional subregions, a left posterior subregion and a right posterior subregion. The optional subregions can operate in conjunction with or in replacement of the left anterior subregion and/or the right anterior subregion. For example, electrical signals can be collected from the left posterior subregion and the right anterior subregion simultaneously. Alternatively, electrical signals can be collected from pairs of left and right subregions **532a** such as the left and right anterior subregions or the left and right posterior subregions simultaneously.

[0061] A second embodiment (top right) of FIG. **5** illustrates a conductive layer with a left subregion associated with a left conductive cap of a set of conductive caps **514b** and a right subregion associated with a right conductive cap of a set of conductive caps **514b**, where the left subregion is electrically separated from the right subregion (e.g., by a region that is not conductive). The subregions **532b** span the entire width of the system. Furthermore, each subregion **532b** can include more than one conductive cap in each region. The optional conductive caps of the left and right subregions **532b** can be located in any position within the subregions **532b** and can operate in addition to or instead of the conductive caps **514b** (e.g., if one cap fails or is otherwise compromised).

[0062] A third embodiment (bottom left) of FIG. **5** illustrates a conductive layer with three left subregions **532c** each associated with a conductive cap of a set of conductive caps **514c** and three right subregions **532c** each associated with a conductive cap of a set of conductive caps **514c**, where all of the subregions are electrically isolated (e.g., by a region that is not conductive). The subregions **532c** can be used simultaneously for generating electrical signals from each pair of left and right foot portions or for targeting signal

generation of specific portions (e.g., anterior, middle, and posterior portions) of each foot.

[0063] A fourth embodiment (bottom right) of FIG. 5 illustrates a conductive layer with a left subregion **532d** associated with a left conductive cap of a set of conductive caps **514d** and a right subregion **532d** each with a conductive cap of a set of conductive caps **514d**. The subregions **532d** only span a portion of the width of the system and can be used for extracting electrical signals from a specific targeted region of the user feet (e.g., central region).

[0064] FIG. 5 illustrates four embodiments of the system, but is not exclusive or representative of every embodiment of the system. For example, the system can include a larger number of subregions than the amount shown by FIG. 5 for generating signals from multiple regions of each foot. The subregions can also be oriented differently, such as rotating the subregions 90 degrees or adjusting the shape and size of the subregions to satisfy design criteria (e.g., ease of manufacturing, ease of use, etc.).

[0065] FIG. 6 is a schematic of a top view of a specific embodiment of a system for health monitoring. The embodiment in FIG. 6 illustrates a conductive layer **630** with four electrically isolated subregions **632** each with one conductive cap **614**. Each subregion **632** of the conductive layer **630** has a rectangular footprint when the broad surface is projected onto a horizontal plane, where the rectangular footprint has rounded edges. The subregions **632** of the conductive layer **630** can alternatively have any other suitable footprint. For example, the subregions **632** can be one or more of: a circle, a square, or a triangle when the broad surface is projected onto a horizontal plane. In dimensions, the conductive layer **630** can have a width from 1-50 centimeters, a length from 1-50 centimeters, and a thickness from 10 nanometers to 2 centimeters; however, the conductive layer **630** can alternatively have any other suitable dimensions.

[0066] The embodiment in FIG. 6 includes a display **670** embedded in the substrate **620**. The display **670** can also be embedded within the base, as described in more detail below. Alternatively, the display **670** can be contained within, coupled to, or protrude from a different or additional component of the system. For instance, a portion of the display **670** can be coupled to the substrate **620** and/or a portion can be coupled to the conductive layer **630**. The display **670** can also protrude from the surface of the conductive layer **630** and/or the substrate **620**.

[0067] The user **605** can interact with different subregions of the conductive layer **630** by standing on the device and having a left foot contact one or more subregions and having a right foot contact one or more subregions. As such, the user **605** can place a portion of his/her foot each subregion **632**. In the embodiment of FIG. 6, the user **605** can place the anterior portion of his/her left foot in the top left subregion **632** and the anterior portion of his/her right foot in the top right subregion **632**. The user **605** can place the posterior portion (e.g., heel portion) of his/her left foot in the bottom left subregion **632** and the posterior portion (e.g., heel portion) of his/her right foot in the bottom right subregion **632**. Alternatively, the user **605** can place his/her feet in a different direction (e.g., 90 degrees from the orientation described above, 180 degrees from the orientation described above, at another rotational angle from the orientation described above), and the system can be configured to correctly extract electrical and/or force signals (with elec-

trical subsystem re-mapping in firmware or through another means). As such, in more detail, each subregion **632** can generate an electrical signal from the corresponding portion of the user foot. The system can be configured to detect placement of a left foot at a respective subregion **632** (e.g., based upon pressure distributions detected by the force sensors, based upon contact through capacitive sensing, based upon light transmission patterns through the substrate, etc.) and a right foot at a respective subregion **632** and to properly generate or determine an electrical signal based upon the placements of the left and the right foot. The device can measure biological signals from the user **605** as described.

1.4 System—Electronics

[0068] As shown in FIGS. 1A and 1B, the electronics subsystem **150** includes at least one electrical signal channel **152** and at least one force signal channel **153**. The force signal channel **153** receives a signal from a set of force sensors **140** in order to transmit information about a user **105**, in response to forces generated within or by the user's body when the user interfaces with the system **100**. The force signal channel **153** can relay metrics such as body weight, ballistocardiograph (BCG) waveforms, and balance analysis. The electrical signal channel receives an electrical signal transmitted from the user **105** by a fastener **110**. The electrical signal channel **152** can transmit both cardiac and non-cardiovascular metrics including pulse rate, heart rate variability (HRV), body impedance, and cardiac waveforms such as impedance plethysmograph (IPG) waveforms and electrocardiograph (ECG) waveforms. The cardiac waveforms can be analyzed by the networked analysis engine **159** or another system not shown (e.g., firmware) to evaluate cardiovascular health parameters. In specific examples, cardiovascular health parameters can include systolic time intervals such as pre-ejection period (PEP), left ventricular ejection time (LVET), pulse transit time (PTT), and pulse arrival time (PAT). The electronics subsystem **150** may also evaluate the environmental context of the device described in greater detail below.

[0069] In material characteristics, the electronics subsystem **150** can have a format that includes different materials and/or properties. For instance, the electronics subsystem **150** can include a printed circuit board (PCB), where the PCB include materials with different characteristics (e.g. flexible, rigid, ductile, brittle, etc.). The PCB can be single sided, double sided, or multi-layer. The material of the PCB can include a conductive component such as copper and a substrate composed of a dielectric composite material. Alternatively, the electronics subsystem can be composed of other suitable materials.

[0070] In relation to characteristics of the electronics subsystem **150**, the electronics subsystem **150** can include circuitry characteristics configured to improve function in relation to processing of multiple types of signals, noise mitigation due to different electrical and/or mechanical factors, signal transmission, and/or other factors. For instance, the electronics subsystem **150** can include configurations where analog and/or digital components associated with different types of signals are separated from each other in relation to prevention of interference. Additionally or alternatively, the electronics subsystem **150** can include elements that promote isolation or mitigation of electrical noise sources. Additionally or alternatively, the electronics

subsystem **150** can include elements that promote isolation or mitigation of mechanical or vibrational noise sources (e.g., with mechanical noise isolation elements coupled to the sensor(s), with vibration dampeners coupled to the substrate, with vibration dampeners coupled to the base, etc.). Additionally or alternatively, the electronics subsystem **150** can include architecture that promotes efficient signal transmission characteristics (e.g., can include architecture with a specified density of interconnects or distance between electronics components).

[0071] In relation to mechanical properties, the material(s) of the electronics subsystem **150** can have a compressive strength, a shear strength, a tensile strength, a strength in bending, an elastic modulus, a hardness, a derivative of the above mechanical properties and/or other properties that enable structural support of the user and/or other system elements in various operation modes associated with use of the system **100**. The materials chosen can satisfy a variety of characteristics that are relevant to electronics.

[0072] In relation to electrical properties, the material(s) of the electronics subsystem **150** can have a conductivity, resistivity, a derivative of the above electrical properties and/or other properties that the electronics subsystem **150** to receive electrical signal transmission. In an embodiment, as shown in FIG. 4, an electronics subsystem **450** is electrically coupled to a conductive lead **464** in order to receive electrical signals from a fastener **410**. The fastener receives and transmits an electrical signal from a conductive cap **414** to the conductive lead **464**. The conductive lead can also have a conductivity, resistivity, a derivative of the above electrical properties to transmit an electrical signal from the fastener **410** to the electronics subsystem **450**.

[0073] In the configurations shown, the electronics subsystem **150** is positioned inferior to the conductive surface **120** to protect the electronics subsystem **150** from user **105** interference or other factors. In the embodiment shown in FIG. 4, an electronics subsystem **450** is contained within an internal cavity **466**. In some embodiments, the internal cavity **466** can be an internal cavity of one or more of: a base **460** or the substrate **460**. The base **460** can be composed of an insulative material to function to prevent excess noise propagating through the system from the conductive layer **130**. The base **460** can also serve to prevent undesired signal interaction between the fastener **410** and other system components (e.g., a power subsystem, the substrate **420**). Alternatively, the electronics subsystem can be coupled to the conductive layer **460** or an exterior surface of the system in another manner. In order to protect the integrity of the electrical subsystem **450**, the subsystem **450** can be sealed from external dangers such as water, dirt, or other environmental conditions that may cause damage to the electrical subsystem **450**. For instance, as shown in FIG. 7A (which is described in more detail below), a conductive layer **730** is coupled to a conductive cap **714** and the conductive cap comprises a compliant and conductive polymer material that cooperates with the substrate **720** to form a seal **770**. The seal **770** prevents water and other fluids or particles from flowing towards an electronics system housed below the conductive layer **130**.

[0074] The seal **770** formed by the conductive cap **714** composed of a compliant material also functions to interface components of the system. The conductive cap **714** provides contouring between the conductive layer **730**, the substrate **720**, and the fastener **710**. As the fastener **710** is tightened,

the conductive cap **714** fills the gaps between the fastener **710**, the conductive layer **730**, and the substrate **720** in order to maximize the conductive contact surface area. The conductive cap **714** also provides a mechanical connection to attach the base **760** to the substrate **720**. As such, the conductive cap **714** functions as a shock absorber between the substrate **720** and the fastener **710**, preventing damage to the substrate **720** or the conductive layer **730**.

[0075] As described above in relation to FIGS. 2C and 2D, the system configuration shown in FIGS. 7A-7C includes mating contacting faces that provide mechanical and electrical contact functionality, where coupling of an interface (e.g., self-centering counter-sunk interface of the substrate **720**) with a compliant interface material of the conductive cap **714** between the conductive layer **730** coupled to the substrate **720** and a respective body of a fastener **710** provides a reliable connection (in terms of electrical contact) and allows for some shock absorption.

1.4.1 System—Additional Sensors

[0076] The system can also include or otherwise receive signals from additional sensors (e.g., temperature sensors, light sensors, moisture sensors), where additional sensors can be coupled to appropriate portions of the system. For instance, the system can include temperature sensors that function to protect the system and/or to provide contextual data that can be processed, with other biometric signals, to analyze health states of the user. If the temperature is too low or too high for safe and effective operation, the system can power off or send warning message to a display (e.g., such as display **670** shown in FIG. 6). A light sensor can function to adjust the brightness of a display such that the display is visible in different background lighting. The system may also include a moisture sensor to evaluate the humidity. The moisture, temperature and other environmental signals can be evaluated and interpreted to relate the environmental context data to the user data.

1.5 System—Assembly

[0077] The system **100** of FIGS. 1A and 1B can be assembled according to one or more of embodiments. FIGS. 7A-7C and FIGS. 8A-8H described below illustrate the assembly of one embodiment of the system **100**. Alternatively, the system **100** can be assembled in any suitable manner.

[0078] As described briefly above, FIG. 7A is a cross section view of a portion of an embodiment of a system. FIG. 7B is an isometric view of a cross section of an expanded portion of the embodiment of the system shown in FIG. 7A, from a top right view. A broad surface of a conductive layer **730** is coupled to a substrate **720** which is coupled to a base **760**. A port **724** is shown to pass through the conductive layer **730**, the substrate **720** and the base **760**. FIG. 7C is a similar isometric view of a system from a top right view. FIG. 7C includes a fastener **710** inserted into the port **724**. The fastener **710** is coupled to an interior region of the substrate **720** and the base **760**. As described earlier in relation to FIG. 7A, the fastener **710** and the conductive cap **714** can prevent substances such as water or dust from entering through the port **724**. The conductive cap **714** forms a conical sheathing around a region of the fastener **710**, allowing for compliance between components.

[0079] The system components are coupled such that the device can be comfortable and attractive to the user. FIG. 8A is an isometric view, from the top right, of an embodiment of a system described in relation to FIGS. 7B and 7C. The system has a height of 3.1 centimeters, a width of 31.1 centimeters, and a length of 40.6 centimeters. The device can have a length of 20-100 centimeters, width of 10-80 centimeters, and a height of 1-15 centimeters. Alternatively, the system can have any suitable dimensions. The system weighs 7.5 pounds, but the system can have a weight of 2-20 pounds. Alternatively, the system can have a weight of any suitable amount. FIGS. 8B-H show different views of the embodiment shown in FIG. 8A. As such, the dimensions of the system shown in FIGS. 8A-H can be considered consistent for the purposes of illustration.

[0080] FIG. 8B is an isometric view, from the bottom right, of the embodiment of the system shown in FIG. 8A. The base 860 has an area large enough to provide structural support for the user and the system in various operation modes. Four feet 869 are coupled to or extend from the base 860. The feet 869 provide an interface between the ground and the force sensor(s). Alternatively the base 860 may have two or more feet 869 of various shapes and sizes or may not have feet 869.

[0081] FIG. 8C is a top view of the embodiment of the system shown in FIG. 8A. The embodiment includes four conductive caps 814 electrically coupled to the conductive layer 830. The conductive layer includes four electrically isolated subregions 832 illustrated by dashed lines. The conductive layer appears continuous and symmetric to the user across the longitudinal axis to increase aesthetic appeal.

[0082] FIG. 8D is a right side view of the embodiment of the system shown in FIG. 8A. FIG. 8E is a front view of the embodiment of the system shown in FIG. 8A. Shown in FIG. 8D and 8E, the fastener 810 couples the inferior surface of the conductive layer 810 to the superior surface of the substrate 820. The inferior surface of the substrate 820 is coupled to the superior surface of the base 860. The base includes a front left and right foot 869 and a back left and right leg foot. The feet 869 provide an interface between the base 860 and the ground that provides structural support for the user in various operation modes.

[0083] FIG. 8F is a bottom view of the embodiment of the system shown in FIG. 8A. The system is powered by four AA batteries contained in a battery compartment 868 positioned within the base of the system. The battery compartment 868 is located in the center of the bottom of the system. Alternatively, the battery compartment 868 could be located in another region of the system and/or could be coupled to the base 860 or other layer of the system. The system can also be alternatively powered by a rechargeable battery or other form of power through an outlet. FIG. 8F includes four feet 869, a left and right posterior foot 869 and a left and right anterior foot 869. The feet 869 allow the system to be placed on the ground such that the user can stand on the system as directed and the system will remain physically balanced.

[0084] FIG. 8G is a left side view of the embodiment of the system shown in FIG. 8A and FIG. 8H is a back view of the embodiment of the system shown in FIG. 8A. According to FIGS. 8G and 8H, a fastener 810 couples the inferior surface of the conductive layer 810 to the superior surface of the substrate 820. The inferior surface of the substrate 820 is coupled to the superior surface of the base 860. The base

includes a front left and right foot 869 and a back left and right foot 869. The feet 869 provide an interface between the base 860 and the ground that provides structural support for the user in various operation modes.

1.6 System—Operation Modes

[0085] There are several operation modes associated with the system 100. FIG. 9 illustrates operation modes of a system for health monitoring, in accordance with one or more embodiments. FIG. 9 includes three modes of the system: a signal generation mode 980, a content provision mode 990, and a content storage mode 995. The system operates in the signal generation mode 980 when the user 905 interacts with the system. The user interface, in the signal generation mode 980, includes a conductive layer 930, a conductive cap 914, a base 960 and a substrate 920. In relation to the signal generation mode 980, when the user 905 steps onto the device, the conductive layer 930 facilitates formation of an electrical circuit through the body of the user, and receives bioelectrical signals from the user 905. The conductive cap 914 transmits the signal to the electronics subsystem 950. A set of force sensors 940 receive a force signal from the interaction and transmit the signal to the electronics subsystem 950.

[0086] The electrical signal and force signal received by the electronics subsystem 950 are processed in the signal generation mode 980 by the networked analysis engine 959. The data interpreted by the networked analysis engine 959 can include pulse rate, heart rate variability (HRV), body impedance, and cardiac waveforms (e.g. plethysmograph (IPG), ballistocardiograph (BCG), electrocardiograph (ECG)). The networked analysis engine 959 can determine systolic time intervals such as pulse transit time (PTT), pre-ejection period (PEP), pulse arrival time (PAT), and left ventricular ejection time (LVET) from the cardiac waveforms. The non-cardiovascular metrics from the force sensors evaluated by the networked analysis engine 959 can include body weight and balance analysis. The networked analysis engine 959 can also process and evaluate environmental context data described above.

[0087] In the content provision mode 990, as shown in FIG. 9, data interpreted by the networked analysis engine 959 is transmitted to the electronics subsystem, which generates instructions for rendering information derived from outputs of the networked analysis engine 959 at the display. In the content provision mode 990, the display 970, being electrically coupled to the electronics subsystem 950, renders information derived from data processed by the networked analysis engine 959 such as plethysmograph (IPG), a ballistocardiograph (BCG), an electrocardiograph (ECG), weight, and pulse. In the signal generation mode 980, the networked analysis engine 959 can also be in communication with a user device 908 in order to store the data in a content storage mode 995. The user can access his/her data in order to track changes in user health and promote early detection of health related issues.

[0088] The foregoing description of the embodiments has been presented for the purpose of illustration; it is not intended to be exhaustive or to limit the patent rights to the precise forms disclosed. Persons skilled in the relevant art can appreciate that many modifications and variations are possible in light of the above disclosure.

[0089] Some portions of this description describe the embodiments in terms of algorithms and symbolic repre-

sentations of operations on information. These algorithmic descriptions and representations are commonly used by those skilled in the data processing arts to convey the substance of their work effectively to others skilled in the art. These operations, while described functionally, computationally, or logically, are understood to be implemented by computer programs or equivalent electrical circuits, microcode, or the like. Furthermore, it has also proven convenient at times, to refer to these arrangements of operations as modules, without loss of generality. The described operations and their associated modules may be embodied in software, firmware, hardware, or any combinations thereof.

[0090] Any of the steps, operations, or processes described herein may be performed or implemented with one or more hardware or software modules, alone or in combination with other devices. In one embodiment, a software module is implemented with a computer program product comprising a computer-readable medium containing computer program code, which can be executed by a computer processor for performing any or all of the steps, operations, or processes described.

[0091] Embodiments may also relate to an apparatus for performing the operations herein. This apparatus may be specially constructed for the required purposes, and/or it may comprise a general-purpose computing device selectively activated or reconfigured by a computer program stored in the computer. Such a computer program may be stored in a non-transitory, tangible computer readable storage medium, or any type of media suitable for storing electronic instructions, which may be coupled to a computer system bus. Furthermore, any computing systems referred to in the specification may include a single processor or may be architectures employing multiple processor designs for increased computing capability.

[0092] Embodiments may also relate to a product that is produced by a computing process described herein. Such a product may comprise information resulting from a computing process, where the information is stored on a non-transitory, tangible computer readable storage medium and may include any embodiment of a computer program product or other data combination described herein.

[0093] Finally, the language used in the specification has been principally selected for readability and instructional purposes, and it may not have been selected to delineate or circumscribe the patent rights. It is therefore intended that the scope of the patent rights be limited not by this detailed description, but rather by any claims that issue on an application based hereon. Accordingly, the disclosure of the embodiments is intended to be illustrative, but not limiting, of the scope of the patent rights, one implementation of which is set forth in the following claims.

What is claimed is:

1. A system for measuring health signals for a user, the system comprising:

- a first fastener and a second fastener, each of the first fastener and the second fastener comprising a body and a conductive cap ensheathing a first end region of the body;
- a substrate comprising a first broad surface, the substrate comprising a first port and a second port each passing into the first broad surface, the first port retaining the first fastener in position and the second port retaining the second fastener in position;

- a conductive layer coupled to the first broad surface and separated into a first subregion electrically coupled to the conductive cap of the first fastener and a second subregion electrically coupled to the conductive cap of the second fastener, the first subregion electrically isolated from the second subregion;

- a set of force sensors in communication with the substrate; and

- an electronics subsystem comprising an electrical signal channel electrically coupled to the first fastener and the second fastener and comprising a force signal channel coupled to the set of force sensors.

2. The system of claim 1, wherein the conductive cap of at least one of the first fastener and the second fastener is flush with the conductive layer.

3. The system of claim 1, wherein the body of at least one of the first fastener and the second fastener is composed of a conductive metal material and wherein the conductive cap of at least one of the first fastener and the second fastener is composed of an electrically conductive polymer.

4. The system of claim 3, wherein the electrically conductive polymer, with at least one of the conductive layer and the substrate forms a seal that prevents fluid flow toward the electronics subsystem during use.

5. The system of claim 3, wherein the electrically conductive polymer comprises of carbon-doped silicone rubber.

6. The system of claim 1, wherein the conductive cap of at least one of the first fastener and the second fastener is composed of a compliant material and wherein the conductive cap is configured to provide a robust mechanical interface between the fastener, the substrate, and a base housing the electronics subsystem.

7. The system of claim 1, further comprising a base and a retainer, wherein a second end region of at least one of the first fastener and the second fastener, with the retainer, couples the substrate to the base.

8. The system of claim 7, further comprising a conductive lead coupled to at least one of the first fastener and the second fastener by the retainer, the conductive lead electronically coupled to the electronics subsystem.

9. The system of claim 8, wherein the base comprises an internal cavity, wherein at least one of the first fastener and the second fastener, with the retainer, retains the conductive lead in position within the internal cavity, and wherein the electronics subsystem is secured to the base within the internal cavity.

10. The system claim of 1, wherein the electronics subsystem comprises a signal generation mode wherein, in response to a user interaction with the conductive layer, the first and the second fasteners detect an electrocardiogram (ECG) signal contemporaneously with generation of a force signal by the set of force sensors.

11. The system of claim 10, further comprising a display coupled to the electronics subsystem, the electronics subsystem comprising a content provision mode wherein, in response to the user interaction, the electronics subsystem provides information derived from the ECG signal and the force signal through the display.

12. The system of claim 11, wherein the display is positioned inferior to the first broad surface of the substrate and the substrate, with the conductive layer, allows passage of light from the display.

13. A system for measuring health signals, the system comprising:

a first fastener and a second fastener, each of the first fastener and the second fastener comprising a body and a conductive cap coupled to a first end region of the body;

a substrate comprising a first broad surface, the substrate comprising a first port and a second port each passing into the first broad surface, the first port retaining the first fastener in position and the second port retaining the second fastener in position;

a conductive layer coupled to the first broad surface and coupled to the conductive caps of the first fastener and the second fastener; and

a base coupled to the substrate by the first fastener and the second fastener.

14. The system of claim **13**, wherein the conductive cap of at least one of the first fastener and the second fastener is flush with the first broad surface of the substrate, wherein the conductive cap ensheathes the body, and wherein the conductive cap, with at least one of the conductive layer and the substrate, forms a seal that prevents fluid flow past the body.

15. The system of claim **13**, wherein the body of at least one of the first fastener and the second fastener is composed of a conductive metal material and wherein the conductive cap of at least one of the first fastener and the second fastener is composed of an electrically conductive polymer.

16. The system of claim **13**, further comprising a first retainer coupling a second end region of the first fastener to

the base and a second retainer coupling a second end region of the second fastener to the base.

17. The system of claim **13**, further comprising an electronics subsystem retained within an internal cavity of the base, a first conductive lead coupled to the first fastener by a first retainer, and a second conductive lead coupled to the second fastener by a second retainer, the first conductive lead and the second conductive lead coupled to an electrocardiogram (ECG) channel of the electronics subsystem.

18. The system of claim **17**, further comprising a display coupled to the electronics subsystem, the electronics subsystem comprising a content provision mode wherein, in response to a user interaction with the conductive layer, the electronics subsystem provides information derived from an ECG signal received at the ECG channel.

19. The system of claim **13**, further comprising an electronics subsystem and a set of force sensors along a force transmission pathway from the substrate to the base, wherein the set of force sensors is electronically coupled to a force signal channel of the electronics subsystem.

20. The system claim of **19**, wherein the electronics subsystem comprises a signal generation mode wherein, in response to a user interaction with the conductive layer, the first and the second fasteners detect an electrocardiogram (ECG) signal contemporaneously with generation of a force signal by the set of force sensors.

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专利名称(译)	心血管健康监测装置		
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摘要(译)

一种用于同时获取心电图 (ECG) 信号, 阻抗体积描记图 (IPG) 信号, 心冲击描记图 (BCG) 信号以及通过用户的脚测量体重的装置。该装置包括导电表面, 用于接触使用者的脚并在使用期间支撑使用者的重量。该装置还包括一个或多个力传感器, 用于检测导电表面上的力和力变化, 用于处理从导电表面产生和/或检测的电信号的电子器件, 来自该组力传感器的信号, 以及包含基座的基座。电子产品。基座通过一组导电紧固件在结构上耦合到导电表面, 所述导电紧固件将信号从导电表面传输到电子器件。该设备还可以包括集成显示器, 用于向用户提供健康见解。

