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(54) **System and method for the analysis of biopotential signals using motion artifact removal techniques**

System und Verfahren zur Analyse von Biopotenzialsignalen mit Artifaktentfernungstechniken

Système et procédé pour l'analyse de signaux biopotentiels utilisant des techniques d'extraction d'artefact de mouvement

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- **LARS KOTTHOFF ET AL: "An Evaluation of Machine Learning in Algorithm Selection for Search Problems", AI COMMUNICATIONS, vol. 25, no. 3, 1 August 2012 (2012-08-01) , pages 257-270, XP055127031,**

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Description**Technical Field**

[0001] The present invention relates generally to the field of biopotential signal analysis, e.g. detecting, monitoring and/or processing electrocardiogram (ECG), electroencephalogram (EEG) or electromyography (EMG) signals. More specifically the invention relates to a system and a method for the analysis of such biopotential signals using motion artifact removal techniques.

Background

[0002] In real life situations and ambulatory recordings of biopotential signals, motion artifacts result from relative movement of recording electrodes, cables, and acquisition system with respect to the skin and the environment. The most significant changes during motion are happening on the interface between the skin and the electrodes. These might be due to changes in the charge distribution along the contact surface or skin deformations and hence changes in conduction within the skin. However, different type of movements might induce distinct changes in the measured electrical activity.

[0003] A known system that proposes motion artifact removal from ECG signals is described in paper "Motion Artifact Removal using Cascade Adaptive Filtering for Ambulatory ECG Monitoring System", Hyejung Kim et al., Proc. BioCAS 2012.

[0004] Another known technique for motion artifact removal from ECG signals is disclosed in paper "Implementation of Fuzzy-rule based Activity Classification and Optimized Adaptive Filter-set for Wearable ECG Recording", Yun-Hong Noh and Do-Un Jeong, International Journal of Multimedia and Ubiquitous Engineering, Vol.7, No.4, October 2012. The solution proposes the use of an adaptive filter with an optimal filter coefficient selection to remove motion artifacts. With the data obtained from a three-axis accelerometer, activity status can be classified into different states and optimal filter coefficients can then be selected to minimize the distortion of ECG signal.

[0005] US patent 5,513,649 describes an EEG (electroencephalogram) system that detects brain waves from a subject, and reduces the adverse effect of artifacts due to head, body and eye movements. A head and body movement reference signal can be provided by an accelerometer, motion detector or, alternatively, spatial average of EEG channels. Eye motion sensors are used as a reference for eye movement artifacts.

[0006] Patent application WO 2011/149752 describes a system able to identify artifacts in order to optimize an algorithm for removing artifacts from EEG signals.

Summary

[0007] According to the invention, there is provided a system for the analysis of biopotential signals, comprising: a motion classification module configured for receiving at least one biopotential signal and at least one reference secondary input signal, performing motion artifact classification for determining motion information (MMI) comprising a type and/or severity indication about motion phenomena causing artifacts in the biopotential signal and communicating said motion information (MMI) to a motion artifact reduction module; the motion artifact reduction module configured for performing motion artifact removal from the biopotential signal based on the information received from the motion classification module; characterized in that the system is further configured for evaluating the effectiveness of at least one algorithm used for motion artifact removal and generating feedback information between the motion classification module and the motion artifact reduction module for optimizing the performance of the motion artifact classification.

[0008] According to exemplary embodiments of the invention, there is provided a new and improved system and method for removing motion artifacts from biopotential signals.

[0009] Advantageously, according to embodiments of the invention, the proposed system and method adaptively and automatically determines and sets appropriate motion artifact reduction techniques based on the motion type and/or severity affecting the biopotential signal.

[0010] According to some exemplary embodiments of the invention, the proposed system and method is particularly advantageous for wireless, low power data acquisition technology and/or ambulatory biopotential measurement applications.

[0011] It is also advantageous that the proposed system and method allows for reliable and high quality biosignal monitoring in ambulatory conditions.

[0012] According to some embodiments, it is important to focus on characterizing the effects of human motion on EEG but also other biopotential signals that can be monitored with low-power devices.

[0013] According to an exemplary embodiment, there is provided a system for the analysis of biopotential signals, comprising: a motion artifact reduction module configured for reducing or eliminating a motion artifact estimate from a

recorded biopotential signal; and a motion classification module configured for determining information about the motion causing the artifacts and communicating said information to the motion artifact reduction module.

[0014] According to an exemplary embodiment, the determined information about the motion comprises an indication or classification of type and/or severity of the motion phenomena causing the artifacts in the recorded biopotential signal.

[0015] According to an exemplary embodiment, the motion classification module may be configured for determining information about the motion causing the artifacts based on information about one or a combination comprising contact impedance, contact force, motion acceleration, temperature or humidity sensor signals.

[0016] According to another exemplary embodiment, the motion classification module may be further configured for determining and communicating setting parameters for artifact removal to the motion artifact reduction module. Said setting parameters may comprise, for example, an artifact removal technique selection indication and/or coefficients related to a given artifact removal technique and/or signal selection indication for a given artifact removal technique.

[0017] According to another exemplary embodiment, the motion artifact reduction module may be further configured for applying, configuring and/or optimizing a certain artifact removal technique based on information received from the motion classification module.

[0018] In another exemplary embodiment, the motion classification module and the motion artifact reduction module may be configured for performing one or a combination of classification, statistical analysis, spectral analysis, cross-signal analysis, PCA, ICA, CCA, AF, BF or EMD techniques.

[0019] According to still another embodiment, the system (100) may further comprise a pre-processing module configured for adapting the received signals in order to be processed by the motion classification module and/or a post-processing module configured for adapting the output signals provided by the motion classification module and/or the motion artifact reduction module.

[0020] According to an exemplary embodiment, the system is further configured to store and process outputs of the a motion classification module and the motion artifact reduction module in different periods of time in order to generate said feedback information for optimizing the performance of the motion artifact classification.

[0021] According to another exemplary embodiment, evaluating the effectiveness of at least one algorithm used for motion artifact removal comprises comparing the clean biopotential signal after motion artifact removal with a reference baseline signal of such biopotential signal.

[0022] The invention also relates to an electronic device comprising a system for the analysis of biopotential signals according to any of the embodiments as herein described.

[0023] According to another exemplary embodiment there is also provided a method for the analysis of biopotential signals, comprising, in a system: receiving at least one biopotential signal; receiving at least one secondary input signal from a sensor providing direct or indirect information about electrode motion; determining a classification information of the kind of motion causing artifacts in the received biopotential signal; and using that classification information for reducing or eliminating a motion artifact affecting the received biopotential signal.

[0024] According to another exemplary embodiment, there is provided a method for the analysis of biopotential signals, comprising, in a system according to an embodiment of the invention: receiving at least one biopotential signal; receiving at least one secondary input signal; performing motion artifact classification for determining motion information comprising a type and/or severity indication about motion phenomena causing artifacts in the biopotential signal; performing removal of the motion artifact from the biopotential signal based on that motion artifact classification; and evaluating the effectiveness of the removal of the motion artifact from the biopotential signal and generating feedback information for optimizing the performance of the motion artifact classification.

[0025] Certain objects and advantages of various new and inventive aspects have been described above. It is to be understood that not necessarily all such objects or advantages may be achieved in accordance with any particular embodiment of the present invention. Those skilled in the art will recognize that the solution of the present invention may be embodied or carried out in a manner that achieves or optimizes one advantage or group of advantages without necessarily achieving other objects or advantages.

Brief description of the drawings

[0026] The above and other aspects of the system and a method according to the present invention will be shown and explained with reference to the non-restrictive example embodiments described hereinafter.

Figure 1 shows a general block diagram of a system for the analysis of biopotential signals according to a first exemplary embodiment.

Figure 2 shows a block diagram of a system for the analysis of biopotential signals according to a second exemplary embodiment.

Figure 3 shows a schematic block diagram of a system for the analysis of biopotential signals according to a third exemplary embodiment.

Figure 4A shows a flow diagram of a method for the analysis of an EEG signal according to a first exemplary embodiment.

Figure 4B illustrates an exemplary graph of the standard deviation of measured electrode-to-skin impedance and 3-axis motion acceleration signals during EEG monitoring when applying the method shown in **Figure 4A**.

Figure 4C shows the skewness of the signals shown in **Figure 4B**.

Figure 4D shows the kurtosis of the signals shown in **Figure 4B**.

Figure 4E illustrates an exemplary graph of the magnitude of measured electrode-to-skin impedance and 3-axis motion acceleration signals during EEG analysis when applying a method as shown in **Figure 4A**.

Figure 5A shows a flow diagram of a method for the analysis of an EEG signal according to a second exemplary embodiment.

Figure 5B illustrates an exemplary graph of the deviation from the mean of measured force applied on the electrode and 3-axis motion acceleration signals during EEG monitoring when applying a method as shown in **Figure 5A**.

Figure 5C illustrates an exemplary graph of the magnitude of measured force and an EEG signal during EEG analysis when applying a method shown in **Figure 5A**.

Figure 6A shows a general block diagram of a system for the analysis of biopotential signals according to a fourth exemplary embodiment.

Figure 6B shows an exemplary block diagram of a system for the analysis of biopotential signals of **Figure 6A**.

Figure 6C shows a flow diagram of a method for the analysis of an EEG signal according to a third exemplary embodiment.

Figure 7A shows a flow diagram of a method for the analysis of an EEG signal according to a fourth exemplary embodiment.

Figure 7B illustrates an exemplary graph of EEG spectral contents for a baseline EEG and the EEG obtained after application of different types of motion artifact removal during EEG analysis when applying a method as shown in **Figure 7A**.

Figure 7C illustrates an exemplary graph of a distribution of the data points for a reference, input and cleaned EEG signal during EEG analysis when applying a method as shown in **Figure 7A**.

Detailed description

[0027] In the following, in the description of exemplary embodiments, various features may be grouped together in a single embodiment, figure, or description thereof for the purpose of streamlining the disclosure and aiding in the understanding of one or more of the various inventive aspects. This is however not to be interpreted as the invention requiring more features than the ones expressly recited in the main claim. Furthermore, combinations of features of different embodiments are meant to be within the scope of the invention, as would be clearly understood by those skilled in the art. Additionally, in other instances, well-known methods, structures and techniques have not been shown in detail in order not to obscure an understanding of the description.

[0028] **Figure 1** shows a general block diagram of an exemplary system **100** for the analysis of biopotential signals. The system **100** comprises a motion classification module **110** configured for analyzing the input signals **40**, **50**, extracting meta-information about the motion, determining the type of motion causing the artifacts and communicating settings for artifact removal to a motion artifact reduction module **120**. According to one exemplary embodiment, the motion artifact reduction module **120** is configured for receiving information from the motion classification module **110** and performing artifact removal based on available signal input and information received. According to another exemplary embodiment, the motion artifact reduction module **120** may also provide information or data to the motion classification module **110**, for example for updating some parameters.

[0029] The system **100** may receive at least one biopotential signal **40** which may be contaminated by a motion artifact and one or more secondary inputs **50** related to the subject or electrode motion and/or direct or indirect artifact distortion causes. The system **100** may provide as output: at least one cleaned biopotential signal **60** which is the result of applying some motion artifact reduction technique(s) to the received contaminated biopotential signal **40** and secondary outputs **70** with motion meta-information about the type and features of the motion detected.

[0030] According to an exemplary embodiment, extraction of a clean EEG signal from the contaminated one may be performed in the system **100** based on the meta-information extracted from one or more reference secondary input signals **50**, such as, but not limited to, electrode-to-tissue impedance, applied or contact force or acceleration of/on the electrode. The meta-information extracted from those reference secondary inputs **50** may comprise, but is not limited to, signal properties, such as standard deviation, slope and/or higher-order statistics. From such extracted meta-information, certain optimized filtering methods and parameters may be automatically selected. According to an exemplary embodiment, the system **100** is configured for selecting the most appropriate filtering technique for a determined type and severity of motion that affects the biopotential signal and to adjust certain filter or other motion artifact reduction settings to be applied to the contaminated biopotential signal. Such filtering techniques may include, but are not limited

to, adaptive filtering, ICA, and/or wavelet decomposition.

[0031] **Figure 2** shows another block diagram of an exemplary system **100** for the analysis of biopotential signals. The system **100** may comprise a pre-processing module **105** configured for performing basic signal preprocessing required before motion classification and/or artifact handling. The pre-processing module **105** may comprise simple linear filtering (e.g. for removing power line noise), resampling, etc. The system **100** further comprises a motion classification module **110** configured for analyzing the input signals, estimating the kind of motion that causes the artifacts, extracting meta information about the motion, and/or communicating optimized settings for artifact removal to the motion artifact reduction module **120**. According to one exemplary embodiment, the motion artifact reduction module **120** is configured for receiving information from the motion classification module **110** and performing artifact reduction based on available signal input. According to another exemplary embodiment, the motion artifact reduction module **120** may also provide input information or data **190** for the motion classification module **110**, for example for updating some parameters. After the motion artifact reduction module **120**, a post-processing module **125** may be provided for formatting the output information or signals, along with the raw input received by the system. According to an exemplary embodiment, the post-processing module **125** may be configured also for combining the outputs of different artifact removal methods.

[0032] The system **100** may receive: a) biopotential input signals **X1 to Xn** consisting of n biopotential channels/electrodes measuring biopotential of interest at different locations. Biopotential signals may be, but are not limited to, EEG, ECG or EMG signals; b) auxiliary sensor input signals **AUX** such as, but not limited to, contact impedance, contact force and/or acceleration of the sensors. Said sensors may be, but not necessarily, located at the electrodes; and/or c) contextual sensor input signals **CON** such as, but not limited to, acceleration, temperature and/or humidity.

[0033] The system **100** may provide, as output: a) motion meta information **MMI** about the type and features of the motion detected. This can be, for example, a type of motion (e.g., walking, running), or the severity of the impact of motion on the biopotential signal of interest; b) artifact meta information **AMI** about the artifact removal method(s) used, along with the additional information that might be useful; and/or c) cleaned biopotential signals **Cleaned BioP** which are the result of applying artifact reduction techniques on the biopotential input signals. The cleaned biopotential signals are signals in which the artifact contamination has been totally or partially removed.

[0034] **Figure 3** shows another schematic block diagram of an exemplary system **100** for the analysis of biopotential signals. According to an exemplary embodiment, the motion classification module **110** and the motion artifact reduction module **120** may share methods and algorithms used for signal analysis and classification.

[0035] According to an exemplary embodiment, the motion classification module **110** may be configured for carrying out some classification techniques in combination with statistical analysis, spectral analysis, cross-signal analysis, and/or wavelet analysis methods. A list of such possible methods can be found, for example, in paper "Introduction to Applied Statistical Signal Analysis", by Richard Shiavi, Elsevier Inc., 3rd edition, San Diego, 2006, but it may also include higher (than 4) order statistics, and/or non-linear signal analysis methods. According to another exemplary embodiment, the motion classification module **110** may be also configured for performing some artifact handling functions, such as, for example, PCA, ICA and/or CCA. According to another exemplary embodiment the motion classification module **110** may be also configured for carrying out some classification algorithms, such as KNN, LDA, SVM, BN, NN. A description of such algorithms can be found in the literature and are known for the person skilled in the art.

[0036] According to an exemplary embodiment, the motion artifact reduction module **120** may be configured for carrying out procedures such as, for example, PCA, ICA, CCA, AF, BF, and/or EMD. A recent review of such methods is disclosed in paper "Artifact Removal in Physiological Signals - Practices and Possibilities", by Kevin T. Sweeney et al., IEEE Transactions on Information Technology in Biomedicine, Vol. 16, Issue 3, pages 488-500, 2012. According to another exemplary embodiment, the motion artifact reduction module **120** may be also configured for performing cross-signal analysis, wavelet analysis, etc., and/or may also perform some of the classification methods.

[0037] It shall be understood, for a person skilled in the art, that the above introduced list of methods and techniques, individually or in combinations, is not exhaustive.

[0038] **Figure 4A** shows a flow diagram of a method for the analysis of an EEG signal according to a first exemplary embodiment. The method is based on the usage of information about electrode-to-skin impedance **Z**, electrode (3-axis) acceleration motion **A**, and the EEG as the biopotential signal of interest **EEG**. According to an exemplary embodiment, the motion classification module **110** may be configured for determining and analyzing the standard deviation, skewness and kurtosis of the impedance magnitude **|Z|** and acceleration signals **A**. Based on the output of the motion classification module **110**, the motion artifact reduction module **120** may either perform CCA or ICA techniques.

[0039] The method may comprise the following steps:

- in step 1, if standard deviation of impedance magnitude and (or) acceleration in all (or a subset of) directions is larger than predetermined threshold, then go to step2. Otherwise provide the clean EEG signal (and eventually information about the impedance and acceleration signals). **Figure 4B** illustrates, for example, the standard deviation of those signals during an EEG recording that contains artifacts between seconds 35 and 105. According to an exemplary embodiment, the threshold values can be set to 1k Ω for impedance magnitude and 0.025g for acceleration;

- in step 2, if skewness and (or) kurtosis **HOS** of impedance magnitude and (or) acceleration in all (or a subset of) directions is larger than the predefined threshold, then go to step 3. Otherwise go to step 4. As an example, **Figures 4C and 4D** illustrate, respectively, the skewness and kurtosis of the impedance magnitude and acceleration for the same segment as depicted in **Figure 4B**.

- in step 3, use the ICA method to extract the components from the EEG (and other signals), since ICA uses higher order statistics (e.g., skewness and kurtosis) in the analysis and then go to step 5;

- in step 4, use the CCA method to extract the components from the EEG (and other signals), since CCA uses only first and second order statistics (e.g., mean and standard deviation) in the analysis and then go to step 5;

- in step 5, correlate the identified components from the EEG signal(s) with the impedance magnitude and acceleration signals, select the component that has the highest correlation and then go to step 6. As an example, **Figure 4E** illustrates an EEG signal along impedance magnitude and acceleration signals, for the same segment as in **Figures 4B to 4D**. They can be used to select the component in the EEG that represent the artifact and that is extracted using the ICA or CCA method;

- in step 6, remove the identified component from the EEG signal and reconstruct the 'clean EEG' (**Cleaned BioP** in **Figure 2**).

[0040] In case the artifact is not identified, the clean EEG will be the same as the input EEG.

[0041] **Figure 5A** shows a flow diagram of another exemplary method for the analysis of an EEG signal. The method is based on the usage of information about the force applied to an electrode **F**, electrode (3-axis) acceleration motion **A**, and the EEG as the biopotential signal of interest **EEG**. According to an exemplary embodiment, the motion classification module **110** may be configured for determining and analyzing the deviation from the mean and optionally based on a well-tested classifier. Based on the output of the motion classification module **110**, the motion artifact reduction module **120** may perform an adaptive filtering method that uses either force or the acceleration signal with the largest deviation from the mean as a reference signal. The selection of the reference signal is also provided by the system as a motion meta Information indicating whether there is a force (pressure) change in one or more electrodes, or there is a head and/or body movement.

[0042] The method may comprise the following steps:

- in step 1, if deviation from the mean of the force in all (or a subset of) electrodes is larger than deviation from the mean of acceleration in all (or a subset) of electrodes and in all (or a subset) of directions, then go to step 2. Otherwise go to step 3. As an example, **Figure 5B** illustrates the deviation from the mean during the recording that contains artifacts between second 40 and 360. In the example of the figure, it can be observed that the deviation from the mean for force is much larger than the deviation from the mean for acceleration (in all directions). In case this step is not so obvious, more advanced techniques can be used for making an adequate choice in this step, e.g., using LDA, or KNN classification methods;

- in step 2, use the AF method with force signal as a reference signal to estimate the filter coefficients and then go to step 4. The sample data that can be used in this step is illustrated in **Figure 5C**. For a person skilled in the art it is known how AF can be used to remove artifacts from the EEG recording;

- in step 3, use the AF method with acceleration signal in the direction of the largest deviation from the mean as a reference signal to estimate the filter coefficients and then go to step 4;

- in step 4, use filter coefficient to filter the EEG signal and obtain a clean EEG (**Cleaned BioP** in **Figure 2**) and forward information as the motion meta data that either force was applied on all (or a subset) of electrodes or there is a head/body movement.

[0043] **Figure 6A** shows a general block diagram of another exemplary system for the analysis of biopotential signals. The system uses all available information that may include biopotential signal(s) (for example, EEG signals), auxiliary signal(s), and contextual information, as an input for the motion classification module **110**. The system **100** shows the usage of a neural network (NN), but the embodiment can be based on classifiers other than NN. The usage of such classifier requires training. Training should be performed on the data set that has sufficient samples of the signals obtained during artifact and non-artifact (clean) segments, such that these segments are labeled as e.g., moderate artifact segments, severe artifact segments, and clean segments. Another more detailed exemplary embodiment of the system is illustrated in **Figure 6B**. The output of motion classification module **110** during training are the coefficients that will be used for real time operation of the NN as well as data statistics, such as probability density function of different input signals for artifact and clean data segments.

[0044] According to another exemplary embodiment, in real-time operation, the motion classification module **110** uses coefficients which are the output of the training stage and the motion artifact reduction module **120** uses data distribution information obtained in the training stage.

[0045] **Figure 6C** shows a flow diagram of another exemplary method for the analysis of an EEG signal. The method

may comprise the following steps:

- in step 1, use the Neural Network to classify the input signal(s) (**EEG**, **|Z|**, **A**, **F**, **pdf(EEG)**, **pdf(|Z|)**, **pdf(A)**, **pdf(F)**) and in case it is classified as segment with moderate artifacts then go to step 2. Otherwise go to step 4. The NN is used to distinguish between segments that do not require artifact removal, ones that require, and ones that are too noisy for the artifact removal technique to be effective;
- in step 2, the information about the data distribution of the clean and contaminated segments (e.g., probability density function) is used as an input for Wiener filtering (or other filtering method that uses information about data distribution **pdf(EEG)**, **pdf(|Z|)**, **pdf(A)**, **pdf(F)**), resulting in the Wiener filter coefficients (as can be seen in **Figure 6B**). After obtaining the coefficients go to step 3;
- in step 3, use a Wiener filtering method and obtain a clean EEG (**Cleaned BioP** in **Figure 2**) based on all available input signals, update the artifact data distribution information **pdf(EEG)**, **pdf(|Z|)**, **pdf(A)**, **pdf(F)**, and go to step 5;
- in step 4, if the NN classifies the segment as a clean data segment, then update the clean data distribution information **pdf(EEG)**, **pdf(|Z|)**, **pdf(A)**, **pdf(F)** and go to step 5.
- in step 5, output motion meta information based on the output of the classification step, i.e., whether it is a segment with no artifacts, segment with too much artifacts, or a segment where artifact reduction is applied.

[0046] It is understood that all the above described embodiments may be implemented by hardware and/or software means, for example, in a microprocessor or microcomputer environment.

[0047] **Figure 7A** shows a flow diagram of a method for the analysis of an EEG signal according to a fourth exemplary embodiment. The method uses all available information that may include biopotential signal(s) (for example, EEG signals), auxiliary signal(s), and contextual information, as an input (**EEG**, **|Z|**, **A**, **F**, **pdf(EEG)**, **pdf(|Z|)**, **pdf(A)**, **pdf(F)**) for the motion classification module **110**. The motion classification module **110** may use a motion classification approach, but not limited to, as implemented in the exemplary embodiments of **Figures 4A**, **5A** and **6A**. The output of the motion classification module **110** is then assigned to a segment (i.e., epoch) of biopotential data, denoting what type of motion artifact is present in the signal **Type 1 MA to Type n MA**. Several motion artifact reduction algorithms may be available and applied in the motion artifact reduction module **120** and the output of this motion artifact removal algorithms is then evaluated with respect to the expected signal properties and the estimated effectiveness of each of the algorithms is used to build the knowledge on how to optimize motion classification as well as motion artifact reduction.

[0048] The method may comprise the following steps:

- in step 1, use one or a combination of motion classification algorithms to determine one or more types of motion artifact **Type 1 MA to Type n MA**. The algorithm(s) used may be pre-defined but may also be based on a built knowledge about the effectiveness of the algorithms for motion artifact handling performed in step 3 and accumulated in step 4. The input signals used in the classification may be predefined but may also be based on the evaluation performed in steps 3 and 4. The knowledge on the optimal algorithm for motion artifact types extracted in step 4 may be used for, but not limited to: adjusting the parameters of the motion artifact classification algorithms (e.g., the thresholds used, the size of the neural network, etc.) to achieve better classification; and/or selecting which algorithm to use (including the selection of parameters for that motion artifact reduction algorithm) to achieve better classification;
- in step 2 several implementation of motion artifact reduction algorithms (and/or their combinations) are applied to the input signals. The algorithm(s) used can be pre-defined but can also be based on a built knowledge about the effectiveness of the algorithms for motion artifact handling performed in step 3 and accumulated in step 4. The input signals used in the classification can be predefined but may also be based on the evaluation performed in steps 3 and 4. The result is a clean EEG (**Cleaned BioP** in **Figure 2**) based on all (or a subset) of available input signals. The knowledge on the optimal algorithm for motion artifact types extracted in step 4 can be used for, but not limited to: adjusting the parameters of the motion artifact reduction algorithms (e.g., the number of filter coefficients for adaptive filtering, type of the wavelets used for wavelet transform, etc.) to achieve better motion artifact reduction; and/or selecting which algorithm to use for a specific motion artifact type (including the selection of parameters for that motion artifact reduction algorithm) to achieve better motion artifact reduction; and/or selecting the optimal combination of algorithms to be used (e.g., adaptive filtering and discrete wavelet transform, Wiener filtering and ICA, etc.) to achieve better motion artifact reduction;
- in step 3 an evaluation of the motion artifact handling algorithm may be done based on comparing the obtained clean EEG signal and the expected signal. In case of an EEG this may be done, for example, by comparing the spectral content of the baseline EEG (without artifact contamination) and the one(s) obtained after application of the artifact removal algorithm(s) (e.g. sagittal, coronal, standing, walking, jumping). Such signals are illustrated in **Figure 7B**. Another option for evaluating would be to look at the distribution of the data points between the baseline and the artifact-contaminated signal. Such signals, for an EEG biopotential signal, are illustrated in **Figure 7C**.

Similarly, in case of an ECG biopotential signal, the obtained clean ECG signal can be compared with a template ECG signal or a baseline one. Other evaluation metrics (or a combination of those) may be used in a similar way;

- in step 4, based on the evaluation of a) the output of one or more motion artifact reduction algorithm(s) from the motion artifact reduction module **120**, b) the output of one or more motion artifact classification algorithm(s) from the motion classification module **110**, and, when available, c) previous outputs of these modules on the data segments already processed, feedback information is generated to optimize the performance of the motion artifact classification described in step 1, and motion artifact reduction described in step 2;

- in step 5, the method may output motion meta-information **MMI** based on the output of the classification step (step 1), i.e., whether it is a segment with no artifacts, a segment with too much artifacts, or a segment where artifact reduction is applied, which classification algorithm(s) is(are) used and what parameters. Also the information from step 4 is used, describing the optimal setup for motion artifact reduction approach for a certain type of motion artifact.

[0049] Further advantageous embodiments and background information of the invention will be described below. For example, according to an exemplary embodiment of the invention, extraction of a clean biopotential signal from the contaminated one is performed in two stages. Based on the meta information extracted from one or more reference signals (such as electrode to tissue impedance, force on the electrode or acceleration of the electrode) the proper filtering method and parameters are automatically selected. This is performed by a 'motion classifier' (using signal properties, such as standard deviation, slope, higher-order statistics) which performs the selection of the filtering technique. Hence, the motion classifier will be used to select the most appropriate filtering technique for the type and severity of motion at hand and to adjust filter settings. Filtering techniques can include adaptive filtering, ICA, wavelet decomposition, etc.

[0050] Data supporting the proposed invention is at least based on the experiment performed with a number of participants where EEG, force, impedance and acceleration were continuously monitored while applying force on dry EEG electrode or performing various movements. The Table given below illustrates the changes that are observed in each of the signals.

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	Con	Rep	Imp	Nod	Til	Sta	Wal	Jum
EEG(mV)	mean	-1.7±0.17	-1.7±0.09	-1.7±0.20	-0.17±0.22	-1.7±0.23	-1.7±0.28	-1.4±0.61
	max-min	3.1±2.41	3.0±3.39	4.2±1.91	2.6±1.25	3.8±2.99	3.3±2.93	11.9±3.88
	stdev	0.1±0.06	0.1±0.11	0.2±0.15	0.1±0.11	0.2±0.11	1.5±0.13	1.0±0.85
Imp(kΩ)	mean	39±21	35±12	41±20	57±23	53±24	52±25	59±20
	max-min	32±21	23±24	35±21	36±33	28±42	14±12	94±26
	stdev	8.7±6.5	5.1±3.5	5.9±5.6	7.5±6.8	3.9±5.1	1.5±1	7.4±2.5
For(N)	mean	1.5±0.28	1.2±0.25	1.0±0.39	0.8±0.29	0.9±0.26	0.8±0.52	0.9±0.53
	max-min	4.5±0.73	3.2±0.89	4.0±1.03	1.1±0.49	1.1±0.38	1.0±0.31	3.1±1.18
	stdev	1.0±0.19	0.7±0.18	0.3±0.11	0.3±0.16	0.2±0.06	0.1±0.03	0.2±0.06
Acc(g)	mean	0.7±0.06	0.7±0.05	0.7±0.06	0.7±0.05	0.7±0.07	0.7±0.05	0.7±0.05
	max-min	0.2±0.07	0.16±0.2	0.3±0.18	0.4±0.12	0.6±0.08	0.5±0.11	1.2±0.33
	stdev	0.0±0.00	0.0±0.00	0.0±0.00	0.1±0.02	0.1±0.01	0.0±0.01	0.1±0.02

[0051] The columns represent different force applications (continuous, repetitive, impact) or different movements (head nodding, head tilting, standing up/sitting down, walking and jumping). There is a difference between the values of EEG, impedance, force and acceleration across different conditions.

[0052] Different conditions also result in different correlation between the signals in question. For example, large correlation coefficient values between the EEG and impedance can be observed for short-term large amplitude changes due to external force (impact force). The correlation of segments containing large changes in force or large changes in acceleration can be characterized. High correlation can be observed (to a lesser degree) for head movements (sagittal and coronal), stand up/sit down movements, force application and release in case of continuous force application, and particularly in the correlation values for jumping segments. Similar outcomes can be observed when looking into correlation of EEG with other signals.

[0053] Such results demonstrate that the system can extract information on the type and dynamics of motion based on the signal properties. According to an exemplary embodiment of the invention, such information may be used in the motion classifier module to select which filtering to apply, what parameters to use in the filtering, as well as which signals to use for removing artifacts. Numerous methods exist in the literature that can be used for artifacts removal that can be part of the system, namely, adaptive filtering, blind source separation methods, wavelet transform, etc. Furthermore, the motion classifier can select a number of them to be applied in sequence or in parallel to have more efficient artifact removal.

Claims

1. A system (100) for the analysis of biopotential signals, comprising:

a motion classification module (110) configured for receiving at least one biopotential signal (40) and at least one reference secondary input signal (50), performing motion artifact classification for determining motion information (MMI) comprising a type and/or severity indication about motion phenomena causing artifacts in the biopotential signal and communicating said motion information (MMI) to a motion artifact reduction module (120); the motion artifact reduction module (120) configured for performing motion artifact removal from the biopotential signal based on the information received from the motion classification module (110);

characterized in that

the system is further configured for evaluating the effectiveness of at least one algorithm used for motion artifact removal and generating feedback information (190) between the motion classification module (110) and the motion artifact reduction module (120) for optimizing the performance of the motion artifact classification.

2. A system (100) according to claim 1 wherein the system is further configured to store and process outputs of the motion classification module (110) and the motion artifact reduction module (120) in different periods of time in order to generate said feedback information (190) for optimizing the performance of the motion artifact classification.

3. A system (100) according to any of the previous claims wherein evaluating the effectiveness of at least one algorithm used for motion artifact removal comprises comparing the clean biopotential signal after motion artifact removal with a reference baseline signal of such biopotential signal.

4. A system (100) according to any of the previous claims wherein the at least one reference secondary input signal (50) is a signal comprising information about one or a combination of contact impedance, contact force, motion acceleration, temperature or humidity.

5. A system (100) according to any of the previous claims wherein the motion classification module (110) is further configured for determining and communicating setting parameters for artifact removal to the motion artifact reduction module (120).

6. A system (100) according to claim 5 wherein said setting parameters comprise an artifact removal technique selection indication and/or coefficients related to a given artifact removal technique and/or signal selection indication for a given artifact removal technique.

7. A system (100) according to any of the previous claims wherein the motion artifact reduction module (120) is further configured for applying, configuring and/or optimizing a certain artifact removal technique based on information

received from the motion classification module (110).

8. A system (100) according to any of the previous claims wherein the motion classification module (110) and the motion artifact reduction module (120) are configured for performing one or a combination of classification, statistical analysis, spectral analysis, cross-signal analysis, PCA, ICA, CCA, AF, BF or EMD techniques.
9. A system (100) according to any of the previous claims further comprising a pre-processing module (105) configured for adapting the received signals in order to be processed by the motion classification module (110) and/or a post-processing module (125) configured for adapting the output signals provided by the motion classification module (110) and/or the motion artifact reduction module (120).
10. An electronic device comprising a system (100) for the analysis of biopotential signals according to any one of claims 1 to 9.
11. A method for the analysis of biopotential signals, comprising, in a system (100) according to claim 1:
 - receiving at least one biopotential signal (40);
 - receiving at least one secondary input signal (50);
 - performing motion artifact classification for determining motion information (MMI) comprising a type and/or severity indication about motion phenomena causing artifacts in the biopotential signal;
 - performing removal of the motion artifact from the biopotential signal based on that motion artifact classification;
 - evaluating the effectiveness of the removal of the motion artifact from the biopotential signal and generating feedback information (190) for optimizing the performance of the motion artifact classification.

Patentansprüche

1. System (100) zur Analyse von Biopotenzialsignalen, umfassend:

ein Modul zum Klassifizieren von Bewegungen (110), das konfiguriert ist zum Empfangen mindestens eines Biopotenzialsignals (40) und mindestens eines sekundären Referenzeingangssignals (50), um eine Klassifizierung von Bewegungsartefakten auszuführen, zum Ausführen einer Klassifizierung von Bewegungsartefakten zum Bestimmen von Bewegungsinformationen (MMI), die eine Art und/oder eine Schweregradangabe über Bewegungsphänomene, die Artefakte in dem Biopotenzialsignal verursachen, umfassen, und zum Mitteilen der Bewegungsinformationen (MMI) an ein Modul zum Reduzieren von Bewegungsartefakten (120); wobei das Modul zum Reduzieren von Bewegungsartefakten (120) konfiguriert ist zum Ausführen einer Unterdrückung von Bewegungsartefakten in dem Biopotenzialsignal basierend auf den Informationen, die von dem Modul zum Klassifizieren von Bewegungen (110) empfangen werden;
dadurch gekennzeichnet, dass das System ferner konfiguriert ist zum Beurteilen der Wirksamkeit mindestens eines Algorithmus, der zum Unterdrücken von Bewegungsartefakten und zum Generieren von Rückkopplungsinformationen (190) zwischen dem Modul zum Klassifizieren von Bewegungen (110) und dem Modul zum Reduzieren von Bewegungsartefakten (120) verwendet wird, um die Ausführung der Klassifizierung von Bewegungsartefakten zu optimieren.

2. System (100) nach Anspruch 1, wobei das System ferner konfiguriert ist, um Ausgaben des Moduls zum Klassifizieren von Bewegungen (110) und des Moduls zum Reduzieren von Bewegungsartefakten (120) in verschiedenen Zeiträumen zu speichern und zu verarbeiten, um die Rückkopplungsinformationen (190) zum Optimieren der Ausführung der Klassifizierung von Bewegungsartefakten zu generieren.
3. System (100) nach einem der vorhergehenden Ansprüche, wobei das Beurteilen der Wirksamkeit mindestens eines Algorithmus, der zum Unterdrücken von Bewegungsartefakten verwendet wird, das Vergleichen des sauberen Biopotenzialsignals nach dem Unterdrücken von Bewegungsartefakten mit einem Referenz-Basisliniensignal dieses Biopotenzialsignals umfasst.
4. System (100) nach einem der vorhergehenden Ansprüche, wobei das mindestens eine sekundäre Referenzeingangssignal (50) ein Signal ist, das Informationen über eine oder eine Kombination von Kontaktimpedanz, Kontaktkraft, Bewegungsbeschleunigung, Temperatur und Feuchtigkeit umfasst.

5. System (100) nach einem der vorhergehenden Ansprüche, wobei das Modul zum Klassifizieren von Bewegungen (110) ferner konfiguriert ist, um Einstellungsparameter zum Unterdrücken von Artefakten zu bestimmen und dem Modul zum Reduzieren von Bewegungsartefakten (120) mitzuteilen.
- 5 6. System (100) nach Anspruch 5, wobei die Einstellungsparameter eine Angabe zur Auswahl einer Technik zum Unterdrücken von Artefakten und/oder Koeffizienten bezüglich einer bestimmten Technik zum Unterdrücken von Artefakten und/oder eine Signalauswahlangebe für eine bestimmte Technik zum Unterdrücken von Artefakten umfassen.
- 10 7. System (100) nach einem der vorhergehenden Ansprüche, wobei das Modul zum Reduzieren von Bewegungsartefakten (120) ferner konfiguriert ist, um eine bestimmte Technik zum Unterdrücken von Artefakten basierend auf Informationen, die von dem Modul zum Klassifizieren von Bewegungen (110) empfangen werden, anzuwenden, zu konfigurieren und/oder zu optimieren.
- 15 8. System (100) nach einem der vorhergehenden Ansprüche, wobei das Modul zum Klassifizieren von Bewegungen (110) und das Modul zum Reduzieren von Bewegungsartefakten (120) konfiguriert sind, um eine oder eine Kombination von Klassifizierungs-, statistischen Analyse-, Spektralanalyse-, Kreuzsignalanalyse-, PCA-, ICA-, CCA-, AF-, BF- oder EMD-Techniken auszuführen.
- 20 9. System (100) nach einem der vorhergehenden Ansprüche, ferner umfassend ein Vorverarbeitungsmodul (105), das konfiguriert ist, um die empfangenen Signale anzupassen, damit sie von dem Modul zum Klassifizieren von Bewegungen (110) verarbeitet werden, und/oder ein Nachverarbeitungsmodul (125), das konfiguriert ist, um die Ausgangssignale anzupassen, die von dem Modul zum Klassifizieren von Bewegungen (110) und/oder dem Modul zum Reduzieren von Bewegungsartefakten (120) bereitgestellt werden.
- 25 10. Elektronische Vorrichtung, umfassend ein System (100) zur Analyse von Biopotenzialsignalen nach einem der Ansprüche 1 bis 9.
- 30 11. Verfahren zur Analyse von Biopotenzialsignalen, umfassend folgende Schritte in einem System (100) nach Anspruch 1:
 - Empfangen mindestens eines Biopotenzialsignals (40);
 - Empfangen mindestens eines sekundären Eingangssignals (50);
 - Ausführen einer Klassifizierung von Bewegungsartefakten, um Bewegungsinformationen (MMI) zu bestimmen,
 - 35 die eine Art und/oder eine Schweregradangabe über Bewegungsphänomene, die Artefakte in dem Biopotenzialsignal verursachen, umfassen;
 - Ausführen einer Unterdrückung des Bewegungsartefakts in dem Biopotenzialsignal basierend auf dieser Klassifizierung von Bewegungsartefakten;
 - Beurteilen der Wirksamkeit der Unterdrückung des Bewegungsartefakts in dem Biopotenzialsignal und Generieren von Rückkopplungsinformationen (190) zum Optimieren der Ausführung der Klassifizierung von Bewegungsartefakten.
 - 40

Revendications

- 45 1. Système (100) pour l'analyse de signaux biopotentiels, comprenant :
 - un module de classification de mouvement (110) configuré pour recevoir au moins un signal biopotentiel (40) et au moins un signal d'entrée secondaire de référence (50), effectuant une classification d'artefact de mouvement pour déterminer des informations de mouvement (MMI) comprenant une indication de type et/ou de
 - 50 sévérité concernant des artefacts provoquant des phénomènes de mouvement dans le signal biopotentiel et communiquant lesdites informations de mouvement (MMI) à un module de réduction d'artefact de mouvement (120) ;
 - le module de réduction d'artefact de mouvement (120) étant configuré pour effectuer l'enlèvement d'artefact de mouvement depuis le signal biopotentiel en se basant sur les informations reçues en provenance du module de classification de mouvement (110) ;
 - 55

caractérisé en ce que

le système est en outre configuré pour évaluer l'efficacité d'au moins un algorithme utilisé pour l'enlèvement d'artefact de mouvement et pour produire des informations de rétroaction (190) entre le module de classification de mouvement (110) et le module de réduction d'artefact de mouvement (120) pour optimiser la performance la classification d'artefact de mouvement.

2. Système (100) selon la revendication 1, dans lequel le système est en outre configuré pour stocker et traiter des sorties du module de classification de mouvement (110) et du module de réduction d'artefact de mouvement (120) dans les périodes de temps différentes afin de produire lesdites informations de rétroaction (190) pour optimiser la performance de la classification d'artefact de mouvement.
3. Système (100) selon n'importe laquelle des revendications précédentes, dans lequel l'évaluation de l'efficacité d'au moins un algorithme utilisé pour l'enlèvement d'artefact de mouvement comprend la comparaison du signal biopotentiel propre après enlèvement d'artefact de mouvement à un signal de ligne de base de référence d'un tel signal biopotentiel.
4. Système (100) selon n'importe laquelle des revendications précédentes dans lequel l'au moins un signal d'entrée secondaire de référence (50) est un signal comprenant des informations concernant une seule ou une combinaison d'une impédance de contact, force de contact, accélération de mouvement, température ou humidité.
5. Système (100) selon n'importe laquelle des revendications précédentes dans lequel le module de classification de mouvement (110) est en outre configuré pour déterminer et communiquer des paramètres de réglage pour l'enlèvement d'artefact au module de réduction d'artefact de mouvement (120).
6. Système (100) selon la revendication 5, dans lequel lesdits paramètres de réglage comprennent une indication de sélection de technique d'enlèvement d'artefact et/ou des coefficients liés à une technique d'enlèvement d'artefact donnée et/ou une indication de sélection de signal pour une technique d'enlèvement d'artefact donnée.
7. Système (100) selon n'importe laquelle des revendications précédentes, dans lequel le module de réduction d'artefact de mouvement (120) est en outre configuré pour appliquer, configurer et/ou optimiser une certaine technique d'enlèvement d'artefact basée sur des informations reçues en provenance du module de classification de mouvement (110).
8. Système (100) selon n'importe laquelle des revendications précédentes, dans lequel le module de classification de mouvement (110) et le module de réduction d'artefact de mouvement (120) sont configurés pour effectuer une seule ou une combinaison d'une classification, analyse statistique, analyse spectrale, analyse de signal croisé, techniques PCA, ICA, CCA, AF, BF ou EMD.
9. Système (100) selon n'importe laquelle des revendications précédentes, comprenant en outre un module de pré-traitement (105) configuré pour adapter les signaux reçus afin d'être traités par le module de classification de mouvement (110) et/ou un module de post-traitement (125) configuré pour adapter les signaux de sortie fournis par le module de classification de mouvement (110) et/ou le module de réduction d'artefact de mouvement (120).
10. Dispositif électronique comprenant un système (100) pour l'analyse de signaux biopotentiels selon n'importe laquelle des revendications 1 à 9.
11. Procédé pour l'analyse de signaux biopotentiels, comprenant, dans un système (100) selon la revendication 1 :
 - la réception d'au moins un signal biopotentiel (40) ;
 - la réception d'au moins un signal d'entrée secondaire (50) ;
 - l'exécution d'une classification d'artefact de mouvement pour déterminer des informations de mouvement (MMI) comprenant une indication de type et/ou de sévérité concernant des artefacts provoquant des phénomènes de mouvement dans le signal biopotentiel ;
 - l'exécution d'un enlèvement de l'artefact de mouvement depuis le signal biopotentiel en se basant sur cette classification d'artefact de mouvement ;
 - l'évaluation de l'efficacité de l'enlèvement de l'artefact de mouvement depuis le signal biopotentiel et la production d'informations de rétroaction (190) pour optimiser la performance de la classification d'artefact de mouvement.

Figure 1

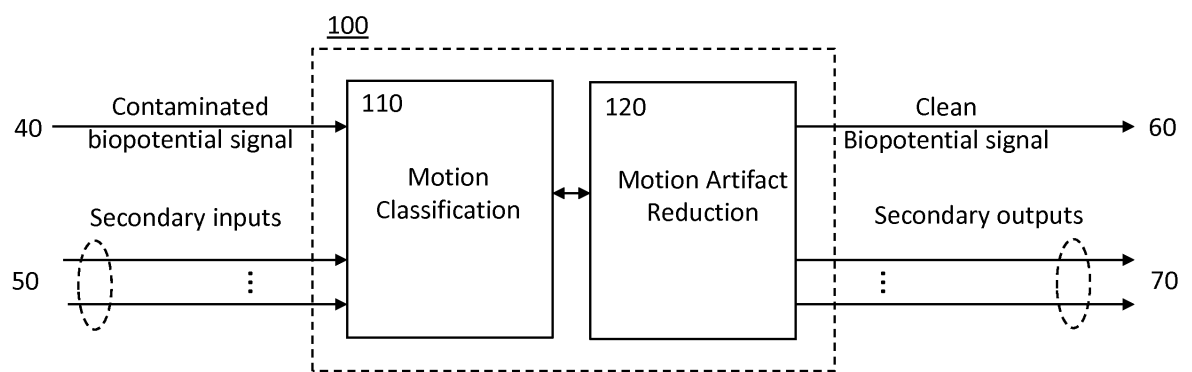


Figure 2

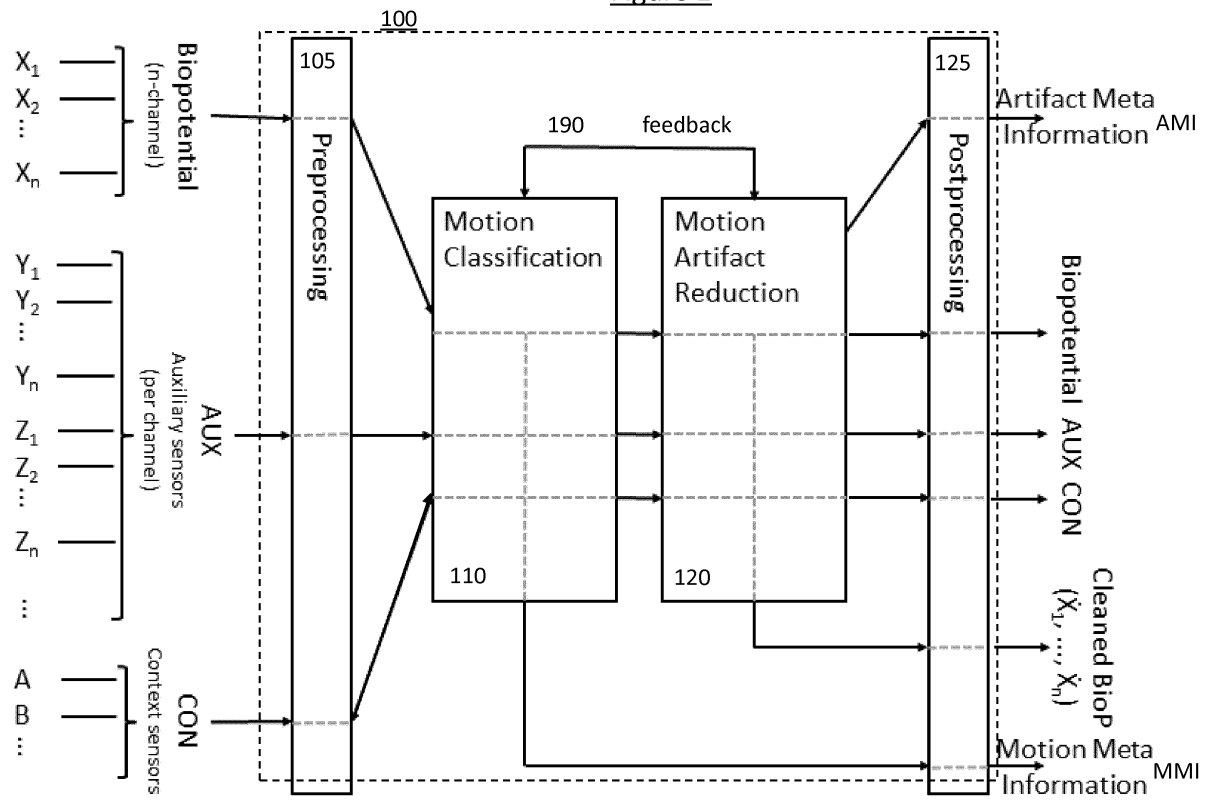


Figure 3

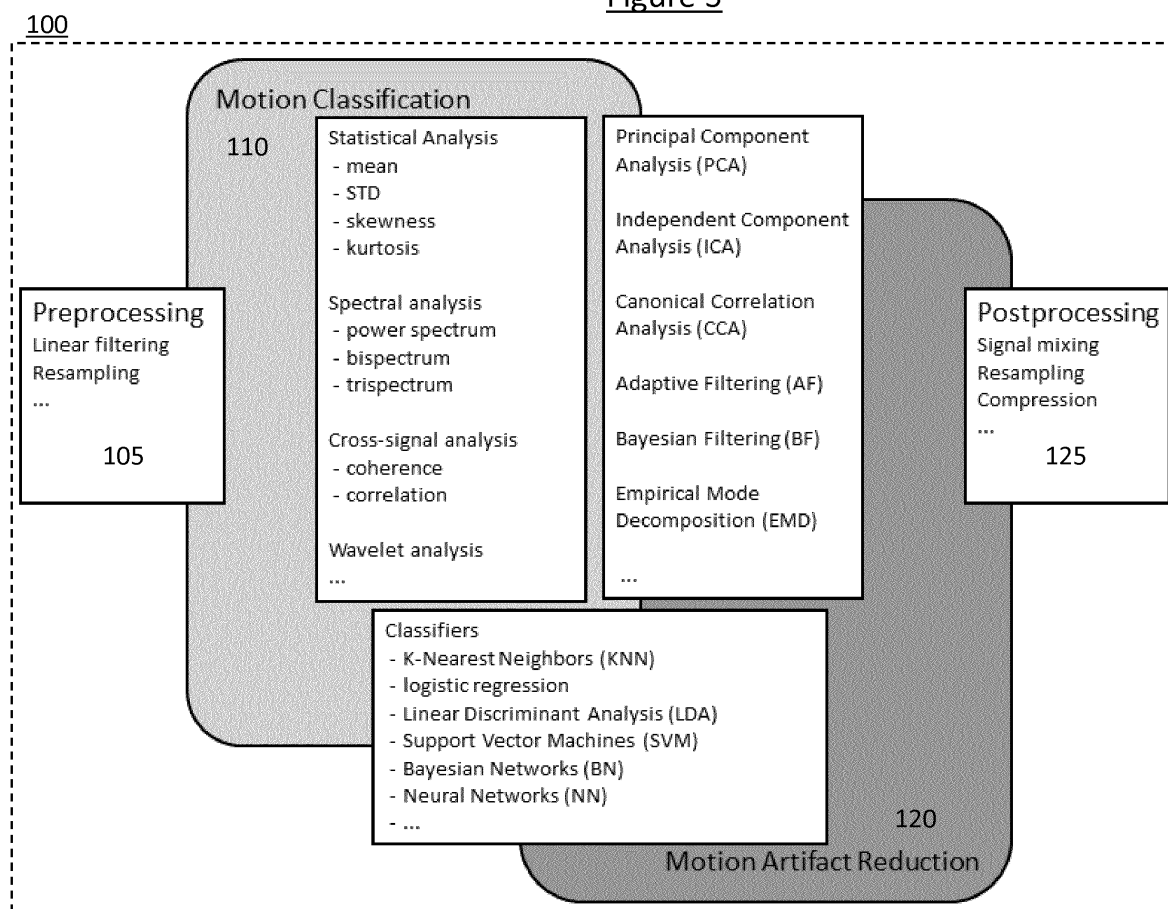


Figure 4A

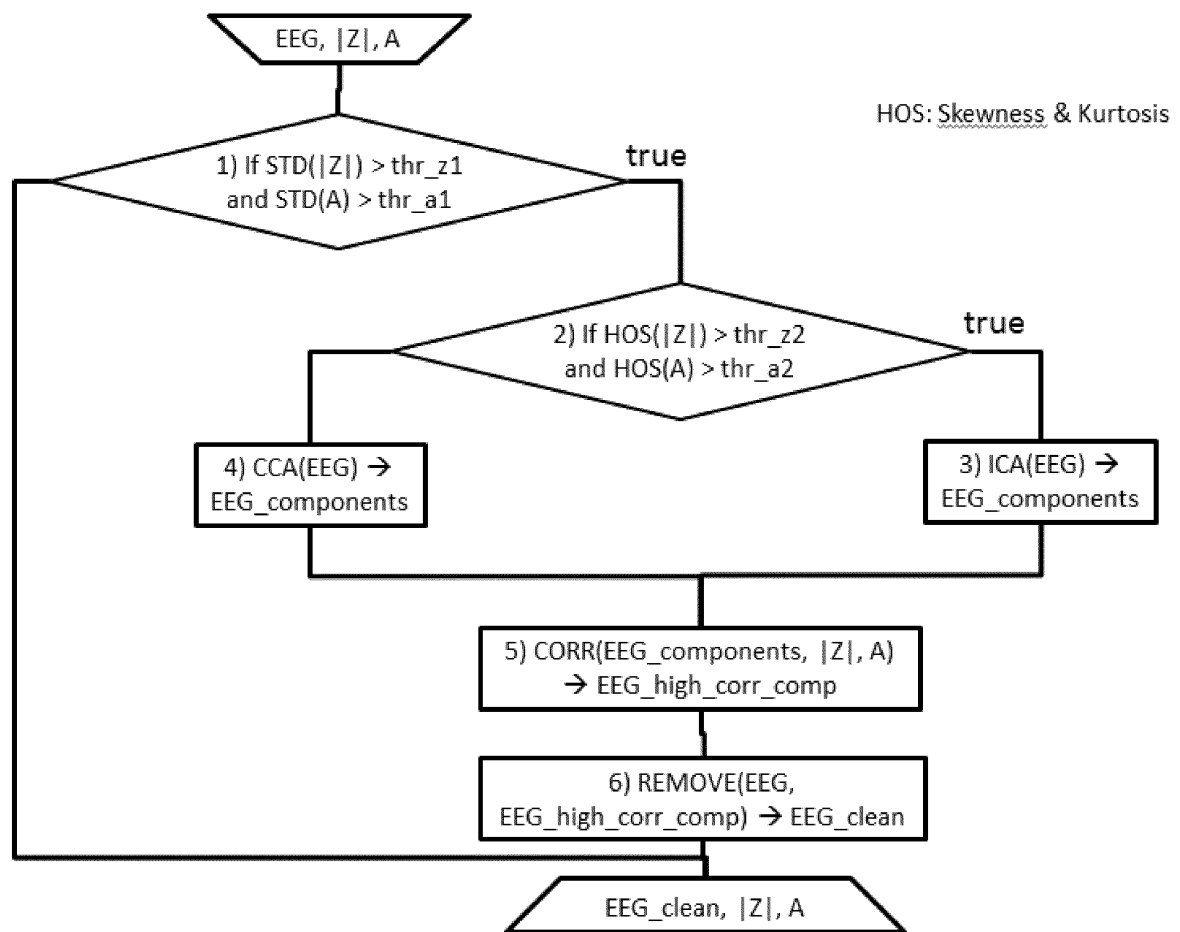


Figure 4B

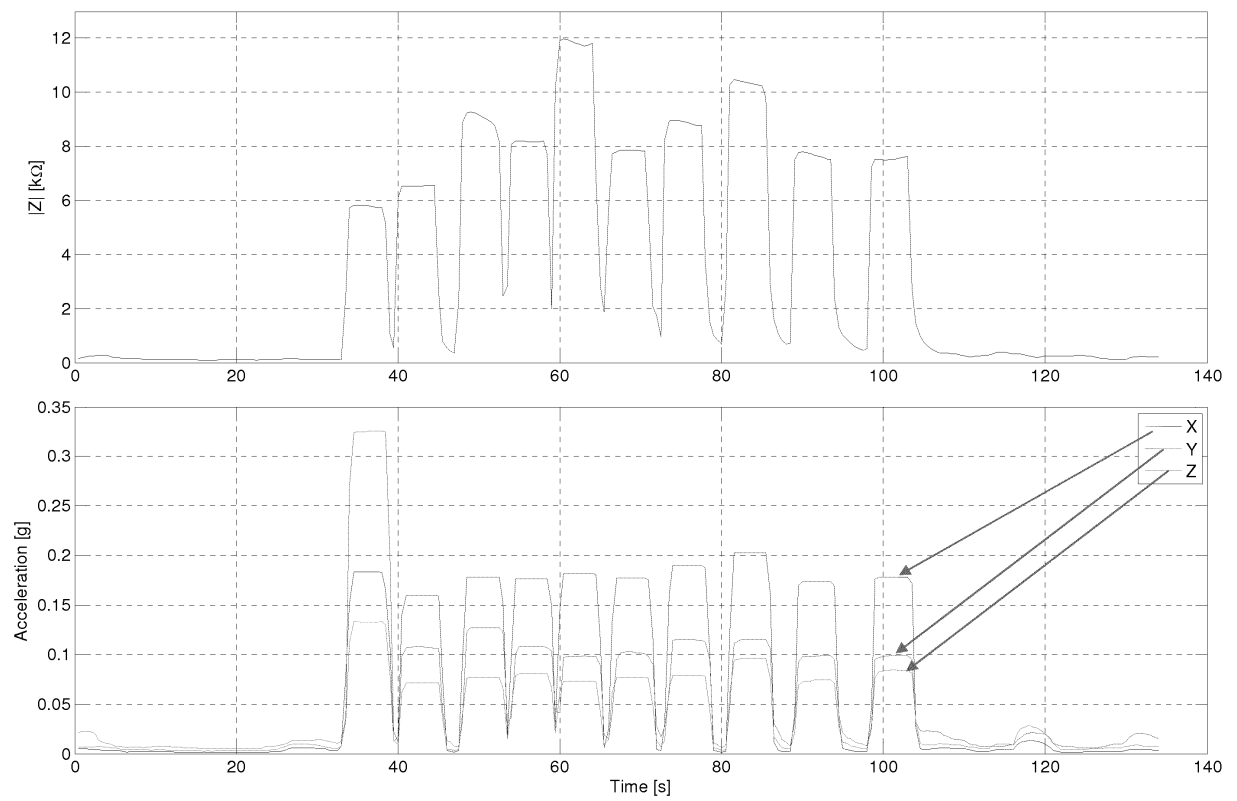


Figure 4C

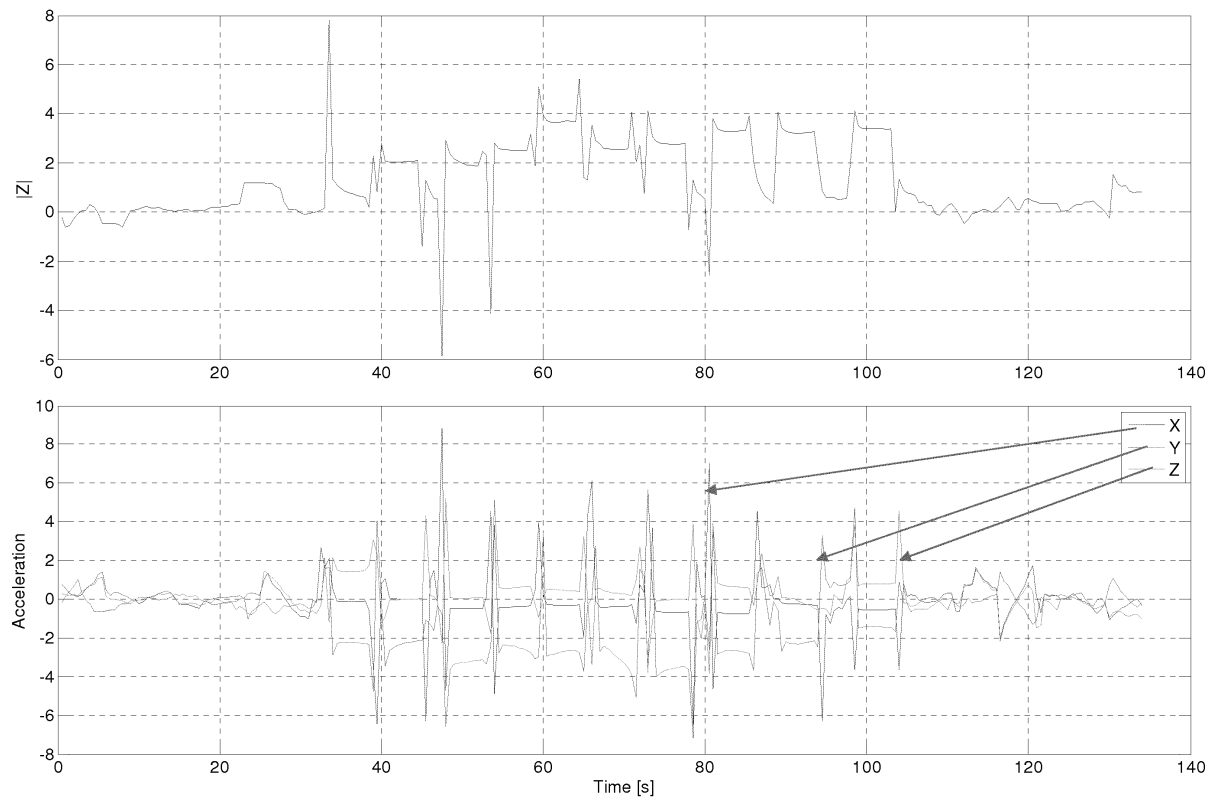


Figure 4D

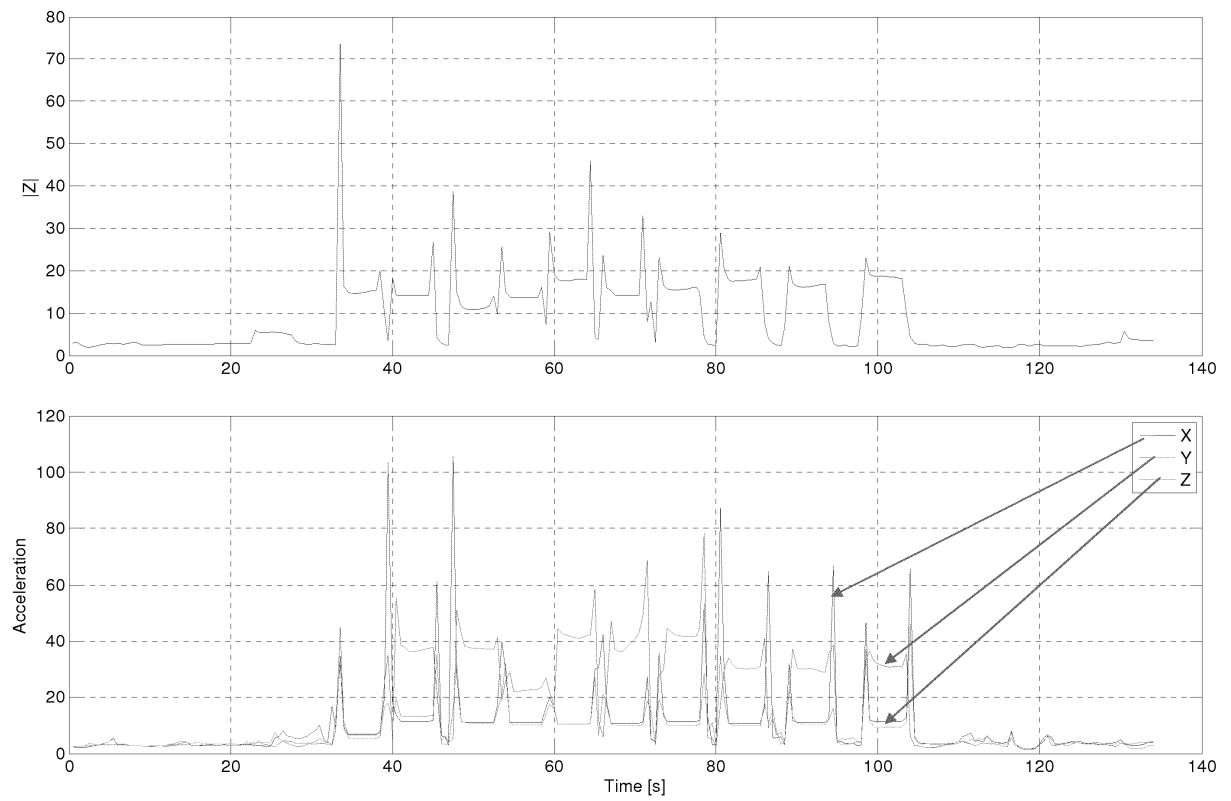


Figure 4E

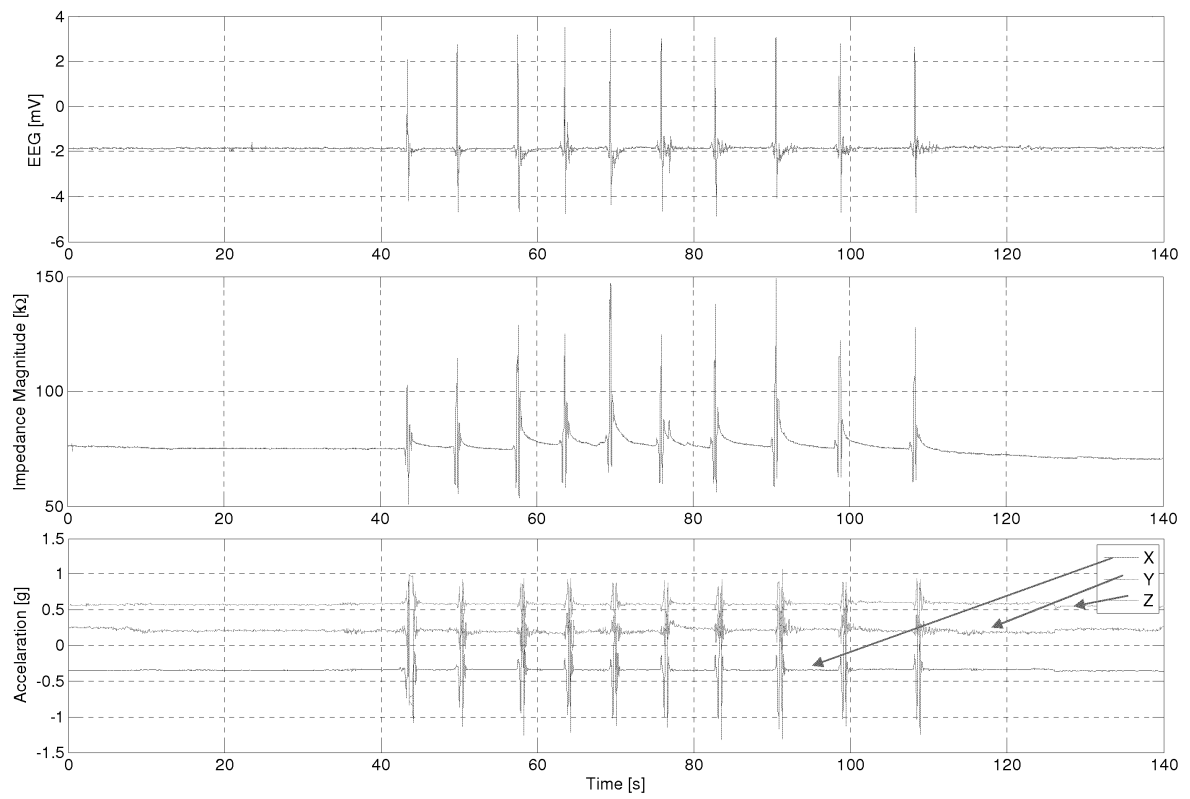


Figure 5A

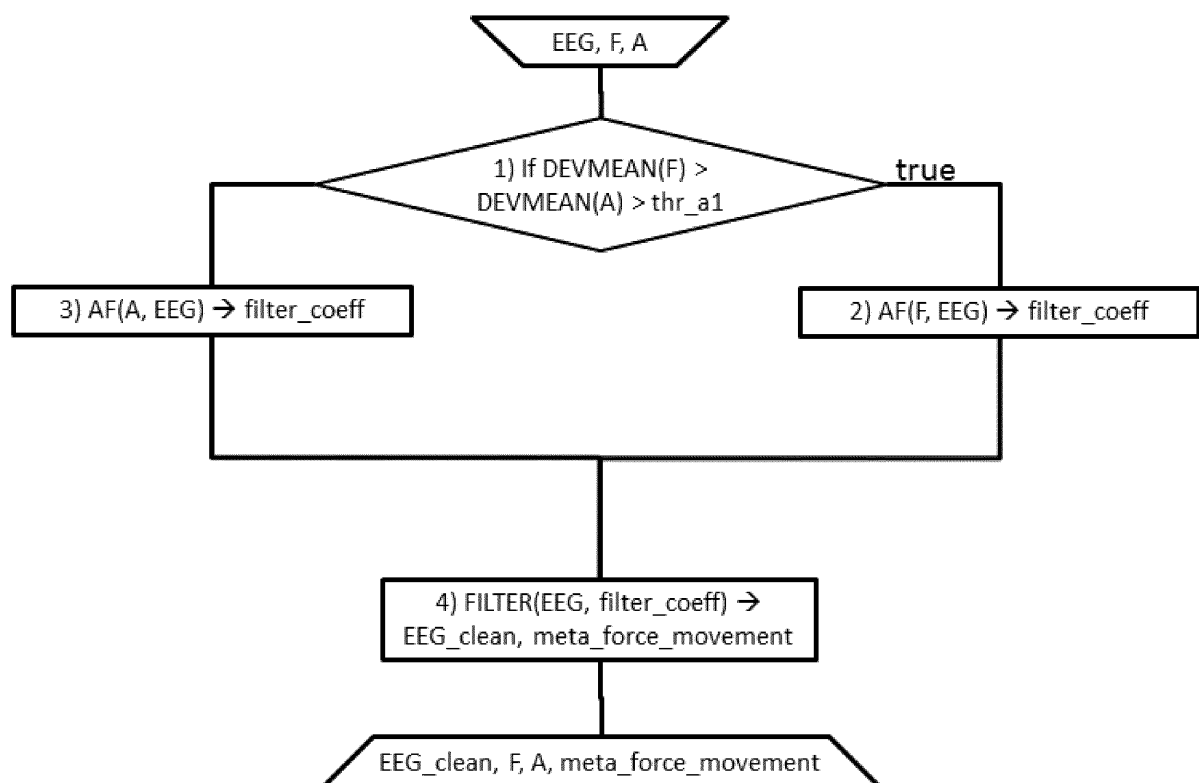


Figure 5B

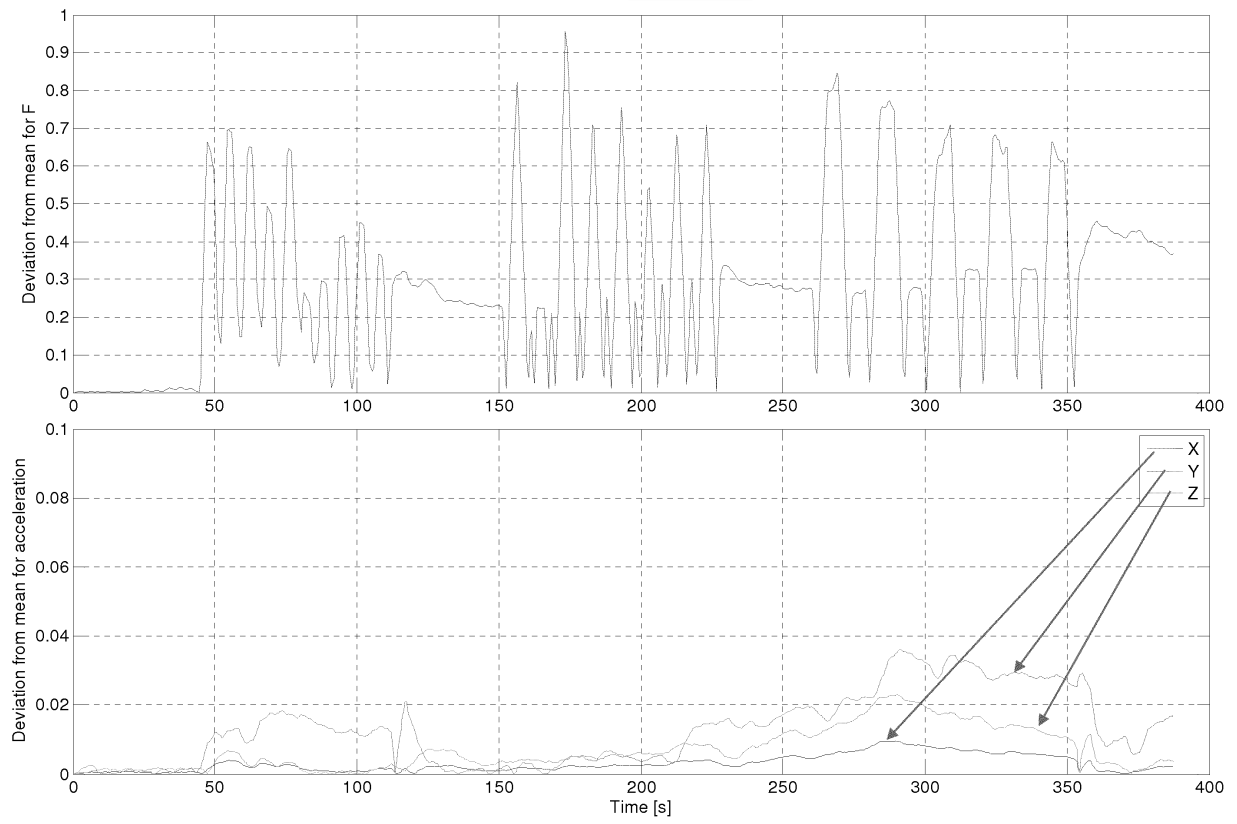


Figure 5C

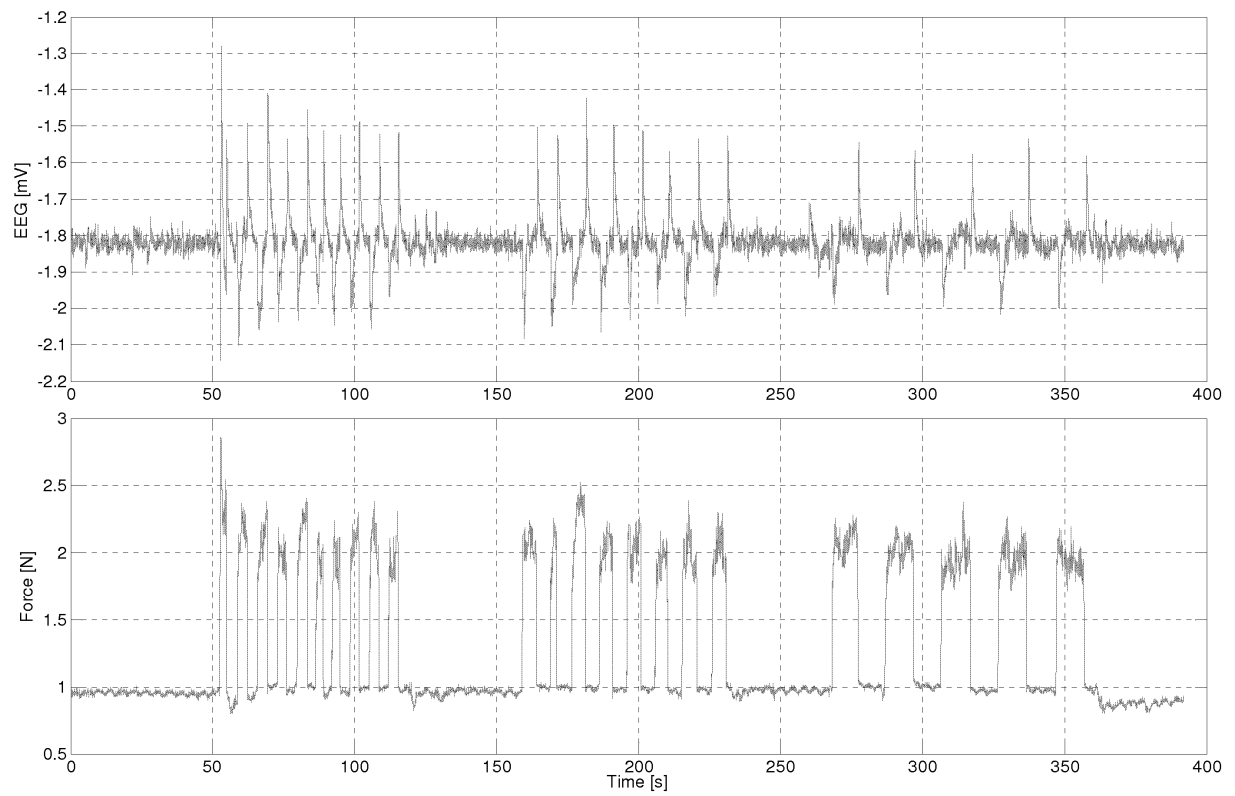


Figure 6A

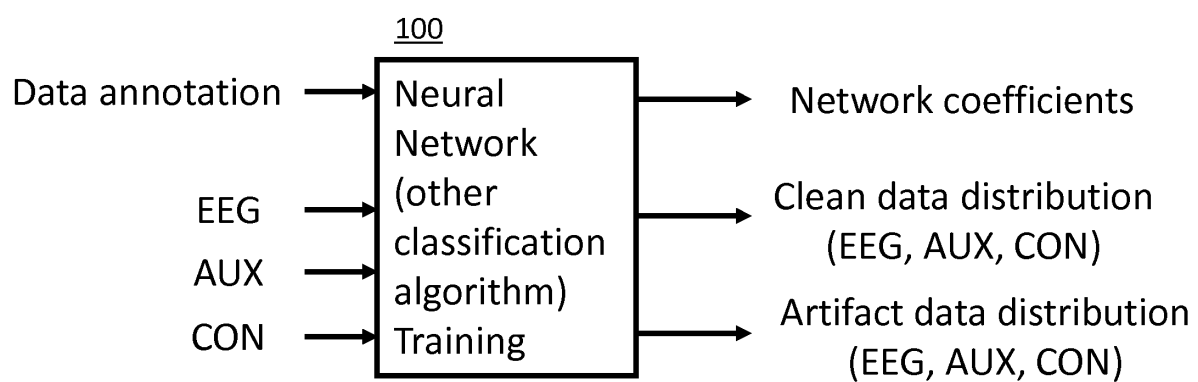


Figure 6B

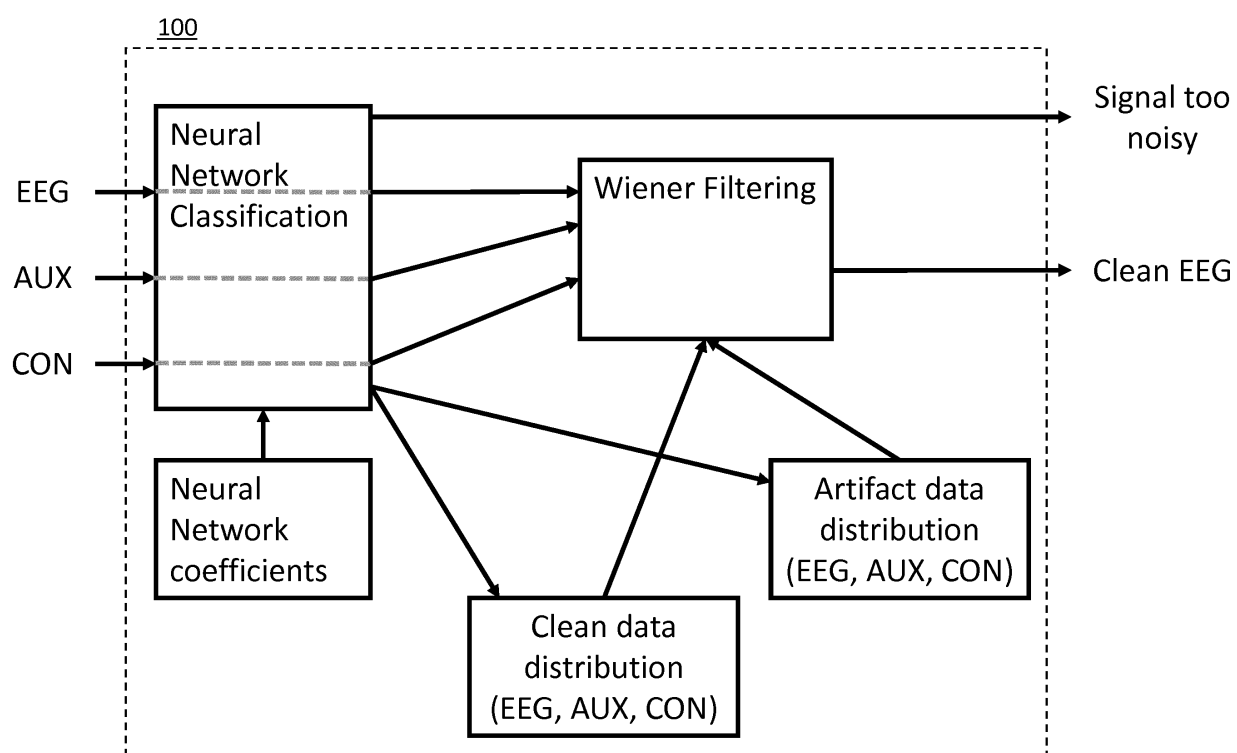


Figure 6C

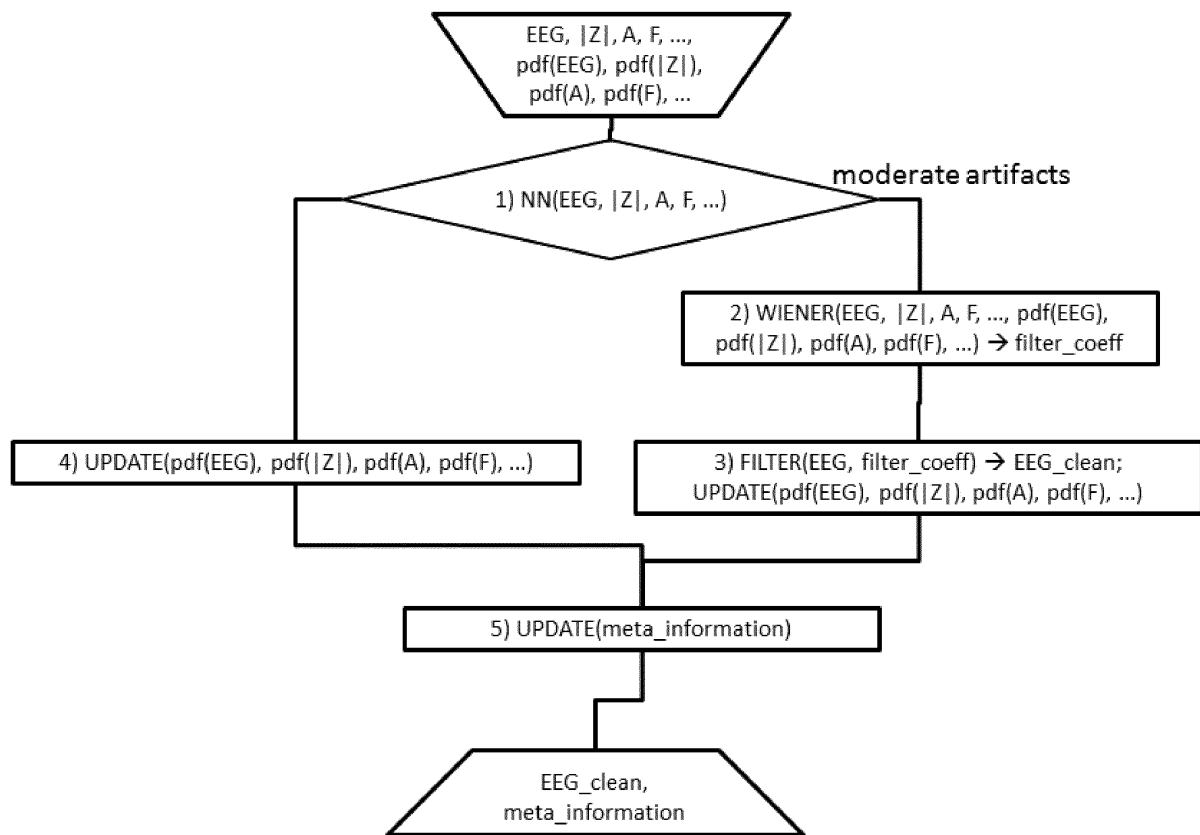


Figure 7A

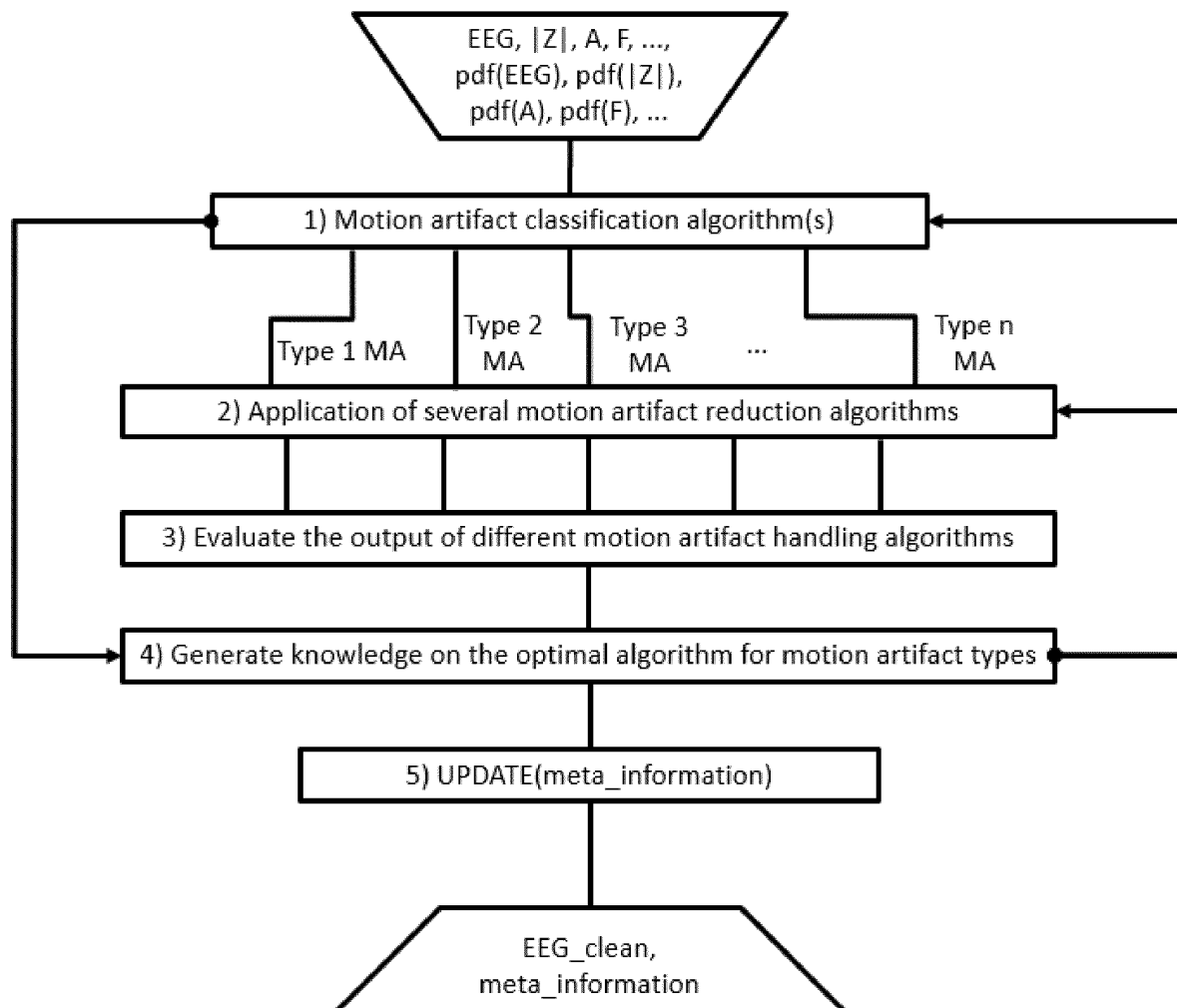


Figure 7B

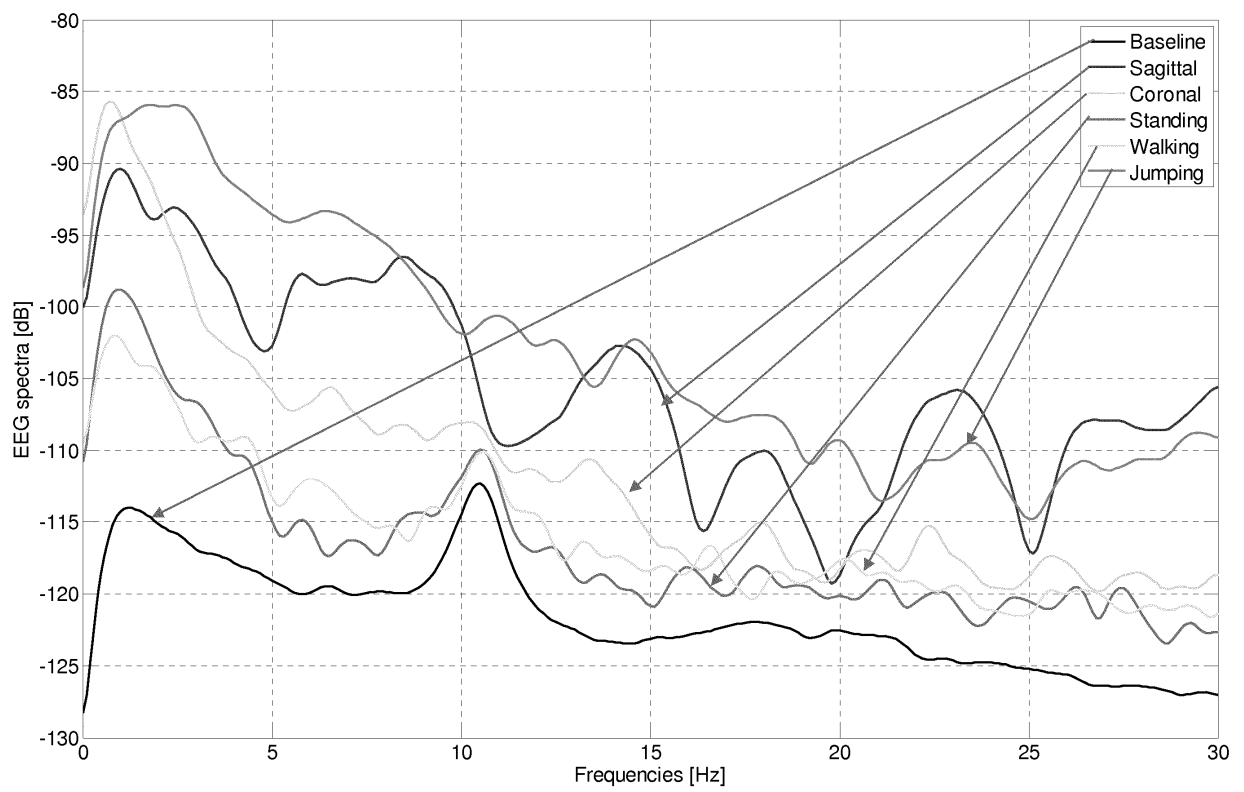
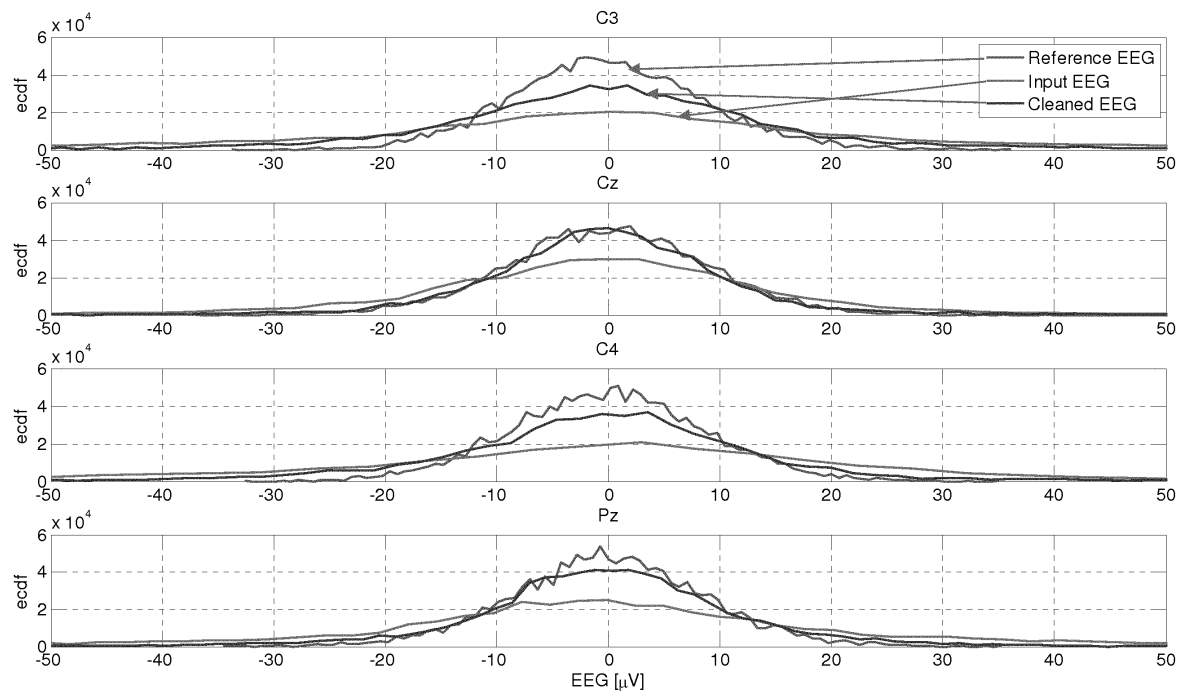


Figure 7C



REFERENCES CITED IN THE DESCRIPTION

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专利名称(译)	使用运动伪影去除技术分析生物电势信号的系统和方法		
公开(公告)号	EP2792297B1	公开(公告)日	2016-03-02
申请号	EP2014164272	申请日	2014-04-10
[标]申请(专利权)人(译)	非盈利IMEC荷兰		
申请(专利权)人(译)	IMEC STICHTING NEDERLAND		
当前申请(专利权)人(译)	IMEC STICHTING NEDERLAND		
[标]发明人	GRUNDLEHNER BERNARD MIHAJLOVIC VOJKAN		
发明人	GRUNDLEHNER, BERNARD MIHAJLOVIC, VOJKAN		
IPC分类号	A61B5/00 A61B5/04		
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代理机构(译)	CLERIX , 安德烈		
优先权	2013163813 2013-04-15 EP		
其他公开文献	EP2792297A1		
外部链接	Espacenet		

摘要(译)

本发明涉及一种用于分析生物电势信号的系统 (100) , 包括 : 运动分类模块 (110) , 被配置为接收至少一个生物电势信号 (40) 和至少一个参考次级输入信号 (50) , 执行运动用于确定运动信息 (MMI) 的伪像分类, 包括关于引起生物电势信号中的伪像的运动现象的类型和/或严重性指示, 并将所述运动信息 (MMI) 传送到运动伪影减少模块 (120) ; 运动伪影减少模块 (120) , 被配置为基于从运动分类模块 (110) 接收的信息从生物电势信号执行运动伪影去除; 其中, 所述系统还被配置用于评估用于运动伪影去除的至少一个算法的有效性, 并且在运动分类模块 (110) 和运动伪影减少模块 (120) 之间生成反馈信息 (190) , 以优化运动伪影减少模块 (120) 的性能。运动神器分类。

Figure 1

